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Enhancing the accuracy of rotational velocity measurement for vortex beams within the optimal ability of phase retrieval algorithm

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The measurement of the rotational velocity using the rotational Doppler effect (RDE) of a vortex beam is easily affected by atmospheric turbulence, leading to dispersed orbital angular momentum (OAM), and reduced measurement accuracy. This study investigates the optimal ability of the Gerchberg-Saxton (GS) phase retrieval algorithm to compensate for the optical field and enhance the velocity measurement accuracy within the optimal range of intrinsic parameters, such as the number of GS iterations, and extrinsic parameters, such as the atmospheric turbulence intensity and beam properties. Through detailed theoretical and simulation analyses, we demonstrate the outstanding effectiveness of the GS algorithm in improving the velocity measurement accuracy. Simulations conducted for a system-target distance of $z_{S-T} = 500$ m show a 29.88% improvement in the velocity measurement accuracy and a 1.03-fold increase in the spectral signal-to-noise ratio (SSNR) within the optimal range. It showcases advantages that set it apart from other methods. This study reveals the threshold of the ability of GS algorithm to significantly enhance the rotational velocity measurement accuracy, providing valuable insights to precision measurements of rotational velocities in free-space applications.

KEYWORDS

the rotational Doppler effects, velocity measurement accuracy, orbital angular momentum, phase retrieval algorithm, atmospheric turbulence

1 Introduction

The vortex beam is characterized by its spiral wavefront structure with an orbital angular momentum (OAM) and a phase factor of $\exp(i\ell\theta)$ [1]. When irradiated onto the surface of a rotating object, the vortex beam induces a rotational Doppler shift (RDS) related to the angular velocity of the object, which is known as the rotational Doppler effect (RDE) of the vortex beam [2]. Recent research has extensively explored the RDE, focusing on its intrinsic mechanism, expanding application scenarios, and optimizing rotational velocity measurements [3–9].

Although vortex beam detection offers high sensitivity in sensing applications, the beam is susceptible to the influence of random atmospheric turbulence in practical remote-sensing scenarios [10]. This causes a OAM spectrum dispersion [11], leading to a decrease in the spectral signal-to-noise ratio (SSNR) and rotational velocity measurement accuracy. In previous studies, Li *et al.* investigated the mode crosstalk phenomenon of vortex beams in

atmospheric turbulence utilizing Monte Carlo phase screens and Fresnel diffraction methods [12]. Ren conducted experiments to investigate channel impairments caused by atmospheric turbulence, which affect interchannel multimode crosstalk, and system power loss in OAM multiplexed free-space optical links over distances exceeding 120 m [13]. Numerous other studies have examined the influence of atmospheric turbulence on the optical fields, crosstalk, system power loss, and bit error rate (BER), among other factors [14, 15]. Adaptive optics (AO) algorithms, such as the Shack-Hartmann (SH) wavefront correction method [16–18], stochastic parallel gradient descent (SPGD) [19], and the Wirtinger flow (WF) algorithm [20], and others [21–23], play a crucial role in mitigating the beam distortion caused by atmospheric turbulence. Among these methods, the Gerchberg-Saxton (GS) algorithm, a phase retrieval AO algorithm, utilizes the distorted wavefront to compensate for the received beam and has a wide range of applications [24–26]. However, the ability of phase retrieval algorithms to improve the rotational velocity measurement accuracy of vortex beam has not been widely discussed.

Through theoretical and simulation analyses, this study investigates the ability of the GS phase retrieval algorithm to compensate for the optical field and enhance the velocity measurement accuracy within the optimal range of intrinsic parameters, such as the number of GS iterations, and extrinsic parameters, such as the atmospheric turbulence intensity and beam property. Additionally, this study further broadens the scope of the phase retrieval algorithm in practical applications, providing a significant assistance for enhancing the precise measurement of remote rotational velocity in vortex beams application.

2 Simulation principles

2.1 RDE and velocity measurement accuracy

The Laguerre-Gaussian (LG) beam is most used for RDE measurements. Its complex amplitude can be represented as $E_0 (r/\omega_0)^{|l|} \exp(-r^2/\omega_0^2) \exp(il\theta)$ in cylindrical coordinates. Here, E_0 represents the electric field amplitude, (r, θ) represents the polar coordinates in the $z = 0$ plane, ω_0 represents the beam waist radius, and l represents the topological charge [27].

The RDE occurs due to the deviation angle γ between the motion direction of photons in the vortex beam and the optical axis [28]. It can be effectively described using the velocity projection model [29], where $\sin \gamma = |l|/kr$ and k represents the wave number [30]. For a single-mode vortex beam, the RDS is expressed as $\Delta f = |l|\Omega/2\pi$, where Ω is the rotational velocity of the target. The standard deviation of the spectral peak in laser velocimetry can be represented as follows [31].

$$\sigma_f = \frac{\sqrt{3}}{\tau\pi\sqrt{2SSNR}} \quad (1)$$

In Eq. 1, τ denotes the accumulation time of the Avalanche photodiode (APD). The SSNR is given by $SSNR = 10 \log_{10}(P_{signal}/P_{noise}) = 20 \log_{10}(A_{signal}/A_{noise})$, where A_{signal} and A_{noise} represent the spectral amplitudes of the signal and noise, respectively.

