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Influence of local scour on the dynamic responses of OWTs under wind-wave loads

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Offshore wind turbines (OWTs) often operate in complex marine environments, where they are not only subjected to wind and wave loads, but also adversely affected by scour. Therefore, it is of great significance to explore the effect of scour on the dynamic responses of OWTs under external loads to ensure structural safety, improve performance, and extend service life. In this study, a comprehensive numerical model of a 5-MW OWT, including tower, monopile, and soil-structure interaction (SSI) systems, is established by using ABAQUS platform. Aerodynamic loads is generated using blade element momentum, while wave loads is generated using the P-M spectral. The depth of scour is obtained based on on-site measured data. A comparative analysis is conducted between fixed foundations and SSI systems when conducting dynamic response analysis of OWTs under wave loads. Subsequently, the effect of scour on dynamic responses of OWTs under aerodynamic and wave loads is investigated. Results demonstrate that SSI can significantly influence the natural frequency and dynamic responses of the OWT. Therefore, it is essential to thoroughly consider SSI when evaluating the dynamic response of the OWT with local scour. The tower-top displacement and acceleration of the OWT with show a significant increasing trend compared to the non-scoured OWT. An increase in scour depth leads to higher maximum stress and stress amplitude in the steel monopile, which could potentially cause fatigue issues and should be given due attention.

KEYWORDS

offshore wind turbines, local scour, wave loads, wind loads, dynamic analysis

1 Introduction

The operating environment of OWTs is more complex than that of onshore wind power structures, with higher technical requirements. The long-term harsh service environment makes OWTs more prone to damage under complex loading conditions. OWTs are inevitably affected by various natural disasters during service, among which

scour, wind, wave loads are the most common disaster causing factors. The scour reduces the soil cover around the pile, changes the stiffness and boundary conditions of the pile foundation, and causes irreversible changes in its dynamic characteristics under aerodynamic and wave loads, posing significant risks to the safe operation of OWTs.

Offshore wind energy has the characteristics of abundant resources, high wind speed, low turbulence intensity, no land occupation, and few restrictions on wind farm construction. Pile-supported structure as a key load-bearing component of OWTs, accounts for 20% to 25% of the total cost and is an important part of the design process of OWTs (Keivanpour et al., 2017). Under local scour, scour pits will form near the monopile foundation, leading to a decrease in the horizontal bearing capacity of the foundation and affecting the normal operation of OWTs (Qi and Gao, 2016). Therefore, considering the local scour effect becomes particularly important for the design of the support structure. The support structure of OWTs is subjected to simultaneous loads from wind, waves, and currents, resulting in significant overturning moments at the mud surface position. Under the simultaneous action of currents and waves, there is usually scour at the seabed position, forming scour pits near the support structure, reducing the insertion depth of the foundation, thereby reducing its horizontal bearing capacity and affecting the normal operation of OWTs.

For the problem of local scour of a cylinder under uniform flow, Sumer et al. (Sumer et al., 1992) found, based on the research of Breusers et al. (Breusers et al., 1977), that the average equilibrium scour depth of a vertical cylinder under uniform flow conditions is $1.3D$, with a variance of $0.7D$, and the local scour is independent of the Re number, where $Re = UD/\nu$, U is the average flow velocity at depth, D is the diameter of the cylinder, ν is the viscosity coefficient of fluid motion. Regarding the problem of local scour of vertical cylinders under wave action, Sumer et al. (Sumer et al., 1992) and Kobayashi and Oda (1994) found that the equilibrium scour depth is closely related to the wave KC number. Local scour only occurs when $KC \geq 6$, where $KC = U_m T/D$, where U_m is the velocity amplitude of wave water point movement, and T is the wave period. This is mainly because vortex shedding occurs behind the pile at this time, and the horseshoe vortex in front can be fully developed. The maximum depth of local scour of a vertical cylinder under the combined action of waves and currents is relatively complex. In addition to being affected by the KC number, it is also related to the ratio of uniform flow velocity U_c to the amplitude of wave water quality point velocity U_m (Sumer and Fredsøe, 2001). The above research work has given people a profound understanding of the local scour problem of underwater vertical cylinders. However, the above empirical prediction formulas are mostly established on the basis of loose and uniform sand physical experiments, and cannot consider the common transport characteristics of cohesive soil in engineering sea areas. Therefore, it is difficult to directly apply them to the scour prediction of prototype pile foundations. In summary, scour is influenced by multiple factors, and the current method to obtain accurate scour depth is still on-site measurement. Therefore, this study will use on-site scour measurement data of wind turbine foundations in wind farms to analyze the dynamic response of OWTs.

In addition, many researchers have also analyzed the impact of local scour on the dynamic response of structures under external environmental loads. Ma et al (Ma et al., 2018). applied finite element method to study the effect of scour on the structural response of triangular OWTs. Tseng et al (Tseng et al., 2017). studied the deformation response of monopile foundations under scour by modifying the soil resistance pile deformation (p - y) curve around the pile. Qi et al (Qi et al., 2016). conducted a series of centrifuge model tests with different scour profiles to investigate the effects of local and general scour on the response of laterally loaded piles. The study introduced the concept of effective soil depth to determine the corresponding p - y curves for shallowly buried piles in sand, which serves as a practical method for assessing the impact of scour. Li et al. (Biao et al., 2024) performed a comprehensive finite element analysis to explore the effects of scour on lateral pile-soil interaction. They quantified how the slope angle of scour pits affects the lateral response of pile foundations using the effective soil depth method. Their study refined the formula for evaluating the impact of scour on p - y curves and extended its application to any slope angle of scour pits. Liu et al. (Liu et al., 2016) conducted local scour experiments on the foundation structures of monopile OWTs with different diameters, studying the relationship between the size of scour pits and the depth of scour. Bush et al. (Bush et al., 2009) studied the influence of foundation on the structural response of OWTs based on their consideration of aerodynamic characteristics. Jun et al. (Jung et al., 2015) applied the finite element method to calculate the top load response curve of the foundation, and simulated the influence of the foundation on the structural response of OWTs by solving the foundation stiffness matrix. Hansen et al. (Hansen et al., 2007) studied the variation law of scour through actual measurements. Li et al. (Li et al., 2014) used data obtained from on-site monitoring and numerical simulation to obtain the dynamic response law of OWTs under different water depths and wave loads. Kim et al. (Kim et al., 2014) conducted a refined simulation of OWTs by establishing spring elements to simulate pile-soil interactions. Takehiko and Takeshi (2014) conducted a series of studies on OWTs in service to investigate the load combination effects when they encounter earthquakes during operation. He (2015) studied the effects of depth, width, and slope angle of scouring pits on the horizontal bearing capacity of pile foundations. Hu et al. (Hu et al., 2015) studied the horizontal bearing capacity of a monopile under different scouring conditions, and obtained the influence of scouring and the fixing method of the pile top on the bearing capacity of a monopile. Zha et al. (Zha et al., 2023) innovatively applied the hyperplastic ratcheting model to a aero-hydro-servo-elastic simulation tool, considering the changes in stiffness, damping, and accumulated displacement of monopile OWTs under cyclic loading. The research provides an accurate model for estimating the fatigue life of monopile OWTs. Zha et al. (Zha et al., 2022) proposed a simplified model with two cyclic loading factors to accurately predict the accumulated displacement of monopiles. This model effectively predicts the accumulated displacement of monopiles in soft clay. The research findings provide a new method for design codes to accurately estimate monopile displacements. In summary, the analysis of the impact of scour on the dynamic responses of monopile foundations or

OWT support structures is relatively extensive. However, studies evaluating the effects of actual scour depth on the dynamic response of OWTs under aerodynamic and wave loads are still relatively rare.

