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EDITED BY

Noor Saeed Khan,
University of Education Lahore, Pakistan

REVIEWED BY

Khadija Maqbool,
International Islamic University,
Islamabad, Pakistan
Humaira Yasmin,
King Faisal University, Saudi Arabia

*CORRESPONDENCE

Zahir Shah,
✉ zahir@ulm.edu.pk
Narcisa Vrinceanu,
✉ vrinceanu.narcisai@ulbsibiu.ro

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Numerical study of magnetized Powell–Eyring hybrid nanomaterial flow with variable heat transfer in the presence of artificial bacteria: Applications for tumor removal and cancer cell destruction

Tao-Qian Tang^{1,2,3,4,5}, Muhammad Rooman⁶, Zahir Shah^{6*},
Saima Khan⁷, Narcisa Vrinceanu^{8*}, Ahmed Alshehri⁹ and
Mihaela Racheriu^{10,11}

¹Department of Internal Medicine, E-Da Hospital, I-Shou University, Kaohsiung, Taiwan, ²School of Medicine, College of Medicine, I-Shou University, Kaohsiung, Taiwan, ³International Intercollegiate Ph.D. Program, National Tsing Hua University, Hsinchu, Taiwan, ⁴Department of Family and Community Medicine, E-Da Hospital, I-Shou University, Kaohsiung, Taiwan, ⁵Department of Engineering and System Science, National Tsing Hua University, Hsinchu, Taiwan, ⁶Department of Mathematical Sciences, University of Lakki Marwat, Lakki Marwat, Pakistan, ⁷Department of Physics, Abdul Wali Khan University, Mardan, Pakistan, ⁸Department of Industrial Machines and Equipment, Faculty of Engineering, "Lucian Blaga" University of Sibiu, Sibiu, Romania, ⁹Department of Mathematics, Faculty of Sciences, King Abdulaziz University, Jeddah, Saudi Arabia, ¹⁰Medicine Faculty, Lucian Blaga University of Sibiu, Sibiu, Romania, ¹¹City Clinical Emergency Hospital, Sibiu, Romania

This investigation determined the effectiveness of an exterior magnetic field on bacteria enclosed by thousands of magnetite nanoparticles. Variable thermal conductivity and Joule heating were used in the interstitial nano liquid in which artificial bacteria were swimming in a biotic cell. The unsteady motions of a Powell–Eyring fluid in two dimensions were assumed. The porous extending wall was used as a bent surface shape. To convert the governing non-linear PDEs into non-linear ODEs, suitable transformations were exploited. The homotopy analysis technique (HAM) was utilized to resolve the semi-analytical results of non-linear ODEs. Plots were utilized to investigate the impact of significant parameters of velocity distribution, temperature profile, bacterial density field, nutrient concentration field, skin friction, Nusselt number, and nutrient concentration density. Clinical disease has shown that daring tumors have reduced blood flow. The results of this study showed that augmenting the values of unsteady parameters improved the blood velocity profile. The velocity distribution decreased for higher magnetite volume fraction values, as well as porosity and magnetic parameters. As the concentration of magnetite nanoparticles increased, so did the blood temperature distribution. As a result, the immersion of magnetite nanoparticles improved the physical characteristics of the blood. These findings also demonstrated that magnetic parameters and Eckert number play an essential role in increasing heat transfer rates.

KEYWORDS

Powell–Eyring fluid, blood flow, magnetite nanoparticles, porous medium, curved biological boundary, joule heating, artificial bacteria

1 Introduction

Radiotherapy and chemotherapy are frequently applied to treat patients with cancer. However, the combination of these treatments may be inadequate to achieve a cure in some cases. Thus, the development of advanced and novel tactics may provide oncologists with additional therapeutic possibilities. A laboratory in Spain recently produced an artificial magnetic bacterium that, when consumed, can trigger a charged magnetism compass to mark and destroy tumors because the compass rotation speed heats and melts tumors. This method is based on hyperthermia caused by magnets, which is an exploratory treatment method in which magneto-nanoparticle-saturated tumors are subjected to a discontinuous magnetic field. This treatment begins by immersing a tumor in iron magneto-nanoparticles. Every cell in the body requires oxygen to function, and tumors cannot grow beyond the size of a sugar pill without it. Thus, tumors produce hormones that permit them to obtain oxygen-rich blood by hijacking surrounding blood vessels. Moreover, because blood arteries grow in tumors in an unorganized and faster manner, they are porous and defective. When ferromagnetic iron nanoparticles are infused into blood circulation, they travel throughout the body, avoiding healthy blood vessels unless they enter the leakages that nourish tumors. Mathuriya et al. (2015) reported that these vaccinated magnetic iron nanomaterials eventually pass through the blood unless they reach a tumor's blood generator, in which these particles accumulate. Magnetic nanoparticles show potential as a drug conveyance module because of their large surface area, high viability, low toxicity, and volume proportions. Furthermore, magnetic hyperthermia uses magnetic nanoparticles to reduce tumor volume and to target and eliminate malignant cells. Magnetic bio partitioning is useful for detaching a specific atom from a catalog of molecules. One example is the magnetic bio partitioning used to restrict viral RNA for further investigation by polymerase chain reaction. Furthermore, magnetic particles exhibit imaging characteristics, making them useful for multimodal theranostics. These characteristics of magnetic nanomaterials allow simultaneous treatment and diagnostics (Anik et al. (2021). Kong et al. (2014) and Cui et al. (2012) used an unsteady applied magnetic field impact to examine the movement of magnetotactic bacteria (MTB) in a Newtonian fluid. The authors addressed the swimming motion of MTB from a fluid dynamics standpoint in conjunction with an entire three-dimensional Stokes flow. Vincenti et al. (2018) scrutinized the effect of a magnetic field on micro-swimmer suspensions in liquid. Furthermore, Nagaraj et al. (2018) reported on the joint effect of electric and magnetic fields on the synovial fluid in a biological context. Bhatti (2021) recently investigated nanomedicine utilizing suspensions of magnetized gold (*Au*) nanoparticles. Afridi et al. (2019) explored the effect of thermal dissipation and entropy formation on the flow of a hybrid nanofluid across a curved sheet. Moreover, it is practical to use a spreading twisted surface for interstitial nanoparticle flow, in which artificial magnetic bacteria swim within biological cells. Shukla et al. (2019) examined the effects of viscoelasticity factors on second-order fluid in carotid artery blood flow. The HAM was used to initiate an entropy creation evaluation of time-dependent second-grade nanofluid and heat transfer under the influence of a magnetic field. The authors discovered that increasing the second-order viscoelastic and magnetic values increased the entropy production number.

Many studies have proposed strategies for mathematical models within the human body, including the flow of fluid across a curved surface. Several investigators have also considered abdominal fluid flowing through biological cells as a non-Newtonian Powell–Eyring fluid. Saleem and Munawar (2016) examined blood flow *via* a stenotic artery in a constant magnetic field by assuming that blood within the artery was an Powell–Eyring fluid. Hina et al. (2016) investigated the heat transfer characteristics of a Powell–Eyring fluid in peristaltic flow within a curved channel with compliant walls. According to Riaz et al. (2019), the heat transfer procedure in the human body is a complex process that includes heat movement in tissues, membrane pores, electromagnetic radiation emitted by cell phones, exterior interface, metabolic heat production, and arterial-venous blood circulation. Their research aimed to determine the impact of bioheat and mass transfer in the peristaltic movement of an Powell–Eyring liquid in a three-dimensional rectangular cross section in the context of the human thermoregulation framework and thermotherapy. Hussain et al. (2020) numerically explored flow and explained blood flow behavior through tapered arteries as a non-Newtonian Powell–Eyring fluid. Asha and Sunitha (2018), Gholinia et al. (2019), Mallick and Misra (2019), Sultan et al. (2019), and Basha and Sivaraj (2021) conducted relevant research on this model. In the presence of a magnetic field generated using magnetite (Fe_3O_4), Yasmin (2022), Alyousef et al. (2023), Yasmin et al. (2023a), Yasmin et al. (2023b), and Yasmin et al. (2023c) performed biomedical investigations of fluid flow and studied nanofluid flow and hybrid nanofluids experimentally and theoretically, with stability analysis in the context of energy storage and other applications.

Based on these previous findings, the present study considered the growth of artificial magnetic bacteria in a non-Newtonian Powell–Eyring nanofluid on a stretching curved surface using a porous medium. The variable fluid thermal conductivity of the nanofluid was considered. As shown in Figure 1, curvilinear coordinates were used to model mathematical expressions across the curved biological boundary. This investigation also used magnetite nanoparticles. The temperature, concentration, and velocity of magnetite/blood in biological cells were acquired by the homotopy analysis method (HAM) *via* MATHEMATICA and depicted in a set of plots. Additionally, different scenarios were developed by varying the impact of dimensionless parameters, and distinct cases were constructed to obtain maximum reference data. The magnetic bacterium function as a magnetically charged compass to mark and abolish tumors by revolving at such a high rate that tumors heat and melt. Section 2 provides the mathematical formulas and all relevant details. Section 3 presents the physical quantities and the solution method, and its convergence with the validation of the results is shown in Sections 4 and 5. Section 6 includes the results and discussion. Finally, Section 7 contains the conclusions.

