



Interannual Variation in the Population Dynamics of Juveniles of the Deep-Sea Crab *Chionoecetes tanneri*

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Understanding the population dynamics of commercially fished deep-sea species, on seasonal to inter-annual scales, is of great importance in areas where fishing pressure is high. The remoteness of the deep-sea environment constitutes a challenge for monitoring these populations. The few studies that have investigated population structure of deep-sea species, have used trawls, a destructive approach for benthic ecosystems. The development of deep-sea observatories offers a continuous long-term presence on the seafloor. Using imagery from the Ocean Network Canada deep-sea observatory, video footage was acquired on a daily basis and analyzed to describe the population dynamics of the deep-sea crab Chionoecetes tanneri located in depths of 900-1000 m in Barkley Canyon, off Vancouver Island (BC, Canada). The objectives here were to describe the dynamics of the local population in relation to changes in environment and/or life-cycle related behaviors. Sampling sites were located along the canyon axis and on the canyon wall. Only juveniles (1-10 cm) were found at the axis site (1000 m depth) with densities varying from 0 to 144 individuals/m². On the canyon wall (900 m depth), adults (>10 cm) were sporadically observed and densities were lower (max. 13 individuals/m²). Variation in density between the two sites reflected the observed arrival of small individuals (<2.4 cm) at the axis site in summer and autumn. Apart from a distinct migration event in January 2015, intra-annual variability in density was higher than inter-annual variability as illustrated by significant annual and sub-annual cycles of 7.5 and 3.5 months. Our results confirmed the hypothesis of ontogenic migration and provide further insight into inter-molt periodicity; we demonstrated a duration of 16 months for one crab to grow from 1.8 cm to more than 5 cm. Our findings also show a correlation between population dynamics, chlorophyll concentration, surface wave height and wind speed, suggesting that surface blooms have a potential influence on the migration patterns of C. tanneri. Although our study was spatially limited (maximum surface 9 m), this innovative long-term study of a deep-sea crab demonstrates the potential of deep-sea observatories to enable research into the population dynamics of some deep-sea species.

Keywords: marine imagery, deep-sea observatory, Ocean Network Canada, oxygen minimum zone, tanner crab, reproduction, temporal trends, British Columbia

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INTRODUCTION

With the decline of some species targeted by fisheries, including crab stocks (Orensanz et al., 1998; Johnston et al., 2011; Mullowney et al., 2014), and with increasing efficiency of vessels and fishing gear, fleets now operate at increasingly greater depths, impacting populations down to 3000 m (Ramirez-Llodra et al., 2011). To evaluate the viability of a fishery, knowledge of the species' biology, population dynamics, and life-history traits is essential. However, due to the remoteness of the environment, our understanding of the structure and function of deep-sea ecosystems and of species' dynamics is still too rudimentary to properly inform sustainable fisheries (Francis and Clark, 2005; Ramirez-Llodra et al., 2011). To date, most studies on deep-sea commercial species are based on trawling surveys (Francis and Clark, 2005; Devine et al., 2006). While trawling is an appropriate method to collect samples for precise identification, measurements, sexing and various observations such as hardness of shell or presence of diseases in deep-sea decapods (Phillips and Lauzier, 1997; Workman et al., 2002; Boutillier and Gillespie, 2005; Perry et al., 2005; Keller et al., 2012; Cusba and Paramo, 2017; Chakraborty et al., 2018), it is not suitable for high frequency time series (López Abellán et al., 2002; Keller et al., 2012). In addition, trawling is a destructive sampling technique which can impact the seafloor (Puig et al., 2012; Martín et al., 2014; Clark et al., 2016). In contrast, in situ video surveys were used to quantify the density of Nephrops norvegicus as a complementary method to fishery trawling (ICES, 2013; Martinelli et al., 2013). Over the last decade, the increasing use of imagery has provided insights into our knowledge of deepspecies distribution ranges and abundances while mitigating the impact of more destructive techniques on the environment (Van den Beld et al., 2016; De Leo et al., 2017; Domke et al., 2017). More recently, the development of deep-sea observatories, facilitating multidisciplinary studies over periods of several years at high temporal resolution, offer new means to study and assess the temporal dynamics of deep-sea ecosystems (Aguzzi et al., 2012; Matabos et al., 2012; Lelièvre et al., 2017; Chauvet et al., 2018). In this study, we propose to use this technology for the first time to assess the population dynamics of a commercially targeted deep-sea crab species.

One of the best known groups of crustacean is the infraorder Brachyura (true crabs). They can colonize diverse environments and are found in a broad range of salinity [from freshwater to hypersaline >175% of normal (Gross, 1961; Yeo et al., 2008)], temperature [<0 to 43°C (Edney, 1961; Dawe and Colbourne, 2002)] and oxygen [supporting life in hypoxia (Levin, 2003; Ng et al., 2008)]. They can be terrestrial or aquatic and colonize areas from 2,000 m above sea level on mountains down to abyssal depths (6,000 m deep) (Ng et al., 2008). The biology and ecology of deep-sea crabs has been studied mostly in chemosynthetic environments, such as hydrothermal vents, because of their potential adaptations to extreme environmental conditions (e.g., Chausson et al., 2001; Goffredi et al., 2014; Watsuji et al., 2015, 2017; Hui et al., 2017). Few studies have focused on population dynamics, with the exception of some harvested species, whether as bycatch such as the portunid crab Bathynectes piperitus in

Benguela (Abelló et al., 1990) and the red crab *Chaeceon affinis* in the Faroes (Lorance, 2007) or as a primary targeted species, e.g., the red king crab *Paralithodes camtschaticus* (ICES, 2010) with its high commercial value (Dvoretsky and Dvoretsky, 2016). Only a subset of those studies has focused on spatial structure at small scales and life-history characteristics (e.g., Abelló et al., 1990; López Abellán et al., 2002; Martí-Trujillo et al., 2014; Biscoito et al., 2015). Indeed, most studies have focused on the estimation of biomass for the management of the development of new fisheries (Defeo et al., 1991; Pezzuto et al., 2006; Perez et al., 2009; Masello and Defeo, 2016). These studies often recommended a need for increased knowledge of population dynamics (Perez et al., 2003).

