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Coordinated optimization scheduling of wind, solar, hydro and methane power generation with adjustable methane

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To enhance methane utilization in coal-rich regions and integrate methane power generation with distributed renewable energy systems, this study proposes a coordinated optimization dispatch model with adjustable methane-fired generation. The methodology first establishes a methane transmission model incorporating virtual storage characteristics based on coal mine power supply topology and extraction processes, then develops a multi-resource optimization framework integrating wind, solar, hydropower, and methane under distribution network constraints, equipment operation limits, and coal mine safety requirements. Through case studies in a Shanxi coal mine under multiple scenarios, the results validate the model's effectiveness in improving methane utilization and coordinating hybrid energy resources, with the proposed fuzzy-enhanced IGDT (F-EIGDT) method demonstrating enhanced robustness against source-load uncertainties compared to conventional approaches. The study confirms methane's dual role as fuel and virtual storage medium in mining-area power systems, providing a safety-constrained coordination paradigm for fossil-renewable integration, while suggesting the need for further optimization of long-term storage strategies.

KEYWORDS

methane power generation, virtual storage characteristics of methane, wind-solarhydro-methane multi-resource coordination, fuzzy-enhanced information gap decision theory (F-EIGDT), economic dispatch

1 Introduction

Methane is a flammable gas, typically referring to coal mine methane or natural gas. In this paper, the methane discussed is coal mine methane, primarily composed of methane (CH_4), which is a high-energy, clean fuel. Its production is generally associated with coal mining (Bai et al., 2024). The total amount of coal mine methane resources in China can reach $30.05 \times 10^{12} \text{ m}^3$, with 41% of this being recoverable, making it an important source of natural gas in the country (Chen et al., 2024a). With the development of clean energy technologies, methane, as an essential low-carbon energy source, has gradually gained more attention for its development and utilization (Kang et al., 2024). The utilization methods of methane vary depending on its concentration, with CH_4 volume fractions greater than 6% being suitable for power generation (Akbari et al., 2024). Methane power generation typically uses gas turbines, internal combustion engines, or fuel cells. Gas turbines are suitable for medium to high-concentration methane and offer rapid startup and response

capabilities. Internal combustion engines are highly adaptable and can adjust output based on methane supply, making them suitable for lower-concentration methane. Fuel cells, on the other hand, generate electricity through electrochemical reactions using the hydrogen in methane, making them ideal for small-scale or distributed energy systems (Wang et al., 2024). As a crucial component of China's energy structure adjustment, methane power generation plays an essential role in improving the utilization of coal-associated resources, reducing greenhouse gas emissions, and promoting clean energy development. However, in the context of the rapid development of new energy sources, fully leveraging the regulatory role of methane power generation to accommodate fluctuations in wind and solar energy, while coordinating various renewable energy sources to achieve power balance in the grid and enhance grid stability, has become a hot topic in the energy sector.

With the increasing share of renewable energy, methane power generation, with its flexible regulatory capabilities, has become an important means of balancing grid load and ensuring the stability of electricity supply, especially in integrated energy systems and microgrids. Nadaraju et al. (2019) utilizes ventilation air methane emission reduction heat recovery to provide flexible regulation and self-sustaining operation, supporting grid stability and energy system integration. The van oxidation device was used to convert low concentration coal mine methane into thermal energy for use in coal mines (Hu et al., 2022), which to some extent improved the utilization rate of methane. Similarly, a regenerative thermal oxidizer device is used to convert low concentration coal mine methane into thermal energy through catalytic oxidation for recovery and utilization (Wang et al., 2022). Huang et al. (2021) integrates various renewable energy sources such as coal mine methane, and utilizes abandoned mines in mining areas to transform into pumped storage power stations to participate in system coordination and operation, improving the utilization level of coal mine methane. These studies have made significant theoretical contributions to methane power generation and multi-energy collaborative operation, improving the efficiency of coal mine methane participation in the power system's operation. However, most of the studies have rough methane power generation modeling processes, insufficient consideration of safety constraints, and little research on optimizing scheduling in the context of coal mine production and the actual operation of coal mine distribution networks.

The power output of methane power generation is mainly determined by the methane gas source and the characteristics of the equipment. During coal mine production, factors such as methane content, geological conditions, and extraction techniques can all impact the methane gas source, introducing a certain level of uncertainty into methane power generation. How to address this uncertainty is an important issue in system optimization scheduling. Existing studies often use methods such as scenario generation, robust optimization, stochastic optimization, and interval optimization to handle uncertainty. Zhang et al. (2024) proposed a novel scenario generation method based on filtering scenarios with environmental wind conditions, enhancing scenario deployment while using minimal resources to meet the required risk levels. This method provides an accurate and effective solution for opportunity-constrained economic scheduling problems. Lin et al. (2023) transformed a fuzzy set-based distributed robust optimization model into a scenario-oriented

model with probabilistic uncertainty, effectively avoiding complex mathematical transformations. Cao et al. (2024) considered source-load uncertainty and established an uncertain islanding model using correlated random variables, generating islanding scenarios with scenario trees to enhance energy supply reliability under islanding conditions. Kou and Li (2020) used interval optimization to decompose the potential transmission capacity uncertainty of wind power into lower and upper boundary models, transforming the problem into a single-level maximization problem, thus achieving efficient solutions. While the above studies improve the system's adaptability to uncertainty, these methods are computationally complex, and the models often rely on historical information or probability functions of uncertainty variables. In practice, however, methane power plants have limited access to detailed information about the methane gas source, as they typically only record partial information about the gas injected into the power generation units (i.e., the modulated methane gas information), making the information on the methane power source constrained.