The standard deviation of the angular velocity measurement can be obtained from the error transfer equation as follows.

$$\sigma_\Omega = \frac{\sqrt{6}}{|l|\tau\sqrt{SSNR}} \quad (2)$$

According to Eq. 2, the rotational velocity measurement error depends on three factors:

(a) Detector accumulation time

APD with reasonably long accumulation time can increase the number of detected photons, provide stable and reliable results, and improve the statistical accuracy of the signal, thereby reducing the velocimetry error.

(b) SSNR

Detector system factors such as the grain noise, dark counts, and thermal noise can reduce the SSNR, leading to a decrease in the measurement accuracy. Therefore, a higher SSNR results in smaller rotational velocity measurement errors.

(c) Topological charge

As shown in the formula $\Delta f = |l|\Omega/2\pi$ for RDS, when utilizing high-mode vortex beams for detection, the RDS value of the detection signal will be amplified by a factor of $|l|$. It is worth mentioning that when utilizing the superposition of high-mode vortex beams, the RDS will be amplified by a factor of $2|l|$, resulting in a doubling of the velocity measurement accuracy compared to a single-mode vortex beam [2]. Therefore, increasing the topological charge of the vortex beam can enhance the precision of velocity measurements.

2.2 GS phase retrieval algorithm

The basic principle of the GS algorithm is to iterate the optical intensity information according to the initial and distorted optical field, and obtain the pre-compensated phase screen through the algorithm calculation [32–34]. The distorted optical field achieves phase compensation through the correction of the pre-compensated phase screen. The flowchart of the GS algorithm is shown in Figure 1. Specifically, the complex amplitude of vortex beam $E_i \exp(i\varphi_i)$ is chosen as the input. After the fast Fourier transform (FFT), the optical field in the image plane $E_m \exp(i\varphi_m)$ is obtained. Then, the amplitude is replaced by the distorted beam amplitude E_0 to obtain a new optical field $E_0 \exp(i\varphi_m)$, the inverse fast Fourier transform (IFFT) is performed to obtain the complex amplitude in the source plane. After that, replace the amplitude with the original beam E_i and continue FFT. Finally, when the number of iterations reaches N_{GS} , the phase distribution φ in the reconstructed diffraction plane is obtained, and then the pre-compensated phase H is obtained as $\varphi_i - \varphi$.

2.3 Simulation design for rotational velocity extraction

The simulation was designed for rotational velocity extraction based on the following steps:

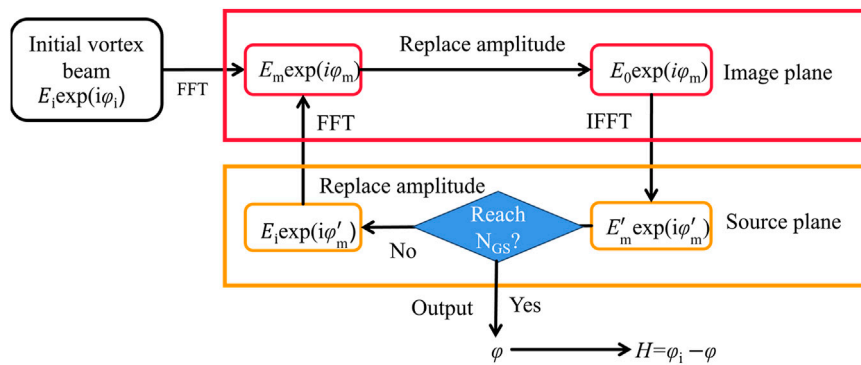


FIGURE 1 Flowchart of GS phase retrieval algorithm.

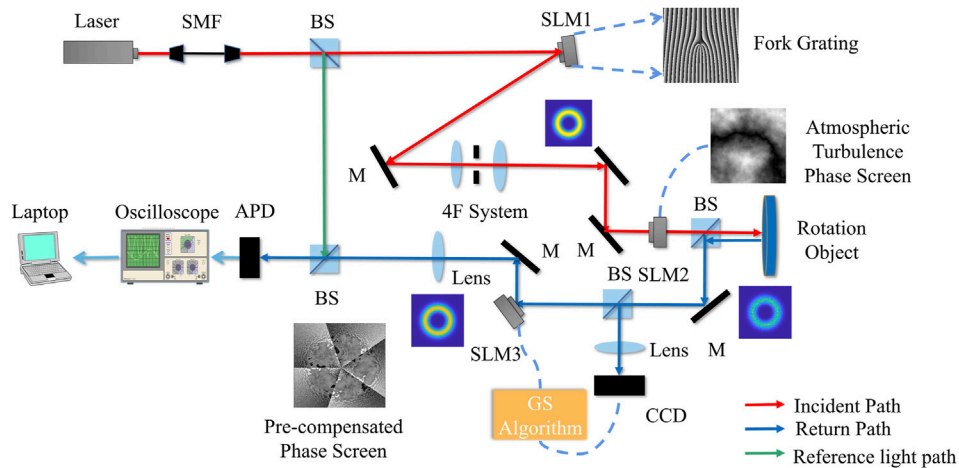


FIGURE 2 Schematic illustration of the system design.

