



A Global Ocean Oxygen Database and Atlas for Assessing and Predicting Deoxygenation and Ocean Health in the Open and Coastal Ocean

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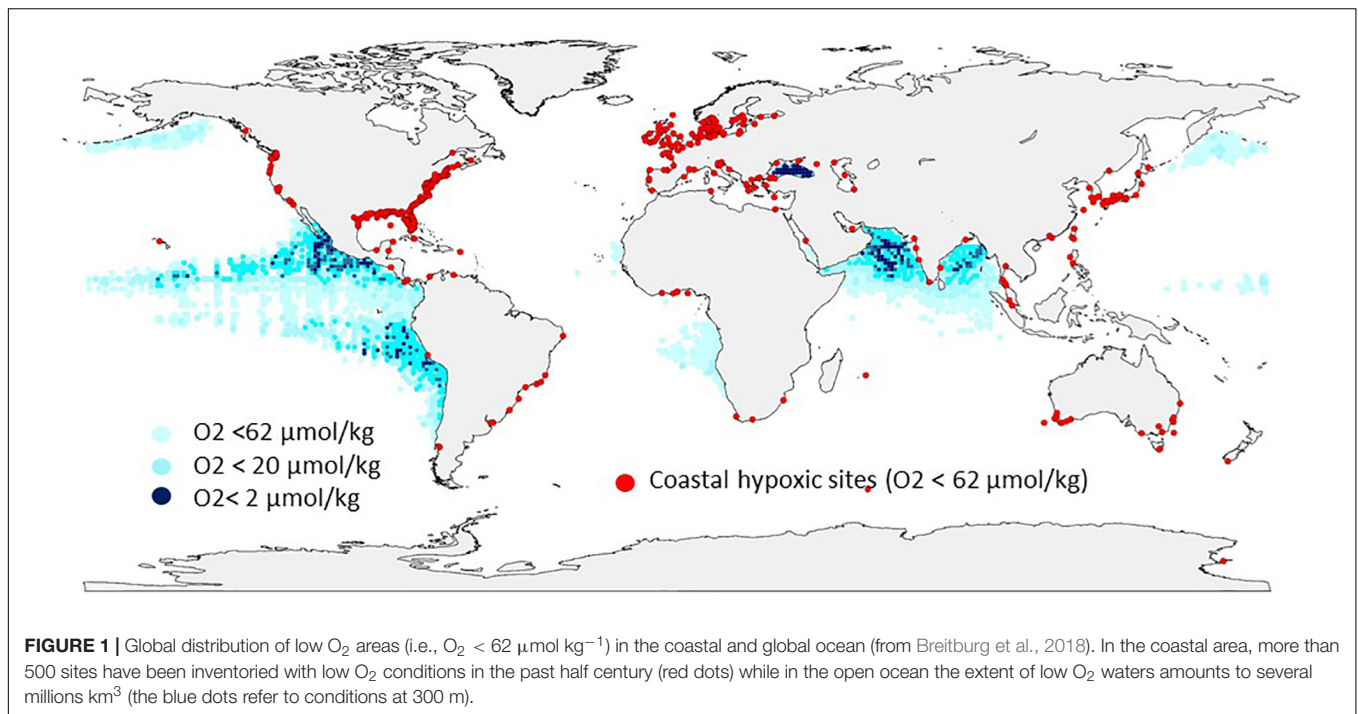
In this paper, we outline the need for a coordinated international effort toward the building of an open-access Global Ocean Oxygen Database and Atlas (GO₂DAT) complying with the FAIR principles (Findable, Accessible, Interoperable, and Reusable). GO₂DAT will combine data from the coastal and open ocean, as measured by the chemical Winkler titration method or by sensors (e.g., optodes, electrodes) from Eulerian and Lagrangian platforms (e.g., ships, moorings, profiling floats, gliders, ships of opportunities, marine mammals, cabled observatories). GO₂DAT will further adopt a community-agreed, fully documented metadata format and a consistent quality control (QC) procedure and quality flagging (QF) system. GO₂DAT will serve to support the development of advanced data analysis and biogeochemical models for improving our mapping, understanding and forecasting capabilities for ocean O₂ changes and deoxygenation trends. It will offer the opportunity to develop quality-controlled data synthesis products with unprecedented spatial (vertical and horizontal) and temporal (sub-seasonal to multi-decadal) resolution. These products will support model assessment, improvement and evaluation as well as the development of climate and ocean health indicators. They will further support the decision-making processes associated with the emerging blue economy, the conservation of marine resources and their associated ecosystem services and the development of management tools required by a diverse community of users (e.g., environmental agencies, aquaculture, and fishing sectors). A better knowledge base of the spatial and temporal variations of marine O₂ will improve our understanding of the ocean O₂ budget, and allow better quantification of the Earth's carbon and heat budgets. With the ever-increasing need to protect and sustainably manage ocean services, GO₂DAT will allow scientists to fully harness the increasing volumes of O₂ data already delivered by the expanding global ocean observing system and enable smooth incorporation of much higher quantities of data from autonomous platforms in the open ocean and coastal areas into comprehensive data products in the years to come. This paper aims at engaging the community (e.g., scientists, data managers, policy makers, service users) toward the development of GO₂DAT within the framework of the UN Global Ocean Oxygen Decade (GOOD) program recently endorsed by IOC-UNESCO. A roadmap toward GO₂DAT is proposed highlighting the efforts needed (e.g., in terms of human resources).

Keywords: oxygen, atlas, database, observing, mapping, data-products, open and coastal ocean, deoxygenation

INTRODUCTION

Current evidence indicates that the coastal (i.e., most directly influenced by land) and open ocean is losing oxygen (O₂) since the middle of the last century (**Figure 1**), with consequences for living organisms and biogeochemical cycles that are not yet fully understood (e.g., Keeling et al., 2010; Breitburg et al., 2018). In the open ocean the O₂ inventory has decreased by a few

percent (i.e., 0.5–3%) and the Oxygen Minimum Zones (OMZs) are expanding. Although observations and model simulations document a net decline of the global ocean O₂ inventory, there is disagreement among analyses (**Figure 2**) resulting in inconsistent regional estimates of the rate of O₂ loss (i.e., deoxygenation) (e.g., Oschlies et al., 2018). Uncertainties and differences between estimates could be attributable to the scarcity of accessible data, the use of different datasets (e.g., volume



and quality of data) and the employment of different mapping techniques and models.

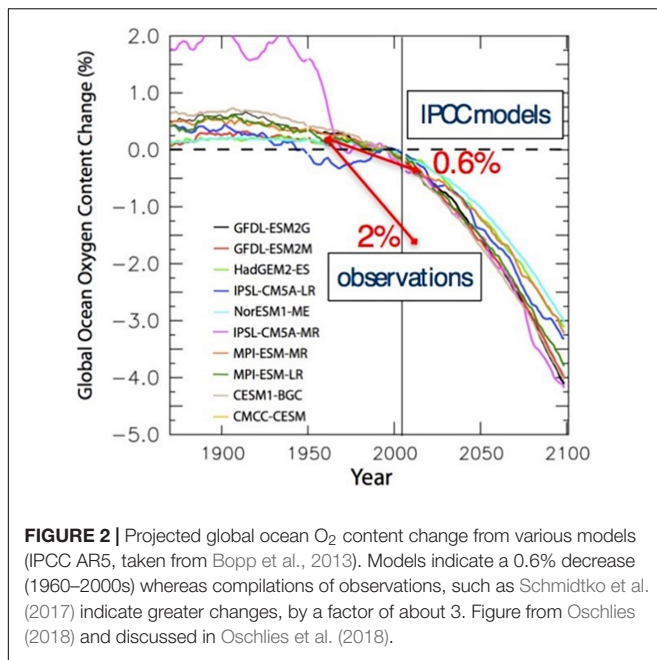
In the global coastal ocean, O₂ deficient zones are mostly intermittent features that essentially appear in the benthic boundary layer (BBL, i.e., the layer overlying the seabed where processes are influenced by the presence of the bottom) when the O₂ consumption by respiration outpaces the O₂ supply by ventilation and bottom photosynthesis (e.g., Pitcher et al., 2021). The number of coastal hypoxic sites has increased in response to worldwide eutrophication; yet a precise quantification of the O₂ trend in the global coastal zone is still debated. The availability of O₂ observations in international databases does not allow a comprehensive quantitative assessment of the severity of hypoxia (i.e., O₂ < 60 μmol kg⁻¹) at seasonal and interannual scales. This issue is particularly critical in regions with limited institutional infrastructure where the connection between National Oceanographic Data Centers (NODCs) and international oceanographic databases is not always well-established, or NODCs do not exist. Short-term (i.e., in terms of hours) and small-scale (i.e., in the BBL) variability and amplification of non-linearity in the coastal ocean require data of higher temporal and spatial resolution to characterize O₂ dynamics and events of depletion. The reference distribution of hypoxic sites assembled by Diaz and Rosenberg (2008) (Figure 1) highlighted for the first time the worldwide extent of the coastal hypoxia phenomenon. This effort has been valuable but could be updated and amended with the large volume of (sometimes disparate) quantitative information on coastal O₂ concentrations, including inventories of the frequency, timing, duration, intensity and spatial extension of the hypoxic events, and links to the original data contained in a globally accessible database. Tracking of the severity and evolution of coastal hypoxia requires access to

coherent observational O₂ datasets for the global coastal ocean that are amenable to global analysis.

Since the community white paper by Gruber et al. (2010) that called for the addition of O₂ sensors on Argo floats, the number of Argo O₂ profiles has increased considerably, up to 220,880 O₂ profiles as of June 8th 2021. Profiling biogeochemical (BGC) Argo floats provide unprecedented vertical (i.e., at least one order of magnitude larger than the 12–36 points offered by Niskin bottles) and temporal (~each 5–10 days) resolution and coverage at regional and global scales down to a depth of 2000 m. Currently ~10% of the active Argo floats (i.e., 396 over 3828 floats) have O₂ sensors¹. This percentage increases to more than 25% (i.e., 41 over 152 floats) when considering the Deep Argo floats only. This spurs initiatives like the GOOS strategy for BGC variables and the international BGC Argo program (Johnson and Claustre, 2016; Roemmich et al., 2019). This new program aims at operating a global array of 1000 BGC-floats that measure vertical profiles of all six core BGC and environmental variables including O₂. In this context, the U.S. National Science Foundation has recently decided to add 500 BGC floats (all measuring O₂) to the global Argo network in the next five years, and several other nations are increasing their contributions, which will boost the array to meet 50% of its target for global BGC sampling of the ocean.

The increasing number of observation platforms will improve our capabilities to monitor O₂ in the open ocean and would remedy the chronic lack of O₂ data compared to physical data for mapping and modeling marine systems. However, these several hundred thousand O₂ profiles collected by profiling floats and gliders are not currently incorporated in a global compilation of data. Current gridded products and assessment of climate trends

¹<https://fleetmonitoring.euro-argo.eu/dashboard>



(e.g., Garcia et al., 2005, 2013, 2019; Stramma et al., 2008; Lauvset et al., 2016; Schmidtko et al., 2017) are generally based on Winkler and CTD data. The lack of a community accepted data standard treatment (e.g., quality checks, adjustment procedures) and information to the users (e.g., quality flagging) across databases and platforms challenges the development of uniform-quality data-synthesis products that combine different data sources. The integration of sensor and Winkler data from different databases would offer the possibility to advance data-synthesis products at an increased resolution. It would also support the development of an O₂ gridded product for the global coastal ocean facilitating a regular assessment of the evolution of coastal hypoxia in a warming climate.

This paper aims at outlining the need, establishing and proposing a roadmap toward the building of a Global Ocean Oxygen Database and Atlas (GO₂DAT) for regional seas, coastal zones and open ocean. GO₂DAT will integrate O₂ data from both Eulerian and Lagrangian observations (i.e., Winkler titrations and O₂ sensor measurements performed on conductivity-temperature-depth-O₂ sondes, fixed moorings, autonomous platforms, and other emergent platforms). It will adopt a fully documented metadata format with traceable quality control (QC) procedures and assess uncertainty including quality flagging (QF), that will be agreed upon by the scientific community. The GO₂DAT concept is aligned with the principles of the Framework for Ocean Observing (FOO, UNESCO, 2012). GO₂DAT will comply with the FAIR² principles (Findable, Accessible, Interoperable, and Reusable, Wilkinson et al., 2016), be available free of charge and contribute to the motto “measure once-use many times.” GO₂DAT datasets and products are envisaged to support ocean research and societal needs and will be made available through a web-platform for scientific analysis,

²FAIR principles: <https://www.go-fair.org/fair-principles/>

decision making and education (Figure 3). In this paper, we aim at engaging the community (e.g., scientists, data managers, policy makers, service users) toward the development of GO₂DAT.

