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# Using global datasets to estimate flood exposure at the city scale: an evaluation in Addis Ababa

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**Introduction:** Cities located in lower income countries are global flood risk hotspots. Assessment and management of these risks forms a key part of global climate adaptation efforts. City scale flood risk assessments necessitate flood hazard information, which is challenging to obtain in these localities because of data quality/scarcity issues, and the complex multi-source nature of urban flood dynamics. A growing array of global datasets provide an attractive means of closing these data gaps, but their suitability for this context remains relatively unknown.

**Methods:** Here, we test the use of relevant global terrain, rainfall, and flood hazard data products in a flood hazard and exposure assessment framework covering Addis Ababa, Ethiopia. To conduct the tests, we first developed a city scale rain-on-grid hydrodynamic flood model based on local data and used the model results to identify buildings exposed to flooding. We then observed how the results of this flood exposure assessment changed when each of the global datasets are used in turn to drive the hydrodynamic model in place of its local counterpart.

**Results and discussion:** Results are evaluated in terms of both the total number of exposed buildings, and the spatial distribution of exposure across Addis Ababa. Our results show that of the datasets tested, the FABDEM global terrain and the PXR global rainfall data products provide the most promise for use at the city scale in lower income countries.

## KEYWORDS

floods, cities, global datasets, rain-on-grid model, hydraulic model, risk

## 1 Introduction

Flood risk is an acute and growing problem in the cities of the global south. Often, hydraulic infrastructure and its maintenance is inadequate in these population centres (Lumbroso, 2020), and people living in these environments are more vulnerable to floods (Rentschler et al., 2022). The rapid and poorly regulated urbanisation occurring in these cities is increasing runoff on account of land use changes, and is also resulting in a greater number of people settling and properties being constructed in flood prone areas (e.g., Egbinola et al., 2017). Furthermore, the increasing occurrence of extreme rainfall intensities associated with climate change is elevating flood hazard in many places (Martel et al., 2021).

Flood risk assessments often rely on hydrodynamic models to map hazard, understand flood impacts, and explore interventions to mitigate risks (Lamb et al., 2009; Cai et al., 2019; Molinari et al., 2019). However, modelling flood hazard at the city scale is challenging, in part because of the need to consider multiple sources of flooding often present in cities. Urban infrastructure also presents a key challenge; data on the many fine scale features that exert strong controls on flow hydraulics is often scant, and representing their geometric and operational characteristics at scale is often unfeasible. One solution to the challenge of representing multiple sources of flooding is to use a direct rain-on-grid modelling approach where rainfall is applied directly to each grid cell of a 2D domain (Yu et al., 2016; UK Environment Agency, 2019). Runoff volumes are computed in each cell and are routed dynamically over the model terrain. Direct rain-on-grid modelling has been applied for over a decade now but has become more prevalent in recent years largely due to advances in computational power (Ryan et al., 2022), and is still regarded as relatively new compared to traditional approaches that model hydrology and hydraulics separately. Direct rain-on-grid modelling enables fluvial, pluvial, and tidal (where applicable) sources of flooding to be represented in an efficient manner. These models are primarily driven by topography and rainfall data, and as such these data form the critical inputs into the model. However, the global south suffers from a scarcity of these data, with local digital elevation models (DEMs) and rainfall data often being unavailable or limited in their coverage (van de Giesen et al., 2014; Hawker et al., 2018). These data gaps are increasingly being filled with global datasets.

The term *global datasets* refers to datasets with global or near global spatial coverage, which are partly or wholly derived from remotely sensed observations from Earth observation satellites. Global datasets have been used for some time now to study flood risk at large scales (Komi et al., 2017; Lindersson et al., 2020), as exemplified by the establishment of global flood models (GFMs) over the last decade or so. GFMs harness several global datasets to model and map flood hazard globally (Ward et al., 2015; Bernhofen et al., 2018). Similarly, satellite imagery is now being harnessed to construct historical flood extent maps with global coverage (Tellman et al., 2021). Such global hazard maps provide a consistent modelling approach and data, enabling objective flood risk management decisions to be made by those operating across multiple countries (Trigg et al., 2016). As global datasets and their derivative hazard maps improve in resolution and accuracy, they are increasingly being used in data scarce situations and at smaller (sub-national) scales including the city scale. One well documented example is the emergency response to Cyclones Idai and Kenneth in Mozambique in 2019, which used global flood extent maps from Fathom and the high resolution settlement layer to predict flood exposure at the district scale (Emerton et al., 2020). Global data such as terrain or precipitation are also being used by complementing them with local data at the sub-basin scale (Haile et al., 2016); the city scale (Sayers and Partners, 2019; McClean et al., 2020); and the infrastructure scale (Golder Associates, 2021). At these local scales, the spatial resolution and accuracy of global datasets is relatively low, and their use in assessing flood risk poses important questions about the efficacy of doing so. Research into this is ongoing (see for example; Domeneghetti, 2016; Ekeu-wei and Blackburn, 2018; Schumann et al., 2018; Courty et al., 2019; Fleischmann et al., 2019; Kettner et al., 2019;

Li et al., 2022); and needs to continue as new global datasets emerge and see use in a wide range of scales and situations.

This study aims to evaluate the suitability of relevant global datasets for mapping flood hazard in support of city-scale flood risk assessments in data scarce, low to middle income contexts. Specifically, we use global rainfall and terrain data to drive a flood hazard model then test the resulting hazard maps in a city-wide flood exposure assessment. We also test a GFM hazard map product in the exposure assessment. To conduct the tests, we first developed a city-scale rain-on-grid hydrodynamic flood model based on local data and used the model results to identify buildings exposed to flooding. We then observed how the results of this flood exposure assessment change when each of the global datasets are used in turn to drive the hydrodynamic model in place of the local dataset, and when the GFM flood hazard product is used instead of our flood hazard model output. Results are evaluated in terms of both the total number of exposed buildings, and the spatial distribution of exposure across the study area. Sensitivity analyses were also run on the key hydrodynamic model parameters that are uncertain, to place the results of the global dataset tests into the context of the uncertainties that are inherent in flood hazard modelling.

We test two global terrain datasets: the FABDEM (Forest And Buildings removed Copernicus DEM) (Hawker et al., 2022) and the MERIT (Multi-Error-Removed Improved-Terrain) DEM (Yamazaki et al., 2017). The FABDEM—derived from the Copernicus Global 30 m DEM (Copernicus, 2021)—is the first global digital elevation model (DEM) with forests and buildings removed at a 30 m resolution. It has been shown to be more accurate than other global DEMs, has a higher resolution than most global DEMs, and is therefore expected to improve flood hazard and risk estimates in data scarce areas that were previously reliant on other global DEMs (Hawker et al., 2022). However, little research has been done to assess its performance when used to model flood hazard or assess risk. The MERIT DEM—derived from the Shuttle Radar Topography Mission (SRTM) v3 (Farr et al., 2007) below N60°—has seen extensive use in flood hazard modelling at various scales and has been well tested (Chen et al., 2018; Tavares da Costa et al., 2019; Uemaa et al., 2020). Following its release it was generally accepted as being the most appropriate freely available global bare Earth DEM product to use in flood hazard modelling (Hawker et al., 2018; Minderhoud et al., 2019; Rentschler et al., 2022). We experiment with it here as it provides important context for evaluating the FABDEM and other global datasets. We did not consider the ALOS PALSAR RTC DEM product because the source elevation data for this product is SRTM (or the USGS National Elevation Dataset where available), and the 12.5 m resolution of this DEM does not reflect the underlying resolution of the source elevation data (Alaska Satellite Facility, 2015).