Information Gap Decision Theory (IGDT) is a method for handling uncertainty and information insufficiency in decision-making processes. It aims to make robust decisions by assessing and addressing information gaps, especially in situations where decisions must be made under incomplete information or in response to uncertainty challenges (Ben-Haim, 2006). IGDT has been widely applied in the field of power systems. Zhang et al. (2023) combined IGDT with opportunity constraints to handle forecast deviations in load demand and distributed generation, as well as associated power fluctuations in distribution networks, to obtain proactive management strategies for operators. Yazdaninejad et al. (2020) specifically modeled uncertainty sources and used multi-level IGDT to establish a framework for non-deterministic and non-probabilistic uncertainty, where each uncertainty parameter is targeted at a specific range around its expected value. Chen et al. (2024b) applied the IGDT method to provide optimal bidding strategies for load aggregators, considering time-shifted loads and distributed renewable energy under uncertainty. Khaloie et al. (2022) used IGDT to address the uncertainty of photovoltaic output by combining conditional risk values to handle both stochastic uncertainty and the information gap in IGDT. However, there has been little research applying IGDT to quantify the uncertainty in methane power generation, and the methods in the aforementioned studies lack probabilistic information, which limits the decision-making process. Most of these studies focus on maximizing the region or range of uncertainty variables under the condition of meeting pre-set objectives, rather than incorporating a more comprehensive uncertainty analysis.

Therefore, to address the issues of rough methane power generation modeling, insufficient exploration of its regulatory potential, and the uncertainty arising from limited source-side information, this paper proposes a coordinated optimization scheduling method for wind, solar, and hydropower systems with adjustable methane power generation. The main contributions of this paper are as follows:

- 1) Developing a detailed model for methane power generation and virtual storage based on coal mine production realities. In this paper, a detailed modeling approach is applied to methane extraction and power generation within the actual

coal mine energy supply network. Key factors influencing methane extraction are extracted based on current coal mining production standards. Considering the energy storage characteristics of methane gas, the model integrates methane storage and utilization closely, establishing a virtual storage model for methane that focuses on dynamic regulation. Through detailed modeling, the flexibility and rapid response capability of the methane power generation units are quantitatively assessed, providing a theoretical foundation for fully exploiting the regulatory potential of methane power generation.

- 2) Promoting coordinated optimization scheduling of wind, solar, hydropower, and methane generation using the dynamic regulation characteristics of methane storage tanks. By introducing coal mine safety constraints and the operating mechanism of methane storage tanks, while accounting for network flow and equipment operating constraints, an optimization scheduling model for wind, solar, hydropower, and adjustable methane power generation is developed, with a focus on economic and environmental objectives. The dynamic regulation of methane injection and extraction processes enables the time-shifting and flexible utilization of methane resources. This effectively addresses the randomness and intermittency of wind and solar generation, enhances the overall regulation capability of the system, and achieves the efficient integration of methane power generation with wind, solar, and hydropower.
- 3) Enhancing the uncertainty handling capability of IGDT with fuzzy logic. This paper considers the uncertainty in wind, solar, and hydropower output, load forecasting, and the time-varying characteristics of coal mine methane supply. Using IGDT, these uncertainties are integrated into the optimization decision-making process. On this basis, fuzzy logic is introduced to handle both uncertainty and fuzziness, leading to the development of a F-EIGDT. By combining fuzzy logic and fuzzy set theory, this method addresses the lack of probabilistic information in IGDT, ensuring that the decision-making process remains robust and feasible when facing fluctuations in wind and solar output and methane supply.

The rest of the paper is organized as follows: [Section 2](#) introduces the coal mine-grid system topology with adjustable methane power generation. [Section 3](#) discusses the coordinated optimization scheduling model for wind, solar, hydropower, and methane power generation. [Section 4](#) addresses the coordinated optimization scheduling model for wind, solar, hydro, and methane under source-load fluctuations based on F-EIGDT. [Section 5](#) presents case studies. Finally, [Section 6](#) provides the conclusions.

2 Coal mine-grid system topology with adjustable methane power generation

The system topology with adjustable methane power generation is shown in [Figure 1](#), consisting of four components: the coal mine distribution network, methane extraction system, methane power generation system, and urban distribution network. The methane

extraction and power generation system serves as an intermediate link, where methane extracted from the coal mine is used for power generation, supplying the urban distribution network. This system also forms the physical connection between the coal mine distribution network and the urban distribution network. The characteristics of each system component are as follows:

Coal Mine Distribution Network: Based on the actual power supply system of a coal mine in Shanxi, this paper simplifies the topology to a 34-node coal mine distribution system. Detailed load information for each node can be found in ([Liang et al., 2024b](#)), with node 9 representing the methane extraction station, where methane is extracted from the coal mine.

Methane Extraction System: This system consists of two main parts: methane extraction and methane storage. Methane extraction involves drawing methane from underground coal seams, adjacent layers, and mined-out areas through a pipeline system, which includes control valves, water-ring vacuum pumps, and auxiliary equipment ([Zhou et al., 2024](#)). Methane storage involves temporarily storing the extracted methane in surface methane storage tanks.

Methane Power Generation System: The methane power generation system consists of methane storage tanks, a mixer, and a methane generator set. The mixer adjusts the air intake based on the methane concentration to ensure the optimal combustion mixture of methane and air. The intake valve controls the flow of combustible methane-air mixture into the generator. The mixture burns in the generator, driving pistons in a reciprocating motion, converting the chemical energy of the gas into electrical and thermal energy output.

Urban Distribution Network: The urban distribution network consists of 33 nodes and 32 branches. Node 5 is connected to a photovoltaic generation unit, node 21 to a wind turbine, node 14 to a hydropower unit, and node 4 to the methane power generation unit.

Through the above-mentioned coal mine methane power generation and coal mine-grid coordinated operation, the system ensures the safety of both coal mine and grid operations while improving methane resource utilization efficiency. Methane storage tanks are configured based on coal mine production conditions and the demand of the distribution network, allowing for flexible adjustment of methane power generation. This helps to mitigate the fluctuations of wind and solar generation while achieving efficient power distribution.

