



Peregrine Solitons of the Higher-Order, Inhomogeneous, Coupled, Discrete, and Nonlocal Nonlinear Schrödinger Equations

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This study reviews the Peregrine solitons appearing under the framework of a class of nonlinear Schrödinger equations describing the diverse nonlinear systems. The historical perspectives include the various analytical techniques developed for constructing the Peregrine soliton solutions, followed by the derivation of the general breather solution of the fundamental nonlinear Schrödinger equation through Darboux transformation. Subsequently, we collect all forms of nonlinear Schrödinger equations, involving systematically the effects of higher-order nonlinearity, inhomogeneity, external potentials, coupling, discontinuity, nonlocality, higher dimensionality, and nonlinear saturation in which Peregrine soliton solutions have been reported.

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1 INTRODUCTION

In 1834, the British engineer J. S. Russell observed a hump of water propagating in a narrow canal created by a boat that maintained its speed and shape for several miles. Unlike a repeated pattern of sinusoidal waves or a spreading out of water wave pulses, the most remarkable feature of the observed single hump is that it was not a series of peaks and troughs wave; instead, it has a “solitary wave” structure with only one peak oscillating with a constant velocity and unchanging profile with time which led him to advert it a “wave of translation”. He followed his observations by intensive experiments in a water wave tank leading to demonstrating that, in contrast with the linear case where increasing the amplitude has nothing to do with the wave speed, the speed of the solitary wave is related to its height through $v = \sqrt{g(d+h)}$ and its envelope profile can take the form of $h \operatorname{sech}^2[k(x-vt)]$, where h , d , k , g , x , and t denote the wave height, the tank depth, the wavenumber, the gravitational acceleration, the propagation direction, and the time, respectively [1].

The conclusions made by Russell were argued by many mathematical theories such as the wave theory of G. B. Airy which indicates that the crest of a wave of a finite amplitude propagates faster than its remaining structure and eventually breaks [2] and G. G. Stokes theory which states that only the periodic waves can be in a finite and permanent profile [3]. In contrast to these mathematical arguments, in 1895 the Dutch mathematician D. Korteweg and his student G. de Vries came up with a model that describes the propagation of long surface waves in a narrow water channel [4]. A considerable conclusion of Korteweg and de Vries’s model was its admissibility of a special solution that travels with constant speed and amplitude, which was in an exact match with Russell’s

description. Currently, this model is known as the Korteweg–de Vries (KdV) equation. Disappointedly, the significance of this solution and Russell's observations were overlooked and not understood until 1965 when N. J. Zabusky and M. D. Kruskal pioneered numerical solutions to the KdV equation [5] and observed solitary wave pulses interact between themselves elastically as if they are real particles and return to their initial properties after the collision, except for some phase shifts. This results in a localized solution that remains stable and constant during the propagation which is now referred to as a bright soliton or briefly as a soliton. Nowadays, it is well known that solitons are constructed due to a dynamic balance between the group velocity dispersion and the nonlinearity of the system.

Nonlinear systems have attracted increasing interest after C. S. Gardner and his colleagues J. M. Greene, M. D. Kruskal, and R. M. Miura in 1967 introduced a method [6] now known as the inverse scattering transform (IST) that yields a solution to initial value problems (IVPs) for nonlinear partial differential equations (NPDEs). The IST method may be seen as an extension to the Fourier transform for NPDEs. The integrability of the nonlinear Schrödinger equation (NLSE) was discovered in 1972 when V. Zakharov and A. B. Shabat generalized the IST method and derived, for the first time, its soliton solution upon associating the NLSE to a linear system of differential equations [7]. The integrable NLSE equation is, in principle, admitting infinitely many independent solutions. Later on, the IST method was adopted to find a wide class of solutions to the NLSE and its various versions. Recently, all known solutions of the fundamental NLSE and its different versions were collected by [8].

The first breather type solution on a finite background of the NLSE was achieved in 1977 by E. A. Kuznetsov [9] and independently by Y. C. Ma [10] in 1979; now it is accordingly named Kuznetsov-Ma breather. Such a solution is periodic in time and localized in space. The Kuznetsov-Ma breather was derived by solving the initial value problem of the NLSE where the initial profile is a continuous wave (CW) on a background superposing with a soliton solution. The soliton profile in this context can be considered as a perturbation source on the CW. The modulational instability analysis is used to study the dynamics of the Kuznetsov-Ma breather when the amplitude of the soliton is much smaller than the background of the CW. The Kuznetsov-Ma breather solution can be also seen as a soliton on a finite background. In 1983, D. H. Peregrine [11] derived an exact solution to the focusing NLSE equation that is localized in both time and space domains, on a nonzero background. As a result of its dual localization which is the feature of a solitary wave, currently, this solution is known as Peregrine soliton. Physically, the Peregrine soliton models the closet prototype of rogue waves and thus usually takes the full name Peregrine rogue waves [12–14]. Rogue waves have been first studied in the context of oceanography [12, 15, 16]. Peregrine soliton is the lowest order rational solution of the NLSE that takes the form of one dominant peak, appears from “nowhere”, causes danger, and “disappears without a trace” [17, 18]. Its dominant peak is accompanied by two side holes that exist as a result of energy conservation. Due to its danger, oceanographers often call it using some other names such as the “freak waves”, the “killer waves”, the “monster waves”,

the “abnormal waves”, and the “extreme waves” and rarely use the words “rogon waves”, “giant waves”, or “steep waves”. The highest amplitude of the Peregrine soliton equals two to three times the amplitude of the surrounding background waves.

Shortly, after the revelation of the Peregrine soliton, N. Akhmediev et al., in 1985, found another breather type solution on a finite background to the NLSE which is, contrary to the Kuznetsov-Ma breather, breathing periodically in space and localized in time domain [19]. This solution is now referred to as Akhmediev breather. In relation to the modulational instability analysis, when the frequency of the applied perturbation tends to zero (the soliton's frequency approaches zero), the Kuznetsov-Ma breather tends to a Peregrine soliton. More precisely, taking the temporal period of the Kuznetsov-Ma breather solution to infinity results in a Peregrine soliton. Interestingly, the Akhmediev breather solution also turns out into a Peregrine soliton when the spacial period tends to infinity.

Together with the Kuznetsov-Ma and the Akhmediev breathers, the Peregrine soliton belongs to the family of the solitons on a nonzero background. This family can be represented in one general breather solution form in which the Peregrine soliton can be recovered. The Peregrine soliton, particularly, is considered as the first-order rational solution of a series of infinite recurrence orders of rational solutions. The second-order Peregrine soliton appears with a higher amplitude than the first-order Peregrine soliton [17, 20]. Higher-order of rational solutions and Peregrine soliton hierarchy are also revealed in Refs. 21 and 22.

Although the formation of Peregrine soliton requires ideal mathematical conditions which could be practically impossible, earlier intensive experiments are performed to randomly observe optical rogue waves [23, 24], acoustic rogue waves [25], and rogue waves in parametrically excited capillary waves [26]. In 2010, B. Kibler et al. succeeded for the first time in demonstrating experimentally the dynamics of the Peregrine soliton in nonlinear fiber optics under nonideal excitation condition modeled by the NLSE [27]. Soon after, Peregrine solitons have been observed in deep water wave tanks [28].

Rogue waves can be naturally created via various generating mechanisms. From the perspective of the MI analysis, there is always a chance for these modulations on the CW background to create multiple breathers that are scattering in random directions. Collisions between these grown breathers probably proceed a formation of wave amplification. Higher peaks than the ones associated with the breathers can be generated from the growth of Akhmediev breathers [18, 29–31]. A similar result can be obtained when the collided breathers are Kuznetsov-Ma breathers [20]. Another possible mechanism for the rogue waves' creation is when the collision occurs between multiple solitons carrying different heights and propagating with different phases [32–36]. At the collision point, the amplitude of the peak becomes higher than the solitons individually, thanks to the nonlinear interaction between them. For other scenarios, see also [20, 30, 37–42].

Considerable efforts have been directed toward testing the stability of the Peregrine soliton behavior, analytically and

numerically, against external perturbations [43–46, 46, 47, 47–54]. The stability issue is of important interest to experimentalists, as they seek to reproduce or generate solutions under a laboratory setting. Determining the stability of the solution allows the estimation of the range of practical applications that the solution can occupy. Generally, the studies reveal that, due to the high double localization and sharp structure associated with the Peregrine soliton solution, it, consequently, exhibits high sensitivity to small perturbations or changes in the initial conditions and thus reveals unstable characteristics. Other interesting works on the stability of the Peregrine soliton can be found for instance in [55–65].

Peregrine soliton is of crucial importance due to its doubly dimensional localization in space and time and because it defines a limit case of a wide range of solutions to the NLSE. Thus, it has received huge attention from mathematicians, physicists, and engineers. Its investigations have been rolled up through many contexts such as observation of Peregrine solitons in a multicomponent plasma with negative ions [66, 67], phase properties of Peregrine soliton in the hydrodynamic and optical domains [68], implementation of breather-like solitons extracted from the Peregrine rogue wave in the nonlinear fibers [69], demonstrating experimentally and numerically the generation and breakup of the Peregrine soliton in telecommunications fiber [70], optical rogue waves in an injected semiconductor laser [71], and Peregrine solution in the presence of wind forcing in deep water wave tank laboratories [72].

Besides the experimental observations, numerous numerical simulations and theoretical studies have been performed to demonstrate and predict the occurrence of such a unique type of soliton on a finite background in diverse physical media, for example, in Bose-Einstein condensates [73], freak waves as limiting Stokes waves in the ocean [74], in a mode-locked fiber laser [75], in singly resonant optical parametric oscillators [76], Peregrine solitons and algebraic soliton pairs in Kerr nonlinear media [77], the interaction of two in-phase and out-of-phase Peregrine solitons in a Kerr nonlinear media [41], and recently in lattice systems [78]. For other studies, see also [18, 21, 29, 79–85].

In this work, we aim at reviewing the theoretical studies that have been performed for Peregrine solitons of NLSEs with different setups and conditions. The work is arranged as follows. In **Section 2**, we derive the general breather class of the NLSE via the Darboux transformation and Lax pair method. We show that the Peregrine soliton solution is a limiting case of the general breather solution. An alternative route is then presented where we implement a specific seed solution to derive directly the Peregrine soliton solution. **Section 3** is devoted to reviewing the Peregrine solitons of higher-order and inhomogeneous NLSEs. In **Section 4**, the Peregrine solitons of NLSEs with external constant and variable potentials are reviewed. **Section 5** discusses the Peregrine solitons in coupled NLSEs, known as the Manakov system or the vector NLSE (N-coupled NLSEs), the coupled Gross-Pitaevskii equations, the coupled Hirota equations, the coupled cubic-quintic NLSEs, the PT-symmetric coupled NLSEs, and the

higher-order coupled NLSEs. In **Section 6**, we review the works done on Peregrine solitons of the discrete NLSEs, the Ablowitz-Ladik equations, the generalized Salerno equation, and the Hirota equations. In **Section 7**, the Peregrine solitons in nonlocal NLSEs are presented. The nonlocal NLSE is a non-Hermitian and PT-symmetric equation with the nonlinearity term potential $V(x, t)u(x, t) = u(x, t)u^*(-x, t)u(x, t)$, where $u(x, t)$ is the mean field wavefunction, satisfying the PT-symmetric condition, $V(x, t) = V^*(-x, t)$. The nonlocality can also be seen in the presence of the reverse time dependency where $V(x, t) = V^*(x, -t)$ or with the combination of spatial and temporal nonlocalities $V(x, t) = V^*(-x, -t)$. In **Section 8**, we discuss the Peregrine solitons of higher dimensional and mixed NLSEs. In **Section 9**, the Peregrine solitons in saturable NLSEs will be discussed. We end up in **Section 10** by the main conclusions and outlook for future work. The solutions for all the NLSEs considered are provided in the **Supplementary Material**.

2 ANALYTICAL DERIVATION OF THE FUNDAMENTAL PEREGRINE SOLITON

Various analytical methods are used to solve different versions of the NLSE such as the inverse scattering transform [86–93], the Adomian Decomposition method [94], the Homotopy Analysis method [95, 96], the similarity transformation method [97–102], and the Darboux transformation and Lax pair method [103–106], just to name a few. This section is devoted to deriving the general breather solution of the fundamental NLSE using the Darboux transformation and Lax pair method [107]. We show that, under certain limits, the general breather solution reduces to the Akhmediev breather, the Kuznetsov-Ma breather, the Peregrine soliton, the single bright soliton, or the continuous wave solution. The Darboux transformation method is an applicable method for solving only linear systems and cannot be directly applied for nonlinear systems. A crucial additional step is required to make it applicable for nonlinear systems as well. It is to search for an appropriate pair of matrices that associates the nonlinear equation to a linear system. This pair was introduced firstly in 1968 by P. D. Lax [108] and now named Lax pair. The Lax pair should be associated with the nonlinear system through what is called a compatibility condition. The next step is to solve the obtained linear system using a seed solution, which is a known exact solution to the nonlinear system. This technique gives remarkable merit which is the applicability to perform new exact solutions. Each seed solution performs another exact solution that belongs to the family of the seed solution. The latter obtained solution could be used as a new seed solution for the next performance round. All achieved solutions will belong to the same family of the initial seed solution. It is well known that using the trivial solution, $u(x, t) = 0$, as a seed in the Darboux transformation method for the NLSE will produce the single bright soliton solution. The single bright soliton solution can act as a seed solution in the next round to generate the two-soliton solution. Keeping on the same track, multisoliton solutions can be generated in this way. In order to generate the general breather

solution of the NLSE, a nontrivial seed solution is needed, namely, the continuous wave solution $u(x, t) = A e^{iA^2 t}$, where A is an arbitrary real amplitude of the wave. Here we include the final results. For the details of the mathematical derivation see **Supplementary Appendix**.