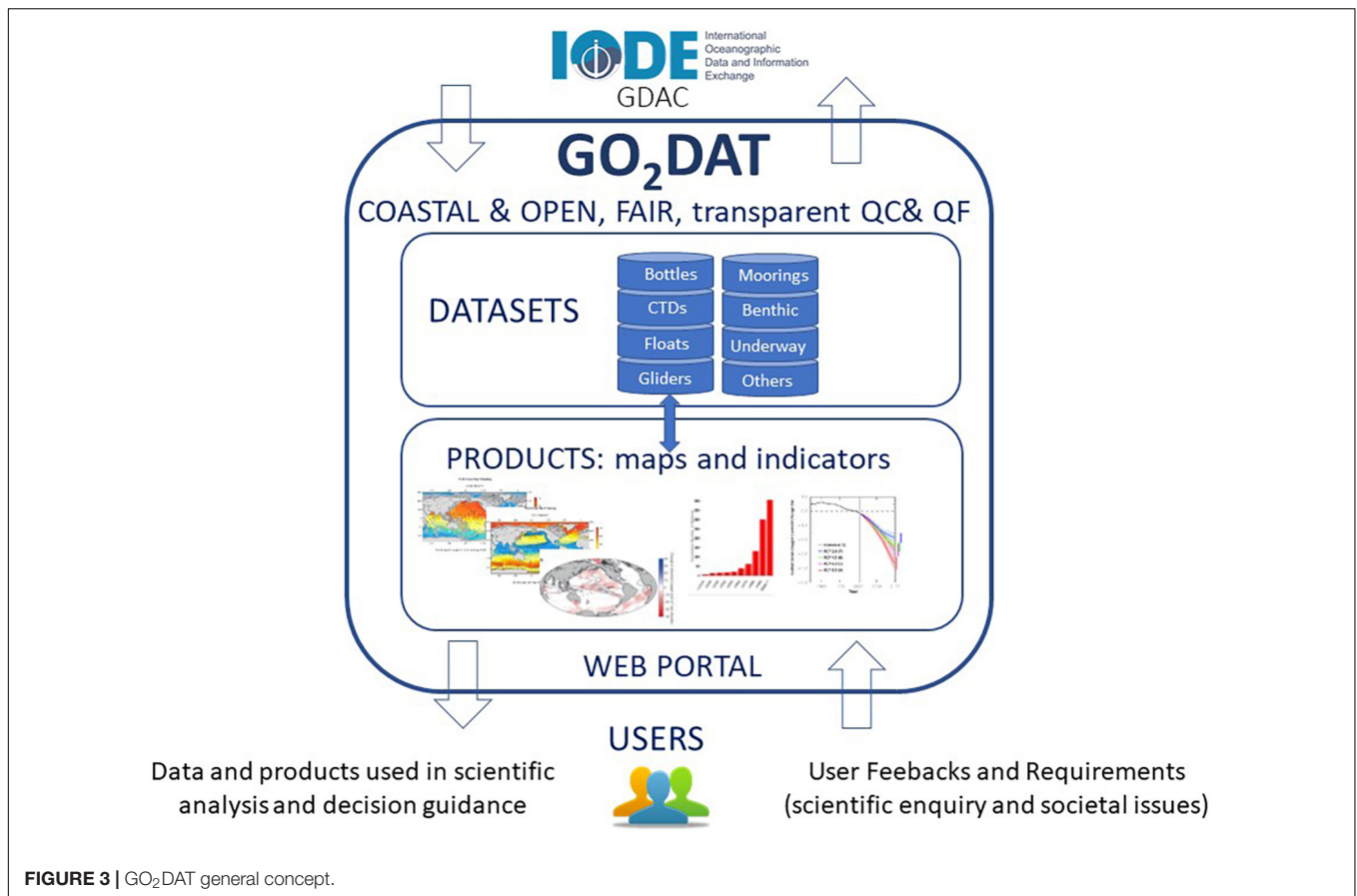
This paper is organized along the three pillars of the FOO value chain of O₂ data from requirement setting, through data collection to product delivery. We first demonstrate the need for GO₂DAT in support of scientific analyses and decision making and underline the requirements on the quality of O₂ data to assess O₂ state and variability. Next, we review the methodologies for observing ocean O₂ concentrations. The basic principles underlying the most used techniques to measure O₂, known technical challenges and possible solutions are described. For each observing platform, we synthesize the evolution of O₂ measurements, calibration procedures and the existence of Data Assembly Centers (DACs) that centralize data processing according to an established protocol vetted by the oceanography community. The adequacy of current O₂ data to assess variability at climate and weather scales and calibration procedures applied to collected O₂ data (i.e., post-calibration or second order calibration) are discussed. Finally, a roadmap for achieving GO₂DAT is presented.

SCIENTIFIC RATIONALE

Physical and Biogeochemical Controls of Ocean O₂ Dynamics

The dynamics of O₂ in the ocean is governed by both physical, biogeochemical and biological processes. The ocean gains O₂ in the upper layer (i.e., ~0–100 m) due to photosynthesis by autotrophic organisms and dissolution from the atmosphere in undersaturated waters near the surface. Conversely, O₂ is lost due to the diffusion of O₂ to the atmosphere in over-saturated surface waters, and from the respiration of aerobic organisms and oxidation of chemical species in the water column and sediments. The surface mixed layer is well oxygenated in most of the ocean, but below the sunlit surface layer, there is no photosynthesis and, the renewal of the O₂ consumed requires a physical mechanism (i.e., currents) that transports relatively well-oxygenated waters to regions of lower O₂. This mechanism, called ocean ventilation, is responsible for the oxygenation of the ocean interior and modifies the distribution of O₂ within the ocean. The distribution of O₂ in the ocean interior thus offers information on physical and biogeochemical mechanisms in the ocean. For instance, physical oceanographers investigate the circulation and mixing of water masses from its distribution (e.g., Körtzinger et al., 2004; Coppola et al., 2017; Racapé et al., 2019; Li and Tanhua, 2020; Ulses et al., 2021), marine biogeochemists infer the balance of biological and chemical processes from its variability (e.g., Emerson et al., 1997; Keeling and Manning, 2014; Resplandy et al., 2018) and the O₂ content is an indicator of ocean health.

In some subsurface regions where the renewal of O₂ by physical transport is low, the O₂ concentration can reach levels that are too low to support the survival of many aerobically respiring organisms. Organisms that are found in these areas can exhibit reduced growth and reproduction, avoidance, and, in extreme cases and for non-mobile species, experience low-O₂



induced mortality (e.g., Levin, 2003; Levin et al., 2009). In the open ocean, OMZs are mainly found in the Eastern boundary upwelling systems in the tropical Pacific and Atlantic, and in the northern Indian Ocean (**Figure 1**) and extend from ~100 to 1000 m (e.g., Helly and Levin, 2004; Paulmier and Ruiz-Pino, 2009). In these OMZs, the degradation of the organic material sinking from the surface takes place through denitrification leading to a consumption of fixed nitrogen and production of N₂ and potentially N₂O (**Figure 4**). Observational analysis and model results indicate that OMZs have expanded during recent decades (e.g., Stramma et al., 2012; Schmidtke et al., 2017).

O₂ dynamics in the coastal ocean can be highly variable over small spatial and temporal scales, from diel cycles with nighttime hypoxia developing in productive coastal systems (Tyler et al., 2009) to episodic events developing over days, to seasonal and multiannual scales (Rabalais et al., 2002; Conley et al., 2009; Carstensen and Conley, 2019). Coastal hypoxia occurs when O₂ consumption outpaces its supply, (e.g., during the period of stratification), driving concentrations below thresholds critical for living aerobic communities that cannot escape and have not developed adaptation process. Since the middle of the last century, the worldwide eutrophication³ process has increased the level of primary production in the coastal

zone, promoting bottom O₂ depletion with consequences for living marine communities (e.g., Conley et al., 2009; Rabalais et al., 2010; Yasuhara et al., 2012, 2017; Breitburg et al., 2018). Scientific papers and technical reports document the widespread occurrence of coastal hypoxia around the world (Diaz and Rosenberg, 2008; Breitburg et al., 2018; Pitcher et al., 2021), although some regions are still poorly investigated (Altieri et al., 2017).

Why Is a Global O₂ Database and Atlas Needed?

The need for a standardized, well-documented, high-quality, and comprehensive database integrating O₂ data and other environmental variables from multiple sources is growing rapidly with the increasing threat of ocean deoxygenation for marine ecosystems and delivery of their associated services to society.

The decision-making process aimed at sustaining a healthy, productive and resilient ocean as prioritized by international policies and initiatives (e.g., UN SDG 14, the EU MFSD, the UN Decade of Ocean Science for Sustainable Development) requires sound environmental mapping and modeling capabilities of known quality.

³The enrichment of water by nutrients causing an accelerated growth of algae and higher forms of plant life to produce undesirable disturbance to the balance of

organisms present in the water and to the quality of the water concerned (OSPAR definition).

TABLE 1 | Examples of stakeholders, international conventions, directives and programs that would benefit from GO₂DAT.

| International bodies | |
|------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------|
| CBD | Convention on Biological Diversity |
| EEA | European Environmental Agency |
| FAO | Food and Agriculture Organization of the United Nations |
| GOOS | Global Ocean Observing System |
| GESAMP | Group of Experts on the Scientific Aspects of Marine Environmental Protection |
| IMO | International Maritime Organization |
| IOC-UNESCO | Intergovernmental Oceanographic Commission of UNESCO |
| IOCCP | International Ocean Carbon Coordination Project |
| IPBES | Intergovernmental Science-Policy Platform on Biodiversity and Ecosystem Services |
| IPCC | Intergovernmental Panel on Climate Change |
| LTC-ISA | The Legal and Technical Commission of the International Seabed Authority |
| RFMO | Regional Fisheries Management Organizations and advisory bodies |
| WMO | World Meteorological Organization |
| International conventions, directives | |
| EU MSFD | EUropean Marine Strategy Framework Directive |
| UNCLOS-BBNJ | United Nations Convention on the Law of the Sea for marine Biodiversity of areas Beyond National Jurisdiction |
| UNFCCC | United Nations Framework Convention on Climate change |
| International programs, projects, networks and initiatives | |
| CMEMS | Copernicus Marine Environment and Monitoring Service |
| DOSI | Deep-Ocean Stewardship Initiative |
| EMODnet | European Marine Observation and Data Network |
| GLODAP | Global Ocean Data Analysis Project |
| GOOD | Global Ocean Oxygen Decade |
| IMBeR | Integrated Marine Biosphere Research |
| IODE | International Oceanographic Data and Information Exchange program |
| SOLAS | Surface Ocean Lower Atmosphere Study |
| UN Decade | UN Decade of Ocean Science for Sustainable Development |

A Clean Ocean

Increasingly, O₂ factors into management-related analyses of ecological responses to nutrient inputs into coastal zones (Rabalais et al., 2007a; Kemp et al., 2009), ensuring sustainable fisheries (Breitburg et al., 2009; Dulvy et al., 2011; Eero et al., 2015; Rabalais, 2015), ocean management under climate change (Queirós et al., 2016; Lu et al., 2018; Levin et al., 2020), and as indicators of the progress of large-scale restoration efforts (e.g., Rabalais et al., 2010; Andersen et al., 2011; Zhang et al., 2018). Tomasetti and Gobler (2020) argue that environmental regulations and water quality standards have not kept pace with the rising importance and increasing scientific understanding of coastal hypoxia and acidification. Although some coastal zones are well characterized, many are not; for example, it has been found that corals in the tropics may be at risk from both warming, eutrophication and hypoxia (Altieri et al., 2017; Hughes et al., 2020).

A Healthy and Resilient Ocean

The O₂ content is an indicator of ocean health. The development and extension of low O₂ areas degrade the living conditions and vertically contract the metabolically viable habitat for a large number of pelagic, mesopelagic, and benthic organisms. At 100% saturation, the amount of O₂ available in one liter of water is ~35 times less than that in an equivalent volume of air. The effects on individuals exposed to low O₂ can cascade and result in altered foodweb structure, including the diversion of organic matter flow to low O₂ tolerant species like microbes (Breitburg et al., 2018). O₂ data are important for assessing the habitat quality of many organisms within the coastal-shelf-open ocean environments. Examples include field-based determination of effects of O₂ on zooplankton (Wishner et al., 2018; Roman et al., 2019), benthos (Levin, 2003; Rabalais et al., 2007b; Levin et al., 2009; Yasuhara et al., 2012, 2017; Gammal et al., 2017), fish and shellfish (Keister et al., 2000; Breitburg, 2002; Pollock et al., 2007; Thomas and Rahman, 2010; Keller et al., 2017; Limburg and Casini, 2019; Roman et al., 2019), deep-sea coral along seamounts (e.g., Anderson et al., 2016), and fish habitat (e.g., Stramma et al., 2012; Sánchez-Velasco et al., 2019; Gallo et al., 2020). The effects of low O₂ on the physiological conditions of organisms have been investigated in many laboratory and field studies (e.g., Vaquer-Sunyer and Duarte, 2008; Wu, 2009; Neilan and Rose, 2014; Limburg and Casini, 2018, 2019) and are summarized by the metabolic index (ability to meet temperature-dependent O₂ demands) and related indices (P_{crit}) for species in a variety of systems (Chu and Gale, 2017; Deutsch et al., 2020; Howard et al., 2020; Seibel et al., 2021). The tight link between thermal tolerance (TT) and O₂ and capacity limitation (OCL) is proposed to govern body size, species biogeographical range distributions and their response to climate change (Pörtner, 2021).

A Productive Ocean

Evidence is growing that O₂ is an important driver of fish population and food web dynamics (Noone et al., 2013; de Mutsert et al., 2017; Townhill et al., 2017; Cheung, 2018; Rose et al., 2018) and its relationship with fishing activities (vessels and fishers) has been documented for multiple fisheries (Druon et al., 2017; Keller et al., 2017; Purcell et al., 2017). Understanding O₂ conditions in the current and future climate has important consequences for management decisions in fisheries and other sectors. For example, Asch et al. (2018) used a habitat-based approach and showed that maximum catch potential under climate change (2100 under business-as-usual RCP 8.5 scenario), which included a decrease in O₂ concentrations, would be reduced by more than 50% in some areas for the Pacific Island countries and territories. Rose et al. (2019) recently reviewed, using case studies, how low O₂ in coastal systems and OMZs can affect the modeling analyses used to inform fisheries management decisions; situations arise that result in decisions (management advice) that likely underestimate the risk of overfishing.

Beyond fisheries, climate-sensitive industries such as aquaculture and tourism may rely on O₂ data for a historical perspective, for spatial planning, and potentially for the provision of an early warning. Management of living resources and tourism can benefit from improved hypoxia modeling, understanding

changes in habitat quality, links to HABs, and resilience. The same is true for environmental management of ocean industries extracting non-living resources such as minerals or oil (Levin et al., 2020).