(a) The vortex beam, generated in the grating diffraction method, passes through a random phase screen to simulate atmospheric turbulence. The modal expansion method [2] is used to analyze the received optical field carrying the RDS after interacting with the rotating object. Barring any specialized treatment applied to the target, the different modes of scattered light are approximately uniformly distributed. Angular spectrum analysis is then performed on the received optical field. The expression is simplified and represented in the following form:

$$E = \exp(-i2\pi ft) [\varepsilon_1 \exp(il_1\Omega t) + \varepsilon_2 \exp(il_2\Omega t) + \dots + \varepsilon_N \exp(il_N\Omega t)] \quad (3)$$

where $l_i, i = 1, 2, 3 \dots N$, represents the OAM modes contained in the received beam, which undergoes angular spectrum dispersion in atmospheric turbulence. ε_i represents the relative power of the l_i -th mode.

(b) The distorted beam is utilized to recovery the optical field using the GS algorithm, which iterates the light intensity information several times to obtain a pre-compensated phase screen.

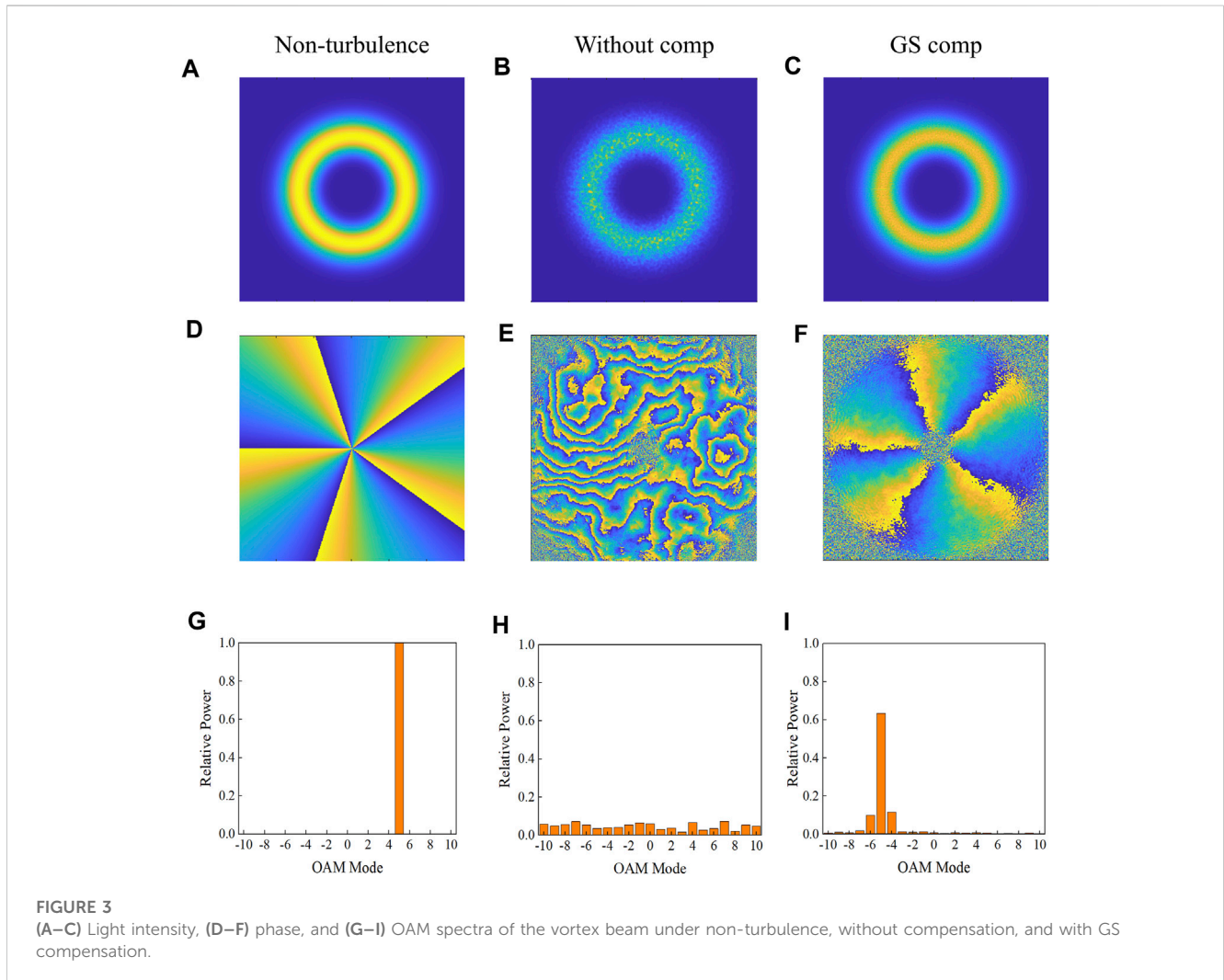
(c) The recovered optical field is subjected to angular spectrum and spectral analyses based on Eq. 3. The RDS peak is extracted, and the rotational velocity and measurement accuracy of the object are obtained.

