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A comprehensive review of remote sensing techniques for monitoring *Ulva prolifera* green tides

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In recent years, *Ulva prolifera* green tide, as a large-scale marine ecological phenomenon, has occurred frequently in coastal areas such as the Yellow Sea and the East China Sea, significantly affecting marine ecosystems and fishery resources. With the continuous advancement of remote sensing technologies, these technologies have become indispensable tools for monitoring *Ulva prolifera* green tides. This review provides a comprehensive overview of the advances in remote sensing band indices for detecting green tides, including spatiotemporal distribution analysis, area and biomass estimation, drift trajectory modeling, and investigations of their driving mechanisms. Additionally, it identifies the limitations and unresolved challenges in current approaches, such as constraints on data resolution, algorithmic biases, and environmental variability. The potential for integrating multi-source remote sensing data with marine environmental parameters and deep learning techniques is discussed, emphasizing their roles in improving the accuracy and reliability of monitoring and predicting *Ulva prolifera* green tides. This review aims to guide future research efforts and technological innovations in this field.

KEYWORDS

Ulva prolifera green tide, Yellow Sea, East China Sea, remote sensing, deep learning

1 Introduction

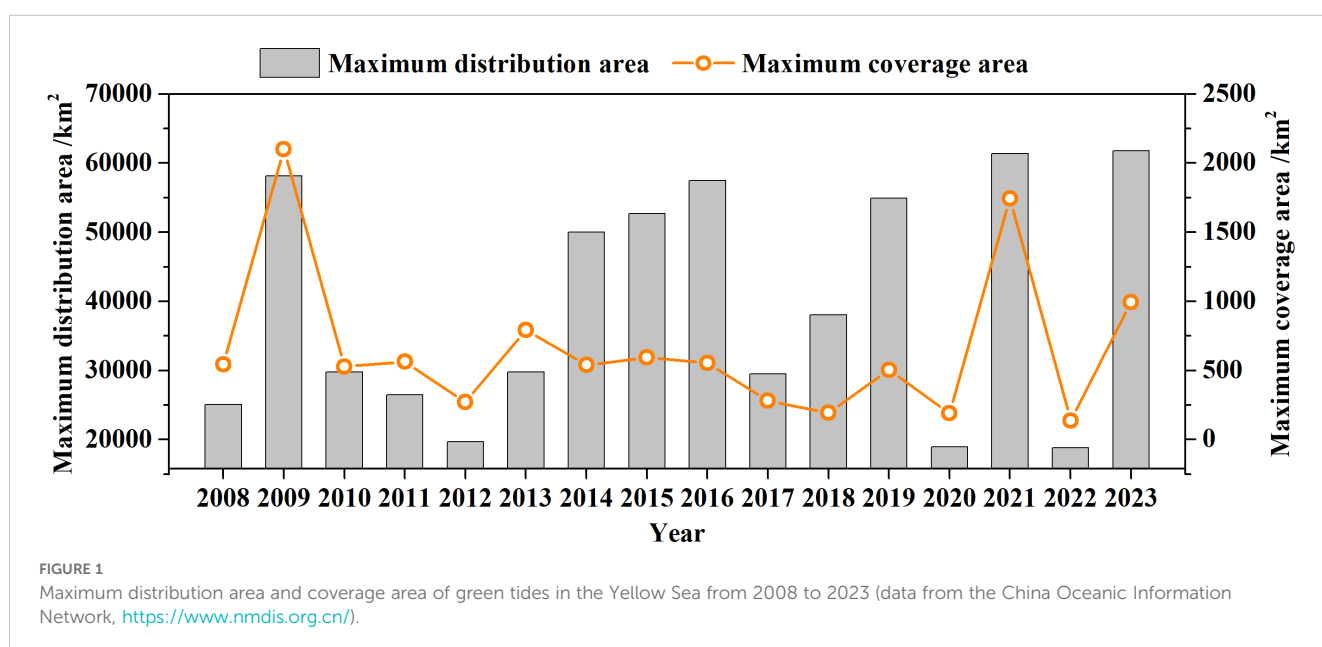
Considering global environmental change, the dynamics of large-scale algal blooms, particularly *Ulva prolifera* green tides, have become a central topic of research. Since 2007, large-scale green tides have occurred annually in the Yellow Sea of China, attracting considerable attention from the government and researchers, especially after the 2008

outbreak in the waters near Qingdao, which interfered with Olympic sailing events (Hu and He, 2008; Zhang et al., 2019). Figure 1 illustrates the annual extent of green tides in the Yellow Sea from 2008 to 2023. Although the maximum distribution and coverage areas were relatively low in 2012, 2020, and 2022, the extent and coverage of green tides have shown an increasing trend over the years. These blooms not only affect the coastal landscape but also obstruct navigation channels, thereby posing serious threats to coastal fisheries, aquaculture, and tourism (Hu and He, 2008; Xing and Hu, 2016).

Over the past two decades, the cultivation areas for *Porphyra* in China have expanded nearly fourfold, as shown in Figure 2. The *Porphyra* aquaculture rafts areas in the Subei Shoal (Lianyungang, Yancheng, and Nantong) are widely recognized as the primary breeding grounds for *Ulva prolifera* green tides (Hu, 2009; Liu et al., 2010; Xing et al., 2011; Keesing et al., 2011; Xing et al., 2018). These regions provide optimal conditions for the proliferation and dispersal of *Ulva prolifera*, driven by aquaculture activities, nutrient enrichment (both inorganic and organic), sea surface temperature, solar radiation, and hydrodynamic conditions. Previous studies have also highlighted a strong correlation between large-scale seaweed cultivation in the Subei region and the occurrence of extensive macroalgal blooms in the southern Yellow Sea (Geng et al., 2015; Zhang et al., 2017). In addition, this strong correlation was further confirmed through rDNA sequence analysis, with identical morphological characteristics observed (Liu et al., 2010; Zhang et al., 2014). In general, *Porphyra* cultivation begins every October, with rafts and ropes deployed into the sea, providing surfaces where green algae such as *Ulva* readily attach (Liu et al., 2010). By the following spring, as seawater temperatures reach approximately 20°C, *Ulva prolifera* rapidly competes with *Porphyra* for space. During *Porphyra* harvest and raft removal, some *Ulva* inevitably detaches in shallow waters (Liu et al., 2016; Hu et al., 2023). A study estimated that approximately 4,000 tons of *Ulva prolifera* biomass detached from aquaculture rafts during the

raft retrieval period, floating into the surrounding waters of the Subei Shoal and providing the initial biomass for the large-scale green tide outbreak in the Yellow Sea (Han et al., 2020). Driven by tides, currents, and winds, these algae float to the surface and flourish under favorable light, temperature, and nutrient conditions, thereby drifting northward to the Shandong coast (Hu et al., 2010; Liu et al., 2013; Wang et al., 2015; Xing et al., 2019). Figure 3 illustrates the temporal and spatial dynamics of *Ulva prolifera* green tides over May, June, and July. During May, *Ulva prolifera* first appears in the Subei Shoal, marking the initial stage of its development. In June, it undergoes rapid growth, reaching its maximum coverage. In July, the algae gradually drift and accumulate in the waters near Qingdao, driven by prevailing hydrodynamic conditions. These spatiotemporal dynamics are consistent with findings reported by Kwan et al. (2022) and Yuan (2022), who also observed similar growth patterns and drifting behaviors in their studies. This phenomenon can be attributed to a combination of favorable natural conditions, such as hydrodynamic patterns and nutrient availability, alongside anthropogenic influences like coastal aquaculture and pollution, making the Yellow Sea and the East China Sea a hotspot for *Ulva prolifera* green tide blooms (Li et al., 2017; Zhang et al., 2019, 2020). Additionally, *Ulva prolifera* green tide has also occurred along the coasts of South Korea, certain regions of Southeast Asia, and the Gulf of Mexico (Hu, 2009; Kim et al., 2020; Shao et al., 2024). Although the frequency and extent of these green tide events in these regions are relatively lower than those in the Yellow Sea and the East China Sea, they still represent potential sites for green tide growth because of favorable environmental conditions.

Satellite remote sensing offers extensive monitoring coverage, high temporal resolution, and low-cost monitoring of green tides, enabling long-term dynamic observation. Consequently, remote sensing is widely applicable for monitoring green tide coverage, biomass, and drift trajectory of *Ulva prolifera* blooms. As reviewed in the literature, various sensors with distinct spectral bands and



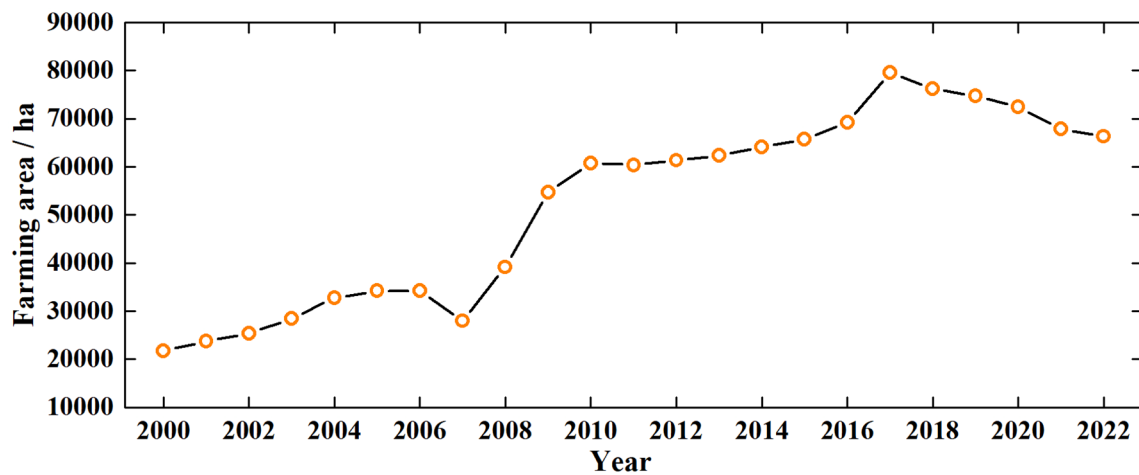


FIGURE 2
Cultivated area of Porphyra in China (data from the National Fisheries Statistical Yearbook).

resolutions have been used to monitor *Ulva prolifera* green tides, including MODIS, VIIRS, GOCI I/II, Landsat-3/5/7/8/9, as well as China's GaoFen series, HJ-1 series, and HaiYang-2 series satellites (Son et al., 2015; Xing and Hu, 2016, 2016; Sun et al., 2021; Men et al., 2023), as summarized in Table 1.

