



# Vibration Isolation of a Rubber-Concrete Alternating Superposition In-Filled Trench for Train-Induced Environmental Vibration Based on 2.5D Indirect Boundary Element Method

Liguo Jin<sup>1</sup>, Jingya Wang<sup>2\*</sup>, Xujin Liu<sup>3</sup>, Qiangqiang Li<sup>2</sup> and Zhenghua Zhou<sup>3,4</sup>

<sup>1</sup>Institute of Geophysics, China Earthquake Administration, Beijing, China, <sup>2</sup>Department of Civil Engineering, Shanxi Agricultural University, Jinzhong, China, <sup>3</sup>School of Transportation Engineering, Nanjing Tech University, Nanjing, China, <sup>4</sup>Institute of Engineering Mechanics, Nanjing Tech University, Nanjing, China

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### \*Correspondence:

Jingya Wang  
jingyawang1220@163.com

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A new train-induced vibration isolation measure of rubber-concrete alternating superposition in-filled trench is presented in this paper. For analyzing the vibration isolation effect of the new measure, this paper establishes a 2.5D train-track-layered foundation-filled trench model to analyze the dynamics of track and layered foundation with the in-filled trench. The correctness of the model is verified by using the measured data of the Sweden X-2000 high-speed train. The vibration isolation effect of the rubber-concrete alternating superposition in-filled trench is calculated by using the actual soft soil foundation parameters of the X-2000 high-speed train, and the vibration isolation effect is also compared with that of the empty trench, rubber in-filled trench, and concrete in-filled trench. The results show that the vibration isolation effect of the rubber-concrete alternating superposition in-filled trench proposed in this paper is better than that of the C30 concrete in-filled trench, especially the impact on displacement. Compared with low-frequency vibrations generated by the lower train speed, the rubber-concrete alternating superposition in-filled trench has a better vibration isolation effect on high-frequency vibrations caused by higher-speed trains. The rubber-concrete alternately superposition in-filled trench has the frequency band characteristics of elastic waves. Elastic waves in the passband frequency range can propagate without attenuation, while the elastic waves in the forbidden frequency range will be filtered out.

**Keywords:** rubber-concrete alternating superposition in-filled trench, isolation trench, trains moving loads, 2.5D indirect boundary element method (IBEM), layered foundation

## INTRODUCTION

With the large-scale construction of rail transit, the environmental vibration induced by train operation has attracted more and more attention. Research on vibration isolation of environmental vibration induced by train operation plays a guiding role in the design and construction of rail transit, and can effectively improve the quality of life of residents near the railway.

In the past, train vibration isolation was mainly by excavating a vibration isolation trench, and the trench was usually empty or in-filled with concrete. In 1968, Woods [1] was the first to summarize the basic criteria for barrier vibration isolation trench design through many experiments. Yang and Hung [2] conducted a parameter analysis on vibration isolation effects of empty trench and concrete in-filled trench. With [3] studied the isolation effect of vibration isolation measures on far-field vibration caused by trains. Since then, scholars have analyzed the vibration isolation efficiency of empty trench and concrete in-filled trench in the uniform half-space foundation [4–9], the layered half-space foundation [10–15], the homogeneous saturated foundation [16–22], and the layered saturated soil foundation under moving loads.

The above studies are all aimed at empty trenches and concrete in-filled trench, which sometimes fail to achieve a good vibration isolation effect [23–28]. For this reason, this paper puts forward the vibration isolation measures of rubber-concrete alternating superposition in-filled trench. In this paper, a 2.5D train-track-layered foundation-filled trench model is established to analyze the dynamics of track and layered foundation with the in-filled trench, and the correctness of the model is verified by using the measured data of Sweden X2000 high-speed train. Finally, the vibration isolation efficiency of rubber-concrete alternating superposition in-filled trench is calculated using the actual soft soil foundation parameters of Sweden X2000 high-speed train, and the vibration isolation efficiency is compared with that of the empty trench, rubber in-filled trench, and concrete in-filled trench.