A Predicted Ocean

A challenge going forward is the use of O₂ data to understand and mitigate climate risks. This will involve cross-system comparisons and extensive development and testing of biogeochemical models. Presently, O₂ data are used to provide inventories, budgets, and spatio-temporal trends analyses (Fennel and Testa, 2019; Mavropoulou et al., 2020) on regional (Long et al., 2016; Coppola et al., 2017; Levin, 2018; Sasano et al., 2018; Savchuk, 2018) and global scales (Beaty et al., 2017; Schmidtko et al., 2017; Claustre et al., 2020).

O₂ data are frequently used to calibrate, validate, initialize and force regional (Montes et al., 2014; Vergara et al., 2016; Duteil et al., 2018) and earth system (global) models (Ridgwell et al., 2007; Andrews et al., 2017; Kriest et al., 2017; Oschlies et al., 2018). O₂, along with other water quality variables, has been incorporated into data assimilation (Dickey, 2003; Brasseur et al., 2009) to improve the forecasting skill of biogeochemical, water quality, and nutrient-phytoplankton-zooplankton models (Pastres et al., 2003; Gharamti et al., 2017). Further analyses and model development to project future ocean O₂ content and distribution in the open and coastal ocean will be greatly enhanced by the development of GO₂DAT that will offer a high-quality reference dataset for constraining formulation, parameterization, assimilation and validation of models.

A Safe Ocean

GO₂DAT will offer the information to support a better understanding and forecasting of hypoxic and anoxic events, which in the extreme cases are hazards to human health. Deoxygenation can lead to the production of H₂S, a toxic gas that can eventually escape to the atmosphere, and consumption of spoiled seafood killed by low-oxygen events can lead to illness in people dependent on these resources for health and livelihoods.

An Accessible Ocean

With some exceptions such as the World Ocean Database (WOD, Boyer et al., 2018), GLODAP (Global Ocean Data Analysis Project, Key et al., 2004; Olsen et al., 2016, 2020), the Copernicus Marine Environment and Monitoring Service (CMEMS) and the European Marine Observation and Data Network (EMODnet) – Chemistry (Vinci et al., 2017; Martín Míguez et al., 2019), a large portion of observational O₂ data are not openly accessible, nor are they usable online without restrictions and with well-documented uncertainty estimates. For this reason, most analyses of O₂ data use only a subset of all that are available and the quality and quantity of the data vary across analyses. Each system has multiple case studies that use different, often independent O₂ datasets, making cross-systems analyses a challenge. In some cases, published information (rather than the underlying data) has been used to characterize O₂ conditions in coastal and ocean areas (Diaz and Rosenberg, 2008; Gilbert et al., 2010; Levin, 2018). Additionally, to improve the overall quality of individual datasets,

researchers often perform empirical adjustments (e.g., data bias adjustments) and specific quality control procedures that are often not described in detail. Transparency of quality control protocols and resulting adjustments is paramount in order to achieve reproducibility of data analyses (e.g., trend estimate) and reusability for data synthesis. It is difficult to replicate independently the findings of most studies that assess the trend of ocean O₂ content based on observations. The GO₂DAT will offer a single unified database to enable more rigorous and comparative analyses, and better integration of results across studies within a system and across systems.

An Inspiring and Engaging Ocean

GO₂DAT can also support educational activities from K-12 through to underpinning Ph.D. theses, provide a resource for journalists and other communication media, facilitate capacity building and provide a foundation for technology transfer. GO₂DAT will contribute to the building of a digital twin of the ocean for O₂ making available to a wide variety of stakeholders a quality control information on ocean O₂ in the three space directions and in time.

Quality Requirements of O₂ Data to Assess Mean State, Weather and Climate Variability

The required accuracy (i.e., the difference between the measurement and a true value, the Certified Reference Material, CRMs, which is not directly defined for O₂ but indirectly through e.g., Winkler, atmospheric pO₂) and precision (i.e., the repeatability between measurements of a same sample) of the O₂ measurements differ depending on the scientific questions to be answered, and the signal amplitude to be detected which varies from a few tenths up to a few $\mu\text{mol kg}^{-1}$ for the climate and weather changes, respectively (Table 2). Quantifying global ocean deoxygenation trend (i.e., $0.075 \mu\text{mol kg}^{-1} \text{yr}^{-1}$ or $\sim 4.5 \mu\text{mol kg}^{-1}$ over the last 60 years) imposes stringent requirements on the quality of the data, while for estimating the typical O₂ levels in a region or the occurrence of hypoxia, even far less accurate data can be of scientific value (e.g., accuracy better than $5 \mu\text{mol kg}^{-1}$).

The quantification of the Net Community Production (i.e., NCP, the net difference between community photosynthesis and respiration) from the high frequency variation of O₂ is very sensitive to the presence of bias and noise in the data. A 0.5% ($\approx 1 \mu\text{mol kg}^{-1}$) error in O₂ measurements significantly degrades the quality of the retrieved NCP (Emerson et al., 2008; Soetaert and Grégoire, 2011). In OMZs, because, nanomolar levels O₂ inhibit denitrification and anaerobic ammonium oxidation, studies of these processes require sensors with detection limits of a few nanomoles (Tiano et al., 2014).

For ecological analyses, the required data quality depends on the specific organisms, biological processes, and questions (hypotheses) being addressed. Common topics include detecting, and if possible, quantifying, the O₂ effects on individual organisms in terms of: (1) presence, absence or abundance, (2) energetics-related physiology, and (3) behavior and vital process

TABLE 2 | Examples of scientific topics, characteristics of the signal, recommended quality, applications.

| Scientific topics | Signal characteristics to capture | Recommended quality of O ₂ measurement | Applications |
|--------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------|
| Mean state determination | | | |
| Order of magnitude of the O ₂ content Gridded fields Coastal hypoxic area | 227.4 ± 1.1 petamoles (10 ¹⁵ mol) ⁽¹⁾ | Accuracy better than 5 μmol kg ⁻¹ | Model initialization, validation |
| OMZs (O ₂ < 45 μmol kg ⁻¹) Extension, Oxycline | High vertical gradient, up to 20 μmol kg ⁻¹ m ⁻¹ ⁽³⁾ | High ratio of the sampling frequency over the response time (a few sec) and/or low vertical sampling velocity ⁽⁴⁾ | Ocean health, environmental Management Ocean health |
| AMZs (O ₂ < a few nmol kg ⁻¹) Extension | Detection of zero value | Zero detection a few nmol kg ⁻¹ ⁽³⁾ | Global denitrification, model parameterization in anoxic conditions |
| Climate variability | | | |
| Global ocean deoxygenation trend | Global decrease: 4.38 ± 1.98 μmol kg ⁻¹ since 1960 ⁽¹⁾ | Accuracy better than 0.5 μmol kg ⁻¹ | Climate application Carbon budget |
| Weather variability | | | |
| Air-Sea seasonal fluxes | Open ocean 5–10 μmol kg ⁻¹ in oligotrophic waters, up to 37.5 μmol kg ⁻¹ for well-mixed regions ⁽⁵⁾ . Coastal vegetated ecosystem 37.5–50 μmol kg ⁻¹ ⁽⁶⁾ . | Accuracy: ~1–5 μmol kg ⁻¹ Precision: ~ 1–5 μmol kg ⁻¹ | |
| Processes estimation | | | |
| Net Community Production | Open ocean: from 1 to 6 molO ₂ m ⁻² yr ⁻¹ ⁽⁵⁾ . Coastal vegetated ecosystem: 23.2 ± 8.2 molO ₂ m ⁻² yr ⁻¹ ⁽⁶⁾ . | Very sensitive to the presence of noise (e.g., an error of 0.5% degrades the estimation of the rate) ^(7,8) . Smoothing is recommended. | Understanding ocean physical and biogeochemical functioning |
| Ventilation/convection | > 20 mol m ⁻² yr ⁻¹ (during the months of convection) ^(9,10) | Deep waters: 1–2 μmol kg ⁻¹ Intermediate waters: few μmol kg ⁻¹ | |

Recommended quality of O₂ measurement is done through either referring to existing studies or considering that the measurement's accuracy should be better than 1% of the expected signal. (1) Schmidtko et al., 2017; (2) 1% of saturation; (3) Tiano et al., 2014; (4) Bittig et al., 2014; (5) Emerson et al., 2008; (6) Champenois and Borges, 2019; (7) Emerson et al., 2008; (8) Soetaert and Grégoire, 2011; (9) Körtzinger et al., 2004; (10) Coppola et al., 2017.

rates of growth, mortality, and reproduction (Batiuk et al., 2009). Analyses are also performed to quantify O₂ effects on groups of individuals, such as spatial distributions, and on scaled-up responses, such as population-level (reduced annual abundance), community (e.g., diversity), and food web (e.g., changes in predator-prey interactions) (Wu, 2002). In some cases, very high precision and accuracy will be needed because responses are ultra-sensitive to small changes in O₂ concentrations (Wishner et al., 2018), while in other situations precision and accuracy can be relatively low because the taxa or responses of interest show low sensitivity to variation or the O₂ concentrations themselves vary greatly across the comparisons.

METHODOLOGY FOR O₂ OBSERVATION

Methods for Measuring O₂

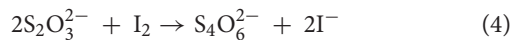
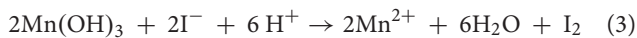
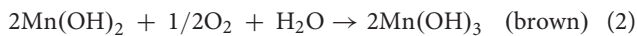
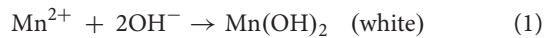
There are three major methods used for determining the amount of O₂ in seawater. These are (a) the iodometric titration (the

so-called Winkler titration); (b) electrochemical approaches (e.g., potentiometry, amperometry); and (c) optical (fluorescence quenching) sensors method. Each method has its specific merits, applications and quality.

Iodometric Methods: Winkler Titration

Winkler titration (Winkler, 1888) is a reference method used for 140 years to measure O₂. Winkler O₂ determination during oceanographic cruises requires a discrete sample commonly collected from a Niskin bottle into a glass bottle (Winkler bottle). The Winkler chemical titration is based on the oxidation of Mn(II) by O₂ in alkaline conditions (Equations 1 and 2) and the reaction of the precipitated Mn(III) with iodide in acidic conditions to form iodine and tri-iodine in a second step (Equation 3). The lumped amount of iodine and tri-iodine is quantified by a titration with thiosulfate (Equation 4; Carpenter, 1965; Langdon, 2010) or spectrophotometrically (Labasque et al., 2004) and from that the concentration of O₂ is determined. The Winkler O₂ measurement is a commonly used reference to

calibrate the data provided by O₂ sensors.



Sensors

The electrochemical and optical methods for measuring O₂ are simple, fast and automated. They are now widely used on platforms such as CTD-O₂ rosette samplers, autonomous platforms (e.g., floats, gliders), drifting buoys and fixed-point moorings. Their use on autonomous platforms offers continuous monitoring of O₂ in space and time throughout the ocean. The number of sensor-based O₂ measurements in the water column collected in the past decade alone is now comparable to the Winkler O₂ data collected since 1900 (Figure 5).

Electrochemical Sensors

Electrochemical detection is the most widely used method, within which the polarographic O₂ sensor is the most common application (see the review by Wei et al., 2019). The working principle of polarographic sensors is based on the measurement of a current that is proportional to the rate of O₂ diffusing through a permeable membrane and being reduced on a metal surface. In Clark-type O₂ sensors (Clark et al., 1953), the O₂ diffuses through the membrane and dissolves in the electrolyte before reacting with the cathode. The amount of O₂ that diffuses through the membrane depends on the external O₂ partial pressure (pO₂) (Glud et al., 2000). At the cathode, O₂ is reduced

and gives an electric signal that depends on the amount of O₂. This implies that the sensor signal is dependent on the transport of the analyte from the surrounding medium, the so-called stirring sensitivity (Glud et al., 2000). A robust conversion of the electric signal into a pO₂ requires a steady flux of O₂ into the sensor tip. If there is no steady-state O₂ diffusion across the membrane and cathode, the conversion is not robust. There is thus a trade-off between the sensor's stirring sensitivity and its response time: sensors with a high stirring sensitivity have short response time but the O₂ flux is much more variable. Low stirring sensitivity microsensors can be constructed while macro-sensors are more affected by this effect.

The modifications of Clark-type O₂ microsensors led to the development of the STOX (Switchable Trace amount OXYgen) sensor, based on Clark-type microsensors, where O₂ can be determined at low (nM) concentrations (Revsbech et al., 2009). The small dimensions of the tip in O₂ microsensors make them able to achieve response times of 0.1 s and are thus recommended for high-resolution measurements. However, O₂ microsensors are more affected by aging and sensitive to drifts than macrosensors due to their reduced quantity of electrolytes and the smaller size of their cathodes.