Ulva prolifera green tides are characterized by their dark green appearance in remote sensing imagery, primarily due to the filamentous structure of their thalli. This distinctive appearance of *Ulva prolifera* green tides is attributed to its unique spectral nature, which features higher reflectance in the green wavelength range and lower reflectance in the near-infrared (NIR) band (Zhang et al., 2013). Based on these spectral characteristics, several band indices have been developed and applied for detecting *Ulva prolifera* green tides. A comprehensive summary of these indices and their applications is presented in Table 1. These band indices include the normalized difference vegetation index (NDVI) (Hu and He, 2008; Hu, 2009), the normalized difference algae index (NDAI) (Shi and Wang, 2009), the floating algae index (FAI) (Hu, 2009; Garcia et al., 2013; Hu et al., 2015), the alternative floating algae index (AFAI) (Wang and Hu, 2016, 2017), the scaled algae index (Keesing et al., 2011), the enhanced vegetation index (EVI) (Xing et al., 2018;

Zheng et al., 2020), the difference vegetation index (DVI) (Li et al., 2018; Xing et al., 2019), virtual-baseline floating algae height (VBFAH) (Li et al., 2018), and the ratio vegetation index (RVI) (Wang et al., 2019; Zheng et al., 2020), among others indices (Yu et al., 2023; Wei and Wang, 2024; Zhang et al., 2024a). These indices have significantly advanced the detection of location, estimation of the coverage area and biomass, and prediction of the drift trajectories for *Ulva prolifera* green tides. Furthermore, the integrating of optical remote sensing indices with oceanographic dynamic parameters and environmental variables has yielded valuable insights into the spatiotemporal characteristics of green tides (Son et al., 2015; Jin et al., 2018; Wang et al., 2023a; Li et al., 2022). However, the dynamic nature of the marine environment often results in clouds and fog obstructing observations, making it challenging to obtain valid data. Fortunately, synthetic aperture radar (SAR), with its ability to penetrate clouds and fog and operate in all-weather, day-and-night conditions, has proven invaluable in overcoming these challenges (Cui et al., 2018; Gao et al., 2022; Li et al., 2023, 2024). For example, Li et al. (2023) effectively utilized Sentinel-1 SAR data to monitor the spatial distribution of *Ulva prolifera*, demonstrating its robustness in capturing key

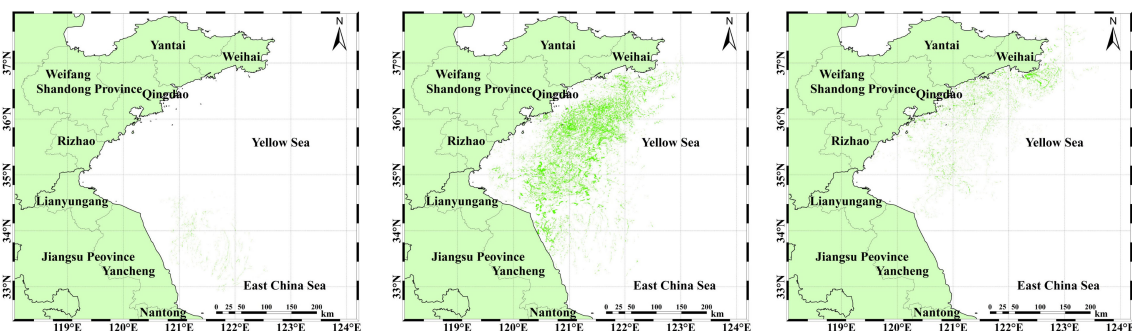


FIGURE 3
Distribution of *Ulva prolifera* detected using Sentinel-1 from May to July 2019. From Left to right: May, June, and July. Green areas indicate the distribution of *Ulva prolifera*.

TABLE 1 Overview of remote sensing data, resolutions, and methods for *Ulva prolifera* green tide monitoring.

| Author | Study area | Sensor | Spatial Resolution | Index | Method |
|----------------------------|--------------------------------|---|--------------------------------------|-------------------------|--|
| (Lou et al., 2006) | Zhejiang Coast East China Sea | MODIS | 500 m | FRGB | Visual Interpretation |
| (Nezlin et al., 2007) | Upper Newport Bay | Aerial photography, field measurements | 25 cm | Spectral signatures | Spectral Angle Mapper |
| (Hu and He, 2008) | Qingdao | MODIS | 250 m | NDVI | Visual Interpretation |
| (Liu et al., 2009) | north-eastern coast of China | MODIS | – | RGB, NDVI | Visual Interpretation |
| (Shi and Wang, 2009) | Yellow Sea | MODIS | – | NDAI | Histogram threshold |
| (Hu et al., 2010) | Yellow Sea and East China Sea | MODIS, Landsat | 30 m, 250 m | FAI | Visual Interpretation and set threshold |
| (van der Wal et al., 2010) | Netherlands and United Kingdom | MODIS, <i>In situ</i> | 250 m | NDVI | Fix threshold |
| (Casal et al., 2011) | NW Galicia, Spain | CHRIS-PROBA, Field survey | 17 m | Band3/5/7/9-11/12/14-17 | ML, Spectral Angle Mapper |
| (Xing et al., 2011) | Yellow Sea and East China Sea | MODIS, Landsat | 500 m, 30 m | NDVI | Dynamic threshold |
| (Keesing et al., 2011) | Yellow Sea | MODIS | 250 m | NDVI, SAI | Statistical analysis and set threshold |
| (Son et al., 2012) | Yellow Sea and East China Sea | GOCI, <i>In situ</i> | 500 m | NDVI, EVI | Fix threshold |
| (Garcia et al., 2013) | Yellow Sea | MODIS | 250 m | SAI, NDVI, FAI | Global threshold |
| (Zhang et al., 2013) | Yellow Sea | HJ-1A/1B, field survey | 30 m | FRGB | – |
| (Hu et al., 2015) | Gulf of Mexico, Bermuda | MODIS, Landsat, WorldView-2, HICO, AVIRIS | 250-1000 m, 30 m, 2 m, 90 m, 8-15 m | NDVI, FAI | Visual inspection and interpretation, set threshold |
| (Liu et al., 2015) | Yellow Sea | MODIS | 250 m | NDVI | Fix threshold |
| (Son et al., 2015) | Yellow Sea and East Coast Sea | GOCI | 500 m | NDVI, IGAG | Fix threshold |
| (Xing et al., 2015) | Yellow Sea | MODIS, SeaWiFS | 9.2 km | NDVI | Statistical analysis |
| (Qi et al., 2016) | Western Yellow Sea | MODIS | 250 m | FAI | Fix threshold, Linear mixing method |
| (Xing and Hu, 2016) | Yellow Sea and East Coast Sea | Landsat, HJ-1, Field data | 30 m | NDVI, EVI, FAI, VB-FAI | Visual inspection and interpretation, Statistic analysis |
| (Xu et al., 2016) | Yellow Sea | MODIS, Landsat, HJ-1, ENVISAT, CCD | | NDVI, NRCS | Otsu threshold |
| (Wang and Hu, 2016) | Central West Atlantic | MODIS | 1 km, 4 km | AFAI | Global threshold |
| (Hu et al., 2017) | Yellow Sea | MODIS, field-measured | 250 m | FAI | Set threshold |
| (Wang and Hu, 2017) | Caribbean Sea | MODIS | 1 km | AFAI | Statistic threshold |
| (Qi et al., 2017) | East China Sea | MODIS, VIIRS, GOCI, Landsat-8 | 1 km, 0.75 km, 0.5 km, and 30 m | AFAI | Statistical analysis |
| (Xiao et al., 2017) | Yellow Sea | MODIS, HJ-1B | 500 m, 30m | NDVI | Statistic threshold, Spectral unmixing |
| (Xu et al., 2017) | South Yellow Sea | MODIS, HJ-1, UAV, Field Observations | 250 m, 30 m, 12 cm | NDVI, RGB | Set threshold |
| (Cui et al., 2018) | Yellow Sea | MODIS, GOCI, HJ-1, GF-2, airborne SAR | 250 m and 1km, 500 m, 30 m, 4 m, 3 m | NDVI, DVI | Statistic threshold |

(Continued)

TABLE 1 Continued

| Author | Study area | Sensor | Spatial Resolution | Index | Method |
|----------------------------------|---|---|--|---|---|
| (Harun-Al-Rashid and Yang, 2018) | Eastern Yellow Sea | Landsat-8 | 30 m | NDVI, FAI | Fix threshold |
| (Jin et al., 2018) | Southern Yellow Sea | GOCI, Landsat | 500 m, 30 m | AFAI | Fix threshold |
| (Li et al., 2018) | Yellow Sea | HJ-1, GF-1 | 30 m, 16 m | NDVI, DVI, VB-FAH | Linear mixing reflectance spectra |
| (Qiu et al., 2018) | Yellow Sea | GOCI | 500 m | NDVI, AFAI | Machine learning |
| (Sun et al., 2018) | Southern Yellow Sea | HJ-1, MODIS, GOCI | 30 m, 250 m, 500 m | NDVI | Visual interpretation, Set threshold |
| (Wang et al., 2018) | Yellow Sea | Radarsat-2 | 5 m | PDP | Statistical analysis |
| (Xing et al., 2018) | Yellow Sea | MODIS, GF, CBERS | 16 m, 30 m, 250 m | DVI | Dynamic threshold |
| (Cao et al., 2019) | Yellow Sea | MODIS | 30 m | NDVI | Fix threshold |
| (Chen et al., 2019) | Southern Yellow Sea | GF-2, <i>in-situ</i> spectral data | 4 m | NDVI | Fix threshold |
| (Kim et al., 2019) | Yellow Sea, East China Sea | MODIS, GOCI, Landsat | 1 km, 500 m, 30 m | NDVI | Fix threshold |
| (Li et al., 2019) | The easternmost end of the Shandong Peninsula | MODIS, GF-1 | 16 m, 250 m | NDVI | Visual interpretation and set threshold |
| (Wang et al., 2019) | Yellow Sea | MODIS, Sentinel-2 | 500 m, 10 m | NDVI, RVI, DVI, FAI | GMM fuzzy classification and improved D-S evidence theory |
| (Xing et al., 2019) | Yellow Sea | Sentinel-2, GF-1, Landsat, MODIS, UAV, Spectro-radiometer | 10 m, 16 m, 30 m, 250 m, 10 m, less than 25 cm | DVI | Fix threshold |
| (Jiang et al., 2020a) | South Yellow Sea | UAV | 0.09-0.15 m | EXG, NGBDI, NGRDI, RGB_FAI, RGBVI, VDVI | Histogram threshold |
| (Kim et al., 2020) | Yellow Sea, East China Sea | GF-1 | 16 m | RGB | Deep learning |
| (Kim et al., 2020) | Jeju coast of Korea | UAV | 4.86 cm | RGB | ML, MHD, MID, ANN |
| (Li et al., 2020) | Yellow Sea | MODIS, GF-1, UAV | 250 m, 16 m, - | NDVI | Dynamic threshold |
| (Zhang et al., 2020a) | Southern Yellow Sea | MODIS, HJ-1A/B | 250 m, 30 m | NDVI | Visual interpretation and fixing threshold |
| (Zheng et al., 2020) | Yellow Sea | MODIS, GOGI, Sentinel-3, Landsat8, GF-1 | 1000 m, 500 m, 300 m, 30 m, 16 m | RVI, NDVI, EVI, FAI, other indices. | Semi-automatic threshold |
| (Li et al., 2021) | Yellow Sea | Sentinel-2, Landsat, MODIS | 10 m, 30 m, 250 m | NDVI | Gray-level thresholding |
| (An et al., 2021) | Yellow Sea | MODIS, HJ-1A/1B, GF-1, and Sentinel-2 | 250 m, 30 m, 16 m, and 10 m | DVI | Dynamic threshold |
| (Qi and Hu, 2021) | Yellow Sea and East China Sea | Sentinel-2/3, Laboratory and field data | 10 m, 300 m | AFAI | Statistical analysis |
| (Sun et al., 2021) | South Yellow Sea | Landsat | 15 m | FAI, other indices | Statistic threshold |
| (Wan et al., 2021) | Yellow Sea | GOGI | 500 m | RGB | Deep learning |
| (Wang et al., 2021b) | Yellow Sea | MODIS, Sentinel-1 | 250 m, 10 m | NDVI | Deep learning |
| (Zhang et al., 2021) | Southern Yellow Sea | Landsat-8, Sentinel-2 | 30 m, 10 m | NDVI | Adaptive threshold |
| (Chen et al., 2022) | Gouqi Island | UAV | 5.8 cm | NDVI, RVI, EVI, other indices | Machine learning (RF, GBDT) |