The fundamental NLSE can be written in dimensionless form as

$$iu_t + \frac{1}{2}u_{xx} + |u|^2 u = 0, \tag{1}$$

where $u = u(x, t)$ is the complex wave function and the subscripts denote partial derivatives with respect to t and x . The general breather solution of **Eq. 1** can be compactly written as*

$$u[1] = A e^{iA^2 t} \times \left\{ 1 - \frac{\sqrt{8} \lambda_{1r} (A^2 + \Gamma^2) \cos(q_1) + i (A^2 - \Gamma^2) \sin(q_1)}{A + 2A [\Gamma_r \cosh(q_2) - i \Gamma_i \sinh(q_2)]} \right\}, \tag{2}$$

where

$$q_1 = \delta_1 + \sqrt{2} [\sqrt{2} x \Delta_i - 2 t (\Delta_i \lambda_{1i} + \Delta_r \lambda_{1r})],$$

$$q_2 = \delta_2 + \sqrt{2} [\sqrt{2} x \Delta_r - 2 t (\Delta_r \lambda_{1i} - \Delta_i \lambda_{1r})]$$

$$\Delta_r = \text{Re} \left[\sqrt{2 (\lambda_{1r} - i \lambda_{1i})^2 - A^2} \right], \Delta_i = \text{Im} \left[\sqrt{2 (\lambda_{1r} - i \lambda_{1i})^2 - A^2} \right]$$

$$\Gamma_r = \Delta_r + \sqrt{2} \lambda_{1r}, \Gamma_i = \Delta_i - \sqrt{2} \lambda_{1i}, \text{ and } \Gamma = \sqrt{\Gamma_r^2 + \Gamma_i^2}$$

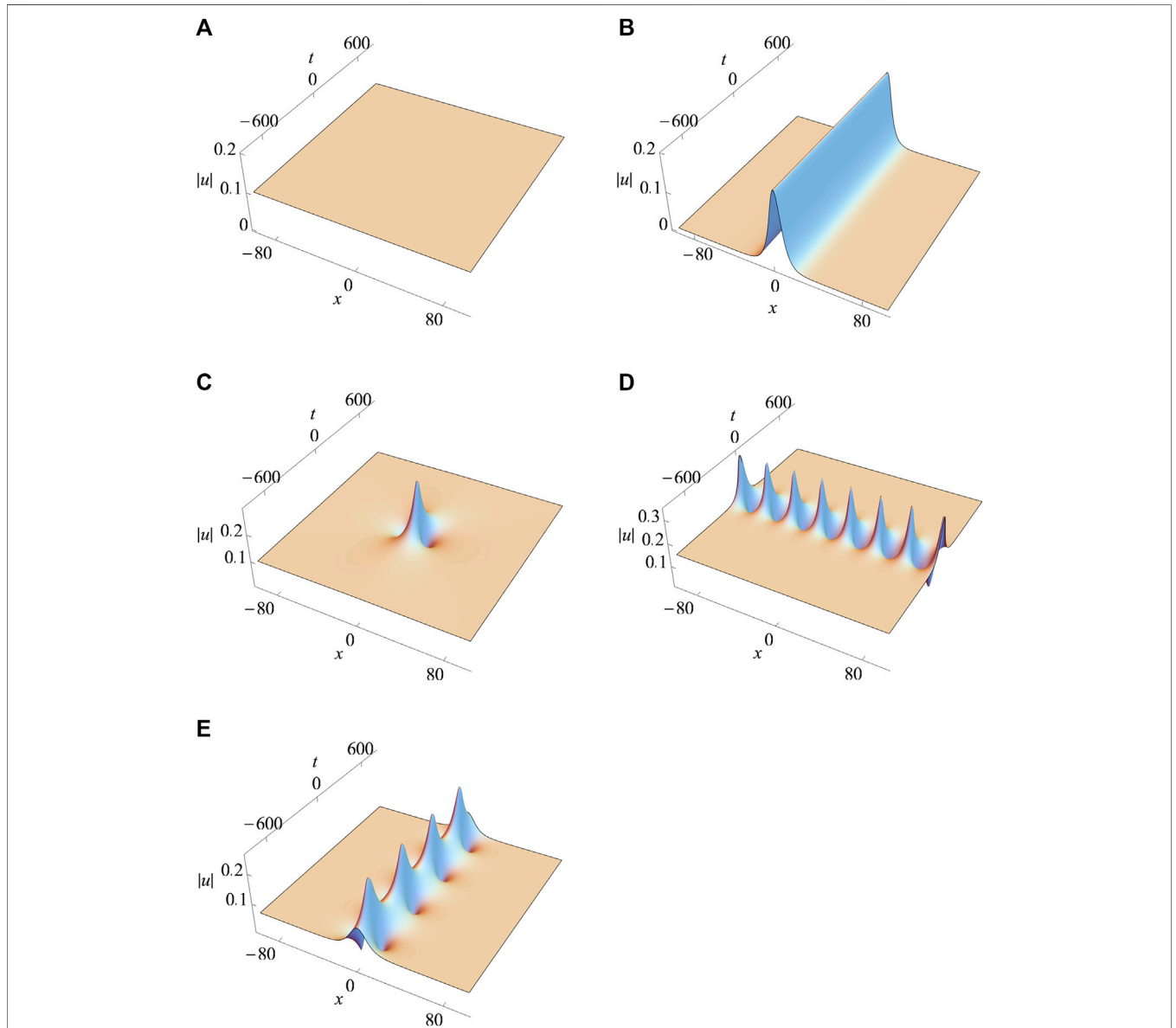


FIGURE 1 | The five members of the solution class (2) all at $\lambda_{1r} = 0.07$. **(A)** CW at $A = \sqrt{2}\lambda_{1r}$, **(B)** soliton at $A = 0$, **(C)** Peregrine soliton at $A = -\sqrt{2}\lambda_{1r}$, **(D)** Akhmediev breather at $A = 1.5\sqrt{2}\lambda_{1r}$, **(E)** Kuznetsov-Ma breather at $A = \sqrt{2}\lambda_{1r}/1.5$.

This is the general breather solution of the NLSE with five arbitrary real parameters, λ_{1r} , λ_{1i} , δ_1 , δ_2 , and A , which can be, with certain sets of parameter's values, reduced to different types of solutions within the same family. For the sake of obtaining the Akhmediev breather, the Kuznetsov-Ma breather, the Peregrine soliton, the single bright soliton, and the continuous wave solution as limiting cases of solution Eq. 2, the first four free parameters are held on $\lambda_{1r} = 0.05$, $\lambda_{1i} = 0$, $\delta_i = 0$, and $\delta_r = 0$, while we choose A to be the variable parameter.

- (1) Continuous wave: In the limit $A \rightarrow \sqrt{2}\lambda_{1r}$, the general breather solution returns back to the seed solution with an amplitude $A = -\sqrt{2}\lambda_{1r}$ (Figure 1A)

$$u[1] = -\sqrt{2}\lambda_{1r} e^{2i\lambda_{1r}^2 t} \tag{3}$$

- (2) Soliton: In the trivial limit, when $A \rightarrow 0$, the general breather solution reduces to a soliton solution which is localized in x and does not change as it propagates, fixed shape along t direction (Figure 1B)

$$u[1] = -2\sqrt{2}\lambda_{1r} e^{4i\lambda_{1r}^2 t} \operatorname{sech}(2\sqrt{2}\lambda_{1r} x) \tag{4}$$

- (3) Kuznetsov-Ma breather: When $|A| < \sqrt{2}\lambda_{1r}$ the general breather solution becomes periodic only in t and localized in x , which is referred to as a KM breather (Figure 1E).
- (4) Akhmediev breather: When $|A| > \sqrt{2}\lambda_{1r}$ the general breather solution becomes periodic in x and localized in t , which is currently known as an Akhmediev breather (Figure 1D).
- (5) Peregrine soliton: In the nontrivial limit, when $A \rightarrow -\sqrt{2}\lambda_{1r}$, the period goes to infinity and the breather solution reduces to the Peregrine soliton which is localized in both x and t and given by the rational expression (Figure 1C)

$$u[1] = \sqrt{2}\lambda_{1r} e^{2i\lambda_{1r}^2 t} \left(\frac{-3 - 16i\lambda_{1r}^2 t + 8\lambda_{1r}^2 x^2 + 16i\lambda_{1r}^4 t^2}{1 + 8\lambda_{1r}^2 x^2 + 16\lambda_{1r}^4 t^2} \right) \tag{5}$$

*There are different forms of the general breather solution in the literature. Three more expressions are listed in [8].

3 PEREGRINE SOLITONS OF HIGHER-ORDER AND INHOMOGENEOUS NLSES

This section is dedicated to review existing Peregrine soliton solutions of the inhomogeneous NLSE with higher-order effects and potentials reported in the literature. In general, the higher-order NLSE (HNLSE) encompasses the effects of the higher-order dispersion, the higher-order nonlinearity, the stimulated Raman self-frequency shift, and the self-steepening effects in addition to group velocity dispersion (GVD) and cubic nonlinearity of

fundamental NLSE. Such HNLSEs play a significant role in describing the dynamics of the ultrashort pulse propagation, supercontinuum generation [109], Heisenberg spin chain [110], ocean waves [16], and so forth. However, our context will be adhering to the Peregrine soliton solutions realized for such HNLSEs with different higher-order dispersive and nonlinear effects under certain circumstances. Diverse HNLSEs have been reported in the literature, namely, the Hirota equation [111], the Lakshmanan-Porsezian-Daniel equation [110], the quintic NLSE [22], the sextic NLSE [112, 113], heptic NLSE [112], and octic NLSE [112]. This section attempts to review the occurrence of the Peregrine solution reported in the aforementioned HNLSEs. Additionally, the inhomogeneous NLSE which is commonly termed as variable coefficient NLSE is also explored for the occurrence of Peregrine solutions [114, 115]. Understanding such inhomogeneous NLSEs plays a significant role in describing the nonuniform, defective, and irregular space-time dependence of the physical systems as well as discovering the apt control parameters required for diverse complex systems [85, 116–118]. The higher-order and inhomogeneous NLSEs, in which Peregrine solutions are reported, are listed below.

3.1 The Interaction of the Optical Rogue Waves Described by a Generalized HNLSE With (Space-, Time-) Modulated Coefficients [118]

$$i\psi_z = \beta(z, t)\psi_{tt} + [V(z, t) + i\gamma(z, t)]\psi + g(z, t)|\psi|^2\psi + i \left[\alpha_1(z)\psi_{ttt} + \alpha_2(z)\frac{\partial(|\psi|^2\psi)}{\partial t} + \alpha_3(z)\psi\frac{\partial|\psi|^2}{\partial t} \right] + [\mu(z) + i\sigma(z, t)]\psi_t \tag{6}$$

In the above equation, $\beta(z, t)$, $V(z, t)$, $\gamma(z, t)$, and $g(z, t)$ represent the (space-, time-) modulated coefficients of GVD, external potential, gain/loss, and SPM, respectively. $\alpha_1(z)$, $\alpha_2(z)$, and $\alpha_3(z)$ account for third-order dispersion, self-steepening, and stimulated Raman scattering coefficients, respectively. $\mu(z)$ and $\sigma(z, t)$ denote the coefficients of differential gain or loss parameter and (space-, time-) modulated walk-off, respectively. (Solutions: See S1 & S2.)

3.2 The Fourth-Order Integrable Generalized NLSE With Higher-Order Nonlinear Effects Describing the Propagation of Femtosecond Pulse Through a Nonlinear Silica Fiber [119]

$$i\psi_t + \psi_{xx} + 2|\psi|^2\psi + \gamma_1(\psi_{xxxx} + 6\psi_x^2\psi^* + 4|\psi_x|^2\psi + 8|\psi|^2\psi_{xx} + 2\psi^2\psi_{xx}^* + 6|\psi|^4\psi) = 0 \tag{7}$$

Here γ_1 indicates the strength of higher-order linear and nonlinear effects. (Solution: See S3.)

3.3 The Fifth-Order NLSE Describing One-Dimensional Anisotropic Heisenberg Ferromagnetic Spin Chain [120]

$$\begin{aligned}
 i\psi_t + \frac{1}{2}(\psi_{xx} + 2|\psi|^2\psi) - i\alpha(\psi_{xxx} + 6|\psi|^2\psi_x) \\
 + \gamma[\psi_{xxx} + 6|\psi|^4\psi + 2\psi^2\psi_{xx}^* + 4\psi|\psi_x|^2 + 6\psi^*(\psi_x)^2] \\
 + 8|\psi|^2\psi_{xx} - i\delta[\psi_{xxxx} + 30|\psi|^4\psi_x + 20\psi^*\psi_x\psi_{xx} \\
 + 10|\psi|^2\psi_{xxx} + 10(\psi|\psi_x|_x)_x] = 0,
 \end{aligned}
 \tag{8}$$

where the parameters α , γ , and δ are the coefficients of third-order dispersion, fourth-order dispersion, and fifth-order dispersion, respectively. (Solution: See S4.)

3.4 The Dynamics of Ultrashort Optical Pulses Propagating Through an Optical Fiber Described by a Higher-Order NLSE [121]

$$i\psi_x + \alpha_2 K_2(\psi) - i\alpha_3 K_3(\psi) + \alpha_4 K_4(\psi) - i\alpha_5 K_5(\psi) = 0, \tag{9}$$

where K_2 , K_3 , K_4 , and K_5 are cubic, Hirota, Lakshmanan-Porsezian-Daniel, and quintic operators, respectively.

$$\begin{cases}
 K_2 = \psi_{tt} + 2\psi|\psi|^2, \\
 K_3 = \psi_{ttt} + 6\psi_t|\psi|^2, \\
 K_4 = \psi_{tttt} + 8|\psi|^2\psi_{tt} + 6|\psi|^4\psi + 4|\psi_t|^2\psi + 6\bar{\psi}\psi_t^2 + 2\psi^2\bar{\psi}_{tt}, \\
 K_5 = \psi_{ttttt} + 10|\psi|^2\psi_{ttt} + 10(\psi|\psi_t|^2)_t + 20\bar{\psi}\psi_t\psi_{tt} + 30|\psi|^4\psi_t.
 \end{cases}$$

α_i ($i = 1, 2, 3, 4, 5$) are real constants. (Solution: See S5.)