2 Mathematical formulas

We assumed a two-dimensional unsteady boundary layer Powell–Eyring nanofluid flow on a strained curved surface using a

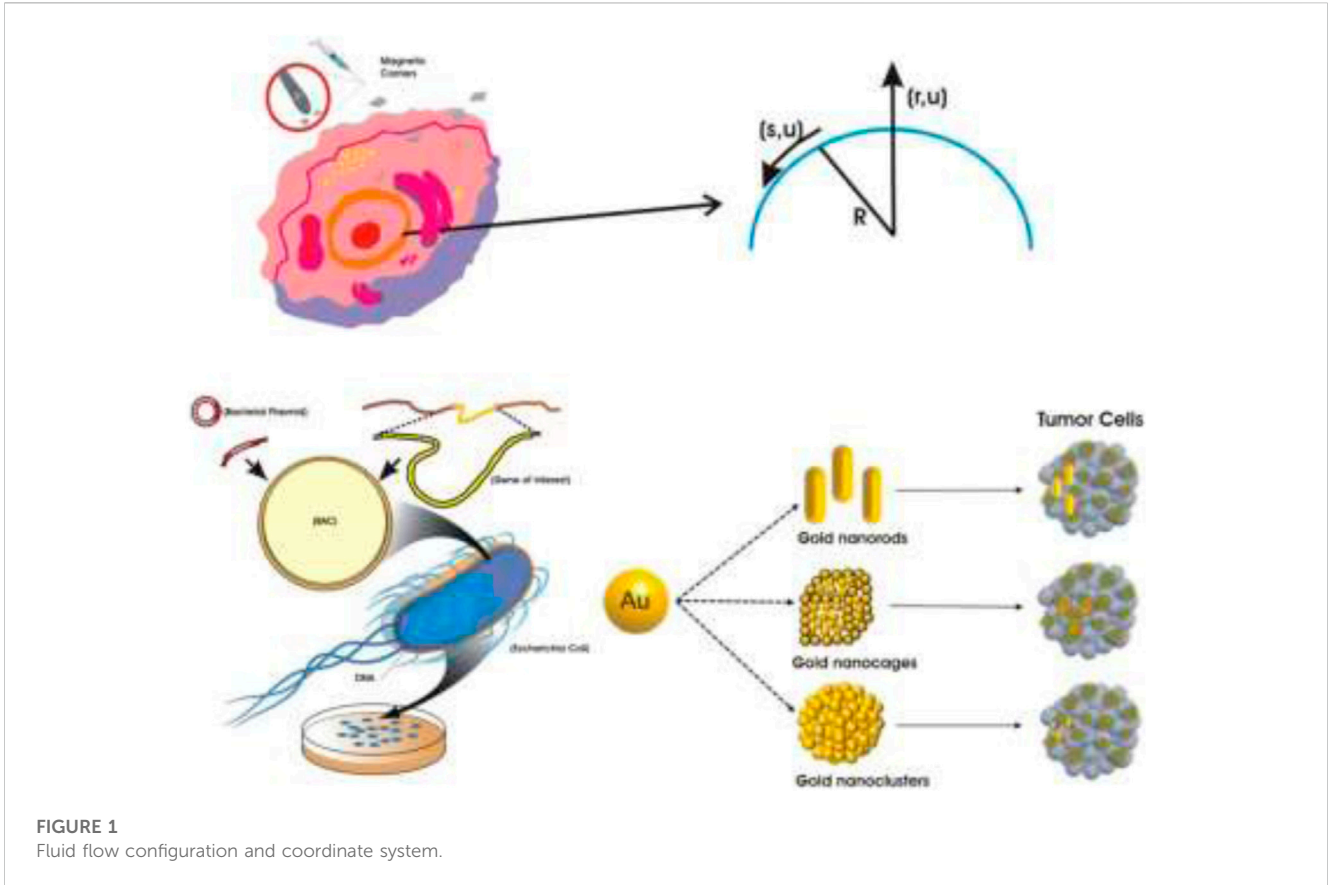


FIGURE 1 Fluid flow configuration and coordinate system.

porous medium that was a spiral in a circle with radius R around the curvilinear coordinates. The stretching surface in the s - direction had a velocity $u = U_w$ and was vertical to the r - direction. A magnetic field of intensity $B(t)$ was applied in the vertical direction. The nanofluid was embedded in the porous medium, and its flow behavior in the porous medium was accounted for by using the Brinkman model. The effects of variable thermal conductivity, heat generation/absorption, and joule dissipation were all considered. We used reaction-diffusion equations to explicitly model the dynamics of the bacterial density ρ_n and nutrient concentration n .

2.1 Formal model and geometry

Figure 1 shows the geometry of the flow problem along with the coordinate system, velocity field, and other details.

2.1.1 Governing equations and boundary conditions after applying assumptions

Navier-Stokes flow is a type of fluid movement in which the spinning speed of the flow, U_w , is extremely low and the typical dimension a is slight. The Stokes estimate is commonly used to describe the motion of magnetic bacteria because it ignores the inertial term in the Navier-Stokes equation by using a low Reynolds number. Thus, the Navier-Stokes and continuity equations govern the fluid speed produced by swimming magnetotactic bacteria. The theory of rate mechanisms was utilized to deduce the Powell-Eyring model (1994) to define shear in non-Newtonian flow. The shear

tensor in the Powell-Eyring fluid model is given by (Riaz et al. (2019)

$$\tau = \mu \nabla V + \frac{1}{\beta_1} \sinh^{-1} \left(\frac{1}{c_1} \nabla V \right) \quad (1)$$

and

$$\sinh^{-1} \left(\frac{1}{c_1} \nabla V \right) \approx \left(\frac{1}{c_1} \nabla V \right) - \frac{1}{6} \left(\frac{1}{c_1} \nabla V \right)^3, \quad \left| \frac{1}{c_1} \nabla V \right| \ll 1. \quad (2)$$

The appropriate governing equations to examine the foregoing fluid flow are as follows:

$$\bar{r} \frac{\partial v}{\partial r} + r + R \frac{\partial u}{\partial s} = 0, \quad (3)$$

$$\frac{u^2}{\bar{r}} = \frac{1}{\rho_{nf}} \frac{\partial p}{\partial r}, \quad (4)$$

$$\begin{aligned} \rho_{nf} \left(\frac{\partial u}{\partial t} + v \frac{\partial u}{\partial r} + \frac{R}{\bar{r}} u \frac{\partial u}{\partial s} + uv \right) &= -\frac{R}{\bar{r}} \frac{\partial p}{\partial s} + \left(\mu_{nf} + \frac{1}{\beta_1 c_1} \right) \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial r} + \frac{u}{\bar{r}} \right) \\ &\quad - \frac{1}{6 \beta_1 c_1^3} \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial r} + \frac{u}{\bar{r}} \right)^3 \\ &\quad - \sigma_{nf} B^2(t) u - \frac{\mu_{nf}}{k_1} u, \end{aligned} \quad (5)$$

$$\begin{aligned} (\rho C_p)_{nf} \left(\frac{\partial T}{\partial t} + v \frac{\partial T}{\partial r} + \frac{R}{\bar{r}} u \frac{\partial T}{\partial s} \right) &= \frac{1}{\bar{r}} \frac{\partial}{\partial r} \left(\bar{r} k_{nf}(T) \frac{\partial T}{\partial r} \right) + \sigma_{nf} B^2(t) u^2 \\ &\quad + Q^*(T - T_\infty), \end{aligned} \quad (6)$$

$$\left(\frac{\partial \rho_n}{\partial t} + v \frac{\partial \rho_n}{\partial r} + \frac{R}{\bar{r}} u \frac{\partial \rho_n}{\partial s} \right) = D_n \left(\frac{\partial^2 \rho_n}{\partial r^2} + \frac{1}{\bar{r}} \frac{\partial \rho_n}{\partial r} \right) + A(n, t) \rho_n, \quad (7)$$

TABLE 1 Thermophysical characteristics of Fe_3O_4 magnetite nanoparticles and blood (Alyousef et al., 2023; Yasmin et al., 2023a).

Thermophysical property	ρ (kg/m ³)	C_p (J/kg K)	k (W/m K)	σ (S/m)
Blood	1,000	4,180	0.543	0.0109
Iron oxide Fe_3O_4	5,180	670	9.7	25,000

$$\left(\frac{\partial n}{\partial t} + v \frac{\partial n}{\partial r} + \frac{R}{\bar{r}} u \frac{\partial n}{\partial s}\right) = D_n \left(\frac{\partial^2 n}{\partial r^2} + \frac{1}{\bar{r}} \frac{\partial n}{\partial r}\right) - \frac{A(n, t)}{Y} \rho_n. \tag{8}$$

subject to the boundary condition (Elgazery et al., 2022)

$$\left. \begin{aligned} u = U_w = \frac{as}{1-ct}, \quad v = 0, \quad T = T_w, \quad \rho_n = (\rho_n)_w, \quad n = n_w \text{ at } r \rightarrow 0 \\ u \rightarrow 0, \quad \frac{\partial u}{\partial r} \rightarrow 0, \quad T \rightarrow T_\infty, \quad \rho_n \rightarrow (\rho_n)_\infty, \quad n \rightarrow n_\infty, \quad as \quad r \rightarrow \infty \end{aligned} \right\}. \tag{9}$$

Here, $\bar{r} = r + R$, $B(t) = \frac{B_0}{\sqrt{1-ct}}$, $Y = \frac{(\rho_n)_w - (\rho_n)_\infty}{n_w - n_\infty}$ is the conversion factor, $A(n, t) = a\lambda(t) \frac{n}{(K_m + n)}$ represents the variable nutrient bacterial growth rate, and $\lambda(t) = \frac{\lambda_0}{1-ct}$ represents the maximum growth rate. In this present discussion, we assume that n is greater than the Monod constant K_m and that $a > 0$ and $c \geq 0$ with dimension (time)⁻¹.

