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OPEN ACCESS

APPROVED BY Frontiers Editorial Office, Frontiers Media SA, Switzerland

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RECEIVED 07 October 2024 ACCEPTED 08 October 2024 PUBLISHED 17 October 2024

CITATION

Barone P, Bedia MG and Gomila A (2024) Corrigendum: A minimal Turing test: reciprocal sensorimotor contingencies for interaction detection. *Front. Hum. Neurosci.* 18:1507296. doi: 10.3389/fnhum.2024.1507296

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Corrigendum: A minimal Turing test: reciprocal sensorimotor contingencies for interaction detection

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KEYWORDS

Turing test, interaction, sensorimotor contingencies, reciprocity, perceptual crossing

A Corrigendum on

A minimal Turing test: reciprocal sensorimotor contingencies for interaction detection

by Barone, P., Bedia, M. G., and Gomila, A. (2020). *Front. Hum. Neurosci.* 14:102. doi: 10.3389/fnhum.2020.00102

In the published article, there was an error in Figure 1 as published. The probability of success for block 3 in the bot condition should be 0.70, as correctly stated in Table 1 and the second paragraph of the **Results** section. However, in Figure 1, this value is incorrectly shown as 0.95. The corrected Figure 1 and its caption appear below.

The authors apologize for this error and state that this does not change the scientific conclusions of the article in any way. The original article has been updated.

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FIGURE 1

Successes and crossings per type of agent and block in Study 1. (A) Probability of success in each block per type of agent. The horizontal dashed line represents chance level (50%). (B) Mean number of crossings in each block per type of agent. Error bars depict 95% confidence intervals.