(Continued)

TABLE 1 Continued

| Author | Study area | Sensor | Spatial Resolution | Index | Method |
|-----------------------|--|--|---|---|--|
| (Gao et al., 2022) | Yellow Sea | MODIS, Sentinel-1, GF-3, Ship Survey Data | 250 m, 10 m, 10 m | RGB, VV+VH, HH+VH | Deep learning |
| (Guo et al., 2022) | Yellow Sea | Sentinel-1 | 10 m | | Deep learning |
| (Li et al., 2022) | Yellow Sea | Sentinel-2, Landsat, MODIS, UVA, ship data | 10 m, 30 m, 10 m, -, - | NDVI | Adaptive threshold |
| (Ma et al., 2022) | Yellow Sea | Sentinel-1, MODIS | 10 m, 250 m | DVI | Visual interpretation and threshold |
| (Qi et al., 2022) | Yellow Sea, East Coast Sea, Atlantic Ocean | Sentinel-1/2 | 10 m | FRGB, VV, AFAI | Deep learning |
| (Yuan, 2022) | Western Yellow Sea | MODIS | 250 m | DVI | Fix threshold |
| (Zhang et al., 2022) | South Yellow Sea | MODIS | 250 m and 500 m | NDVI | Visual interpretation and set threshold |
| (Cui et al., 2023) | Yellow Sea | GOCI | 500 m | NDVI | Fix threshold and machine learning |
| (Ji et al., 2023) | Western Yellow Sea | Landsat, Sentinel-2 | 30 m, 10 m | NDVI | Global threshold, histogram threshold, Maximum cross-correlation |
| (Li et al., 2023) | Southern Yellow Sea | Sentinel1/3, NPP | 10 m/300 m/375 m | NRCS, NDVI | Visual interpretation and set threshold |
| (Men et al., 2023) | Yellow Sea | GF-1, MODIS | 16 m, 250 m | NDVI | Machine learning (a linear regression model) |
| (Pan et al., 2023) | Yellow Sea | GF-1/4, Landsat, MODIS | 16/50 m, 30 m, 250 m | NDVI | Context-sensitive level set |
| (Qi et al., 2023) | Yellow Sea | MODIS, Sentinel-2 | 250 m, 10 m | AFAI | Fix threshold |
| (Shang et al., 2023) | Yellow Sea | PlanetScope Super Dove images, UAV | 3 m, 12.4 megapixels | RGB | Deep learning (VGGUnet) |
| (Wang et al., 2023a) | Yellow Sea | MODIS | 250 m | Band1, NDVI, Band2 | Deep learning (LSTM) |
| (Wang et al., 2023b) | Yellow Sea | GF-1, HY-1, Sentinel-2 | 16 m, 50 m, 10m | DVI | Statistic threshold |
| (Xing et al., 2023) | Bohai Sea | UAV, GF-1, Landsat | 0.10-0.17 m, 16 m, 30 m | RGB | Deep learning(U-Net) |
| (Xu et al., 2023) | Yellow Sea | GF-1, Landsat, HJ-1, MODIS | 16 m, 30 m, 50 m, 250 m | NDVI | Statistic threshold |
| (Yu et al., 2023) | East China Sea | Sentinel-2, GF-1 | 10 m, 16 m | DVI, Blue-Green, SUI-I | Machine learning (RF) |
| (Liu et al., 2024) | Yellow Sea, East China Sea, and northern Vietnam | GF-1 | 16 m | RGB, Red tide detection index, Pseudo hue angle | Deep learning |
| (Zhang et al., 2024a) | Yellow Sea | HY-1C/D, GF-1, HJ-1A/B, Sentinel2, COCI | 50 m, 16 m, 30 m, 10 m, 250 m | TCG | Adaptive thresholding |
| (Zhan et al., 2024) | Yellow Sea | HY-1, MODIS, GF-1/3/6, RADARSAT-2 | 16 m and 50 m, 250 m, 16 m and 10 m, 25 m | NDVI | Maximum inter-class variance |
| (Hou et al., 2024) | South Yellow Sea | GOCI I/II | 250 m/500 m | ACI, NDVI | Machine learning |
| (Zhang et al., 2024b) | Northwest Yellow Sea | GOCI, MODIS, in Situ | 500 m, - | AFAI | Machine learning |
| (Wei and Wang, 2024) | Gulf of Mexico and Yellow Sea | MODIS, Landsat | 500 m, 30 m | AFAI, FRGB, REA | Statistic threshold |

morphological features, even under adverse weather conditions. Moreover, SAR's sensitivity to variations in surface roughness allows for the identification of floating algal blooms by differentiating them from surrounding water surfaces and other floating objects (Qi et al., 2022). In addition, SAR has been employed in biomass estimation and spatiotemporal tracking of green tides. By integrating SAR-derived backscatter metrics with auxiliary environmental data, researchers have developed models to estimate algal density and monitor its drift trajectories under varying oceanographic conditions (Guo et al., 2022; Li et al., 2023).

Given its wide coverage and strong monitoring capability, remote sensing has become a vital tool for studying the dynamics of large-scale *Ulva prolifera* green tide blooms. However, the accuracy of remote sensing monitoring and green tides assessments is influenced by the spatial and temporal resolution of various remote sensing data sources. For example, low-resolution satellite imagery (particularly within the range of 100–1000 m) tends to overestimate the coverage area of large algal blooms, often missing smaller patches in affected areas (Wang et al., 2021a). This overestimation occurs because pixels containing algae are often mixed, including background water information, as highlighted by Hu et al. (2019) and Qi et al. (2019). To address this issue, linear spectral unmixing techniques have been employed to decompose mixed pixels, thereby improving the accuracy of algal coverage and biomass estimates (Hu et al., 2023). Moreover, image compositing methods, which integrate individual images or average monthly observations, have been shown to further enhance the accuracy of coverage assessments (Qi et al., 2016).

The effectiveness of green tide detection methods depends heavily on the algorithm employed, as certain approaches inherently introduce biases and limitations that can impact the accuracy and reliability of the results. For example, manual visual interpretation, fixed thresholding, or adaptive threshold for threshold selection remains a common practice in green tide monitoring. However, these methods are often unstable due to varying observational conditions (Cui et al., 2023; Tang et al., 2023). In contrast, machine learning and deep learning models have demonstrated greater capability, accuracy, and efficiency in detecting and analyzing *Ulva prolifera* green tides. Nevertheless, their application faces several challenges, such as the need for large, high-quality training datasets, and the issue of limited interpretability (Zhu et al., 2017). Compounding these challenges, the dynamics of *Ulva prolifera* green tide blooms are influenced by a range of environmental factors, which make large-scale monitoring even more complex. For example, several studies have reported that the highest *Ulva prolifera* green tide coverage occurred in 2021, which was several times greater than that in 2019 (Li et al., 2022; Zheng et al., 2022a). In contrast, another study indicated that the coverage of *Ulva prolifera* green tide peaked in 2019 (Qi et al., 2022). These discrepancies underscore the inconsistencies arising from differences in sensors, methodologies, and environmental conditions, which collectively complicate the detection and estimation of *Ulva prolifera* green tide blooms.

In summary, significant progress has been achieved in remote sensing-based monitoring of *Ulva prolifera* green tides. However, several critical challenges remain, including the influence of data

resolution on area and biomass estimations, biases introduced by algorithmic selections, and inconsistencies in monitoring results caused by sensors and environmental conditions variations. Therefore, it is essential to systematically review the progress in this field, summarize the strengths and limitations of existing approaches and explore future research directions. By providing a comprehensive overview of recent developments, key techniques, and applications related to *Ulva prolifera* green tides, this study offers valuable insights to advance research and proposes feasible strategies to address current scientific challenges. This work serves as a valuable resource for researchers in remote sensing, marine ecology, and environmental science. Furthermore, it offers guidance for practitioners involved in coastal management and algal bloom prevention, as well as for policymakers and government administrators.

2 Development and current status

This study focuses on the field of remote sensing monitoring of *Ulva prolifera* green tide blooms. A literature search was performed using the keywords “*Ulva prolifera* and remote sensing” and “green tides and remote sensing” in the Web of Science, yielding 153 relevant publications from 2009 to 2024. A visual analysis of these publications was conducted using the CiteSpace bibliometric analysis tool, revealing the developmental trajectory and current state of research in the remote sensing monitoring of *Ulva prolifera* green tide blooms.

The temporal variation in publication numbers reflects the growing interest in *Ulva prolifera* green tide monitoring, underscoring its increasing importance in the scientific community. Between 2009 and 2017, the number of relevant articles remained relatively low, with no publications in 2012. However, since 2017, the volume of publications has steadily increased, peaking in 2023 with 26 articles. These publications were distributed across 60 journals, with *Remote Sensing* leading with 19 articles, followed by *Marine Pollution Bulletin* with 12, and *Marine Environmental Research* with 7, among others. This upward trend in publication volume indicates that remote sensing-based monitoring of green tides has become a prominent research focus, in line with the latest scientific developments, as shown in Figures 4, 5.

Further analysis of the author collaboration network, using CiteSpace, identifies several prominent research groups, with two central clusters led by Hu Chuanmin and Xing Qianguo. This finding indicates a growing trend toward collaborative research in the field of *Ulva prolifera* green tide monitoring, as shown in Figure 6. In addition, the research institution collaboration network underscores the remarkable contributions of institutions such as the Chinese Academy of Sciences, Ocean University of China, and Yantai Institute of Coastal Zone Research, all of which play key roles in advancing this area of study, as illustrated in Figure 7.