2.1.2 Similarity transformations and modeled ODEs

Using the following dimensionless similarity transformations (Elgazery et al., 2022),

$$\left. \begin{aligned} \xi = \sqrt{\frac{a}{\nu_f(1-ct)}} r, \\ u = \frac{as}{1-ct} f'(\xi), \quad p = \rho_f \left(\frac{as}{1-ct}\right)^2 P(\xi), \quad T = T_\infty + (T_w - T_\infty)\theta(\xi), \\ \rho_n = (\rho_n)_\infty + ((\rho_n)_w - (\rho_n)_\infty)\chi(\xi), \quad n = n_\infty + (n_w - n_\infty)\omega(\xi). \end{aligned} \right\} \tag{10}$$

and using the aforementioned dimensionless quantity, the equation of continuity is satisfied, and after pressure elimination the governing Eqs 7–12 can be written as follows:

$$\begin{aligned} &(\varphi_4 + \alpha_1) \left[f^{IV} + \frac{2f'''}{\xi} - \frac{f''}{(\xi)^2} + \frac{f'}{(\xi)^3} \right] - \varphi_3 M \left(f'' + \frac{f'}{\xi} \right) - \varphi_4 \beta_0 \left(f'' + \frac{f'}{\xi} \right) \\ &- \alpha_2 \left[\left(f''^2 + \frac{2f'f''}{\xi} + \frac{f'^2}{(\xi)^2} \right) f^{IV} + \left(f''^2 - \frac{3f'f''}{\xi} - \frac{f'^2}{(\xi)^2} \right) \frac{f''}{(\xi)^2} + \frac{3f'^3}{(\xi)^5} \right. \\ &+ 2 \left(f'' + \frac{f'}{\xi} \right) f''^2 + 2 \left(3f''^2 + \frac{2f'f''}{\xi} - \frac{f'^2}{(\xi)^2} \right) \frac{f'''}{\xi} \\ &\left. + \varphi_1 \left[\frac{K(f f''' - f' f'')}{\xi} + \frac{K(f f'' - f'^2)}{(\xi)^2} - \frac{K f f'}{(\xi)^3} - \frac{\gamma}{\xi} \left(\frac{\xi}{2} f'' + f' \right) \right. \right. \\ &\left. \left. - \frac{\gamma}{2} (\xi f''' + 3 f'') \right] \right] = 0, \tag{11} \end{aligned}$$

$$\begin{aligned} &\varphi_5 \left[(1 + \beta \theta) \left(\theta'' + \frac{\theta'}{\xi} \right) + \beta (\theta')^2 \right] + \varphi_3 M Pr Ec f'^2 \\ &+ \varphi_2 Pr \left[\left(\frac{Kf}{\xi} - \frac{\gamma \xi}{2} \right) \theta' + \frac{Q}{\varphi_2} \theta \right] = 0, \tag{12} \end{aligned}$$

$$\chi'' + \frac{\chi}{\xi} + Lb \left[\left(\frac{Kf}{\xi} - \frac{\gamma \xi}{2} \right) \chi' + \lambda (\Omega + \chi) \right] = 0, \tag{13}$$

$$\omega'' + \frac{\omega}{\xi} + Lb \left[\left(\frac{Kf}{\xi} - \frac{\gamma \xi}{2} \right) \omega' + \lambda (\Omega + \chi) \right] = 0. \tag{14}$$

Similarly, pressure can be expressed as follows:

$$\begin{aligned} P(\xi) = &\frac{\bar{\xi}}{2K} (\varphi_4 + \alpha_1) \left[f''' + \frac{f''}{\xi} - \frac{f'}{(\xi)^2} \right] \\ &+ \frac{\varphi_1}{2} \left[f f'' - f'^2 + \frac{f f'}{\xi} - \frac{\bar{\xi}}{K} \gamma \left(\frac{\xi}{2} f'' + f' \right) \right] \\ &- \frac{\bar{\xi}}{2K} (\varphi_3 M + \varphi_1 \beta_0) f' + \frac{\bar{\xi}}{2K} \alpha_2 \left(f'' + \frac{f'}{\xi} \right)^2 \left(f''' + \frac{f''}{\xi} - \frac{f'}{(\xi)^2} \right). \tag{15} \end{aligned}$$

subject to the boundary conditions

$$\begin{aligned} f'(0) = \theta(0) = \chi(0) = \omega(0) = 1, \quad f(0) = 0, \\ f'(\infty) = f''(\infty) = \theta(\infty) = \chi(\infty) = \omega(\infty) = 0, \end{aligned} \tag{16}$$

where $\bar{\xi} = \xi + K$, $K = \sqrt{\frac{a}{\nu_f(1-ct)}} R$, $M = \frac{\sigma_f B_0^2}{\rho_f a}$, $\Omega = \frac{(\rho_n)_w}{(\rho_n)_w - (\rho_n)_\infty}$, $\alpha_1 = \frac{\mu_f}{\beta_1 c_1}$, $\alpha_2 = \frac{a^3 s^2}{\beta_1 c_1^2 \rho_f \nu_f^2 (1-ct)^3}$, $\beta_0 = \frac{\mu_f (1-ct)}{\rho_f k_1 a}$, $Lb = \nu_f / D_n$, $Q = \frac{1-ct}{a(\rho C_p)_f} Q^*$, and $Pr = \frac{\nu(\rho C_p)_f}{k_0}$ ($Pr \approx 21$ for blood).

2.1.3 Thermo-physical characteristics of nanofluid

The thermo-physical characteristics of an effective nanofluid can be expressed as follows (Mallick and Misra, 2019; Yasmin, 2022; Alyousef et al., 2023):

$$\mu_{nf} = \varphi_1 \mu_f, \quad \rho_{nf} = \varphi_2 \rho_f, \quad (\rho C_p)_{nf} = \varphi_3 (\rho C_p)_f, \quad \sigma_{nf} = \varphi_5 \sigma_f, \tag{17}$$

where

$$\left. \begin{aligned} \varphi_2 = (1 - \phi) + \frac{\rho_p}{\rho_f} \phi, \quad \varphi_3 = (1 - \phi) + \phi \frac{(\rho C_p)_p}{(\rho C_p)_f} \\ \varphi_5 = \frac{(\sigma_p + 2\sigma_f + 2\phi(\sigma_p - \sigma_f))}{(\sigma_p + 2\sigma_f - \phi(\sigma_p - \sigma_f))}, \quad \varphi_1 = (1 - \phi)^{-2.5} \end{aligned} \right\}. \tag{18}$$

Here, the index f represents the base fluid and P refers to the nanoparticles (Fe_3O_4). The thermophysical characteristics of magnetite nanoparticles are given in Table 1. Moreover, the nanoliquid variable thermal conductivity can be considered as follows (Yasmin, 2022):

$$\kappa_{nf}(T) = \varphi_4 \kappa_0 (1 + \beta \theta(\eta)), \tag{19}$$

where $\varphi_4 = \left(\frac{k_p + 2k_f + 2\phi(k_p - k_f)}{k_p + 2k_f - \phi(k_p - k_f)} \right)$, k_0 represents the constant thermal conductivity of the base fluid and β is a parameter used for variable thermal conductivity.

3 Physical quantities

The physical quantities of concern in the current research are expressed as follows:

$$C_f = \frac{\tau_w}{\rho_f U_w^2}, \quad Nu_s = \frac{sq_w}{k_f (T_w - T_\infty)}, \quad Nn_s = \frac{sq_n}{D_n (n_w - n_\infty)}, \tag{20}$$

TABLE 2 Tables 2(a-d).

ξ	HAM solution	Numerical solution	Absolute error
(a) Validations of the HAM with a numerical method for $f'(\xi)$			
0.0	1.000000	1.000000	0.000000
0.5	0.654935	0.656548	0.001613
1.0	0.466136	0.469411	0.003275
1.5	0.346991	0.351120	0.004129
2.0	0.256295	0.260327	0.004032
2.5	0.180685	0.183972	0.003287
3.0	0.119248	0.121564	0.002315
3.5	0.073023	0.074451	0.001428
4.0	0.041167	0.041928	0.000762
4.5	0.021032	0.021363	0.000331
5.0	0.009352	0.009439	0.000087
(b) Validation of the HAM with the numerical method for $p(\xi)$			
0.0	1.000000	1.000000	0.000000
0.5	0.622007	0.622523	0.000516
1.0	0.402824	0.403989	0.001165
1.5	0.262053	0.263350	0.001297
2.0	0.169004	0.170127	0.001122
2.5	0.107701	0.108555	0.000854
3.0	0.067856	0.068458	0.000602
3.5	0.042343	0.042748	0.000405
4.0	0.026223	0.026486	0.000264
4.5	0.016145	0.016313	0.000168
5.0	0.009897	0.010003	0.000105
(c) Validation of the HAM with the numerical method for $\theta(\xi)$			
0.0	1.000000	1.000000	0.000000
0.5	0.644781	0.644908	0.000127
1.0	0.410030	0.410170	0.000141
1.5	0.257583	0.257698	0.000115
2.0	0.160285	0.160368	0.000083
2.5	0.099048	0.099105	0.000057
3.0	0.060908	0.060945	0.000037
3.5	0.037330	0.037354	0.037354
4.0	0.022829	0.022844	0.000015
4.5	0.013942	0.013951	9.44×10^{-6}
5.0	0.008507	0.008513	5.89×10^{-6}

(Continued in next column)

TABLE 2 (Continued)

ξ	HAM solution	Numerical solution	Absolute error
(d) Validation of the HAM with the numerical method for $\chi(\xi)$			
0.0	1.000000	1.000000	0.000000
0.5	0.657530	0.658168	0.000637
1.0	0.424080	0.424782	0.000703
1.5	0.269068	0.269642	0.000574
2.0	0.168602	0.169017	0.000416
2.5	0.104703	0.104985	0.000283
3.0	0.064615	0.064801	0.000185
3.5	0.039707	0.039826	0.000119
4.0	0.024333	0.024409	0.000075
4.5	0.014886	0.024409	0.000047
5.0	0.009097	0.009126	0.000029

where C_f signifies the skin friction, Nu_s denotes the Nusselt number, and Nn_s represents the nutrient concentration. Moreover, τ_w , q_w , and q_n are the surface shear stress, heat flux, and wall nutrient concentration flux, respectively. These are defined as follows:

$$\tau_{rs} = \left[\left(\mu_{nf} + \frac{1}{\beta c} \right) \left(\frac{\partial u}{\partial r} + \frac{u}{r} \right) - \frac{1}{6\beta c^3} \left(\frac{\partial u}{\partial r} + \frac{u}{r} \right)^3 \right]_{r=R}, \quad (21)$$

$$q_w = -k_{nf} \left[\frac{\partial T}{\partial r} \right]_{r=0}, \quad q_s = -D_n.$$

These quantities can be written in non-dimensional form as follows:

$$C_f (Re_s)^{1/2} = (\varphi_1 + \alpha_1) \left(f''(0) + \frac{f'(0)}{\xi} \right) - \alpha_2 \left(f''(0) + \frac{f'(0)}{\xi} \right)^3,$$

$$Nu_s (Re_s)^{-1/2} = -\theta'(0), \quad Nn_s (Re_s)^{-1/2} = -\omega'(0), \quad (22)$$

where $(Re_s)^{1/2} = \sqrt{\frac{a}{\nu_f(1-c)}} s$ represents the local Reynolds number.

4 Solution methods

To find the solution to the system of Eqs 11–14 under the boundary constraints (16), a HAM (Liao, 2004) approach was used and figures were sketched for convergence. The complete procedure is shown in Eqs 23–45.