Optical Sensors

Optical O₂ sensors (optodes) have become attractive in the past four decades because there is no O₂ consumed during the measurement (i.e., no stirring sensitivity as with polarographic sensors), they offer good precision and accuracy and they can measure O₂ in both gas and liquid phase. Bittig et al. (2018, 2019) provide a thorough review of the most widely used optodes. Optical O₂ sensors used in oceanography are mostly

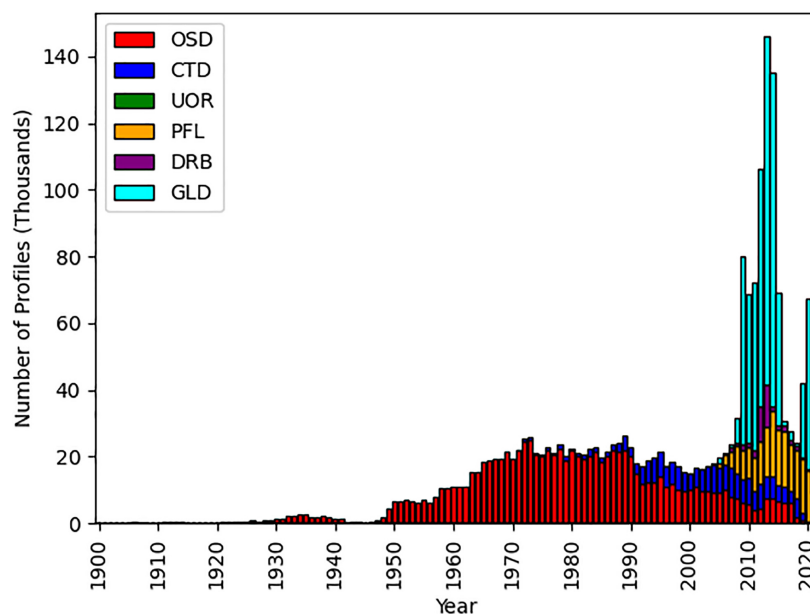


FIGURE 5 | Number of dissolved O₂ profiles available in the WOD 2018 (WOD18, Boyer et al., 2018) by observing system/instrument. OSD: chemical Winkler data from shipboard bottle Ocean Station Data; CTD, sensor data from Conductivity-Temperature-Depth-Oxygen (~200 000 profiles); PFL, Profiling Float data (~160 000 profiles); DRB, Drifting Buoy Data (~40 000 profiles); GLD, GLider Data (~450 000 profiles); UOR, Undulating Oceanographic Recorder (~360 profiles).

based on the principle of luminescence quenching (Lakowicz, 2006). A luminescent substance is embedded in a sensing foil or coating and placed on an optical window. The sensing foil of the optode is permeable only to gases, i.e., the sensors respond to the gases' partial pressure, in this case pO_2 . By modification of the luminescent substance, oxygen optodes can be used to measure trace amounts of oxygen down to a detection limit of 0.5 nM (Lehner et al., 2015), though only available so far for laboratory measurements.

Platforms

We provide an overview of the Eulerian and Lagrangian platforms from which O_2 is measured using the Winkler titration method or optical and electrochemical sensors. **Table 3** provides a synthesis, for each O_2 observing platform, of information on the existence of best practices documents, a DAC that centralizes data processing, community-agreed calibration, correction (secondary QC) and QF as well as level of accessibility, in particular, in Real Time (RT) and Delayed Mode (DM) mode. This across platforms analysis allows to understand how the different platforms are currently organized in terms of calibration, QC and QF and can be coordinated toward the building of GO₂DAT.

Ship-Based CTD- O_2 Observations

Over the past decades, there have been significant advancements in O_2 sensor instrumentation mounted on CTD rosette samplers (e.g., Wang et al., 2019) and probes. Historically, polarographic sensors were used on ship-based CTDs while now optical sensors are also used. The polarographic sensors used on CTD casts are mostly based on the Clark-type polarographic membrane-covered electrodes. In order to avoid the stirring effect (Gust et al., 1987) without compromising the time response of the sensors in rosette samplers, an external water pump supplying a constant water flow to the sensor is used in the standard CTD configurations. In areas with sharp O_2 gradients such as in OMZs and low O_2 coastal waters the cast speed should be adjusted to adequately sample the oxycline.

Irrespective of present-day O_2 sensor type, calibration at sea or in delayed mode of O_2 sensors is often performed using simultaneous water sampling at one or preferably more selected depths (e.g., at all the Niskin sampling depths) together with routine O_2 analysis using Winkler titrations (Langdon, 2010; Uchida et al., 2010). This calibration is particularly important in oceanic regions with large spatial O_2 concentration gradients. International research programs such as the World Ocean Circulation Experiment (WOCE), Climate and Ocean:

TABLE 3 | Characteristics of the last generation of ocean O_2 observing systems: (1) Bittig and Körtzinger, 2015; (2) Thierry et al., 2018; (3) Thierry and Bittig, 2018; (4) Bittig et al., 2019; (5) BGC-Argo data are freely available from the Global Data Assembly Centres (GDACs: <ftp://ftp.ifremer.fr/ifremer/argo/> and <ftp://usgoda.gov/pub/outgoing/argo/>); (6) Testor et al., 2019; (7) oceangliders (<https://www.oceangliders.org/>); (8) Uchida et al., 2010; (9) WOCE and GO-SHIP protocols; (10) WOCE and GO-SHIP data are freely available on CLIVAR and Carbon Hydrographic Data Office; (11) Coppola et al., 2016; (12) Best Practices EMSO/OceanSites (OBPS); (13) National Data Buoy Center (NDBC) in the United States and Coriolis at IFREMER; (14) in delayed mode (see GO-SHIP method); (15) under development; (16) based on Winkler or 100%-0% calibration of sensors; (17) no DAC but Stratmann et al., 2019.

| Observing platform | Methods | Spatial and temporal scales resolved | Spatial and temporal coverage | Community-agreed calibration and best practices | Community-agreed QF | Secondary community-agreed correction | GDAC | (N)RT/DM FAIR | |
|--------------------------------------|------------------------|-------------------------------------------------------------------------------------|------------------------------------------------------|-------------------------------------------------|----------------------|--------------------------------------------|---------------------|---------------|-----|
| Profiling floats | Sensors | Horizontal: 10–10 ² km Vertical: 10 ⁻³ km 5–10 days | 10 ² –10 ³ km 3–5 years | With the atmosphere ⁽¹⁾ | Yes ^(2,3) | Yes <i>In situ</i> Drift ⁽⁴⁾ | Yes ⁽⁵⁾ | NRT and DM | Yes |
| Gliders | Sensors | Horizontal: 10 ⁻¹ –1 km Vertical: 10 ⁻³ km Hourly-daily | 1–10 ² km Several days-weeks | In progress ⁽⁶⁾ | No | No | Yes ⁽⁷⁾ | NRT and DM | Yes |
| Ship-based Repeat Hydrography | Winkler + Sensors | Horizontal: 10 km Vertical: 10 ⁻³ km Decadal | 10 ² –10 ³ km Multi-decadal | At sea or in delayed mode using Winkler | Yes ⁽⁸⁾ | Yes ⁽⁹⁾ | Yes ⁽¹⁰⁾ | DM | Yes |
| Moored fixed point observatories | Mainly optical sensors | Hourly | Multi-year | Yes ⁽¹¹⁾ | Yes ⁽¹²⁾ | No | Yes ⁽¹³⁾ | NRT & DM | No |
| Ship-based Fixed-point Observatories | Winkler + Sensors | Monthly | Multi-year | No ⁽¹⁴⁾ | Yes ⁽⁸⁾ | Yes | Yes ⁽¹⁰⁾ | DM | Yes |
| Ship-based underway observations | Optical sensors | Sub-weekly to monthly | 10–10 ² km | No ⁽¹⁵⁾ | No | No | No | DM | No |
| Coastal/benthic | Winkler + Sensors | Vertical: 10 ⁻⁵ –10 ⁻⁴ km Temporal: punctual | 10–10 ² km | Yes ⁽¹⁶⁾ | No | No | No ⁽¹⁷⁾ | DM | No |

Table adapted from the Global Ocean Observing System (GOOS) Panel-Biogeochemistry-01-EOV-Oxygen Essential Ocean Variables (EOV) version 2.0 (August, 2017) see here https://www.jcomm.info/index.php?option=com_oe&task=viewDoclistRecord&doclistID=168.

Variability, Predictability and Change (CLIVAR) and Global Ocean Ship-based Hydrographic Investigations Program (GO-SHIP) adopt the precision of the “best-laboratory” O₂ data. For example, WOCE and GO-SHIP adopted an O₂ target precision of 0.08% ($\sim \pm 0.2 \mu\text{mol kg}^{-1}$) of the highest concentration found in the ocean (Joyce, 1991; Hood et al., 2010).

Biogeochemical Argo

O₂ was the first BGC variable to be measured by Argo (Körtzinger et al., 2004; Gruber et al., 2010) and continues to be the most common BGC variable measured. **Figure 6** illustrates how Argo floats can be used to investigate the mesoscale O₂ dynamics at the oxic-anoxic transitional layer in the Black Sea where the O₂ level varies from saturation to zero.

Since 2002, BGC Argo floats have been equipped with different categories of O₂ sensors (electrochemical, optical, multipoint-calibrated, air-calibrated). **Table A1** in Appendix summarizes information on the types of sensors used, known issues, adjustments performed and data streams. BGC-Argo has two data streams: “RT” and “DM.” The RT stream, targeted at operational users, is subject to automated, RT QC (e.g., automated search for outliers) and may receive an automated, initial adjustment (“A” data). The DM stream, targeted at science users, provides the best quality data.

Some floats include regular in-air measurements as recommended by the SCOR WG 142 (Bittig et al., 2015). This provides an accurate (i.e., 1%), easily accessible reference for correction (Bittig and Körtzinger, 2015; Johnson et al., 2015; Bushinsky et al., 2016) of the drift between manufacturer calibration and deployment (Johnson et al., 2017; Bittig et al., 2018). For older floats where in-air measurements were not performed, such data can be mimicked by using the WOA

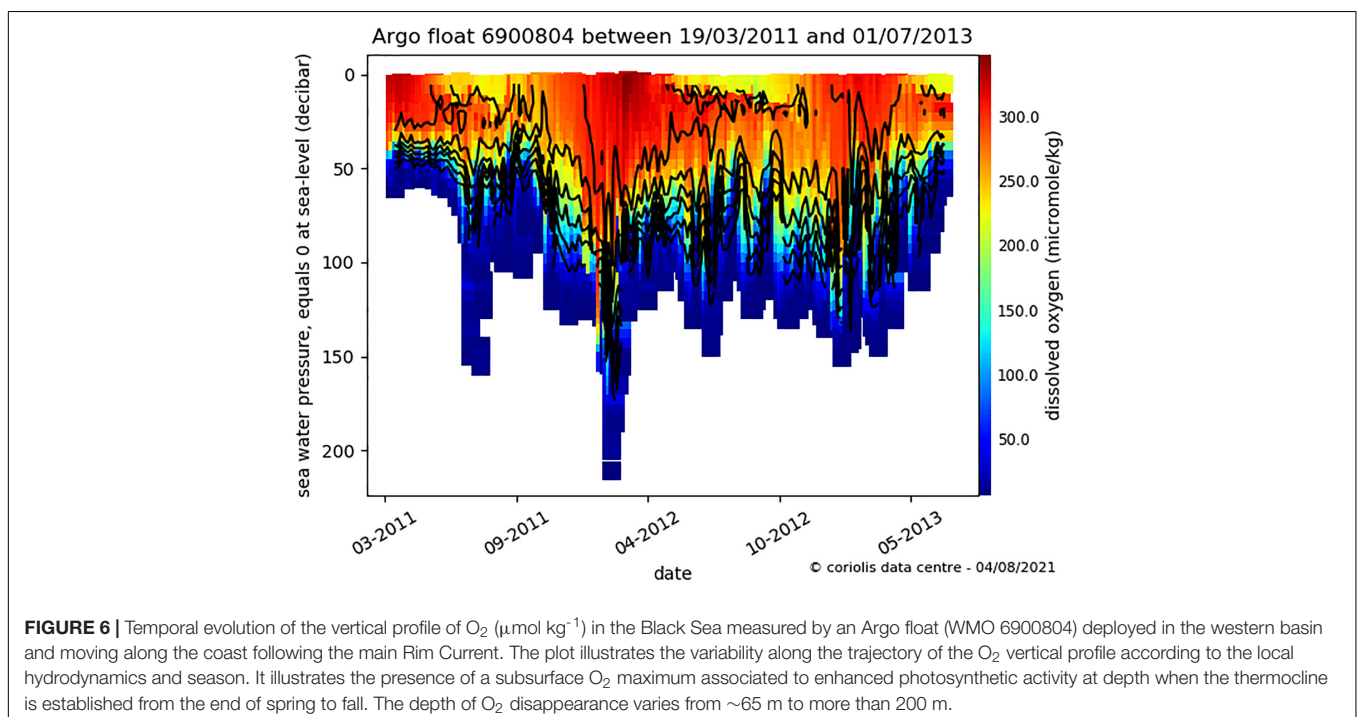
surface O₂ saturation field and converting O₂ saturation to surface partial pressure (pO₂) using the float’s temperature and salinity (Thierry and Bittig, 2018).

When available, a laboratory calibration using standard O₂ water (Winkler) before the launching of the float and corrections based on frequent ship observations after the float launching can be used to check the accuracy of measurements. If multiple check and correction methods are available before and after launching Argo O₂ floats, the integrated calibration procedure will be useful to assess and improve accuracies for the O₂ and the long-term drift of O₂ values.

Gliders

Underwater gliders may be thought of as profiling floats that are able to control their horizontal position (Rudnick, 2016a). This control over position makes gliders especially useful for regional oceanography, complementing the global footprint of Argo. The same suite of sensors as in floats is used, including Aanderaa O₂ optodes (Nicholson et al., 2008; Adams et al., 2016), and Sea-Bird SBE 43 (Ohman et al., 2013) and 63 (Takeshita et al., 2021). Gliders are used to investigate the (sub)mesoscale O₂ variability (**Figure 7**).

