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# The coupled Boussinesq equation and its Darboux transformation on the time–space scale

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Gel'fand–Dikii (GD) formalism is an approach for generating integrable systems in terms of fractional powers of the  $\delta$  differential operator. In this paper, it extends the GD formalism associated with the third-order  $\delta$  differential operator  $L$  to the time scale. Then, the coupled Boussinesq equation on the time–space scale is given by taking special values, and it can be reduced on different time–space scales. Moreover, the exact solutions of the coupled Boussinesq equation on the time–space scale and the classical Boussinesq equation are constructed *via* employing the extensions of the Darboux theorem and Crum theorem on the time scale.

## KEYWORDS

Gel'fand–Dikii formalism, Darboux transformation, time–space scale, Boussinesq equation, soliton solution

## 1 Introduction

There are many methods to produce soliton equations, such as the Ablowitz–Kaup–Newell–Segur (AKNS) method [1], Ablowitz–Ladik (AL) method [2], and GD formalism [3]. Compared with the other two methods, the difference of GD formalism is that differential operators, shift operators, and their inverses are regarded as essential tools to generate integrable systems. In this formalism, arbitrary Lax pairs can be constructed from the calculation of fractional powers of the operator  $L$  [4]. In addition, it is also quite significant in studying the symmetries, bi-Hamiltonian formulations, and construction of recursive operators for nonlinear PDE [5–7].

Nevertheless, earlier studies mostly centered on continuous systems or discrete systems. Since there are some complex problems that can only be solved exactly when considering the parallel analysis of continuous and discrete cases, the time scale was initiated by Stefan Hilger in 1988 [8–10]. Recently, soliton equations on time scales have been studied widely [11–14]. Agarwal et al. defined hyperbolic functions on the time scale to solve evolution equations [15]. Gürses et al. extended the GD formalism on the time scale to obtain more universal integrable nonlinear dynamic equations and generated integrable equations in terms of integers  $\mathbb{Z}$  and  $q$ -numbers particularly. On this basis, the  $\Delta$ -Burgers hierarchy and its recursion operator were derived by taking appropriate  $\delta$  differential operators [7]. Ahlbrandt et al. investigated the Hamiltonian system on the time scale and its symplectic flow properties [16].

Darboux theorem was first proposed by Darboux in 1882 from the eigenfunction of the Schrödinger equation and the covariant transformation of potential and applied to surface theory [17]. In 1995, Crum obtained a popularization of the Darboux theorem *via* a recurrent relation from the  $N$ -fold Darboux transformation [18]. The notable merit of DT (Darboux transformation) is that solutions of the soliton equation may be obtained by means of finite iteration, which results it in a research focus of integrable systems in continuous or discrete form [19–23]. A Lax pair for the modified Boussinesq equation and its DT was derived by Geng [24]. Nimmo constructed the DT for the discrete KP equation and reduced to the discrete BKP equation resulting from an invariance of the binary transformation [25]. At present, the DT has been considered on the time scale, and several research results have been acquired. Hovhannisyan et al. obtained a solution of the KdV equation hierarchy from extensions of the Darboux theorem and Crum theorem on the time scale calculus [13]. By using gauge transformation, Dong et al. obtained the DT of the Gerdjikov–Ivanov equation on the time–space scale [26]. However, the DT of integrable systems has still rarely been studied under the unified analysis of continuous systems and discrete systems.

The Boussinesq equation is an important soliton equation [27–29], alongside other important research achievements in physics and mathematics such as one-dimensional nonlinear lattice waves [30, 31], vibrations in a nonlinear string [27], and ion sound waves in plasma [32]. A normative approach was presented to obtain the DT for the classical Boussinesq system by Zhang et al. [33]. In [34], the new solutions of the Boussinesq–Burgers equation were achieved *via* applying a DT with multi-parameters [34]. In order to better promote the research of the Boussinesq equation on the time scale, the coupled Boussinesq equation and its exact solution will be obtained on the time–space scale by extending the GD formalism and Darboux theorem to the time scale in this paper.

This paper is organized as follows. In Section 2, through employing the GD formalism associated with the third-order  $\delta$  differential operator  $L$ , the coupled Boussinesq equation on the time–space scale is produced from its spectral problem. Section 3 presents the exact solutions of the coupled Boussinesq equation on the time–space scale, and the single-soliton solution of the classical Boussinesq equation is achieved on the special time scale  $\mathbb{R}$ . The last section is the conclusion.

## 2 Coupled Boussinesq equation on the time–space scale

In this section, taking special values, we will establish the coupled Boussinesq equation on the time–space scale from the

extension for GD formalism on the time scale. Primarily, we will introduce several notions connected to the time scale [8, 9, 35].