3.5 The Sixth-Order NLSE With a Single Higher-Order Dispersion Term Describing the Dynamics of Modulation Instability, Rogue Waves, and Spectral Analysis [122]

$$i\psi_z + \delta_2\Gamma_2(\psi) + \delta_6\Gamma_6(\psi) = 0, \tag{10}$$

where δ_2 and δ_6 are the second- and sixth-order dispersion coefficients, respectively. Γ_2 and Γ_6 are cubic and sextic operator, respectively. In this analysis, the second-order dispersion coefficient value is fixed as $\delta_2 = 1/2$.

$$\begin{cases}
 \Gamma_2 = \psi_{tt} + 2\psi|\psi|^2, \\
 \Gamma_6 = \psi_{tttttt} + \psi^2[60|\psi_t|^2\psi^* + 50\psi_{tt}(\psi^*)^2 + 2\psi_{ttt}^*] \\
 + \psi[12\psi^*\psi_{tttt} + 18\psi_t^*\psi_{ttt} + 8\psi_t\psi_{ttt}^* + 70(\psi^*)^2\psi_t^2 + 22|\psi_{tt}|^2] \\
 + 10\psi_t[3\psi^*\psi_{ttt} + 5\psi_t^*\psi_{tt} + 2\psi_t\psi_{tt}^*] + 10\psi^3[2\psi^*\psi_{tt} + (\psi_t^*)^2] \\
 + 20\psi^*\psi_{tt}^2 + 20\psi|\psi|^6.
 \end{cases}$$

(Solution: See S6.)

3.6 An Infinite Hierarchy of the Integrable NLSE [112]

$$\begin{aligned}
 F[\psi(x, t)] = i\psi_x + \alpha_2 K_2[\psi(x, t)] - i\alpha_3 K_3[\psi(x, t)] \\
 + \alpha_4 K_4[\psi(x, t)] - i\alpha_5 K_5[\psi(x, t)] + \alpha_6 K_6[\psi(x, t)] \\
 - i\alpha_7 K_7[\psi(x, t)] + \alpha_8 K_8[\psi(x, t)] \\
 - i\alpha_9 K_9[\psi(x, t)] + \dots = 0,
 \end{aligned}
 \tag{11}$$

where K_2 , K_3 , K_4 , K_5 , K_6 , K_7 , K_8 , and K_9 are cubic, Hirota, Lakshmanan-Porsezian-Daniel, quintic, sextic, heptic, octic, and ninth-order operators, respectively. α_j ($j = 1, 2, 3, 4, 5, 6, 7, 8, 9, \dots$) are real constants. The higher-order operators up to K_8 are provided below

$$\begin{cases}
 K_2 = \psi_{tt} + 2\psi|\psi|^2, \\
 K_3 = \psi_{ttt} + 6\psi_t|\psi|^2, \\
 K_4 = \psi_{tttt} + 8|\psi|^2\psi_{tt} + 6|\psi|^4\psi + 4|\psi_t|^2\psi + 6\psi_t^2\psi^* + 2\psi^2\psi_{tt}^*, \\
 K_5 = \psi_{ttttt} + 10|\psi|^2\psi_{ttt} + 10(\psi|\psi_t|^2)_t + 20\psi^*\psi_t\psi_{tt} + 30|\psi|^4\psi_t, \\
 K_6 = \psi_{ttttt} + [60\psi^*\psi_t|^2 + 50(\psi^*)^2\psi_{tt} + 2\psi_{ttt}^*]\psi^2 \\
 + \psi[12\psi^*\psi_{tttt} + 8\psi_t\psi_{ttt}^* + 22|\psi_{tt}|^2] \\
 + \psi[18\psi_{ttt}\psi_t^* + 70(\psi^*)^2\psi_t^2] + 20(\psi_t)^2\psi_{tt}^* + 10\psi_t[5\psi_{tt}\psi_t^* \\
 + 3\psi^*\psi_{ttt}] + 20\psi^*\psi_{tt}^2 + 10\psi^3[(\psi_t^*)^2 + 2\psi^*\psi_{tt}^*] + 20\psi|\psi|^6, \\
 K_7 = \psi_{tttttt} + 70\psi_{tt}^2\psi_t^* + 112\psi_t|\psi_{tt}|^2 + 98|\psi_t|^2\psi_{tt} \\
 + 70\psi^2[\psi_t[(\psi)^2 + 2\psi^*\psi_{tt}^*] + \psi^*(2\psi_{tt}\psi_t^* + \psi_{ttt}\psi^*)] \\
 + 28\psi_t^2\psi_{tt}^* + 14\psi[\psi^*(20|\psi_t|^2\psi_t + \psi_{tttt}) + 3\psi_{ttt}\psi_{tt}^*] \\
 + 2\psi_{tt}\psi_{ttt}^* + 2\psi_{ttt}\psi_t^* + \psi_t\psi_{ttt}^* + 20\psi_t\psi_{tt}(\psi^*)^2] + 140|\psi|^6\psi_t \\
 + 70\psi_t^3(\psi^*)^2 + 14(5\psi_{tt}\psi_{ttt} + 3\psi_t\psi_{tttt})\psi^*, \\
 K_8 = \psi_{ttttttt} + 14\psi^3[40|\psi_t|^2(\psi^*)^2 + 20\psi_{tt}(\psi^*)^3 + 2\psi_{ttt}^*\psi^*] \\
 + 3(\psi_t^*)^2 + 4\psi_t^*\psi_{tt}^*] + \psi^2[28\psi^*(14\psi_{tt}\psi_{tt}^* + 11\psi_{ttt}\psi_t^* \\
 + 6\psi_t\psi_{ttt}^*) + 238\psi_{tt}(\psi_t^*)^2 + 336|\psi_t|^2\psi_{tt}^* + 560\psi_t^2(\psi^*)^3 \\
 + 98\psi_{ttt}(\psi^*)^2 + 2\psi_{tttt}^*] + 2\psi\{21\psi_t^2[9(\psi_t^*)^2 + 14\psi^*\psi_{tt}^*] \\
 + \psi_t[728\psi_{tt}\psi_t^*\psi^* + 238\psi_{ttt}(\psi^*)^2 + 6\psi_{tttt}^*] + 34|\psi_{ttt}|^2 \\
 + 36\psi_{ttt}\psi_{tt}^* + 22\psi_{tt}\psi_{ttt}^* + 20\psi_{tttt}\psi_t^* + 161\psi_{tt}^2(\psi^*)^2 \\
 + 8\psi_{tttt}\psi^*\} + 182\psi_{tt}|\psi_{tt}|^2 + 308\psi_{tt}\psi_{ttt}\psi_t^* + 252\psi_t\psi_{ttt}\psi_{tt}^* \\
 + 196\psi_t\psi_{tt}\psi_{ttt}^* + 168\psi_t\psi_{ttt}\psi_{tt}^* + 42\psi_t^2\psi_{ttt}^* + 14\psi^*(30\psi_t^3\psi_t^* \\
 + 4\psi_{tttt}\psi_t + 5\psi_{ttt}^2 + 8\psi_{tt}\psi_{ttt}) + 490\psi_t^2\psi_{tt}(\psi^*)^2 \\
 + 140\psi^4\psi^*[(\psi_t^*)^2 + \psi^*\psi_{tt}^*] + 70\psi|\psi|^8.
 \end{cases}$$

(Solution: See S7.)

3.7 A Generalized Variable Coefficient Inhomogeneous NLSE With Varying Dispersion, Nonlinearity, Gain, and External Potentials [123]

$$i\psi_t + \frac{1}{2}\beta(t)\psi_{xx} + G(t)|\psi|^2\psi - \left(2\alpha(t)x + \frac{1}{2}\Omega(t)x^2\right)\psi = i\frac{\gamma(t)}{2}\psi. \tag{12}$$

Here, $\beta(t)$ and $G(t)$ are the dispersion and nonlinearity management parameters. $\alpha(t)$, $\Omega(t)$, and $\gamma(t)$ represent linear and harmonic oscillator potential and gain ($\gamma(t) < 0$) or loss ($\gamma(t) > 0$) coefficients, respectively. (Solutions: See S8 & S9.)

3.8 A Special Case of Eq. 12: The Variable Coefficient Inhomogeneous NLSE for Optical Signals [124]

$$i\psi_x + \frac{1}{2}\beta(x)\psi_{tt} + \chi(x)|\psi|^2\psi + \alpha(x)t^2\psi = i\gamma(x)\psi. \tag{13}$$

Here, $\beta(x)$, $\chi(x)$, $\alpha(x)$, and $\gamma(x)$ denote GVD, nonlinearity, normalized loss rate, and loss/gain coefficients, respectively. (Solutions: See S10 & S11.)

3.9 An Electron-Plasma Wave Packet With a Large Wavelength and Small Amplitude Propagating Through the Plasma Described by an Inhomogeneous NLSE With a Parabolic Density and Constant Damping Interaction [125]

$$i\psi_z + \psi_{tt} + 2|\psi|^2\psi - (\alpha t - \beta^2 t^2)\psi + i\beta\psi = 0, \tag{14}$$

where α and β are linear and damping coefficient, respectively. αt and $\beta^2 t^2$ account for the profiles of linear and parabolic density. (Solution: See S12.)

3.10 The Propagation of the Femtosecond Pulse Through an Inhomogeneous Fiber With Selective Linear and Nonlinear Coefficients Described by an Inhomogeneous Hirota Equation [126]

$$\psi_z = \alpha_1(z)\left(i\psi_{tt} + \frac{1}{3\delta}\psi_{ttt}\right) + \alpha_4(z)(i\delta\psi|\psi|^2 + |\psi|^2\psi_t) + \alpha_6(z)\psi, \tag{15}$$

where $\alpha_6 = \frac{\alpha_{1,z}\alpha_4 - \alpha_1\alpha_{4,z}}{2\alpha_1\alpha_4}$. Here $\alpha_1(z)$, $\alpha_2(z)$, and α_6 represent the contribution of the dispersion, nonlinearity, and gain/loss coefficient, respectively; δ is a constant. (Solution: See S13.)

3.11 The NLSE Describing the Water Waves in the Infinite Water Depth [127]

$$i(\psi_t + c_g\psi_x) - \frac{\omega_0}{8k_0^2}\psi_{xx} - \frac{1}{2}\omega_0k_0^2|\psi|^2\psi = 0, \tag{16}$$

where $c_g = \partial\omega/\partial k$ is the group velocity. The angular frequency $\omega_0 = \sqrt{gk_0}$, where k_0 and g are the wave number and the acceleration due to gravity, respectively. (Solution: See S14.)

4 PEREGRINE SOLITONS WITH EXTERNAL POTENTIALS

This section deals with reviewing the Peregrine soliton solutions reported in the NLSE with diverse external potentials. In nonlinear dynamics, a waveform which can exhibit a localized translation resulting from the counteracting dispersive and nonlinear effects is coined as “soliton”. Such classical soliton is also referred to as autonomous soliton, owing to the role of time as an independent variable and its absence in the nonlinear evolution equation. Those autonomous solitons can preserve their shape and velocity before and after collisions with an introduction of a phase shift [5]. However, in real circumstances, physical systems may be subjected to external space- and time-dependent forces. In such a case, these systems are known as nonautonomous systems and their corresponding solitons are known as nonautonomous solitons [128–130]. Furthermore, it is confirmed that solitons in such systems still have the ability to preserve their profile after collisions and adapt to the external potentials as well as to dispersive and nonlinear variations, but sacrificing the stability in amplitude, speed, and spectra [116, 131, 132]. In addition, such nonautonomous NLSEs can be generalized to describe the unusual phenomenon of rogue waves in different situations [85, 105, 123, 133–137]. Those rogue waves are characterized by spatiotemporal localization and possess the amplitudes greater than twice as that of the surrounding background [11, 13, 17, 18]. Further, dynamics of such rogue waves have been demonstrated experimentally in nonlinear optics [23, 24, 27, 138], plasma physics [139], Bose-Einstein condensation (BEC) [73], and atmospheric dynamics [140]. One of the basic waveforms of the rogue wave is the Peregrine soliton [11] whose appearance in the nonautonomous NLSEs under the influence of various external potentials will be presented below.

4.1 The Gross-Pitaevskii (GP) Equation Describing Matter Rogue Wave in BEC With Time-Dependent Attractive Interatomic Interaction in Presence of an Expulsive Potential [141]

$$i\psi_t - \frac{1}{2}\psi_{xx} + a(t)|\psi|^2\psi + \frac{1}{2}\lambda^2x^2\psi = 0, \tag{17}$$

where $a(t)$ is the nonlinear coefficient, defined by $a(t) = |a_s(t)|/a_B$ with $a_s(t)$ the s-wave scattering length and a_B the Bohr radius. The aspect ratio is given by $\lambda = |\omega_0|/\omega_\perp$, where ω_0 and ω_\perp are oscillator frequencies in the direction of cigar and transverse axes, respectively. (Solution: See S15.)

4.2 A Generic (1 + 1)-Dimensional NLSE With Variable Coefficients in Dimensionless Form [142]

$$i\psi_t + \frac{D}{2}\psi_{xx} - g|\psi|^2\psi - V\psi = 0, \tag{18}$$

where D and g represent the coefficient of dispersion and nonlinearity and V is an external potential denoting the trap confining the atoms in BECs. (Solutions: See S16 & S17.)

4.3 NLSE Describing the Nonlinear Optical Systems With the Spatially Modulated Coefficients in Presence of a Special Quadratic External Potential in the Dimensionless Form [143]

$$i\psi_z + d(x)\psi_{xx} + 2\gamma(z, x)|\psi|^2\psi + V(z, x)\psi = 0. \tag{19}$$

Here, $d(x)$ and $\gamma(z, x)$ are the diffraction and the nonlinearity coefficients, respectively. $V(z, x) = d(x)(ax^2 + b)$ denotes the external potential modulated by the diffraction coefficient, with a and b being the real constants. (Solution: See S18.)

4.4 A GNLSE With Distributed Coefficients Describing the Amplification or Absorption of Optical Pulse Propagating Through a Monomode Optical Fiber [144]

$$i\psi_z - \frac{1}{2}\beta(z)\psi_{tt} + \gamma(z)|\psi|^2\psi + id(z)\psi = 0, \tag{20}$$

where $\beta(z)$, $\gamma(z)$, and $d(z)$ are GVD, nonlinearity, and amplification/absorption coefficients, respectively. (Solution: See S19.)

4.5 NLSE Describing the Rogue Wave Dynamics under a Linear Potential [105]

$$i\psi_t + \frac{1}{2}\psi_{xx} + \gamma(t)(x - x_0(t)) + |\psi|^2\psi = 0, \tag{21}$$

where $\gamma(t)$ and $x_0(t)$ are real arbitrary functions. (Solutions: See S20 & S21.)