In British Columbia (Canada), four species of crabs are commercially targeted: the Dungeness crab (Cancer magister), the red rock crab (Cancer productus), the golden king crab (Lithodes aequispinus) and the red king crab (Paralithodes camtschaticus) (British Columbia Marine Conservation Analysis Project Team, 2010), all distributed at depths from shallow waters to 400 m (Butler and Hart, 1962; Rickets et al., 1968). A decline in the Dungeness crab fishery in the 1990s encouraged the development of a new sustainable fishery along the Pacific coast of Canada (Perry et al., 2005) and the grooved Tanner crab C. tanneri became a species of interest. Before a fishery was instigated, an initial review of knowledge on the biology and ecology of C. tanneri and its congeneric species C. angulatus identified numerous data gaps regarding the distribution, abundance, population structure, life history characteristics, and bycatch in existing fisheries (Phillips and Lauzier, 1997). As a result of subsequent trawl and trap surveys used to assess abundance and life-history features (Boutillier et al., 1998; Workman et al., 2001, 2002), conservative commercial fishing quotas were set, and one area was closed to fishing as a control (Perry et al., 2005). Because of its potential as an emerging fishery, it is of great importance to better understand the distribution and population dynamics of C. tanneri.

The genus Chionoecetes includes four species from the Gulf of Alaska to northern Mexico (Rathbun, 1925; Pereyra, 1966; Hart, 1982): Chionoecetes bairdi and C. opilio, which occur in waters shallower than 450 m and C. tanneri and C. angulatus found from 458 to 1784 m and from 1069 to 3000 m, respectively (Rathbun, 1925; Pereyra, 1966; Hart, 1982; Workman et al., 2001). Stages of maturity are depth-segregated, with adults living from 600 to 900 m depth (Pereyra, 1966; Workman et al., 2002; Gillespie et al., 2004; Keller et al., 2012, 2016), and juveniles and subadults (immature with carapace width <10 cm; Keller et al., 2016) deeper than 900 m (1200 m for C. angulatus). Reproduction also impacts crab distribution through aggregating behaviors of adults in late winter (Pereyra, 1966; Workman et al., 2001). Chionoecetes crabs are opportunistic and feed on benthic invertebrates: mostly amphipods, copepods, smaller juvenile Chionoecetes, ophiuroids, clams, worms and detritus (Phillips and Lauzier, 1997).

Since 2009, the Ocean Networks Canada (ONC) observatory has provided continuous interdisciplinary data at various locations off Vancouver Island (British Columbia, Canada), from coastal areas to the abyssal plain. One of ONC's research themes focuses on the study of bentho-pelagic coupling in Barkley Canyon, a mid-slope submarine canyon located in the Northeast Oxygen Minimum Zone (dissolved oxygen <0.5 mL/L). Recent studies reported the presence of C. tanneri from 550 to 1400 m depth in the region (De Leo et al., 2017; Doya et al., 2017; Chauvet et al., 2018). ONC cameras located between 800 and 1000 m depth along the axis of Barkley Canyon have revealed the presence of a few adults and a large number of juveniles of C. tanneri (Doya et al., 2017; Chauvet et al., 2018). Barkley Canyon has been hypothesized to offer shelter for species with a high tolerance to hypoxia (Chauvet et al., 2018). The seasonal dynamics that characterize benthic communities in the canyon (Doya et al., 2017; Chauvet et al., 2018) could affect the behavior and dynamics of the crab populations in relation to changes in environmental conditions or biotic interactions (e.g., predation, resource variability). Using available long-term, high-resolution data provided by ONC, this study aims to demonstrate that the use of imagery offers an alternative method to study deep-sea species population dynamics. More specifically, the objectives are to: (i) describe the dynamics of the local population of C. tanneri and (ii) investigate how these dynamics relate to changes in environmental factors and/or life-cycle related behaviors. We expected that at depths > 890 m, mainly juvenile C. tanneri would occur, particularly since this would be an area with few predators but sufficient food to allow their development. We also expected to observe the seasonal arrival and departure of crabs linked to reproductive migration (Jamieson et al., 1990; Pereyra, 1966; Workman et al., 2001). Our study used daily video observations collected over a period of 2.5 years to measure abundance and size frequency of C. tanneri. Results will contribute to increasing biological knowledge useful for the sustainable management of this potential commercial species.

MATERIALS AND METHODS

Sampling Site

Barkley Canyon incises the continental margin 80 km west of Vancouver Island (British Columbia, Canada) commencing at a depth of \sim 400 m and opening out to a submarine fan at \sim 2,200 m depth (**Figure 1**). It is \sim 42 km long with a maximum width at the canyon head of 8 km.

The two sampling sites were located in the canyon axis (latitude: 48°19.0087'N, longitude: 126°03.077'W, depth: 985 m) at the ONC-designated pod 1 site and on the canyon wall (latitude: 48°18.8915'N, longitude: 126°03.4912'W, depth: 894 m) at the ONC-designated pod 4 and pod 3 sites. Pods are cabled instrument platforms equipped with biological and physico-chemical sensors. For more details on the cabled network specifications see Juniper et al. (2013).