3 Coordinated optimization scheduling model for wind, solar, hydropower, and methane power generation

3.1 Constraints of methane gas extraction system

Assuming that there are no tunneling tasks scheduled for the day and only mining tasks are carried out, based on the current coal mine industry standards in China ([China National Coal Mine Construction Association, 2018](#)), the key characteristics of coal mine production are abstracted. The critical factors influencing methane yield in coal mines, such as coal production and geological conditions, are identified. A methane

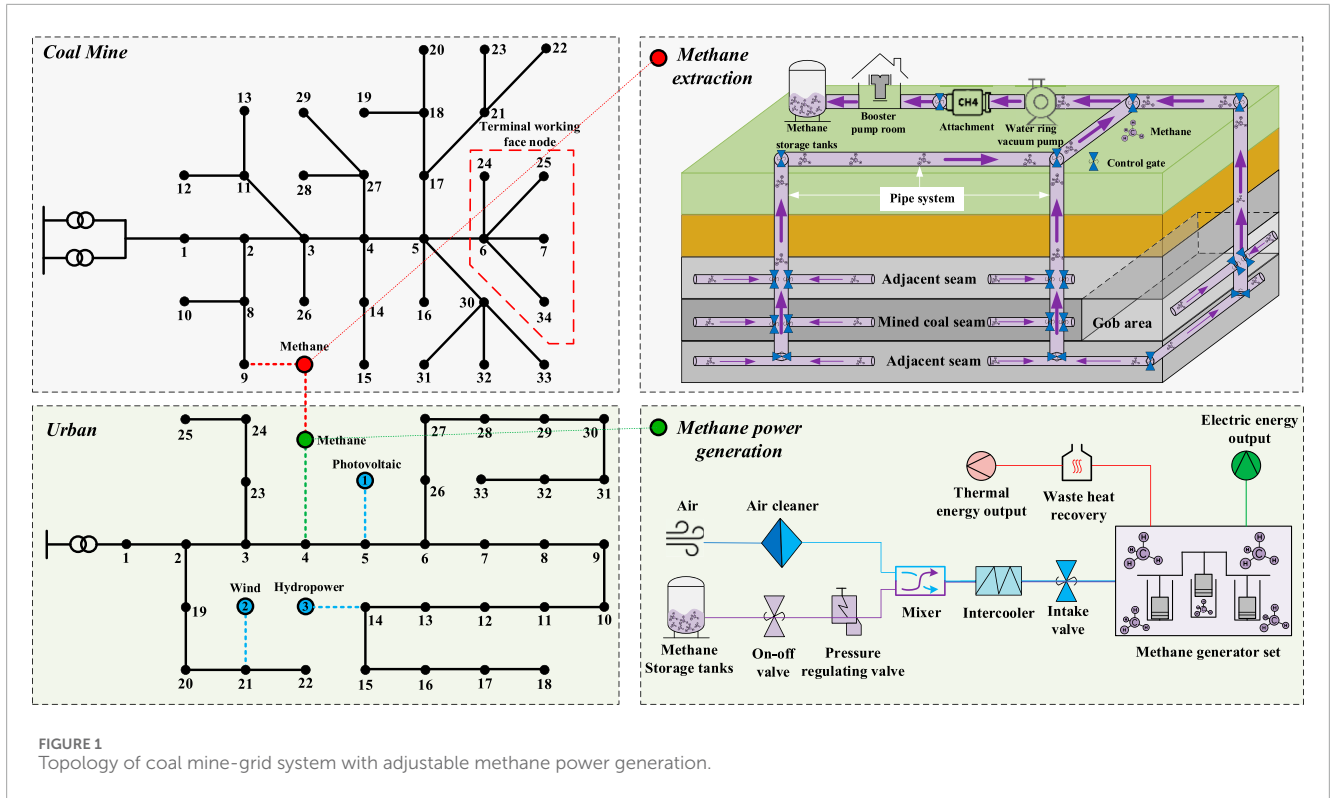


FIGURE 1 Topology of coal mine-grid system with adjustable methane power generation.

extraction model considering coal mine production characteristics is then constructed, as shown in Equations 1–4.

$$G_{\text{mine}} = \frac{K_1 \times K_c \times L_1 \times L_2 \times M \times \gamma \times (W_0 - W_1)}{365 \times 24 \times \Delta t} \quad (1)$$

$$G_{\text{adja}} = \frac{K_1 \times L_3 \times L_4 \times \gamma \times \sum_j m_j \times (W_{0j} - W_{cj}) \times \eta_j}{330 \times 24} \times K_y \quad (2)$$

$$G_{\text{goaf1}} = \frac{M_C \times W_0 \times k_1 \times k_2 \times k_3 \times (W_0 - W_c)}{W_0 \times 365 \times 24} \quad (3)$$

$$G_{\text{goaf}} = K_g (G_{\text{goaf1}} - G_{\text{mine}}) \quad (4)$$

Where G_{mine} , G_{adja} , G_{goaf} represent the methane extraction rates from the mined coal seam, adjacent seam, and gob area, respectively. G_{goaf1} is the total methane that can be extracted from the coal mine. K_1 , K_c are the methane extraction imbalance coefficient and the ratio of pre-extraction methane to extraction during the mining process for the specific coal seam. L_1 , L_2 , L_3 , L_4 represent the width of the mining face, length of the mining face, width of the mining face, and the annual advancing length of the mining face, respectively. M is the average thickness of the pre-extracted coal seam. γ is the apparent density of coal. W_0 , W_c , W_1 are the original methane content, residual methane content, and pre-extraction qualified methane content of the coal seam, respectively. m_j , η_j represent the coal thickness and gas emission rate of the j -th adjacent seam. K_y is the methane extraction rate from the adjacent seam due to pressure relief. W_{0j} , W_{cj} are the original methane content and residual methane content of the j -th adjacent coal seam, respectively. M_C is the coal reserve in the mined coal seam. k_1 is the negative pressure extraction coefficient, k_2 is the expected methane

extraction rate for the coal seam, and k_3 is the methane emission rate in the mine.