## MODEL AND METHODOLOGY

As shown in **Figure 1A**, the train tracks are laid on a layered foundation including a rubber-concrete alternating superposition in-filled trench. The in-filled trench is  $W$  in width and  $H$  in depth and is parallel to the train track with the distance  $D$ . The train track is simulated as a Euler beam with bending stiffness  $EI$ , mass  $m_b$  per unit length, and width  $B$  ( $B = 2\Delta$ ). The layered ground is formed by  $N$  horizontal layers and the underlying half-space. Each of the  $N$  soil layers is assumed to be slightly dissipative and is characterized by the shear wave velocity  $\beta_s^{Li}$ , the mass density  $\rho_s^{Li}$ , Poisson's ratio  $\nu_s^{Li}$ , and the hysteretic damping ratio  $\xi_s^{Li}$  ( $i = 1, 2, 3 \dots N$ ). The underlying half-space is characterized by the complex S-wave velocity  $\beta_s^R$ , the mass density  $\rho_s^R$ , Poisson's ratio  $\nu_s^R$ , and the hysteretic damping ratio  $\xi_s^R$ . The rubber-concrete alternating superposition in-filled trench is composed of  $M$  rubber-concrete superposition layers. Each of the  $M$  rubber-concrete superposition layers is characterized by the shear wave velocity  $\beta_t^j$ , the mass density  $\rho_t^j$ , Poisson's ratio  $\nu_t^j$ , and the hysteretic damping ratio  $\xi_t^j$  ( $j = 1, 2, 3 \dots M$ ). Point  $P_1$  ( $x = 10\text{ m}$ ,  $y = 0\text{ m}$ ,  $z = 0\text{ m}$ ) is the observation point.

When solving the flexibility of the layered elastic foundation with an in-filled trench under the moving load, one section of the vertical track can be used for the solution, and the dynamic response caused by the moving load at the section can be calculated. Then, according to the speed of the train, the remaining cross-sections are shifted to the corresponding phase, and the dynamic response generated at the other cross-

sections is obtained. For solving the flexibility of the layered half-space with in-filled trench under moving load, this paper divides the layered half-space with in-filled trench into two parts: the layered half-space outside the in-filled trench and the soil layer inside the in-filled trench. The total wave field of the layered elastic half-space outside the in-filled trench includes the free field and the scattered wavefield, and the wavefield of the soil layer inside the in-filled trench only includes the scattered wave field. The free wave field is defined as the dynamic response (displacement and stress) of a layered half-space without an in-filled trench under a moving load, which is solved by the direct stiffness method. The scattered wavefield is defined as the additional wavefield generated by the scattering due to the existence of the in-filled trench, which is simulated by applying two sets of virtual moving uniformly distributed line loads on the boundary of the in-filled trench. This method is called the moving Green's function method. The density of the virtual moving uniformly distributed line loads can be determined by the corresponding boundary conditions. Finally, the total wave field of the layered elastic half-space outside the in-filled trench is the superposition of the free wave field and the scattered wavefield, that is, the flexibility of the layered elastic half-space containing the in-filled trench under the action of moving uniformly distributed vertical load is obtained.

## The Flexibility of the Layered Half-Space with In-Filled Trench

The stiffness matrix given in [29] can be adopted for the dynamic stiffness matrix of the 3D layered foundation  $[M_{P,SV,SH}]$ . If the uniform distributed vertical load moving along the  $y$ -axis direction has a distribution length of  $2\Delta$  along the  $x$ -axis direction, the density is  $q_0$ , which can be expressed as

$$q(x, y, t) = q_0 \delta(y - ct) \phi(x), \tag{1}$$

where  $\delta$  is the Dirac function;  $\phi(x)$  is the distribution function, when  $|x| \leq \Delta$ ,  $\phi(x) = 1$ , otherwise  $\phi(x) = 0$ ;  $c$  is the speed of the moving load. The Fourier transform of **Eq. 1** can be obtained as