Figure 8 presents the keyword co-occurrence network analysis, highlights the frequently used keyword terms such as *Ulva prolifera*, green tide, Yellow Sea, East China Sea, remote sensing, biomass, and area estimation. Research on *Ulva prolifera* green tides focuses on topics such as growth, expansion, bloom events, dynamics,

interannual variability, growth rates, biomass, area estimation, and prediction modeling, with a strong emphasis on applications of remote sensing technologies. Notably, this study specifically centers on the Yellow Sea and East China Sea regions, which serve as key areas for understanding the dynamics and impacts of *Ulva prolifera* green tides.

3 Overview of data sources

The remote sensing monitoring of *Ulva prolifera* green tide primarily relies on satellite, aerial, and unmanned aerial vehicle (UAV) technologies, as listed in Table 1. Each platform offers advantages and limitations in monitoring green tides, as summarized in Table 2. Satellite remote sensing technology is highly effective for large-scale, long-term observations, extensive coverage and regular revisit capabilities. However, their spatial resolution and ability to detect smaller patches of green tides are insufficient compared to aerial remote sensing. In addition, *in-situ* measurements and oceanographic environmental data, such as sea surface temperature (SST), sea surface wind (SSW), sea surface salinity (SSS), rainfall, ocean currents, and solar radiation, are used to calibrate and validate remote sensing data.

3.1 Remote sensing data

3.1.1 Satellite remote sensing data

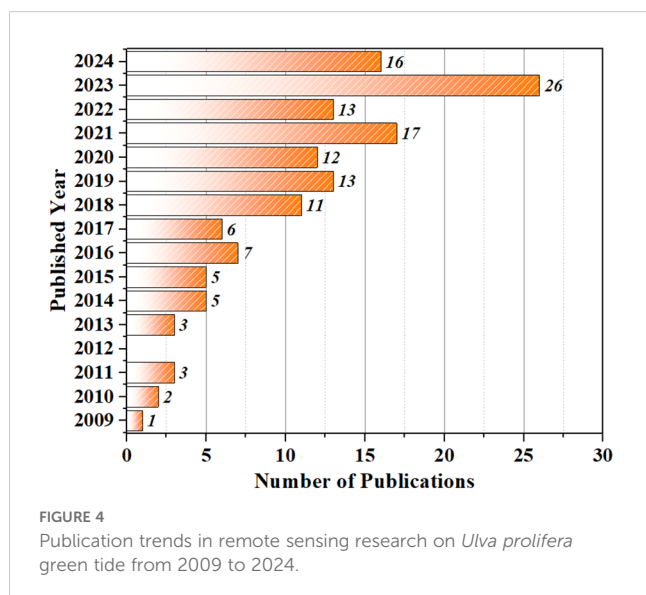
MODIS (TERRA/AQUA) has been providing data from 36 bands with spatial resolutions of 250 m, 500 m, and 1 km capturing observations twice daily since 2002, making it a widely used tool for long-term monitoring of algal blooms (An et al., 2022; Men et al., 2023; Qi et al., 2023). Similarly, GOCI I/II, with its capability for high-frequency observations at 1-hour intervals and spatial resolution of 250 and 500 m, is particularly well-suited for real-time monitoring of algal bloom dynamics, distribution, and drift of

Ulva prolifera green tides (Gu et al., 2011; Son et al., 2012). The first application of MODIS data for green tide research was conducted by Hu and He (2008), who studied the origin, nearshore distribution, and temporal variations of floating algae during the 2008 Beijing Olympic sailing competitions (Hu and He, 2008). High-resolution satellites, such as Landsat-3/5/7/8/9, Sentinel-2/3, GF-1/2, and HY-1A/B/C/D/E, provide high spatial resolution and they can effectively complement the limitations of MODIS and GOCI I/II in monitoring green tides over wide areas (Xu et al., 2016). However, optical remote sensing remains vulnerable to disruptions caused by cloud cover, fog, and rainfall, which often hinder data acquisition in real-world scenarios. To address the limitation, synthetic aperture radar (SAR) satellites, such as ASAR, ENVISAT, Sentinel-1, and Radarsat-1/2, have been employed (Xu et al., 2016; Qi et al., 2022). These synthetic aperture radar (SAR) satellites offer all-weather, day-and-night observation capabilities, enabling continuous and reliable monitoring of the spatial distribution and movement patterns of green tides (Wang et al., 2018; Li et al., 2023). Given the advantages and limitations of optical and SAR remote sensing, a growing trend in *Ulva prolifera* green tide research is the integration of multi-sensor imagery to achieve a comprehensive understanding of the spatial distribution, temporal variation, and movement patterns of green tides, while mitigating the inherent limitations of each data source (Hu et al., 2015; Xu et al., 2016).

Additionally, SST and SSW derived from passive microwave sensors play a critical role in the development of green tides, influencing their germination, growth rates, movement direction, and spatial distribution (Zhan et al., 2024). A review of the literature indicates that SSW data are primarily obtained from microwave scatterometers such as ASCAT and QuikSCAT, which provide a spatial resolution of 0.25°. In contrast, SST data are commonly retrieved from MODIS and NOAA sensors, offering higher spatial resolutions of 0.1° and 0.25°, respectively.

3.1.2 Aerial remote sensing data

In general, aerial remote sensing, including UAV and manned aircraft, provides higher resolution than satellite remote sensing, often achieving the centimeter level or even finer. This high resolution enables the capture of detailed information about *Ulva prolifera* green tides, particularly in nearshore and shallow water areas, where small-scale green tides can be effectively identified (Xing et al., 2011; Kim et al., 2020; Li et al., 2020; Xing et al., 2023). For example, Li et al. (2020) investigated the northernmost drift location of green tides in the Yellow Sea. Although satellite imagery had suggested that no green tides had reached the Shidao Island area, UAV imagery revealed small nearshore patches, indicating that green tides had already invaded local aquaculture zones. In addition, aerial remote sensing offers flexibility for conducting local flights within a short time frame, enabling the acquisition of real-time data without the limitation of satellite revisit cycles. Furthermore, it facilitates the customization of spectral bands (e.g., visible light, infrared, thermal imaging, and LiDAR) to address specific monitoring requirements, thereby making it highly adaptable to diverse applications (Rossiter et al., 2020; Chen et al., 2023; Shang et al., 2023; Xing et al., 2023). For



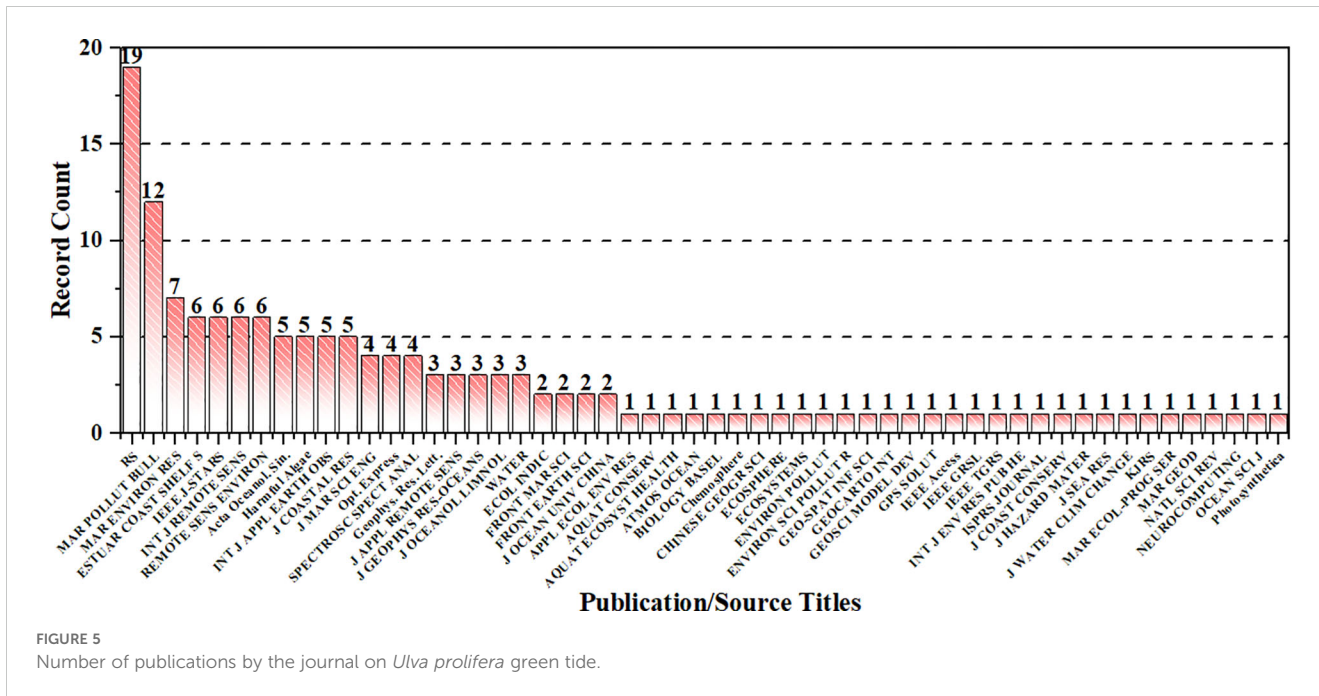


FIGURE 5 Number of publications by the journal on *Ulva prolifera* green tide.

example, [Jiang et al. \(2020a\)](#) developed a new green tide index based on UAV images, which demonstrated superior extraction accuracy for green tides during the decay phase under hazy atmospheric conditions. Similarly, [Jiang et al. \(2020b\)](#) used UAV to detect and evaluate the initial biomass of green algae attached to aquaculture rafts in shallow waters of northern Jiangsu.

While these studies highlight the advantages of aerial remote sensing in algal monitoring—such as high spatiotemporal resolution, flexibility, mobility, and the capacity to carry diverse sensors—certain limitations, including restricted coverage and operational constraints, primarily position it as a tool or supporting and validating satellite remote sensing data.