Definition 1. Let  $\mathbb{T}$  be a time scale. For  $s \in \mathbb{T}$ , forward and backward jump operators  $\xi, \zeta: \mathbb{T} \rightarrow \mathbb{T}$  are specified as

$$\xi(s) = \inf\{x \in \mathbb{T}: x > s\}, \quad \zeta(s) = \sup\{x \in \mathbb{T}: x < s\}. \quad (1)$$

Definition 2. Forward and backward jump distance functions  $\mu, \nu: \mathbb{T} \rightarrow [0, +\infty)$  are specified as

$$\mu(s) = \xi(s) - s, \quad \nu(s) = s - \zeta(s), \quad (2)$$

which are also called graininess functions.

Lemma 1. When  $\mathbb{T} = \mathbb{R}, \mathbb{T} = \mathbb{Z}$ , forward jump operators and graininess functions become

$$\begin{aligned} \xi(s) &= \inf(s, -\infty) = s, & \xi(s) &= \inf\{x + 1, x + 2, \dots\} = x + 1, \\ \mu(s) &= \xi(s) - s = 0, & \mu(s) &= \xi(s) - s = 1, \end{aligned} \quad (3)$$

respectively.

**Theorem 1.** Let  $\mathbb{T}^k$  represent Hilger’s truncated set which is composed of  $\mathbb{T}$  removing the largest left-scattered point in  $\mathbb{T}$ , and  $f: \mathbb{T} \rightarrow \mathbb{R}, s \in \mathbb{T}^k$ ,

- (1) when  $f$  is  $\Delta$  differentiable at  $s$ ,  $f$  is continuous at  $s$ ;
- (2) when  $f$  is continuous at  $s$  and  $s$  is right-scattered,  $f$  is  $\Delta$  differentiable at  $s$

$$f^{(s)}(s) = \frac{f(\xi(s)) - f(s)}{\mu(s)};$$

- (3) when  $s$  is right-dense,  $f$  is  $\Delta$  differentiable at  $s$  and the limit

$$\lim_{y \rightarrow s} \frac{f(s) - f(y)}{s - y}$$

exists as a finite number. In this case,  $f^{(s)}(s)$  is equal to this limit;

- (4) when  $f$  is  $\Delta$  differentiable at  $s$ ,

$$f(\xi(s)) := f^\xi(s) = f(s) + \mu(s)f^{(s)}(s).$$

*Remark:* when  $\mathbb{T} = \mathbb{R}, \mathbb{T} = h\mathbb{Z}$ , the  $\Delta$  - derivative  $f^{(s)}(s)$  in (2) becomes

$$\begin{aligned} f^{(s)}(s) &= f_s(s), \\ f^{(s)}(s) &= \frac{f(s+h) - f(s)}{h} \\ &= \frac{Ef - f}{h}, \end{aligned}$$

where  $E$  is the shift operator.

Afterward, the general integrable nonlinear evolution equations on the time–space scale are generated *via* considering Theorem 2 and Theorem 3 [7].

**Theorem 2.** Let the  $N$ th-order  $\delta$  differential operator

$$L = u_N \delta^N + u_{N-1} \delta^{N-1} + u_{N-2} \delta^{N-2} + \dots + u_0, \quad (4)$$

where  $u_j$  ( $j = 0, \dots, N$ ) are  $\Delta$ -smooth functions with the time variable( $t$ ) and space variable( $s$ ). Here, the time variable is taken as continuous. By using the Lax equation

$$\frac{dL}{dt} = [A, L], \quad A = \left(L^{\frac{n}{N}}\right)_{\geq 0}, \quad n = 1, 2, \dots \tag{5}$$

hierarchies of integrable nonlinear evolution equations are produced, where  $n$  is a positive integer not divisible by  $N$ .

**Theorem 3.** Let

$$L^{\frac{1}{3}} = a_1\delta + a_0 + a_{-1}\delta^{-1} + a_{-2}\delta^{-2} + \dots,$$

then, through employing the Gelfand-Dikii formalism on the time scale, the operator  $A$  is obtained:

$$\begin{aligned} A &= \left(L^{\frac{1}{3}}\right)_{\geq 0} \\ &= a_1 a_1^{\xi} \delta^2 + (a_1 a_1^{(s)} + a_1 a_0^{\xi} + a_1 a_0) \delta + a_1 a_0^{(s)} + a_1 a_{-1}^{\xi} + a_0^2 \\ &\quad + a_{-1} a_1^{-\xi}. \end{aligned} \tag{6}$$