3 Velocimetry system design

The schematic of the system design is displayed in Figure 2. The laser output a Gaussian mode beam at $\lambda = 532 \text{ nm}$. The laser beam was coupled to a single-mode optical fiber (SMF) for collimation. The beam passed through spatial light modulator 1 (SLM1), loaded with a fork grating pattern, and generated a vortex beam. The vortex beam was obtained using a 4F system with an aperture that filtered the first-order diffraction modulation signal from the incident beam. The beam underwent distortion through SLM2, which loaded a random phase screen to simulate atmospheric turbulence using the power spectrum inversion method. The modified Von Karman spectrum [35] was used, and a subharmonic

TABLE 1 Simulation parameters.

Parameter	Value	Parameter	Value
ω	0.003 m	Iteration number N_{GS}	50
Phase screen resolution	600×600	Ω	50 rad/s
Turbulence inner scale l_0	0.005 m	τ	0.1 s
Turbulence outer scale L_0	20 m	System-target distance z_{S-T}	200 m
C_n^2	$1 \times 10^{-14} \text{ m}^{-2/3}$	l	5



compensation method was adopted for the lack of low-frequency components present in the phase screen [36], with a compensation level of $p = 3$. The beam, after undergoing distortion, illuminated the rotating target surface. After passing through the beam splitter, the reflected echo beam was focused onto a Charge coupled device (CCD) to record the spot intensity. The distorted beam intensity was used as the iteration information for the GS algorithm to generate the pre-compensated phase screen, which was loaded onto SLM3. The transmitted echo beam passed through SLM3 to undergo

phase compensation. After interfering with the reference light, an APD received and collected the photon signals, generating a temporal signal of the light intensity, which was Fourier-transformed to extract the RDS. The results were detected using an oscilloscope, and the data were processed to calculate the rotational velocity of the target. Figure 2 displays the intensity distribution of the selected vortex beam after passing through 4F system, and the SLM-loaded fork grating pattern. It also shows the atmospheric turbulence phase screen and the pre-compensated phase screen.

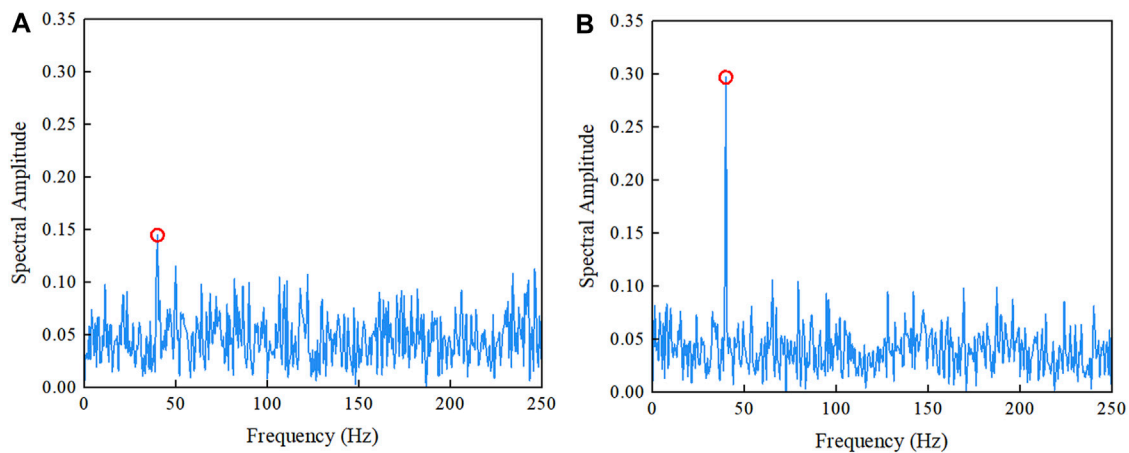


FIGURE 4 Spectrum of the vortex beam (A) without compensated, and (B) compensated with the GS algorithm. Red circles indicate the RDS peak.

4 Results and analysis

4.1 GS algorithm to improve velocity measurement accuracy

First, we conducted a simulation analysis to assess the enhancement of velocity measurement accuracy for the distorted vortex beam utilizing the GS algorithm. The reversal of topological charges, resulting from the reflection of the dispersed OAM modes by the target and mirrors, was considered. The simulation parameters are listed in Table 1, unless specified otherwise. As shown in Figure 3, the phase compensation applied by the GS algorithm has notably smoothed the annular light intensity structure of the vortex beam, which originally became rough due to turbulence. The distorted phase distribution was substantially restored, which enabled a clear interpretation of the phase structure. The helical spectrum relative power (purity) of the reflected -5 mode increased significantly from 0.036 to 0.635, indicating a remarkable 16.64-fold improvement. In the spectrum shown in Figure 4, a RDS peak at $f_1 = 40$ Hz (marked with a red circle) is discernible, which differs from the theoretical value by only 0.48%, and the spectral amplitude improved 1.05-fold. The SSNR increased from 9.9 dB to 15.76 dB, indicating a 59.2% SSNR improvement factor ($SSNR_{IF}$). The velocity measurement accuracy improved from 1.56 rad/s to 1.23 rad/s, reflecting a 21.15% velocity measurement accuracy improvement factor (σ_{IF}). These results show that the optical field and angular spectral purity of the vortex beam, which are distorted by atmospheric turbulence, are significantly improved by the compensation of the GS algorithm. This improvement highlights the amplitude distinction between the RDS peak and noise, thus improving the SSNR and consequently increasing the velocity measurement accuracy.