The rainfall dataset we test is the global rainfall intensity duration frequency (IDF) dataset known as Parametrized eXtreme Rain (PXR), produced by Courty et al. (2019b). This Global IDF dataset is derived from the European Centre for Medium-Range Weather Forecasts Fifth Generation Re-Analysis (ERA5) (Hersbach et al., 2020). ERA5 is a gridded dataset constructed from the assimilation of historical weather

predictions with observational data. It has global coverage, a 0.25° (approximately 31 km) spatial resolution, and covers the period from 1950 until present with a 1-h temporal resolution. ERA5 has been shown to outperform other rainfall reanalysis products (McClellan et al., 2021) and may represent the preferential source of precipitation data for estimating flood hazard in many data scarce situations. Several GFM use climate reanalysis products as their source of rainfall data (Trigg et al., 2021), and whilst the relatively coarse resolution of ERA5 limits its ability to characterise localised rainfall processes such as convective storms (Reeder et al., 2022), it has been shown to provide useful flood risk information when applied at the catchment and city scales (see Cantoni et al., 2022; Mercogliano et al., 2022). Whilst the direct use of ERA5 to simulate historical flood events has been explored, the PXR IDF dataset has not, despite its potential utility in flood hazard and risk assessment.

A fourth dataset we test is a GFM flood extent map product. GFM came into existence over a decade ago with a primary purpose of helping our understanding of the global distribution of flood risk. They have since undergone several iterations of development, and some GFM are now considered to be potentially useful as national scale flood maps (Bernhofen et al., 2022). Whilst GFM do not provide the level of detail of the national scale flood maps typically available in high income countries, they have shown some value when used to assess flood risk within individual countries down to the district scale (Emerton et al., 2020) or across refugee camps (Bernhofen et al., 2023). Testing GFM at the sub-national scale has been limited however. Here, we test flood extent maps produced by the Fathom 2.0 GFM (Sampson et al., 2015; Fathom, 2019), which at the time of writing is generally considered to be amongst the most locally relevant of the GFM due to its relatively high 1 arc second spatial resolution and its relatively small minimum river size of 50 km<sup>2</sup> upstream drainage area (Trigg et al., 2021).

Our test case is Addis Ababa—the capital city of Ethiopia. Addis Ababa experiences many of the flood risk problems and challenges typically faced by the cities of the global south. Flooding here in August 2006 is regarded as the most severe in Ethiopian history, killing an estimated 647 people and leaving around 200,000 people homeless (De Risi et al., 2020). The population of Addis Ababa is around 5 million people, a number that is growing by around 3.8% annually largely on account of rural to urban migration (Shouler et al., 2021; Dusseau et al., 2023). The city is exposed to both fluvial and pluvial floods, and climate change projections show that flood hazard will increase in the future due to more frequent extreme rainfall (Birhanu et al., 2016; USAID, 2017). Urban expansion onto floodplains combined with sub-standard drainage systems and waste management practices is increasing the level of flood exposure here, and many properties in the city are highly vulnerable to floods because of the poor quality of their construction (World Bank, 2015). The frequency with which people and properties are exposed to flooding in Addis Ababa is also high; this is typical of cities in lower income countries that have little or no formal flood defences (Rentschler et al., 2022) and makes Addis Ababa a suitable test case for global datasets in lower income contexts. Addis Ababa experiences a warm and temperate climate with two rainy seasons: the primary one (Kiremt) falls from June to September; and a secondary one (Belg) occurs from mid-February to April (Bekele et al., 2022). The average annual rainfall

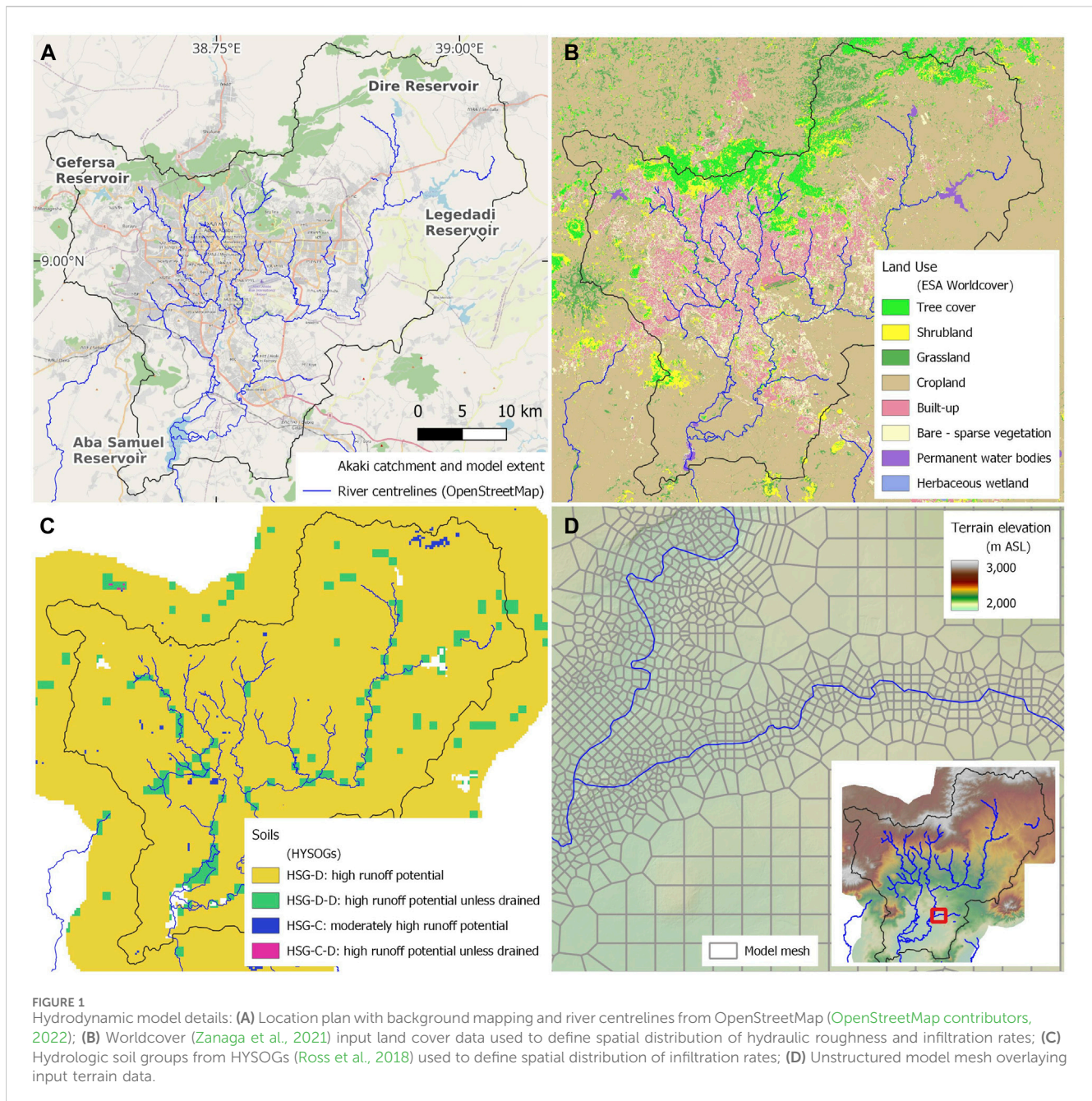
is 1184mm; roughly equal to that in the Scottish city of Glasgow. Temperatures are on average 16°C, and average maximum and minimum temperatures are 22.9 and 10.2°C respectively (Shouler et al., 2021).