4.6 NLSE Describing Rogue Wave Under a Quadratic Potential [105]

$$i\psi_t + \frac{1}{2}\psi_{xx} + \frac{1}{2}(\dot{\gamma}^2 - \ddot{\gamma})x^2\psi + e^\gamma|\psi|^2\psi = 0, \tag{22}$$

where $\gamma(t)$ is an integrability condition of the above equation, relating the coefficients of the quadratic potential and the nonlinearity. (Solution: See S22.)

4.7 A GP Equation With an External Potential Describing the Mean Field Dynamics of a Quasi-One-Dimensional BEC [145]

$$i\psi_t + \frac{1}{2}\psi_{xx} + \gamma(t)|\psi|^2\psi + V(x, t)\psi - \frac{i}{2}g(t)\psi = 0, \tag{23}$$

where the nonlinearity parameter is defined by $\gamma(t) = \frac{a_s(t)}{a_B}$, with $a_s(t)$ the scattering length and a_B the Bohr radius. $V(x, t) = \frac{1}{2}\Omega^2(t)x^2 + h(t)x$ denotes the external potential, $\Omega^2(t) = \frac{\omega_0^2(t)}{\omega_\perp^2}$ with ω_0 and ω_\perp representing the trap frequency in the axial direction and the radial trap frequency, respectively. $h(t)$ and $g(t)$ denote the linear potential and gain/loss coefficients for atomic and thermal cloud. (Solution: See S23.)

4.8 A GNLSE Describing the Pulse Propagation Through Tapered Graded-Index Nonlinear Waveguide Amplifier [146]

$$i\psi_z + \frac{1}{2}\psi_{xx} + F(z)\frac{x^2}{2}\psi - \frac{i}{2}G(z)\psi + |\psi|^2\psi = 0, \tag{24}$$

where $F(z)$ and $G(z)$ are the dimensionless tapering function and gain profile, respectively. (Solutions: See S24 & S25.)

4.9 The Propagation of Rogue Waves Described by a Nonautonomous NLSE With an External Harmonic Potential [147]

$$i\psi_t + \frac{\alpha(t)}{2}\psi_{xx} + \left(-i\gamma(t) + \frac{\omega(t)r^2}{2} + \beta(t)|\psi|^2\right)\psi = 0, \tag{25}$$

where $\alpha(t)$, $\gamma(t)$, and $\beta(t)$ represent the coefficients of the dispersion, the distributed gain/loss, and the Kerr nonlinearity, respectively. $\omega(t)r^2/2$ represents the harmonic potential. (Solutions: See S26 & S27.)

4.10 An Inhomogeneous NLSE With an External Potential to Tune the Width and Shape of the Pulse [148]

$$i\psi_t + \psi_{xx} + 2|\psi|^2\psi + \alpha^2x^2\psi + i\alpha\psi = 0, \tag{26}$$

where α is a real number. (Solution: See S28.)

4.11 The (1 + 1)-Dimensional Nonautonomous NLSE With a Linear Potential [149]

$$i\psi_z + \frac{\beta(z)}{2}\psi_{tt} + \chi(z)|\psi|^2\psi - 2\alpha(z)t\psi - i\gamma(z)\psi = 0, \quad (27)$$

where $\beta(z)$ and $\chi(z)$ are the coefficients of varying dispersion and nonlinearity, respectively. The term $2\alpha(z)t\psi$ denotes an approximate form of self-induced Raman effect. $\gamma(z)$ is the gain parameter. (Solutions: See S29 & S30.)

4.12 A Nonautonomous NLSE With Variable Coefficients in Presence of Varying Linear and Harmonic Potentials Describing the Optical Pulse Propagation [150]

$$i\psi_z(z, t) + \frac{d(z)}{2}\psi_{tt}(z, t) + r(z)|\psi(z, t)|^2\psi(z, t) + \nu_1(z)t\psi(z, t) + \nu_2(z)t^2\psi(z, t) = 0, \quad (28)$$

where $d(z)$ describes the varying dispersion. $r(z)$ is a transformation coefficient that relates the nonlinear coefficient with the gain/loss coefficient. $\nu_1(z)$ and $\nu_2(z)$ denote the varying linear and harmonic potential, respectively. (Solution: See S31.)

4.13 A NLSE Describing Varying Dispersion With an External Harmonic Oscillator Potential [151]

$$i\psi_z + \frac{D(z)}{2}\psi_{tt} + R(z)|\psi|^2\psi + i(\alpha(z) + \delta D(z)P(z)t)\psi_t - \frac{\Gamma(z)}{2}\psi = 0. \quad (29)$$

Here $D(z)$, $R(z)$, $\alpha(z)$, $P(z)$, and $\Gamma(z)$ are varying dispersion in a harmonic oscillator potential form, varying nonlinearity, velocity of propagation, nonlinear focus length, and gain/loss coefficient, respectively. (Solutions: See S32 & S33.)

4.14 NLSE With Spatially Modulated Coefficients and a Special External Potential in the Dimensionless Form [39]

$$i\psi_z + \frac{1}{2}\beta(x)\psi_{xx} + \chi(x)|\psi|^2\psi + \frac{1}{2}\beta(x)\left(-\frac{1}{4}x^2 + m + \frac{1}{2}\right)\psi = 0. \quad (30)$$

Here, $\beta(x)$ and $\chi(x)$ denote coefficients of the diffraction and the nonlinearity, respectively. The external potential is a simple quadratic potential modulated by the diffraction coefficient,

where m is a nonnegative integer referred to as the quantum modal parameter. (Solution: See S34.)

4.15 A Quasi-One-Dimension Gross-Pitaevskii Equation Describing BEC With Time-Dependent Quadratic Trapping Potential [152]

$$i\psi_t + \frac{1}{2}\psi_{xx} + \sigma\gamma(t)|\psi|^2\psi + f(t)\frac{x^2}{2}\psi + h(t)x\psi - \frac{i}{2}g(t)\psi = 0. \quad (31)$$

Here $\gamma(t) = 2a_s(t)/a_B$ with a_s and a_B being the atomic scattering length and the Bohr radius. Further, $f(t) = -\omega_0^2(t)/\omega_\perp^2$, $h(t) = -\alpha(t)/\omega_\perp^2 a_\perp$, and $g(t) = \eta(t)/\hbar\omega_\perp$ are the atoms confined in a cylindrical trap, time-dependent parabolic trap, and linear time-dependent potential, respectively, with $a_\perp = (\hbar/m\omega_\perp)^{1/2}$. Here, $\sigma = +1(-1)$ corresponds to $a_s(t) < 0(> 0)$ defining attractive (repulsive) time-dependent scattering length. ω_0 and ω_\perp are the trap frequency in the axial direction and the radial trap frequency, respectively. $\alpha(t)$ and $\eta(t)$ represent the interaction of linear time-dependent potential trap and gain/loss term incorporates the interaction of condensate with normal atomic cloud through three body interactions, respectively. (Solutions: See S35 & S36.)

5 PEREGRINE SOLITONS IN COUPLED NLSES

This section presents the Peregrine soliton solutions reported in the context of coupled NLSEs (CNLSEs), starting from basic vector NLSEs or the Manakov model [153] to the CNLSEs with the effects of higher-order dispersion/diffraction, self-focusing/defocusing, and other higher-order nonlinear effects [109, 154]. Such CNLSEs play a vital role in describing the interaction of multiple components of a vector wave or multiple scalar waves in numerous physical systems. In literature, several reports have demonstrated the significance of the CNLSEs in nonlinear science, namely, birefringent optical fibers [155], BEC [156], oceanic studies [157], biophysics [158], and even finance [159]. Recently, vector rogue waves featured with more than one component have been given special attention in nonlinear science, for their striking dynamics when compared to those of the scalar systems. A plethora of studies has been reported to understand such phenomena, which demonstrate new excitation patterns manifesting the vector rogue waves compared to that of the scalar rogue waves with well-known eye-shaped patterns [16, 160, 161]. Bludov et al. originally reported the numerical existence of the rogue waves in a two-component BEC described by the coupled GP equation with variable scattering lengths [162], followed with substantial analytical studies describing the spatiotemporal distribution of dark rogue waves [163], higher-order solutions [164], and baseband modulation stability featuring bright-dark and dark-dark rogue waves [165]. Furthermore a multi-rogue wave reveals four-petaled flower in

spatiotemporal distribution [166] and resonant interactions [167] in a three-component coupled NLSEs. In addition, these rogue waves have also been found to demonstrate unusual distribution of rogue waves in spatiotemporal distribution plane when compared to the scalar ones. Moreover, integrable mixed CNLSEs (M-CNLSEs) feature-rich solutions of the multi-rogue wave structures including rogue wave doublet, bright-dark composites, bright-dark triplet, and bright-bright and bright-dark quartets are also constructed to understand the rogue wave dynamics in multicomponent physical systems [168]. This section will be confined within our aim to present the Peregrine soliton solution under the framework of CNLSEs.

5.1 A Manakov Model [169–173]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0, \end{aligned} \tag{32}$$

(solutions: See S37, S38, S39, S40, S41, S42 & S43.)

5.2 Special Cases of the Manakov System

i. The Manakov system of the form [174]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2\mu(|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2\mu(|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0, \end{aligned} \tag{33}$$

where μ is a real constant. (Solution: See S44.)

ii. The two-coupled NLSE describing the wave evolution dynamics through a two-mode nonlinear fiber in dimensionless form [175]

$$\begin{aligned} i\psi_{1z} + \psi_{1tt} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2z} + \psi_{2tt} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0. \end{aligned} \tag{34}$$

(Solution: See S45.)

iii. The Manakov model in the normal dispersion regime [63]

$$\begin{aligned} i\psi_{1z} - \psi_{1tt} + \sigma(|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2z} - \psi_{2tt} + \sigma(|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0, \end{aligned} \tag{35}$$

where z , t , σ are the propagation distance, retarded time, and the strength of the cubic nonlinearity, respectively. (Solution: See S46.)

iv. The focusing CNLSE of the form [38, 164]

$$\begin{aligned} i\psi_{1t} + \frac{1}{2}\psi_{1xx} + (|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2t} + \frac{1}{2}\psi_{2xx} + (|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0. \end{aligned} \tag{36}$$

(Solutions: See S47 & S48.)

v. The Manakov system [165]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} - 2s(|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} - 2s(|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0, \end{aligned} \tag{37}$$

where the constant s takes the value -1 or $+1$ for focusing or defocusing regime, respectively. (Solution: See S49.)

vi. The Manakov system describing the propagation of optical pulses through the birefringent optical fibers [176]

$$\begin{aligned} i\psi_{1x} + \frac{D}{2}\psi_{1tt} + (|\psi_1|^2 + |\psi_2|^2)\psi_1 &= 0, \\ i\psi_{2x} + \frac{D}{2}\psi_{2tt} + (|\psi_1|^2 + |\psi_2|^2)\psi_2 &= 0. \end{aligned} \tag{38}$$

Dispersion (D) indicates the normal dispersion for ($D = -1$) and the anomalous dispersion for ($D = 1$). (Solution: See S50.)

5.3 The Three-Component CNLSE [177]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_2 &= 0, \\ i\psi_{3t} + \psi_{3xx} + 2(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_3 &= 0. \end{aligned} \tag{39}$$

5.4 A Special Case of Eq. (39): The Three-Component CNLSE [178]

$$\begin{aligned} i\psi_{1t} + \frac{1}{2}\psi_{1xx} + (|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_1 &= 0, \\ i\psi_{2t} + \frac{1}{2}\psi_{2xx} + (|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_2 &= 0, \\ i\psi_{3t} + \frac{1}{2}\psi_{3xx} + (|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_3 &= 0. \end{aligned} \tag{40}$$

(Solutions: See S51 & S52.)

5.5 The Three-Component Manakov System in the Defocusing Regime [179]

$$\begin{aligned} i\psi_{1z} + i\delta\psi_{1t} + \psi_{1tt} - \sigma(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_1 &= 0, \\ i\psi_{2z} - i\delta\psi_{2t} + \psi_{2tt} - \sigma(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_2 &= 0, \\ i\psi_{3z} + \psi_{3tt} - \sigma(|\psi_1|^2 + |\psi_2|^2 + |\psi_3|^2)\psi_3 &= 0, \end{aligned} \tag{41}$$

where δ denotes the group velocity mismatch and σ describes the coefficient of cubic nonlinearity. (Solution: See S53.)

5.6 The CNLSE Describing the Nonlinear Interaction of the Short Wave (A) and the Long Wave (U) [180]

$$\begin{aligned} i\frac{\partial A}{\partial \xi} + \frac{1}{2}\frac{\partial^2 A}{\partial \tau^2} + UA &= 0, \\ \frac{\partial U}{\partial \xi} - \frac{\partial |A|^2}{\partial \tau} &= 0. \end{aligned} \tag{42}$$

(Solution: See S54.)

5.7 The Integrable M-CNLS [168]

$$i\psi_t^{(l)} + \psi_{xx}^{(l)} + \psi^{(l)} \sum_{j=1}^M \delta_j |\psi^{(j)}|^2 = 0, \quad l = 1, 2, \dots, M. \quad (43)$$

Here δ_j s can be positive (negative) value defining focusing (defocusing) nonlinearity. (Solution: See S55.)

5.8 A Two-Coupled NLSE in Dimensionless Form [163]

$$\begin{aligned} i\psi_{1z} + \sigma_1 \psi_{1tt} + [2g_1 |\psi_1|^2 + 2g_2 |\psi_2|^2] \psi_1 &= 0, \\ i\psi_{2z} + \sigma_2 \psi_{2tt} + [2g_1 |\psi_1|^2 + 2g_2 |\psi_2|^2] \psi_2 &= 0, \end{aligned} \quad (44)$$

where σ_1 and σ_2 define the sign of GVD, taking the value +1 or -1 for anomalous or normal GVD, respectively. g_1 and g_2 are nonlinearity parameters determining the properties of Kerr medium with electrostriction mechanism. (Solution: See S56.)

5.9 The Coupled Derivative NLSE [181]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} - \frac{2}{3} i\epsilon [(|\psi_1|^2 + |\psi_2|^2) \psi_1]_x &= 0, \\ i\psi_{2t} + \psi_{2xx} - \frac{2}{3} i\epsilon [(|\psi_1|^2 + |\psi_2|^2) \psi_2]_x &= 0, \end{aligned} \quad (45)$$

where ϵ takes the value ± 1 . (Solution: See S57.)