Data Collection

Faunal Characterization

The crab *C. tanneri* (**Figure 2**) was identified and enumerated in video sequences that were recorded with a color camera mounted on a motorized pan/tilt head allowing for a maximum of 360° sweep for 5 min, every two hours (60 min per day) (all videos¹). Illumination was provided by two Deep-Sea Power and Light variable intensity projectors. Because the pan and tilt limit settings for the camera were modified during annual maintenance cruises, the surface area covered by the camera varied between 3.9 and 9 m² over the study period (see details in Table 1). From the 60 min of daily records, we analyzed the 5-min record from 0800 to 0805 daily (which we refer to as a "sample") from 12 June 2012 to 11 January 2015. This time window was chosen to minimize the number of gaps in the timeseries. Previous research at the wall site suggests the absence of a diel or tidal rhythm for this species (Doya et al., 2014). Each video was viewed using VLC media player®. All visible crabs were counted and density (ind/m²) obtained by dividing the observed abundance with the surface area of the field of view. Because the footage quality was too low for precise measurement on the wall (pod 3), only individuals from the axis were measured. For one video sequence per week, snapshots were taken to cover the total surface recorded during a single camera rotation using VLC 2.0.1[©]. All pictures were then overlapped with a perspective grid previously built using laser and referenced rulers with Imagel[©] (Ferreira and Rasband, 2012; Figure 3). From August 2014 to January 2015, the change in tilt did not allow the creation of a precise perspective grid for most of the surface covered by the camera; thus, the surface area over which crabs could be measured with sufficient precision was reduced to 0.5 m². We measured carapace width (CW), i.e., the greatest measurement across the branchial regions of the carapace excluding the lateral spines (Pereyra, 1966; Figures 2, 3), in crabs with visible carapace. To validate whether a single video per week provided a representative sample of crab size and abundance, we collected daily samples during three non-consecutive weeks (15 to 23 of June and 01 to 05 of August 2012, and from 26 to 31 of January 2013) (chosen during phases of increased or decreased crab density -results not shown-). Measurement accuracy (0.2 cm) was determined by sizing 10 crabs, 10 times in five different snapshots.

Environmental Characterization

In a previous study, we showed that benthic environmental conditions were homogeneous over the study period with temperature ranging from 3.51 to 4.07°C, oxygen concentration from 0.24 to 0.34 mL/L and the benthic boundary layer current varying from 0 to 0.2 m/s (Chauvet et al., 2018; **Supplementary Figure 1**). In addition, epibenthic community dynamics appear to respond predominantly to changes in surface rather than bottom conditions (Chauvet et al., 2018).

Atmospheric pressure (dbar), significant wave height (m), and wind speed (m/s) were acquired by an NBDC meteorological buoy 46206 on La Perouse Bank (Tofino, British Columbia, latitude: 48°50′24″N, longitude: 126°00′00″W²) (**Table 2**). Surface concentration of chlorophyll used for the analysis was provided as 8-day averages by MODIS, NASA Earth Observations (NEO) Goddard Ocean Color Group³ (**Table 2**).

¹http://dmas.uvic.ca/SeaTube

²http://www.ndbc.noaa.gov

³http://neo.sci.gsfc.nasa.gov



FIGURE 1 | Location map. Left panel: position of the cabled Ocean Networks Canada observatory. Right panel: Barkley Canyon showing the position of the sampling sites; the axis site is shown as a pink square and wall site as a yellow square. Inset side: topography of transects traversing the canyon lengthwise (A,B) and widthwise (C,D).



FIGURE 2 | (A) An adult *Chionoecetes tanneri* sampled with an ROV during a 2016 maintenance cruise at the wall (pod 3) at 890 m depth in Barkley Canyon (British Columbia, Canada). The carapace width (yellow line) is 15 cm. (B) Snapshot of this crab walking on the bottom before being sampled. (C) Snapshot of a video record at the wall (pod 3) station taken by the fixed camera showing two juveniles and one sub adult (on the right); the red line on the scaling ruler corresponds to 10 cm.

Ctation	Omilana	Datas	Comoro	Cureen engle	Curfees sourced
Station	Cruises	Dates	Camera	Sweep angle	Surface covered
Pod 1	2012	12 June 12 to 11 May 13	AXIS P1347 SubAqua Im.Syst.Inc.	360°	6.1 ²
Pod 3	2012	26 July 12 to 11 May 13	ROS HD inspector camera 5 MP	180°	4.3 ²
Pod 1	2013	12 May 13 to 15 Feb 14	Dragonfish	360°	9 ²
		16 Feb 14 to 05 May 14	SubC imaging	360°	7.2 ²
	2014	11 May 14 to 11 Aug 14	Dragonfish	180°	6.1 ²
		12 Aug 14 to 11 Jan 15	SubC imaging	100°pan +45°tilt	3.9 ²

TABLE 1 List of the characteristics of the camera systems deployed in Barkley Canyon (British Columbia, Canada) from (i) 12 June 2012 to 11 January 2015 at 985 m depth at pod 1 at the axis and (ii) 26 July 2012 to 11 May 2013 at 894 m depth at pod 3 on the wall.

Data Processing

A Kruskal-Wallis test showed no significant differences in size between the weekly and daily samples (p-value >0.2), confirming the accuracy of weekly sampling frequency in representing the dynamics in size frequency.

Because the size frequency distributions of individual *C. tanneri* displayed a multi-modal pattern, we assumed that the sampled population was composed of mixed cohorts. Histograms of the size frequency distributions were analyzed as mixtures of statistical distributions for samples containing at least 40 individuals (18 samples fitted this restriction). Histograms of classes of size frequency were derived following the criteria described by Jollivet et al. (2000), with most size-classes having at least five individuals, the number of adjacent empty classes minimized, and an interval greater than the error of measurement. We determined the overlapping component distribution that gives the best fit to the histogram with the "mixdist" package (Macdonald and Pitcher, 1979; Macdonald and Du, 2012) in R (RStudio Team, 2016). Measurements made on juveniles and sub-adults sampled in Oregon (United States)



FIGURE 3 | An example of a snapshot taken at 985 m depth at the axis (pod 1) in Barkley Canyon (British Columbia, Canada) combined with the perspective grid (each square = $10 \text{ cm} \times 10 \text{ cm}$). The red square delimits the area where measurements were made with sufficient precision. The purple line represents a 10-cm vector and the yellow line the measurement of carapace width.

(Tester, 1975) and British Columbia (Canada) (Gillespie et al., 2004) revealed nine consistent modes between 1 and 10.5 cm (Table 3). Input values in the function MIX can be used to test the validity of certain constraint parameters, here, the mean size for each cohort based on findings reported in the literature. The test, which is based on the chi-square approximation to the likelihood ratio statistic, is considered valid as long as most of the intervals have expected counts of >5. This allowed the identification of gamma components and their parameters (mean, sigma, estimated proportion), each corresponding to a different cohort. The mean size and sigma given by averaging the results of the MIX analysis were used to define cohorts observed at the axis at 985 m depth (pod 1) in Barkley Canyon. The entire set of observation dates was then decomposed into their individual constituent cohorts (i.e., for all dates, individuals were pooled into size class corresponding to defined cohorts) and these were used in the ensuing analyses. The measuring accuracy of our method resulted in overlap of the smallest cohorts given in the literature. Thus, we pooled the first three cohorts (i.e., cohort 1, 2, and 3 in **Table 3**) as a single group, labeled cohort 1 thereafter.