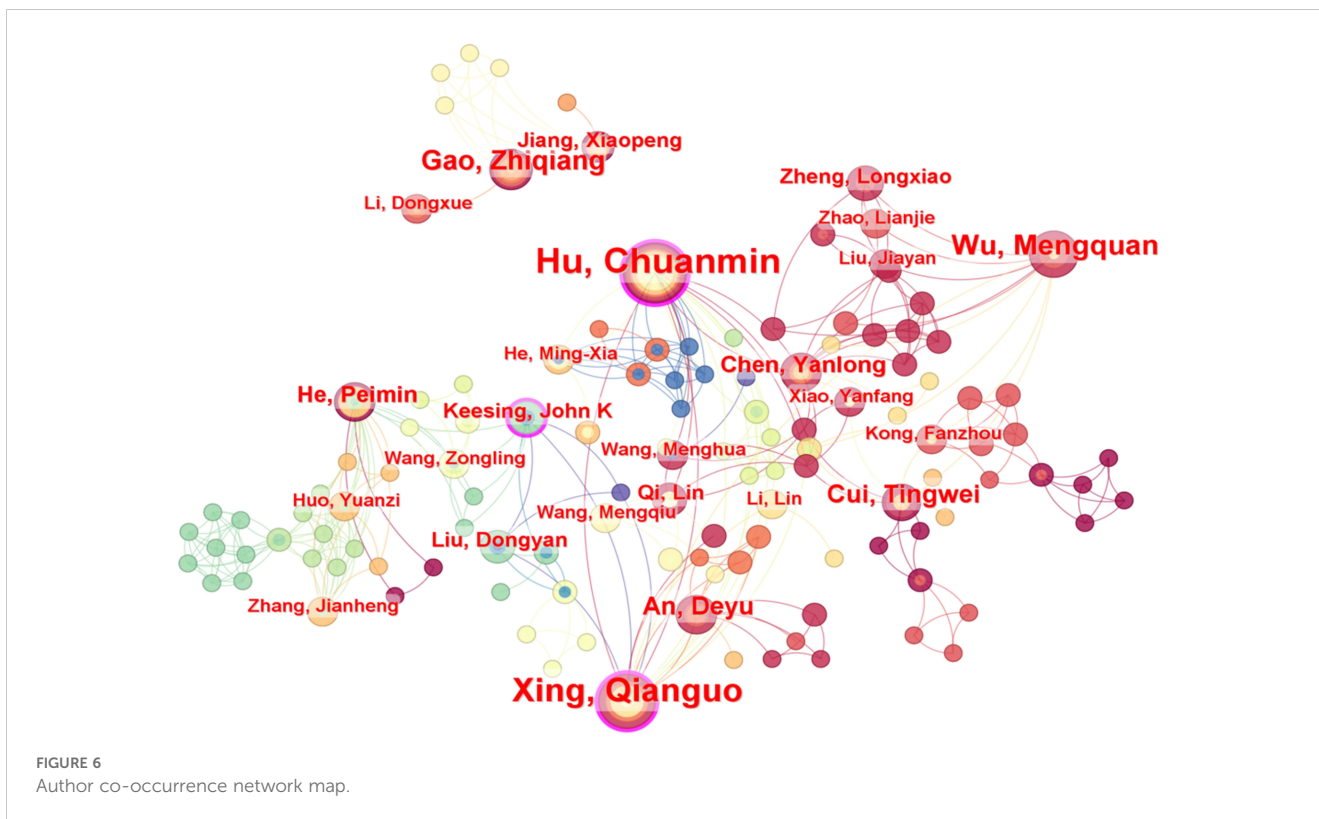


FIGURE 6 Author co-occurrence network map.

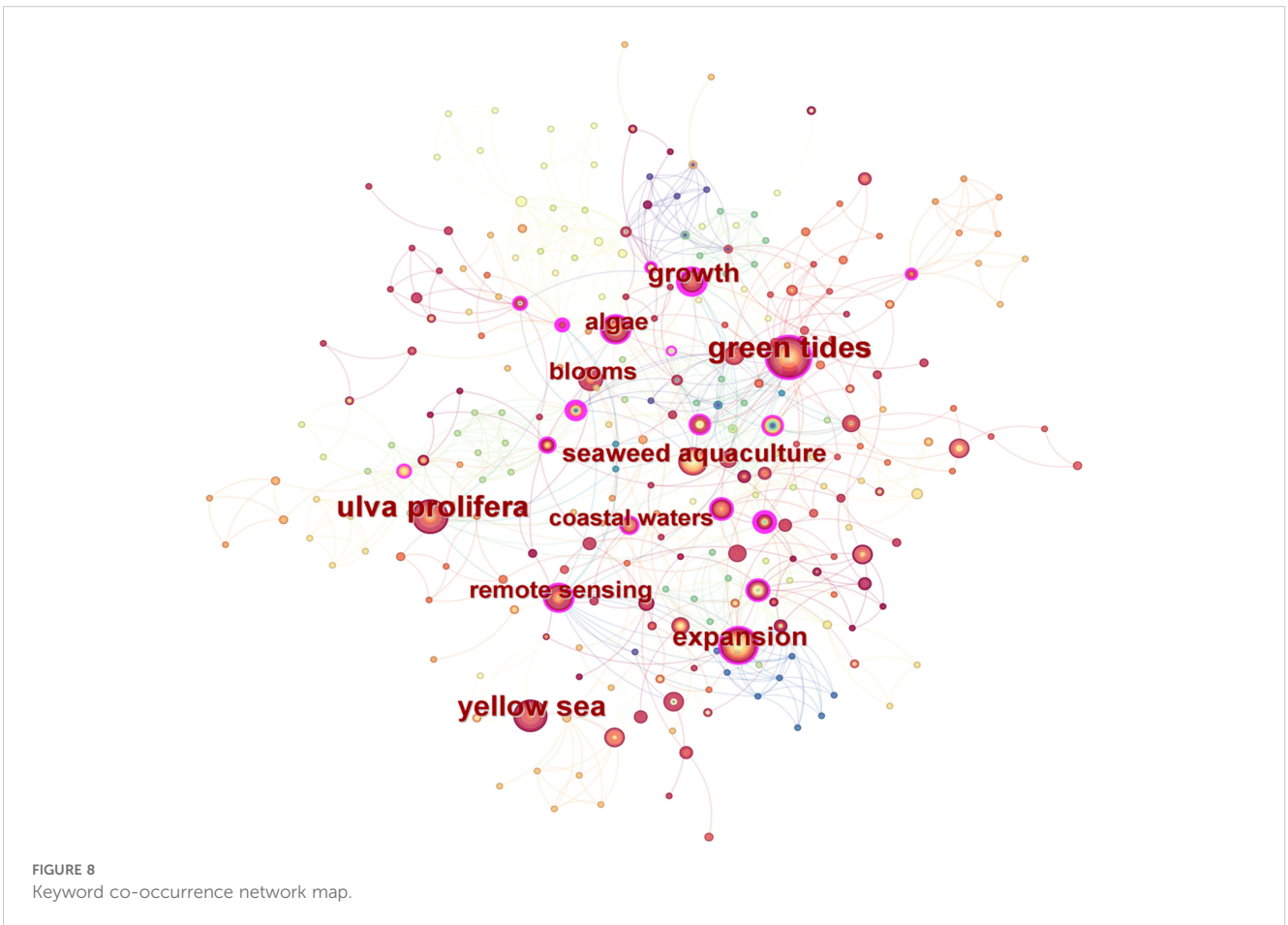
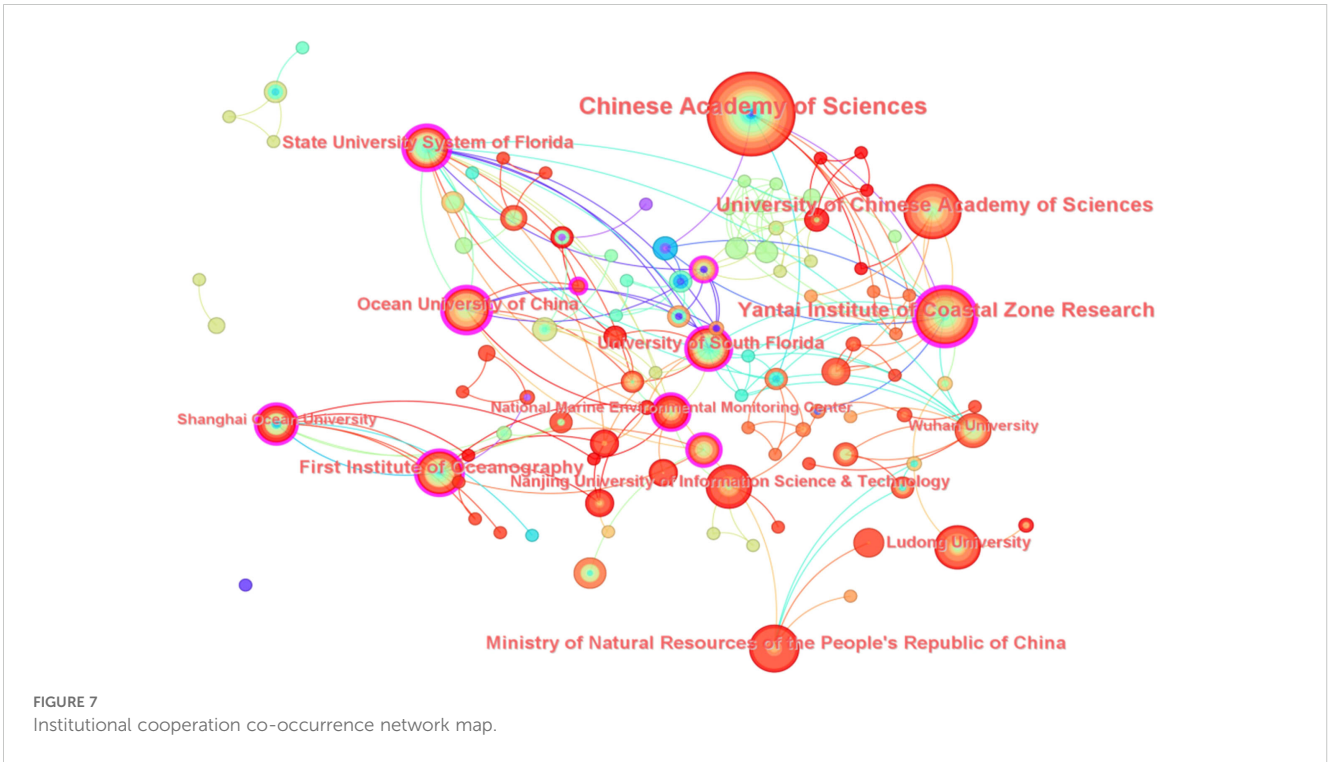


TABLE 2 Comparing the advantages and limitations of different platforms.

| Platforms | Advantages | Limitations |
|------------------------|---|---|
| Optical remote sensing | Large spatial and time coverage Long-term; High spatial and spectral resolution; Rich spectral information | Affected by weather and clouds; Limited nighttime acquisition capability; |
| SAR | All-weather and day-night capabilities; High spatial resolution; Rich polarimetric information | Speckle noise affects image quality; Complex interpretation; |
| Aerial remote sensing | Very high spatiotemporal; resolution, flexibility, mobility; Carry diverse sensors | Limited coverage; High costs; Dependent on battery life and weather conditions |
| <i>In-situ</i> | High-accuracy data; Provides multi-dimensional environmental information | Limited spatial coverage; Low sampling frequency and high costs limited coverage, time-consuming, and substantial costs |

3.2 *In situ* and auxiliary data

3.2.1 Field observations

Field Observation data offer high precision and resolution, making them crucial for the calibration and validation of remote sensing data, to ensure the accuracy of remote monitoring results (Hu et al., 2019; Xiao et al., 2019; Zhang et al., 2024b). On-site measurements, such as the biomass of green tides and environmental parameters (e.g., SST, SSS, and nutrient concentrations), provide essential calibration data for the validation of remote sensing observations (Zhang et al., 2024b). Laboratory or field measurements of the surface reflectance of mixed algae-water samples at various ratios can help establish the upper threshold values for pixel decomposition, which is critical for accurately estimating the coverage of green tides (Hu et al., 2017). Ground-based high-frequency multispectral cameras are used to measure spectral reflectance in the field, enabling the accurate identification and classification of different algae types, as well as the estimation of their coverage and health status (van der Wal et al., 2014). Additionally, data assimilation techniques allow ocean buoy data to be integrated with satellite remote sensing and historical data within ocean circulation models to simulate the drift paths of floating algae (Choi et al., 2023).