The initial guesses were selected as follows:

$$f_0(\eta) = 1 - e^{-\eta}, \theta_0(\eta) = e^{-\eta}, \chi_0(\eta) = e^{-\eta}, \omega_0(\eta) = e^{-\eta}. \quad (23)$$

The linear operators are taken as L_f, L_θ, L_χ , and L_ω :

$$L_f(f) = f''' - f', L_\theta(\theta) = \theta'' - \theta, L_\chi(\chi) = \chi'' - \chi, L_\omega(\omega) = \omega'' - \omega, \quad (24)$$

which have the following properties:

$$L_f(c_1 + c_2\eta + c_3e^{-\eta} + c_4e^{\eta}) = 0, \quad L_\theta(c_5e^{\eta} + c_6e^{-\eta}) = 0, \quad (25)$$

$$L_\chi(c_7e^{-\eta} + c_8e^{\eta}) = 0, \quad L_\omega(c_9e^{-\eta} + c_{10}e^{\eta}) = 0,$$

where c_i ($i = 1 - 10$) are the constants in the general solution. The resultant non-linear operatives N_f, N_θ, N_χ , and N_ω are given as follows:

$$N_f[f(\eta; p)] = (\varphi_4 + \alpha_1) \left[\frac{\partial^4 f(\eta; p)}{\partial \eta^4} + \frac{2}{\xi} \frac{\partial^3 f(\eta; p)}{\partial \eta^3} - \frac{1}{\xi^2} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} + \frac{1}{\xi^3} \frac{\partial f(\eta; p)}{\partial \eta} \right]$$

$$- \varphi_3 M \left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \right) - \varphi_4 \beta_0 \left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \right)$$

$$\times \left[\begin{aligned} & \left(\left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} \right)^2 + \frac{2}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} + \frac{2}{\xi^2} \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^2 \right) \frac{\partial^4 f(\eta; p)}{\partial \eta^4} \\ & + \left(\left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} \right)^2 - \frac{3}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} - \frac{2}{\xi^2} \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^2 \right) \frac{1}{\xi^2} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} \\ & + \frac{3}{\xi^3} \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^3 + 2 \left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \right) \left(\frac{\partial^3 f(\eta; p)}{\partial \eta^3} \right)^2 \\ & + 2 \left(3 \left(\frac{\partial^2 f(\eta; p)}{\partial \eta^2} \right)^3 + \frac{2}{\xi} \frac{\partial f(\eta; p)}{\partial \eta} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} - \frac{1}{\xi^2} \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^2 \right) \frac{1}{\xi} \frac{\partial^3 f(\eta; p)}{\partial \eta^3} \end{aligned} \right]$$

$$\times \varphi_1 \left[\begin{aligned} & \frac{k}{\xi} \left(f(\eta; p) \frac{\partial^3 f(\eta; p)}{\partial \eta^3} - \frac{\partial f(\eta; p)}{\partial \eta} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} \right) + \frac{k}{\xi^2} \left(f(\eta; p) \frac{\partial^2 f(\eta; p)}{\partial \eta^2} - \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^2 \right) \\ & \frac{k}{\xi^3} f(\eta; p) \frac{\partial f(\eta; p)}{\partial \eta} - \frac{\gamma}{\xi} \left(\frac{\xi}{2} \frac{\partial^2 f(\eta; p)}{\partial \eta^2} - \frac{\partial f(\eta; p)}{\partial \eta} \right) - \frac{\gamma}{2} \left(\xi \frac{\partial^3 f(\eta; p)}{\partial \eta^3} + 3 \frac{\partial^2 f(\eta; p)}{\partial \eta^2} \right) \end{aligned} \right] \quad (26)$$

TABLE 3 Comparison of skin friction.

M	Present results	Imtiaz et al. (2019)
0.0	-3.035213606332084	-3.03837
0.2	-3.426597847646775	-3.42970
0.5	-3.8509138382373056	-3.85035

$$N_\theta[f(\eta; p), \theta(\eta; p)] = \varphi_5 \left[\left(1 + \beta \frac{\partial \theta(\eta; p)}{\partial \eta} \right) \left(\frac{\partial^2 \theta(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial \theta(\eta; p)}{\partial \eta} \right) \right]$$

$$+ \beta \left(\frac{\partial \theta(\eta; p)}{\partial \eta} \right)^2 - \varphi_3 M Pr Ec \left(\frac{\partial f(\eta; p)}{\partial \eta} \right)^2$$

$$+ \varphi_2 Pr \left[\left(\frac{k_f}{\xi} - \frac{\gamma \xi}{2} \right) \frac{\partial \theta(\eta; p)}{\partial \eta} + \frac{Q}{\varphi_2} \theta(\eta; p) \right], \quad (27)$$

$$N_\omega[f(\eta; p), \omega(\eta; p)] = \frac{\partial^2 \omega(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial \omega(\eta; p)}{\partial \eta}$$

$$+ Lb \left[\left(\frac{K}{\xi} f(\eta; p) - \frac{\gamma \xi}{2} \right) \frac{\partial \omega(\eta; p)}{\partial \eta} \right]$$

$$+ \lambda (\Omega + \chi(\eta; p)) \quad (28)$$

$$N_\chi[f(\eta; p), \chi(\eta; p)] = \frac{\partial^2 \chi(\eta; p)}{\partial \eta^2} + \frac{1}{\xi} \frac{\partial \chi(\eta; p)}{\partial \eta}$$

$$+ Lb \left[\left(\frac{K}{\xi} f(\eta; p) - \frac{\gamma \xi}{2} \right) \frac{\partial \chi(\eta; p)}{\partial \eta} \right] + \lambda (\Omega + \chi(\eta; p)). \quad (29)$$

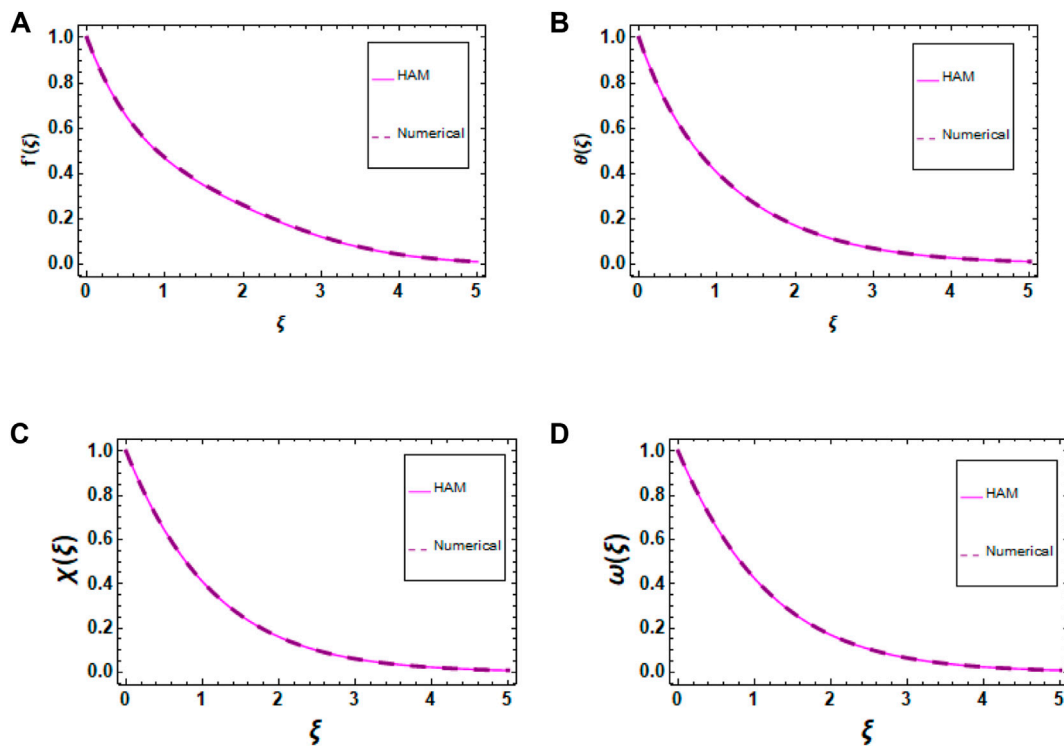


FIGURE 2 (A–D) Graphical validations of the HAM with numerical methods for $f'(\xi)$, $p(\xi)$, $\theta(\xi)$, and $\chi(\xi)$.

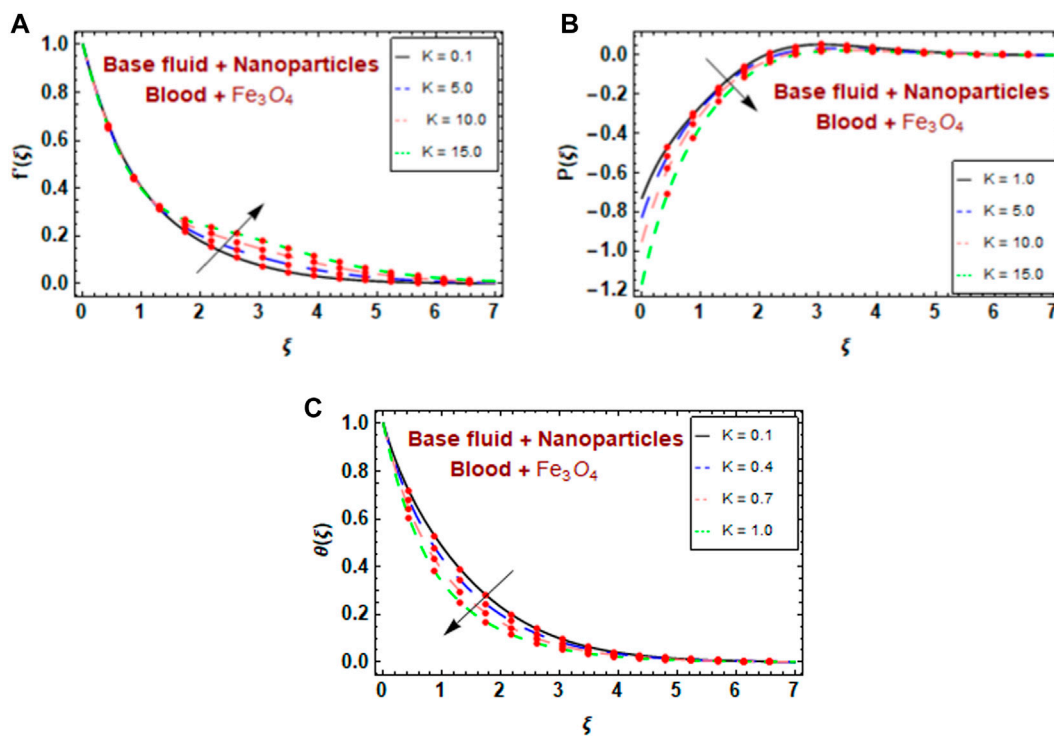


FIGURE 3 (A–C) Variations in $f'(\xi)$, $p(\xi)$, and $\theta(\xi)$ for distinct numbers of K .