## 2 Materials and methods

### 2.1 Flood hazard model development

The 2D flood hazard modelling was carried out using the United States Hydrologic Engineering Center's River Analysis System (HEC-RAS) software, Version 6 (Brunner, 2020b). Our 2D model domain covers the entire Akaki River catchment upstream of the Aba Samuel Reservoir (Figure 1); the city of Addis Ababa is situated entirely within this catchment. The water surface elevation of the Aba Samuel Reservoir forms the downstream boundary condition of the model. We adopted the diffusion wave solver in HEC-RAS and used the 2D sub-grid capability in HEC-RAS. As such, in our model we use a 5 m resolution DEM whilst adopting a variable model resolution of 50 m for river channels and floodplains and 200 m elsewhere. The DEM was obtained from the Ethiopian Geospatial Information Institute, and was generated from aerial photogrammetry using a ground sampling distance of 25 cm. The DEM has a reported vertical accuracy of 50 cm (Bekele et al., 2022). We removed off-terrain features including vegetation, buildings, bridges, and other anthropogenic objects from the DEM using the WhiteboxTools remove off-terrain objects tool (Lindsay, 2018). Other inputs to the reference model include the 10 m resolution WorldCover product developed from Sentinel satellite imagery (Zanaga et al., 2021), which we use to define the spatial distribution of hydraulic roughness. Manning's n roughness coefficient values were assigned to the various WorldCover land cover types based on average values given in Brunner (2020a). WorldCover was also used in conjunction with a 250 m resolution map of Hydrologic Soil Groups (HYSOGs250 m) (Ross et al., 2018) to define the spatial distribution of the US soil conservation service (SCS) curve number values (CN), this being the model's infiltration rate parameter. CN values were obtained from TR-55 (USDA, 1986). These model inputs are depicted in Figure 1 and summarised in Table 1.

Stormwater runoff within the Akaki catchment is managed to some degree by local drainage systems not captured by the DEM. When modelling urban flood hazard at large scales, instead of explicitly modelling these drainage systems it is common to represent them in a simplified manner by applying a drainage removal rate (DRR) to the model (e.g., Scottish Environment Protection Agency, 2018; Xing et al., 2022). DRRs essentially remove rainfall depths from the model at a rate equal to the level of service provided by the drainage system. DRR values were determined using the approach detailed in van Leuwen et al. (2019) who cite Horrit et al. (2009), which was developed for large scale flood hazard mapping undertaken in the United Kingdom. The approach utilises a modified version of the Rational Method and its application here is set out in the Supplementary Material. We calculated DRR values of 8.6 mm/h and 1.8 mm/h for urban and rural areas respectively. These DRR



values incorporate the assumption that the urban drainage systems will partially block and operate at 50% of their assumed hydraulic capacity. It is known that blockage of drainage systems due to inadequate waste management practices plays a significant role in urban flooding in Addis Ababa (Birhanu et al., 2016; Adugna et al., 2019).

## 2.2 Flood hazard model validation

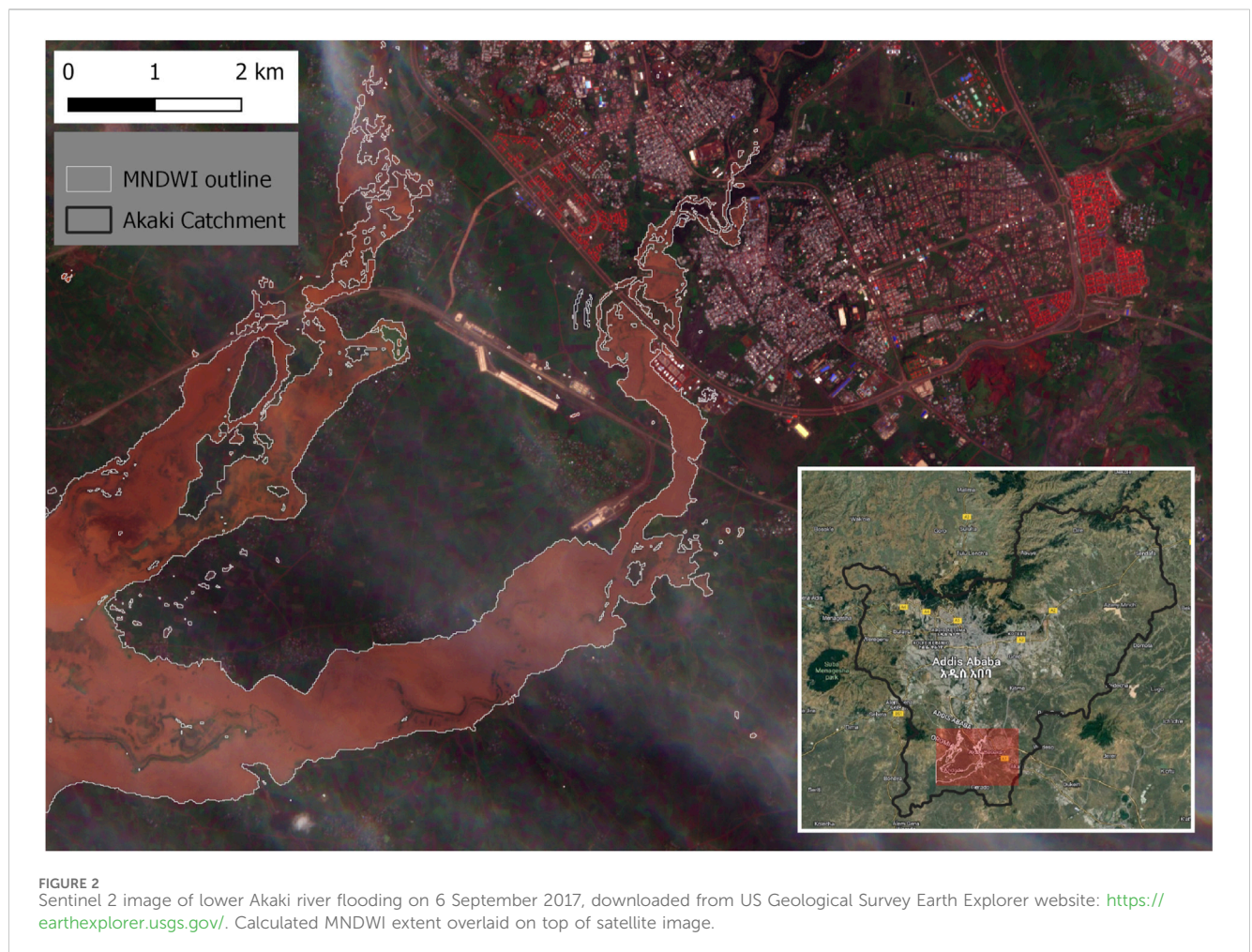
As a hydrodynamic model validation exercise, a flood event captured by satellite imagery on 6 September 2017 was simulated and the modelled flood extent compared with observations. The historical event model simulation was driven by spatially and