Because gliders are deployed and recovered, there is opportunity for pre- and post-mission laboratory calibrations and drift correction. In some applications of Sea-Bird instruments, the sensor is plumbed in line with the CTD, taking advantage of a constant flow and the presence of tributyltin antifouling measures. The requirement for plumbing in this case and the need to minimize drag on gliders make it challenging to measure in air for *in situ* calibration. However, Nicholson and Feen (2017) used a mount forward of a glider’s tail fin to achieve this calibration at sea using an Aanderaa optode.



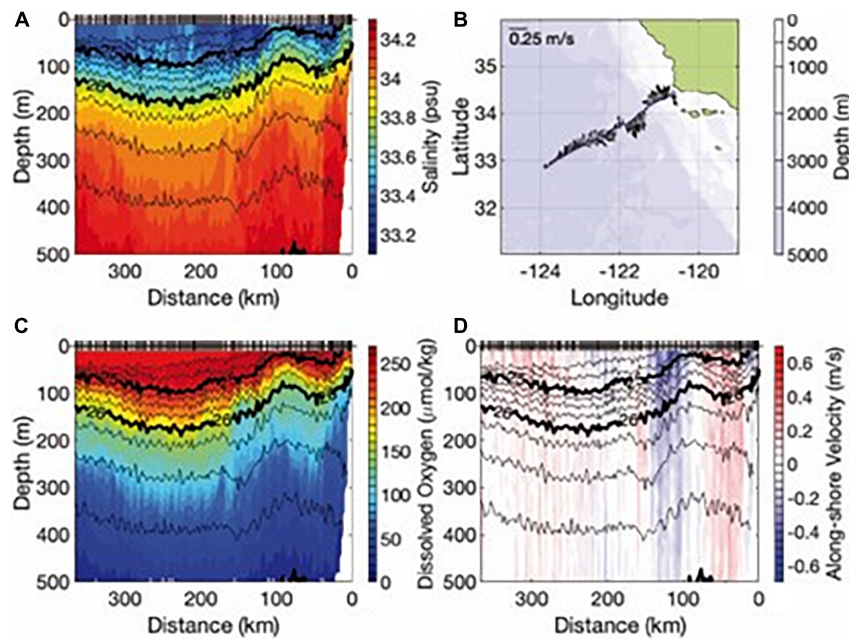


FIGURE 7 | Data from the California Underwater Glider Network (Rudnick, 2016b; Rudnick et al., 2017). Shown are (B) the track and 500-m depth average velocity, and sections of (A) salinity, (C) dissolved O₂, and (D) alongshore velocity. Nearshore upwelling brings dense low O₂ water to the surface. Further offshore a strong cyclonic feature has upward doming isopycnals with associated high salinity and low O₂. The separation between glider profiles is 3 km allowing resolution of these structures with sizes of tens of kilometers.

The OceanGliders program (Testor et al., 2019) provides an international umbrella in GOOS for ocean observations using underwater gliders. In common with many regional observing assets, the support for glider programs usually comes from the countries where the observations are undertaken. For this reason, the international glider data system is not as advanced as other more mature programs like Argo. Data management is accomplished through regional DAC, with established centers in the United States, Australia, and Europe. An ongoing initiative is to coalesce around a single international underwater glider data format. This format, which will be compliant with Climate Forecasting conventions, is likely to be adopted within the next 2 years.

Moorings

Although any type of O₂ sensor can be used on fixed-point mooring systems, optical sensors are more common due to their long-term stability compared to electrochemical sensors. In general, the response time of optical sensors is slower than that of electrochemical sensors; however, the effect of slow response time is reduced on fixed-point mooring systems as the surrounding environment (O₂ concentration, temperature and pressure) does not change rapidly. But, if O₂ sensors with slow response times are used on moored profilers, data quality may be reduced particularly in environments with strong vertical gradients.

Drift in O₂ measurements over time is the main issue for long-term deployments (e.g., 1-year). The drift is principally due to: (1) degradation, (2) marine biofouling, and (3) time-dependent pressure hysteresis of the sensing element (only on

very deep moorings >1000 m). In particular, biofouling may rapidly degrade the quality of O₂ and CTD data collected at shallow depths (<200 m).

Due to the efforts of the FIXEd-point Open Ocean Observatories (FIXO³) and European Multidisciplinary Seafloor and Water-Column Observatory (EMSO) European Research Infrastructure Consortium (ERIC) communities some recommendations have been proposed as best practices for O₂ sensors installed on fixed moorings (Coppola et al., 2016). The recommendations include conducting an intercomparison at sea with Winkler data after mooring line recovery. This intercomparison allows O₂ data from the mooring to be adjusted using slope and offset coefficients.

Benthic Platforms

Numerous benthic O₂ measurements have been performed over the last 40 years. They were generally based on single sampling or deployments in the water column and sediment conducted during cruises (Tengberg et al., 1995). Benthic observation platforms were originally based on landers which carry instrumentation for measuring exchange fluxes between the sediment and the water column by benthic chambers or O₂ distribution in sediment porewaters using micro-electrodes. The basic principle of these benthic chambers is the enclosure of a known surface area of sediment and its incubation over a short time to estimate exchange fluxes (Jahnke and Christiansen, 1989; Tengberg et al., 1995; Berelson et al., 2019). O₂ concentration measurements in the benthic chambers are nowadays mostly based on optode measurements in the chamber (see Hall et al.,

2017; Staudinger et al., 2018). These exchange fluxes offer a unique method to describe the metabolic activity in sediments.

Observation of O₂ in BBL and sediments was achieved by measuring O₂ distribution across the water-sediment interface using *in situ* microsensors (Tengberg et al., 1995; Wenzhöfer and Glud, 2002; Glud, 2008; Cathalot et al., 2010). The microsensors measured O₂ concentration in the BBL as a forcing variable or external control, but very few measurement campaigns were dedicated to the measurement of O₂ in the BBL except specific instruments such as the benthic boundary sampler (Holtappels et al., 2011). Recently, nanolanders for *in situ* monitoring of O₂ in the BBL and benthic fauna behavior in O₂-limited zones (Gallo et al., 2020) were developed. Among other things, these new types of observation allow a better understanding of temporal O₂ dynamics in hypoxic bottom waters and its impact on benthic fauna.

In addition, a new observation system has been developed during the last decade based on eddy covariance techniques (Berg and Hüttl, 2008; Reimers et al., 2012). In this technique, joint high frequency measurement of O₂ (>10 Hz) and of vertical currents at a given point in BBL by an acoustic doppler velocimeter (ADV) enables continuous estimates of the O₂ exchange flux and O₂ dynamics within the BBL. The technique is also applicable in habitats with hard and complex substrate in coastal or deep-ocean settings (Berg et al., 2009; Rovelli et al., 2015; Attard et al., 2019; Polsenaere et al., 2021).

More recently, mobile and fixed platforms were developed in order to capture temporal variations linked to intense events (deep mixing by convection, storms and floods in the coastal ocean). Single-point benthic observatories measure O₂ concentration and various other environmental characteristics in the BBL (e.g., S, T, turbidity) in the deep-sea (EMSO, NEPTUNE) or the coastal sea (Pairaud et al., 2016). At these coastal or deep-sea observatories, time series of sediment O₂ distributions based on micro-electrode profiles are acquired by benthic stations in the coastal ocean (Toussaint et al., 2014; Rigaud et al., 2018). Furthermore, mobile platforms called crawlers or rovers (Wenzhöfer et al., 2016; Smith et al., 2017; Lemburg et al., 2018) were recently developed and deployed to explore the spatial heterogeneity inherent in the benthic realm and to study its temporal variation. This enables investigations of the spatio-temporal O₂ dynamics in the BBL and porewaters for one year (or more) (Purser et al., 2013).

CTDs with O₂ sensors are routinely mounted on remotely operated vehicles (ROVs) and human occupied vehicles (HOVs) conducting benthic research. Single dives typically provide vertical profiles made during descent and ascent and extended measurements within 2 m of the sea floor during bottom operations. The data may be accessed through operating agencies (e.g., NOAA⁴) or through PIs, but are not always accessible or in databases.

The availability in databases of O₂ concentrations in the BBL and in sediments is limited and not optimally organized. Pioneering papers (CARS, 2009; Jahnke, 1996) proposed a synthesis of the limited dataset of benthic O₂ demand collected

at that time which contains indications of O₂ concentration in bottom waters. Some regional syntheses were conducted using basin scale compilations of O₂ demands (e.g., South Atlantic; Wenzhöfer and Glud, 2002). More recently, a compilation based on 230 papers containing a collection of total and diffusive O₂ uptakes was achieved and made publicly available (Stratmann et al., 2019) from published and unpublished data (Pangaea data publisher⁵). None of these data collections, however, comprises an exhaustive compilation of O₂ in the BBL and in the sediments. This work remains to be completed.

Concerning common (or best) practices, most calibrations ultimately rely on sensor readings in 100 and 0% O₂ solutions prior to deployment most often combined with Winkler O₂ titration on recovered water samples, some long-term moorings rely on measurements of O₂ concentration using calibrated optodes throughout the deployment, but no consensus on best practices has been established for the bottom part of the ocean including sediments.

At a first stage, GO₂DAT will incorporate O₂ concentration data from the water column including the BBL. Accurate O₂ data in the BBL are crucial for the mapping of bottom water hypoxia. CTDs usually stop ~2 m before the bottom and do not sample the BBL. Benthic O₂ fluxes and oxygen concentrations in sediment porewaters will be integrated at a later stage.

Underway Systems

Underway systems are typically ship-based, but can also include instrumented marine mammals. The potential for collecting high temporal resolution data from such platforms is high, but currently there is no real community for underway O₂ measurements (on any platform) and no consensus as to which sensors should be used and what quality control measures should be taken. Ships Of Opportunity (SOOPs) of the European Integrated Carbon Observation System (ICOS) ERIC, which measure surface pCO₂ and contribute to the Surface Ocean CO₂ Observing NETwork (SOCONET, Wanninkhof et al., 2019), are required to perform concurrent surface O₂ measurements for scientific use to be labeled as “Class 1” station (Steinhoff et al., 2019), which currently 11 out of 12 ICOS-Ocean SOOP lines have. They typically use O₂ optodes in a flow through system. However, data processing and quality control is not yet standardized by SOOPs. To this end, Becker et al. (2021) present a setup that allows regular in-air measurements in such underway installations on SOOPs, thus allowing continuous drift correction and drastically improving data accuracy. From a preliminary assessment with only a few transects, they estimate an accuracy around 3% with an uncertainty (i.e., the standard deviation of the measured O₂ concentration compared to a standard reference value) of 0.26%. Bailleul et al. (2015) added an optode sensor 4330F to Argos CTD-SRDL (i.e., Depth-Satellite Relayed Data Loggers) tags deployed on female elephant seals in the Southern Ocean as a way to both increase the O₂ database in the Southern Ocean and to investigate the relationship between air-breathing marine predators and other components of marine ecosystems. O₂ pop-up satellite archival tags (DO-PATs) have been deployed

⁴<https://www.ncei.noaa.gov/maps/oer-digital-atlas/mapsOE.htm>

⁵<https://www.pangaea.de>

on bluntnose six gill sharks to understand their vertical and horizontal distributions (Coffey and Holland, 2015). A MEOP (Marine Mammals exploring the ocean pole to pole) data base⁶ exists but presently only includes pressure, temperature and salinity profiles.

Quality and Calibration of O₂ Data

Data Quality of Winkler O₂ Measurements

Winkler O₂ measurements are the reference for the major range of O₂ concentrations in the oxygenated ocean. Historical (pre-1970) Winkler O₂ measurements have an overall precision of about $\pm 1 \mu\text{mol kg}^{-1}$. In recent years, the use of potentiometric, amperometric, spectro-photometric and photometric O₂ end-point detection methods have improved the quality of the titrations because of greater automation. Winkler O₂ measurements have an estimated accuracy of 0.1% (Carpenter, 1965); equivalent to approximately $\pm 0.25 \mu\text{mol kg}^{-1}$ and a precision of $0.15 \mu\text{mol kg}^{-1}$ (Saunders, 1986; Langdon, 2010).

However, some compounds commonly present in seawater can modify the Winkler-estimated O₂ concentration. In fully oxic conditions, the most relevant interference is iodate that increases the measured concentration by 1.5 $\mu\text{moles of O}_2$ per $\mu\text{mol of iodate}$. The concentration of iodate in the oceans is relatively stable with values of 0.35–0.45 $\mu\text{mol kg}^{-1}$ in the surface and deep waters, respectively, and lower values in coastal areas (Wong and Cheng, 1998; Chance et al., 2014). Considering these typical iodate concentrations, Winkler measurements overestimate the real O₂ concentration by 0.53–0.68 $\mu\text{mol O}_2 \text{ kg}^{-1}$, which could be a significant error in OMZs, if one wants to estimate the air-sea O₂ fluxes (Wong and Li, 2009) or determine NCP from O₂ trends (Yang et al., 2017). In addition, samples can be contaminated by exposure to the atmosphere during sample handling and from polymers, present even in the widely used Niskin bottle (Broenkow and Cline, 1969; Garcia-Robledo et al., 2021). Therefore, the quality of Winkler measurement degrades and overestimations of the *in situ* O₂ concentrations might be produced which can be of significance in OMZ (see **Box 1**). For the building of GO₂DAT, full information on the data collection protocol is required (e.g., type of bottles, atmospheric contamination). This is particularly critical in OMZs where details on the level of NO₂ that can potentially interfere with the measurement of O₂ is also needed.

Data Quality of Sensor O₂ Measurements

Although O₂ sensor technology has advanced further compared to some other biogeochemical sensors, the quality of sensor-based *in situ* O₂ measurements is still heterogeneous and differs, depending mainly on the calibration type, calculation method (see **Box 2** for an example), and possibility of frequent recalibration. Proper use, calibration, response time and drift remain challenges.