The monopile-supported OWT will inevitably be affected by foundation scour caused by seabed currents and wave impact at the sea surface. The soil surrounding the pile will gradually erode, creating an increasingly larger scour pit, which poses a significant threat to the overall structural safety of the OWT under aerodynamic and wave loads. Therefore, ensuring the safety and stability of the OWT under foundation scour and external loads is particularly important. Based on the above analysis, the study first simulates the aerodynamic loads on the blades using the blade element momentum theory. Next, wave loads are simulated in the time domain using the P-M wave spectrum. Subsequently, a complete finite element model of the OWT, including the tower, monopile foundation, and SSI system, is established using the ABAQUS platform. Aerodynamic and wave loads are synchronously applied to the OWT model for dynamic response calculation. Finally, the impact of different scour depths on the dynamic response of the OWT under external loads is analyzed. The results of this study provide a theoretical basis for the engineering design, construction, and safety assessment of OWTs.

2 Establishment of structural model of OWTs

2.1 5-MW OWT and monopile

The National Renewable Energy Laboratory (NREL) 5-MW OWT has been used in a number of wind energy projects. Monopile is a foundation structure commonly used to support wind turbines in offshore locations. It consists of a single steel pile that is driven into the seabed, upon which the wind turbine is mounted. The monopile-supported OWT used in this study is illustrated in Figure 1, which also defines the coordinate system, where x , y and z represent the heave, fore-aft and side-to-side direction of the OWT, respectively. Table 1 shows the parameter properties of NREL 5-MW wind turbine.

A finite element model of the monopile OWT was established using ABAQUS. The tower model and the monopile model above the mudline were constructed using the shell element (ABAQUS: S4 elements). The monopile model below the mudline was established using the beam element (ABAQUS: B31 element) to facilitate the application of nonlinear soil springs to consider the influence of

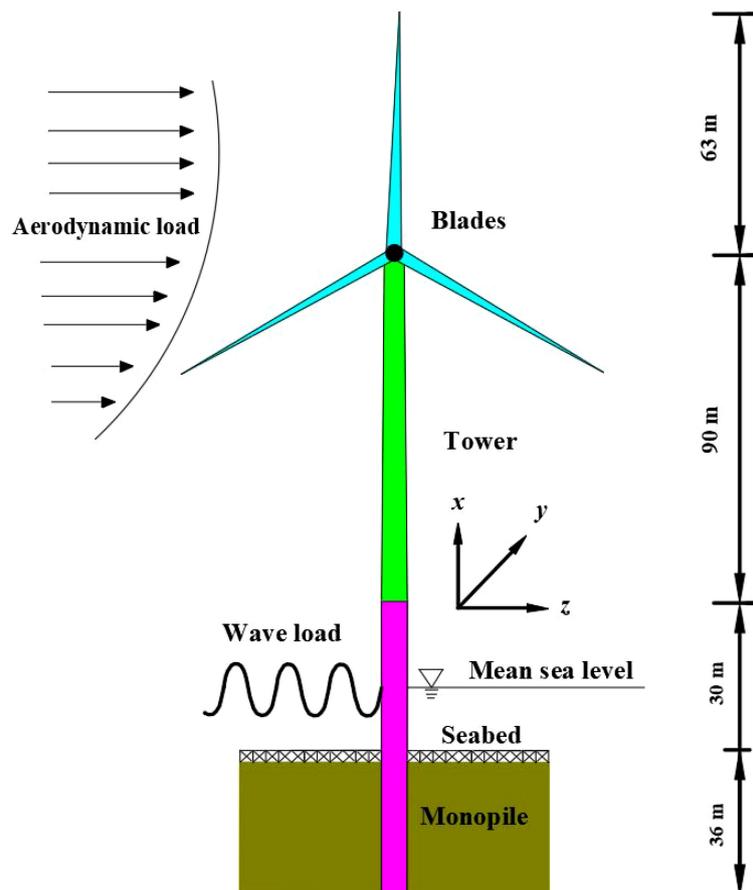


FIGURE 1
NREL 5-MW OWT and monopile foundation.

TABLE 1 Parameter properties of NREL 5-MW wind turbine and monopile (Jonkman et al., 2009).

Component part	Parameter	Value
Blade	Rotor orientation, configuration, diameter	Upwind, 3 blades, 126 m
	Hub height	90 m
	Cut-in, rated, cut-out wind speed	3 m/s, 11.4 m/s, 25 m/s
	Overall (integrated) mass	17,740 kg
Hub and Nacelle	Hub diameter	3 m
	Hub mass	56,780 kg
	Nacelle mass	240,000 kg
Tower	Height above water	90 m
	Overall (integrated) mass	347,460 kg
Monopile	Diameter	6.0 m
	Length below the seabed	36.0 m
	Total length	66.0 m

soil-structure interaction (SSI). Rotor-Nacelle Assembly (RNA) mass is assumed as a lumped mass attached on the top of the tower. To uphold deformation continuity at the junction between the tower and the monopile, the cross sections of the tower-bottom and the monopile-top are tied. A unit mesh size of 1 meter along the tower and monopile of the OWT is proven adequate for achieving accurate simulations.

The total damping of OWTs mainly includes contributions from the aerodynamic damping, hydrodynamic damping, structural damping, and soil damping. The aerodynamic damping given in the literature varies between 2% and 8% (Hansen et al., 2006; Koukoura et al., 2015). In this study, aerodynamic damping is simulated by placing dampers on the top of the tower of the OWT (Schafhirt and Muskulus, 2018). The aerodynamic damping of 3.5% is considered in this study as suggested in Kuhn (2001). In this study, a constant Rayleigh damping equivalent to a damping ratio of 2% of critical damping is utilized, which consists of 1% structural damping, 0.2% hydrodynamic damping, and 0.8% soil damping. The similar choice has been utilized by several other authors (Carswell et al., 2015; Damgaard et al., 2015).

In this study, the fundamental frequency of the monopile OWT with SSI is 0.243 Hz, which is between 1P and 3P recommended in (DNV-OS-J101, 2014). The natural frequencies of the monopile

OWT without and with SSI are presented in Table 2. From the Table 2, it can be observed that there is a significant difference in the vibration mode of the OWT between fixed foundation and considering SSI, which also reflects the significant impact of SSI on the vibration characteristics of the OWT. In addition, it can be seen that the first few natural frequencies of the OWT established in this study are consistent with those obtained by Yang et al. (Yang et al., 2019), which verifies the reliability of the OWT model.

2.2 Soil-structure interaction

The p-y method can better reflect the deformation characteristics of pile-soil interaction, especially in describing the nonlinearity of pile-soil interaction. Compared with other linear simulation methods such as *K* method and *m* method, it is more reasonable. This is because the p-y method considers the nonlinear effects of soil, rather than just treating it as an elastic body. The p-y method can more accurately predict the response of piles under horizontal loads by simulating the relationship curve between the horizontal reaction of the soil at a certain depth below the mudline and the deflection of the pile at that point.

The p-y method is utilized to simulate SSI. This study calculates the soil spring parameters based on the soil layer information provided in (Passon, 2006), and all soil layers are made of sandy soil, as shown in Table 3. This study utilized the nonlinear p-y curves obtained based on the LPILE platform under cyclic loads (Passon, 2006). The p-y curves used in this study are shown in Figure 2.