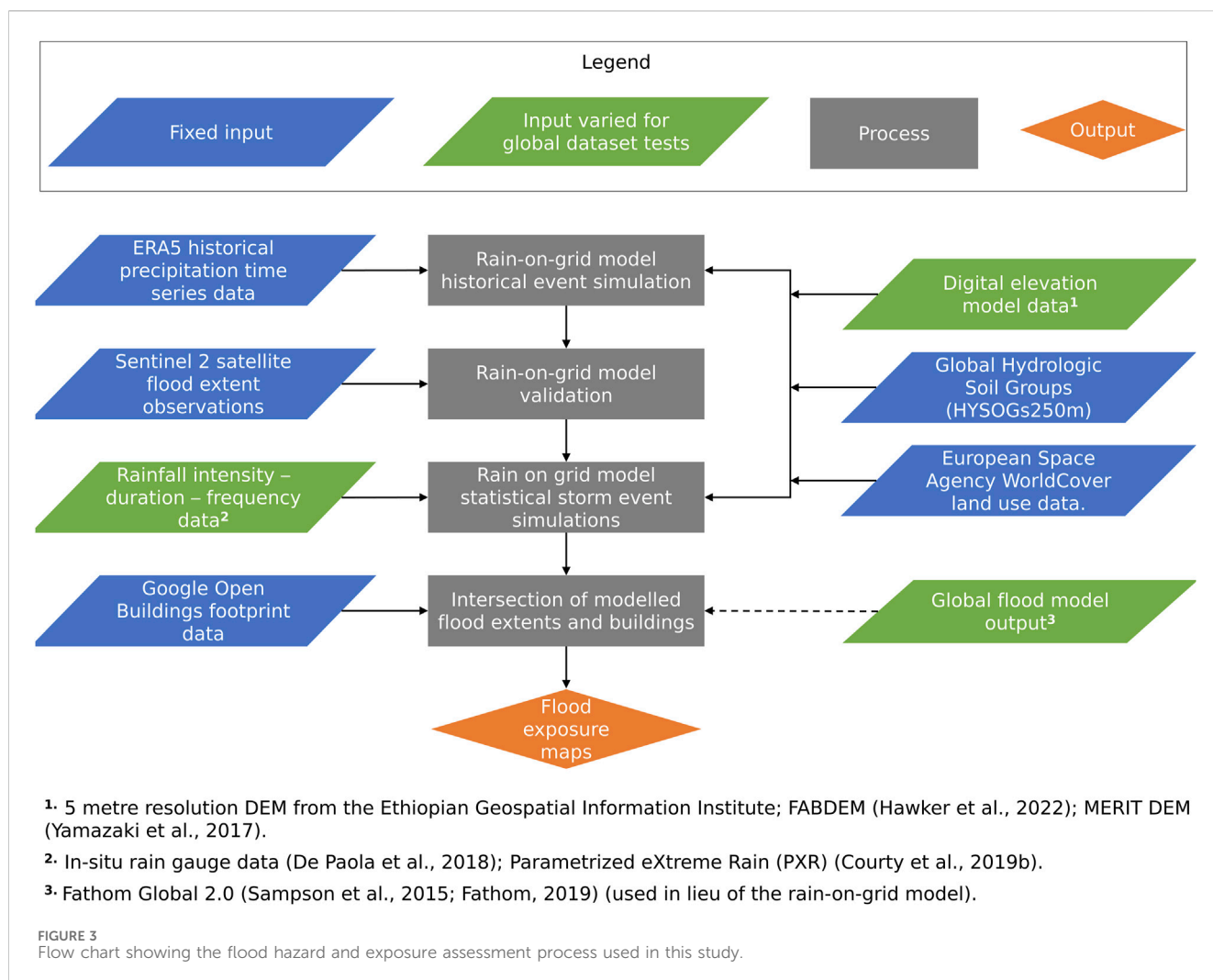
temporally varied precipitation data from ERA5. Model initial conditions were prescribed in the form of a water surface elevation (WSE) grid covering the 2D domain. The WSE values used for the initial conditions were generated from a preliminary model run that simulated the average daily flow observed (gauged) on the Big Akaki River during the wet season months of August and September. These initial conditions represent three reservoirs in the upstream part of the catchment (Gefersa, Legedadi, and Dire) as full, thus assuming they provide no flood attenuation, an assumption corroborated in a discussion we held with the reservoir operators from the Addis Ababa Water and Sewerage Authority (AAWSA, personal communication, 2023).

Satellite imagery capturing the lower Akaki river inundating was acquired at approximately 07:30 UCT on 6 September 2017 by the

TABLE 1 Summary of datasets used in this study.

Dataset	Resolution	Type	Source
ESA WorldCover global land use map	10 m	GeoTIFF	<a href="https://esa-worldcover.org/en">https://esa-worldcover.org/en</a> Zanaga et al. (2021)
HYSOGs Global Hydrologic Soil Groups	250 m	GeoTIFF	<a href="https://doi.org/10.3334/ORNLDAAAC/1566">https://doi.org/10.3334/ORNLDAAAC/1566</a> Ross et al. (2018)
Sentinel 2 Optical satellite imagery	10 m	GeoTIFF	<a href="https://dataspace.copernicus.eu/explore-data/data-collections/sentinel-data/sentinel-2">https://dataspace.copernicus.eu/explore-data/data-collections/sentinel-data/sentinel-2</a>
DEM covering the Akaki catchment	5 m	GeoTIFF	Provided by the Ethiopian Geospatial Institute
FABDEM	30 m	GeoTIFF	<a href="https://doi.org/10.5523/bris.25wfy0f9ukoge2gs7a5mqpq2j7">https://doi.org/10.5523/bris.25wfy0f9ukoge2gs7a5mqpq2j7</a> Hawker et al. (2022)
MERIT DEM	90 m	GeoTIFF	<a href="http://hydro.iis.u-tokyo.ac.jp/~yamada/MERIT_DEM">http://hydro.iis.u-tokyo.ac.jp/~yamada/MERIT_DEM</a> Yamazaki et al. (2017)
ERA5 precipitation time series	31 km; 1 h	Netcdf	<a href="https://cds.climate.copernicus.eu/#/home">https://cds.climate.copernicus.eu/#/home</a> Hersbach et al. (2020)
IDF curves for Addis Ababa	N/A	Equation and parameters	<a href="https://doi.org/10.3390/hydrology5020028">https://doi.org/10.3390/hydrology5020028</a> De Paola et al. (2018)
Parametrized eXtreme Rain global IDF curves	31 km	Netcdf	<a href="https://zenodo.org/records/3351812">https://zenodo.org/records/3351812</a> Courty et al. (2019b)
Fathom 2.0 Global Flood model flood depth grid	90 m	GeoTIFF	<a href="https://www.fathom.global/product/global-flood-map/">https://www.fathom.global/product/global-flood-map/</a> Sampson et al. (2015); Fathom. (2019)
Google Open Buildings Dataset Version 1	0.5 m	CSV	<a href="https://sites.research.google/open-buildings/#download">https://sites.research.google/open-buildings/#download</a> Sirko et al. (2021)





Sentinel 2 optical instrument. We processed the optical imagery by calculating the modified normalised difference water index (MNDWI), which enhances the visibility of open water whilst diminishing built-up area features (Xu, 2006). The result is shown in Figure 2. We then analysed the differences between the modelled and observed flood extents by calculating three performance metrics, details of which are given in the results section. Subsequent comparison of the observed flood extent and modelled statistical floods showed that the observed flood was a relatively minor one (smaller extents than the 1-in-5 years modelled flood extent).