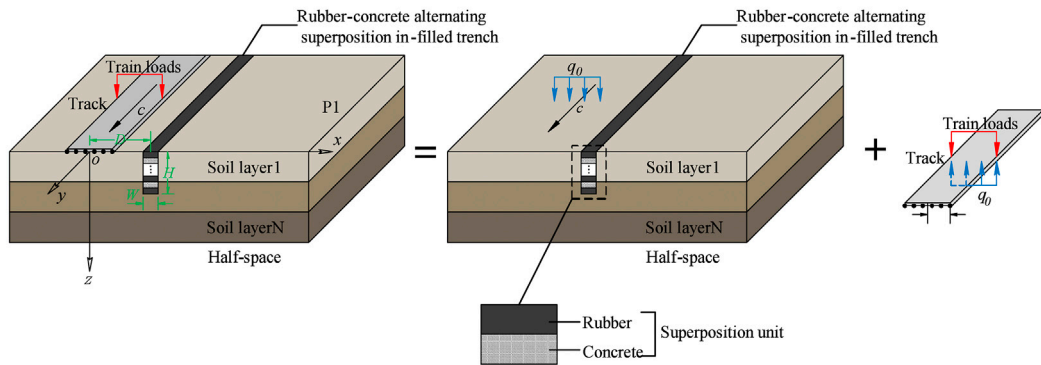
$$\begin{aligned} \bar{q}(k_x, k_y, \omega) &= \frac{1}{8\pi^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\Delta}^{\Delta} q \cdot e^{\exp(i\omega t - ik_x x - ik_y y)} dx dy dt \\ &= \frac{q_0 \sin(k_x \Delta)}{4\pi^2 k_x c} \delta\left(k_y - \frac{\omega}{c}\right), \end{aligned} \tag{2}$$

Here,  $k_x$  and  $k_y$  are the wavenumbers in the  $x$  and  $y$  directions, and  $\omega$  is the circular frequency. In the layered elastic foundation, the external force and displacement on the interface of each soil layer satisfy the equilibrium equation [30] as

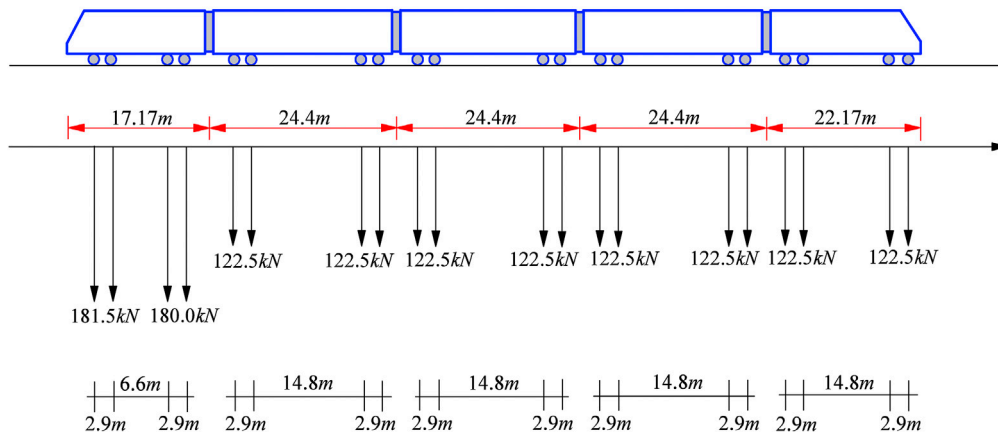
$$\begin{aligned} \{\bar{w}_{x0}, \bar{w}_{y0}, i\bar{w}_{z0}, \dots, \bar{w}_{xN}, \bar{w}_{yN}, i\bar{w}_{zN}\} \\ = [M_{P,SV,SH}]^{-1} \{0, 0, i\bar{q}, \dots, 0, 0, 0\}. \end{aligned} \tag{3}$$

Among them,  $\{\bar{w}_{x0}, \bar{w}_{y0}, i\bar{w}_{z0}, \dots, \bar{w}_{xN}, \bar{w}_{yN}, i\bar{w}_{zN}\}$  is the displacement amplitude vector at the interface of the soil layer, and  $\{0, 0, i\bar{q}, \dots, 0, 0, 0\}$  is the external force vector at the interface

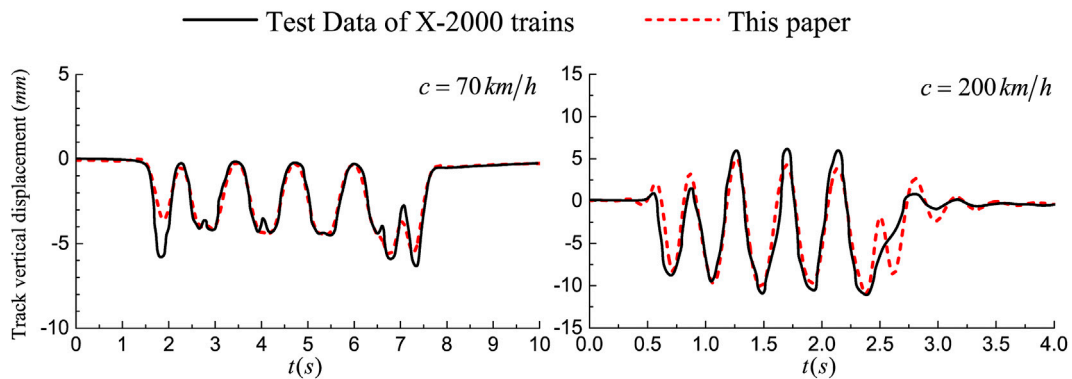
**A 2.5D dynamic interaction model of the train-track-layered half space-filled trench system**