When  $N = 3$ , Eq. 4 becomes

$$L = u_3 \delta^3 + u_2 \delta^2 + u_1 \delta + u_0. \tag{7}$$

Then, by substituting Eqs. 6, 7 into Eq. 5, we get

$$\frac{dL}{dt} = \left[\left(L^{\frac{1}{3}}\right)_{\geq 0}, L\right], \tag{8}$$

and the following equations

$$a_1 a_1^{\xi} u_3^{\xi\xi} - (a_1 a_1^{\xi})^{\xi\xi\xi} u_3 = 0, \tag{9}$$

$$\begin{aligned} a_1 a_1^{\xi} (u_3^{(s)\xi} + u_3^{\xi(s)}) - u_3 b_2 + a_1 a_1^{\xi} u_2^{\xi\xi\xi} - u_2 (a_1 a_1^{\xi})^{\xi\xi} \\ + b_1 u_3^{\xi} - u_3 b_1^{\xi\xi\xi} = 0, \end{aligned} \tag{10}$$

$$\begin{aligned} a_1 a_1^{\xi} u_3^{(ss)} + a_1 a_1^{\xi} u_1^{\xi\xi} - u_1 (a_1 a_1^{\xi})^{\xi} + b_1 u_3^{(s)} + b_1 u_2^{\xi} - u_2 b_1^{\xi\xi} \\ - u_3 b_3 + u_3 b_4 = u_{3t}, \end{aligned} \tag{11}$$

$$\begin{aligned} u_1^{\xi(s)} + u_1^{(s)\xi} - u_3 (a_1 a_1^{\xi})^{(sss)} - u_1 (a_1 a_1^{\xi})^{(s)} + a_1 a_1^{\xi} (u_2^{(ss)} + u_0^{\xi\xi} - u_0) \\ + b_1 u_2^{(s)} + b_1 u_1^{\xi} - u_1 b_1^{\xi} - u_2 [(a_1 a_1^{\xi})^{(ss)} + b_1^{(s)\xi} + b_1^{\xi(s)}] \\ - u_3 b_5 + u_2 b_6 = u_{2t}, \end{aligned} \tag{12}$$

$$\begin{aligned} a_1 a_1^{\xi} (u_1^{(ss)} + u_0^{\xi(s)} + u_0^{(s)\xi}) + b_1 u_1^{(s)} - u_1 b_1^{(s)} + b_1 u_0^{\xi} \\ - u_0 b_1 - u_3 b_7 - u_2 b_8 + u_1 b_9 = u_{1t}, \end{aligned} \tag{13}$$

$$a_1 a_1^{\xi} u_0^{(ss)} + b_1 u_0^{(s)} - u_3 b_{10}^{(sss)} - u_2 b_{10}^{(ss)} - u_1 b_{10}^{(s)} = u_{0t}. \tag{14}$$

where

$$\begin{aligned} b_1 &= a_1 a_1^{(s)} + a_1 a_0^{\xi} + a_1 a_0, \\ b_2 &= (a_1 a_1^{\xi})^{\xi\xi(s)} + (a_1 a_1^{\xi})^{\xi(s)\xi} + (a_1 a_1^{\xi})^{(s)\xi\xi}, \\ b_3 &= (a_1 a_1^{\xi})^{(ss)p} + (a_1 a_1^{\xi})^{(s)\xi(s)} + (a_1 a_1^{\xi})^{\xi(ss)} + b_1^{\xi\xi(s)} + b_1^{\xi(s)\xi} + b_1^{(s)\xi\xi}, \\ b_4 &= a_1 a_0^{(s)} - (a_1 a_0^{(s)})^{\xi\xi\xi} + a_1 a_{-1}^{(s)} - (a_1 a_{-1}^{(s)})^{\xi\xi\xi} + a_{-1} a_1^{-\xi-1} - (a_{-1} a_1^{-\xi-1})^{\xi\xi\xi} \\ &\quad + a_0^2 - a_0^{\xi\xi\xi}, \end{aligned}$$

$$\begin{aligned} b_5 &= (a_1 a_0^{(s)})^{(s)\xi\xi\xi} + (a_1 a_0^{(s)})^{\xi\xi(s)} + (a_1 a_0^{(s)})^{\xi(s)\xi} + b_1^{(ss)\xi} + b_1^{(s)\xi(s)} \\ &\quad + b_1^{\xi(ss)} + (a_1 a_{-1}^{\xi})^{\xi\xi(s)} + (a_1 a_{-1}^{\xi})^{\xi(s)\xi} + (a_1 a_{-1}^{\xi})^{(s)\xi\xi} + (a_0^2)^{\xi\xi(s)} \\ &\quad + (a_0^2)^{\xi(s)\xi} + (a_0^2)^{(s)\xi\xi}, \end{aligned}$$

$$\begin{aligned} b_6 &= a_1 a_0^{(s)} - (a_1 a_0^{(s)})^{\xi\xi} + a_1 a_{-1}^{\xi} - (a_1 a_{-1}^{\xi})^{\xi\xi} + a_0^2 - (a_0^{\xi\xi})^2 \\ &\quad + a_{-1} a_1^{-\xi-1} - (a_{-1} a_1^{-\xi})^{\xi\xi}, \end{aligned}$$