## 2.3 Flood exposure assessments

Once the model was validated, we used it to estimate the number of properties in Addis Ababa that are exposed to the 1-in-5 and 1-in-100 years rainfall events. These statistical rainfall events were chosen to test both low and high-frequency flood events, and were derived from rainfall IDF information for Addis Ababa derived from *in situ* rain gauge data (De Paola et al., 2018). The temporal storm profile was generated using a 24 h duration HEC-HMS frequency-based hypothetical storm (Scharffenberg et al., 2018). The rainfall events

were applied uniformly across the model domain, and the same initial conditions as those used for the historical event simulations were prescribed. The flood extents resulting from these statistical rainfall event simulations were then intersected with the Google Open Buildings Dataset Version 1 (Sirko et al., 2021) to identify all exposed buildings. This dataset contains building footprints from 50 cm satellite imagery, covering the entire African continent, and provides a confidence score to indicate how likely each feature is a building (this score was not used in our assessment process). South Asia, South-East Asia, Latin America and the Caribbean have also since been added to the latest version (V3) of Google Open Buildings. Finally, the spatial distribution of exposure across the study area is mapped by using a heatmap renderer to convert the exposed building points to a 100 m resolution exposure density raster. The entire flood exposure assessment process is depicted in Figure 3.

## 2.4 Model tests: Global datasets and parameter sensitivity

To test the global terrain and rainfall datasets, we repeated the flood hazard modelling and exposure assessment described in the

previous sub-section but sequentially replaced one of the reference model (RM) inputs with a global dataset. To run the hydrodynamic model with each of the global DEMs, each DEM was first augmented with river channel bathymetry information. Bathymetry is generally absent from global DEMs and when they are used in flood modelling it is common to add bathymetry to account for the important role that channels play in flood hydraulics (Sampson et al., 2015; Neal et al., 2021). In data scarce contexts the bathymetry usually needs to be estimated in the absence of observations. We followed this practice to test the global DEMs in this context in a credible manner. To augment the MERIT DEM and FABDEM with bathymetry, we estimate bathymetry by applying hydraulic geometry (HG) theory combined with Manning's equation. HG theory relates channel width and depth to bank full discharge using power law relationships (Leopold and Maddock, 1953; Gleason, 2015), and has been used extensively to estimate bathymetry in data scarce situations (Neal et al., 2012; Schumann et al., 2013; Yamazaki et al., 2013; Fleischmann et al., 2019). HG is often supplemented with some basic open channel flow hydraulic analysis to calculate channel depth. In many cases this involves applying Manning's equation and assuming uniform flow conditions (e.g., Sampson et al., 2015), and we adopt this approach here. All channels with an upstream drainage area of 10 km<sup>2</sup> or above are added, based on previous research suggesting that 30 m resolution global DEMs can define river channels with upstream areas as small as this (Annis et al., 2019; Bernhofen et al., 2021). Details of the procedure used are given in the [Supplementary Material](#).

To run the hydrodynamic model with the PXR IDF dataset we replaced the gauge-based rainfall depths with depths from the PXR IDF curves. The storm temporal profile was then generated in the same way as described previously. The GFM test was conducted by combining the Fathom 2.0 fluvial and pluvial flood depth grids and converting the resulting depth grid into a flood extent map, which was then used to estimate flood exposure *in lieu* of our hydrodynamic model results.

In addition to the four global dataset tests, we also conducted five sensitivity tests on the RM. This involved re-running the RM using upper and lower bound values of key model parameters that are uncertain or subjective, and seeing how sensitive the flood exposure results are to this ambiguity. The parameters tested include the SCS CN values used to compute runoff; the DRR used to model urban drainage; Manning's *n* hydraulic roughness values; the minimum exposure depth threshold value; and the choice of method used to downscale results from the computational grid resolution to the DEM resolution. CN values were varied by  $\pm 20\%$ , reflecting the range in minimum and maximum textbook values for a given land cover type (USDA, 1986). The DRR value was reduced to 0 and increased to 25 mm/h in urban areas, representing assumptions of 100% blockage and a level of service (LoS) of 1-in-10 years (Keaney and Jaegerfelt Mouritsen, (2015) provide accounts of some big cities in middle income countries upgrading drainage systems to this LoS in recent years). Manning's *n* was varied by  $\pm 30\%$  as this is the typical degree of variation between minimum and maximum textbook values for a given surface (e.g., Arcement and Schneider, 1984). A review of reported minimum inundation exposure depth threshold values yielded values between zero (UK Environment Agency, 2019), to 200 mm (BMT Group Ltd, 2019), hence we adopt this range. Finally, we use two methods of

downscaling from the computational grid resolution to the DEM resolution: 1) interpolating the sloping water surface within computational grid cells using values at 2D cell corners only; 2) interpolating the sloping water surface using values at cell corners and face centres, and weighting water surface elevations by face depths so that deep faces have more effect than shallow faces. Method 2) produces considerably smaller flooded areas than method 1). Either of these methods can be used in HEC-RAS.

## 3 Results

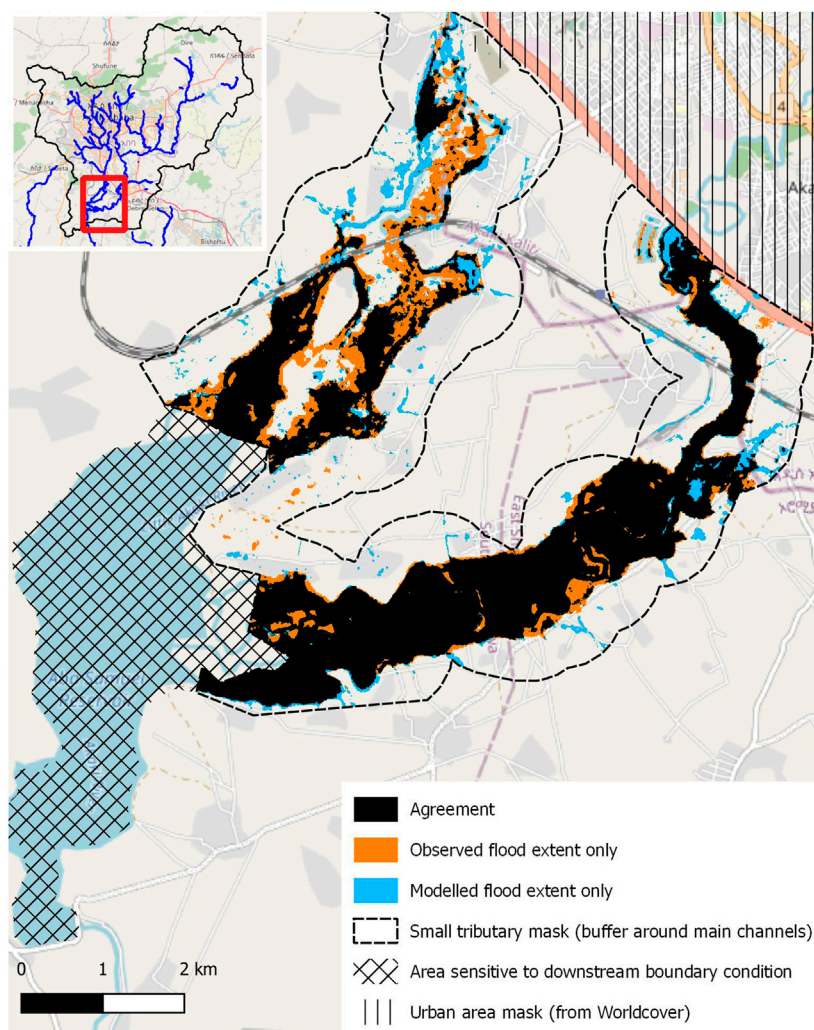
### 3.1 Flood hazard model validation

The results of the model validation exercise for flood extent are shown in [Figure 4](#). The flooded area subjected to validation was constrained to the area downstream of the urban area of Addis Ababa where clouds were absent and, to avoid issues known to occur when extracting inundation extents of minor flood events from satellite imagery in urban areas (Tanim et al., 2022). We also removed an area immediately upstream of the Aba Samuel reservoir from the validation, as initial model sensitivity tests showed flooding in this area was sensitive to the modelled downstream boundary condition. Furthermore, we excluded minor tributaries entering the main rivers along the validation reaches because the resolution of the satellite images is too coarse to detect inundation along these small tributaries.