**B X-2000 train geometry and axle loads**



**C Comparisons between our results and the test data of X-2000 trains**



**FIGURE 1 |** Model information.

of the soil layer. Considering that there is only the vertical load on the surface, only the third element has a value, and the other elements are zero.  $[M_{P,SV,SH}]$  is the 3D stiffness matrix of the

layered half-space. Substituting **Eq. 2** into **Eq. 3**, the displacement on the interface of each soil layer can be obtained. Subsequently, the amplitude of the upward and downward waves in each soil

layer can be obtained from the relationship between the amplitude of the upward and downward waves in each soil layer and the displacement at the interface of each soil layer. Finally, the displacement  $\{\tilde{\tilde{w}}_{xf}, \tilde{\tilde{w}}_{yf}, \tilde{\tilde{w}}_{zf}\}^T$  and stress  $\{\tilde{\tilde{T}}_{xf}, \tilde{\tilde{T}}_{yf}, \tilde{\tilde{T}}_{zf}\}^T$  of any point in the frequency-wavenumber domain can be obtained from the relationship between the displacement and stress and the amplitude of the up and down waves.

For the scattered wavefield caused by the in-filled trench, let  $[G_u^D(x, y, z)]$ ,  $[G_t^D(x, y, z)]$  be the displacement and stress Green's function matrixes in the outer half-space of the in-filled trench and  $[G_u^S(x, y, z)]$ ,  $[G_t^S(x, y, z)]$  be the displacement and stress Green's function matrixes in the inner half-space of the in-filled trench, respectively [31]; then, the displacement and stress of any point outside and inside the in-filled trench can be expressed as

$$\{\tilde{w}_{xg}^D, \tilde{w}_{yg}^D, \tilde{w}_{zg}^D\}^T = [G_u^D(x, y, z)]\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T, \tag{4a}$$

$$\{\tilde{T}_{xg}^D, \tilde{T}_{yg}^D, \tilde{T}_{zg}^D\}^T = [G_t^D(x, y, z)]\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T, \tag{4b}$$

$$\{\tilde{w}_{xg}^S, \tilde{w}_{yg}^S, \tilde{w}_{zg}^S\}^T = [G_u^S(x, y, z)]\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T, \tag{4c}$$

$$\{\tilde{T}_{xg}^S, \tilde{T}_{yg}^S, \tilde{T}_{zg}^S\}^T = [G_t^S(x, y, z)]\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T. \tag{4d}$$

Here, the subscripts "u" and "t", respectively, represent the displacement and stress Green's function; the subscript "G" represents the dynamic response caused by the moving uniform distributed line load; the superscripts "D" and "S", respectively, represent the layered elastic half-space outside the in-filled trench and the elastic soil layer inside the in-filled trench.  $\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T$  and  $\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T$  are virtual distributed line load.

The continuous conditions of stress and displacement on the interface  $s$  of the in-filled trench can be expressed as

$$\int_s [W(s)]^T \left( \begin{bmatrix} \tilde{T}_{xg}^D(s) \\ \tilde{T}_{yg}^D(s) \\ \tilde{T}_{zg}^D(s) \end{bmatrix} + \begin{bmatrix} \tilde{T}_{xf}(s) \\ \tilde{T}_{yf}(s) \\ \tilde{T}_{zf}(s) \end{bmatrix} \right) ds = \int_s [W(s)]^T \begin{bmatrix} \tilde{T}_{xg}^S(s) \\ \tilde{T}_{yg}^S(s) \\ \tilde{T}_{zg}^S(s) \end{bmatrix} ds, \tag{5a}$$

$$\int_s [W(s)]^T \left( \begin{bmatrix} \tilde{w}_{xg}^D(s) \\ \tilde{w}_{yg}^D(s) \\ \tilde{w}_{zg}^D(s) \end{bmatrix} + \begin{bmatrix} \tilde{w}_{xf}(s) \\ \tilde{w}_{yf}(s) \\ \tilde{w}_{zf}(s) \end{bmatrix} \right) ds = \int_s [W(s)]^T \begin{bmatrix} \tilde{w}_{xg}^S(s) \\ \tilde{w}_{yg}^S(s) \\ \tilde{w}_{zg}^S(s) \end{bmatrix} ds. \tag{5b}$$