2.3 Scour depth

The depth of scour is influenced by various factors, and the scour mechanism is also very complex. The waves, currents, tides, and other factors in the marine environment are one of the main factors affecting the depth of scour. Strong winds, waves, and high tides can increase the impact of the marine environment on the foundation, leading to deeper scour depths. In addition, the shape, material, size, and other characteristics of the foundation structure can affect the depth of scour. For example, flat bottomed foundations may be more susceptible to scour compared to columnar foundations because they provide a larger surface area in contact with water flow, thereby increasing the likelihood of scour. The type, density, stability, and other characteristics of

TABLE 2 The natural frequencies of the monopile OWT without and with SSI.

Mode	Description	Fixed	SSI	SSI in (Yang et al., 2019)
1	1st order OWT fore-aft mode	0.264	0.243	0.249
2	1st order OWT side-side mode	0.260	0.239	0.248
3	2nd order OWT fore-aft mode	1.937	1.512	1.534
4	2nd order OWT side-side mode	1.417	1.368	1.383

TABLE 3 Soil condition used in this study (Passon, 2006).

Depth below the seabed	Soil layer	Saturated unit weight γ_{sat}	Angle of friction ϕ
0~5 m	Layer 1	10.0 kN/m ³	33.0°
5~14 m	Layer 2	10.0 kN/m ³	35.0°
14~36 m	Layer 3	10.0 kN/m ³	38.5°

seabed soil can also affect the depth of scour. Soft seabed soil may be more susceptible to scour, resulting in deeper scour depths, while hard seabed soil is relatively less susceptible to scour. The depth of scour gradually accumulates over time. Basic structures exposed to the marine environment for a long time will be subjected to continuous scour, resulting in a gradual increase in scour depth.

On site measurement is one of the most accurate methods for evaluating the depth of scour. By regularly inspecting and

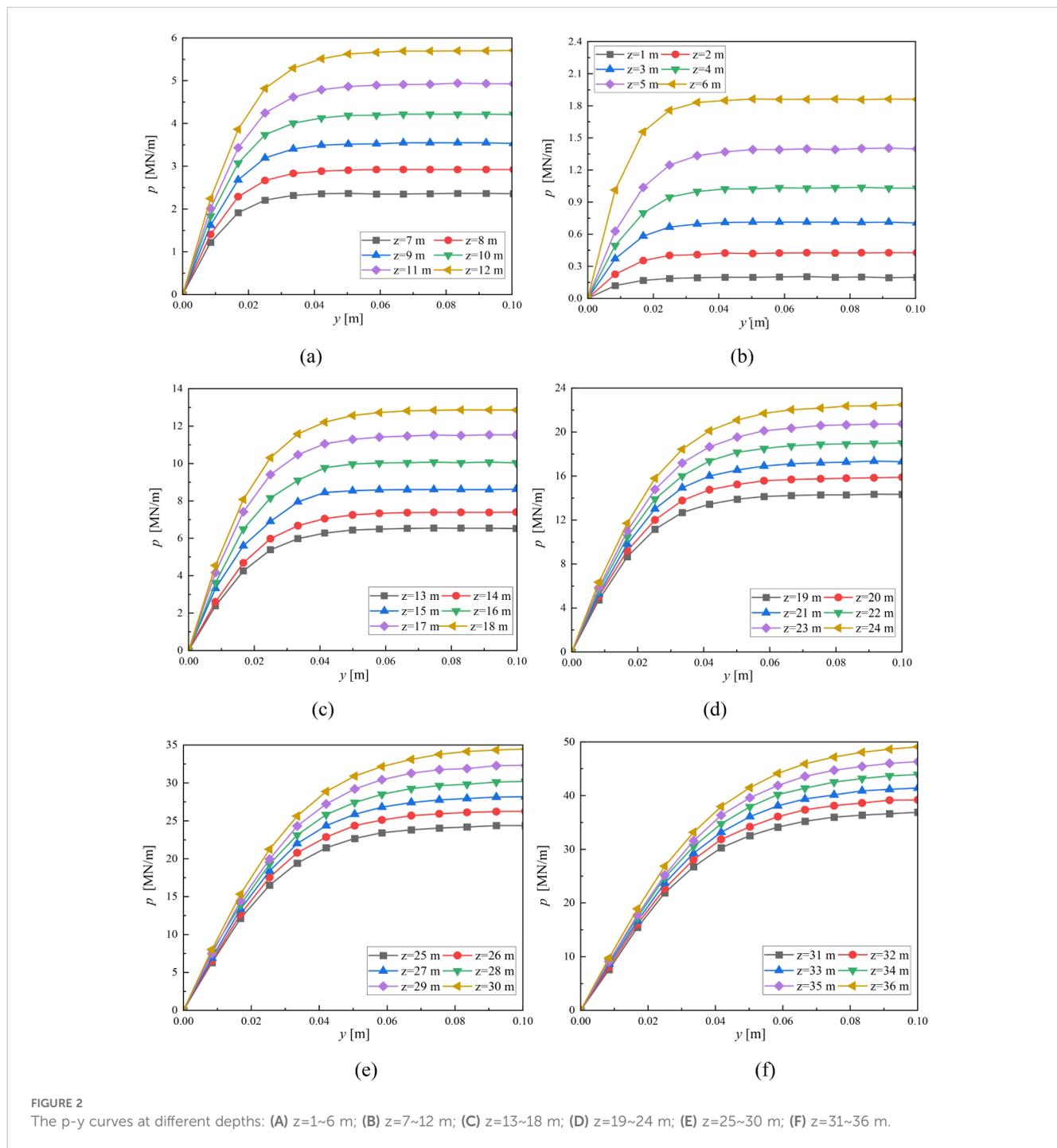


FIGURE 2 The p-y curves at different depths: (A) z=1~6 m; (B) z=7~12 m; (C) z=13~18 m; (D) z=19~24 m; (E) z=25~30 m; (F) z=31~36 m.

measuring the foundation structure in actual marine environments, it is possible to directly observe and record changes in scour depth. This method can take into account the actual situation of the marine environment and the actual state of the infrastructure, and has high accuracy and reliability.

Therefore, this study will use the on-site scouring and scanning results of a wind turbine foundation in a certain offshore wind farm as a theoretical analysis basis to conduct dynamic response analysis of OWTs under scouring conditions. Figure 3 shows a three-dimensional monitoring diagram of wind turbine foundation scour in a certain offshore wind farm. Table 4 presents the measured results of wind turbine foundation scour in a certain offshore wind farm. In order to investigate the impact of scour depth on the overall dynamic performance of OWTs, this study conducted a detailed analysis of a scour depth of 7.38 m.

3 External loads

3.1 Aerodynamic loads

The model based on the logarithmic law of wind speed variation was established and expressed as follows:

$$V_h/V_{h_r} = \ln(h/h_0)/\ln(h_r/h_0) \tag{1}$$

where V_h and V_{h_r} represent mean wind speeds, h represents elevation, h_r represents reference height, and h_0 represents roughness parameter.

The Kaimal spectrum (Burton et al., 2001) was utilized to obtain frequency components, which can be expressed as:

$$S_{Kaimal}(f) = \frac{4\sigma^2 L_k/V_h}{(1 + 6fL_k/V_h)^{5/3}} \tag{2}$$

where f denotes cyclic frequency, L_k represents integral length, and σ is standard deviation.