The calibration and validation of remote sensing data using field observation data play an essential role in ensuring the accuracy and reliability of remote sensing results. However, despite the high precision and resolution of these observations, their application in large-scale monitoring faces several challenges, such as limited coverage, time-consuming, and substantial costs. Therefore, to achieve effective monitoring of the occurrence, development, and temporal dynamics of *Ulva prolifera* green tides over large spatial and long temporal scales, it remains essential to integrate satellite and aerial remote sensing technologies. This integration is crucial for improving the spatial and temporal accuracy of monitoring.

3.2.2 Oceanographic environmental parameters

Table 3 lists the commonly used oceanic environmental parameters, including SST, SSW, photosynthetically available

radiation (PAP), ocean currents, salinity, precipitation, chlorophyll concentration, and nutrient levels, which influence *Ulva prolifera* green tide growth, decay, and drift (Xu et al., 2016; Li et al., 2017; Jin et al., 2018; Li et al., 2022; Xiao et al., 2024). In addition to remote sensing data, SST and SSW are frequently obtained from datasets such as the ECMWF Reanalysis 5th Generation (ERA5) and the Hybrid Coordinate Ocean Model (HYCOM), with spatial resolutions ranging from 0.08° to 0.25° (Li et al., 2020, 2021; Zheng et al., 2022b). Table 3 also lists the spatial and temporal resolutions for other oceanic environmental parameters (Li et al., 2021, 2022; Xue et al., 2023; Hou et al., 2024). Although existing oceanic physical, ecological, and other environmental data typically have much lower spatial resolution than remote sensing data, studies have not identified significant discrepancies in the large-scale spatiotemporal distribution, biomass estimation, driving factor analysis, or drift trajectory of green tides when using data from different models.

4 Remote sensing research on *Ulva prolifera* green tide

Researchers have developed several remote sensing methods for monitoring *Ulva prolifera* green tides, focusing on detecting their spatial distribution and estimating their biomass and coverage area. As shown in the *Ulva prolifera* green tide distribution map from May to July 2019 in Figure 8. Additionally, studies have extended to analyzing the spatial and temporal distribution patterns of green tides, integrating environmental factor analysis to understand the conditions driving their growth. Furthermore, predictive models have been applied to track the drift trajectories of green tides, enhancing understanding of their movement and spread (Li et al., 2014; Wang et al., 2015). These approaches include band indices, thresholding segmentation, machine learning, and deep learning methods. Among these methods, while deep learning approaches are currently the most widely used, several challenges remain, such as lack of interpretability and significant computational resources required, with the detailed summary provided in Table 4.

TABLE 3 Potential driving factors of *Ulva prolifera* green tides.

| Data | Dataset name | Spatial Resolution | Time Resolution |
|-----------------------------|--|--------------------|----------------------------|
| SSW | QuickScat | 0.25° | 3-Day/Weekly/Monthly |
| | ASCAT | 0.25° | Daily/3-Day/Weekly/Monthly |
| | WindSat | 0.25°C | Daily/Monthly |
| | ECMWF | 0.125° | 3 h |
| | Windspeed | 0.25°C | Daily |
| SST | MODIS | 0.1° | – |
| | NOAA CDR OISST | 0.25° | Daily |
| | ERA5 | 0.25° | Hourly |
| | HYCOM | 0.08° | 3h/Daily |
| SSS | HYCOM | 0.08° | 3h/Daily |
| | WindSat | 0.25°C | Daily/Monthly |
| PAR | MODIS-Aqua v2018.0 | 0.1° | Daily |
| | Himawari-8 | 0.05°C | Hourly |
| Water depths | GEBCO | 1 km | – |
| Chlorophyll-a concentration | GOCI | 500 m | Hourly |
| | MODIS | 4 km or 9 km | Daily/Monthly |
| Precipitation | GPM | 0.1°C | Hourly |
| | ERA5 | 0.25° | Hourly |
| Ocean currents | HYCOM | 0.08° | 3h/Daily |
| | OSCAR_L4_OC_FINAL_V2.0, OSCAR_L4_OC_NRT_V2.0 | 0.25° | Daily |
| Nutrients data | GLOBAL_MULTIYEAR_BGC_001_029 | 0.25° | Daily |

4.1 Identification and extraction of *Ulva prolifera* green tides

4.1.1 Band indices for identification

Various remote sensing band indices, including NDVI, FAI, EVI, SAI, DVI, and RVI, have been commonly employed in monitoring *Ulva prolifera* green tides, as summarized in Table 1. The definitions for these indices are provided below in Equations (1) to (5). NDVI utilizes the reflectance difference between the NIR bands to identify floating algae. NDVI was first applied successfully to describe the origin and evolution of floating algae in the Yellow Sea during the 2008 Beijing Olympic Games (Hu and He, 2008). However, NDVI values are highly sensitive to environmental factors such as aerosols, solar/viewing geometry, and water turbidity, which may complicate its effectiveness in distinguishing floating algae from surrounding waters (Hu, 2009). For example, in clear water, the red and NIR bands absorb light, leading to low NDVI values, while suspended materials like sediments and Sargassum modify the reflectance characteristics, particularly in these bands. These variations reduced contrast between floating algae and surrounding water, complicating the quantitative analysis of NDVI values (Hu, 2009; Huang et al., 2021). Additionally, NDVI's reliance on the reflectance difference between red and NIR bands limits its ability to accurately reflect high biomass levels when algae concentration is

high. To address these limitations, alternative indices such as EVI and FAI have been developed. EVI improves upon NDVI by incorporating the blue band to reduce atmospheric aerosol and water interference, thereby enhancing the response to vegetation photosynthesis. This makes it more accurate when monitoring high concentrations of green tides and Sargassum (Xing et al., 2018; Zheng et al., 2020). RVI, as an adaptation of the EVI, utilizes the ratio of reflectance between the NIR and RED bands. This modification enhances its ability to identify and monitor the spatial distribution and spread of floating algae, such as Sargassum and green tides, particularly under variable environmental conditions (Wang et al., 2019; Zheng et al., 2020). FAI combines the RED, NIR, and short-wave infrared (SWIR) bands, greatly reducing the impact of sun glint or haze and improving its ability to distinguish algae from suspended matter (Xing et al., 2018; Zheng et al., 2020). Studies have shown that FAI is less sensitive to environmental and observational changes, making it more stable than NDVI and EVI (Hu, 2009). However, FAI does not offer an effective cloud masking method, which results in both clouds and Sargassum exhibiting high FAI values in images. To address this, a modified version of FAI, known as AFAI, was proposed, which uses different spectral bands (RED = 667 nm, NIR = 748 nm, SWIR = 869 nm) to improve accuracy (Wang and Hu, 2016). A major limitation of FAI is the unavailability of SWIR

TABLE 4 Comparing the advantages and limitations of green tide monitoring methods.

| Method | Advantages | Limitations |
|------------------------|---|--|
| Band indices | Simple and high computational efficiency; High interpretability | Dependence on environmental conditions; Lack of adaptability; Low accuracy |
| Threshold segmentation | Simple and high computational efficiency; Strong model interpretability | Sensitivity to threshold selection; Sensitivity to noise; Difficulty in integrating multi-source data; Lower accuracy |
| Machine learning | High computational efficiency; Model interpretability; Small sample advantage; Multi-source data integration | Dependence on feature selection; Inability to automatically learn features |
| Deep learning | Automated feature extraction; Nonlinear modeling capability; High accuracy | Data dependency; High computational cost; Lack of interpretability; Hyperparameter tuning |

bands on many satellite sensors, which necessitates the use of alternatives such as DVI. DVI is particularly sensitive in areas with low vegetation cover, making it suitable for early-stage and mid-stage algae detection (Li et al., 2018; Xing et al., 2018, 2019). In environments with highly variable atmospheric conditions, turbid waters, or sun glint effects, the Scaled Algae Index (SAI) has been proposed to improve the detection of floating algae. This index utilizes reflectance differences among the SWIR, NIR, and RED bands, reducing interference from water turbidity and other impurities, and thereby improving algae detection (Keesing et al., 2011). In addition, several other band indices, such as NDAI (Son et al., 2012), VB-FAH (Li et al., 2018), and VDVI (Visible-Band Difference Vegetation Index, VDVI) (Jiang et al., 2020a), have been developed based on the unique reflectance characteristics of algae.

$$NDVI = (R_{nir} - R_{red}) / (R_{nir} + R_{red}) \quad (1)$$

$$EVI = G \times (R_{nir} - R_{red}) / (R_{nir} + a \times R_{red} - b \times R_{blue} + c) \quad (2)$$

$$RVI = R_{nir} / R_{red} \quad (3)$$

$$FAI = (R_{nir} - R_{red}) + (R_{red} - R_{swir}) \times (\lambda_{nir} - \lambda_{green}) / (\lambda_{swir} - \lambda_{red}) \quad (4)$$

$$NDAI = \frac{[\rho_t(\lambda_{nir}) - \rho_r(\lambda_{nir})] - [\rho_t(\lambda_{red}) - \rho_r(\lambda_{red})]}{[\rho_t(\lambda_{nir}) - \rho_r(\lambda_{nir})] + [\rho_t(\lambda_{red}) - \rho_r(\lambda_{red})]} \quad (5)$$

where R_{nir} , R_{red} , R_{blue} are the reflectance values in the near-infrared, red, and blue bands, respectively. λ_i are the wavelength with the subscript band name. ρ_t represents the top-of-atmosphere reflectance, ρ_r represents the corresponding Rayleigh scattering reflectance. G is the gain factor, and a , b and c are pixel-independent coefficients to compensate for aerosol effects and vegetation background.

However, each of these band index methods has its strengths and limitations. In complex environments, where meteorological conditions, solar angles, and aerosol concentrations vary, cloud

cover or in waters with high suspended matter, relying on a single band index to detect high-accuracy green tide information across all stages and sensor types is difficult (Wang et al., 2019). Therefore, a combination of multiple band indices and approaches may be required for more effective monitoring of green tide dynamics.

4.1.2 Thresholding methods

The spectral differences between water and algae are commonly utilized to detect *Ulva prolifera* green tide information using various band indices at different resolutions. To effectively distinguish between water and algae, thresholding methods are frequently applied based on these band indices, such as fixed threshold, statistical threshold, global threshold, and dynamic threshold. A summary of these methods is presented in Table 1.