We computed the density time-series of each cohort and environmental factors with a Whittaker-Robinson (WR) periodogram to reveal potential periodicities. In the WRperiodogram analysis, time series are folded into Buys-Ballot tables with periods of 2 to a maximum of n/2, where n is the total

TABLE 2 | List of instruments acquiring environmental data in Barkley Canyon(British Columbia, Canada) including (i) hydrographic parameters on the seafloor atthe axis of the canyon at pod 1 station (48°19'N, 126°03'W) at 985 m depth, (ii)weather data from La Perouse buoy (48°50'N, 126°00'W, Tofino, British Columbia)and, (iii) sea surface chlorophyll concentrations from NASA satellites in a squaresurface around Barkley Canyon (45°56' to 50°05'N, 124°87' to 132°07'W).

Sampling Site	Instruments Sampling dates	Measured parameters	Sampling frequency	Units
Sea-floor Data	ADCP Jan-11 to Jan-15	Northward BBLc (Ubar)	10 s	m/s
		Eastward BBLc (Vbar)	10 s	m/s
		Temperature	10 s	°C
Weather data	La perouse bank buoy Jan-11 to Jan-15	Significant wave height	1 h	m
		Horizontal wind speed	1 h	m/s
		Atmospheric pressure	1 h	mbar
Sea-surface Data	NASA satellites Jan-11 to Jan-15	Surface chlorophyll concentration	8 days	mg/m3

BBLc = Benthic Boundary Layer current.

TABLE 3 | In gray, mean size of subadults and juvenile of Chionoecetes tannericohorts from trawl sampling of populations found in Oregon (United States)between April 1973 and March 1975 (Tester, 1975) and British Columbia (Canada)between 1999 and 2003 (Gillespie et al., 2004).

Literature			This study					
Cohort names		Mean size (cm)	Cohort names	N siz	lean e (cm)	Sd		
1		1	1	<	1.7	_		
2		1.4						
3		1.8						
4		2.6	4		2.4	0.4		
5		3.5	5		3.3	0.5		
6		4.9	6		4.3	0.5		
7		6.5	7			-		
8		8		>	5.0			
9		10.5						

In white, the parameters used to define the five cohorts of the juvenile population of C. tanneri in our study, measured weekly at 985 m depth along the axis of Barkley Canyon (British Columbia, Canada) from 16 June 2012 to 11 January 2015.

number of observations. Amplitude is the underlying statistic used in this periodogram function and equals the standard deviation of the means of the columns of the Buys-Ballot table (Legendre and Legendre, 2012). The WR periodogram can handle missing values in the datasets. Prior to periodogram analyses, trends were removed after linear regression and residuals were used in the periodogram analysis. Some degree of caution is warranted in the interpretation as this type of periodogram also finds the harmonics of basic periods to be significant (Legendre and Legendre, 2012).

Each density time-series of each cohort was tested for autocorrelation using the Auto-Correlation Function (ACF) (library stats, R). Correlations among cohorts and between cohorts and environmental factors were tested using the Cross-Correlation Function (CCF) (library stats, R).

To identify potential groups of seasons/years in the local population, we used Principal Component Analysis to visualize the distribution of individual samples (i.e., densities of measured crabs for each observation date) on the first two principal axes. PCA was performed on Hellinger-transformed density data, preserving the Hellinger distance which is appropriate in Euclidean -based multivariate methods. This transformation also mitigates the importance of zero-inflated data (i.e., to avoid inferring similarity between sites from double absences) (Legendre and Gallagher, 2001). This analysis suffered from a horseshoe distortion (Guttman effect) characterized as a onedimensional ecological gradient that bent into an arch in axis 1 - axis 2 space. This type of distortion limits interpretation and is often due to the progressive change of samples along an environmental gradient (Legendre and Legendre, 2012). As an alternative method, we computed extended dissimilarities (De'ath, 1999), allowing us to generate an ordination where the sites are ordered more linearly along the gradient. The step-across function in vegan was used to transform the dissimilarity matrix on which we applied a Principal Coordinate Analysis (PCoA) (Legendre and Legendre, 2012).

All statistical analyses were performed with R statistical software 3.3.2 (RStudio Team, 2016).

RESULTS

A total of 3,962 individuals were counted at the wall site (pod 3) from 26 July 2012 to 11 May 2013 while at the axis site (pod 1), a total of 53,040 individuals were recorded between 16 June 2012 and 11 January 2015. At both sites, crabs feeding on dead juvenile crabs and empty shells were observed (**Figure 4**).

Densities of C. tanneri varied with time (from 0 to 144/m² at the axis and 0 to $13/m^2$ at the wall) following a similar pattern at both sites during the overlapping sampling period (July 2012 to May 2013). Density was relatively constant from July to October before increasing to a maximum in mid-November 2012 (Figure 5) followed by a decrease to a minimum in December 2012. A second density peak occurred in mid-January 2013 at the wall (pod 3) attaining the same low values observed in the previous year. At the axis site, in 2013, periodic peaks of density occurred at the end of February, April, and July and from November to mid-January 2014. In 2014, peaks were again observed in April (minor) and then in July, September, late November and, in unusually high proportions, in January 2015 (Figure 5). An unusually high number of individuals were observed walking in the same direction (144 ind/m²) on 11 January 2015 (Supplementary Figure 4). Whittaker-Robinson periodograms revealed 3 significant scales of periodicity at the axis: a broad ~annual cycle (from 351 to 393 days), an intermediate cycle of \sim 7.5 months (from 210 to 239 days) and a short cycle of \sim 2.5 months (from 72 to 73 days). The shorter time-series available for the wall site meant that only a fine cycle of \sim 3.5 months (from 102 to 114 days) was detectable.