The Blade Element Momentum (BEM) theory was applied to calculate aerodynamic loads on blades, with lift force F_L perpendicular to relative flow direction and drag force F_D parallel to it. F_L and F_D per unit length can be calculated using lift and drag coefficients C_L and C_D , blade chord length c , and relative wind speed V_{rel} .

$$F_L = \frac{\rho c}{2} V_{rel}^2 C_L(\alpha) \tag{3}$$

$$F_D = \frac{\rho c}{2} V_{rel}^2 C_D(\alpha) \tag{4}$$

The wind loads time history on the blades is simulated based on the FAST platform, with an average wind speed of 11.4 m/s selected for the hub height. Due to the fact that this study only considers the dynamic effects in the Fore-Aft direction, only the wind force F_x and bending moment M_y are given, as shown in Figure 4.

3.2 Wave loads

Pierson and Moskowitz (1963) proposed a formula for an energy spectrum distribution of wind-generated sea wave in 1963. This spectrum, commonly referred to as the P-M model, has been widely adopted by ocean engineers and stands as one of the most representative spectra in waters worldwide.

The P-M spectrum model characterizes a fully developed ocean, determined by a single parameter: wind speed. Both fetch and duration are considered infinite. Applicability of this model necessitates prolonged, near-constant wind speeds over large areas for many hours before wave data acquisition, with minimal variations in wind direction. Despite these assumptions, the P-M model finds numerous applications in the design of marine structures.

The P-M spectrum model can be expressed as:

$$S(\omega) = \alpha g^2 \omega^{-5} \exp[-0.74 \left(\frac{\omega U_w}{g}\right)^{-4}] \tag{5}$$

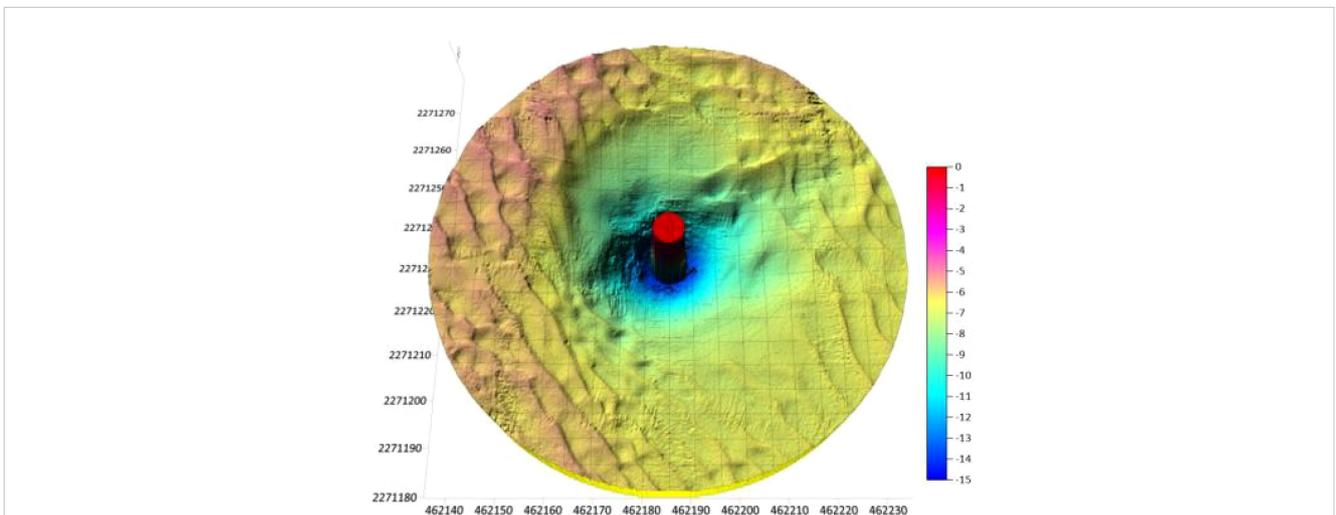


FIGURE 3 Three dimensional monitoring diagram of OWT foundation scour in a certain offshore wind farm.

TABLE 4 Actual measurement results of wind turbine foundation scour in a certain offshore wind farm.

Monopile diameter [m]	Pile sinking date	Monitoring date	Scour depth [m]	Scour volume [m ³]
6.0	2020/08/25	2022/03/06	7.38	3380

where $\alpha = 0.0081$. Alternatively, in term of the frequency of spectral peak:

$$S(\omega) = \alpha g^2 \omega^{-5} \exp[-1.25 \left(\frac{\omega}{\omega_0}\right)^{-4}] \tag{6}$$

The variance of the wave elevation (σ^2) or the zeroth moment (m_0) is defined as the area under the spectral curve:

$$\sigma^2 = m_0 = \int_0^\infty S(\omega) d\omega \tag{7}$$

If we substitute $x = 1.25 \left(\frac{\omega}{\omega_0}\right)^{-4}$:

$$(\omega)^{-5} d\omega = -\frac{dx}{5\omega_0^4} \tag{8}$$

$$\sigma^2 = m_0 = \frac{\alpha g^2}{5\omega_0^4} \tag{9}$$

If we substitute for α ,

$$\alpha = \frac{5\sigma^2 \omega_0^4}{g^2} \tag{10}$$

$$S(\omega) = 5\sigma^2 \frac{\omega^{-5}}{\omega_0^{-4}} \exp[-1.25 \left(\frac{\omega}{\omega_0}\right)^{-4}] \tag{11}$$

Also, the root square water surface elevation, σ , is related to the peak frequency as:

$$\sigma = \sqrt{\alpha/5g} / \omega_0^2 \tag{12}$$

Noting that

$$H_s = 4\sigma \tag{13}$$

The peak frequency is related to the significant wave height H_s by

$$\omega_0^2 = 0.161g/H_s \tag{14}$$

An equivalent expression for the P-M spectrum in terms of the cyclic frequency, $f (= \omega/2\pi)$ may be expressed as:

$$S(f) = \frac{\alpha g^2}{(2\pi)^4} f^{-5} \exp[-1.25 \left(\frac{f}{f_0}\right)^{-4}] \tag{15}$$

where $f_0 = \omega_0/2\pi$.

To perform the generation of sample functions of the wave load process according to Equations 5–15, which take advantage of the classical fast Fourier transforms, the upper cutoff frequency is taken as 50 Hz and the global period is taken as 500 s. Two random sample functions based on the P-M wave spectral model are generated. One of them is generated at the significant wave height of 3.5 m and the peak spectral period of 5.4 s. The other one is generated at the significant wave height of 6.3 m and the peak spectral period of 9.0 s. The wave parameters used in this study are presented in Table 5. The time series of two wave loads are displayed in Figure 5 for the entire period 500 s in order to better visualize the differences and similarities among the generated time histories.

4 Result analysis

4.1 The effect of SSI

The mode analysis results of the OWT using fixed foundation and considering SSI are shown in Figure 6. For brevity, the first two order normalized Fore-Aft modal shapes along elevation above

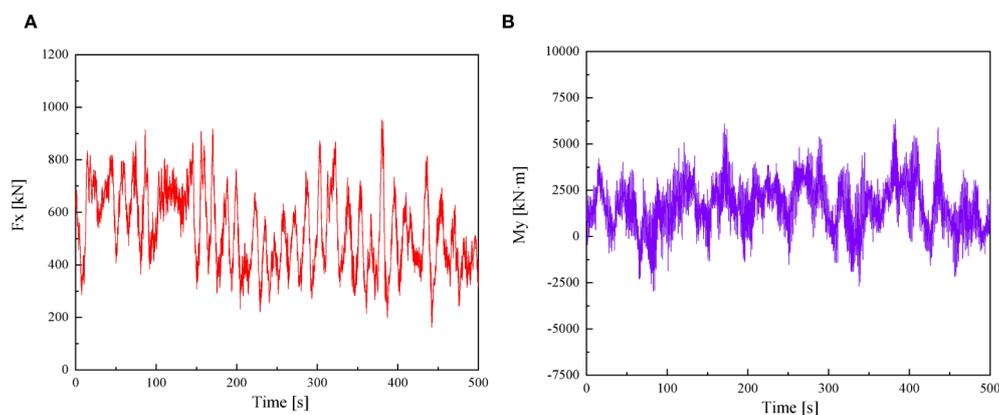


FIGURE 4 Time history of equivalent loads acting on blades. (A) Wind load 227 F_x ; (B) Bending moment M_y .