In earlier studies, adjusting and selecting appropriate thresholds through visual interpretation and statistical analysis was a relatively accurate approach (Shi and Wang, 2009). For the green tides in the Yellow Sea, the NDVI method commonly applies thresholds greater than -0.2 or 0 for algae, with water values being below 0 (Hu and He, 2008; Hu, 2009). Similarly, the EVI method uses thresholds above 0.02, and the FAI method typically adopts thresholds around 0.02, with water values generally being less than or equal to 0 (Hu, 2009). Through iterative visual inspection and calibration, Hu et al. (2010) refined the FAI lower threshold to a range between -0.001 and 0.001. While thresholding methods adjusted through interactive visual interpretation are accurate for monitoring targets with clear boundaries, they lack robustness under varying conditions, as threshold values often differ across scenarios, which limits their applicability across periods or regions (Hou et al., 2024). Son et al. (2012) conducted statistical analyses of NDVI, EVI, and IGAG values to determine optimal thresholds for extracting green tide pixels. They observed that the number of extracted pixels was highly sensitive to the selected threshold (Son et al., 2012). Although NDVI and EVI methods are effective when applied to both high-resolution and medium-to-low-resolution satellite data, their reliability diminishes in scenarios with low algae density or under complex conditions such as cloud cover, aerosol interference, or

water turbidity (Son et al., 2012). One solution involves removing the background water signal from the area of interest to normalize local algae indices. For example, in the NDAI method, algae pixel values are refined by subtracting the average value of surrounding non-algal pixels, resulting in a homogeneous background that enables the application of global thresholds to isolate floating algae pixels (Shi and Wang, 2009). However, global thresholds are prone to underestimation in scenes with highly variable backgrounds (Garcia et al., 2013). To address these limitations, Garcia et al. (2013) proposed the SAI algorithm, which scales the NDVI or FAI images by subtracting local ocean medians and then applies a scene-wide exclusion method to segment algae pixels. Additionally, dynamic thresholding methods have been developed to detect *Ulva prolifera* green tides under challenging conditions such as solar flares, thin clouds, or other interferences (Xing et al., 2018; An et al., 2021). Local adaptive thresholding methods further enhance performance by dynamically selecting thresholds within moving pixel windows based on satellite top-of-atmosphere reflectance data and canopy greenness indices. These methods have shown promising results in non-optimal observation conditions, including complex water backgrounds, sun glint, and cloud cover (Zhang et al., 2024b).

Although threshold-based classification algorithms are widely adopted for their practicality and simplicity in binary classification, they face significant challenges in adapting to dynamic marine environment conditions. Changes in illumination, seasonal variations, water depth, and turbidity can alter the reflection properties of green tides, reducing the effectiveness of these methods. Consequently, thresholding methods require frequent adjustments and struggle to differentiate fine-scale algae features under low-resolution conditions, leading to reduced robustness and adaptability (Hou et al., 2024).

4.1.3 Machine learning methods

Machine learning methods, including the Mahalanobis distance (MHD), maximum likelihood (ML), minimum distance (MD), support vector machine (SVM), and random forest (RF), have been widely applied in the remote sensing monitoring of *Ulva prolifera* green tides. These methods, along with their specific applications, are summarized in Table 1. Gu et al. (2011) demonstrated that decision tree models could effectively utilize spectral differences among *Sargassum*, seawater, and solar glint, reducing image noise caused by solar flares and extracting *Sargassum* information from imagery. Similarly, Casal et al. (2011) demonstrated that the ML method is highly effective in distinguishing algae pixels from non-algae pixels, with an accuracy exceeding 90% when validated against ground-truth samples. Among classification algorithms such as MHD, ML, MD, and artificial neural networks (ANN), ML and ANN achieved the highest accuracy in evaluating green tide areas from UAV remote sensing data (Kim et al., 2020). The multi-layer perceptron effectively addresses challenges such as clouds, aerosols, and solar flares under various environmental conditions better than traditional methods (Qiu et al., 2018). However, these supervised classification methods inevitably require human intervention for sample delineation and image interpretation, which is a time-consuming and labor-intensive

process. To address this, a method combining the Gaussian mixture model and an improved Dempster-Shafer evidence theory has been proposed to enable automatic detection of *Sargassum* distribution. This approach can automatically integrate NDVI, RVI, DVI, and FAI features to extract the distribution and coverage of *Sargassum* (Wang et al., 2019). Additionally, by applying advanced machine learning algorithms like RF and gradient boosting decision trees (GBDT), researchers assessed the biomass of various intertidal algae species, demonstrating that GBDT provides a more accurate biomass evaluation (Chen et al., 2022). High-resolution remote sensing data, with their fine spatial resolution, enable the detection of detailed green tide features, while low-resolution data, offering higher temporal resolution, support frequent monitoring of temporal changes. By integrating high- and low-resolution data, machine learning models can effectively analyze the appearance, evolution, and migration patterns of green tides (Men et al., 2023). As spatial resolution improves, the ability to distinguish different algae features is significantly enhanced. For example, the RF method, known for its strong robustness, has been demonstrated to efficiently monitor the spatial and temporal distribution of *Sargassum* and other algae (Yu et al., 2023). Additionally, a hybrid remote sensing model combining the RF algorithm with the optical algal cloud index has been shown to accurately distinguish between thin cloud boundaries and dense green tide areas, outperforming SVM and nearest neighbor methods (Hou et al., 2024).

Compared with traditional thresholding methods, machine learning approaches provide greater robustness and adaptability for detecting *Ulva prolifera* green tides under varying environmental conditions, such as changes in lighting, seasonality, water depth, and turbidity. These models can fully exploit spectral, spatial, and textural features, enabling automatic and efficient detection even with limited labeled samples. However, their performance heavily depends on manually designed feature extraction processes, requiring expert knowledge to select effective features such as color and texture, and inadequate or irrelevant feature selection can compromise the model's accuracy.

4.1.4 Deep learning methods

Artificial intelligence (AI) is a comprehensive research field encompassing various technologies and methodologies, with machine learning serving as a crucial approach for realizing AI, thus becoming a central component of the field. Deep learning, a subset of machine learning, employs deep neural networks for data modeling and feature extraction and has emerged as one of the most advanced technologies in recent years (Jordan and Mitchell, 2015). Unlike traditional methods such as threshold segmentation, SVM, and RF, which typically rely on manually designed features (e.g., color, texture, and shape) for green tide detection, deep learning models can automatically learn these features from raw data, significantly improving detection accuracy and adaptability. Additionally, deep learning not only utilizes the spectral information from individual pixels but also incorporates spatial relationships among these pixels, thereby achieving better feature extraction results (Qi et al., 2022). For example, Kim et al. (2020) compared the performance of MHD, ML, MD, and ANN for coastal

green tide monitoring and found that ML and ANN methods yielded the highest accuracy (Kim et al., 2020). Unlike traditional methods, which often struggle to distinguish algae from other marine objects with similar spectral features, deep learning networks can capture subtle differences among various target features, enabling more accurate differentiation (Kim et al., 2020). Moreover, deep learning methods can effectively consider the spectral information of each pixel and the spatial context among pixels, leading to a remarkable improvement in green tide detection accuracy compared to traditional approaches (Wan et al., 2021). Green tide outbreaks are often widely covered in the news, and a significant correlation is found between these events. Deep learning can leverage temporal and spatial features to model these correlations, enabling the detection of daily green tides and utilizing observed green tides to infer societal reactions (Wang et al., 2021b). Although deep learning is robust in green tide detection, it often requires large amounts of labeled data. However, in practice, pure samples are scarce, and background samples are often predominant, leading to class imbalance. These challenges can be addressed by optimizing the loss function to improve performance (Guo et al., 2022). Furthermore, by optimizing U-Net model, more accurate estimates of green tide coverage and biomass density can be extracted (Shang et al., 2023). Deep learning can also adapt to different illumination conditions and environmental factors when analyzing remote sensing images, allowing for the precise detection of green tides under varying conditions. In particular, mixed pixels in low-resolution images may hinder accurate biomass estimation, but deep learning can integrate pre-trained image super-resolution models to enhance the spatial resolution of satellite imagery and strengthen edge features, thereby minimizing the impact of mixed pixels (Liu et al., 2024).

Compared to machine learning, deep learning models can automatically select features, reducing the need for manual feature design. These models are also better at capturing complex patterns and features, demonstrating greater stability and robustness when confronted with diverse marine environments and conditions. However, there are certain limitations (Zhu et al., 2017). First, deep learning is highly dependent on labeled data, requiring a large quantity of high-quality labeled data for training. Inaccurate labeling or insufficient samples from diverse scenarios (such as varying lighting conditions or cloud cover) can significantly impair the model's generalization ability. Second, training deep learning models is computationally expensive, particularly when dealing with high-resolution remote-sensing images. Third, the black-box nature of deep learning models makes them less interpretable than traditional machine learning methods. This lack of interpretability poses challenges for decision-makers and environmental managers who need to understand why a model makes certain predictions. Furthermore, the complexity of deep learning models limits their explainability.

4.2 Estimation of green tide biomass

With the expansion of seaweed farming on the northern Jiangsu shallow shoals, *Sargassum* (green tide) shed or discarded during the

harvesting and dismantling of seaweed farming rafts has been identified as a major source of large-scale green tide outbreaks in the Yellow Sea (Liu et al., 2009; Keesing et al., 2011). To estimate the cumulative biomass of these outbreaks, Wang et al. (2015) developed a mathematical model that utilized initial biomass data from seaweed farming rafts, combined with floating and growth rates of green tides derived from field experiments. Expanding on this work, Liu et al. (2015) established 27 monitoring stations in regions with the most severe outbreaks and employed both remote sensing and field surveys during and after seaweed raft cleaning to estimate large-scale green tide biomass accurately. To improve biomass estimation, Hu et al. (2017) developed a remote sensing model based on reflectance-derived FAI, using biomass and reflectance data from laboratory experiments. Subsequently, this model was later extended to MODIS remote sensing imagery, enabling large-scale biomass estimation of green tides in the Yellow Sea (Hu et al., 2017). Furthermore, Hu et al. (2019) refined this approach by constructing an FAI gradient image to reduce the impact of suspended sediments, atmospheric turbidity, and sunlight on coverage estimation. They extracted algae-containing pixels and calibrated the relationship between coverage and biomass based on tank and field experiments (Hu et al., 2019). While effective, this method still faced challenges under extreme observational conditions, such as large viewing angles or high atmospheric turbidity (Hu et al., 2019). In addition to FAI, other indices have been explored for green tide biomass estimation. Xiao et al. (2019) demonstrated strong exponential relationships between biomass per unit area and indices such as EVI, NDVI, and FAI, with EVI being the least affected by mixed pixels. They further applied EVI to MODIS imagery to estimate the maximum green tide biomass in the Yellow Sea from 2007 to 2016. Similarly, Xing et al. (2018) utilized the DVI to develop linear regression models for surface coverage, enabling potential biomass estimation. Xu et al. (2023) adopted Gompertz and logistic growth models to fit cumulative coverage area data from 2008 to 2022, effectively tracking daily variations in green tide coverage.