The relationship between the coal reserve in the mined coal seam and the coal mining amount, as shown in Equation 5.

$$L_1 \times L_2 \times M \times \gamma = M_C - \sum_{i=1}^t M_S^i \quad (5)$$

Where M_S^i represents the coal mining amount of the mining machine at the i th time.

In addition, since K_1 , K_c , m_j , and η_j are all geological parameters of the coal mine, Equations 1–4 can be transformed into a function of coal mining amount and geological conditions, as shown in Equations 6–9.

$$G_{\text{mine}}^t = a_1 \left(M_C - \sum_{i=1}^t M_S^i \right) \quad (6)$$

$$G_{\text{adja}}^t = a_2 \quad (7)$$

$$G_{\text{goaf1}}^t = a_3 \quad (8)$$

$$G_{\text{goaf}}^t = a_4 \sum_{i=1}^t M_S^i + b_1 \quad (9)$$

Therefore, based on the coal mining process, the mathematical model for gas extraction can be simplified as Equations 10, 11.

$$G_{\text{stope}}^t = G_{\text{mine}}^t + G_{\text{adja}}^t + G_{\text{goaf}}^t \quad (10)$$

$$G_{\text{stope}}^t = c_1 \sum_{i=1}^t M_S^i + d_1 \quad (11)$$

Where G_{stope}^t represents the gas extraction amount at time t . $a_1, a_2, a_3, a_4, b_1, c_1$, and d_1 are constants, which are related to the geological conditions of the mined coal.

In Equation 11, it can be seen that the gas extraction amount from the coal mine at time t is related to the coal production and geological conditions at previous time t .

3.2 Consideration of the adjustable methane generation model based on the methane virtual storage characteristics

3.2.1 Methane virtual storage model

In this article, “virtual storage” specifically refers to simulating the physical storage behavior of methane (CH_4) resources through mathematical models and dynamic regulation mechanisms, rather than relying on traditional physical energy storage facilities such as batteries and pumped storage. The core idea is to utilize the dynamic characteristics of methane in pipelines, storage tanks, and production consumption processes to achieve time translation and flexible scheduling of energy.

When establishing the methane virtual storage model, the following assumptions or limitations need to be made:

- (1) Methane is considered an ideal gas.
- (2) The temperature and pressure distribution inside the methane storage tank are uniform.
- (3) The compression process of methane gas is considered isothermal.

This paper focuses on the process of methane virtual storage, including the injection of extracted methane gas into the storage tank via the pressurization pump station, storage within the tank, and the release process. The ‘gas loading status’ of the storage tank is defined to represent the current remaining capacity of methane in the storage tank. The methane virtual storage model is shown in Equations 12–18.

$$G_{\text{stope}}^t p_{\text{stope}}^t = V_{\text{boos}}^t p_{\text{boos}}^t \quad (12)$$

$$G_{\text{stope}}^t \rho_{\text{stope}}^t = V_{\text{boos}}^t \rho_{\text{boos}}^t \quad (13)$$

$$\dot{m}_{\text{in}}^t = C_d \sqrt{2 \frac{\rho_{\text{boos}}^t M_{\text{meth}} p_{\text{boos}}^t}{R_{\text{meth}} T_{\text{meth}}}} (p_{\text{boos}}^t - p_{\text{tank}}^t) \quad (14)$$

$$\dot{m}_{\text{out}}^t = C_d \sqrt{2 \frac{\rho_{\text{out}}^t M_{\text{meth}} p_{\text{out}}^t}{R_{\text{meth}} T_{\text{meth}}}} (p_{\text{tank}}^t - p_{\text{out}}^t) \quad (15)$$

$$\dot{m}_{\text{tank}}^t = \frac{p_{\text{tank}}^t M_{\text{meth}} V_{\text{tank}}}{R_{\text{meth}} T_{\text{meth}}} + (\dot{m}_{\text{in}}^t - \dot{m}_{\text{out}}^t) \Delta t \quad (16)$$

$$\eta_{\text{soc}}^t = \frac{p_{\text{tank}}^t V_{\text{tank}}}{p_{\text{tank}}^{\text{max}} V_{\text{tank}}} = \frac{p_{\text{tank}}^t}{p_{\text{tank}}^{\text{max}}} = \frac{\dot{m}_{\text{tank}}^t}{\dot{m}_{\text{tank}}^{\text{max}}} \quad (17)$$

$$V_{\text{tout}}^t = \frac{\dot{m}_{\text{out}}^t R_{\text{meth}} T_{\text{meth}}}{\rho_{\text{tank}}^t M_{\text{meth}} p_{\text{tank}}^t} \quad (18)$$