TABLE 5 Wave parameters used in this study.

Wave case	Return period	Significant wave height	Peak spectral period
W_1	1 year	3.5 m	5.4 s
W_2	50 years	6.3 m	9.0 s

mudline. The first-order natural frequencies of the OWT with fixed foundation and considering SSI are 0.264 Hz and 0.243 Hz, respectively. It can be observed that SSI has a significant impact on the natural frequency of the OWT.

In addition, this section of the study mainly considers the impact of SSI on dynamic behaviour of the OWT. 500 seconds wave load time series is applied to the OWT for dynamic response calculation. In this part of the examples, the scouring effect was not considered, which means that the scouring depth is 0 m. Figures 7 and 8 show the displacement time histories of the tower-top of the

OWT under W_1 and W_2 wave loads, respectively. As shown in Figures 7 and 8, the tower-top displacement of the OWT considering SSI shows a significant increasing trend compared to the tower-top displacement of the OWT under fixed foundation. In addition, it can be observed that as the wave load increases, this displacement amplification trend becomes more pronounced. Table 6 lists the maximum displacement at the tower-top of the OWT. As shown in Table 6, when the OWT is subjected to wave loads W_1 and W_2 , the maximum displacement at the tower-top of the OWT considering SSI is 0.114 m and 0.180 m, respectively. Compared with the maximum displacement of 0.062 m and 0.107 m without SSI, it increases by 83.9% and 68.2%, respectively.

Figures 9 and 10 show the acceleration time histories of the tower-top of the OWT under W_1 wave loads and W_2 wave loads, respectively. As shown in Figures 9 and 10, the acceleration at the tower-top of the OWT considering SSI is significantly higher than that without SSI. As the wave load increases, the acceleration at the tower-top also gradually increases. Table 6 lists the maximum

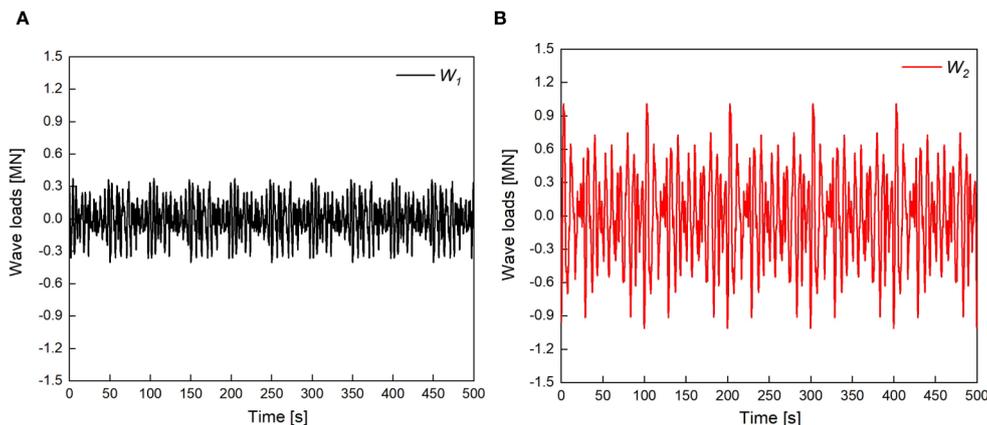


FIGURE 5 The time series of two wave conditions used in this study. (A) W_1 wave 272 loads; (B) W_2 wave loads.

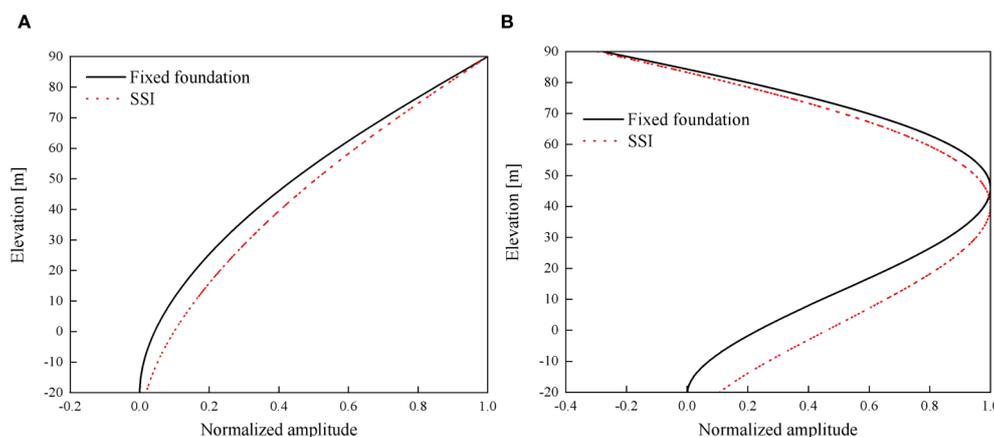


FIGURE 6 The first two order normalized modal shapes of the OWT above mudline (scour depth=0 m). (A) 1st order Fore-Aft mode; (B) 2nd order Fore-Aft mode.

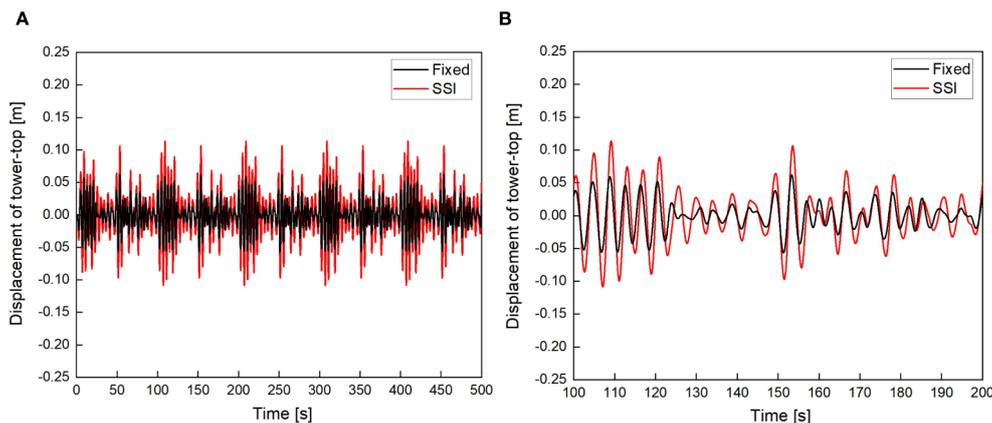


FIGURE 7 Displacement of tower-top with and without SSI under W_1 wave loads (scour depth=0 m) (A) 0~500 s; (B) 100~200 s.

acceleration at the tower-top of the OWT. As shown in Table 6, when the OWT is subjected to W_1 wave loads and W_2 wave loads, the maximum accelerations at the tower-top of the OWT considering SSI are 0.279 m/s^2 and 0.338 m/s^2 , respectively. Compared with the maximum accelerations of 0.162 m/s^2 and 0.196 m/s^2 without SSI, the maximum accelerations increase by 72.2% and 72.4%, respectively. From the above analysis, it can be concluded that SSI has a significant impact on tower-top

displacement and acceleration. Therefore, it is crucial to fully consider the impact of SSI on the dynamic response of the OWT.