The uncertainty (i.e., the standard deviation of the measured O₂ concentration compared to a standard reference value) on O₂ sensor-based data differs depending mainly on the calibration type, calculation method and possibility of frequent recalibration

through comparison with Winkler measurements or in-air calibration (e.g., BGC Argo). **Table 4** shows that the uncertainty associated to the last generation of optical sensors that uses a community-adopted calibration and calculation method has been reduced by a factor of ~ 2 – 3 compared to the previous generation.

O₂ sensors are generally affected by three main types of drift: (1) an O₂ sensitivity drift when not deployed and stored in air (i.e., the “storage” drift), (2) an “*in situ*” drift when submerged in the water and (3) a drift in the pressure correction visible on deep moorings (> 1000 m). The storage regime drift is the most problematic with a loss of O₂ sensitivity that can reach $\sim 5\% \text{ yr}^{-1}$ and requires a re-calibration of the sensor before its deployment (see **Box 2**). The *in situ* drift amounts $\sim 0.5\% \text{ yr}^{-1}$ and requires frequent recalibrations and adjustments. For instance, best practices for electrochemical sensors (e.g., SBE43) recommend calibration of the sensor daily with Winkler O₂ data acquired from surface to deep waters (Coppola et al., 2016). A least-square method (Uchida et al., 2010) is then used to adjust the coefficients of the empirical equation relating O₂ voltage and temperature to O₂ concentrations. These frequent recalibrations are particularly critical for autonomous platforms with long time series and/or without recovery like Argo floats. In that case, climatological surface O₂ data can be employed for crude correction (Takeshita et al., 2013), and the advent of optodes with in-air measurements provides a robust approach to address *in situ* drift correction, offering a routine calibration of the sensors (Bittig and Körtzinger, 2015). In addition, oxygen optodes can show a time-dependent lag in response to a change in O₂, which affects data accuracy when sensors experience O₂ gradients, e.g., on profiling platforms. Methods to characterize the response time and to correct for the sensor lag have been described in the literature (Bittig et al., 2014; Bittig and Körtzinger, 2017; Gordon et al., 2020). The time response of the sensors is a function of the membrane thickness, temperature, and flow. For instance, for the most common O₂ sensor used in CTDs, the Sea-Bird SBE-43, it may vary from a few to several tens of second. The effect of time-dependent pressure hysteresis is serious for O₂ sensors deployed at deeper depths as long-term change in the O₂ concentration in the deep ocean might be smaller than the magnitude of the pressure hysteresis (e.g., Uchida et al., 2010). The Scientific Committee on Oceanic Research (SCOR) 142 Working Group on “Quality Control Procedures for O₂ and Other Biogeochemical Sensors on Floats and Gliders” produced well-documented guidelines for the calibration of O₂ optodes (e.g., Bittig et al., 2018) that serve notably for the calibration of BGC Argo (e.g., Thierry and Bittig, 2018).

The quality flagging of O₂ data collected by sensors requires the full specification of the sensors, calibration method and equation as well as information on potential drift corrections by the data owner. This will be recommended for the building of GO₂DAT (see section “Roadmap to GO₂DAT”).

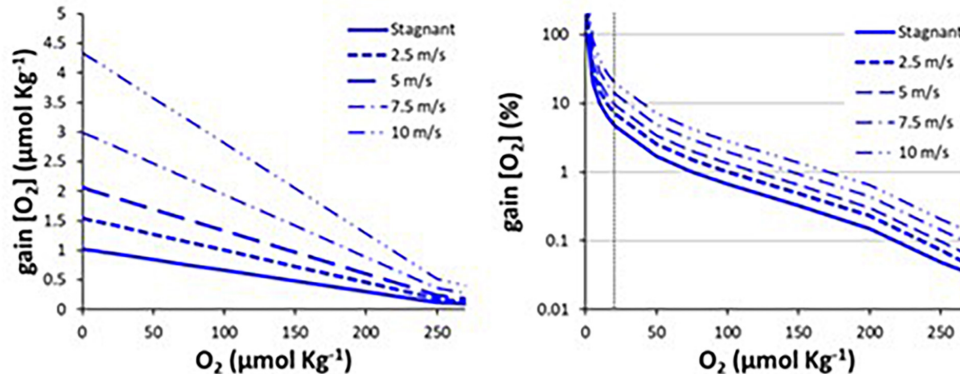
Adequation of O₂ Measurements to Assess Mean State, Weather and Climate Variability

The uncertainty associated with the last generation of O₂ sensors that uses the best calibration and calculation methods amounts, in the best case at $\sim 2 \mu\text{mol kg}^{-1}$ (**Table 4**) which is adequate

⁶<http://www.meop.net/database/>

BOX 1 | Challenges of measuring low O₂ values.

Anoxic samples collected in the core of the OMZs and subpycnocline waters of some coastal systems have the maximum concentration difference with the atmosphere or with O₂ permeable materials such as many polymers commonly used in scientific equipment (e.g., silicone, PVC, rubber, nylon). The contact of the sample with these compounds results in the increase of the O₂ concentration from the initially anoxic sample to values up to 1 μmol kg⁻¹ just by the Niskin collection (García-Robledo et al., 2021). In addition, samples are exposed to the atmosphere during the filling process and the waiting time until reagents are added and the bottle is finally closed, allowing certain equilibration with the atmosphere. As a consequence, in under-saturated waters, atmospheric O₂ dissolves in the sample and increases the measured concentration up to a few μmol kg⁻¹.



The above figure shows the estimation of the O₂ contamination from the atmosphere calculated as a function of the initial sample concentration (*x*-axis) and wind speed on deck (or sailing speed if there is no wind, in m/s), considering an oceanic sample at 10°C being collected on a 160 ml bottle with an opening diameter of 2.4 cm. The extra O₂ dissolved in the sample is also used to calculate the gain in percentage of the initial O₂ in the sample (right panel). A dotted line at 20 μmol kg⁻¹ is drawn to illustrate the O₂ range in the OMZs. Note the logarithmic scale in the right panel. The contamination of O₂ introduced only by the atmosphere could be as high as ca. 4.5 μmol kg⁻¹.

Some compounds interfere with the Winkler titration. At low O₂ concentrations, these interferences gain relevance due to the lower O₂ measured and the increase in some of these compounds. Iodate is consumed in anoxic environments, but at low O₂ conditions such as the oxyclines of OMZs, it can increase the measured concentrations by 0.5–0.6 μmol kg⁻¹. Below the oxycline, nitrite usually accumulates in truly anoxic conditions such as the anoxic core of the Pacific OMZs. However, nitrite also interferes with Winkler titration, increasing the apparent O₂ concentration by 0.5 μmoles per μmole of nitrite. Considering that nitrite concentrations up to 10 μmol kg⁻¹ can be measured in the Pacific OMZs, the deviation from anoxic values can be as high as 5 μmol kg⁻¹ excluding other sources of error. If the contamination with atmospheric O₂ is taken into account, a variable apparent O₂ concentration of ca. 10 μmol kg⁻¹ could be measured in samples collected in anoxic environments. Although extreme precautions can be taken to avoid atmospheric O₂ contamination (Broenkow and Cline, 1969), other chemical compounds must be also quantified to correct the final O₂ concentration estimated by Winkler titration. Due to the complexity of such corrections and the likely lack of complementary data from historical databases, Winkler determinations should not be used to correct *in situ* sensors in waters with [O₂] < 15–20 μmol kg⁻¹ (estimated error ~10%). In such cases a zero-calibration is recommended.

to answer questions on the mean state and weather variability but is still too large to resolve climate variability (Table 2). On the other hand, Winkler O₂ data have the level of accuracy and precision needed to assess the long-term climate deoxygenation signal. Yet, these data do not have the quality, spatial and temporal coverage needed to infer the long-term trend in OMZs spatial extension and to concurrently correct sensor data in these regions. A *posteriori* correction or calibration of historical O₂ data requires information on the sampling (e.g., contamination, concentrations of other compounds, calibration procedures, sampling protocol) that is very often not available. The rapid evolution over the last decades of sensor technology and calibration methods makes the application of a correction scheme derived from current instruments to past measurements difficult.

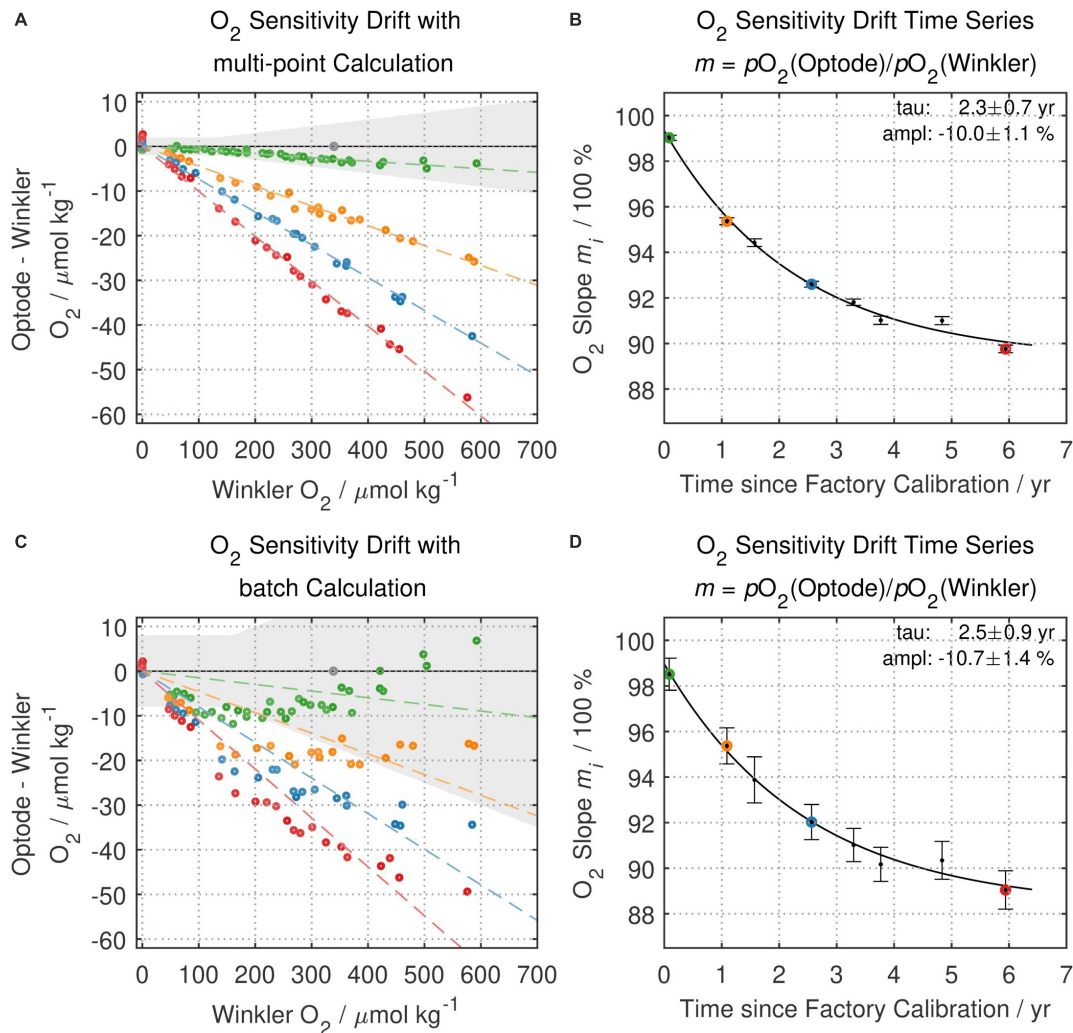
Second Order Adjustment of O₂ Data

A *posteriori* correction can also be performed to increase the internal consistency of diverse datasets collected over several decades by different methodologies and laboratories. This secondary correction will not improve the accuracy of the data but rather is expected to increase the internal consistency of

the datasets (e.g., Key et al., 2004) for e.g., the building of data synthesis products. In the deep ocean (~2000 m), a common procedure consists of correcting sensors' offsets by comparing their measured values with those collected by Winkler (e.g., Winkler-based climatology, data taken years apart), assuming that the level of O₂ remains unchanged in that part of the ocean. For instance, GLODAP (Key et al., 2004; Olsen et al., 2016) uses a crossover analysis to determine cruise-by-cruise offsets for discrete bottle data (Winkler) collected since 1972. The comparison is made irrespective of the year and season of data collection. Identified offsets larger than 1% are then adjusted after expert evaluation of all available information, including known climate trends in O₂ and water mass structure (Tanhua et al., 2010; Lauvset and Tanhua, 2015; Olsen et al., 2020). Significant O₂ and temperature warming trends have been detected even below 2000 m depth (e.g., Desbruyères et al., 2016; Schmidt et al., 2017). For instance, Desbruyères et al. (2016) reported long-term (1991–2010) global warming trends at all pressure levels below 2000 m with the strongest warming rates in the abyssal layer (4000–6000 m). Even if the changes in O₂ associated with this warming is likely less than 1%, it requires differentiating sensor drift from climate variability.

BOX 2 | O₂ response drift in optical and electrochemical sensors.

An O₂ sensitivity drift has been reported frequently between calibration by the manufacturer and deployment in the field (i.e., the “storage” drift, order $-5\% \text{ yr}^{-1}$, Bittig et al., 2018). This leads to a significant deviation of the stability properties compared to those found during the factory/laboratory calibrations (e.g., Bittig et al., 2012; Takeshita et al., 2013). Bittig and Körtzinger (2015) describe the nature of the storage drift as systematic, linear with O₂ level and towards underestimation of actual O₂.