Where V_{boos}^t represents the methane gas volume at time t after being pressurized by the pressurization pump station. p_{stope}^t and p_{boos}^t represent the methane gas pressure before and after pressurization at

time t , respectively, where $p_{\text{stope}}^t < p_{\text{boos}}^t$; ρ_{stope}^t and ρ_{boos}^t represent the methane gas volume fractions before and after pressurization at time t , respectively. \dot{m}_{in}^t and \dot{m}_{out}^t represent the mass flow rates of methane gas entering and exiting the methane storage tank, respectively. ρ_{boos}^t , ρ_{tank}^t , and ρ_{out}^t represent the methane gas volume fractions before injection into the storage tank, inside the storage tank, and after release from the storage tank, respectively. p_{boos}^t , p_{tank}^t , and p_{out}^t represent the methane gas pressure before injection into the storage tank, inside the storage tank, and after release from the storage tank, respectively, where $p_{\text{out}}^t < p_{\text{tank}}^t < p_{\text{boos}}^t$; \dot{m}_{tank}^t represents the mass of methane gas in the storage tank at time t . M_{meth} is the molar mass of methane gas; V_{tank} is the volume of the methane storage tank; R_{meth} is the ideal gas constant. T_{meth} is the absolute temperature of the methane gas. η_{soc}^t represents the gas holding state of the methane storage tank at time t . $p_{\text{tank}}^{\text{max}}$ and $\dot{m}_{\text{tank}}^{\text{max}}$ represent the maximum methane gas pressure and mass inside the storage tank, respectively. V_{tout}^t represents the volume of methane gas released from the storage tank at time t .

3.2.2 Adjustable methane power generation model

Methane can balance fluctuations in other resources (Hu et al., 2022; Huang et al., 2021). Methane and filtered air are mixed in the mixer, and after reaching the preset concentration, they are injected into the methane power generation unit through the intercooler and intake valve. The combustion generates electrical energy and waste heat. The waste heat is recovered by a waste heat recovery device, while the electrical energy is transmitted through the city power grid. The model is shown in Equations 19–25.

$$p_{\text{tout}}^t V_{\text{tout}}^t = p_{\text{chan}}^t V_{\text{chan}}^t \quad (19)$$

$$\rho_{\text{tout}}^t V_{\text{tout}}^t = \rho_{\text{chan}}^t V_{\text{chan}}^t \quad (20)$$

$$V_{\text{mix}}^t = V_{\text{chan}}^t + V_{\text{air}}^t \quad (21)$$

$$\rho_{\text{mix}}^t V_{\text{mix}}^t = \rho_{\text{chan}}^t V_{\text{chan}}^t \quad (22)$$

$$p_{\text{mix}}^t = \frac{p_{\text{chan}}^t V_{\text{chan}}^t + p_{\text{air}}^t V_{\text{air}}^t}{V_{\text{mix}}^t} \quad (23)$$

$$p_{\text{inga}}^t T_{\text{in}} = p_{\text{mix}}^t T_{\text{out}} \quad (24)$$

$$P_{\text{meth}}^t = \eta_{\text{meth}}^e V_{\text{inga}}^t \rho_{\text{inga}}^t C_{\text{meth}} \quad (25)$$

Where p_{chan}^t , p_{air}^t , p_{mix}^t , and p_{inga}^t represent the pressure of the methane gas after pressure regulation, the pressure of the air involved in mixing, the pressure of the mixed methane gas, and the pressure of the methane gas injected into the methane power generation unit, respectively. V_{chan}^t , V_{mix}^t , and V_{air}^t represent the volume of methane gas after pressure regulation, the volume of the mixed gas, and the volume of the air involved in mixing, respectively. ρ_{chan}^t , ρ_{mix}^t , and ρ_{inga}^t represent the volume fractions of methane gas at time t after pressure regulation, in the mixed gas, and injected into the methane power generation unit, respectively, where $\rho_{\text{mix}}^t = \rho_{\text{inga}}^t$. T_{out} and T_{in} represent the gas temperature of the mixed methane

gas after the intercooler output and the gas temperature before output, respectively. P_{meth}^t is the power output of the methane power generation unit. η_{meth}^e is the efficiency of the methane power generation unit; C_{meth} is the heating value of methane gas. V_{inga}^t is the volume of methane gas injected into the methane power generation unit, and its value is equal to V_{mix}^t .

3.3 Other power generation model

3.3.1 Photovoltaic power generation model

The output power of the photovoltaic system is mainly determined by the solar radiation, the area of the photovoltaic array, the system efficiency, and the temperature correction factor. Its simplified model is shown in Equations 26–28.

$$P_{\text{pv}}^t = AR^t \eta_{\text{sys}} \eta_{\text{temp}} \quad (26)$$

$$\eta_{\text{temp}} = 1 - \theta(T_c - T_{\text{ref}}) \quad (27)$$

$$T_c = T_{\text{amb}} + \frac{R^t}{800} \Delta t \quad (28)$$

Where P_{pv}^t is the output power of the photovoltaic system at time t . A is the total area of the photovoltaic array. R^t is the solar irradiance per unit area at time t . η_{sys} is the conversion efficiency of the photovoltaic system. η_{temp} is the temperature correction factor. θ is the temperature coefficient. T_c is the actual operating temperature of the photovoltaic module. T_{ref} is the reference temperature. T_{amb} is the ambient temperature. Δt is the temperature rise of the photovoltaic module under radiation.

3.3.2 Wind power generation model

The output power of the wind power generation system has a nonlinear relationship with wind speed, which specifically depends on whether the wind speed is between the cut-in wind speed, rated wind speed, and cut-out wind speed. The model is shown in Equation 29.

$$P_{\text{wt}}^t = \begin{cases} 0, & 0 \leq v_t < v_{\text{ci}} \cup v_t \geq v_{\text{co}} \\ P_{\text{wt}}^t \frac{(v_t^3 - v_{\text{ci}}^3)}{(v_r^3 - v_{\text{ci}}^3)}, & v_{\text{ci}} \leq v_t < v_r \\ P_{\text{wt}}^r, & v_r \leq v_t < v_{\text{co}} \end{cases} \quad (29)$$

Where P_{wt}^t is the wind power generation output at time t . v_t is the wind speed at time t . v_{ci} , v_r , and v_{co} are the cut-in, rated, and cut-out wind speeds of the wind turbine, respectively. P_{wt}^r is the rated power of the wind turbine.