$$\begin{aligned} b_7 &= b_1^{(sss)} + (a_1 a_0^{(s)})^{(ss)\xi} + (a_1 a_0^{(s)})^{(s)\xi(s)} + (a_1 a_0^{(s)})^{\xi(ss)} + (a_1 a_{-1}^{\xi})^{(ss)\xi} \\ &\quad + (a_1 a_{-1}^{\xi})^{(s)\xi(s)} + (a_1 a_{-1}^{\xi})^{\xi(ss)} + (a_0^2)^{(ss)\xi} + (a_0^2)^{(s)\xi(s)} + (a_0^2)^{\xi(ss)} \\ &\quad + (a_{-1} a_1^{-\xi-1})^{(ss)\xi} + (a_{-1} a_1^{-\xi-1})^{(s)\xi(s)} + (a_{-1} a_1^{-\xi-1})^{\xi(ss)}, \end{aligned}$$

$$\begin{aligned} b_8 &= b_1^{(ss)} + (a_1 a_0^{(s)})^{(s)\xi} + (a_1 a_0^{(s)})^{\xi(s)} + (a_1 a_{-1}^{\xi})^{(s)\xi} + (a_1 a_{-1}^{\xi})^{\xi(s)} \\ &\quad + (a_0^2)^{(s)\xi} + (a_0^2)^{\xi(s)} + (a_{-1} a_1^{-\xi-1})^{(s)\xi} + (a_{-1} a_1^{-\xi-1})^{\xi(s)}, \end{aligned}$$

$$\begin{aligned} b_9 &= a_1 a_{-1}^{\xi} - (a_1 a_{-1}^{\xi})^{\xi} + a_1 a_0^{(s)} - (a_1 a_0^{(s)})^{\xi} + a_0^2 - (a_0^{\xi})^2 \\ &\quad + a_{-1} a_1^{-\xi-1} - (a_{-1} a_1^{-\xi-1})^{\xi}, \end{aligned}$$

$$b_{10} = a_1 a_0^{(s)} + a_1 a_{-1}^{\xi} + a_0^2 + a_{-1} a_1^{-\xi-1}.$$

Next, by taking  $a_1 = 1$ ,  $a_0 = u_3 = u_2 = 0$ , the coupled Boussinesq equation is obtained on the time-space scale:

$$\begin{aligned} u_{1t} &= u_1^{(ss)} - u_0^{(s)} + a_{-1} u_1 + a_{-1}^{(ss)} - a_{-1}^{\xi\xi(ss)} - u_1 a_{-1}^{\xi\xi}, \\ u_{0t} &= u_0^{(ss)} - u_1^{(sss)} - u_1 u_1^{(s)} + u_1 a_{-1}^{\xi\xi(s)} + a_{-1}^{\xi\xi(ss)}. \end{aligned} \tag{15}$$

In the following, the classical Boussinesq equation and coupled semi-discrete Boussinesq equation are obtained, respectively.

(1) In the case  $\mathbb{T} = \mathbb{R}$ ,  $(t, s) \in \mathbb{R} \times \mathbb{R}$ , we get the coupled Boussinesq equation

$$\begin{aligned} u_{1t} &= u_{1ss} - u_{0s}, \\ u_{0t} &= u_{0ss} - \frac{2}{3} u_{1sss} - \frac{2}{3} u_1 u_{1s}, \end{aligned} \tag{16}$$

then when  $u_1 = u_{0s}$ , the classical Boussinesq equation is obtained:

$$u_{1tt} + 2u_{1ss} - \frac{1}{3} (u_1^2)_{ss} - \frac{5}{3} u_{1sss} = 0. \tag{17}$$

(2) In the case  $\mathbb{T} = \mathbb{Z}$ ,  $(t, s) \in \mathbb{R} \times \mathbb{Z}$ , we have  $\mu(t) = 0$ ,  $\mu(s) = 1$ , and

$$\begin{aligned} f^{\xi}(t, s) &= f(t, s), \\ f^{\xi}(t, s) &= E f(t, s) = f(t, s) + (E - 1) f(t, s). \end{aligned}$$

Therefore, the coupled semi-discrete Boussinesq equation is obtained

$$\begin{aligned} u_{1t} &= (1 - E) u_0 + (E^2 + E + 1)^{-1} u_1^2 - u_1 E^2 (E^2 + E + 1)^{-1} u_1 \\ &\quad + (E - 1)^2 [1 + (E^2 + E + 1)^{-1} - E^2 (E^2 + E + 1)^{-1}] u_1, \\ u_{0t} &= (E - 1)^2 u_0 + (E - 1)^3 [E^2 (E^2 + E + 1)^{-1} - 1] u_1 \\ &\quad + u_1 [(E - 1) E^2 (E^2 + E + 1)^{-1} + (1 - E)] u_1. \end{aligned} \tag{18}$$

### 3 The exact solutions of the coupled Boussinesq equation on the time-space scale

In the following, the exact solutions of the coupled Boussinesq equation on the time-space scale and classical

Boussinesq equation will be obtained based on the extension of the DT on the time scale.