Here,  $\tilde{T}_{xg}^D(s)$ ,  $\tilde{T}_{yg}^D(s)$ ,  $\tilde{T}_{zg}^D(s)$ ,  $\tilde{w}_{xg}^D(s)$ ,  $\tilde{w}_{yg}^D(s)$ , and  $\tilde{w}_{zg}^D(s)$  are the stress and displacement along the  $x$ -,  $y$ -, and  $z$ -coordinate directions generated by the layered elastic half-space out of the in-filled trench acting on each element of the in-filled trench boundary.  $\tilde{T}_{xg}^S(s)$ ,  $\tilde{T}_{yg}^S(s)$ ,  $\tilde{T}_{zg}^S(s)$ ,  $\tilde{w}_{xg}^S(s)$ ,  $\tilde{w}_{yg}^S(s)$ , and  $\tilde{w}_{zg}^S(s)$  are the stress and displacement along the  $x$ -,  $y$ -, and  $z$ -coordinate directions generated by the layered elastic half-space inner of the in-filled trench acting on each element of the in-filled trench boundary.  $\tilde{T}_{xf}(s)$ ,  $\tilde{T}_{yf}(s)$ ,  $\tilde{T}_{zf}(s)$ ,  $\tilde{w}_{xf}(s)$ ,  $\tilde{w}_{yf}(s)$ , and  $\tilde{w}_{zf}(s)$

are the stress and displacement along the  $x$ -,  $y$ -, and  $z$ -coordinate directions generated by the free field on each element at the boundary of the in-filled trench.  $[W(s)]$  is the weight function matrix, which can be taken as the unit matrix, so that the integral can be performed independently on each element. Substituting Eq. 4 into Eq. 5 can be obtained

$$[T_p^L]\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T + [T_f] = [T_p^T]\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T, \tag{6a}$$

$$[V_p^L]\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T + [V_f] = [V_p^T]\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T, \tag{6b}$$

where

$$[T_p^L] = \int_s [W(s)]^T [G_t^D(s)] ds, \tag{7}$$

$$[T_p^T] = \int_s [W(s)]^T [G_t^D(s)] ds, \tag{8}$$

$$[T_f] = \int_s [W(s)]^T [\tilde{T}_{xf}(s), \tilde{T}_{yf}(s), \tilde{T}_{zf}(s)]^T ds, \tag{9}$$

$$[V_p^L] = \int_s [W(s)]^T [G_u^D(s)] ds, \tag{10}$$

$$[V_p^T] = \int_s [W(s)]^T [G_u^S(s)] ds, \tag{11}$$

$$[V_f] = \int_s [W(s)]^T [\tilde{w}_{xf}(s), \tilde{w}_{yf}(s), \tilde{w}_{zf}(s)]^T ds. \tag{12}$$

From Eq. 6, the virtual moving uniform distributed line loads  $\{\tilde{p}_{1x}, \tilde{p}_{1y}, \tilde{p}_{1z}\}^T$  and  $\{\tilde{p}_{2x}, \tilde{p}_{2y}, \tilde{p}_{2z}\}^T$  applied on the boundary of the filling trench can be obtained, and substituting them into Eq. 4 can obtain the scattered wave field. Finally, by combining the free wave field and the scattered wavefield, the total displacement of any point in the layered elastic half-space can be obtained

$$\{\tilde{u}_x, \tilde{u}_y, \tilde{u}_z\}^T = \{G_{u_x}(x, y, z, \omega), G_{u_y}(x, y, z, \omega), G_{u_z}(x, y, z, \omega)\}^T \tilde{q}(y, \omega). \tag{13}$$