The above figure shows the characterization of the O₂ sensitivity storage drift using as an example a subset of calibration data from an optode (Aanderaa optode model 3835) with factory two-point/batch calibration (in November 2010), multi-point calibrated directly afterward (December 2010) and, thereafter, multi-point recalibrated in approximately yearly intervals. All data courtesy of Craig Neill (CSIRO Oceans & Atmosphere, Hobart). **(A)** Difference between optode data and Winkler reference data using the multi-point calculation, with the factory two-point data (gray circles) as initial state. Dashed lines are the slope regression forced through the origin and the different colors correspond to different time since factory calibration shown in panel **(B)**. Only a subset of recalibrations (colored circles) is shown for clarity. **(B)** Temporal evolution of the O₂ slope [i.e., $pO_2(\text{Optode})/pO_2(\text{Winkler})$] with colors corresponding to calibrations shown in panel **(A)**. **(C)** Same data as in **(A)** but treated with the batch-foil/2-point adjustment calibration calculation. The linear O₂ sensitivity drift appears non-linear with the batch-foil calculation. A slope O₂ regression (dashed lines) still shows a drift towards lower O₂, however, slopes are dependent on at which O₂ levels reference data are available. **(D)** Same as **(B)** but for batch-foil calculation. The above figure illustrates the potentially biasing effect of calibration method on the appearance of storage drift. **(A)** Shows that in the case of the multi-point calibration the O₂ sensitive bias can be modelled (through regression) at each calibration time (i.e., from 0 to 7 years since factory calibration) as a linear function of the O₂ going through the origin with a negative slope. In the case of using the same, multi-point data but with the batch foil calibration approach with a two-point correction (e.g., 0 and 100 % O₂ saturation), the O₂ sensitivity drift appears non-linear but still a regression line indicates a drift towards lower O₂ **(C)**. However, slopes are dependent on which O₂ levels reference data are available. This is where a large portion of the added uncertainty on batch-foil calibrated optodes originates (**Table 4**).

Bittig et al. (2018) propose a parameterization of the drift as a slope effect (i.e., the loss of O₂ sensitivity defined as $pO_2(\text{optode})/pO_2(\text{Winkler})$) resulting from reduced O₂ sensitivity with a small positive offset coming from a reduced luminophore lifetime. **(B)** Shows that the storage drift rate (i.e., the slope effect) decreases with age of the sensor, being strongest in new optodes, of the order of $5\% \text{ yr}^{-1}$, and decreasing in more mature optodes. Therefore, *in-situ* calibration before or during deployment is crucial and can be done either using Winkler-O₂ determination on a cast taken at the same time and place of the sensor's deployment or, in the case of Argo floats equipped with optode in-air measurements, using near surface and in-air measurements (Bittig and Körtzinger, 2015; Johnson et al., 2015).

TABLE 4 | Calibration type and calculation method for sensors and platforms.

| Calibration type and calculation method | Examples for sensors | Examples for platforms | Uncertainty |
|----------------------------------------------------------------|------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------|------------------------------|
| Electrochemical sensors with 2-point calibration | SBE43 | Shipboard CTD, 1st category of sensors used on Argo Floats, Moorings, Benthic Observations, Gliders | 2–10 $\mu\text{mol kg}^{-1}$ |
| Batch-foil calibration; polynomial with 2-point adjustment | Aanderaa 3830/3835, all Aanderaa 4330/4831 produced until 2013, some Aanderaa 4330/4831 produced 2013–2018 | Moorings, Benthic Observations, Gliders, 2nd category of sensors used on Argo Floats. | 6–25 $\mu\text{mol kg}^{-1}$ |
| Multi-point calibration; SVU/Uchida et al., 2010-like equation | Aanderaa 4330/4831 since 2018, SBE63, RINKO ARO-FT | Moorings, Benthic Observations, Gliders, 3rd category of sensors used on Argo Floats. | 2–10 $\mu\text{mol kg}^{-1}$ |

Measurement uncertainty is defined here as the standard deviation of the measured O_2 concentration compared to a standard reference value (mostly Winkler).

Shallower coastal regions are subject to higher variability than deep, open-ocean regions, which further complicates the application of adjustments. Deep reference values cannot be used for data calibration in the shallower coastal areas, and thus, targeted data calibration approaches and QC procedures are needed there.

Mapping O_2 : Technical Challenges

Some of the most common objective mapping procedures used in ocean sciences are the Barnes scheme (Barnes, 1964) which is used to create WOA18 and GLODAPv1.1, and variational inverse analysis (such as DIVA – data interpolating variational analysis; Troupin et al., 2012; Barth et al., 2014), which is used to create GLODAPv2. There are many objective mapping methods, and each has advantages and disadvantages depending on the data product requirements, the availability of high-quality data, behavior of the mapping method around topographic features (e.g., islands, trenches, seamounts), the ability to take ocean currents into account, and other factors. Mapping is commonly done on depth/pressure surfaces, but mapping on isopycnal (density) surfaces is also useful where possible. There are several technical challenges for creating mapped O_2 data products, including the need to merge several highly diverse data sources with different sampling frequencies in time and space. Additionally, there are issues specifically related to ocean biogeochemical variables and, in particular, O_2 , such as the heterogeneous data distribution in time and space, data quality, and the existence of Anoxic Marine Zones (AMZs) (i.e., $O_2 = 0 \mu\text{mol kg}^{-1}$) and OMZs, which present several challenges including the scarcity of data, high gradients and ultra-low O_2 values (e.g., Bianchi et al., 2012). The global coastal ocean presents another challenge given its relatively higher variability when compared to the open ocean. It is therefore likely that mapped data products for the global open and coastal ocean will have to sometimes rely on auxiliary data (such as temperature and salinity) and machine learning methods (such as neural networks, e.g., Krasnopolsky et al., 2016; Barth et al., 2020).

Existing and commonly used mapped data products include GLODAPv1.1 (Key et al., 2004), GLODAPv2 (Lauvset et al., 2016), WOA18 (Garcia et al., 2019), CSIRO Atlas of Regional

Seas (CARS, 2009), and Global Nutrients Dataset 2013 (GND13; Aoyama, 2020). All these data products are examples of global three-dimensional (longitude, latitude, and depth) fields of O_2 and other variables, with varying temporal resolution (monthly to annual averages), created using various forms of objective mapping procedures. In addition, there exist several regional mapped data products such as EMODNet Chemistry.

ROADMAP TO GO_2 DAT

The WOD (Garcia et al., 2005, 2019), CMEMS (Le Traon et al., 2019), GLODAP (Key et al., 2004; Olsen et al., 2016, 2020), and EMODnet (Giorgetti et al., 2018) are excellent foundations to support the development of GO_2 DAT. Data collected by Argo, gliders and moorings have their own GDACs, which offers a certain level of consistency in terms of metadata specifications, QC, QF, computation models of sensors response (i.e., from raw data to O_2 value), calibration and adjustment procedures. Best practice documents are available for sensor calibration (e.g., see **Table 4**) and the data are delivered according to the FAIR principles in RT and DM streams. However, these different databases and GDACs have their specific standards and, inside a given platform, these standards may differ across regional DACs. A GO_2 DAT steering committee will be established and will work with existing GDACs and the IOC UNESCO International Oceanographic Data and Information Exchange program (IODE) towards the definition of common best practices and an alignment between GDACs of metadata structure, QC and QF procedures as concerns O_2 . These community agreed best practices will be communicated to data providers and repositories via the OceanTeacher network. GO_2 DAT will have its own O_2 GDAC (i.e., GO_2 DAT-GDAC), approved by IODE and complying with the terms of references of a, IODE-approved GDAC (see https://www.iode.org/index.php?option=com_content&view=article&id=372&Itemid=100088). For instance, GO_2 DAT-GDAC will receive and assemble marine O_2 data and metadata from the data streams described in section “ GO_2 DAT data flow,” check their consistency, identify duplicates, make sure that the data are quality controlled according to the GO_2 DAT-GDAC standards and methods, provide feedbacks

to the source of data regarding quality issues, make data accessible and metadata available through the GO₂DAT data portal and to IODE.

GO₂DAT Data Flow

In order to enable a sustainable data submission system that will integrate and make use of existing infrastructures, it is crucial to align it with overarching data flow and the structural elements of IODE. IODE will offer a seamless connection with its structural elements such as National Oceanographic Data Centres (NODCs), Associated Data Units (ADUs), and GDACS.

The proposed data submission will be two-fold: a centralized data submission to existing GDACS and a bottom-up data flow via NODCs (Figure 8). For platforms that already have their own GDAC (see Table 3), the submission process will remain unchanged (i.e., data will be submitted to the corresponding GDAC, e.g., Argo, gliders, moorings). Otherwise, submission to NODCs will be encouraged. Data providers will nevertheless still have the possibility to directly submit their data to regional hubs (e.g., EMODnet, CMEMS-TAC) and, in that case, data will be instantly exchanged with NODCs where PIDs will be assigned, and data get archived.

At the end, all data will be delivered and archived in the GO₂DAT GDAC. The adjustments performed on each data set at each level should be traceable and well documented. During the whole process, best practices and OceanTeacher will guide data providers in the submission process.

Acknowledgment of data providers will be provided through the assignment of a PID (e.g., DOI) where appropriate credit is given not only to the data provider but also to the project, funding

agency and hosting agencies/institutes. The data usage license should be free and open but requires citation (e.g., Creative Commons BY). Data providers, NODCs, and Associated Data Units (ADUs) should be informed of download statistics.

Annual release of the GO₂DAT data will be publicized and interconnection with international initiatives (e.g., CMEMS, SeaDataNet, GLODAP, WOD) and other related GDACS will be recommended. Data will be received and made available through the World Data Service for Oceanography of the World Data System.

Table 5 summarizes the fundamental principles of GO₂DAT.

Definition of Community-Approved GO₂DAT Standards Metadata Specifications

Understanding O₂ variability and change requires information on the environmental conditions associated with each measurement. For instance, temperature and salinity are essential variables to estimate the density and O₂ solubility of a water parcel allowing differentiation of physical and biogeochemical contributions to the O₂ dynamics and trends. Temperature and salinity are also needed to convert observed O₂ concentration into partial pressure (pO₂), a meaningful quantity when assessing the impact on marine life (e.g., Seibel and Deutsch, 2020). We recommend that raw O₂ data be provided with information on temperature, salinity and pressure. Data will be delivered on a per mass basis in order to avoid the temperature and pressure effect on the volume. A clear and comprehensive definition of metadata specifications needs to be agreed upon by the scientific community. It will be recommended that NODCs, regional

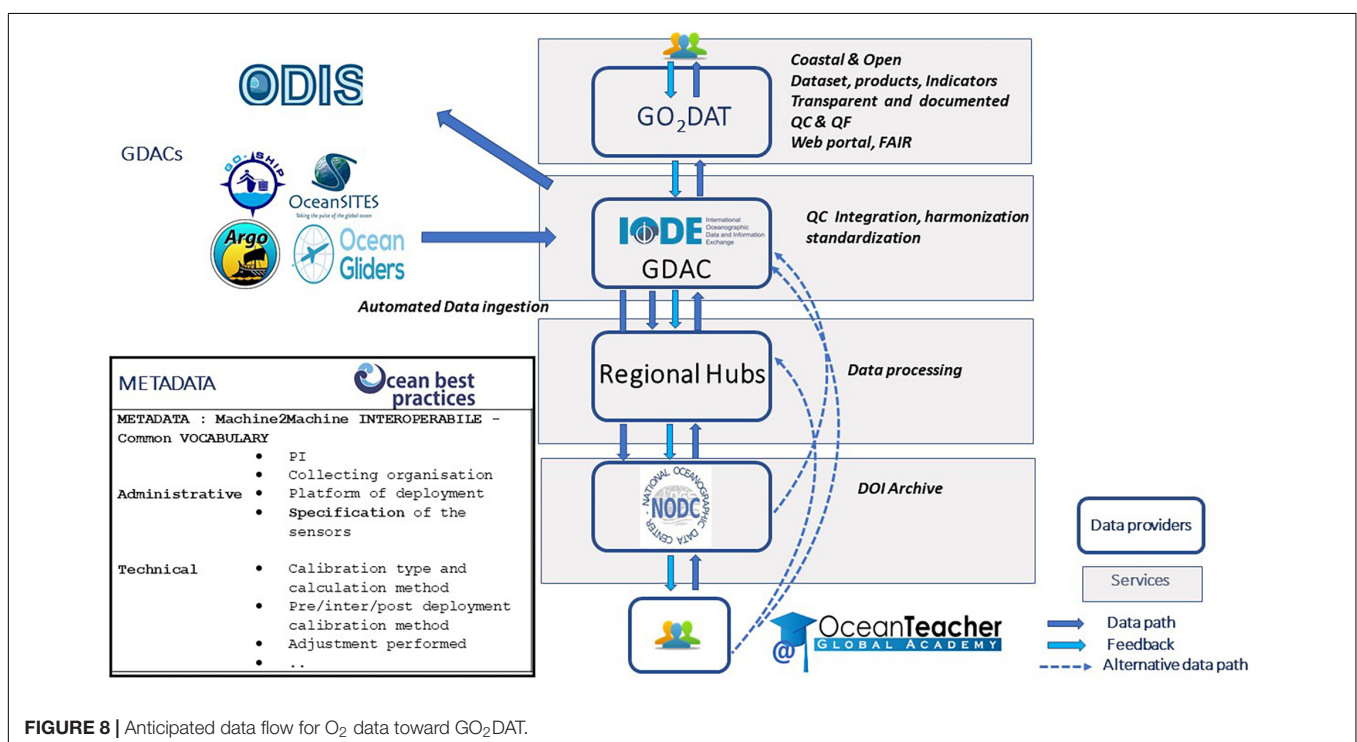


TABLE 5 | GO₂DAT principles.

| Attribute for raw data | Requirements |
|-------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| Access | Open-access without data use restrictions under Creative Commons. |
| Cost to use data and products | Free |
| Data and product attribution | PID, DOI |
| Archival of primary reference | All data must be available at an international long-term archive with long term funding (e.g., World Data Service for Oceanography) |
| Sustainability | Long-term to ensure reproducibility of the products |
| Data versioning | Metadata best practices |
| Reference QC and QF | Community consensus |
| Database structure | Common digital format (e.g., netCDF, ASCII), units, and searchable/download online. |
| Data products | Available online without restriction in common format (e.g., netCDF) |
| Variables | EOV, (ECV, EBV) |
| Reference | Depth (pressure), density |
| Other... | |

hubs, GDACs map their existing standards to the agreed GO₂DAT standard.