3.3.3 Hydropower generation model

The output power of hydropower generation is typically determined by the head height, flow rate, and equipment efficiency (Qiu et al., 2020). The calculation formula is shown in Equations 30, 31.

$$P_{\text{hy}}^t = \eta_{\text{hy}} \rho_{\text{wa}} g Q^t H_{\text{ud}} \quad (30)$$

$$H_{\text{ud}} = \left(Z_u + \frac{p_u}{\rho_{\text{wa}} g} + \frac{\alpha_u v_u^2}{2g} \right) - \left(Z_d + \frac{p_d}{\rho_{\text{wa}} g} + \frac{\alpha_d v_d^2}{2g} \right) \quad (31)$$

Where P_{hy}^t is the output power of the hydropower generation system at time t . η_{hy} is the system equipment efficiency. ρ_{wa} is the density of water. g is the acceleration due to gravity. Q^t is the water flow rate through the turbine. H_{ud} is the head height. Z_u and Z_d are the reference surface heights at the turbine inlet and outlet, respectively. p_u and p_d are the pressures at the turbine inlet and outlet, respectively. v_u and v_d are the flow velocities at the turbine inlet and outlet, respectively. α_u and α_d are the velocity coefficients at the turbine inlet and outlet, respectively.

3.4 Objective function and constraints

3.4.1 Objective function

The coordinated optimization scheduling model for wind, solar, hydro, and methane aims to minimize the total daily operating cost C_{tot} , which includes the operating cost C_{ope} , the investment cost of the methane storage tank C_{gas} , and the environmental management cost C_{poll} . The objective function is shown in Equations 32–35.

$$\min C_{\text{tot}} = C_{\text{ope}} + C_{\text{gas}} + C_{\text{poll}} \quad (32)$$

$$C_{\text{ope}} = \sum_{t=1}^T \left(P_{\text{grid}}^t p_E^t + \sum_{k=1}^{N_e} (\mu_k P_k^t) \right) \quad (33)$$

$$C_{\text{gas}} = \frac{r(1+y)^y}{(1+y)^y - 1} C_{\text{tank}} V_{\text{tank}} \quad (34)$$

$$C_{\text{poll}} = \sum_{t=1}^T \sum_{n=1}^{N_p} (\mu_{\text{meth}}^n P_{\text{meth}}^t \delta_{\text{meth}}^n) \quad (35)$$

Where T is the total number of time periods in the scheduling cycle. P_{grid}^t and p_E^t are the electricity purchase amount from the grid and the time-of-use electricity price at time t , respectively. N_e and N_p are the total number of power station types and the total number of pollutant types emitted by the methane units, respectively. μ_k is the unit operation and maintenance cost of the k -th type of power station. P_k^t is the power output of the k -th power station at time t ; r is the discount rate. y is the planned operating lifetime of the methane storage tank in years. C_{tank} is the unit investment cost of the methane storage tank. μ_{meth}^n and δ_{meth}^n are the emission factor and the environmental management unit cost for the n -th type of pollutant emitted by the methane power generation unit, respectively.

3.4.2 System constraints

The system constraints mainly include distribution network power flow constraints (Equations 36–41), equipment operation constraints (Equations 42, 43), and coal mine production constraints (Equations 44, 45).

3.4.2.1 Distribution network power flow constraints

$$\sum_{ij \in \Omega_{bc}} (P_{t,ij} - r_{ij} I_{t,ij}^2) + P_{t,j} = \sum_{jh \in \Omega_{bc}} P_{t,jh} \quad (36)$$

$$\sum_{ij \in \Omega_{bc}} (Q_{t,ij} - x_{ij} I_{t,ij}^2) + Q_{t,j} = \sum_{jh \in \Omega_{bc}} Q_{t,jh} \quad (37)$$

$$U_{t,i}^2 = U_{t,j}^2 + 2(r_{ij} P_{t,ij} + x_{ij} Q_{t,ij}) + (r_{ij}^2 + x_{ij}^2) I_{t,ij}^2 \quad (38)$$

$$U_{t,i}^2 I_{t,ij}^2 = P_{t,ij}^2 + Q_{t,ij}^2 \tag{39}$$

$$U^{min} \leq U_{t,i} \leq U^{max} \tag{40}$$

$$Q_i^{emin} \leq Q_{t,i}^{ex} \leq Q_i^{emax} \tag{41}$$

Where $P_{t,ij}$ and $Q_{t,ij}$ are the active and reactive power from node i to node j at time t , respectively. r_{ij} and x_{ij} are the resistance and reactance between node i and node j , respectively. $I_{t,ij}$ is the current from node i to node j at time t ; $P_{t,j}$ and $Q_{t,j}$ are the active and reactive power injected at node j at time t , respectively. Ω_{bc} is the set of boundary nodes; $U_{t,i}$ and $U_{t,j}$ are the voltage magnitudes at nodes i and j at time t , respectively; U^{min} and U^{max} are the lower and upper limits of node voltage magnitudes, respectively. $Q_{t,i}^{ex}$ is the reactive compensation at node i of the coal mine distribution network at time t ; Q_i^{emin} and Q_i^{emax} are the maximum and minimum capacities of the reactive compensation device at node i in the coal mine distribution network.

3.4.2.2 Equipment operation constraints

$$0 \leq P_k^t \leq P_k^{max} \tag{42}$$

$$P_k^{down} \leq P_k^t - P_k^{t-1} \leq P_k^{up} \tag{43}$$

Where P_k^{max} , P_k^{down} , and P_k^{up} are the maximum output, ramp-up limit, and ramp-down limit of the k th type of equipment, respectively.