Afterwards, the effectiveness of the GS algorithm in improving the distorted optical field and enhancing the velocimetry accuracy is discussed through experiments. By loading turbulence screen on the SLM to simulate atmospheric turbulence, and employing a rotating motor as a rotating target, we set up the experimental optical path and achieved the velocimetry experiment of $l = 4$ vortex beam at a

rotation velocity of 1,000 r/min (16.67 r/s). The experimental results include intensity and spectrum of the vortex beam under non-turbulence, without GS compensation, and with GS compensation, as illustrated in Supplementary Figures S1, S2. Following the compensation with the GS algorithm, there is a noticeable improvement in the light intensity. In the spectrum, it can be observed that there is a frequency interval of $\Omega/2\pi$ between prominent peaks (Ω is measured in rad/s). This phenomenon is attributed to slight misalignment between the rotating target and the beam, as well as the scattering effect from rough target. Specifically, the power amplitude of the first characteristic peak (marked by a red circle) increases from -27.77 dB to -20.57 dB, representing a 25.93% improvement. In this case, this is a better choice for comparison than the RDS peak. The GS algorithm compensation in the experiment enhances the velocity accuracy by 14.19%, slightly lower than the simulated value of 0.8%. However, due to the reasons mentioned above, the velocity accuracy of the recovered beam is 10.5% lower compared to the simulation. We plan to address this issue in upcoming experiments by incorporating additional equipment for fine-tuning target positioning, refining the target, and optimizing the optical path. It underscores the importance of precise alignment and careful selection of target, which should be a focal point for the improvement of velocity accuracy in subsequent experiments.

4.2 Influence of beam properties on the GS algorithm to enhance velocimetry accuracy

The velocity measurement accuracy of vortex beams with topological charges l from 1 to 8 at $z_{S-T} = 500$ m are shown in Figure 5A. The velocity measurement accuracy curve of recovered beam, obtained through 20 sets of repetitive calculations, exhibit a significant decrease, with reduction rates of 49.38% and 34.28% in the 1st and 2nd modes, respectively. After an average reduction rate of 17.08%, the curve stabilizes at $l = 7$, where the reduction rate is only 5.33% and the velocity measurement error reaches its minimum at 0.93 rad/s. Overall, the GS algorithm has an average

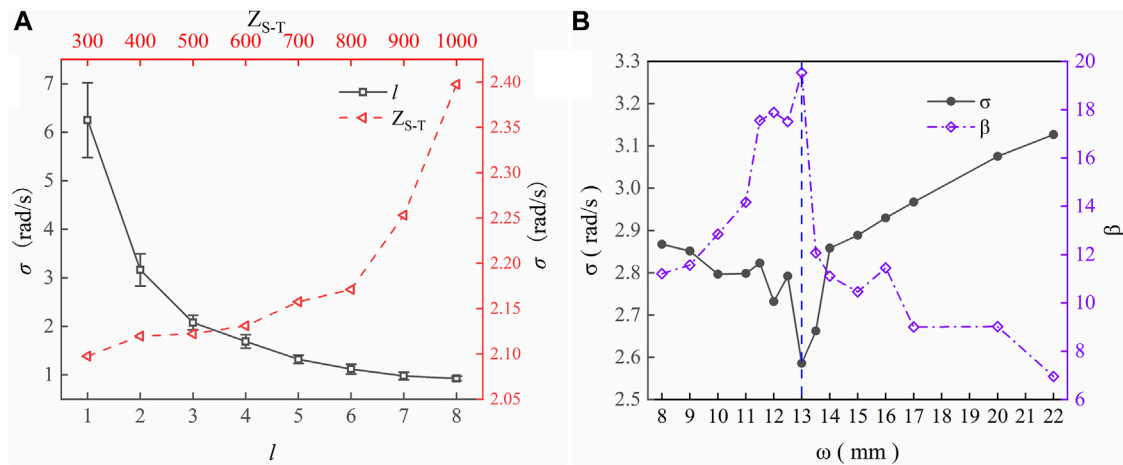


FIGURE 5 σ as a relationship of (A) l and z_{S-T} , and (B) ω and OAM purity enhancement factor β . The dashed vertical line in (B) indicates the beam waist beyond which the ability of the GS algorithm to improve the OAM purity and velocimetry accuracy decreases rapidly.

TABLE 2 Average velocity accuracy without and with GS compensation σ , σ_{GS} , as well as σ_{AIF} and σ_{AVIF} for 1st-to 8th-mode vortex beams in the range of $z_{S-T} = 300$ –1,000 m for three relatively strong, moderate, and weak turbulence intensities.

C_n^2 ($m^{-2/3}$)	σ (rad/s)	σ_{GS} (rad/s)	σ_{AIF}	σ_{AVIF}
1×10^{-13}	2.67	2.54	2.76%	4.58%
1×10^{-14}	2.60	2.23	12.50%	13.91%
1×10^{-15}	2.37	2.42	1.56%	-2.11%

TABLE 3 Comparison of previously published works with this work on the OAM purity enhancement in atmospheric turbulence.