**Theorem 4.** [13] If functions  $\psi_1(t, s), \psi(t, s)$  satisfy

$$L\psi_1 = \lambda_1\psi_1, \quad L\psi = \lambda\psi,$$

then the function

$$\psi[1] = Q_1\psi = \frac{W[\psi_1, \psi]}{\psi_1}, \quad Q_1 := \delta - d_1, \quad d_1 := \frac{\psi_1^{(s)}}{\psi_1}$$

is a solution of

$$L[1]\psi[1] = \lambda\psi[1],$$

where

$$L[1] = \sum_{k=0}^N u_k[1]\delta^k,$$

$$u_p[1] = u_p^\xi + Q_1u_{p+1} + \sum_{k=p+1}^n u_k[1] \sum_{M \in S_{p+1}^k} d^M, \quad p = 0, \dots, N,$$

with  $S_j^k$  being specified as the set containing the whole probable strings of length  $k$  that include  $j$   $\xi$ s and  $k-j$   $\delta$ s exactly.

Considering Lax pairs

$$L[0]\psi(t, s) = \lambda\psi(t, s), \quad A[0]\psi(t, s) = \psi_t(t, s), \quad (19)$$

where

$$L[0] = u_3[0]\delta^3 + u_2[0]\delta^2 + u_1[0]\delta + u_0[0], \\ A[0] = a_1[0]a_1^\xi[0]\delta^2 + (a_1[0]a_1^{(s)}[0] + a_1[0]a_0^\xi[0] + a_1[0]a_0[0])\delta \\ + a_1[0]a_0^{(s)}[0] + a_1[0]a_{-1}^\xi[0] + a_0^2[0] + a_{-1}[0]a_1^{\xi^{-1}}[0].$$

Let  $a_{-1}[0] = a_0[0] = 0, u_2[0] = u_1[0] = u_0[0] = 0$ . Taking eigenfunctions  $\psi$  and  $\psi_1$  of Eq. 19 with eigenvalues  $\lambda$  and  $\lambda_1$ , we get

$$u_3[0]\delta^3\psi = \lambda\psi, \quad (a_1[0]a_1^\xi[0])\delta^2\psi = \psi_t, \quad (20)$$

$$u_3[0]\delta^3\psi_1 = \lambda_1\psi_1, \quad (a_1[0]a_1^\xi[0])\delta^2\psi_1 = \psi_{1t}. \quad (21)$$

By using Theorem 4, the one-fold DT is constructed:

$$\psi[1] = Q_1\psi, \quad Q_1 = \delta - d_1, \quad d_1 = \frac{\psi_1^{(s)}}{\psi_1},$$

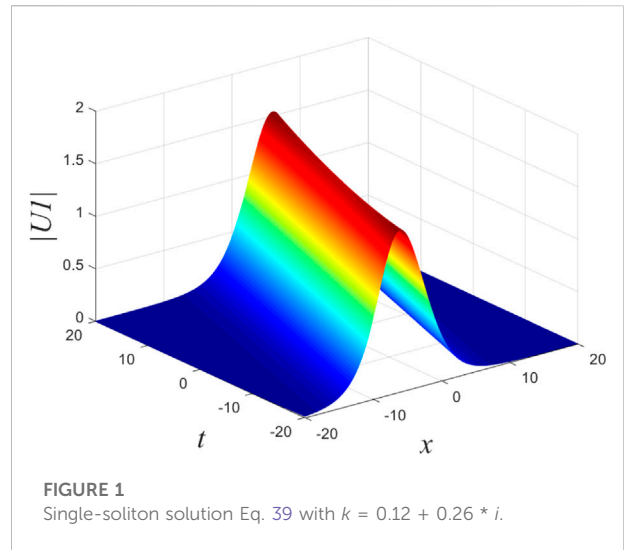
then

$$L[1]\psi[1] = \lambda\psi[1], \quad A[1]\psi[1] = \psi_t[1], \quad (22)$$

where

$$L[1] = u_3[1]\delta^3 + u_2[1]\delta^2 + u_1[1]\delta + u_0[1], \\ A[1] = a_1[1]a_1^\xi[1]\delta^2 + (a_1[1]a_1^{(s)}[1] + a_1[0]a_0^\xi[1] + a_1[1]a_0[1])\delta \\ + a_1[1]a_0^{(s)}[1] + a_1[1]a_{-1}^\xi[1] + a_0^2[1] + a_{-1}[1]a_1^{\xi^{-1}}[1], \quad (23)$$

with



**FIGURE 1** Single-soliton solution Eq. 39 with  $k = 0.12 + 0.26 * i$ .

$$u_3[1] = u_3^\xi[0], \\ u_2[1] = Q_1u_3[0] + u_3^\xi[0]d_1^{\xi\xi\xi}, \\ u_1[1] = u_2[1]d_1^{\xi\xi} + u_3[1](d_1^{(s)\xi\xi} + d_1^{\xi(s)\xi} + d_1^{\xi\xi(s)}), \\ u_0[1] = u_1[1]d_1^\xi + u_2[1](d_1^{(s)\xi} + d_1^{\xi(s)}) \\ + u_3[1](d_1^{(ss)\xi} + d_1^{(s)\xi(s)} + d_1^{\xi(ss)}). \quad (24)$$