Depending on the orientation of the camera and variations in total surface area across the different recording periods (**Table 1**), the proportion of enumerated crabs that could be measured varied over time. From June 2012 and February 2014, 35–63% of the counted crabs on the images could be measured. Between August 2014 and January 2015 this proportion dropped to 18%. A total of 4,985 crabs were measured at the axis (pod 1). No crabs were measured at the wall because of low video quality. However, even if a temporal approach was not possible, with the addition of data from a ROV video transect, we were able to identify adults, subadults (i.e., immature) and juveniles of *C. tanneri* at the wall (**Figure 2**).

At the axis site, the mean carapace width (CW) of individuals in the local crab population was 2.3 cm (SD = 1.1 cm; range: 0.1–12.0 cm) over the entire study period. More than 50% of the measured crabs were between 1.6 and 3.0 cm CW (**Table 4**), indicating they were juveniles according to the literature (<4.0 cm; Workman et al., 2002). Classes of crabs <0.8 cm and >5 cm CW contained fewer than 50 individuals. It is thus important to note that the full population structure was not detected at this site. MIX analysis showed that not all cohorts were present in each sample (**Table 4** and **Figure 6**). However, except for the first and the last cohorts ($\mu = 1$ cm and $\mu = 6$ cm, respectively), each one was present in at least 5 out of the 18



FIGURE 4 | Illustration of cadavers observed at 985 m depth at the axis site in Barkley Canyon (British Columbia, Canada) in June 2013 (left picture) and September 2014.





samples tested and was represented by >50 individuals in total (**Table 4**). Seven cohorts were detected overall (**Table 4**, last three lines) and while the proportion of the population in each cohort varied with time, the most frequently represented size classes had mean carapace widths of 1.4, 1.8, and 2.5 cm. Our results were similar to the mean size recorded in the literature for the 5 first cohorts with carapace widths of 1, 1.4 and 1.7 cm (these three grouped for our analyses), and 2.4 and 3.3 cm (**Table 3** and **Figure 6**). The next two cohorts were smaller than indicated by

the literature, at 4.3 instead of 4.9 cm and 5.8 instead of 6.5 cm. Because of the low abundance of individuals with CW > 5 cm, the three last modes were grouped into a single cohort 7 of subadults [immature crabs with carapace widths between 4.0 and 10.0 cm (Workman et al., 2002; Keller et al., 2016)] (**Table 4**).

Enumerated crabs in each sample were assigned to cohorts using the parameters defined for each cohort by MIX analysis (**Table 4**). At the beginning of the study period, from June to December 2012, the crab population was dominated by cohort 1 **TABLE 4** | Results of MIX analysis conducted on carapace width of *C. tanneri* (for *n* > 40) from 16 June 2012 to 11 January 2015 at 985 m depth at the axis of Barkley Canyon (British Columbia, Canada).

Date	n	Cohort parameters		Modes n°								
			1	2	3	4	5	6	7	X ²	Pr(>Chisq)	df
14/10/2012	66	$\mu \pm$ sigma (cm)		1.2 ± 0	1.9 ± 0.2	2.4 ± 0	3.4 ± 0.5		5.1 ± 1.3	17.882	0.212	14
		proportion (%)		4	25	26	32		13			
11/11/2012	153	$\mu \pm sigma$ (cm)	1 ± 0	1.5 ± 0.2		2.5 ± 0.5				5.27	0.728	8
		proportion (%)	10	75		15						
09/12/2012	63	$\mu \pm sigma$ (cm)		1.6 ± 0.4		2.6 ± 0.4		4.2 ± 0.3		12.218	0.271	10
		proportion (%)		60		35		5				
20/01/2013	41	$\mu \pm$ sigma (cm)			1.8 ± 0.6	2.9 ± 0.2	3.3 ± 2			9.814	0.457	10
		proportion (%)			28	60	12					
15/02/2013	67	$\mu \pm$ sigma (cm)				2.5 ± 0.4	3.1 ± 0.4	4.2 ± 0.1	5.3 ± 0.4	9.172	0.102	5
		proportion (%)				45	46	4	5			
11/04/2013	55	$\mu \pm$ sigma (cm)			1.7 ± 0.4		3.0 ± 0	3.8 ± 0.2		10.648	0.3	9
		proportion (%)			86		6	8				
23/05/2013	46	$\mu \pm$ sigma (cm)			1.9 ± 0.4		3.3 ± 0.3	4.9 ± 1.2		39	0.672	44
		proportion (%)			47		32	21				
26/06/2013	43	$\mu \pm$ sigma (cm)			2.1 ± 0.5	2.6 ± 0.1	3.5 ± 0.1	4.2 ± 0.1		25.672	0.266	22
		proportion (%)			75	14	7	4				
23/09/2013	41	$\mu \pm$ sigma (cm)		1.5 ± 0.3		2.3 ± 0.2	3.2 ± 0.3	3.8 ± 0		5.675	0.578	7
		proportion (%)		27		51	18	4				
27/10/2013	40	$\mu \pm$ sigma (cm)				2.4 ± 0.5	3.1 ± 1			21.844	0.827	29
		proportion (%)				62	38					
13/11/2013	44	$\mu \pm$ sigma (cm)				2.6 ± 0.5		4.8 ± 0.7	10.1 ± 0.2	41.684	0.907	55
		proportion (%)				90		7	3			
22/01/2014	62	$\mu \pm$ sigma (cm)			2.2 ± 0.4	2.9 ± 0.2	3.8 ± 0.5		$6.81 \pm 0;$	30.853	0.3724	29
									$12.3\pm\ 0.2$			
		proportion (%)			43	18	34		5			
27/02/2014	45	$\mu \pm$ sigma (cm)	1 ± 0.0			2.4 ± 0.6		4.1 ± 0.4		7.288	0.923	14
		proportion (%)	4			92		4				
09/04/2014	56	$\mu \pm$ sigma (cm)			1.8 ± 0.1	2.7 ± 0.3		4.3 ± 0.4		15.087	0.179	11
		proportion (%)			62	29		9				
21/05/2014	46	$\mu \pm$ sigma (cm)			1.6 ± 0.2	2.5 ± 0.5		4.2 ± 1.2		18.351	0.863	26
		proportion (%)			40	42		18				
02/07/2014	74	$\mu \pm$ sigma (cm)				2.6 ± 0.7		4 ± 0.4	5.8 ± 0.4	16.506	0.685	20
		proportion (%)				63		24	13			
11/01/2015	46	$\mu \pm$ sigma (cm)			1.7 ± 0.5	2.4 ± 0.2	3.4 ± 0.4		5.8 ± 0.2	9.912	0.271	8
		proportion (%)			56	27	15		2			
		Mean (µ)	1.0	1.4	1.7	2.4	3.3	4.3	5.8; 11.2			
		Mean (sigma)	0.1	0.2	0.5	0.4	0.5	0.5	0.4; 0.2			
		Total n counted	17	166	235	355	128	59	27			