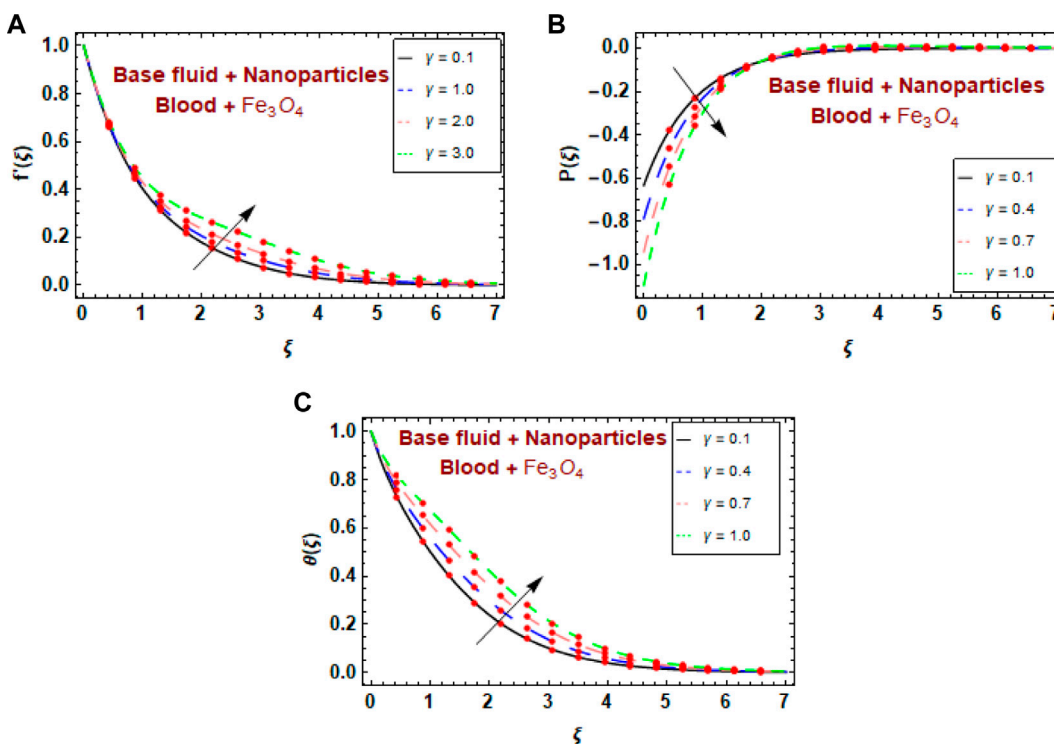


FIGURE 4 (A–C) Variations in $f'(\xi)$, $p(\xi)$, and $\theta(\xi)$ for distinct numbers of γ .

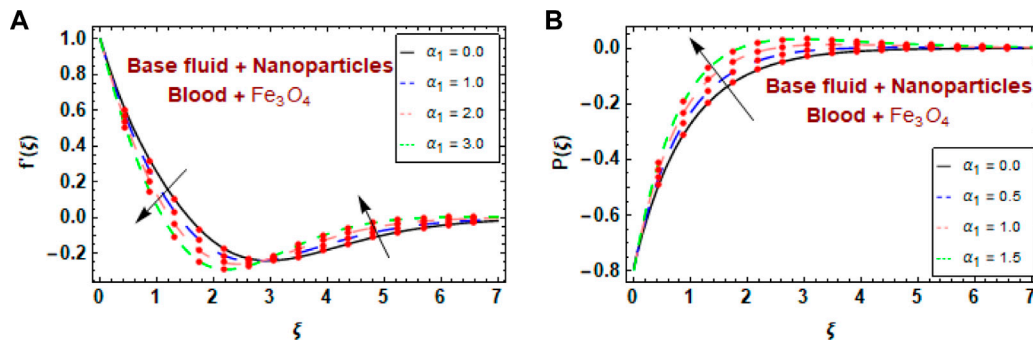


FIGURE 5 (A,B) Variations in $f'(\xi)$ and $p(\xi)$ for distinct numbers of α_1 .

The fundamental concept of HAM is characterized in Cui et al. (2012), Kong et al. (2014), Mathuriya et al. (2015), and Anik et al. (2021). The zeroth-order problems from Eqs 9–12 are as follows:

$$(1 - p)L_f[f(\eta; p) - f_0(\eta)] = p\hbar_f N_f[f(\eta; p)], \quad (30)$$

$$(1 - p)L_\theta[\theta(\eta; p) - \theta_0(\eta)] = p\hbar_\theta N_\theta[f(\eta; p), \theta(\eta; p)], \quad (31)$$

$$(1 - p)L_\omega[\omega(\eta; p) - \omega_0(\eta)] = p\hbar_\omega N_\omega[f(\eta; p), \omega(\eta; p)], \quad (32)$$

$$(1 - p)L_\chi[\chi(\eta; p) - \chi_0(\eta)] = p\hbar_\chi N_\chi[f(\eta; p), \omega(\eta; p), \chi(\eta; p)]. \quad (33)$$

The equivalent boundary conditions are as follows:

$$\begin{aligned} f(\eta; p)|_{\eta=0} = 0, \quad \frac{\partial f(\eta; p)}{\partial \eta}|_{\eta=0} = 1, \quad \frac{\partial f(\eta; p)}{\partial \eta}|_{\eta \rightarrow \infty} = 0, \\ \theta(\eta; p)|_{\eta=0} = 0, \quad \theta(\eta; p)|_{\eta \rightarrow \infty} = 0, \\ \omega(\eta; p)|_{\eta=0} = 0, \quad \omega(\eta; p)|_{\eta \rightarrow \infty} = 0, \\ \chi(\eta; p)|_{\eta=0} = 0, \quad \chi(\eta; p)|_{\eta \rightarrow \infty} = 0, \end{aligned} \quad (34)$$

where $p \in [0, 1]$ is the imbedding parameter and $\hbar_f, \hbar_\theta, \hbar_\omega$, and \hbar_χ are used to control the convergence of the solution. When $p = 0$ and $p = 1$,

$$f(\eta; 1) = f(\eta), \quad \theta(\eta; 1) = \theta(\eta), \quad \omega(\eta; 1) = \omega(\eta), \quad \chi(\eta; 1) = \chi(\eta). \quad (35)$$

and expanding $f(\eta; p), \theta(\eta; p), \omega(\eta; p)$, and $\chi(\eta; p)$ in the Taylor's series about $p = 0$,

$$\begin{aligned} f(\eta; p) &= f_0(\eta) + \sum_{m=1}^{\infty} f_m(\eta) p^m, \\ \theta(\eta; p) &= \theta_0(\eta) + \sum_{m=1}^{\infty} \theta_m(\eta) p^m, \\ \omega(\eta; p) &= \omega_0(\eta) + \sum_{m=1}^{\infty} \omega_m(\eta) p^m, \\ \chi(\eta; p) &= \chi_0(\eta) + \sum_{m=1}^{\infty} \chi_m(\eta) p^m, \end{aligned} \quad (36)$$

where

$$\begin{aligned} f_m &= \frac{1}{m!} \left. \frac{\partial f(\eta; p)}{\partial p} \right|_{p=0}, \quad \theta_m = \frac{1}{m!} \left. \frac{\partial \theta(\eta; p)}{\partial p} \right|_{p=0}, \\ \omega_m &= \frac{1}{m!} \left. \frac{\partial \omega(\eta; p)}{\partial p} \right|_{p=0}, \quad \chi_m = \frac{1}{m!} \left. \frac{\partial \chi(\eta; p)}{\partial p} \right|_{p=0}. \end{aligned} \quad (37)$$

The secondary constraints $\hbar_f, \hbar_\theta, \hbar_\omega$, and \hbar_χ are selected so that the series (27) converges at $p = 1$; substituting $p = 1$ in (27), we obtain:

$$\begin{aligned} f(\eta) &= f_0(\eta) + \sum_{m=1}^{\infty} f_m(\eta), \\ \theta(\eta) &= \theta_0(\eta) + \sum_{m=1}^{\infty} \theta_m(\eta), \\ \omega(\eta) &= \omega_0(\eta) + \sum_{m=1}^{\infty} \omega_m(\eta), \\ \chi(\eta) &= \chi_0(\eta) + \sum_{m=1}^{\infty} \chi_m(\eta). \end{aligned} \quad (38)$$

The m^{th} - order problem satisfies the following:

$$\begin{aligned} L_f[f_m(\eta) - \chi_m f_{m-1}(\eta)] &= \hbar_f R_m^f(\eta), \\ L_\theta[\theta_m(\eta) - \chi_m \theta_{m-1}(\eta)] &= \hbar_\theta R_m^\theta(\eta), \\ L_\omega[\omega_m(\eta) - \chi_m \omega_{m-1}(\eta)] &= \hbar_\omega R_m^\omega(\eta), \\ L_\chi[\chi_m(\eta) - \chi_m \chi_{m-1}(\eta)] &= \hbar_\chi R_m^\chi(\eta). \end{aligned} \quad (39)$$

The following are the corresponding boundary conditions:

$$\begin{aligned} f_m(0) = f'_m(0) = \theta_m(0) = \omega_m(0) = \chi_m(0) = 0, \\ f'_m(\infty) = \theta_m(\infty) = \omega_m(\infty) = \chi_m(\infty) = 0. \end{aligned} \quad (40)$$

