



Corrigendum: A Socially Adaptable Framework for Human-Robot Interaction

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In the published article, there was an error regarding the affiliations for Lola Cañamero. As well as having affiliation 2 “EECAiA Lab, School of Computer Science, University of Hertfordshire, Hatfield, United Kingdom”, they should also have 4 “Neurocybernetics Team, ETIS Lab, CY Cergy Paris Université, ENSEA, CNRS UMR8051, Cergy-Pontoise, France”.

The authors apologize for this error and state that this does not change the scientific conclusions of the article in any way. The original article has been updated.

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