3.4.2.3 Coal mine safety constraints

To ensure the safe operation of the coal mine, under the three-shift system, one shift must be arranged for the maintenance of important equipment. The constraint is as follows:

$$\kappa^t = \begin{cases} 0, & t \in [t_1, t_2] \\ 1, & t \notin [t_1, t_2] \end{cases} \tag{44}$$

$$\sum_{t=1}^T \kappa^t = T - (t_2 - t_1 + 1) \tag{45}$$

Where κ^t is the operating status of the mining machine at time t , where 0 indicates maintenance and 1 indicates operation; t_1 and t_2 are the start and end times of the maintenance period, respectively.

4 Coordinated optimization scheduling model for wind, solar, hydro, and methane under source-load fluctuations based on F-EIGDT

4.1 Overview of F-EIGDT principle

Decision theory aims to provide decision-makers with methods to make optimal choices in uncertain environments. Traditional decision-making methods, such as Bayesian decision theory, rely on probabilistic information. However, in practical applications,

decision-makers often face situations with missing or incomplete information, making it difficult to accurately estimate probability distributions. IGDT addresses this by quantifying the decision-maker's cognitive gap regarding uncertainty, offering a method for assessing the robustness of decision alternatives under extreme uncertainty. However, the conservatism of IGDT may limit its effectiveness in practical applications. Therefore, this paper proposes the introduction of fuzzy logic and fuzzy set theory into IGDT, forming F-EIGDT, to enhance its performance in dealing with fuzzy uncertainty.

4.1.1 IGDT principle

IGDT was proposed by Yakov Ben-Haim in the late 1990s, aiming to provide robust decision alternatives in highly uncertain environments. IGDT evaluates the performance of different decision alternatives under varying levels of information gaps (ϕ), which measure the degree of deviation of decision parameters from reference values (Ben-Haim, 2006). The core of IGDT is to find solutions that can still meet the decision objectives within the maximum information gap range, incorporating both risk-averse and risk-seeking strategies. This paper involves the safe scheduling of coal mines, thus constructing an IGDT robust model to maximize the avoidance of uncertainty's impact on the solution results. The general form of the IGDT robust model (Peng et al., 2022; Lv et al., 2023) is shown in Equation 46.

$$\left\{ \begin{array}{l} \max_s \varphi \\ \left\{ \begin{array}{l} \max F(s, w) \leq F_C \\ F_C = (1 + \beta)F_0 \\ G(s, w) = 0 \\ K(s, w) \leq 0 \\ U(\varphi, \tilde{w}) = \{w: |w - \tilde{w}| \leq \varphi \tilde{w}\} \end{array} \right. \end{array} \right. \tag{46}$$

Where φ represents uncertainty, indicating the fluctuation range of uncertain variables. F is the objective function. s is the decision variable; w is the actual value of the uncertain variable. \tilde{w} is the predicted value of the uncertain variable. F_0 is the optimal solution under the deterministic model. β is the deviation factor, representing the degree of deviation between the expected robust optimization target and the optimal solution of the deterministic model. F_C is the maximum expected value that the decision-maker can accept. $G(s, w) = 0$ is the equality constraint. $K(s, w) \leq 0$ is the inequality constraint; $U(\varphi, \tilde{w})$ is the fluctuation range of the uncertain variable.

4.1.2 IGDT principle

F-EIGDT enhances flexibility and accuracy in handling fuzzy uncertainty by combining fuzzy logic with IGDT. In F-EIGDT, fuzzy set theory defines a membership function that relates elements to their degree of membership in a fuzzy set (Nikoobakht et al., 2020), allowing the expression of partial membership, which can be represented as Equation 47.

$$\tilde{F} = \{(s, \mu_{\tilde{F}}(s)) \mid s \in H\} \tag{47}$$

Where H is the domain of the fuzzy variable. \tilde{F} is the fuzzy set of H . $\mu_{\tilde{F}}(x)$ is the membership function, representing the degree of membership of element s to the fuzzy set \tilde{F} , with a range of [0,1].

The larger the value of it, the higher the likelihood that s belongs to this set.

Common membership functions include linear, Gaussian membership functions, etc. Taking the linear function as an example, the membership function $\mu(\beta)$ of the uncertainty β in the IGDT model and the membership function $\mu(F)$ of the scheduling cost F are represented as Equations 48, 49.

$$\mu(\beta) = \begin{cases} 1 & \beta \geq \beta^{max} \\ \frac{\beta - \beta^{min}}{\beta^{max} - \beta^{min}} & \beta^{min} \leq \beta \leq \beta^{max} \\ 0 & \beta \leq \beta^{min} \end{cases} \quad (48)$$

$$\mu(F) = \begin{cases} 1 & F \leq F^{min} \\ \frac{F^{max} - F}{F^{max} - F^{min}} & F^{min} \leq F \leq F^{max} \\ 0 & F \geq F^{max} \end{cases} \quad (49)$$

Where β^{min} and β^{max} are the minimum and maximum values of uncertainty β . F^{min} and F^{max} are the minimum and maximum values of the scheduling cost F .

The satisfaction of the robust strategy can be expressed in Equation 50.

$$\begin{cases} \max \lambda \\ \frac{\beta - \beta^{min}}{\beta^{max} - \beta^{min}} \geq \lambda \\ \frac{F^{max} - F}{F^{max} - F^{min}} \geq \lambda \\ \text{s.t.} \begin{cases} \max F(s, w) \leq F_C \\ F_C = (1 + \beta)F_0 \\ G(s, w) = 0 \\ K(s, w) \leq 0 \\ U(\varphi, \tilde{w}) = \{w: |w - \tilde{w}| \leq \varphi \tilde{w}\} \end{cases} \end{cases} \quad (50)$$

Where λ is the satisfaction of the robust strategy.

Fuzzy set theory, by introducing membership functions and fuzzy operations, provides a flexible and powerful tool for dealing with and analyzing complex systems with fuzziness and uncertainty. When combined with IGDT, fuzzy set theory can further enhance the expressiveness of the decision model and the accuracy of the robustness evaluation, enabling decision-makers to make more scientific and reasonable decisions in highly uncertain and fuzzy information environments.