Validity of the model is verified with an ANOVA. "n" stands for the number of individual measured. Modes correspond to the different cohorts. Cohorts 1, 2, 3 were grouped for further analysis (see text for details). Mean size (μ) was used as constraint parameter based on mean size of each molt reported in the literature (**Table 3**).

(60%) (**Table 4** and **Figure 7**). Subsequently, a pattern emerged with small juveniles (cohort 1) dominating in spring and larger juveniles (cohorts 4 and 5) dominating in summer (**Table 4** and **Figure 7**). More precisely, the density peaks observed in April in 2013 and 2014 were attributable to the arrival of cohort 1 individuals (**Figures 5**, 7) while the peaks in July in 2013 and 2014 were due to cohorts 4 and 5. In Autumn 2012 and 2014, cohort 1 dominated, while in Autumn 2013 cohort 4 and 5 were dominant (highest densities occurred in November

each year). In winter, the peaks in density observed between January and March in 2013, 2014, and 2015 were attributable to cohorts 4 and 5 (**Figure 7** and **Table 4**). The proportion of large juveniles and subadults (cohorts 6 and 7) peaked at >10% in October 2012, late May and mid-November 2013, and late May and July 2014 (**Table 4** and **Figure 7**). The smallest cohorts displayed a significant periodicity at 5.5 months, while cohorts 4 and 5 displayed significant periodicity at 1, 9, and 12 months.



Auto-correlation functions revealed significant correlations for each cohort for all consecutive weeks (significant correlations for lags from 1 to 2 weeks). Cohort 1 was also significantly autocorrelated with a lag of \sim 5 months, and cohort 4 with a lag of 1.5 months. Large juveniles and sub adults from cohorts 4, 5, 6 and 7 were all cross-correlated with no lag (**Table 5**). Negative lags of 2.5 to 7 months between consecutive cohorts might indicate that an increase of the smallest cohort could induce an increase in the following biggest cohort with a lag of several months. For example, an increase in the smallest juveniles could lead to an increase of cohort 4 and 5 with a lag of 2.5 months (**Table 5**). Positive lags were significant but these correlations are more likely a consequence of covariance related to the annual cycle detected within each cohort.

The absence of correlations between cohort 1 and the largest cohorts is also supported by PCoA (**Figure 8**), which explained 83% of the variance. Cohort 1 was negatively correlated, and cohorts 4, 5, 6, and 7 were positively correlated with the first axis, which showed a gradient of observations from 2012 to 2014–2015 (from left to right). Cohort 4 was positively correlated and cohorts 6 and 7 were negatively correlated with the second axis. This analysis confirmed the association of Cohort 1 with 2012, cohorts 4 and 5 with 2013 and cohorts 6 and 7 with 2014.

Increases in density of cohorts 1 and 6 after 3.5 months, and of cohorts 4, 5, and 7 after 6 months were correlated with an associated increase in chlorophyll concentration (**Table 6**). Similarly, the densities of the three first cohorts were positively

correlated with increases in wave height and wind speed. The other tested environmental parameters (*in situ*) were also significantly correlated but with a very low coefficient and are thus not shown (ccf < 0.25).

DISCUSSION

In this study, populations of juvenile C. tanneri from 900 to 1000 m depth in Barkley Canyon, British Columbia, were studied at daily to weekly scales over two years using imagery data. To our knowledge, this paper presents the first study of the population dynamics of any deep-sea species making use of the high temporal resolution imagery provided by cabled deepsea observatories such as Ocean Networks Canada. Until now, population dynamics of deep-sea species were inferred from samples collected using trawling (Laurenson et al., 2001; Francis and Clark, 2005; Devine et al., 2006; ICES, 2013; Martinelli et al., 2013) or, rarely, using a towed camera (Tuck et al., 1997; Campbell et al., 2009). Trawling provides limited sampling rate and is destructive for seafloor biota and the environment. The imagery provided by observatories is non-destructive and gives a fine temporal resolution over long time periods, and has the potential to open up promising new avenues of research for the study of deep-sea populations.

Crabs observed at 1000 m depth in Barkley Canyon measured from 1.0 to 12.0 cm carapace width (CW), with 95% of them being juveniles (CW: 1.0–4.0 cm). The main difference between the wall (900 m depth) and the axis (1000 m depth) sites was the sporadic presence of adults at the wall site (personal observation), while only juveniles and sub-adults occurred at the deeper axis site. These observations are consistent with the known depth distribution ranges of the life history stages of the species (Pereyra, 1966; Tester, 1975; Jamieson et al., 1990; Boutillier et al., 1998; Workman et al., 2001; Keller et al., 2012).