Here,

$$\begin{aligned} R_m^f(\eta) &= (\varphi_4 + \alpha_1) \left[f_{m-1}'' + \frac{2}{\xi} f_{m-1}' + \frac{1}{\xi^2} f_{m-1} \right] \\ &\quad - \varphi_3 M \left(f_{m-1} + \frac{1}{\xi} f_{m-1}' \right) - \varphi_4 \beta_0 \left(f_{m-1} + \frac{1}{\xi} f_{m-1}' \right) \\ &\quad + \left(\sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l'' + \frac{2}{\xi} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l' \right) \\ &\quad + \frac{2}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l'' \\ &\quad - \alpha_2 \left(\frac{1}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l'' - \frac{3}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l' - \frac{2}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l \right) \\ &\quad + \frac{3}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l' + 2 \left(\sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l'' + \frac{1}{\xi} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l' \right) \\ &\quad + 2 \left(\frac{3}{\xi} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l'' + \frac{2}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l' - \frac{1}{\xi^3} \sum_{k=0}^{m-1} f_{m-1-k} \sum_{l=0}^k f_{k-l} f_l \right) \\ &\quad + \varphi_1 \left(\frac{k}{\xi} \left(\sum_{k=0}^{m-1} f_{m-1-k} f_k'' - \sum_{k=0}^{m-1} f_{m-1-k} f_k' \right) + \frac{k}{\xi^2} \left(\sum_{k=0}^{m-1} f_{m-1-k} f_k' - \sum_{k=0}^{m-1} f_{m-1-k} f_k \right) \right) \\ &\quad + \varphi_1 \left(\frac{k}{\xi^2} \sum_{k=0}^{m-1} f_{m-1-k} f_k'' - \frac{\gamma}{\xi} \left(\frac{\xi}{2} f_{m-1}'' \right) - \frac{\gamma}{2} (\xi f_{m-1}' + 3 f_{m-1}') \right) \end{aligned} \quad (41)$$

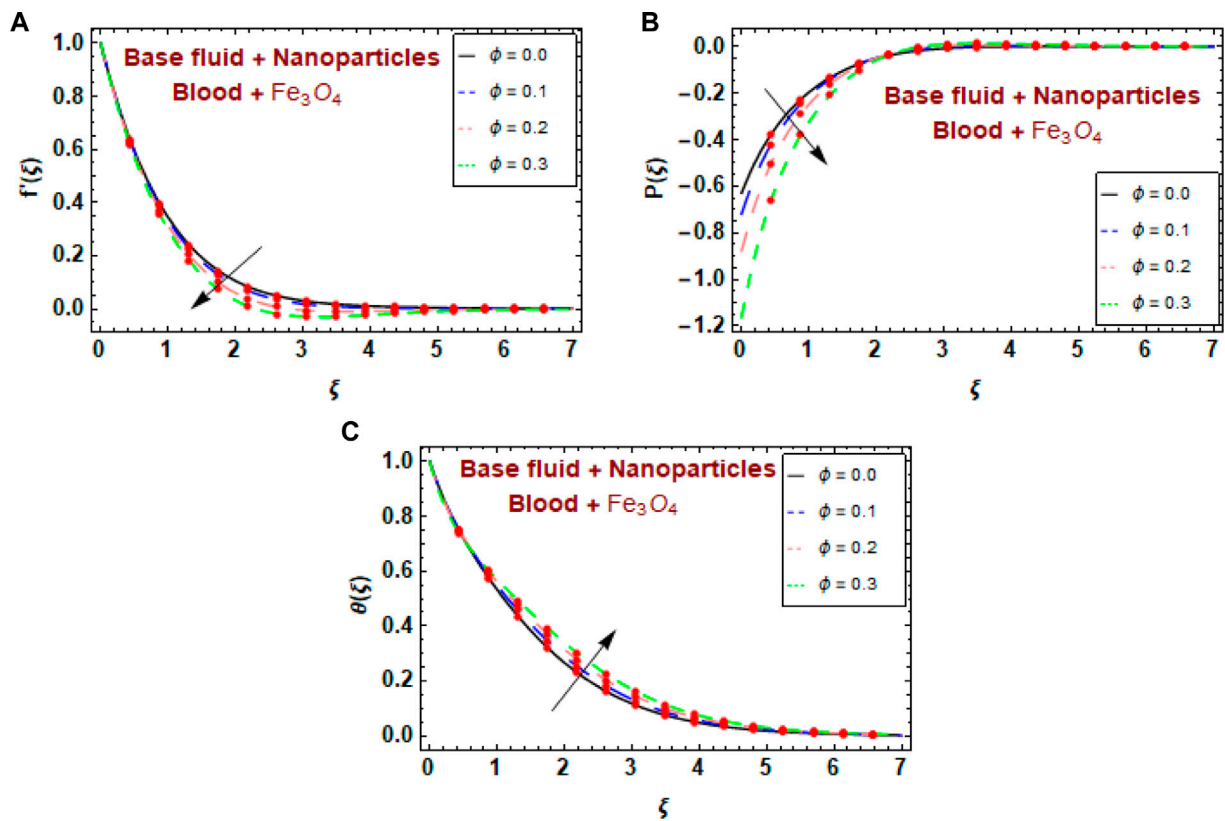


FIGURE 6 (A–C) Variations in $f'(\xi)$, $p(\xi)$, and $\theta(\xi)$ for distinct numbers of ϕ .

$$R_m^\theta(\eta) = \varphi_5 \left(\left(\theta''_{m-1} + \frac{1}{\xi} \theta'_{m-1} \right) + \beta \left(\sum_{k=0}^{m-1} \theta'_{m-1-k} \theta''_k + \frac{1}{\xi} \sum_{k=0}^{m-1} \theta'_{m-1-k} \theta'_k \right) + \beta \sum_{k=0}^{m-1} \theta'_{m-1-k} \theta'_k - \varphi_3 MPrEc \sum_{k=0}^{m-1} f'_{m-1-k} f'_k + \varphi_2 Pr \left(\left(\frac{k_f}{\xi} - \frac{\gamma \xi}{2} \right) \theta'_{m-1} + \frac{Q}{\varphi_2} \theta_{m-1} \right) \right), \quad (42)$$

$$R_m^\omega(\eta) = \omega''_{m-1} + \frac{1}{\xi} \omega'_{m-1} + Lb \left[\left(\frac{K}{\xi} \sum_{k=0}^{m-1} f_{m-1-k} \omega_k - \frac{\gamma \xi}{2} \omega'_{m-1} \right) + \lambda (\Omega + \chi_{m-1}) \right], \quad (43)$$

$$R_m^\chi(\eta) = \chi''_{m-1} + \frac{1}{\xi} \chi'_{m-1} + Lb \left[\left(\frac{K}{\xi} \sum_{k=0}^{m-1} f_{m-1-k} \chi_k - \frac{\gamma \xi}{2} \chi'_{m-1} \right) + \lambda (\Omega + \chi_{m-1}) \right], \quad (44)$$

where

$$\chi_m = \begin{cases} 0, & \text{if } p \leq 1, \\ 1, & \text{if } p > 1. \end{cases} \quad (45)$$

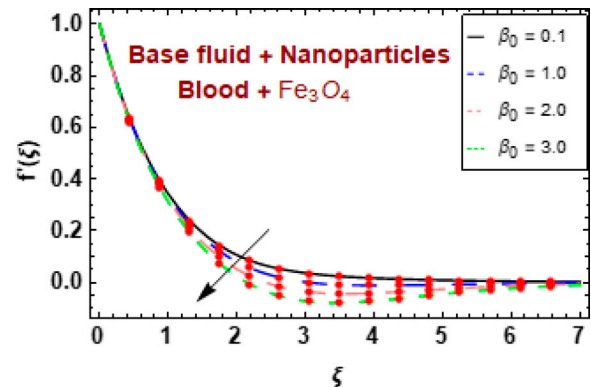


FIGURE 7 Variations in $f'(\xi)$ for distinct numbers of β_0 .

5 Validations of the results

This section shows the result validations graphically and numerically. The results obtained using the semi-analytical HAM

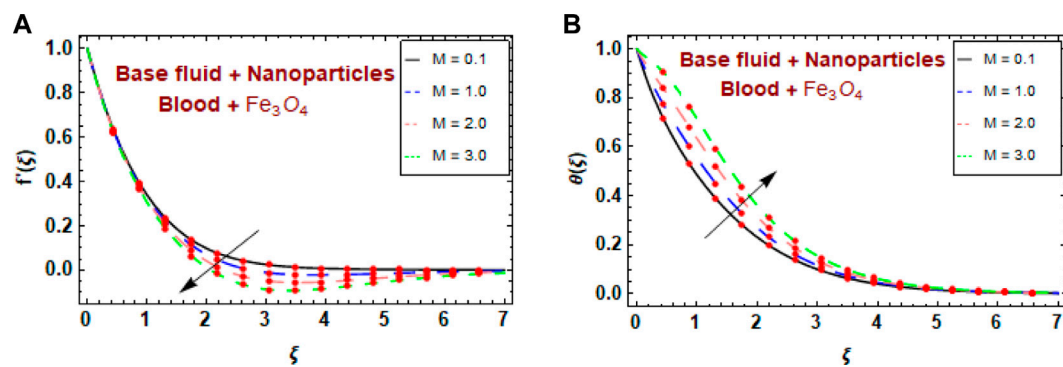


FIGURE 8
(A,B) Variations in $f'(\xi)$ and $\theta(\xi)$ for distinct numbers of M .

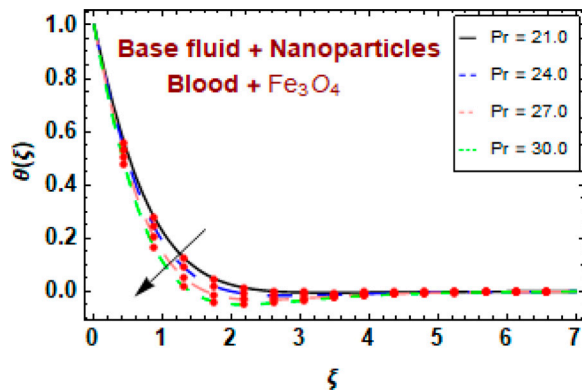


FIGURE 9
Variations in $\theta(\xi)$ for distinct numbers of Pr .

method are compared to the numerical (ND-Solved) techniques for temperature $\theta(\xi)$, pressure $p(\xi)$, velocity $f'(\xi)$, bacterial density field $\chi(\xi)$, and nutrient concentration $\omega(\xi)$.