Generally, there is good agreement between the model and observations, particularly on the Big Akaki river, demonstrating that the model is producing a reasonable reconstruction of the flood inundation dynamics. The modelled flood extents show little bias (just 4% underprediction), give an 81% hit rate (proportion of the observed flood captured by the model), and the critical success index (CSI)—the fraction of the combined modelled and observed flood extent that is correct—is 73%. There are some notable differences in the inundation patterns on the Little Akaki; misrepresentation of terrain and river infrastructure in the model is likely to be part of the reason for this. The remotely sensed inundation patterns are also not error free and will contribute to the disagreement in inundation patterns to some extent. We explored improving model performance by calibrating the friction and infiltration parameters, but doing so did not result in any meaningful improvement in model performance: whilst it reduced the bias, it also reduced the CSI score by a commensurate amount.

### 3.2 Model test results: Global datasets and parameter sensitivity

The exposure building estimates resulting from the Global dataset tests are shown in [Figure 5](#), along with the model sensitivity tests results. Additional hydraulic results including flood extent and depth statistics are provided in [Section 5](#) of the [Supplementary Material](#). The RM produces building exposure estimates of 44,544 and 77,320 for the 1-in-5 and 1-in-100 years return period flood events, respectively. When any one of the global datasets is introduced into the flood hazard modelling process, the exposure estimates increase. The magnitude of this increase varies



**FIGURE 4**  
Hydrodynamic model validation with optical image observed on 6 September 2017. Background mapping from OpenStreetMap (OpenStreetMap contributors, 2022).

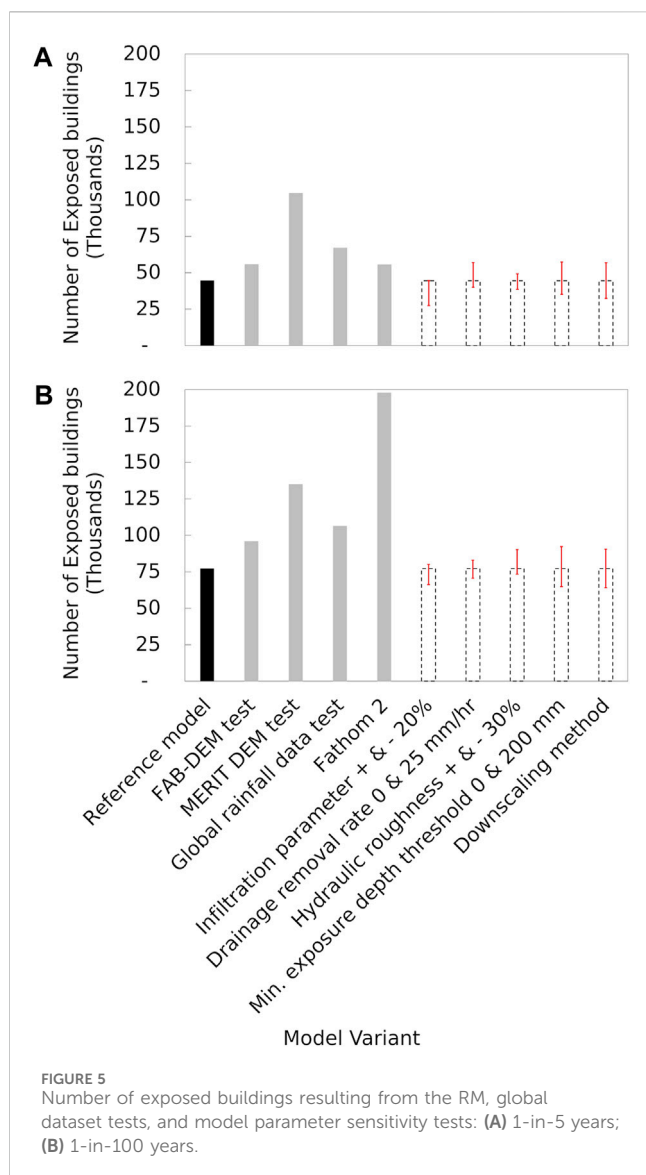
for each test and tends to be greater for the 1-in-5 than the 1-in-100 years event in relative terms (the global flood hazard model test being a notable exception). The percentage increases in exposure relative to the RM, for the 1-in-5 and 1-in-100 years events are, respectively: 25% and 24% for the FAB DEM test; 135% and 75% for the MERIT DEM test; 50% and 38% for the global IDF test; and 25% and 156% for the GFM test.

Of the five sensitivity tests, the 1-in-5 years CN parameter test results vary by a maximum of 38% relative to the RM exposure, which is the largest deviation of all tests. The CN values are the product of the HYSOGs and Worldcover global datasets. Whilst we are not testing these specific datasets in this study, the CN sensitivity test results indicate a need to do so. The HYSOGs data in particular has a relatively coarse 250 m spatial resolution and would benefit from being tested given others are now using at this scale (e.g., 3SPROSPECT, 2021; Rivosecchi and Singh, 2023). The 1-in-5 years results of the DRR, minimum depth threshold, and downscaling method tests all deviate from the RM by up to 28%, whilst the hydraulic roughness test runs vary by no more than 13%. When

compared to the 1-in-5 years results, 1-in-100 years sensitivity test results consistently show less variation relative to the RM, but they are similar in their absolute magnitude. Some of these uncertainties are mitigated where models are calibrated and the parameters can be adjusted to reduce the difference between model results and observations. However, drainage removal rate, minimum flood depth threshold, and the downscaling method are not calibration parameters and modellers should take note of how much the model results can deviate depending on the choices made with these.