5.10 A CNLSE With Negative Coherent Coupling Describing the Propagation of Orthogonally Polarized Optical Waves in an Isotropic Medium [182]

$$\begin{aligned} i\psi_{1z} + \psi_{1tt} + 2(|\psi_1|^2 + 2|\psi_2|^2) \psi_1 - 2\psi_1^* \psi_2^2 &= 0, \\ i\psi_{2z} + \psi_{2tt} + 2(2|\psi_1|^2 + |\psi_2|^2) \psi_2 - 2\psi_1^2 \psi_2^* &= 0. \end{aligned} \quad (46)$$

(Solutions: See S58 & S59.)

5.11 An Integrable Generalization of the CNLSE [183]

$$\begin{aligned} \psi_{1xt} + \alpha\beta^2 \psi_1 - 2i\alpha\beta \psi_{1x} - \alpha\psi_{1xx} + i\alpha\beta^2 \psi_1 \psi_2 \psi_{1x} &= 0, \\ \psi_{2xt} + \alpha\beta^2 \psi_2 - 2i\alpha\beta \psi_{2x} - \alpha\psi_{2xx} - i\alpha\beta^2 \psi_1 \psi_2 \psi_{2x} &= 0, \end{aligned} \quad (47)$$

where α and β are constants. (Solution: See S60.)

5.12 A Coupled NLSE With Special External Potential in a Parabolic Form [184]

$$\begin{aligned} i\psi_{1z} + \beta(x) \psi_{1xx} + 2\chi(x) (|\psi_1|^2 + |\psi_2|^2) \psi_1 + U(x) \psi_1 &= 0, \\ i\psi_{2z} + \beta(x) \psi_{2xx} + 2\chi(x) (|\psi_1|^2 + |\psi_2|^2) \psi_2 + U(x) \psi_2 &= 0, \end{aligned} \quad (48)$$

where $U(x) = \beta(x)(ax^2 + b)$ is a parabolic external potential modulated by the diffraction coefficient, with real constants a

and b . $\beta(x)$ and $\chi(x)$ denote the effective diffraction coefficient and the nonlinearity coefficient, respectively. (Solution: See S61.)

5.13 The Gross-Pitaevskii Equations [185]

$$\begin{aligned} i\psi_{1t} &= -\psi_{1xx} + (g_1 |\psi_1|^2 + g |\psi_2|^2) \psi_1 + \beta(t) \psi_2, \\ i\psi_{2t} &= -\psi_{2xx} + (g |\psi_1|^2 + g_2 |\psi_2|^2) \psi_2 + \beta(t) \psi_1, \end{aligned} \quad (49)$$

where g_1 and g_2 are the dimensionless nonlinear coefficients for the quasi-one-dimensional condensate. The factor g can take two values $g = \pm 1$. The $\beta(t)$ in the last term can be used to switch between the two hyperfine states, originated from the external magnetic field. (Solution: See S62.)

5.14 A Coupled GNLSE [186]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} - 2\psi_1^2 \psi_2 + 4\beta^2 \psi_1^3 \psi_2^2 + 4i\beta (\psi_1 \psi_2)_x \psi_1 &= 0, \\ i\psi_{2t} - \psi_{2xx} + 2\psi_1 \psi_2^2 - 4\beta^2 \psi_1^2 \psi_2^3 + 4i\beta (\psi_1 \psi_2)_x \psi_2 &= 0, \end{aligned} \quad (50)$$

where β is a constant, describing the strength of higher-order terms. (Solution: See S63.)

5.15 A CNLSE [187]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2(|\psi_1|^2 + 2|\psi_2|^2) \psi_1 - 2\psi_1^* \psi_2^2 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2(|\psi_2|^2 + 2|\psi_1|^2) \psi_2 - 2\psi_2^* \psi_1^2 &= 0. \end{aligned} \quad (51)$$

(Solution: See S64.)

5.16 The Two-Component CNLSE With Four-Wave Mixing Term [188]

$$\begin{aligned} i\psi_{1t} + \frac{1}{2} \psi_{1xx} + \sigma (|\psi_1|^2 + 2|\psi_2|^2) \psi_1 + \sigma \psi_2^2 \psi_1^* &= 0, \\ i\psi_{2t} + \frac{1}{2} \psi_{2xx} + \sigma (2|\psi_1|^2 + |\psi_2|^2) \psi_2 + \sigma \psi_1^2 \psi_2^* &= 0, \end{aligned} \quad (52)$$

where $\sigma = \pm 1$ accounts for attractive (+) or repulsive (-) interactions.

5.17 A Special Case of Eq. 52: An Integrable CNLSE [189]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2|\psi_1|^2 \psi_1 + 4|\psi_2|^2 \psi_1 + 2\psi_2^2 \psi_1^* &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2|\psi_2|^2 \psi_2 + 4|\psi_1|^2 \psi_2 + 2\psi_1^2 \psi_2^* &= 0. \end{aligned} \quad (53)$$

(Solutions: See S65 & S66.)

5.18 The Evolution of Two Orthogonally Polarized Components in an Isotropic Medium Described by the Normalized CNLSE [190, 191]

$$\begin{aligned} i\psi_{1z} + \psi_{1tt} + 2(|\psi_1|^2 - 2|\psi_2|^2) \psi_1 - 2\psi_1^* \psi_2^2 &= 0, \\ i\psi_{2z} + \psi_{2tt} + 2(2|\psi_1|^2 - |\psi_2|^2) \psi_2 + 2\psi_2^* \psi_1^2 &= 0. \end{aligned} \quad (54)$$

(Solutions: See S67 & S68.)

5.19 A System of Linearly Coupled NLSEs for Field Variables [60]

$$\begin{aligned} i\psi_{1z} &= -\psi_{1xx} + (\chi_1|\psi_1|^2 + \chi|\psi_2|^2)\psi_1 + i\gamma\psi_1 - \psi_2, \\ i\psi_{2z} &= -\psi_{2xx} + (\chi|\psi_1|^2 + \chi_1|\psi_2|^2)\psi_2 - i\gamma\psi_2 - \psi_1, \end{aligned} \quad (55)$$

where χ_1 and χ denote the SPM and XPM coefficients, respectively. γ represents the PT-balanced gain. (Solution: See S69.)

5.20 A CNLSE Describing the Dynamics of Light Propagation Through PT-Symmetric Coupled Waveguides [192]

$$\begin{aligned} i\psi_{1z} + \frac{1}{2}\psi_{1xx} + (\chi_1|\psi_1|^2 + \chi|\psi_2|^2)\psi_1 &= -\psi_2 + i\gamma\psi_1, \\ i\psi_{2z} + \frac{1}{2}\psi_{2xx} + (\chi|\psi_1|^2 + \chi_1|\psi_2|^2)\psi_2 &= -\psi_1 - i\gamma\psi_2, \end{aligned}$$

where the parameters χ (or $\chi_1 > 0$) and χ (or $\chi_1 < 0$) correspond to the focusing and defocusing case, respectively. The γ in the last term describes PT-balanced gain in the first and loss in the second waveguide. The relation $\psi_2(x, z) = \pm \psi_1(x, z)\exp(\pm i\theta)$ is used which casts above equations into the single equation of the form

$$i\psi_z + \frac{1}{2}\psi_{xx} + (\chi_1 + \chi)|\psi|^2\psi \pm \cos(\theta)\psi = 0. \quad (56)$$

(Solutions: See S70 & S71.)

5.21 A CNLSE With the Four-Wave Mixing Term Which Describes the Pulse Propagation in a Birefringent Fiber [193–196]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2(a|\psi_1|^2 + c|\psi_2|^2 + b\psi_1\psi_2^* + b^*\psi_1^*\psi_2)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2(a|\psi_1|^2 + c|\psi_2|^2 + b\psi_1\psi_2^* + b^*\psi_1^*\psi_2)\psi_2 &= 0. \end{aligned} \quad (57)$$

Here a and c are real constants, describing the self-phase modulation and cross-phase modulation effects, respectively. b is a complex constant, describing the four-wave mixing effects. (Solutions: See S72, S73, S74 & S75.)

5.22 A Focusing-Defocusing Type CNLSE [197]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2\gamma(|\psi_1|^2 - |\psi_2|^2)\psi_1 - \gamma(\psi_1^2 + \psi_2^2)\psi_1^* &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2\gamma(|\psi_1|^2 - |\psi_2|^2)\psi_2 + \gamma(\psi_1^2 + \psi_2^2)\psi_2^* &= 0, \end{aligned} \quad (58)$$

where γ denotes the strength of nonlinearity. (Solution: See S76.)

5.23 A CNLSE With Variable Coefficients [198]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + v(x, t)\psi_1 + g(t)(|\psi_1|^2 + |\psi_2|^2)\psi_1 + i\gamma(t)\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + v(x, t)\psi_2 + g(t)(|\psi_1|^2 + |\psi_2|^2)\psi_2 + i\gamma(t)\psi_2 &= 0, \end{aligned} \quad (59)$$

where $v(x, t)$, $g(t)$, and $\gamma(t)$ are the coefficients of the external potential, nonlinearity, and gain, respectively. (Solutions: See S77 & S78.)

5.24 The Generalized CNLSE for Two Components [199]

$$\begin{aligned} i\psi_{1z} + \alpha_1(z)\psi_{1xx} + \beta_1(z)|\psi_1|^2\psi_1 + \delta_1(z)|\psi_2|^2\psi_1 + \nu_1(x, z)\psi_1 \\ + i\gamma_1(z)\psi_1 = 0, \quad i\psi_{2z} + \alpha_2(z)\psi_{2xx} + \beta_2(z)|\psi_1|^2\psi_2 \\ + \delta_2(z)|\psi_2|^2\psi_2 + \nu_2(x, z)\psi_2 + i\gamma_2(z)\psi_2 = 0, \end{aligned} \quad (60)$$

where $\alpha_1(z)$ and $\alpha_2(z)$ are diffraction (dispersion) coefficients. $\beta_1(z)$ and $\beta_2(z)$ are nonlinear coefficients. $\delta_1(z)$ and $\delta_2(z)$ are the coefficient of gain/loss. ν_1 and ν_2 are the two real valued functions of spatial coordinates x and z , describing the external potentials. γ_1 and γ_2 are real valued functions of the propagation distance z . (Solutions: See S79 & S80.)

5.25 The Coupled Inhomogeneous NLSE [200]

$$\begin{aligned} i\psi_{1t} + \psi_{1xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_1 - (\alpha x - \beta^2 x^2)\psi_1 + i\beta\psi_1 &= 0, \\ i\psi_{2t} + \psi_{2xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_2 - (\alpha x - \beta^2 x^2)\psi_2 + i\beta\psi_2 &= 0, \end{aligned} \quad (61)$$

where α denotes the coefficient of the linear density profile and β is the coefficient of damping. αx and $\beta^2 x^2$ correspond to the linear and parabolic density profiles. (Solution: See S81.)

5.26 The Higher-Order CNLSE With Variable Coefficients [201]

$$\begin{aligned} i\psi_{jz} - \frac{1}{2}\beta_2(z)\psi_{jtt} - \gamma(z)\left(\sum_{n=1}^2 a_{nj}|\psi_n|^2\right)\psi_j + i\beta_3(z)\psi_{jtt} \\ + i\chi(z)\left(\sum_{n=1}^2 a_{nj}|\psi_n|^2\right)\psi_{jt} + i\delta(z)\left(\sum_{n=1}^2 a_{nj}\psi_n\psi_j^*\right)\psi_j \\ + i\Gamma(z)\psi_j = 0, \quad j = 1, 2. \end{aligned} \quad (62)$$

Here $\beta_2(z)$, $\gamma(z)$, $\beta_3(z)$, $\chi(z)$, $\delta(z)$, and $\Gamma(z)$ are coefficients of group velocity dispersion, nonlinearity (SPM and XPM), TOD, SS, SFS, and loss/gain, respectively. (Solution: See S82.)

5.27 The Coupled Hirota Equations [202]

$$\begin{aligned}
 i\psi_{1t} + \frac{1}{2}\psi_{1xx} + (|\psi_1|^2 + |\psi_2|^2)\psi_1 + i\epsilon[\psi_{1xxx} + (6|\psi_1|^2 + 3|\psi_2|^2)\psi_{1x} \\
 + 3\psi_1\psi_2^*\psi_{2x}] = 0, \quad i\psi_{2t} + \frac{1}{2}\psi_{2xx} + (|\psi_1|^2 + |\psi_2|^2)\psi_2 \\
 + i\epsilon[\psi_{2xxx} + (6|\psi_2|^2 + 3|\psi_1|^2)\psi_{2x} + 3\psi_2\psi_1^*\psi_{1x}] = 0,
 \end{aligned}
 \tag{63}$$

where ϵ is a constant that provides the strength of higher-order effects and scales the integrable perturbations of the simple Manakov system. (Solutions: See S83 & S84.)

5.28 A Coupled Cubic-Quintic NLSE Describing the Pulse Propagation in Non-Kerr Media [203]

$$\begin{aligned}
 i\psi_{1z} + \psi_{1tt} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_1 + (\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)^2\psi_1 \\
 - 2i[(\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)\psi_1]_t + 2i(\rho_1\psi_1^*\psi_{1t} + \rho_2\psi_2^*\psi_{2t})\psi_1 \\
 = 0, \quad i\psi_{2z} + \psi_{2tt} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_2 + (\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)^2\psi_2 \\
 - 2i[(\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)\psi_2]_t + 2i(\rho_1\psi_1^*\psi_{1t} + \rho_2\psi_2^*\psi_{2t})\psi_2 = 0,
 \end{aligned}
 \tag{64}$$

where ρ_1 and ρ_2 are the real parameters. (Solution: See S85.)