4.2 The effect of local scour

After discussing the impact of SSI in Sec. 4.1, this section will use W_2 wave load as input to discuss the impact of local scour on the

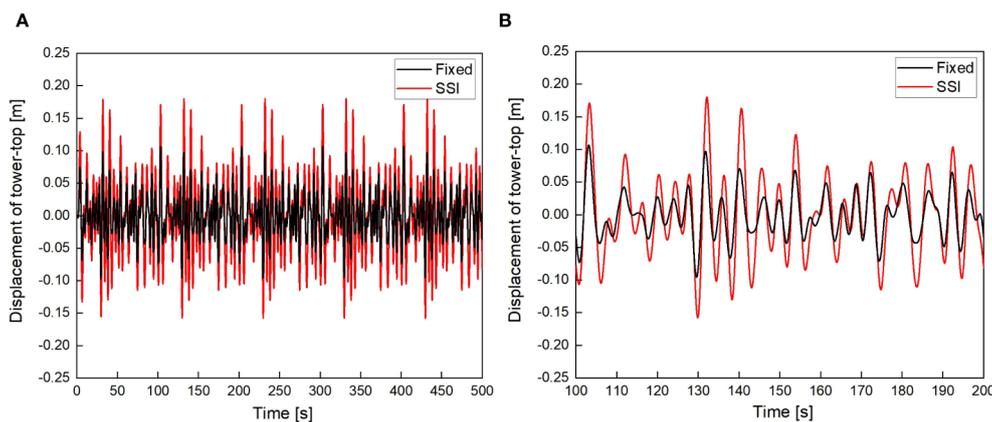


FIGURE 8 Displacement of tower-top with and without SSI under W_2 wave loads (scour depth=0 m). (A) 0~500 s; (B) 100~200 s.

TABLE 6 Maximum of tower-top dynamic responses with and without SSI (scour depth=0 m).

Wave load	Maximum displacement (m)		Maximum acceleration (m/s^2)	
	Fixed	SSI	Fixed	SSI
W_1	0.062	0.114	0.162	0.279
W_2	0.107	0.180	0.196	0.338

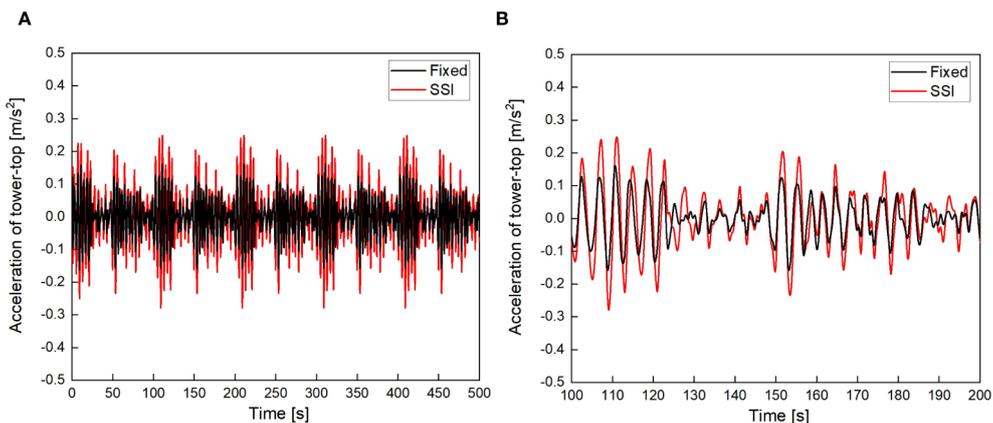


FIGURE 9 Acceleration of tower-top with and without SSI under W_1 wave loads (scour depth=0 m). (A) $t = 0\sim 500$ s; (B) $t = 100\sim 200$ s.

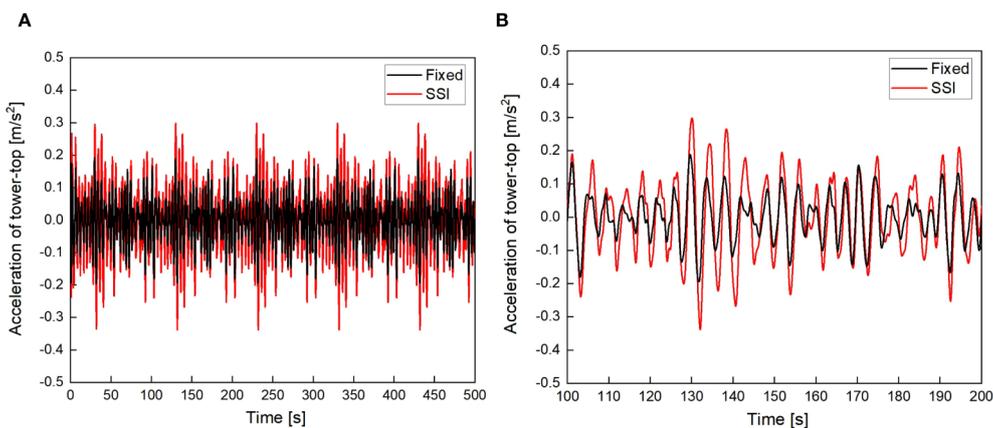


FIGURE 10 Acceleration of tower-top with and without SSI under W_2 wave loads (scour depth=0 m). (A) $t = 0\sim 500$ s; (B) $t = 100\sim 200$ s.

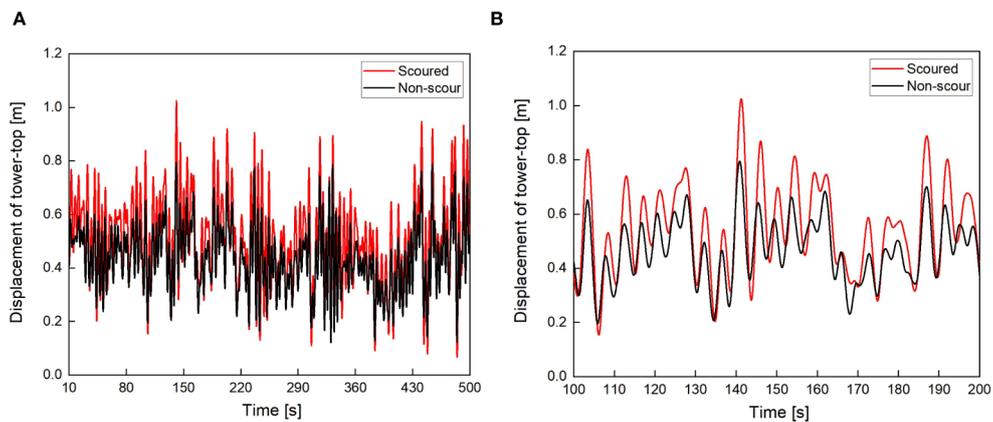


FIGURE 11 Tower-top displacement of the OWT with and without scour under aerodynamic and wave loads. (A) $t = 10\sim 500$ s; (B) $t = 100\sim 200$ s.