Figure 6 shows the heatmap raster maps depicting the spatial distribution of buildings exposed to the 1-in-5 and 1-in-100 years events, for the RM results and each of the global dataset tests. The spatial prioritisation of interventions is a fundamental part of flood risk management, and it is therefore important to assess the spatial distribution of exposure as well as the total number of exposed assets. The RM heatmaps identify a clear exposure hotspot to the southwest of the city, and a site visit to this area in March 2023 verified that widespread inundation of properties has occurred in this area. The heatmaps produced from the global





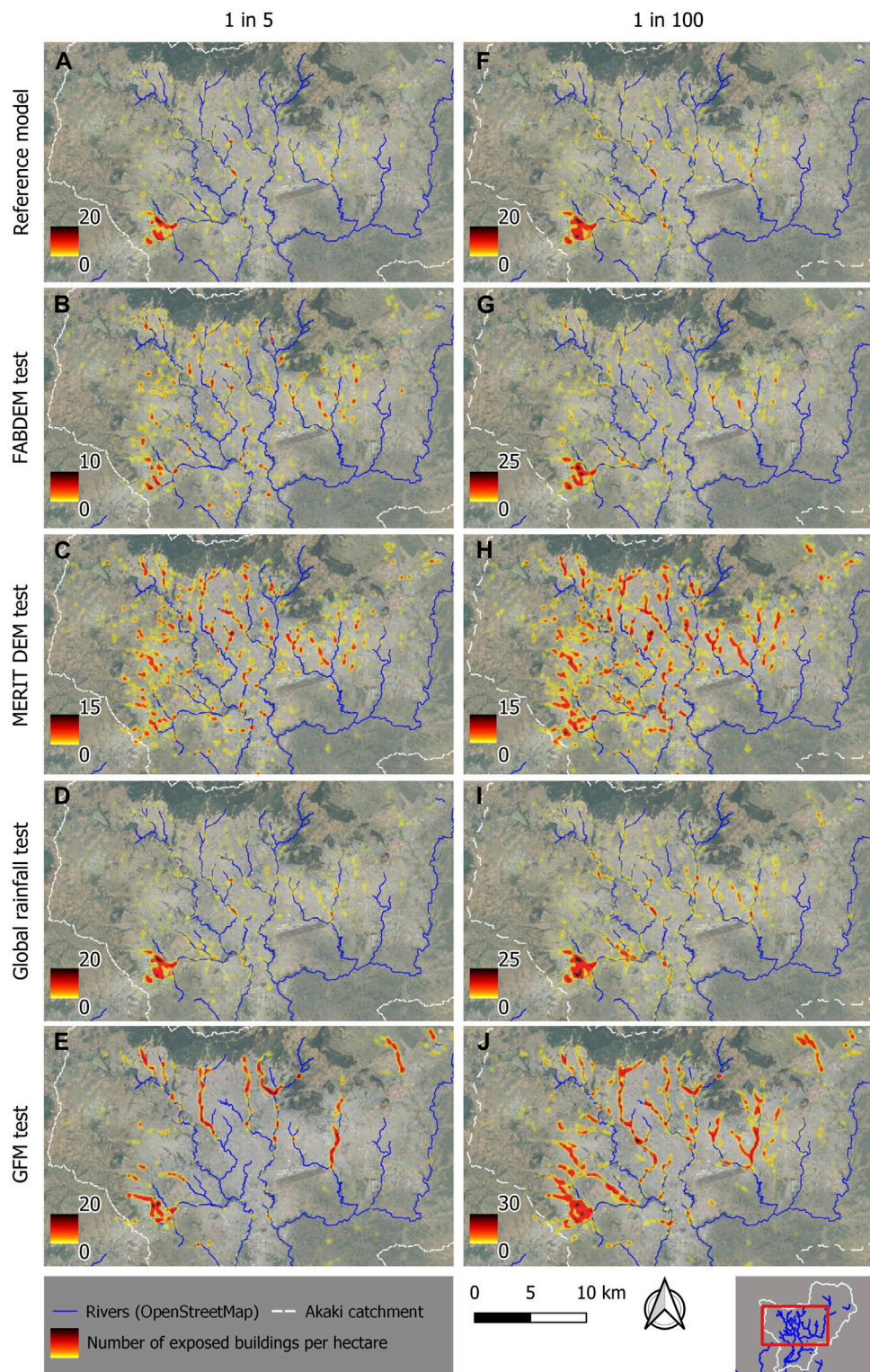
dataset tests diverge from the RM heatmap to varying degrees. The FABDEM increases the exposure to some degree along numerous river reaches across the domain and as a result is unable to define the southwestern hotspot for the 1-in-5 years event. The southwestern hotspot is well defined for the FAB DEM 1-in-100 years scenario. Using the MERIT DEM increases exposure significantly across the model domain for both flood events, and it is unable to define the southwestern hotspot. Global rainfall has no discernible effect on the distribution of exposure as would be expected given rainfall is applied uniformly in the model. The GFM heatmap does not clearly identify the southwestern hotspot for either flood event because it introduces commensurate degrees of exposure along several of the watercourses.

## 4 Discussion

Each dataset overestimates flood exposure to a varying degree. One would expect this to be the case for the global DEMs, as

reducing the DEM resolution will always produce larger flood extents, assuming a consistent vertical accuracy (Saksena and Merwade, 2015). When using FABDEM this overestimation is relatively small and is well within the hydrodynamic model's sensitivity to uncertain parameters. In contrast, the MERIT DEM produces a much larger overestimation far greater than the model's sensitivity, which is broadly in line with the findings of others (McClellan et al., 2020). This result clearly supports the assertion that FABDEM will significantly improve flood hazard and risk estimates in data scarce situations. The 1-in-100 years exposure heatmaps produced using FABDEM also conform much closely to the RM and represent a significant improvement on those produced using the MERIT DEM. To place these results in context, the RM is based on a 5 m DEM from photogrammetry, which is comparable to DEMs used in national scale flood maps produced for some higher income countries (Sayers et al., 2020; Bates et al., 2021). However, the 1-in-5 years FABDEM heatmaps show a limited improvement over the MERIT heatmaps and are unable to replicate the spatial patterns of flood exposure predicted by the RM. The deterioration of the FABDEM results for high-frequency floods may be because the inundation associated with high-frequency events is less extensive, i.e., it is more localised and sensitive to topographic approximations such as the omission of flood defences and hydraulic structures; as noted by others (Quinn et al., 2019; Hawker et al., 2020). The practice of augmenting global DEMs with bathymetry may also play a role in their poor performance in modelling high-frequency floods. Estimating bathymetry by assuming uniform flow does not allow for gradually varied flow conditions such as backwater effects that exist along natural channel systems, meaning channel depths will be underestimated and inundation overestimated in these areas. The tendency to over-predict exposure for more frequent flood events is a recognised limitation of GFMs and their constituent data. Efforts to address this are ongoing: Neal et al. (2021) demonstrated that bathymetry estimation using a gradually varied flow solver instead of Manning's equation for uniform flow can remove the bias in modelled water surface elevation associated with backwater effects. Zhao et al. (2023) developed a novel machine learning-based approach for estimating flood defence standards and demonstrated its utility in improving the representation of flood defences in large scale flood modelling. Such advances are already being used in continental scale modelling (Bates et al., 2021), and they will be adopted in future versions of GFMs. The extent to which they improve GFM high-frequency flood predictions, particularly in low income contexts, remains to be seen.

Using the global IDF dataset increased the number of exposed buildings by a similar magnitude to the more sensitive of the parameter uncertainty tests (infiltration; minimum exposure depth threshold value; downscaling method), and can therefore be regarded as a considerable component of the overall uncertainty of the hydrodynamic modelling process. However, when these results are viewed in the context of the wider flood risk assessment process, the overestimation is relatively small in magnitude. For example, Merz and Thielen (2009) found that flood risk estimates for a relatively data-rich western European city had maximum uncertainties of around -50% and +100%. The vulnerability component of risk (i.e., the relationship between flood hazard magnitude and flood receptor susceptibility) is often the dominant source of uncertainty (Winter 2017; Sarailidis 2023). In lower income countries where data



**FIGURE 6** Heatmaps showing spatial distribution of building exposure to 1-in-5 years (A-E); and 1-in-100 years (F-J) storm events. Heatmap symbology minimum and maximum values are set individually for each map deliberately, to allow each map to define the spatial distribution of exposure as clearly as possible. Background Map data: Google, Maxar Technologies, Airbus.

on vulnerability relationships is particularly scarce, risk assessment uncertainties have been shown to exceed a factor of three (Engelhardt et al., 2019; Bernhofen et al., 2022). As noted in the results section, the

rainfall is not spatially varied and therefore it does not significantly affect the spatial distribution of exposure in our test. The results show that the global IDF curves are appropriate for assessing city scale flood

risk. However, as the behaviour of ERA5 is thought to vary across climatic regions (Gleixner et al., 2020), further testing in other regions is needed to make these findings globally applicable. Contrary to the overestimation shown by our results, others have found that ERA5 tends to underestimate flood hazard and exposure (McClean et al., 2021). The overestimation seen here may be the result of the approach used to derive IDF relationships from ERA5, whereby the IDF extreme value distribution parameters are scaled relative to event duration (refer to Courty et al., 2019b for further details).