5.29 A Coupled Cubic-Quintic NLSE Describing the Effects of Quintic Nonlinearity on the Propagation of Ultrashort Pulse in a Non-Kerr Media [204]

$$\begin{aligned}
 i\psi_{1t} + \psi_{1xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_1 + (\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)^2\psi_1 \\
 - 2i[(\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)\psi_1]_x + 2i(\rho_1\psi_1^*\psi_{1x} + \rho_2\psi_2^*\psi_{2x})\psi_1 \\
 = 0, \quad i\psi_{2t} + \psi_{2xx} + 2(|\psi_1|^2 + |\psi_2|^2)\psi_2 + (\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)^2\psi_2 \\
 - 2i[(\rho_1|\psi_1|^2 + \rho_2|\psi_2|^2)\psi_2]_x + 2i(\rho_1\psi_1^*\psi_{1x} + \rho_2\psi_2^*\psi_{2x})\psi_2 = 0,
 \end{aligned}
 \tag{65}$$

where ρ_1 and ρ_2 are real constants. (Solution: See S86.)

5.30 A Fourth-Order CNLSE Describing the Ultrashort Pulse Propagation in a Birefringent Optical Fiber [205]

$$\begin{aligned}
 i\psi_{at} + \psi_{\alpha\alpha\alpha\alpha} + 2\psi_{\alpha} \sum_{\rho=1}^2 |\psi_{\rho}|^2 + \gamma \left[\psi_{\alpha\alpha\alpha\alpha\alpha} + 2\psi_{\alpha} \sum_{\rho=1}^2 |\psi_{\rho\alpha}|^2 \right. \\
 + 2\psi_{\alpha\alpha} \sum_{\rho=1}^2 \psi_{\rho} \psi_{\rho\alpha}^* + 6\psi_{\alpha\alpha} \sum_{\rho=1}^2 \psi_{\rho}^* \psi_{\rho\alpha} + 4\psi_{\alpha\alpha\alpha} \sum_{\rho=1}^2 |\psi_{\rho}|^2 \\
 + 4\psi_{\alpha} \sum_{\rho=1}^2 \psi_{\rho}^* \psi_{\rho\alpha\alpha} + 2\psi_{\alpha} \sum_{\rho=1}^2 \psi_{\rho} \psi_{\rho\alpha\alpha}^* + 6\psi_{\alpha} \left(\sum_{\rho=1}^2 |\psi_{\rho}|^2 \right)^2 \left. \right] \\
 = 0,
 \end{aligned}
 \tag{66}$$

where $\alpha = 1, 2$. γ is a real parameter that denotes the strength of higher-order linear and nonlinear effects. (Solution: See S87.)

5.31 A NLS-Type System With Self-Consistent Sources Associated With the Two-Component Homogeneous Plasma [206]

$$\begin{aligned}
 \psi_{1t} - \frac{i\alpha}{2}\psi_{1xx} + i\alpha\sigma|\psi_1|^2\psi_1 - k_0\psi_2\psi_3^* = 0, \\
 \psi_{2x} - \psi_1\psi_3 = 0, \quad \psi_{3x} - 2ik_0\psi_3 - \sigma\psi_1^*\psi_2 = 0,
 \end{aligned}
 \tag{67}$$

where α , σ , and k_0 denote the coefficients of dispersion, nonlinearity, and coupling, respectively. (Solution: See S88.)

6 PEREGRINE SOLITONS IN DISCRETE NLSE

This section delivers the Peregrine soliton solutions presented in the literature in the framework of discrete NLSEs. Since its origin from the mid-1960s, the general NLSE of continuous form plays a significant role in unraveling the physical phenomena and insights which lead to numerous scientific and technological applications in various nonlinear systems. Further, owing to its outstanding versatility, different forms of continuous NLSEs, namely, scalar and vector NLSEs, have been proposed with suitable additional terms to predict various dynamical situations in numerous nonlinear systems [90, 109, 207]. From the past three decades, apart from continuous nonlinear systems, considerable efforts have also been made to investigate the nonlinear discrete systems characterized by structural discontinuities and lattices. These systems find potential applications in electronic circuits [208, 209], optical waveguides

[210], nonlinear lattices [211], spatial energy concentrators [212], coupled nonlinear waveguide arrays [213], BEC trapped in periodic optical lattices [214], photorefractive crystals [215], and so forth. Those nonlinear discrete systems, discrete NLSEs, can be modeled through discretizing the continuous NLSE via appropriate transformations. In such discrete NLSEs, the energy evolution is in a semidiscrete form characterized by the spatial discretization and temporal continuity [90].

Additionally, the pioneering work by Ablowitz and Ladik led to a cutting-edge method for constructing a family of semidiscrete and doubly discrete nonlinear systems associated with their linear operator pairs, necessary for obtaining the solutions of the nonlinear systems via the inverse scattering transform (IST) [216]. Further, those formulations include an integrable semidiscretization of NLSE as well as doubly discrete integrable NLSE referred to as integrable discrete NLSE (IDNLSE) [217]. These equations form basic discrete equations which serve as a model for the plethora of applications where exact solutions can be realized through diverse methods such as Darboux and Bäcklund transformations in addition to the IST [86, 87, 89, 90, 93, 218]. Firstly, the DNLSE was reported by Christodoulides et al., in a nonlinear array of coupled waveguides displaying discrete self-focusing [219], followed by the experimental realization of discrete spatial solitons in AlGaAs nonlinear waveguide arrays [213]. Solitons resulting in these systems are due to the interplay between discreteness and self-trapping nonlinearity and coined as spatial discrete solitons or lattice solitons [220]. On the other hand, Peregrine solitons of DNLSEs display different dynamical behavior compared to that of the continuous counterpart and find interesting applications in spatial energy concentrators [212], photonic lattices [221], anharmonic lattices [222], Heisenberg spin chains [223], self-trapping on a dimer [224], and so forth. These Peregrine solitons that arise in discrete systems are studied in a broad category under the context of i) the DNLSEs [90, 219], ii) the Ablowitz-Ladik equations [90, 225], iii) the discrete Hirota equations (a combination of DNLSE and discrete complex modified KdV equations) [90, 226], and iv) the Salerno equation (an interpolation of the cubic DNLSE and the integrable Ablowitz-Ladik equation) [227]. Here, we present the class of DNLSEs where the Peregrine solitons were reported.

6.1 The Focusing and Defocusing Ablowitz-Ladik (AL) Equation [228]

$$i \frac{d\psi_n}{dt} = (1 \pm |\psi_n|^2)(\psi_{n+1} + \psi_{n-1}). \tag{68}$$

In the above AL equation, the term $|\psi_n|^2$ with + and - sign represents focusing and defocusing regimes, respectively. (Solution: See S89.)

6.2 The DNLSE Describing an Array of Coupled Nonlinear Waveguides [229]

$$i \frac{d\psi_n}{dt} + \psi_{n+1} + \psi_{n-1} - 2\psi_n + \sigma |\psi_n|^2 \psi_n = 0. \tag{69}$$

Here, the constant σ takes the value “+ 1” denoting the focusing nonlinearity and “- 1” denoting the defocusing nonlinearity. (Solution: See S90.)

6.3 An Optical Field Propagating Through a Tight Binding Waveguide Array Described by the DNLSE [230]

$$i \frac{d\psi_j}{dz} = -J_j(\psi_{j+1} + \psi_{j-1}) + V_j \psi_j + g |\psi_j|^2 \psi_j, \tag{70}$$

where J_j is the coupling coefficient between j -th waveguide and adjacent waveguides. V_j is the propagation constant of the j -th waveguide. g is the constant describing nonlinear interaction. (Solution: See S91.)

6.4 The Discrete NLSE [231]

$$i \frac{d\psi_n}{dt} = \psi_{n+1} - 2\psi_n + \psi_{n-1} + \psi_n \psi_n^* (\psi_{n+1} + \psi_{n-1}). \tag{71}$$

(Solution: See S92.)

6.5 The Integrable AL Equation [232, 233]

$$i \frac{d\psi_n}{dt} + (\psi_{n-1} + \psi_{n+1})(1 + |\psi_n|^2) - 2\psi_n = 0. \tag{72}$$

(Solutions: See S93 & S94.)

6.6 The Modified AL Equation [234]

$$i \frac{d\psi_n}{dt} + (\psi_{n-1} + \psi_{n+1})(1 + |\psi_n|^2) - 2(q^2 + 1)\psi_n = 0. \tag{73}$$

(Solution: See S95.)

6.7 The Generalized Ablowitz-Ladik-Hirota Lattice Equation With Variable Coefficients [235]

$$i\psi_{n,t} + [\Lambda(t)\psi_{n+1} + \Lambda^*(t)\psi_{n-1}](1 + g(t)|\psi_n|^2) - 2v_n(t)\psi_n + i\gamma(t)\psi_n = 0. \tag{74}$$

Here, the tunnel coupling constant between the sites is given by $\Lambda(t) = \alpha(t) + i\beta(t)$, with $\alpha(t)$ and $\beta(t)$ the differentiable real valued functions. $g(t)$, $v_n(t)$, and $\gamma(t)$ represent time-modulated interstice nonlinearity, space-time-modulated inhomogeneous frequency shift, and time-modulated effective gain/loss constants, respectively. (Solution: See S96.)

6.8 The Generalized Salerno Equation [64]

$$i \frac{d\psi_n}{dt} = -\frac{1}{2} (\psi_{n+1} - 2\psi_n + \psi_{n-1}) - \mu |\psi_n|^2 \psi_n - \frac{1}{2} (1 - \mu) |\psi_n|^2 (\psi_{n+1} + \psi_{n-1}). \tag{75}$$

Above equation corresponds to the DNLS, when $\mu = 1$, and reduces to the AL system, when $\mu = 0$, respectively. (Solution: See S97.)

6.9 The Discrete Hirota Equation [233]

$$i \frac{d\psi_n}{dt} + [(a - ib)\psi_{n-1} + (a + ib)\psi_{n+1}] (1 + |\psi_n|^2) - 2\psi_n = 0. \tag{76}$$

(Solution: See S98.)

6.10 A Spatially Discrete Hirota Equation [236]

$$\begin{aligned} \frac{d\psi_n}{dt} = & \alpha (1 + |\psi_n|^2) [\psi_{n+2} - 2\psi_{n+1} + 2\psi_{n-1} - \psi_{n-2} + \psi_n^* (\psi_{n+1}^2 \\ & - \psi_{n-1}^2) - |\psi_{n-1}|^2 \psi_{n-2} + |\psi_{n+1}|^2 \psi_{n+2} + \psi_n (\psi_{n-1}^* \psi_{n+1} \\ & - \psi_{n+1}^* \psi_{n-1})] - i\beta (1 + |\psi_n|^2) (\psi_{n+1} + \psi_{n-1}) + 2i\beta \psi_n, \end{aligned} \tag{77}$$

where α and β are real constants. (Solution: See S99.)

6.11 A Single Ablowitz-Ladik Equation With Only One Component [237]

$$i \frac{d\psi_n^{(1)}}{dt} + \frac{1}{2h^2} (\psi_{n-1}^{(1)} + \psi_{n+1}^{(1)} - 2\psi_n^{(1)}) + \frac{1}{2} (\psi_{n-1}^{(1)} + \psi_{n+1}^{(1)}) |\psi_n^{(1)}|^2 = 0, \tag{78}$$

where $1/h^2$ is a real coefficient. (Solution: See S100.)

6.12 The Discrete AL Equation [238]

$$i \frac{d\psi_n}{dt} = \frac{\psi_{n+1} + \psi_{n-1} - 2\psi_n}{h^2} + \sigma |\psi_n|^2 (\psi_{n+1} + \psi_{n-1}). \tag{79}$$

Here $\sigma = +1$ and -1 for focusing and defocusing nonlinearity, respectively. h is a real parameter. (Solution: See S101.)

6.13 The Coupled AL Equations Describing the Coupled Discrete Nonlinear Wave Systems [51]

$$\begin{aligned} \psi_{n,t}^{(1)} = & -i(\sigma + |\psi_n^{(1)}|^2) (\psi_n^{(2)*} + \psi_{n-1}^{(2)*}), \\ \psi_{n,t}^{(2)} = & i(\sigma + |\psi_n^{(2)}|^2) (\psi_{n+1}^{(1)*} + \psi_n^{(1)*}). \end{aligned} \tag{80}$$

Here $\sigma = +1$ and -1 denote the focusing and defocusing nonlinearity, respectively. (Solution: See S102.)

6.14 The System of Differential-Difference Equations on the Doubly Infinite Lattice [239, 240]

$$\begin{aligned} i \frac{d\psi_n^{(1)}}{dt} = & \psi_{n+1}^{(1)} - 2\psi_n^{(1)} + \psi_{n-1}^{(1)} - \psi_n^{(1)} \psi_n^{(2)} (\psi_{n+1}^{(1)} + \psi_{n-1}^{(1)}), \\ -i \frac{d\psi_n^{(2)}}{dt} = & \psi_{n+1}^{(2)} - 2\psi_n^{(2)} + \psi_{n-1}^{(2)} - \psi_n^{(1)} \psi_n^{(2)} (\psi_{n+1}^{(2)} + \psi_{n-1}^{(2)}) \end{aligned} \tag{81}$$

with $\psi_n^{(2)} = \sigma \psi_n^{(1)*}$. (Solutions: See S103 & S104.)

6.15 The Coupled AL Equation With Variable Coefficients Describing the Optical Field Through the Tight Binding Waveguide Array [241]

$$\begin{aligned} i \frac{d\psi_n^{(1)}}{dt} + [1 + g_1(t) |\psi_n^{(1)}|^2 + g_2(t) |\psi_n^{(2)}|^2] [\Lambda_1(t) \psi_{n+1}^{(1)} + \Lambda_1^*(t) \psi_{n-1}^{(1)}] \\ - 2v_1(n, t) \psi_n^{(1)} + i\gamma_1(t) \psi_n^{(1)} \\ = 0, i \frac{d\psi_n^{(2)}}{dt} + [1 + g_1(t) |\psi_n^{(2)}|^2 + g_2(t) |\psi_n^{(1)}|^2] [\Lambda_2(t) \psi_{n+1}^{(2)} \\ + \Lambda_2^*(t) \psi_{n-1}^{(2)}] - 2v_2(n, t) \psi_n^{(2)} + i\gamma_1(t) \psi_n^{(2)} = 0. \end{aligned} \tag{82}$$

Here the tunnel coupling coefficients between sites are given by $\Lambda_1(t) = a(t) + ib(t)$, $\Lambda_2(t) = c(t) + id(t)$ with $a(t)$, $b(t)$, $c(t)$, and $d(t)$ being differentiable functions. $g_1(t)$ and $g_2(t)$ denote the time-modulated interstice nonlinearity. The space-time-modulated inhomogeneous frequency shifts are denoted by $v_1(t)$ and $v_2(t)$. $\gamma_1(t)$ and $\gamma_2(t)$ represent the time-modulated effective gain and loss term. (Solution: See S105.)