Thus, Eq. 24 is the solution to Eqs. 11–14:

$$u_{3t}[1] = a_1[1]a_1^\xi[1]u_3^{(ss)}[1] + a_1[1]a_1^\xi[1]u_1^{\xi\xi}[1] \\ - u_1[1](a_1[1]a_1^\xi[1])^\xi + b_1[1]u_3^{(s)}[1] + b_1[1]u_2^\xi[1] \\ - u_2[1]b_1^{\xi\xi}[1] - u_3[1]b_3[1] + u_3[1]b_4[1], \quad (25)$$

$$u_{2t}[1] = -u_3[1](a_1[1]a_1^\xi[1])^{(sss)} - u_1[1](a_1[1]a_1^\xi[1])^{(s)} \\ + b_1[1]u_2^{(s)}[1] + b_1[1]u_1^\xi[1] - u_1[1]b_1^\xi[1] + a_1[1]a_1^\xi[1] \\ \times (u_2^{(ss)}[1] + u_1^{\xi(s)}[1] + u_1^{(s)\xi}[1] + u_0^{\xi\xi}[1] - u_0[1]) \\ - u_3[1]b_5[1] + u_2[1]b_6[1] - u_2[1] \\ \times [(a_1[1]a_1^\xi[1])^{(ss)} + b_1^{(s)\xi}[1] + b_1^{\xi(s)}[1]], \quad (26)$$

$$u_{1t}[1] = a_1[1]a_1^\xi[1](u_1^{(ss)}[1] + u_0^{\xi(s)}[1] + u_0^{(s)\xi}[1]) - u_2[1]b_8[1] \\ - u_1[1]b_1^{(s)}[1] - u_0[1]b_1[1] + b_1[1]u_0^\xi[1] - u_3[1]b_7[1] \\ + b_1[1]u_1^{(s)}[1] + u_1[1]b_9[1], \quad (27)$$

$$u_{0t}[1] = a_1[1]a_1^\xi[1]u_0^{(ss)}[1] + b_1[1]u_0^{(s)}[1] - u_3[1]b_{10}^{(sss)}[1] \\ - u_2[1]b_{10}^{(ss)}[1] - u_1[1]b_{10}^{(s)}[1], \quad (28)$$

where

$$\begin{aligned}
 b_1[1] &= a_1[1]a_1^{(s)}[1] + a_1[1]a_0^\xi[1] + a_1[1]a_0[1], \\
 b_2[1] &= (a_1[1]a_1^\xi[1])^{\xi\xi(s)} + (a_1[1]a_1^\xi[1])^{\xi(s)\xi} + (a_1[1]a_1^\xi[1])^{(s)\xi\xi}, \\
 b_3[1] &= (a_1[1]a_1^\xi[1])^{(ss)\xi} + (a_1[1]a_1^\xi[1])^{(s)\xi(s)} + (a_1[1]a_1^\xi[1])^{\xi(s)s} \\
 &\quad + b_1^{\xi\xi(s)}[1] + b_1^{\xi(s)\xi}[1] + b_1^{(s)\xi\xi}[1], \\
 b_4[1] &= a_1[1]a_0^{(s)}[1] - (a_1[1]a_0^{(s)}[1])^{\xi\xi\xi} + a_1[1]a_{-1}^{(s)}[1] \\
 &\quad - (a_1[1]a_{-1}^{(s)}[1])^{\xi\xi\xi} - a_0^{\xi\xi\xi}[1] + a_{-1}[1]a_1^{\xi-1}[1] \\
 &\quad - (a_{-1}[1]a_1^{\xi-1}[1])^{\xi\xi\xi} + a_0^2[1], \\
 b_5[1] &= (a_1[1]a_0^{(s)}[1])^{(s)\xi\xi} + (a_1[1]a_0^{(s)}[1])^{\xi\xi(s)} \\
 &\quad + (a_1[1]a_0^{(s)}[1])^{\xi(s)\xi} + b_1^{(ss)[1]\xi} + (a_1[1]a_{-1}^\xi[1])^{\xi\xi(s)} \\
 &\quad + (a_1[1]a_{-1}^\xi[1])^{\xi(s)\xi} + (a_1[1]a_{-1}^\xi[1])^{(s)\xi\xi} + (a_0^2[1])^{\xi\xi(s)} \\
 &\quad + (a_0^2[1])^{(s)\xi\xi} + b_1^{(s)\xi(s)}[1] + b_1^{\xi(ss)}[1] + (a_0^2[1])^{\xi(s)\xi}, \\
 b_6[1] &= a_1[1]a_0^{(s)}[1] - (a_1[1]a_0^{(s)}[1])^{\xi\xi} + a_1[1]a_{-1}^\xi[1] \\
 &\quad - (a_1[1]a_{-1}^\xi[1])^{\xi\xi} + a_0^2[1] - (a_{-1}[1]a_1^\xi[1])^{\xi\xi} \\
 &\quad + a_{-1}[1]a_1^{\xi-1}[1] - (a_0^{\xi\xi})^2[1], \\
 b_7[1] &= b_1^{(sss)}[1] + (a_1[1]a_0^{(s)}[1])^{(ss)\xi} + (a_1[1]a_0^{(s)}[1])^{(s)\xi(s)} \\
 &\quad + (a_1[1]a_0^{(s)}[1])^{\xi(ss)} + (a_1[1]a_{-1}^\xi[1])^{(s)\xi(s)} \\
 &\quad + (a_1[1]a_{-1}^\xi[1])^{\xi(ss)} + (a_0^2[1])^{(ss)\xi} + (a_0^2[1])^{(s)\xi(s)} \\
 &\quad + (a_{-1}[1]a_1^{\xi-1}[1])^{(ss)\xi} + (a_{-1}[1]a_1^{\xi-1}[1])^{(s)\xi(s)} \\
 &\quad + (a_{-1}[1]a_1^{\xi-1}[1])^{\xi(ss)} + (a_0^2[1])^{\xi(ss)} + (a_1[1]a_{-1}^\xi[1])^{(ss)\xi}, \\
 b_8[1] &= b_1^{(ss)[1]} + (a_1[1]a_0^{(s)}[1])^{(s)\xi} + (a_1[1]a_0^{(s)}[1])^{\xi(s)} \\
 &\quad + (a_1[1]a_{-1}^{(s)}[1])^{(s)\xi} + (a_1[1]a_{-1}^{(s)}[1])^{\xi(s)} \\
 &\quad + (a_{-1}[1]a_1^{\xi-1}[1])^{(s)\xi} + (a_{-1}[1]a_1^{\xi-1}[1])^{\xi(s)} + (a_0^2[1])^{\xi(s)} \\
 &\quad + (a_0^2[1])^{(s)\xi}, \\
 b_9[1] &= a_1[1]a_{-1}^\xi - (a_1[1]a_{-1}^\xi)^\xi + a_1[1]a_0^{(s)} - (a_1[1]a_0^{(s)}[1])^\xi \\
 &\quad + a_0^2[1] - (a_0^\xi[1])^2 + a_{-1}[1]a_1^{\xi-1}[1] - (a_{-1}[1]a_1^{\xi-1}[1])^\xi, \\
 b_{10}[1] &= a_1[1]a_0^{(s)}[1] + a_1[1]a_{-1}^\xi[1] + a_0^2[1] + a_{-1}[1]a_1^{\xi-1}[1].
 \end{aligned}$$