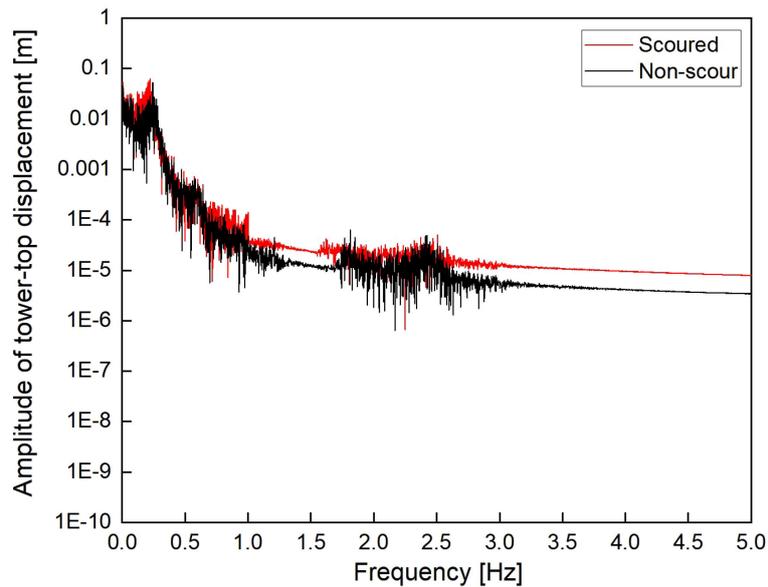


FIGURE 12 Frequency domain results of tower-top displacement with and without scour under aerodynamic and wave loads.

dynamic response of the OWT under wave and aerodynamic loads. And the dynamic response analysis parameters were studied using tower-top displacement and bending stress at the mudline, revealing the influence of scouring on the dynamic response of the OWT. It should be noted that the following calculation conditions all consider SSI. In order to study the impact of scour depth on the overall dynamic performance of the OWT, this study used the measured scour depth of 7.38 m as the calculation basis for scour depth. 500 seconds aerodynamic and wave loads time series are applied to the OWT for dynamic response calculation. In order to eliminate instantaneous interference caused by load application, the calculation results for the first 10 seconds are not displayed.

Figure 11 shows the time-history of displacement of the tower-top with and without scour under aerodynamic and wave loads. As shown in Figure 8, the tower-top displacement of the OWT with

scour under wave and aerodynamic loads is significantly greater than that of the non-scour state. Due to the influence of aerodynamic loads, the random fluctuations of the OWT's tower-top displacement are more pronounced and exhibit reciprocating motion on one side of the equilibrium position. This results in greater magnitude and fluctuation amplitude compared to the displacement of the OWT under wave loads alone. Figure 12 shows the frequency domain results of tower-top displacement with and without scour under aerodynamic and wave loads. It can be seen that compared to the original non-scouring state, the vibration frequency of the OWT after scouring is lower, so the vibration mode excited under aerodynamic-wave loads is lower. In addition, the amplitude of the scoured OWT at the characteristic frequency is greater than the structural amplitude of the original non-scouring state, indicating that the scoured OWT has a higher

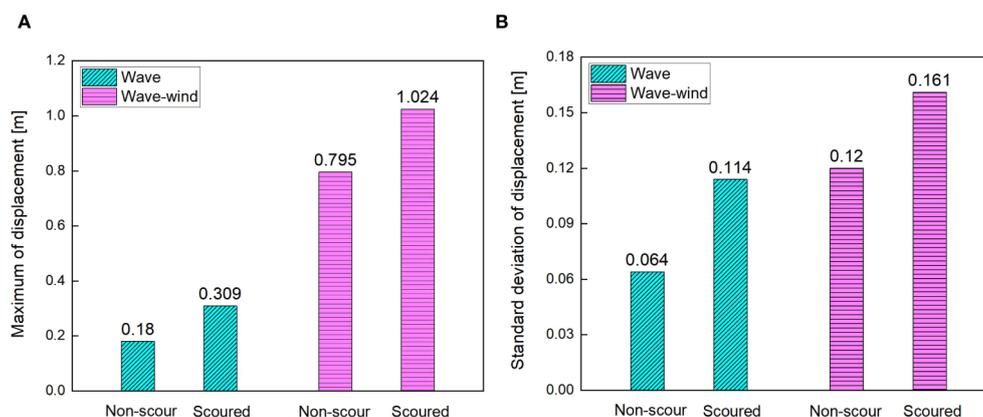


FIGURE 13 Statistic of tower-top displacement with and without scour under wave loads or combined aerodynamic-wave loads. (A) Maximum; (B) Standard deviation.

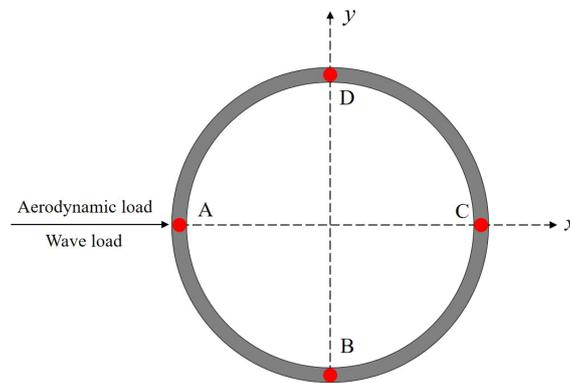


FIGURE 14 Stress points distributed along the cross-section of the monopile.

energy content under load excitation, which in turn leads to a larger dynamic response of the OWT.

Figure 13 shows the statistic of tower-top displacement with and without scour under wave loads or combined aerodynamic-wave loads. It can be observed from Figure 13A that the maximum displacement at the tower-top of the OWT under combined aerodynamic and wave loads is significantly greater than under wave loads alone. For instance, the maximum displacement of the OWT without scour under combined loads is 0.795 m, which is 341.7% higher compared to the maximum displacement of the OWT without scour under wave loads alone. Figure 13B shows a similar trend for the standard deviation of displacement, indicating that the displacement variability of the OWT under combined aerodynamic and wave loads is much larger than under wave loads alone. Thus, it is evident that the OWT experiences more

severe vibrations in operational conditions (wave and aerodynamic loads) compared to its parked state (wave load only). Additionally, scour increases both the maximum displacement and the standard deviation of displacement for the OWT. For example, the maximum displacement and standard deviation of the scour-affected OWT are 1.024 m and 0.161 m under the combined effects of aerodynamic and wave loads, respectively. These values are 28.8% and 34.2% higher than those of the OWT without scour under the same loads. This indicates that scour significantly amplifies the dynamic response of the OWT under external loads, which is highly detrimental to its operational stability and safety.

The bending stress of monopile at the mudline of the OWT under aerodynamic and wave loads are obtained. The stress calculation points (A, B, C, D) of the monopile cross-section are shown in Figure 14. Figure 15 shows the bending stress of mudline

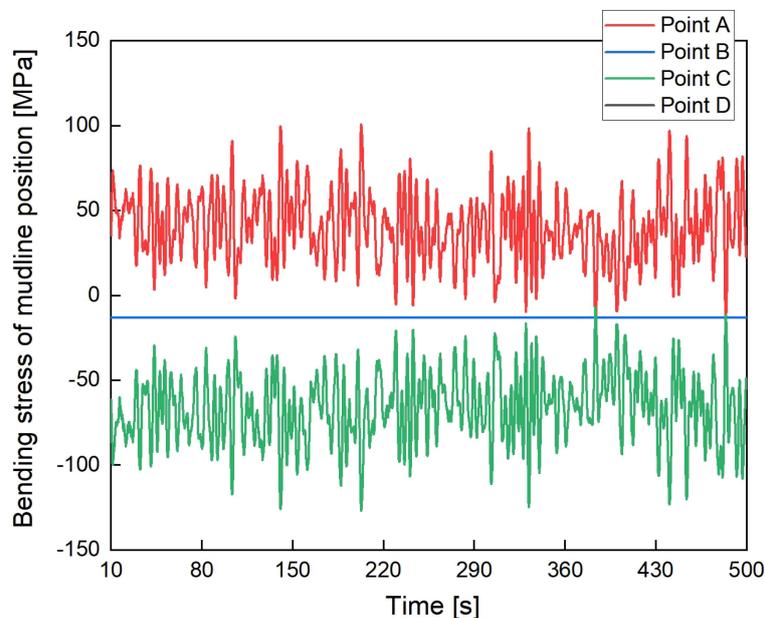


FIGURE 15 Bending stress of mudline position without scour under aerodynamic and wave loads.