Seven of the 9 cohorts assigned to juvenile and sub-adult stages described in the literature were observed in this study (Tester, 1975; Gillespie et al., 2004). Most crabs belonged to cohorts 1 to 4 (maximum carapace width \pm 2 to 3 cm) suggesting that as juveniles grow they migrate to other, probably shallower, areas they enter the adult population that is commonly found living between 600 and 900 m depth (Workman et al., 2001; Gillespie et al., 2004). Mean carapace width for cohorts 1 to 4 coincided with those estimated from trawl data while mean CW for cohorts 5 to 7 were slightly smaller (Tester, 1975; Gillespie et al., 2004). The smaller carapace width measured for the older cohort could be due to measurement bias, lower growth rates related to sever hypoxic conditions, or it may indicate that the biggest crabs of the cohort are not found in the area. A minimum size threshold or trade-off in energy allocation might prevent the smaller crabs from undertaking migration to shallower areas. The axis of the canyon is located in the core of the Pacific Oxygen Minimum Zone where oxygen levels and temperature are stable with waters characterized as severely hypoxic ($\mu = 0.3 \text{ mL/L}$) and cold (3.7°C) throughout the year (Chauvet et al., 2018). Juveniles of decapods develop different strategies to overcome hypoxia (Alter et al., 2015). Growth tends



FIGURE 7 | Time-series of the density of each cohort of *C. tanneri* measured on each observation date. Measurements were made from 16 June 2012 to 11 January 2015 at 985 m depth at the axis site in Barkley Canyon (British Columbia, Canada). Colors represent the proportion of each cohort. Blue stars indicate dates when camera parameters were changed. In gray, the time period for which the proportion of crabs that could be accurately measured was low compared to the total number of crabs in the images (small surface area available for accurate measurements). Please note that for the last date (11 January 2015) an expanded scale was used to accommodate the larger densities encountered.

TABLE 5 Resu	Its of the cross correlation function analysis performed between cohorts of juveniles of C. tanneri samp	oled with a stationary camera from June 2012 to
11 January 201	5 at 985 m depth along the axis of Barkley Canyon (BC, Canada).	

Cohort (x)	Cohort (y)	Lag (months)	Cor						
1	4	0	+	-2.5	+				
	5	0	+	-2.5	+				
	6					-5	-		
	7			-2.5	+				
4	5	0	+	3	+				
	6	0	+	-7.5	+	1:3	+	6.5	+
	7	0	+			3	+	6	+
5	6	0	+	-4	+	-1	+	6.5	+
	7	0	+	-4	+				
6	7	0	+	-6.5	+	-4	+	5:6	+

Cor indicates the direction of the correlation. When cohort (x) and cohort (y) are correlated at a negative lag, then x could influence y at that lag. When cohort (x) and cohort (y) are correlated with a positive lag, then y could influence x at that lag.

to be higher in warmer water for cold-water species of crabs (Siikavuopio and James, 2015). In our study, the larger juveniles probably migrate from the axis site to more oxygenated and warmer habitats that can result in enhanced growth. Conversely, small juveniles might aggregate at depths where the OMZ core is developed, to avoid low oxygen-intolerant predators (Workman et al., 2001) or to be deeper than their predators, for example the thornyhead *Sebastolobus alascanus* (which is absent in the axis of the canyon, but present at 400 m depth in the near-slope (P. Chauvet, personal observation)). Alternatively, the smallest juveniles may aggregate away from adults, as this species is known for cannibalism (Phillips and Lauzier, 1997). This latter hypothesis is supported by the observation of a small increase in juvenile density at 1000 m depth in April, as adults migrate down to 800 m depth to reproduce (Pereyra, 1966; Jamieson et al., 1990; Workman et al., 2001).

Our observations provide some insights into the patterns in molting and recruitment for *C. tanneri* inhabiting the study area. However, we could not resolve the first molting steps described in previous studies (Tester and Carey, 1986; Gillespie et al., 2004) because we pooled at least 3 cohorts, as defined in the literature, into a single cohort. Initial recruitment of *C. tanneri* larvae occurs at various depths (Lough, 1975; Keller et al., 2012), and ontogenetic migration follows to depths deeper than 900 m (Workman et al., 2001; Gillespie et al., 2004). This pattern is consistent with our observations of mass juvenile arrival events at



the end of Autumn each year (i.e., November) and confirmed by the high abundance of juveniles at 890 m depth at the gas hydrate site of Barkley Canyon over the winter in 2013 (Doya et al., 2017). Except for 2014, the peak Autumn density corresponded to cohorts 1–3 (<1.9 cm CW) while the major aggregations observed in February consisted mainly of cohort 4 (between 2 and 2.8 cm CW). The duration between these two major aggregating events coincides with the ~3-month and annual periodicities characterizing the evolution of density at both the wall and axis sites.

Our observations corroborate the known reproductive cycle of C. tanneri. Mature females aggregate at 500-1200 m depth to spawn by the end of winter (Keller et al., 2012). Females then aggregate with males at 600-800 m depth in April to mate (Jamieson et al., 1990; Gillespie et al., 2004). Larval recruitment occurs in June-July at a size of ~0.4 mm (Tester and Carey, 1986). Trawl hauls conducted from 300 to 1200 m depth in southern Oregon revealed the presence of individuals $\sim 1 \text{ cm}$ carapace width in April, 1.4 cm in August, and 1.9 cm in October-November (Tester and Carey, 1986) as we found in our study. The 2.5-month lag correlation between cohort 1–3 (<1.9 cm) and cohort 4 (2-2.8 cm) could reflect the time lag between two molts, as observed between November 2012 and February 2013. The major aggregations observed in February are likely a result of gathering behavior for molting (e.g., Dew, 2010). Based on our correlation results, an additional 13.5 months were required to grow from cohort 4 to cohort 7 (from 3 cm to >5 cm). With a total of \sim 20 months required to develop from the egg to a juvenile of 2.7 cm CW (i.e., cohort 4) (Tester and Carey, 1986),

TABLE 6 Results of the cross correlation function analysis performed between
cohorts of juveniles of C. tanneri and environmental parameters.