7 PEREGRINE SOLITONS IN NONLOCAL NLSEs

The objective of this section is to present the existing Peregrine soliton solutions reported in the literature under the context of nonlocal NLSEs. In nonlinear systems, NLSEs play a ubiquitous role in understanding the diverse nonlinear phenomena, finding potential applications from fundamental to advanced technologies [109]. Out of such diverse manifestations of NLSEs, the NLSE with parity-time symmetry has shown an extensive recent research interest. This equation displays invariance under the joint transformations of time $t \rightarrow -t$, space $x \rightarrow -x$ (both time and space reversal symmetry), and complex conjugation. Its original prediction was by Bender et al. in a class of non-Hermitian PT invariant Hamiltonians in quantum mechanics [242]. PT-symmetric systems have gained great attention in diverse fields

of research. Apart from the quantum mechanics, PT-symmetric systems have been investigated in many other physical systems, namely, nonlinear optics [243], plasmonics [244], BEC [245], electronics [246], and acoustics [247]. Such PT-symmetric systems allow the realization of a new class of gain/loss balanced dissipative as well as conservative systems which features unusual dynamics and control which cannot be realized in the conventional systems [248]. In the background of NLSEs, PT-symmetric systems involve two different models, namely, i) the nonlinear optical system where the optical potential is fixed PT-symmetric [243, 249–251] and ii) the coupled and multicomponent NLSE with a balance gain/loss [60, 252, 253].

Recently, Ablowitz et al. introduced an exactly integrable nonlocal PT-symmetric NLSE where the nonlinearity is nonlocal as well as PT-symmetric [254]. Furthermore, they constructed a discrete one-soliton solution via a left-right Riemann-Hilbert formulation in an exactly solvable PT-symmetric DNLS which then discretized the above reported NLSE [255]. Since then, a numerous nonlocal integrable NLSEs have been reported such as the reverse time NLSE [93], the reverse space-time NLSE [93, 256], the nonlocal derivative NLSE [93, 257], PT-symmetric Davey-Stewartson equation [93, 258], and the reverse space-time complex modified KdV equation [93, 259, 260], to explore the exciting behaviors of nonlocal solutions in such systems. Recently, intense research investigations have been made in rogue waves to understand and control their appearance in nonlinear optics [155], BEC [156], hydrodynamics [157], biophysics [158], and so forth. In general, these rogue waves are mathematically expressed in a rational form which exhibits both spatial and temporal localization. Moreover, they possess interesting dynamical patterns and are found to be observed in a large number of local nonlinear integrable systems [17, 21, 173, 261, 262]. In the following, we list out the Peregrine soliton solution under the context of different nonlocal PT-symmetric NLSEs with space reversal, time reversal, and space-time reversal.

7.1 The Nonlocal NLSE With Parity-Time Symmetric Self-Induced Potential [263]

$$i \psi_z + \frac{1}{2} \psi_{xx} + \psi(x, z) \psi^*(-x, z) \psi(x, z) = 0. \tag{83}$$

(Solutions: See S106 & S107.)

7.2 The Reverse Time Nonlocal NLSE [256]

$$i \psi_t(x, t) = \psi_{xx}(x, t) + 2 \psi^2(x, t) \psi(x, -t). \tag{84}$$

(Solution: See S108.)

7.3 A Nonlocal NLSE With the PT-Symmetric Potential [264]

$$i \psi_t(x, t) = \psi_{xx}(x, t) + 2 \psi^2(x, t) \psi^*(-x, t). \tag{85}$$

(Solution: See S109.)

7.4 A Nonlocal NLSE [265]

$$i \psi_t(x, t) = \psi_{xx}(x, t) - 2 \psi^2(x, t) \psi^*(-x, t). \tag{86}$$

(Solution: See S110.)

7.5 A Nonlocal NLSE With the Self-Induced PT-Symmetric Potential [266]

$$i \psi_t(x, t) + \psi_{xx}(x, t) + \frac{1}{2} \psi^2(x, t) \psi^*(-x, t) = 0. \tag{87}$$

(Solution: See S111.)

7.6 A Reverse Time Nonlocal NLSE [267]

$$i \psi_t(x, t) = \psi_{xx}(x, t) + 2 \sigma \psi^2(x, t) \psi(x, -t). \tag{88}$$

Here, the constant σ takes the values +1 and -1 for focusing and defocusing nonlinearity, respectively. (Solution: See S112.)

7.7 A Nonlocal NLSE [268]

$$i \psi_t(x, t) = \psi_{xx}(x, t) + 2 \sigma \psi^2(x, t) \psi^*(-x, t). \tag{89}$$

Here, σ takes the value +1 or -1 for focusing or defocusing nonlinearity, respectively. (Solution: See S113.)

7.8 A Nonlocal Derivative NLSE [269]

$$i \psi_t(x, t) + \psi_{xx}(x, t) + \sigma [\psi^2(x, t) \psi^*(-x, t)]_x = 0, \tag{90}$$

where σ takes the value +1 or -1 for focusing or defocusing nonlinearity, respectively. (Solution: See S114.)

7.9 A Nonlocal Third-Order NLSE [270]

$$i \psi_t + ic \psi_x + \psi_{xx} + \sigma \psi [\psi(-x, t)]^* \psi + i \lambda \psi_{xxx} + 3i \lambda \sigma \psi [\psi(-x, t)]^* \psi_x = 0, \tag{91}$$

where λ , σ , and c are real constants. (Solution: See S115.)

7.10 An Integrable Three-Parameter Nonlocal Fifth-Order NLSE [271]

$$i \psi_t + S(\psi, r) + \alpha H(\psi, r) + \gamma P(\psi, r) + \delta Q(\psi, r) = 0, \tag{92}$$

where $\psi \equiv \psi(x, t)$, $r \equiv r(x, t)$ are complex fields; α , γ , and δ are all real parameters.

Here, a) $S(\psi, r)$ denotes the nonlocal NLS part

$$S(\psi, r) = \frac{1}{2}\psi_{xx} + \psi^2 r, \tag{93}$$

b) $H(\psi, r)$ represents the nonlocal Hirota part

$$H(\psi, r) = \psi_{xxx} + 6\psi\psi_x r, \tag{94}$$

c) $P(\psi, r)$ denotes the nonlocal Lakshmanan-Porsezian-Daniel (LPD) part

$$P(\psi, r) = \psi_{xxxx} + 8\psi r\psi_{xx} + 6\psi^3 r^2 + 4\psi\psi_x r_x + 6\psi_x^2 r + 2\psi^2 r_{xx}, \tag{95}$$

and d) $Q(\psi, r)$ is the nonlocal quintic part

$$Q(\psi, r) = \psi_{xxxxx} + 10\psi r\psi_{xxx} + 10(\psi\psi_x r_x)_x + 20r\psi_x\psi_{xx} + 30\psi^2 r^2\psi_x, \tag{96}$$

where $r(x, t) = \sigma\psi^*(-x, t)$ and $\sigma = \pm 1$. (Solutions: See S116, S117, S118 & S119.)

7.11 The Nonlocal Variant of the NLSE in a Dimensionless Form [272]

$$\begin{aligned} i\frac{\partial\psi}{\partial t} + \frac{1}{2}\frac{\partial^2\psi}{\partial x^2} + \theta\psi - \mu\psi &= 0, \\ \nu\frac{\partial^2\theta}{\partial x^2} - 2q\theta &= -2|\psi|^2, \end{aligned} \tag{97}$$

where θ represents the optically induced deviation of the director angle, ν is the nonlocality parameter, μ is the propagation constant, and q is the parameter that represents the square of the applied static electric field that pretilts the nematic dielectric. Using Fourier transform θ can be rewritten as

$$\theta = F^{-1}\left[\frac{F[2|\psi|^2]}{\nu k^2 + 2}\right].$$

Here k is the wave number relevant to the Fourier variable. (Solution: See S120.)

7.12 The Generalized PT-Symmetric Nonlocal Coupled NLSE With Nonlocal SPM, XPM, and FWM of the Following Form [273]

$$\begin{aligned} i\frac{\partial\psi_1(x, t)}{\partial t} + \frac{\partial^2\psi_1(x, t)}{\partial x^2} + \left[a\psi_1(x, t)\psi_1^*(-x, t) \right. \\ \left. + b\psi_1(x, t)\psi_2^*(-x, t) + c\psi_2(x, t)\psi_2^*(-x, t) \right. \\ \left. + d\psi_1^*(-x, t)\psi_2(x, t) \right]\psi_1(x, t) \\ = 0, i\frac{\partial\psi_2(x, t)}{\partial t} + \frac{\partial^2\psi_2(x, t)}{\partial x^2} + \left[a\psi_1(x, t)\psi_1^*(-x, t) \right. \\ \left. + b\psi_1(x, t)\psi_2^*(-x, t) + c\psi_2(x, t)\psi_2^*(-x, t) \right. \\ \left. + d\psi_1^*(-x, t)\psi_2(x, t) \right]\psi_2(x, t) = 0, \end{aligned} \tag{98}$$

where a and c correspond to the nonlocal SPM and XPM, respectively, while b, d represent the nonlocal FWM terms. (Solution: See S121.)

8 PEREGRINE SOLITONS IN HIGHER DIMENSIONAL AND MIXED NLSEs

This section aims at presenting the Peregrine soliton solutions of higher dimensional and mixed NLSEs reported in the existing literature. The one-dimensional (1D) cubic NLSE or (1 + 1)-dimensional ((1 + 1)-D) cubic NLSE appears in diverse fields of physics, namely, nonlinear optics, plasma physics, BEC, condensed matter physics, and superfluids [109]. A successful first, completely integrable property of such (1 + 1)-D NLSE has been reported by Ablowitz et al, through the inverse scattering transform technique [87]. Higher dimensional NLSEs of such a basic (1 + 1)-D NLSE can be obtained by replacing the second spatial derivative through the Laplacian. Moreover, higher dimensional NLSEs are not integrable, but localized solutions are found to exist in two transverse directions [274, 275]. However, the obtained solutions are not robust against perturbations and found to be unstable after a finite distance. Also, the (3 + 1)-D NLSEs are not integrable, but localized solutions for these equations have been reported through the numerical simulations [6] and via the similarity transformations [275–277]. In particular, this section is related to the Peregrine soliton solution. The Peregrine solitons found profound interest in diverse areas of physics, namely, optical systems [278], BEC [73], hydrodynamics [12], and superfluids [25]. Originally, such Peregrine soliton solutions have been reported in the two-dimensional graded-index waveguides using the similarity transformation [279], followed by their appearance in a two-dimensional graded-index grating waveguide [280] and two-dimensional coupled NLSEs with distributed coefficients [281]. The Peregrine soliton solutions in a (3 + 1)-D inhomogeneous NLSE with variable coefficients [282] and a (3 + 1)-D higher-order coupled NLSE [283] have also been reported. These Peregrine solitons play an inevitable role in describing the dynamics of ocean waves, nonlinear optics, and BEC. Hence, this section considers reporting the Peregrine soliton solutions of various higher dimensional NLSEs and mixed NLSEs. Here, the mixed NLSEs refer to the higher dimensional NLSEs with other physical effects, namely, inhomogeneity, external potential, variable coefficient, and nonlocality. Such higher dimensional and mixed NLSEs in which Peregrine soliton solutions are reported will be listed in this section.

8.1 THE THREE-DIMENSIONAL INHOMOGENEOUS NLSE WITH VARIABLE COEFFICIENTS IN A DIMENSIONLESS FORM [282]

$$i\psi_t = -\frac{1}{2}\nabla^2\psi + \nu(r, t)\psi + g(t)|\psi|^2\psi + i\gamma(t)\psi. \tag{99}$$

8.2 A Special Case of Eq. 99 [284]

$$i\psi_t = -\frac{\beta(t)}{2}\nabla^2\psi + v(r,t)\psi + g(t)|\psi|^2\psi + i\gamma(t)\psi = 0, \quad (100)$$

where $\psi = \psi(\mathbf{r}, t)$, $\mathbf{r} \in \mathbb{R}^3$, $\mathbf{r} = (x, y, z)$, $\nabla \equiv (\partial_x, \partial_y, \partial_z)$ with $\partial_x = \partial/\partial x$. $v(\mathbf{r}, t)$ is an external potential with a real valued function of time and spatial coordinates. $\beta(t)$, $g(t)$, and $\gamma(t)$ denote the coefficients of linearity, nonlinearity, and gain/loss, respectively. (Solutions: See S122, S123 & S124.)

8.3 A (2 + 1)-Dimensional NLSE With an External Potential [285]

$$i\psi_t + \psi_{xx} + \psi_{yy} - g(x, y, t)|\psi|^2\psi - V(x, y, t)\psi = 0, \quad (101)$$

where $g(x, y, t)$ is the coefficient of nonlinearity and $V(x, y, t)$ is an external potential. (Solutions: See S125 & S126.)

8.4 The 3D Variable Coefficient NLSE of the Form With Linear and Parabolic Potentials [286]

$$i\psi_t + \frac{\beta(t)}{2}\Delta\psi + \chi(t)|\psi|^2\psi + V(t, x, y, z)\psi = i\gamma(t)\psi, \quad (102)$$

where $\psi = \psi(t, x, y, z)$ is the order parameter in BECs or the complex envelope of the electric field in optical communication system. Here $\Delta = \partial_x^2 + \partial_y^2 + \partial_z^2$ is the 3-dimensional Laplacian operator. The functions $\beta(t)$, $\chi(t)$, and $\gamma(t)$ are the coefficients of the diffraction, nonlinearity, and gain/loss. Here, the potential $V = V_1(t)(x + y + z) + V_2(t)Y^2$, where $V_1(t)$ and $V_2(t)$ are linear and parabolic potential strengths and $Y^2 = x^2 + y^2 + z^2$. (Solution: See S127.)