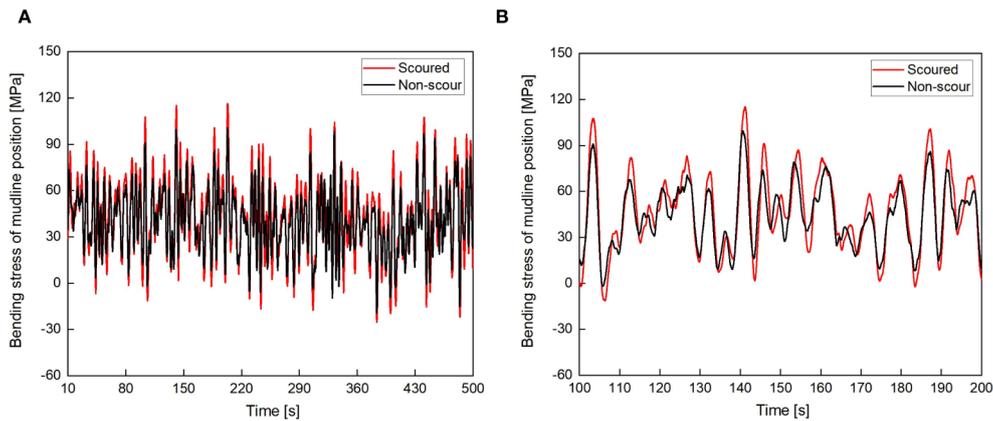


FIGURE 16 Bending stress of point A with and without scour under aerodynamic and wave loads. (A) $t = 10\sim 500$ s; (B) $t = 100\sim 200$ s.

position without scour under aerodynamic and wave loads. It can be found that the stress amplitude range at points A and C is higher than at points B and D. This phenomenon is due to the fact that external loads are directly applied along the A-C line on the cross-section, while the B-D line coincides with the neutral axis of the section. Consequently, the stress cycles at points A and C are significantly higher than those at points B and D.

Figure 16 shows the time history of bending stress at the mudline of the OWT with and without scour under wave and aerodynamic loads. As shown in Figure 16, the bending stress at the mudline of the OWT with scour under wave and aerodynamic loads is slightly greater than that in the original non-scouring state. This is because scour increases the length of the monopile shaft in the water, which expands the unconstrained range of the monopile foundation and makes the OWT as a whole more flexible. Consequently, the stress on the scoured OWT is higher compared to the non-scoured OWT under aerodynamic and wave loads.

Figure 17 shows the statistic of bending stress of mudline position with and without scour under wave loads or combined

aerodynamic-wave loads. It can be observed that the maximum stress on the OWT under combined aerodynamic and wave loads is significantly greater than under wave loads alone. For instance, the maximum stress of the OWT with non-scour under combined loads is 100.583 MPa, which is 222.3% higher than the stress value under wave loads alone. Due to the significant increase in the length of the monopile located in the water under scour, the limiting effect of the soil around the monopile is reduced compared to the original non-scouring state, resulting in a decrease in the overall stiffness of the OWT. The stress level and amplitude of OWT under aerodynamic and wave loads are relatively high, which has a negative impact on the fatigue cumulative damage of OWT.

5 Conclusion

The scouring effect poses a serious challenge to the dynamic behavior of the pile-supported OWT. Especially under complex marine environmental loads, the stability and safety of the OWT

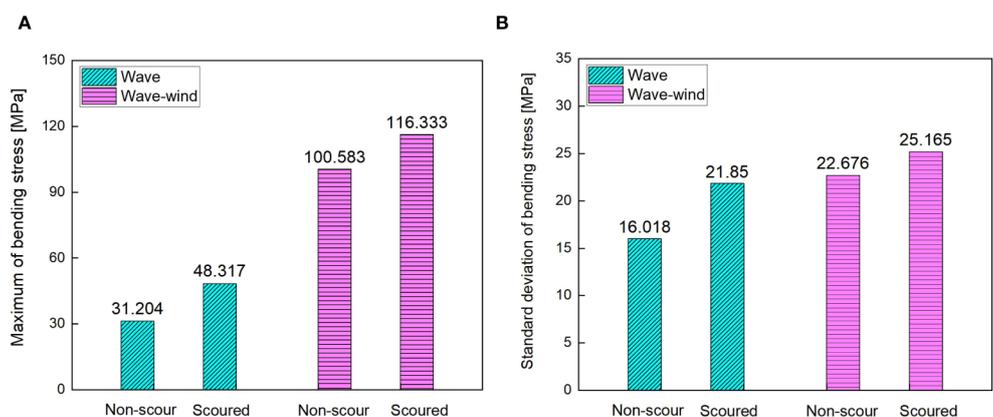


FIGURE 17 Statistic of bending stress of mudline position with and without scour under wave loads or combined aerodynamic-wave loads. (A) Maximum; (B) Standard deviation.

after scour should be given more attention. Based on the calculation results obtained from this study, the following main conclusions have been summarized:

1. The tower-top displacement and acceleration of the OWT considering SSI show a significant increasing trend compared to those under fixed foundations. In addition, it can be observed that as the wave load increases, this amplification trend becomes more pronounced. SSI has a significant impact on tower-top displacement and acceleration. Therefore, it is crucial to fully consider the impact of SSI on the dynamic response of OWT.
2. The tower-top displacement response of the OWT after scour under wave and aerodynamic loads is significantly greater than that of the original non-scouring state. Compared with the original non-scouring state, the vibration frequency of the scoured OWT is lower, resulting in lower vibration modes excited under wind-wave loads.
3. The amplitude of the OWT after scour at the characteristic frequency is greater than that of the original structure without scour, indicating that the OWT after scour has a higher energy content under load excitation, which in turn leads to a larger dynamic response of the OWT.
4. Due to the significant increase in the length of the pile located in the water under scour, the limiting effect of the soil around the pile is reduced compared to the original non-scouring state, resulting in a decrease in the overall stiffness of the OWT. Under wind-wave excitation, the stress level and amplitude of the OWT are higher, which has an adverse effect on the fatigue accumulation damage of the OWT.

Data availability statement

The original contributions presented in the study are included in the article/supplementary material. Further inquiries can be directed to the corresponding author.

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Author contributions

YY: Methodology, Project administration, Writing – original draft. MR: Conceptualization, Investigation, Software, Writing – original draft. CY: Data curation, Formal Analysis, Validation, Writing – review & editing. ZW: Resources, Software, Visualization, Writing – original draft. CZ: Investigation, Project administration, Supervision, Writing – original draft. TW: Methodology, Software, Writing – review & editing.

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Conflict of interest

Authors YY, MR, CY, ZW were employed by the company Guangdong Energy Group Science and Technology Research Institute CO. LTD.

The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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