		Lag		Lag		Lag	
Environment	Cohort	(months)	Cor	(months)	Cor	(months)	Cor
Chlorophyll	1	0	_	-3.5	+		
	4					-6	+
	5					-6	+
	6	0	+	-3.5	+		
	7	0	+			-6	+
Wave height	1	0	+	-1.5	$^+$		
	4	0	+	-4.5	$^+$		
	5	0	+				
Wind speed	1	0	+				
	4	0	+				
	5	0	+	-4.5	+		
Atm. Pressure	1	0	-			-5:-6	+
	4	0	-			-6	+
	6	0	+	-4.5	+		
	7	0	+				

C. tanneri were sampled using a stationary camera from June 2012 to 11 January 2015 at 985 m depth at the axis of Barkley Canyon (BC, Canada). Surface chlorophyll concentrations (mg/L) was obtained with NASA satellites and the MODIS model. Wave height, wind speed and atmospheric pressure were obtained with LaPerouse bank buoy (Tofino, BC, Canada). Cor indicates the direction of the correlation. As the environment is used as a predictor, only the negative lag are shown.

our results indicate that in Barkley Canyon, it takes 2 years and 9 months to grow from an egg to a juvenile of 5 cm CW (the biggest individuals observed in our study). This is 1 or 2 molts away from being an adult which is in agreement with the conclusions of Gillespie et al. (2004) for British Columbia (Canada) crabs. The population of juveniles we observed is thus composed of newly settled recruits and juveniles from the two previous years (**Figure 9**). The biggest individuals observed at the end of our time-series, i.e., cohorts 6 and 7, might therefore be small individuals from cohort 1 to 3 remaining from the Autumn 2012. This is further supported by evidence of molting, (i.e., empty carapaces observed at different times of the year in June and early August 2013 and in early July, August and all of September 2014; **Figure 4**).

Our study confirms the known annual reproductive cycle of C. tanneri, by analyzing each cohort separately. Annual periodicity will inherently lead to significant correlations among the different cohorts at different time lags. However, the proportions of each cohort varied strongly between aggregation events, within and among years. Associated high intra- and interannual variability in the density of crabs can be attributed to the interactions of multiple factors. Indeed, environment, seasonal food arrival (the Autumn density peak at this site is synchronized with the massive arrival of copepods; De Leo et al., 2018), internal rhythms, biotic interactions within and among cohorts (e.g., predation, competition, molting) and interactions with other species (e.g., predation). The influence of surface conditions can partly explain the large fluctuations. For example, the peak density in July 2014 could be a consequence of the surface Spring bloom that would have increased the input of food inside the



canyon (Chauvet et al., 2018). The number of individuals in cohorts 6 and 7, along with the population mean carapace width, significantly increased over the entire period of the study. While a decrease in recruitment, as previously observed by Keller et al. (2012), could account for a higher proportion of larger cohorts, an increase in food input from the surface related to unusually high concentrations of surface chlorophyll above Barkley Canyon starting in 2013 (Supplementary Figure 2; Chauvet et al., 2018), could have supported faster growth and/or delayed the migration of the largest juveniles. This latter hypothesis is supported by the significant correlation between surface production and an increase in the density of crabs at different time lags for all cohorts. Positive correlation between weather conditions and surface chlorophyll concentrations supports the hypothesis that, at the juvenile population scale, annual changes in abundance are mainly related to surface production. Keller et al. (2012) found a significant link between the depth distribution of C. tanneri and the Pacific Decadal Oscillation index (an index of climate variability for the California Current System; Schwing et al., 2009), showing that tanner crabs tend to be deeper when waters are more productive.

While our study demonstrates the potential of a deep-sea observatory as a novel method to study population dynamics of certain deep-sea species, using imagery to quantify the structure of benthic communities has certain limitations. The small area of the seafloor (maximum of 9 m²) sampled constrains the spatial scale of the study and caution must be exercised in interpretation and extrapolation of the results to a broader area. Furthermore, the unusually high arrival of crabs in January 2015 compared to other years could be a bias linked to small surface covered. Indeed, it is possible that we captured the main herd in 2015 while we only captured secondary herd the previous years when we also noted smaller increases in density. The camera angle can bias measurements leading to decreased precision in measuring small sized objects. Ideally to avoid distortion, the camera should be downward facing perpendicular to the sediment surface; however, this would unfortunately reduce the sampled surface area further. The change in camera angle over

our sampling period was a source of variability, even if, in this study, temporal breaks in the change of community structure did not coincide with the dates of maintenance cruises when the angle was changed (Chauvet et al., 2018). The instrumentation structure itself can attract crabs (Santelli et al., 2013) in the area through a "reef-effect." However, Vardaro et al. (2007) suggested that studies in the deep-sea using time-lapse cameras are likely not impacted by aggregating behaviors linked to the presence of the instrument. Moreover, the white light used during recordings is known to not influence the behavior of another species of the genus Chionoecetes (Watanabe, 2002). Furthermore, since the first deployment of the camera system was in 2009 or 2010, we would expect that any effect of infrastructure presence would have stabilized by 2012 and that the observed temporal changes in crab population structure corresponded to real biological changes (Matabos et al., 2012). Lastly, depending on the quality and the level of zoom of the camera, taxonomic identification from imagery remains an issue and is complicated when not associated with the collection of "voucher" individuals (e.g., Cuvelier et al., 2012; Henry and Roberts, 2014; Williams et al., 2015). In our case, we did not sample juveniles of C. tanneri and the identification of the smallest crabs was based on the monospecific presence of individuals with a carapace width >4 cm and the collection of adults in the area. At those depths, the only possible confusion could have been with C. angulatus (Rathbun, 1925; Pereyra, 1966). Several studies strongly suggest that only C. tanneri colonizes this site, and juveniles of C. angulatus are located deeper, between 1069 and 3000 m (Hart, 1982; Jadamec et al., 1999; Workman et al., 2001; Chatzievangelou et al., 2016; Doya et al., 2017; Thomsen et al., 2017; Supplementary Figure 3). Local specialists supported this taxonomic identification.

Accepting the use of imagery has certain limitations, we have demonstrated that this novel approach can enable analysis of deep-sea population dynamics of certain species. We were able to confirm the hypothesis that ontogenic migration occurs in this species and identified individual cohorts with a carapace width measurement accuracy of 0.2 cm. Our results bring further insights into the timing of departure and migration of the biggest juveniles from 1000 m depth and inter-molt periods. Finally, our findings suggest a strong link between surface conditions and the potential impact of surface blooms on the population dynamics and migration patterns of *C. tanneri*.

AUTHOR CONTRIBUTIONS

PC, MM, and AM conceived the ideas and contributed to the interpretation of the results. PC collected and analyzed the data. AM and MM supervised the research project. All authors assisted in the writing process and revised the manuscript.

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SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fmars. 2019.00050/full#supplementary-material

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Conflict of Interest Statement: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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