Items	Reference [20]	Reference [37]	Our Work
Algorithm	Wirtinger flow	AO and HIOA	GS + Optimal parameter range
C_n^2	$1 \times 10^{-14} m^{-2/3}$	$3 \times 10^{-14} m^{-2/3}$	$6 \times 10^{-15} m^{-2/3}$
l	4	3	5
OAM purity improvement (w/o comp ^d →comp)	< 50% → ~ 80%	~ 20% → < 70% ^c	18.69% → 78.72%
Others	$z = 1 \text{ km } \lambda = 1,550 \text{ nm } w = 0.035 \text{ m}$	$z = 500 \text{ m } \lambda = 1,550 \text{ nm } w = 0.0157 \text{ m}$	$z_{S-T} = 500 \text{ m } \lambda = 532 \text{ nm } w = 0.013 \text{ m}$

Note: c represents a specific value not provided in the text. <: less than, ~: approximately; d represents without compensation.

velocity measurement accuracy improvement (velocimetry accuracy average improvement factor, σ_{AIF}) of 15.91% on the 1st to 8th OAM mode with a standard deviation of 3.28%. The reason for the deviations lies in the disparate ability of the GS algorithm to enhance the velocity measurement accuracy at low modes (1st–5th modes, $\sigma_{AIF} = 17.9\%$) and high modes (6th–8th modes, $\sigma_{AIF} = 12.5\%$). This is because the higher-mode vortex beams are more significantly affected by atmospheric turbulence, resulting in limited improvements in the velocity measurement accuracy. The negative topological charge has a similar property.

Furthermore, we analyzed the enhancement in the average velocimetry accuracy of 1st to 8th modes at different z_{S-T} using the GS algorithm. Within the z_{S-T} range of 300 m to 800 m, the inhibitory effect of the transmission distance on the enhancement

ability of the GS algorithm was relatively small (with an average reduction rate of 0.7%). Starting from $z_{S-T} = 800$ m, the inhibitory effect of the transmission distance increased sharply, reaching a maximum value of 6.4%. σ_{AIF} at different transmission distances was 17.14% with a standard deviation of 2.72%. Although the GS algorithm improved the optical field through phase compensation, the velocimetry accuracy decreased owing to the cumulative effects of turbulence with increasing distance. As the transmission distance increased, the inhibitory effect gradually intensified. Similarly, the atmospheric coherence length r_0 decreased with increasing transmission distance, as described by $r_0 = 0.185 [\lambda^2 / \int_z^{z+\Delta z} C_n^2(\epsilon) d\epsilon]^{3/5}$. Overall, the OAM purity of the high-mode vortex beams was lower for longer propagation distances, resulting in a reduced SSNR and larger frequency

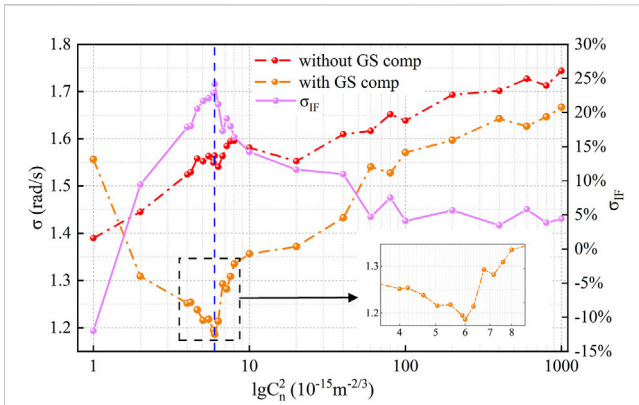


FIGURE 6

Relationships among σ , σ_{IF} , and C_n^2 without or with GS compensation at the $l = 5$ mode of the vortex beam at $z_{S-T} = 500$ m. C_n^2 is presented in logarithmic coordinates. The inset figure shows the improvement in the velocimetry accuracy around the optimal turbulence intensity. The dashed vertical line indicates the turbulence intensity beyond which the velocimetry accuracy and σ_{IF} decrease progressively.

readout errors. The GS phase retrieval algorithm can only provide limited improvement under these conditions. Therefore, when $z_{S-T} < 1,000$ m, the 5th mode vortex beam was selected to suppress the inhibition effect of turbulence more effectively. The GS algorithm was utilized to achieve a balance between the SSNR and the improvement of the velocity measurement accuracy, which facilitated optimal utilization of the algorithm.

We additionally observed a strong dependence of the algorithm's compensation ability on the beam waist radius ω , as displayed in Figure 5B. The dispersion effect of atmospheric turbulence was minimized for a beam waist radius corresponding to the minimum spot size at a given transmission distance. Within the Rayleigh range z_R , the beam propagated approximately in parallel across the propagation distance. When $z = z_R$, the waist radius of the beam increased to $\sqrt{2} \omega_0$, leading to the optimal waist radius $\omega_{\pm} = \sqrt{z\lambda/\pi}$. Specifically, for the low mode (1st–5th) vortex beams, the average velocimetry error in the range of $\omega = 8$ to 13 mm gradually decreased to 2.58 rad/s. Simultaneously, the average OAM purity enhancement factor β gradually increased to 19.54, representing a reduction of 9.9% in velocimetry error and an enhancement of 42.62% in β compared with the values at $\omega = 8$ mm, respectively. When the beam waist radius exceeded 13 mm, the ability of the GS algorithm to improve the OAM purity and velocity accuracy decreased rapidly. Compared to $\omega = 22$ mm, velocimetry accuracy and β increased 1.21-fold and 35.6% at $\omega = 13$ mm, respectively.