Despite these advancements, most biomass assessments still rely on measurements of maximum algal coverage or manually removed biomass, often overlooking the significant growth potential of *Sargassum*. Under favorable conditions, daily biomass growth rates can exceed 25%, resulting in underestimations of green tide coverage (Xing et al., 2018; Yuan, 2022). To address this limitation, Yuan (2022) proposed a folding model to predict upstream algae growth and the potential maximum biomass of green tide outbreaks. This model incorporates both growth dynamics and cumulative coverage, providing a more accurate estimation of outbreak scales in the Yellow Sea.

4.3 Drivers of green tide growth and outbreak

Many researchers have investigated the factors driving the growth and outbreak of *Ulva prolifera* green tides, focusing particularly on the environmental and physical conditions influencing its proliferation and movement. Studies consistently

highlight that SSW plays a pivotal role in the movement and horizontal drift of floating algae. Xu et al. (2014) analyzed the impact of SST and SSW, finding that while SST was not a critical factor affecting the scale of algal bloom, SSW significantly influenced the movement and distribution of floating algae. Similarly, Li et al. (2020) analyzed the development, dissipation, and northward drift of green tides in Rongcheng from 2013 to 2018, concluding that SSW had the greatest impact on the occurrence and movement of *Ulva prolifera* green tide blooms. Furthermore, Zhang et al. (2022) tracked *Ulva prolifera* green tides using remote sensing from 2015 to 2019 and confirmed that SST provided necessary growth conditions, while SSW was the primary driver of horizontal drift, determining the distribution patterns of green tides. Environmental factors affecting green tide growth vary across its life cycle. Jin et al. (2018) found that during the initial phase, SST and available radiation were the primary factors influencing algal biomass; during the outbreak phase, water transparency, precipitation, and wind activity facilitated algal proliferation; and in the dissipation phase, SST, strong radiation, and human cleanup operations accelerated algal mortality. Adequate light conditions have also been identified as a crucial factor. Zhang et al. (2020a) observed that sufficient light during the growth period was a key driver of *Ulva prolifera* green tide outbreaks. Similarly, Cui et al. (2015) identified the optimal SST range for *Ulva prolifera* growth as 20°C to 27°C, a finding that was further corroborated by Nukapothula et al. (2022), who analyzed MODIS SST data. They found that algal blooms typically initiated when SST rose from 18°C to 25°C and that abundance declined when SST exceeded 25°C. These findings highlight the interconnected roles of nutrient availability and physical forcing in both the growth and dispersion of green tides.

In addition to physical conditions, nutrient availability significantly impacts green tide growth. Zhang et al. (2020a) emphasized that while suitable SST and sufficient light promote growth, these factors alone are insufficient under nutrient-poor conditions. High concentrations of nutrient salts, particularly phosphate, and balanced N/P/Si ratios are essential for sustaining rapid algal proliferation. Precipitation also plays a complex role in green tide dynamics. Li et al. (2021) noted that during the dissipation phase, SST was negatively correlated with green tide abundance, as higher temperatures accelerated dissipation. However, precipitation slowed this process, and typhoons could disrupt it. Zheng et al. (2022b) further revealed that moderate light conditions promoted growth and reproduction, while excessive ultraviolet radiation could inhibit algal proliferation.

Recent studies have expanded the understanding of green tide dynamics by integrating multiple environmental and water quality parameters. Hou et al. (2024) identified phosphate content, N/P/Si ratios, and water transparency as additional factors influencing the growth rate of *Ulva prolifera*. These findings underscore the importance of considering a combination of physical, chemical, and biological factors to fully understand the mechanisms driving green tide outbreaks.

4.4 *Ulva prolifera* green tide drift trajectory analysis and prediction

Recent advancements in remote sensing and modeling have significantly improved our ability to monitor and predict the drift trajectories of *Ulva prolifera* green tides. In early May, large algae originate from the turbid waters near the northern Shandong shoals of the Yellow Sea and begin to drift southward. However, as the East Asian summer monsoon strengthens, the primary drift direction shifts northward (Xing et al., 2011). The radial sand ridges in the northern Shandong shoals contribute to longitudinal and transverse ocean currents, with the longitudinal net movement serving as the primary driver for transporting green tides into nearshore waters (Bao et al., 2015). Various studies have confirmed the influence of ocean currents and wind fields on green tide dynamics. For example, Son et al. (2015) highlighted that typhoons and enhanced wind conditions significantly influenced the movement of floating algae patches. Liu et al. (2015) and Li et al. (2020) documented the northward drift of green tides from the coastal waters of Jiangsu Province in May, eventually reaching the southern coast of Shandong Province. Ma et al. (2022) used optical and microwave remote sensing data to monitor the movement of green tides in the Yellow Sea and the East China Sea in 2021, indicating a consistent northward trajectory passing through multiple coastal regions before gradually dissipating near Qingdao. Similar trends were observed using remote sensing at different spatial resolutions, where the overall drift direction of *Ulva prolifera* green tide was found to be northward (Wang et al., 2023a). Recent remote sensing studies indicate that the northward drift of *Ulva prolifera* is primarily driven by ocean currents and wind fields (Hou et al., 2024).

To predict green tide drift trajectories, researchers have combined remote sensing with different modeling methods, such as numerical models and ecosystem models (Hu et al., 2018). Xu et al. (2016) used a Lagrangian spill trajectory model to simulate the migration of floating algae in the Yellow Sea, achieving results consistent with satellite observations. Zhou et al. (2021) enhanced this approach by incorporating an ecological dynamic growth module into the Lagrangian model, enabling the prediction of spatiotemporal variations in large-scale green tide blooms. Despite the utility of Lagrangian models, limitations such as low spatial resolution in large-scale grids and instability in high-resolution settings have been noted (Sheng et al., 2023). To address these challenges, Sheng et al. (2023) developed a bidirectional feedback model that uses algae distribution data from remote sensing as the initial input. This model integrates drift, diffusion, and elimination mechanisms, demonstrating superior predictive performance compared to traditional methods. During the decay phase, green tide growth is closely linked to SST, PAR, and phosphate levels, while salinity and nitrate have minimal effects. Based on these findings, Yang et al. (2023) created a regression model using SST, PAR, and phosphate to predict green tide production rates during this phase.

The growth of *Ulva prolifera* green tide typically follows an S-shaped curve (Banks et al., 2017). Xu et al. (2023) analyzed daily coverage data of green tides in the Yellow Sea from 2008 to 2022 and applied Gompertz and logistic growth curves to model cumulative coverage over time. However, estimating green tide outbreaks solely based on cumulative or maximum coverage can lead to inaccuracies, as these metrics may not fully capture the outbreak scale or temporal dynamics (Yuan, 2022). Sheng et al. (2023) proposed a bidirectional feedback model for *Ulva prolifera* green tide drift, which uses the spatial distribution of algae extracted from remote sensing images as the initial model. Based on the drift and diffusion mechanisms of *Ulva prolifera* green tide, a bidirectional feedback model between algae elimination and driving modules was established, showing superior performance in predicting algae drift and dispersion compared with traditional methods. In cases where remote sensing data have long revisit cycles or limited spatial coverage, predictive challenges arise. To overcome these limitations, Wang et al. (2023b) proposed using Long Short-Term Memory Networks. This approach leverages spatiotemporal features from oceanic physical factors (e.g., SSW and ocean currents) and biological factors (e.g., SST, SSS, and solar radiation) to learn drift patterns. The model can accurately predict the geometric position of *Ulva prolifera* green tides within a seven-day window, offering a robust tool for short-term trajectory forecasting.

5 Challenges and opportunities in monitoring *Ulva prolifera* green tides

Despite significant advancements in understanding the outbreak areas, detection methods, spatiotemporal distribution characteristics, biomass estimation, driving factors, and drift trajectory prediction of the Yellow Sea green tide, several challenges remain unresolved. For example, there remains a persistent trade-off between high temporal and high spatial resolution in multi-source remote sensing data, and effective methods for integrating data from different platforms to fully exploit their complementary strengths are still lacking. Additionally, the estimation of green tide coverage and biomass is susceptible to variations in image quality, data sources, and algorithm selection, which increases the uncertainty of monitoring results. Although factors such as temperature, salinity, and light intensity have been identified as key drivers of green tides, the interactions among these factors and their relationship with the reproduction of *Ulva prolifera* remain inadequately studied. The absence of physical-biological coupled models that integrate ocean dynamics with the biological characteristics of *Ulva prolifera* limits the accuracy of drift trajectory predictions and the spread of green tides. Advanced multimodal data fusion techniques offer a promising solution to overcome the limitation by integrating high-resolution spatial, high-frequency temporal remote sensing data, and filed data. This approach offers a way to enhance the precision and responsiveness of green tide monitoring (Li et al., 2022). It can effectively mitigate challenges associated with cloud cover, weather variability, and noise, enabling researchers to better capture the

dynamic processes of *Ulva prolifera*, including its growth, outbreak, and dissipation phases, thus significantly improving biomass estimation and spatial coverage analysis. Furthermore, incorporating marine environmental factors (e.g., SST, SSS, light intensity, and SSW) and extreme climatic events (e.g., typhoons and heatwaves) into predictive models of green tide drift trajectories provides a more comprehensive understanding of the driving mechanisms underlying the spread and drift of *Ulva prolifera*.

Convolutional Neural Networks (CNNs) offer promising solutions for addressing the challenges associated with the temporal and spatial resolution differences in green tide monitoring, as well as improving predictions of drift trajectories and outbreak trends (Zhu et al., 2017; Wang et al., 2023a). Future research should focus on multi-source fusion (e.g., optical imagery, SAR data, hyperspectral imagery) and non-remote sensing data (e.g., oceanographic monitoring data, meteorological data) to extract and align multimodal features using CNNs, thereby addressing challenges related to temporal and spatial resolution discrepancies. In addition, exploring the nonlinear relationships between *Ulva prolifera* and environmental factors, and developing coupled models that integrate biological processes with remote sensing data, will help reveal the growth, drift, and decay processes of *Ulva prolifera*, as well as predict its drift trajectories and outbreak trends. These studies will facilitate the development of more accurate and real-time monitoring solutions, thereby improving the efficiency of green tide detection and optimizing strategies for early warning, evaluation, and management.

In conclusion, this study comprehensively reviews green tide remote sensing research, highlighting current trends, technological limitations, and future directions. It not only provides researchers with insights into the trends and dynamics of *Ulva prolifera* green tide studies and highlights potential research opportunities but also serves as a valuable reference for government administrators in formulating evidence-based strategies.

Author contributions

XG: Writing – original draft, Writing – review & editing, Conceptualization, Formal analysis, Funding acquisition, Methodology. HL: Conceptualization, Methodology, Writing – review & editing, Data curation. LW: Writing – review & editing. WS: Writing – review & editing. YL: Writing – review & editing.

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Conflict of interest

The authors declare that this research was conducted without any commercial, financial, or personal relationships that could be perceived as influencing the work reported in this paper.

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