Table 2(a–d) shows the results of the HAM solutions, numerical solutions, and the absolute errors for temperature $\theta(\xi)$, pressure $p(\xi)$, velocity $f'(\xi)$, bacterial density field $\chi(\xi)$, and nutrient concentration $\omega(\xi)$. We observed excellent agreement between the results for all profiles. Table 3 shows a comparison between the current and previous results (Elgazery et al., 2022) for skin friction and it was found that both results agreed. Figures 2A–D show comparison between HAM and numerical solutions for the temperature $\theta(\xi)$, pressure $p(\xi)$, velocity $f'(\xi)$, the bacterial density field $\chi(\xi)$, nutrient concentration $\omega(\xi)$. An excellent agreement is found between both results for all profile.

6 Results and discussion

This investigation used HAM to graphically explore the efficacy of numerous governing factors, such as the curvature factor K , volume fraction ϕ , maximum bacteria growth rate λ , fluid parameter α_1 , unsteady parameter γ , magnetic parameter M , porosity

parameter β_0 , non-dimensional bacterial density difference Ω , non-dimensional generation/absorption coefficient, bioconvection Lewis number Lb , and variable thermal conductivity β , on the temperature $\theta(\xi)$, pressure $p(\xi)$, velocity $f'(\xi)$, bacterial density field $\chi(\xi)$, nutrient concentration $\omega(\xi)$, Nusselt number, skin friction, and density of nutrient concentration.

Figures 3A–C show how the curvature factor K affects the velocity $f'(\xi)$, pressure $P(\xi)$, and temperature $\theta(\xi)$ curves, in which increases in velocity and decreases in pressure resulted in increased curvature parameter values. Tumor blood flow usually decreases as tumors grow larger; however, mathematical examination predicted that enhancing the curvature parameter would boost tumor blood flow, which may enhance medical treatment.

Furthermore, as shown in Figures 4A, B increasing the curvature parameter value increased the radius of the curved surface, which increased the velocity and decreased the pressure. Due to vascular damage, the environment within the tumors became hypoxic, acidic, and nutritionally deficient when heated. These suboptimal environmental changes enhance the tumor cell hyperthermia response, inhibit thermal damage repair, and interfere with the development of thermal tolerance. At high temperatures, the acidic environment enhances the tumor cell response to certain drugs. As shown in Figure 4C, the temperature decreased as the curvature factor increased, and increased with increasing unsteady parameter. In medical treatment, to enhance the tumor cell response to magnetic magnetite nanoparticles, γ should be increased, thus increasing the environmental temperature of the nanofluid. Figures 4A, B show increased velocity and decreased pressure with increasing unsteady parameter γ .

Figures 5A, B show the effect of the fluid parameter α_1 on velocity and pressure. Figure 5A shows that the blood velocity first decreased and then gradually increased as the fluid parameter value increased. Figure 5B shows that the blood pressure curves increased for large fluid parameter values.

Figures 6A–C show how the magnetite nanoparticle volume fraction parameter ϕ affects the velocity $f'(\xi)$, pressure $P(\xi)$, and temperature $\theta(\xi)$ curves. As the volume fraction of magnetite nanoparticles increased, the velocity profile and pressure distribution decreased. The mathematical explanation showed that magnetite nanoparticles reduced blood flow pressure, which

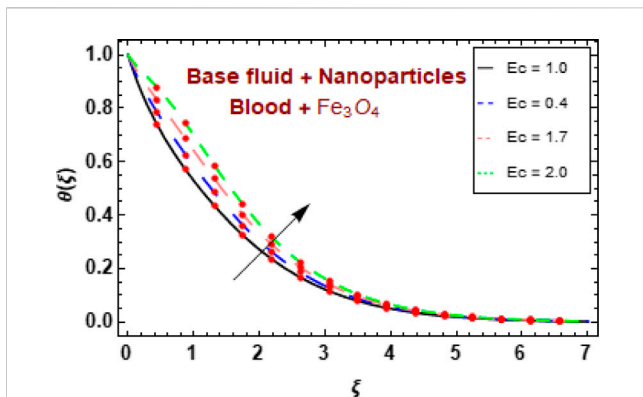


FIGURE 10 Variations in $\theta(\xi)$ for distinct numbers of Ec .

is a beneficial outcome in the medical treatment of cancer, thus demonstrating the potential effectiveness of magnetite nanoparticles in medical therapy. As the concentration of magnetite nanoparticles increased, so did the blood temperature distribution. Therefore, passing magnetite nanoparticles through the blood improves its physical properties.

The impact of the porosity parameter on blood velocity is shown in Figure 7, in which the blood velocity decreased as the porosity

increased. This effect occurred because increasing blood porosity increased the interactions and fraction between the flow and blood cells, resulting in decreased velocity.

The exploration of the magnetic factor M showed that opposition in artificial magnetic bacteria swimming within the blood flow was a major factor. Figures 8A, B show the effects of M on the velocity $f'(\xi)$ and temperature $\theta(\xi)$, respectively. When the magnetic factor M increased, $f'(\xi)$ decreased and $\theta(\xi)$ increased. The changes in magnetite/blood velocity were inversely related to the magnetic factor. Thus, applying a magnetic field to an electrically conducting liquid created a resistive Lorentz force that tended to diminish the fluid flow while increasing the temperature.

Figure 9 depicts the influence of the Prandtl number Pr on the temperature $\theta(\xi)$. As Pr increased, the temperature decreased. The thermal boundary layer thickness decreased as the Prandtl number increased. The Prandtl number is the momentum diffusivity/thermal diffusivity ratio and it governs the relative thickening of the momentum and thermal boundary layers in heat transfer.

Figure 10 shows the temperature distribution for various Eckert number Ec values. The relationship between heat enthalpy difference and flow kinetic energy is known as the Eckert number Ec . Therefore, increasing the Eckert number increases the kinetic energy. Furthermore, temperature is defined as the

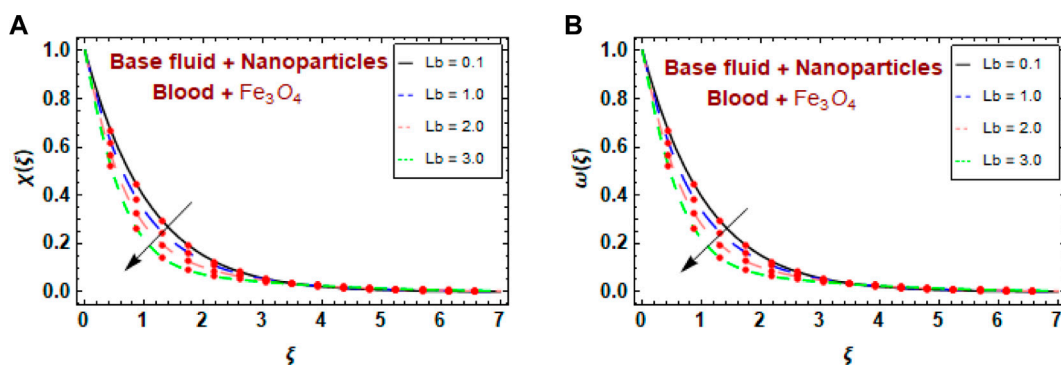


FIGURE 11 (A,B) Variations in $\chi(\xi)$ and $\omega(\xi)$ for distinct numbers of Lb .

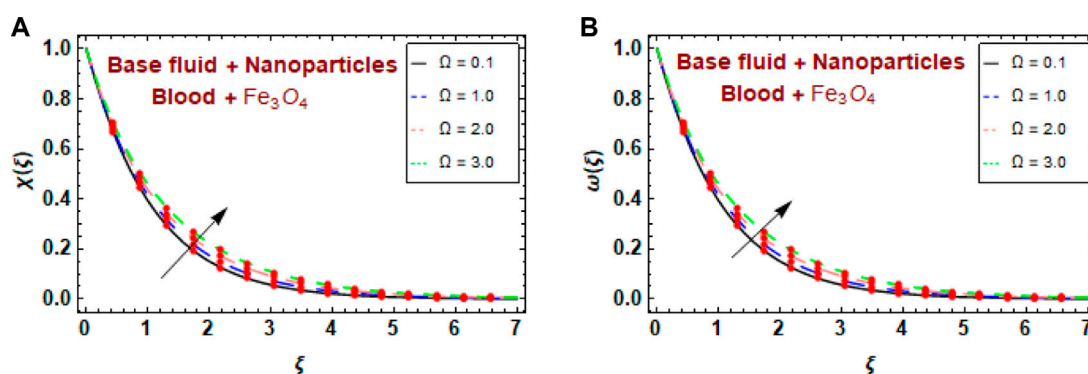


FIGURE 12 (A,B) Variations in $\chi(\xi)$ and $\omega(\xi)$ for distinct numbers of Ω .

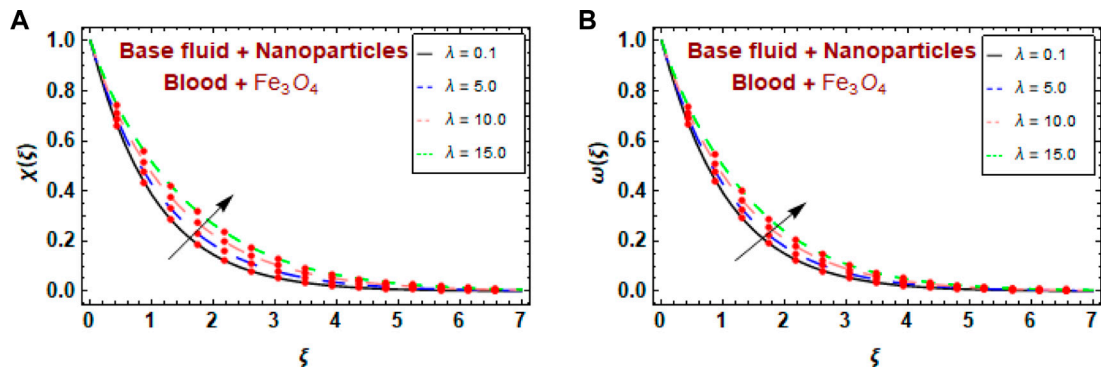


FIGURE 13 (A,B) Variations in $\chi(\xi)$ for distinct numbers of λ .