At the optimal beam waist radius, the GS phase retrieval algorithm can maximize the recovery of the OAM purity, reduce the amplitude of spurious frequency peaks, and thus improve the velocimetry accuracy. However, this was not evident in the higher-mode vortex beams, possibly because they are more affected by atmospheric turbulence. The GS algorithm is constrained in its ability to recover the distortions in excess spots beyond the optimal waist radius through phase compensation, limiting its effectiveness in enhancing the velocimetry accuracy.

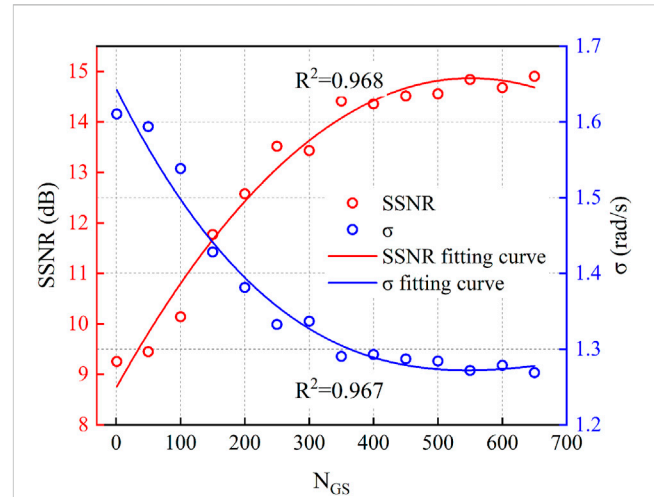


FIGURE 7

Relationships among σ , SSNR, and N_{GS} for the $l = 5$ vortex beam at $z_{S-T} = 500$ m and $C_n^2 = 1 \times 10^{-14} \text{ m}^{-2/3}$. The fit is described in the text.

4.3 Effect of atmospheric turbulence intensity on the GS algorithm to enhance the velocimetry accuracy

Table 2 lists the results for the velocity accuracy enhancement ability of the GS algorithm, which was simulated and analyzed under three relatively strong, moderate, and weak turbulence intensities of the 1st–8th mode vortex beams in the range of $z_{S-T} = 300$ –1,000 m.

Compared to $C_n^2 = 1 \times 10^{-13} \text{ m}^{-2/3}$ and $C_n^2 = 1 \times 10^{-15} \text{ m}^{-2/3}$, phase compensation only achieves a σ_{AIF} of 2.76% and 1.56%, respectively. Remarkably, a σ_{AIF} of 12.5% was achieved at $C_n^2 = 1 \times 10^{-14} \text{ m}^{-2/3}$, and the average velocity measurement error was reduced to its lowest value of 2.23 rad/s. This indicates that the GS algorithm provides excellent measurement accuracy and exercise a more effective compensatory ability under a relatively moderate C_n^2 intensity. The optimal value was subsequently refined by further calculations. Notably, the average velocimetry accuracy improvement factor (σ_{AVIF}) was less than zero at $C_n^2 = 1 \times 10^{-15} \text{ m}^{-2/3}$ because the velocity measurement accuracy of the 1st, 2nd, and 3rd mode vortex beams was superior without the GS algorithm compensation. This observation suggests that in scenarios with a relatively weak atmospheric turbulence intensity, the SSNR closely approximated the values obtained under the non-turbulence condition. The GS algorithm has limited ability to improve the SSNR through phase compensation in relatively weak atmospheric turbulence. Additionally, in scenarios with a strong atmospheric turbulence intensity, significant phase distortion approaches or even surpasses the compensation ability of the GS algorithm, resulting in larger velocity measurement errors.

In Figure 6, when $C_n^2 = 1 \times 10^{-15} \text{ m}^{-2/3}$, the velocity measurement error of the recovered beam is higher than that of the unrecovered beam, corresponding to the finding in Table 2. Within the optimal C_n^2 range of GS algorithm, spanning from 2×10^{-15} to $4 \times 10^{-14} \text{ m}^{-2/3}$, where all $\sigma_{IF} > 9\%$ in this interval, σ_{AIF} is 18.32%. In comparison, the overall σ_{AIF} is only 14.16%. The highest σ_{IF} is 24.15% at $C_n^2 = 6 \times 10^{-15} \text{ m}^{-2/3}$, and the velocimetry accuracy improves to its highest point at 1.18 rad/s. In this region, the velocimetry accuracy of the beam compensated by the GS algorithm has a similar trend as that of

σ_{IF} . Within the C_n^2 range of 4×10^{-14} to $1 \times 10^{-12} \text{ m}^{-2/3}$, the algorithm cannot significantly reduce velocimetry errors as effectively as it does in areas of moderate turbulence intensity, resulting in a decrease of σ_{AIF} to 5%. Compared to $C_n^2 = 1 \times 10^{-12} \text{ m}^{-2/3}$, the velocimetry accuracy at $C_n^2 = 6 \times 10^{-15} \text{ m}^{-2/3}$ is improved by 32.33%. This suggests that the stronger turbulence intensity exerts a significant inhibitory effect to the extent that the ability to improve the velocity measurement accuracy cannot be effectively utilized.