The Fathom 2.0 GFM results show the GFM more than doubles the 1-in-100 years exposure, which is significant even within the context of the wider flood risk assessment process. Interestingly the GFM produces 1-in-5 years exposure estimates that are relatively close to the RM results. This inconsistent magnitude of variation between the GFM and the RM across return periods could be due to differences in the rainfall data used by the two models, or differences between the two models in their approach used representing urban drainage. Distinctions in model computational grid size and geometry, and in the approximations of the shallow water equations employed by the HEC-RAS model and the Fathom model will also play some role in these differences. The heatmaps for both events show that the GFM introduces large amounts of exposure along several watercourses in the study area, preventing a clear definition of the southwestern hotspot for either return period. This undermines its use in any form of city-scale prioritisation study. The elevated exposure along the smaller channels is likely because the bathymetry of these river channels has not been added to the GFM (minimum river size added is 50 km<sup>2</sup>—see Trigg et al., 2021). Compared to the MERIT DEM results, the GFM does a better job of showing the extent of exposure in the hotspot area, which is interesting given the GFM uses the MERIT DEM.

In summary, our results caution against assessing flood risk at the city scale using the Fathom 2.0 GFM or the other GFMs that have been documented in scientific literature in recent years (Yamazaki et al., 2011; Winsemius et al., 2013; Rudari et al., 2015; Sampson et al., 2015; Dottori et al., 2016; Ward et al., 2020; Zhou et al., 2021). As has been well noted by others (Sampson et al., 2015; Schumann and Bates, 2018), global DEM quality is regarded as a key limitation of GFMs. Our FABDEM testing here suggests that GFMs should improve considerably by using this DEM over MERIT, and Fathom have recently done this in the latest upgrade to their GFM version 3.0 (Hawker et al., 2023). Representing the bathymetry of smaller rivers would also seemingly improve the prospect of using future GFMs at the city scale. As GFMs continue to be enhanced with new methods and datasets, and computational advances enable resolution to be refined, researchers will need to continue benchmarking these models and the datasets they are using in an objective manner so that they can be used appropriately.

Having considered only one set of geographic and climatic conditions and used only a limited set of local data for validation, it is important to note that the generalisability of our findings is somewhat limited. Further research is needed to sample a wide range of geographic and climatic conditions and utilise a diverse array of local datasets for validation, which will enhance the generalisability of findings around global datasets. Nonetheless, for those interested in broad-scale flood risk assessment in similar low income, data scarce contexts, there are some practical implications:

- FABDEM provides a viable substitute for local terrain data for flood hazard modelling and should be used in preference to SRTM-derived elevation products. However, users should be mindful that global DEMs will generally tend to overpredict total flood extent and exposure.
- In the absence of local rainfall data, The PXR IDF dataset can be useful for prioritisation studies requiring a comparative assessment of flood exposure across a study area.
- Application of these global datasets and GFMs are best restricted to more extreme flood events such as the 1-in-100 years event. If high-frequency floods are to be assessed, particular caution should be exercised when using global datasets; for these events it becomes even more important to verify global hazard information with local observations and knowledge.
- Based on a workshop held in Addis Ababa in which the results of this study were presented to interested parties, the flood exposure maps that resulted from using FABDEM and PXR IDF data can be of use to practitioners and risk managers. Specifically, representatives from the Fire and Disaster Risk Management Commission, the Ethiopian meteorological institute, and the Ethiopian Construction and Works Corporation indicated that the exposure maps provided new insights into the spatial distribution of flood exposure across the city, and that the information would be useful for emergency response planning.
- Whilst our findings show that certain global datasets can be used credibly to assess flood exposure at the city scale, it is important to reiterate that these findings are specific to low-income settings where little or no physical flood defence or river engineering infrastructure exists. It is also worth noting that the scope of application of global datasets investigated here excludes more local reach or structure scale assessments; the design of individual mitigation measures; or the use of flood depth information for assessment of damages or mitigation scheme options.

## 4.1 Conclusions

This study evaluates the suitability of relevant global datasets for mapping flood hazard in support of city-scale flood risk assessments in data scarce, low to middle income contexts. Specifically, we test the use of FABDEM and MERIT DEM, the PXR global rainfall IDF dataset, and the Fathom 2.0 GFM in assessing flood exposure across Addis Ababa, Ethiopia. We find that FABDEM clearly outperforms the MERIT DEM. MERIT overestimated 1-in-100 years exposure by 75%; this figure was just 25% with FAB DEM, which is less deviation than that arising from the hydrodynamic model sensitivity tests. FABDEM also did a far better job of mapping the spatial distribution of exposure and matched closely the local 5 m DEM from photogrammetry used in the reference model. However, this finding does not hold for frequent flood events where inundation is more localised and sensitive to topographic approximations. The 1-in-5 years FABDEM flood exposure map does not match the reference model well, and is similar to that produced by the MERIT DEM. We therefore conclude that FABDEM is suitable for assessing flood risk at the city scale, but only flood risks

associated with relatively low-frequency floods. The global IDF dataset also holds promise for assessing city scale flood risk associated with both low and high-frequency floods. Its use in place of *in situ* rainfall data elevated exposure estimates by a maximum of 50%, which is small relative to the overall uncertainty associated with the wider flood risk assessment process (particularly the vulnerability component of risk). However, more work is needed to generalise these findings by testing the global datasets in a range of geographic and climatic conditions and using a more diverse set of local data for validation. The Fathom 2.0 GFM we tested was unable to define the spatial distribution of exposure, which precludes its use at the city scale. However, we anticipate that by making use of FABDEM, the latest generation of GFMs will provide hazard information associated with low-frequency flood events that is relevant to city scale assessments in lower income countries. Further research will be needed to test new GFMs and other global datasets that continue to emerge to give users a sense of their limitations.

## Data availability statement

The datasets and HEC-RAS model presented in this study can be found in online repositories. The names of the repository/repositories and accession number(s) can be found below: Direct link: <https://doi.org/10.5518/1428>. The repository name is: Research Data Leads.

## Author contributions

AC: Formal Analysis, Investigation, Methodology, Software, Visualization, Writing—original draft. MT: Conceptualization, Project administration, Supervision, Writing—review and editing. AH: Conceptualization, Resources, Supervision, Writing—review and editing. MB: Data curation, Software, Writing—review and

editing. AA: Project administration, Resources, Writing—review and editing. TB: Project administration, Resources, Validation, Writing—review and editing. CW: Conceptualization, Funding acquisition, Resources, Writing—review and editing.

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## Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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## Supplementary material

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fenvs.2024.1330295/full#supplementary-material>

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