8.5 A (2 + 1)-Dimensional NLSE With Variable Coefficients [287]

$$i\psi_t + \psi_{xy} + \alpha(x, y, t)\psi + \beta(t)\psi\partial_x^{-1}\partial_y|\psi|^2 + i\gamma(t)\psi = 0, \quad (103)$$

where $\psi = \psi(x, y, t)$, with the propagation variables x, y and transverse variable t . $\alpha(x, y, t)$ is an external potential which is the real valued function of space and time. $\beta(t)$ and $\gamma(t)$ are the coefficients of nonlinearity and gain/loss. The inverse d-bar operator, $\partial_x^{-1} = \partial_z^{-1} + \partial_z^{-1}$, $z = x + iy$, $\partial_z = \frac{1}{2}(\partial_x - i\partial_y)$, $\partial_{\bar{z}} = \frac{1}{2}(\partial_x + i\partial_y)$, and $(\partial_{\bar{z}}f) = \frac{1}{\pi} \int_{\mathbb{R}^2} \frac{f(x, y)dx, dy}{z - z_1}$. (Solution: See S128.)

8.6 A Two-Dimensional Nonlocal NLSE [288]

$$i\psi_t = -\psi_{xx} - \sigma\psi \int_{-\infty}^{+\infty} |\psi|^2 dy = 0, \quad (104)$$

where $\psi \equiv \psi(x, y, t)$ is a two-dimensional field envelope and $\sigma (> 0)$ is the nonlinearity coefficient. (Solution: See S129.)

8.7 A (2 + 1)-Dimensional Variable Coefficient NLSE With Partial Nonlocality [289]

$$i\psi_t + \beta(t)\psi_{xx} + \chi(t)\psi \int_{-\infty}^{+\infty} |\psi|^2 dy = 0, \quad (105)$$

where $\psi = \psi(t, x, y)$. $\beta(t)$ and $\chi(t)$ are the coefficients of diffraction and nonlinearity, respectively. (Solution: See S130.)

8.8 A (2 + 1)-Dimensional Variable Coefficient Partially Nonlocal NLSE [290]

$$i\frac{\partial\psi}{\partial z} + \beta(z)\frac{\partial^2\psi}{\partial x^2} + \chi(z)\psi \int_{-\infty}^{+\infty} |\psi|^2 dy + \gamma(z)x^2\psi = 0, \quad (106)$$

where $\psi = \psi(z, x, y)$ describing the optical field or wave function of condensate. $\beta(z)$ and $\gamma(z)$ are the coefficients of diffraction and tapering effect/harmonic trapping potential, respectively. The nonlinearity is localized in x -direction and nonlocalized in y -direction with the coefficient function $\chi(z)$. (Solution: See S131.)

8.9 A (2 + 1)-Dimensional (2D) Nonlocal NLSE Satisfying the Two-Dimensional Parity-Time-Symmetric Potential $V(\mathbf{x}, \mathbf{y}) = V^*(-\mathbf{x}, -\mathbf{y})$ [291, 292]

$$i\psi_t + \psi_{xy} + \psi r = 0, \quad r_y = [\psi(x, y, t)\psi(-x, -y, t)]_x, \quad (107)$$

where $\psi = \psi(x, y, t)$ and $V(x, y, t) = \psi(x, y, t)\psi^*(x, y, t)$. (Solutions: See S132 & S133.)

8.10 A Two-Dimensional Nonlocal NLSE [293]

$$i\psi_t + \psi_{xx} + \psi_{yy} - 2\psi_{xy} + 2\psi V = 0, \quad V = \psi(x, y, t)\psi^*(-x, -y, t), \quad (108)$$

where $\psi = \psi(x, y, t)$. (Solution: See S134.)

8.11 The Integrable “Reverse Space” 2D Nonlocal NLSE [294]

$$\begin{aligned} &(i\partial_t + \partial_{xy}^2)\psi(x, y, t) - \frac{\lambda}{2}\psi(x, y, t)(\partial_z^{-1} \\ &+ \partial_{\bar{z}}^{-1})\partial_y[\psi(x, y, t)\psi^*(-x, -y, t)] \\ &= 0, \quad \lambda = \pm 1. \end{aligned} \quad (109)$$

8.12 A Reverse Space-Time Nonlocal NLSE [294]

$$\begin{aligned} &(i\partial_t + \partial_{xy}^2)\psi(x, y, t) - \frac{\lambda}{2}\psi(x, y, t)(\partial_z^{-1} \\ &+ \partial_{\bar{z}}^{-1})\partial_y[\psi(x, y, t)\psi^*(-x, -y, -t)] \\ &= 0, \quad \lambda = \pm 1. \end{aligned} \quad (110)$$

Here $z \equiv x + iy$ and $\partial_{z\bar{z}}^{-1}$ are operators inverse to $\partial_z \equiv (1/2)(\partial_x - i\partial_y)$ and $\partial_{\bar{z}} \equiv (1/2)(\partial_x + i\partial_y)$. (Solutions: See S135 & S136.)

8.13 A Two-Dimensional Two-Coupled Variable Coefficient NLSE [281]

$$i\psi_{1z} + \frac{\beta(z)}{2}(\psi_{1xx} + \psi_{1yy}) + R(z) \sum_{k=1}^2 |\psi_k|^2 \psi_1 = i\gamma(z)\psi_1,$$

$$i\psi_{2z} + \frac{\beta(z)}{2}(\psi_{2xx} + \psi_{2yy}) + R(z) \sum_{k=1}^2 |\psi_k|^2 \psi_2 = i\gamma(z)\psi_2,$$
(111)

where $\psi_j = \psi_j(x, y, z)$, $j = 1, 2$. The real analytic spatial functions, $\beta(z)$, $R(z)$, and $\gamma(z)$ represent the diffraction, nonlinearity, and gain/loss parameter, respectively. (Solution: See S137.)

8.14 The Variable Coefficient NLSE Describing the Inhomogeneous Nonlinear Waveguide [295]

$$i\psi_{1z} + \frac{\beta}{2}(\psi_{1xx} + \psi_{1yy}) + \chi(z)(r_{11}|\psi_1|^2 + r_{12}|\psi_2|^2)\psi_1$$

$$+ \frac{1}{2}f(z)(x^2 + y^2)\psi_1 = ig(z)\psi_1, i\psi_{2z} + \frac{\beta}{2}(\psi_{2xx} + \psi_{2yy})$$

$$+ \chi(z)(r_{21}|\psi_1|^2 + r_{22}|\psi_2|^2)\psi_2 + \frac{1}{2}f(z)(x^2 + y^2)\psi_2 = ig(z)\psi_2,$$
(112)

where $\psi_1(x, y, z)$ and $\psi_2(x, y, z)$ are the two normalized orthogonal components of electric fields. β , $\chi(z)$, $g(z)$, and $f(z)$ denote the dispersion, nonlinearity, gain, and geometry of tapered waveguide coefficients, respectively. r_{11} and r_{22} are the self-phase modulation coefficients for $\psi_1(x, y, z)$, $\psi_2(x, y, z)$ and r_{12} and r_{21} are the cross-phase modulation coefficients. (Solution: See S138.)

8.15 The Variable Coefficient CNLSE [296]

$$i\psi_{1z} + \frac{1}{2}[\beta_1(z)\psi_{1xx} + \beta_2(z)\psi_{1yy} + \beta_3(z)\psi_{1tt}] + \chi(z)(\sigma_{11}|\psi_1|^2$$

$$+ \sigma_{12}|\psi_2|^2)\psi_1 = i\gamma(z)\psi_1, i\psi_{2z} + \frac{1}{2}[\beta_1(z)\psi_{2xx} + \beta_2(z)\psi_{2yy}$$

$$+ \beta_3(z)\psi_{2tt}] + \chi(z)(\sigma_{21}|\psi_1|^2 + \sigma_{22}|\psi_2|^2)\psi_2 = i\gamma(z)\psi_2,$$
(113)

where $\psi_1(z, x, y, t)$ and $\psi_2(z, x, y, t)$ are the two normalized complex mode fields. $\beta_1(z)$ and $\beta_2(z)$ are the coefficients of diffractions along the x and y transverse coordinates. $\beta_3(z)$ is the coefficient of dispersion. $\chi(z)$ is the SPM, accounting for the self-focusing ($\chi > 0$) or the self-defocusing ($\chi < 0$) nonlinearity. The parameters σ_{11} , σ_{12} , σ_{21} , and σ_{22} determine the ratio of the coupling strengths of the cross-phase modulation to the SPM. For linearly polarized eigenmodes, $\sigma_{11} = \sigma_{22} = 1$, $\sigma_{12} = \sigma_{21} = 2/3$, in

case of circularly polarized eigen modes, $\sigma_{11} = \sigma_{22} = 1$, $\sigma_{12} = \sigma_{21} = 2$ and for the elliptically polarized eigen modes, $\sigma_{11} = \sigma_{22} = 1$, $2 < \sigma_{12} = \sigma_{21} < 2/3$. The parameter $\gamma(z)$ represents the loss when $\gamma(z) < 0$ or gain when $\gamma(z) > 0$. (Solution: See S139.)

9 PEREGRINE SOLITONS IN SATURABLE NLSES

This section presents the Peregrine soliton solutions reported in the literature under the family of the saturable NLSEs. In nonlinear dynamics, the ultrashort optical pulse propagation through the dielectric waveguides like optical fibers is governed by the NLSEs. The key parameter that plays a decisive role in the nonlinear effects of such optical fibers is an intensity dependent variation of the refractive index, also known as the optical Kerr effect. The Kerr index induced refractive index results in the self-phase modulation which ultimately broadens the optical spectrum. Moreover, it is well known that the Kerr nonlinearity determines the nonlinear response of the optical medium up to a certain level of input power, but when input power level exceeds a certain value, the role of higher-order nonlinear susceptibility is inevitable. This eventually results in the saturation of the nonlinear response of the system. In general, all nonlinearities saturation is owing to the upper limit for change in the refractive index of the material medium and thereafter system does not display any change in the nonlinear index even at very high input power levels [109]. Also, it is demonstrated that the saturation in cubic nonlinearity is equivalent to the occurrence of the third-, fifth-, and seventh-order nonlinear susceptibility [297]. Such nonlinear index saturation has been originally observed in dual core nonlinear directional couplers by Stegeman et al. [298], followed by plethora of studies to understand the detrimental effects of nonlinear saturation in the coupling behaviors of directions couplers [299–302]. The propagation of solitons through the materials with nonlinear saturation has also been expressed through numerical and analytical methods. The dynamics of such system provide the evidence of the existence of bistable solitons of the same duration with different peak powers [303]. Moreover, the dynamics of ultrashort pulse propagation through the fibers with saturable nonlinearity in the normal dispersion regime has also been analyzed to determine the minimum duration of the output pulse of fiber-grating compressor [304]. In addition, the nonlinear saturation effects play a significant role in the MI gain spectrum of the ultrashort pulse propagation through the semiconductor doped fibers [305–307]. This section lists out the saturable NLSEs in which Peregrine soliton solutions were reported.

9.1 A NLSE Describes Quasi-1D Bose-Einstein Condensates [308]

$$i\psi_t = -\frac{1}{2}\psi_{xx} + V(x)\psi + \frac{1 - (3/2)|\psi|^2}{\sqrt{1 - |\psi|^2}}\psi,$$
(114)

where $V(x) = \frac{1}{2}\Omega^2 x^2$ is an external potential of harmonic form. Ω is the normalized trap strength. (Solution: See S140.)

10 SUMMARY AND OUTLOOK

The historical review of the discovery of the Peregrine soliton goes side by side with the mathematical steps of its derivation. We have adopted here the most common method of derivation, namely, the use of Lax pair and Darboux transformation. Employing the continuous wave as a seed solution, we have analytically derived the general breather solution of the NLSE through the Darboux transformation and Lax pair technique. We have shown that this class of solution turns out, under certain limits, into its five members, the Akhmediev breather, the Kuznetsov-Ma breather, the Peregrine soliton, the single bright soliton, and the continuous wave solution. When the temporal period of the Kuznetsov-Ma breather approaches infinity, it falls into the Peregrine soliton. A similar result is obtained when the spatial period of the Akhmediev breather tends to infinity. We have then collected all Peregrine soliton solutions of the NLSE and its various variations that are found in the literature. Particularly, we have recorded the Peregrine soliton solutions in higher-order and inhomogeneous NLSEs, in NLSE with external potentials, in coupled NLSEs, in discrete NLSEs, in nonlocal NLSEs, in higher dimensional and mixed NLSEs, and finally in saturable NLSEs. The Peregrine waves in saturable nonlinear systems are not sufficiently explored. Concerning studies in such systems will yield more information about modulation instability and new frequency generations, that will play a crucial role in nonlinear optical fields.

While studying the various nonlinear dynamics modeled by the NLSEs is a developing and attractive area of research, this work will be a useful guideline to keep track of new NLS frameworks that admit Peregrine soliton solutions, youthful stability investigations, up-to-date formation mechanisms, and fresh experimental observations. One future extension of this work is a deep exploration of the existence of Peregrine solitons in higher coupled NLSEs and higher dimensional systems. The accompanying features of these systems could support the robustness of the Peregrine soliton against different perturbations and initial conditions and thus generate more stable rogue wave structures. Additionally, it may be interesting to investigate numerically complex nonintegrable systems in order to achieve more stable rogue

waves. Constructing such models experimentally allows for the monitorization of randomly many possible nonlinear dynamics. This opens the door to a better understanding of the preactions accomplished by extreme events such as rogue waves.

As the multisoliton interaction is one of the formation mechanisms of the rogue waves and it is recently reported in the bioenergy transport mechanism in the helical protein [32], this evidence may also be extended to different biomechanisms. Moreover, one of the not fully explored aspects, yet very important, is the knowledge of how a variety of initial conditions are influencing the rogue wave formation. In nonlinear optics, the knowledge of initial conditions plays an essential role in generating, on purpose, rogue waves in order to produce high energy light pulses. Last but not least, with regard to the dispersion and nonlinearity management, it may be interesting to consider interactions of multi-Peregrine solitons modeling by higher dimensional NLSEs. Recently, photonic rogue waves are analytically reported in lattice systems [78]. This will be useful in understanding wave interactions in diverse crystal structures.

AUTHOR CONTRIBUTIONS

All authors listed have made a substantial, direct, and intellectual contribution to the work and approved it for publication.

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SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fphy.2020.596886/full#supplementary-material>

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Conflict of Interest: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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