Taking the eigenfunction  $\psi_2$  of Eq. 19 with the eigenvalue  $\lambda_2$  and applying Theorem 4., we get the two-fold DT:

$$\psi[2] = Q_2\psi[1] = Q_2Q_1\psi, \quad Q_2 = \delta - d_2, \quad d_2 = \frac{\psi_2^{(s)}[1]}{\psi_2[1]},$$

then

$$\begin{aligned}
 u_3[2] &= u_3^\xi[1], \\
 u_2[2] &= u_2^\xi[1] + Q_2u_3[1] + u_3^\xi[0]d_2^{\xi\xi\xi}, \\
 u_1[2] &= u_1^\xi[1] + Q_2u_2[1] + u_2[2]d_2^{\xi\xi} \\
 &\quad + u_3[2](d_2^{(s)\xi\xi} + d_2^{\xi(s)\xi} + d_2^{\xi\xi(s)}), \\
 u_0[2] &= u_0^\xi[1] + Q_2u_1[1] + u_1[2]d_2^\xi \\
 &\quad + u_3[2](d_2^{(ss)\xi} + d_2^{(s)\xi(s)} + d_2^{\xi(ss)}) \\
 &\quad + u_2[2](d_2^{(s)\xi} + d_2^{\xi(s)}).
 \end{aligned} \tag{29}$$

Similarly, we take the eigenfunction  $\psi_N$  of Eq. 19 with the eigenvalue  $\lambda_N$ . The  $N$ -fold DT is constructed:

$$\psi[N] = Q_N \cdots Q_1\psi = \frac{W[\psi_1, \dots, \psi_N, \psi]}{W[\psi_1, \dots, \psi_N]}, \tag{30}$$

and so

$$\begin{aligned}
 u_3[N] &= u_3^\xi[N-1], \\
 u_2[N] &= u_2^\xi[N-1] + Q_2u_3[N-1] + u_3^\xi[N-2]d_N^{\xi\xi\xi}, \\
 u_1[N] &= u_1^\xi[N-1] + Q_2u_2[N-1] + u_2[N]d_N^{\xi\xi} + u_3[N] \\
 &\quad \times (d_N^{(s)\xi\xi} + d_N^{\xi(s)\xi} + d_N^{\xi\xi(s)}), \\
 u_0[N] &= u_0^\xi[N-1] + Q_2u_1[N-1] + u_1[N]d_N^{\xi} + u_3[N] \\
 &\quad \times (d_N^{(ss)\xi} + d_N^{(s)\xi(s)} + d_N^{\xi(ss)}) \\
 &\quad + u_2[N](d_N^{(s)\xi} + d_N^{\xi(s)}).
 \end{aligned} \tag{31}$$