A Fully Documented and Transparent Quality Flagging System

GO₂DAT will ensure that data in each flagging level are assigned an uncertainty, and that sufficient metadata to interpret this uncertainty are included. This will facilitate understanding of data uncertainty by the users allowing them to decide whether these data fit their specific requirements. Data correction factors and flagging should be fully traceable, consistent and based on a community agreement between groups of experts defined for the different sensors and platforms. Fully documented, transparent flagging procedure will allow any user to understand the details of a particular QF assigned to a data value and to have sufficient information to assess the suitability of the data for a particular purpose (e.g., mean state, variability, climate trend assessment). The questions listed in **Table 2** can serve as a base to define the QF system. In the coastal ocean, the quality of data may vary greatly from very accurate data taken according to the best protocols to low quality data taken with hand-held, air-calibrated meters (e.g., YSI O₂ meter). Even if of lower quality, such datasets should not be rejected from GO₂DAT, but should be appropriately flagged. Some important applications of O₂ data in coastal systems (e.g., protection of fisheries species) do not require the accuracy and precision required in open-ocean climate studies.

Integrating Coastal Ocean Data in GO₂DAT

Whereas open data sharing is generally accepted for open-ocean monitoring, this concept needs further support in coastal communities and, particularly, from NODCs and national and local organizations funding the monitoring programs. The compilation of data for the coastal ocean will be facilitated by the establishment of regional hubs adhering to the GO₂DAT- best

practices. The connection of these regional hubs and GO₂DAT will be realized through international and regional initiatives. For instance, the Chesapeake Bay Program⁷ and, the Baltic Environmental Database⁸ have been instrumental in data sharing, thereby supporting studies of hypoxia at a larger scale (e.g., Hagy et al., 2004; Conley et al., 2009; Carstensen et al., 2014). In the Pacific region, connection with WESPAC-O₂NE (WESTern PACific-Oxygen Network) will promote the sharing of data in a region where the risks of eutrophication and hypoxia are likely to continue to intensify due to the projected increase of discharges of inorganic nitrogen and phosphorus over the next decades (Seitzinger et al., 2010). In the North Pacific, GO₂DAT will benefit from the efforts led by the North Pacific Marine Science Organization (PICES) that is planning to construct a list of coastal O₂ monitoring stations among their member countries. In the Eastern Pacific, existing initiatives like the California Cooperative Oceanic Fisheries Investigation (CalCOFI) and the Tongo Bay (off Chile) observing system⁹ will provide open access, long-term O₂ data that have stimulated numerous mechanistic studies of regional O₂ trends (e.g., Evans et al., 2020). The building of the research infrastructure JERICO-RI for the observation of the coastal ocean at the EU level will probably provide a regular flow of coastal O₂ data to GO₂DAT.

Despite the existing services to facilitate and streamline the ingestion of data by providers not yet connected to marine data management infrastructures, the success of such services depends on the willingness of data holders to share their data. The existence of GO₂DAT, with rules on publication and attribution of data, may encourage individual researchers as well as government agencies responsible for data collection in coastal systems to participate and increase access to their data.

GO₂DAT Products

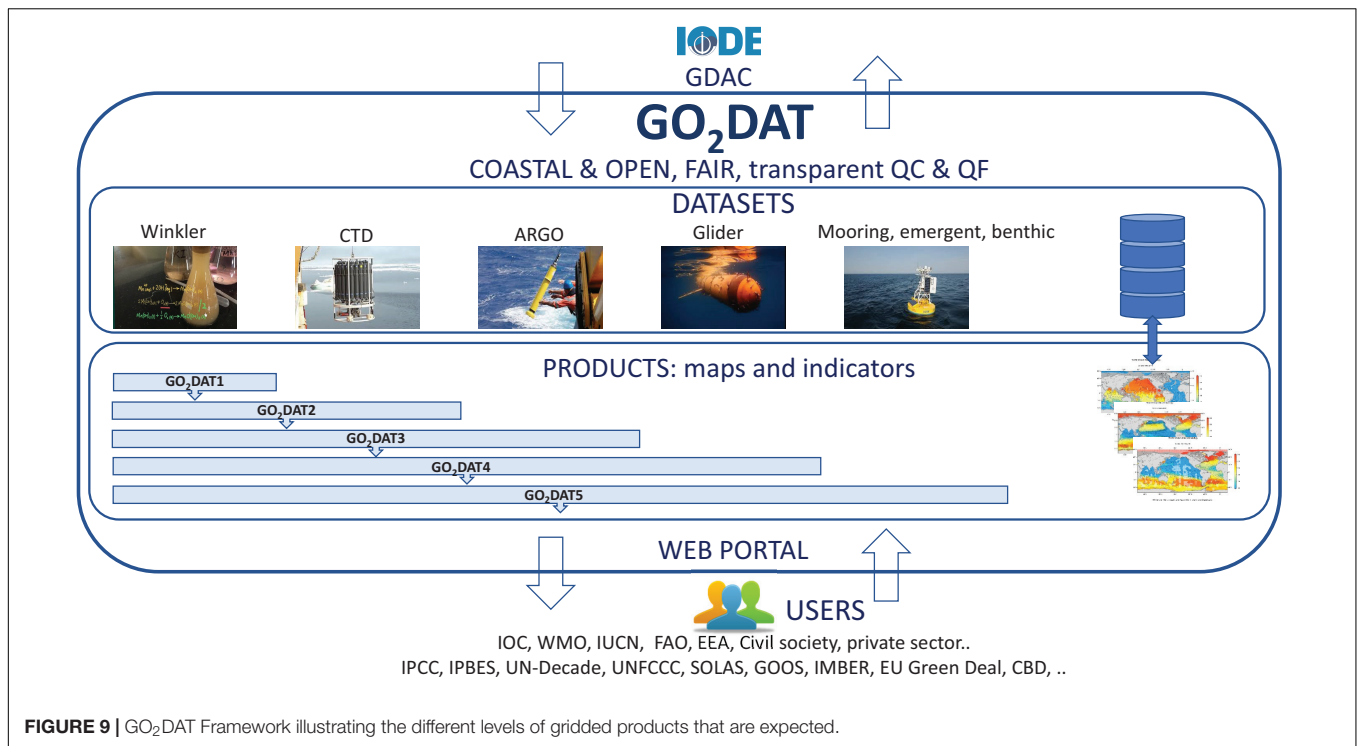
GO₂DAT gridded data products (hereafter referred to as “mapped data”) will be two- or three-dimensional fields of O₂ concentration, pO₂ and degree of saturation for the coastal and global ocean in support of scientific and management purposes. Each GO₂DAT product will be provided with a documented QF and with information about the quality, source and treatment of the data used for their production.

We anticipate providing several choices of mapped O₂ products at different spatial and temporal scales to give users the choice to select the most appropriate for their application. In addition, we will strive to provide information about which methods are appropriate and relevant for the user application. The building of GO₂DAT mapped O₂ products will progress in different iterative steps, as illustrated in **Figure 9**. At the first level, GO₂DAT mapped products will integrate O₂ Winkler observation from the different databases (e.g., WOD, EMODnet, CMEMS) using the consistent community-agreed QC procedure. The second level of mapped O₂ products will include the CTD-O₂ sensor data, after an appropriate QC procedure. The third and fourth levels entail inclusion of O₂ data from Argo-floats

⁷<https://www.chesapeakebay.net/>

⁸<http://nest.su.se/bed/>

⁹<http://www.cdom.cl/equipamiento.php>



and gliders, respectively. The fifth and final level is inclusion of data from moorings and underway systems, as well as BBL data and other emergent data platforms. GO₂DAT will thus make the development of a range of data synthesis products at different depth and density levels possible.

Users will be able to download separate synthesis products for each level, or, when completed, a combined product with all levels included. It is envisioned that the synthesis product will be scalable to accommodate new observing systems and to facilitate continuous updates as new data become available. This is an important and required characteristic to enable frequent updates of products and to serve a wide range of users. GO₂DAT will collaborate closely with the CMEMS *in situ* Thematic Centre, NOAA NCEI and EMODnet Chemistry to avoid duplication of efforts.

While GO₂DAT will focus on providing mapped data products, it will also aid the users wanting to use GO₂DAT datasets for building their own mapped products and develop user-specific tools.

An interactive web-platform where GO₂DAT data and products can be visualized will enhance interactions with the users and general public. This GO₂DAT web interface will be optimized in order to obtain feedback on the interface, datasets and products.

GO₂DAT Human Resources

The development of GO₂DAT will require human resources and engagement from the community including scientists, data managers, data providers and data users. The following tasks have been identified for the building of GO₂DAT to which human resources need to be dedicated.

Definition and documentation in the Ocean Best Practices System of community-agreed GO₂DAT standards for metadata specification, sensors calibration, data quality check and flagging.

Mapping existing data standards (e.g., in NODCs, GDACs) to that agreed in GO₂DAT.

Integration (preferably interoperable) in GO₂DAT GDAC of existing datasets, search for duplicates, application of the agreed GO₂DAT standards.

Building regular updates (e.g., yearly) and analysis of the GO₂DAT mapped products and indicators.

Building of the web interface and interactions with the users.

CONCLUSION

Since the community white paper by Gruber et al. (2010) that called for the addition of O₂ sensors on Argo floats and more generally on autonomous platforms, the number of O₂ sensors has dramatically increased offering unprecedented capabilities to monitor O₂ state and variability in the open, regional and coastal ocean. As the number of profiles increased, the quality of the sensor measurements has also improved. The uncertainty associated to the last generation of sensors has been reduced by a factor of ~3 when the best calibration and calculation method are used. This offers new opportunities to combine sensors and Winkler data in consistent data-synthesis products. These products will be used to understand the O₂ dynamics and the deoxygenation process in the open and global coastal ocean in response to climate change.

The building of GO₂DAT is a timely initiative that can build on WOD, EMODnet, CMEMS, GLODAP. The integration of sensors and Winkler data from eulerian and lagrangian platforms from the different databases would offer data-synthesis products at an increased resolution. For the coastal ocean, the necessity to support the decision-making process aiming at preserving ocean health requires a coordination of NODCs, (inter)national and local organizations via the establishment of regional hubs. GO₂DAT will offer the opportunity to build an O₂ gridded product for the global coastal ocean with regular updates to monitor the multiannual evolution of coastal hypoxia in a warming climate.

The building of GO₂DAT would allow to fully harness the potential of the boost in O₂ profiles that is expected to quadruple in the frame of the future GOOS strategy. The alignment of well-documented and consistent QC and QF procedures proposed in GO₂DAT will allow the user to make an informed choice on which data that are fit for purpose. GO₂DAT will facilitate the dissemination of information on ocean deoxygenation and its impact for marine life to a wide community of stakeholders (e.g., policymakers, industries, see **Table 1**) and contribute to the education of the young generation and general public.

The development of GO₂DAT requires human resources and engagement from the scientific community, data providers, data managers and end-users. Engagement around GO₂DAT will be promoted by the UN Decade GOOD program.

AUTHOR CONTRIBUTIONS

MG, VG, HG, DB, KI, AO, and MT organized the workshops. MG, VG, and HG designed and wrote the manuscript with contributions from all co-authors. All the authors discussed and reviewed the manuscript.

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APPENDIX

TABLE A1 | Characteristics of each generation of floats: type of sensors, known issues, drift correction, number of floats equipped with O₂ sensors, number of profiles (in June 2020) and data streams.

| Generation of floats | Sensors type | Known issues | Drift correction | # floats | # profiles | # RT (1) | # A (2) | # DM (3) |
|----------------------|-----------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|------------|----------|---------|----------|
| First Generation | SBE43 sensors | Sensor stability and drift ⁽⁴⁾ | A gain and offset formulation established in stable deep waters ⁽⁵⁾ | 160 | 26921 | 9972 | 0 | 16949 |
| Second Generation | Aanderaa 3830/3835 4330/4831 | Inadequate temperature compensation and/or distorted, incorrect O ₂ response especially at low to intermediate O ₂ levels ⁽⁶⁾ | Either a gain and offset formulation established in stable deep waters ⁽⁵⁾ or a temperature-dependent O ₂ gain ⁽⁶⁾ | 598 | 111520 | 41929 | 2730 | 66861 |
| Third Generation | Aanderaa 4330/4831-SBE63, RINKO, ARO-FT | Linear O ₂ sensitivity drift ⁽⁶⁾ | Drift correction by an O ₂ gain factor using the surface p O ₂ estimated either from in-air measurement or estimated from climatologies at the ARGO-measured Temperature and salinity ^(6,7) | 498 | 50464 | 22187 | 4883 | 23394 |

⁽¹⁾Real-Time, available 24 h after profiling; ⁽²⁾Adjusted, RT data after automated QC; ⁽³⁾Delayed-Mode, best quality data including realistic error estimates, sophisticated data adjustments and QC procedures, manual inspection by either the float's PI or pre-identified Delayed Mode (DMQC) expert (e.g. Bittig et al., 2019); ⁽⁴⁾Gruber et al., 2010; ⁽⁵⁾Takeshita et al., 2013; ⁽⁶⁾Bittig et al., 2018; ⁽⁷⁾Thierry and Bittig, 2018.