4.4 Effect of the number of GS algorithm iterations to enhance the velocimetry accuracy

Then, we discussed a crucial parameter in the GS algorithm, the number of GS algorithm iterations N_{GS} , and its impact on velocity measurement accuracy and SSNR at $z_{S-T} = 500 \text{ m}$ and $C_n^2 = 1 \times 10^{-14} \text{ m}^{-2/3}$. In Figure 7, the SSNR- N_{GS} and σ - N_{GS} relationship is fitted to a third-order polynomial curve; there is good agreement between the fitting curve and data (with modified goodness-of-fit values of $R^2 = 0.968$ and 0.967 , respectively) after the GS algorithm correction. Both have similar trends and optimal N_{GS} . An increase in N_{GS} initially increases and then stabilizes the SSNR and σ at maximum values of 14.61 dB and 1.28 rad/s, respectively. The optimal number of iterations is determined by identifying the number of iterations with three consecutive SSNR/ σ variation rates of less than 1%. Within the N_{GS} range of 1–350, the SSNR and σ increase rapidly, with average improvements of 32.87% and 12.56%, respectively. In the 350–650 range, the SSNR and σ stabilize with increasing N_{GS} , showing average improvements of 64.24% and 23.24%. Overall, the average improvements are 46.67% and 17.90%, with maximum values of 67.5% and 24.01%, respectively.

We attribute the deviations of the data points from the curves to the random phase fluctuations of the atmospheric turbulence phase screen. This does not have a significantly impact on the overall trend. In the plateau range, the velocity accuracy and SSNR show improved average values of 20.41% and 57.88%, respectively, compared to the values obtained with only one GS iteration. We conclude that the compensation ability of the GS algorithm tends to stabilize when N_{GS} is increased to the point where the SSNR and velocity accuracy enter a smooth phase. This indicates that a further increase in iteration number of the GS algorithm beyond 350 have a limited impact on improving the SSNR and σ of the optical field.

Based on the comprehensive simulation analysis, further investigations were conducted for $z_{S-T} = 500 \text{ m}$ with the reported optimal parameters. The velocity accuracy increased from 1.64 rad/s to 1.15 rad/s, representing a 29.88% improvement. The SSNR increased 1.03-fold, rising from 8.92 dB to 18.14 dB.

Finally, we evaluate the distorted field compensation ability of the GS algorithm within the optimal parameters range and compare it with two other typical algorithms, as summarized in Table 3. Ref. [20] introduced an adaptive optics compensation approach based on the Wirtinger flow algorithm. It can be considered as a gradient descent method with initialization and iteration, effectively preventing convergence to local optimal solutions. Another notable approach, discussed in Ref. [37], involves incorporating Fourier-domain information as input information to the hybrid input-output algorithm (HIOA) to adjust the compensation phase screen. This additional information, combined with distorted light intensity,

results in a substantial enhancement in OAM purity ($\sim 20\% \rightarrow < 70\%$). Both algorithms enhance phase compensation ability through the optimization of iterative processes or the introduction of supplementary compensation information. However, neither discusses the optimal range for the algorithm's application. Compared to other algorithms, a highlight of our work is the outstanding performance of the GS algorithm within the parameter range where it can achieve the optimal improvement in velocity accuracy. The GS algorithm demonstrates a remarkable 20.41% enhancement in velocity accuracy and a substantial 60% improvement in OAM purity. This underscores the significance of our algorithm in achieving optimal improvements in both velocity accuracy and OAM purity, setting it apart from other existing methods.

5 Conclusion

This paper demonstrates the outstanding performance of the GS phase retrieval algorithm to enhance the rotational velocimetry accuracy of distorted vortex beams within an optimal range of intrinsic and extrinsic parameters, as determined through simulation analysis. However, the algorithm's deactivation beyond this range hampers its optimal compensation performance. Despite limitations observed in the simulation results, optimal parameters led to a 29.88% improvement in velocity accuracy and a 1.03-fold improvement in the SSNR. Unlike traditional metrics focusing solely on OAM purity, our study emphasizes SSNR for better distinguishing RDS peak from noise. Our work offers insights applicable to remote precision detection applications in free space. This research contributes to enhancing rotational velocimetry accuracy, with potential implications for diverse remote sensing scenarios.

Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

Author contributions

HW: Conceptualization, Data curation, Formal Analysis, Methodology, Software, Writing—original draft, Investigation. ZZ: Funding acquisition, Project administration, Supervision, Writing—review and editing. HY: Methodology, Investigation, Writing—review and editing. HL: Methodology, Investigation, Writing—review and editing. YZ: Validation, Visualization, Writing—review and editing.

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Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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Supplementary material

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fphy.2023.1333427/full#supplementary-material>

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