In particular, taking seed solutions of Eqs. 11–14

$$\begin{aligned}
 a_{-1}[0] &= a_0[0] = 0, \quad a_1[0] = 1, \\
 u_0[0] &= u_1[0] = u_2[0] = 0, \quad u_3[0] = 1,
 \end{aligned} \tag{32}$$

we obtain

$$u_3[1] = u_3^\xi[0] = 1, \tag{33}$$

$$u_2[1] = \nu(d_1 + d_1^\xi + d_1^{\xi\xi})^{(s)}, \tag{34}$$

$$u_1[1] = \nu(d_1 + d_1^\xi + d_1^{\xi\xi})^{(s)}d_1^{\xi\xi} + d_1^{(s)\xi\xi} + d_1^{\xi(s)\xi} + d_1^{\xi\xi(s)}, \tag{35}$$

$$\begin{aligned}
 u_0[1] &= \nu(d_1 + d_1^\xi + d_1^{\xi\xi})^{(s)}(d_1^{\xi\xi}d_1^\xi + d_1^{(s)\xi} + d_1^{\xi(s)}) \\
 &\quad + (d_1^{(s)\xi\xi} + d_1^{\xi(s)\xi} + d_1^{\xi\xi(s)})(1 + d_1^\xi).
 \end{aligned} \tag{36}$$

When  $\nu \neq 0$ , Eqs. 35, 36 are exact solutions of the coupled Boussinesq equation on the time–space scale Eq. 15:

$$\begin{aligned}
 u_{1t}[1] &= u_1^{(ss)}[1] - u_0^{(s)}[1] + a_{-1}[1]u_1[1] \\
 &\quad + a_{-1}^{(ss)}[1] - a_{-1}^{\xi\xi(ss)}[1] - u_1[1]a_{-1}^{\xi\xi}[1], \\
 u_{0t}[1] &= u_0^{(ss)}[1] - u_1^{(sss)}[1] - u_1u_1^{(s)}[1] \\
 &\quad + u_1[1]a_{-1}^{\xi\xi(s)}[1] + a_{-1}^{\xi\xi(sss)}[1].
 \end{aligned} \tag{37}$$

When  $\nu = 0$ , we get the eigenfunction  $\psi_1$  of Eq. 17 with the eigenvalue  $\lambda_1 = k^3$

$$\psi_1 = e^{\alpha_1 t + \beta_1 s} + e^{\alpha_2 t + \beta_2 s}, \tag{38}$$

where

$$\begin{aligned}
 \alpha_1 &= \frac{k^2(i + \sqrt{3})}{-\sqrt{3} + i}, \quad \alpha_2 = \frac{k^2(i - \sqrt{3})}{\sqrt{3} + i}, \quad \beta_1 = -\frac{2ik}{-\sqrt{3} + i}, \\
 \beta_2 &= -\frac{2ik}{\sqrt{3} + i},
 \end{aligned}$$

then the single-soliton solution of the classical Boussinesq Eq. 17 is obtained:

$$u_1[1] = 3d_{1s} = 3(\beta_1^2 + \beta_2^2 - 2) \frac{e^{(\alpha_1 + \alpha_2)t + (\beta_1 + \beta_2)s}}{(e^{\alpha_1 t + \beta_1 s} + e^{\alpha_2 t + \beta_2 s})^2}. \tag{39}$$

The dynamics image of the single-soliton solution of Eq. 39 is shown in Figure 1.

## 4 Conclusion

The general coupled nonlinear integrable evolution equations and their  $N$ -soliton solutions on the time–space scale are formulated *via* employing the extensions of the GD formalism and standard DT on the time scale. By taking special values, we derive the Boussinesq equation on the time–space scale, and then, the classical Boussinesq equation and coupled semi-discrete Boussinesq equation are obtained by considering the continuous time scale  $\mathbb{R}$  and discrete time scale  $\mathbb{Z}$ , respectively. Afterward, the exact solutions of the Boussinesq equation on the time–space scale are acquired *via* applying its DT, and the single-soliton solution of the classical Boussinesq equation is obtained as the special case. The extensions may supply more nonlinear integrable models and facilitate solving some practical problems unifying continuous and discrete cases. In the next, we will use the generalization of the GD formalism and DT to construct different integrable systems on time–space scales with other the higher-order  $\delta$  differential operator so as to enrich the research of integrable systems on arbitrary time–space scales.

## Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material; further inquiries can be directed to the corresponding author.

## Author contributions

XH, YZ, and HD contributed to the conception and design of the study. XH and YZ wrote sections of the manuscript. All authors contributed to manuscript revision, read, and approved the submitted version.

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## Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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