Among them,  $G_{u_x}(x, y, z, \omega)$ ,  $G_{u_y}(x, y, z, \omega)$ , and  $G_{u_z}(x, y, z, \omega)$ , respectively, represent the dynamic flexibility coefficient of the layered elastic foundation with in-filled trench under the unit moving uniform distributed line load with a width in the  $x$ ,  $y$ , and  $z$  directions;  $\tilde{q}(y, \omega)$  is the vertical uniformly distributed line load; and  $\{\tilde{w}_x, \tilde{w}_y, \tilde{w}_z\}^T$  is the displacement vector generated by the elastic foundation under moving load. The displacement, velocity, and acceleration of any point in the time domain can be obtained by the inverse Fourier transform as shown in the following:

$$\begin{Bmatrix} w_x(x, y, z, t) \\ w_y(x, y, z, t) \\ w_z(x, y, z, t) \end{Bmatrix} = \int_{-\infty}^{\infty} \begin{Bmatrix} \tilde{w}_x(x, y, z, \omega) \\ \tilde{w}_y(x, y, z, \omega) \\ \tilde{w}_z(x, y, z, \omega) \end{Bmatrix} e^{i\omega t} d\omega, \tag{14a}$$

$$\begin{Bmatrix} \dot{w}_x(x, y, z, t) \\ \dot{w}_y(x, y, z, t) \\ \dot{w}_z(x, y, z, t) \end{Bmatrix} = \int_{-\infty}^{\infty} i\omega \begin{Bmatrix} \tilde{w}_x(x, y, z, \omega) \\ \tilde{w}_y(x, y, z, \omega) \\ \tilde{w}_z(x, y, z, \omega) \end{Bmatrix} e^{i\omega t} d\omega, \tag{14b}$$

$$\begin{Bmatrix} \ddot{w}_x(x, y, z, t) \\ \ddot{w}_y(x, y, z, t) \\ \ddot{w}_z(x, y, z, t) \end{Bmatrix} = \int_{-\infty}^{\infty} (-\omega^2) \begin{Bmatrix} \tilde{w}_x(x, y, z, \omega) \\ \tilde{w}_y(x, y, z, \omega) \\ \tilde{w}_z(x, y, z, \omega) \end{Bmatrix} e^{i\omega t} d\omega. \tag{14c}$$

**TABLE 1** | Soil parameters under train speeds of 70 and 200 km/h

Soil layer	Depth (m)	Mass density $\rho$ (kg/m <sup>3</sup> )	Shear wave speed $\beta_s$ (m/s)		Poisson's ratio $\nu$	Damping ratio $\xi$	
			C = 70 km/h	C = 200 km/h		C = 70 km/h	C = 200 km/h
Backfill	1.1	1500	72	65	0.49	0.04	0.063
Silty clay	3.0	1620	41	33	0.49	0.02	0.058
Clay	4.5	1475	65	60	0.49	0.05	0.098
Clay	6.0	1475	87	85	0.49	0.05	0.064
Half-space	$\infty$	1475	100	100	0.49	0.05	0.060

**TABLE 2** | Track properties

Velocity	Track width B/m	Mass density M/(kg/m <sup>3</sup> )	B (E) ending stiffness EI/(MN/m <sup>2</sup> )	D (E) amping ratio $\xi$
70 km/h	3.0	10.83	2006	0.1
200 km/h	3.0	10.83	806	0.1

### Coupling of the Layered Foundation and the Track

Assuming that the interaction pressure density between the track and the foundation is  $q(y, t)$ , the vibration equation of the track's vertical displacement  $\Omega$  can be described as [32]:

$$EI \frac{\partial^4 \Omega}{\partial y^4} + M \frac{\partial^2 \Omega}{\partial t^2} = 2\Delta q(y, t) + \sum_{n=1}^M P_n(y - ct + L_n). \quad (15)$$

Here,  $\sum_{n=1}^M P_n(y - ct + L_n)$  is the wheel load of the train, and its specific parameters can be found in [32]. **Equation 15** is converted into the frequency-wavenumber domain to obtain

$$(EI k_y^4 - M\omega^2) \tilde{\Omega}(k_y, \omega) = 2\Delta \tilde{q}(k_y, \omega) + \sum_{n=1}^M \tilde{P}_n(k_y, \omega). \quad (16)$$