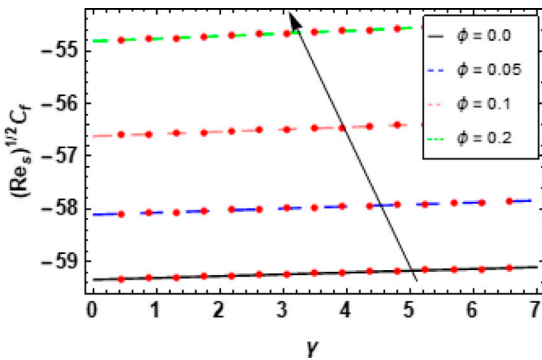


FIGURE 14 Influences of γ and ϕ on skin friction.

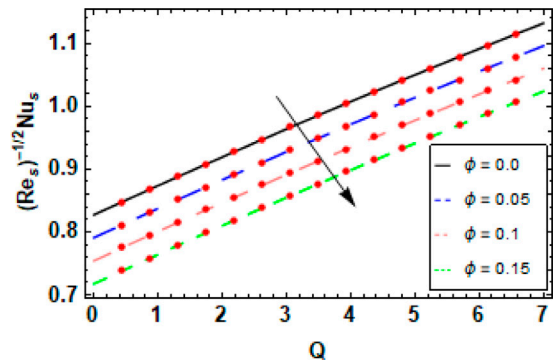


FIGURE 16 Effects of Q and ϕ on $Nu_s (Re_s)^{-1/2}$.

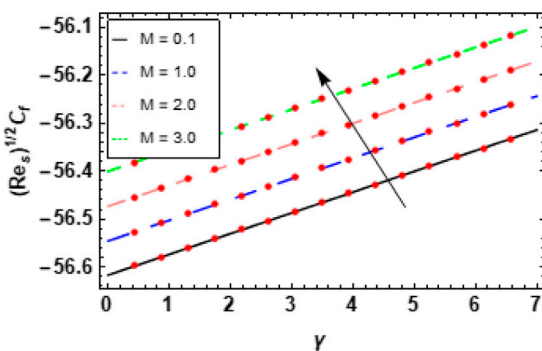


FIGURE 15 Influences of γ and M on skin friction.

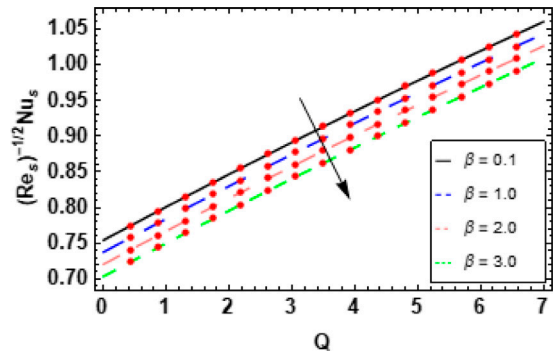


FIGURE 17 Effects of Q and β on $Nu_s (Re_s)^{-1/2}$.

average kinetic energy. Consequently, the temperature of the fluid increased with increasing Eckert number Ec .

Figures 11A, B show the effect of the bioconvection Lewis number Lb on the bacterial density $\chi(\xi)$ and nutrient concentration $\omega(\xi)$, in

which both bacterial density and nutrient concentration decreased with increasing bioconvection Lewis number Lb .

Figures 12A, B show the influence of the bacterial density parameter Ω on the bacterial density field $\chi(\xi)$ and nutrient

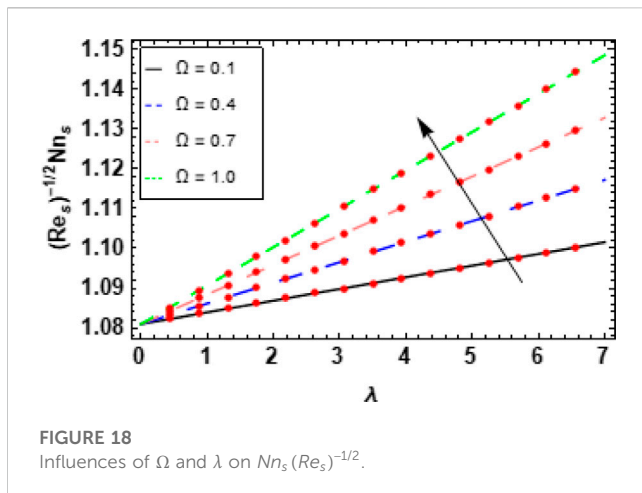


FIGURE 18
Influences of Ω and λ on $Nn_s (Re_s)^{-1/2}$.

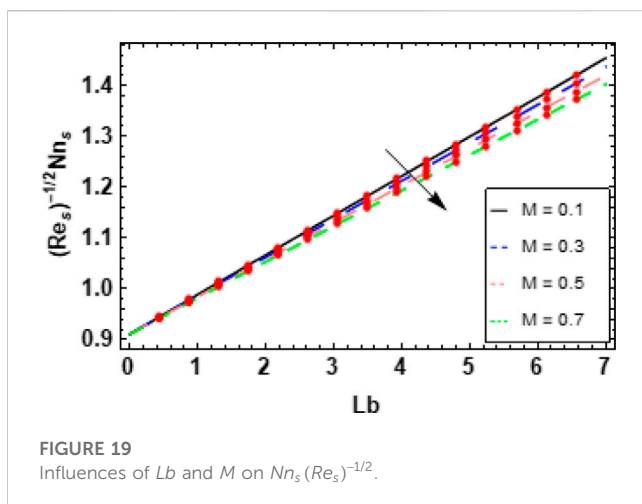


FIGURE 19
Influences of Lb and M on $Nn_s (Re_s)^{-1/2}$.

concentration $\omega(\xi)$. As the Ω increased, so did the bacterial density and nutrient concentration.

The effects of the bacteria maximum growth rate λ on the bacterial density and nutrient concentration are shown in Figures 13A, B, in which the bacterial density and nutrient concentration fields improved when the bacterial maximum growth rate increased.

6.1 Skin friction coefficients and Nusselt numbers

Figures 14, 15 show the effects of the nanoparticle volume fraction ϕ and magnetic factor M on the skin friction coefficient, with mainly significant influences on the unsteady constraint γ on skin friction. The skin friction increased with increasing ϕ and M .

Figure 16 shows the effects of the volume fraction ϕ and variable thermal conductivity constraint β on the Nusselt number. The Nusselt number decreased with increasing ϕ . Figure 17 shows the effects of β against Q on the Nusselt number distribution. The Nusselt number decreased with increasing β .

Figure 18 shows the variation in the nutrient concentration density because of the bacterial difference density Ω and the optimum bacterial growth rate λ . When both the bacterial difference density and the optimum bacterial growth rate increased, the nutrient concentration density increased. These mathematical outcomes showed that in the medical treatment of cancer using magnetite nanoparticles and artificial bacteria, it is preferable to moderate the bacterial difference density and the bacterial growth rate to increase nutrients in normal cells while decreasing nutrient consumption in tumor cells. Figure 19 also shows the behavior of the nutrient concentration density as a function of the bioconvection Lewis number Lb and the magnetic parameter M . The nutrient concentration density value improved as the Lewis number increased but decreased as the magnetic parameter increased. Physically, in medical treatment, increasing the magnetic factor and decreasing the ratio of thermal diffusivity to mass diffusivity are recommended to increase nutrient consumption in normal cells while decreasing nutrient consumption in tumor cells.

7 Conclusion

This study aimed to determine the effectiveness of an external magnetic field on bacteria enclosed by thousands of magnetic magnetite nanoparticles. Variable thermal conductivity and Joule heating were used in the interstitial nanofluid, in which artificial bacteria swam in a biological cell. The unsteady motion of a Powell–Eyring fluid in two dimensions was considered. A porous stretching wall was used as a curved surface structure. To convert the governing non-linear PDEs into non-linear ODEs, suitable transformations were exploited. The HAM was used to resolve the semi-analytical results of non-linear ODEs. This mathematical procedure demonstrates unnatural magnetic bacterium that can function like a compass that is magnetically charged to mark and abolish tumors by spinning at such a high rate that tumors heat and melt. We discovered the following:

- The blood velocity improved at higher curvature parameter values and was unsteady when the velocity decreased for large magnetic factor, volume fraction, and porosity parameter values.
- The blood velocity profile began to decrease and then gradually increased with increasing fluid parameter values.
- The mathematical description revealed that magnetite nanoparticles lower blood pressure, which is a beneficial outcome in the clinical consideration of cancer, and demonstrates the effectiveness of magnetite nanoparticles in such medical therapy.
- The mathematical analysis showed that to enhance the reaction of tumor cells to several drugs in an acidic environment, temperatures should be raised by increasing the characteristics of the nearby environment, including the unsteady parameter, Eckert number, magnetite nanoparticles, and magnetic parameters.

- To increase nutrient consumption in normal cells while decreasing nutrient consumption in tumor cells, our mathematical outcomes showed that the bacterial difference density, bacterial growth rate, and Lewis number should be moderated in the medical treatment of cancer using magnetite nanoparticles and artificial bacteria.
- For the intensification of the unsteady parameter, applied magnetic fields should be considered.

Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material. Further inquiries can be directed to the corresponding authors.

Author contributions

All authors listed have made substantial, direct, and intellectual contributions to the work and approved it for publication.

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Nomenclature

(r, s) curvilinear coordinates

(u, v) velocity components

p pressure

T temperature

R curvature radius

k thermal conductivity

k_1 permeability of the porous medium

t time

n nutrient concentration

D_n nutrient diffusivity

K curvature parameter

Pr Prandtl number

Lb bioconvection Lewis number

M magnetic parameter

Q generation/absorption coefficient

μ dynamic viscosity

ν kinematic viscosity

ρ density

ρ_n bacterial density

β thermal conductivity parameter

β_0 porosity parameter

γ unsteady parameter

Ω bacterial difference density

λ bacteria maximum growth rate

ϕ nanoparticle volume fraction

Subscripts

nf nanofluid

f base fluid

p nanoparticles

w at the curved surface

∞ far from the surface

Greek terms

α_1, α_2 fluid parameters