Considering that the displacement of each point of the track in the transverse direction is  $\Omega$ , the continuous condition of the track center displacement and the corresponding foundation point is

$$\tilde{q}(k_y, \omega) G_w(0, 0, 0, \omega) = \tilde{\Omega}. \quad (17)$$

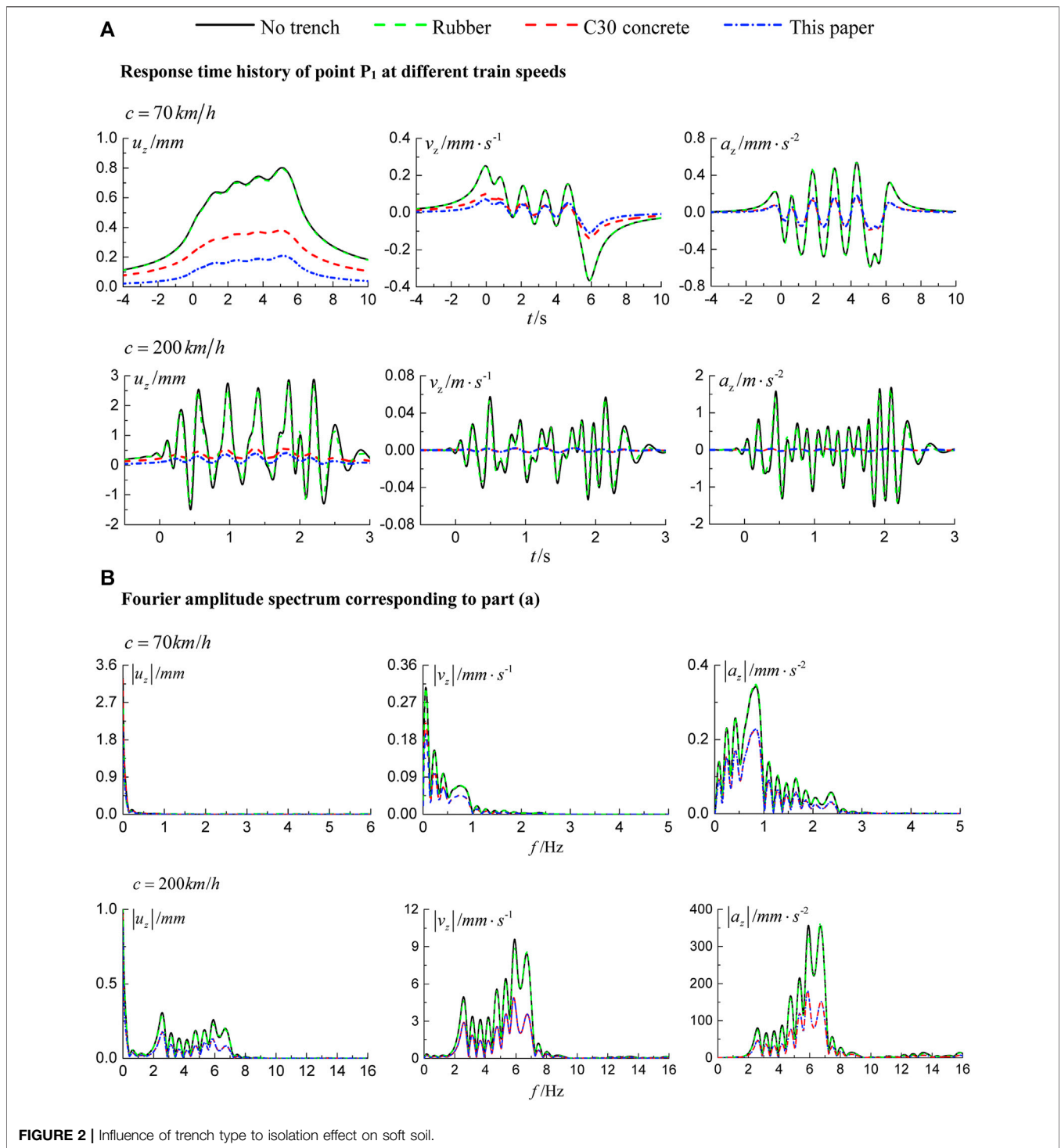
Here,  $G_w(0, 0, 0, \omega)$  is the dynamic flexibility of the layered foundation with an in-filled trench under the action of the moving load in the  $z$ -direction. It expresses the vertical displacement of the midpoint of the element due to the uniform distributed vertical load acting on the element, which can be obtained by **Eq. 13**. Combining **Eqs 16** and **17** can obtain the interaction force between the track and the layered foundation and the track displacement in the frequency-wavenumber domain. Then, the inverse Fourier transform is used to transform the result into the frequency-space domain, and then the displacement response of any position of the elastic foundation in the frequency-space domain can be obtained by **Eq. 13**. Finally, the displacement, velocity, and acceleration responses of any position of the elastic foundation in the time-space domain are obtained from **Eq. 14**.

### METHOD VERIFICATION

This paper verifies the correctness of the numerical analysis of this paper by comparing the calculated results with the actual measured data of the Swedish X-2000 train [32]. In this section, the material parameters in the in-filled trench are taken as the same as the parameters of the soil layer, that is, the half-space with the in-filled trench degenerates into the half-space without an in-filled trench. **Table 1** and **Table 2**, respectively, give the foundation soil parameters and the track system parameters of the Swedish X2000 train at different speeds. The Swedish X2000 train consists of five carriages, and the load distribution of the train wheels is shown in **Figure 1B**. **Figure 1C** shows the comparison between the calculated results in this paper and the measured data when the train speeds are 70 km/h and 200 km/h, respectively. The results in this paper are in good agreement with the measured data, which confirms the reliability of the method in this paper.

### VIBRATION ISOLATION OF THE RUBBER-CONCRETE ALTERNATING SUPERPOSITION IN-FILLED TRENCH

To better demonstrate the superiority of the rubber-concrete alternating superposition in-filled trench for train-induced vibration isolation, this paper takes the vibration generated by the Sweden X2000 high-speed train on the actual soft soil foundation as an example, and compares the vibration isolation effect with that of the empty trench, rubber in-filled trench, and C30 concrete in-filled trench. In the calculation, the thickness of the rubber-C30 superposition unit is taken as 0.4 m, and the trench with 3.0 m depth and 0.5 m width. The actual soft soil foundation parameters of the Sweden X-2000 high-speed train can be found in [33]. The track parameters of the X-2000 train are shown in **Table 2**, and the wheel axle load distribution is shown in **Figure 1B**.



**Figure 2A** shows the results of the vertical displacement, velocity, and acceleration time histories of point P<sub>1</sub> in **Figure 1A** when the speeds of the X2000 train are 70 km/h and 200 km/h, with different types of in-filled trench. **Figure 2B** shows the Fourier amplitude spectrum of the vertical displacement, velocity, and acceleration at point P<sub>1</sub> corresponding to **Figure 2A**.

It can be seen from **Figure 2A** that the rubber-filled trench has almost no vibration isolation effect. At the two speeds of the train, the vibration isolation effect of the rubber-concrete alternately superposition in-filled trench proposed in this paper is significantly better than that of the C30 concrete in-filled trench, which is especially reflected in the vibration isolation effect on displacement. Moreover, the vibration isolation effect of

the rubber-concrete alternately superposition in-filled trench at the speed of 200 km/h is better than that of the speed of 70 km/h. **Figure 2B** shows that the frequency spectrum of ground vibration response behind the trench is significantly changed by the rubber-concrete alternately superposition in-filled trench. Compared with low-frequency vibrations generated by the lower train speed, the rubber-concrete alternately superposition in-filled trench has a better vibration isolation effect on high-frequency vibrations generated by a high-speed train. This shows that the rubber-concrete alternately superposition in-filled trench has the frequency band characteristics of elastic waves, that is, elastic waves in the passband frequency range can propagate without attenuation, while the elastic waves in the forbidden frequency range will be filtered out.

## CONCLUSION

This paper presented a new train-induced vibration isolation measure of rubber-concrete alternating superposition in-filled trench and built a 2.5D train-track-layered foundation-filled trench model to analyze the dynamics of track and layered foundation with the in-filled trench. The correctness of the model is verified by using the measured data of the Sweden X2000 high-speed train. Finally, the vibration isolation efficiency of rubber-concrete alternating superposition in-filled trench is calculated using the actual soft soil foundation parameters of the Sweden X2000 high-speed train, and the vibration isolation efficiency is compared with that of the empty trench rubber in-filled trench and concrete in-filled trench. The results show that the vibration isolation effect

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of the rubber-concrete alternating superposition in-filled trench proposed in this paper is better than that of the C30 concrete in-filled trench, especially the impact on displacement. Compared with low-frequency vibrations generated by the lower train speed, the rubber-concrete alternating superposition in-filled trench has a better vibration isolation effect on high-frequency vibrations caused by higher-speed trains.

## DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material. Further inquiries can be directed to the corresponding author.

## AUTHOR CONTRIBUTIONS

Conceptualization: JW and QL; mathematical derivation: LJ and JW; computer program: LJ and JW; validation and data curation: XL and ZZ; writing: original draft preparation, review, and editing, LJ and JW All authors have read and agreed to publish this manuscript.

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