4.2 Coordinated optimization scheduling model for wind, solar, hydro, and methane based on F-EIGDT

4.2.1 Modeling of source-load uncertainty

The uncertainty fluctuation range of source-load demand under the F-EIGDT model can be expressed in Equations 51–53.

$$U(\alpha_i, \tilde{P}_i^t) = \{P_i^t: |P_i^t - \tilde{P}_i^t| \leq \alpha_i \tilde{P}_i^t\}, i \in \Omega_S \quad (51)$$

$$U(\alpha_L, \tilde{P}_{load}^t) = \{P_{load}^t: |P_{load}^t - \tilde{P}_{load}^t| \leq \alpha_L \tilde{P}_{load}^t\} \quad (52)$$

$$\psi = \sum \varepsilon_i \alpha_i \quad (53)$$

Where α_i is the uncertainty of the i th power generation unit on the source side. \tilde{P}_i^t and P_i^t are the predicted and actual power generation values of the i th generation unit at time t , respectively. Ω_S is the set of power generation units on the source side. α_L is the uncertainty of load demand. \tilde{P}_{load}^t and P_{load}^t are the predicted and actual system load demand values at time t , respectively. ψ is the combined uncertainty. ε_i is the weight coefficient of the i th generation unit, where $\sum \varepsilon_i = 1$.

4.2.2 F-EIGDT mathematical model

The F-EIGDT model is constructed by combining IGDT with fuzzy set theory. Equation 54 is the IGDT robust model, and Equations 55–57 represent the fuzzy set theory model.

$$\begin{cases} \max_X \psi \\ \text{s.t.} \begin{cases} \max C(X, P) \leq C_C \\ C_C = (1 + \beta_R)C_0 \\ U(\alpha_i, \tilde{P}_i^t) = \{P_i^t: |P_i^t - \tilde{P}_i^t| \leq \alpha_i \tilde{P}_i^t\} \\ U(\alpha_L, \tilde{P}_{load}^t) = \{P_{load}^t: |P_{load}^t - \tilde{P}_{load}^t| \leq \alpha_L \tilde{P}_{load}^t\} \\ \psi = \sum \varepsilon_i \alpha_i \\ G(X, P) = 0 \\ K(X, P) \leq 0 \end{cases} \end{cases} \quad (54)$$

$$\tilde{C} = \{(X, \mu_{\tilde{C}}(X)) \mid X \in L\} \quad (55)$$

$$\mu(\psi) = \begin{cases} 1 & \psi \geq \psi^{max} \\ \frac{\psi - \psi^{min}}{\psi^{max} - \psi^{min}} & \psi^{min} \leq \psi \leq \psi^{max} \\ 0 & \psi \leq \psi^{min} \end{cases} \quad (56)$$

$$\mu(C) = \begin{cases} 1 & C \leq C^{min} \\ \frac{C_C - C}{C_C - C^{min}} & C^{min} \leq C \leq C_C \\ 0 & C \geq C_C \end{cases} \quad (57)$$

Where X is the decision variable. P is the uncertainty variable. C_0 is the optimal solution of the deterministic model. C_C is the maximum expected value acceptable to the decision-maker. β_R is the deviation factor. $G(X, P) = 0$ represents other equality constraints; $K(X, P) \leq 0$ represents other inequality constraints. L is the domain of the fuzzy variable. \tilde{C} is the fuzzy set of L ; $\mu_{\tilde{C}}(X)$ is the membership function. $\mu(\psi)$ and $\mu(C)$ are the membership functions of combined uncertainty ψ and scheduling cost C , respectively. ψ^{min} and ψ^{max} are the minimum and maximum values of uncertainty, respectively. C^{min} is the minimum value of scheduling cost.

Based on the above models, the following can be derived, as shown in Equation 58.

$$\begin{cases} \max \lambda_R \\ \frac{\psi - \psi^{min}}{\psi^{max} - \psi^{min}} \geq \lambda_R \\ \frac{C_C - C}{C_C - C^{min}} \geq \lambda_R \\ \psi = \sum \varepsilon_i \alpha_i \\ \text{s.t.} \begin{cases} \max C(X, P) \leq C_C \\ C_c = (1 + \beta_R) C_0 \\ U(\alpha_i, \tilde{P}_i^t) = \{P_i^t : |P_i^t - \tilde{P}_i^t| \leq \alpha_i \tilde{P}_i^t\} \\ U(\alpha_L, \tilde{P}_{load}^t) = \{P_{load}^t : |P_{load}^t - \tilde{P}_{load}^t| \leq \alpha_L \tilde{P}_{load}^t\} \end{cases} \end{cases} \quad (58)$$

Equations (11)–(31), Equations (36)–(45)

Where λ_R is the satisfaction level of the F-EIGDT robust strategy.

Equation 58 is a two-level optimization model, where the lower level model calculates the maximum operating cost of the system based on the system operation scheduling model when uncertain variables fluctuate; The upper level is to solve the maximum satisfaction value when the operating cost of the system meets the predetermined objective of robust optimization; In the lower level model, when the resource output decreases, the system will purchase energy from external sources to compensate for this shortfall, and the lower the output, the higher the cost of external energy purchase; When the system demand increases, the system energy consumption increases, and the greater the load demand, the higher the system scheduling cost. Therefore, for a given range of uncertainty, the maximum operating cost of the lower level model occurs at the lowest resource output and the highest load demand. Therefore, when the resource output takes the lower boundary and the load demand takes the upper boundary value, the lower level scheduling cost is the highest. At this point, the bi-level optimization model in Equation 58 can be equivalently transformed into a single-level optimization model (Dolatabadi et al., 2019), that is Equation 59.

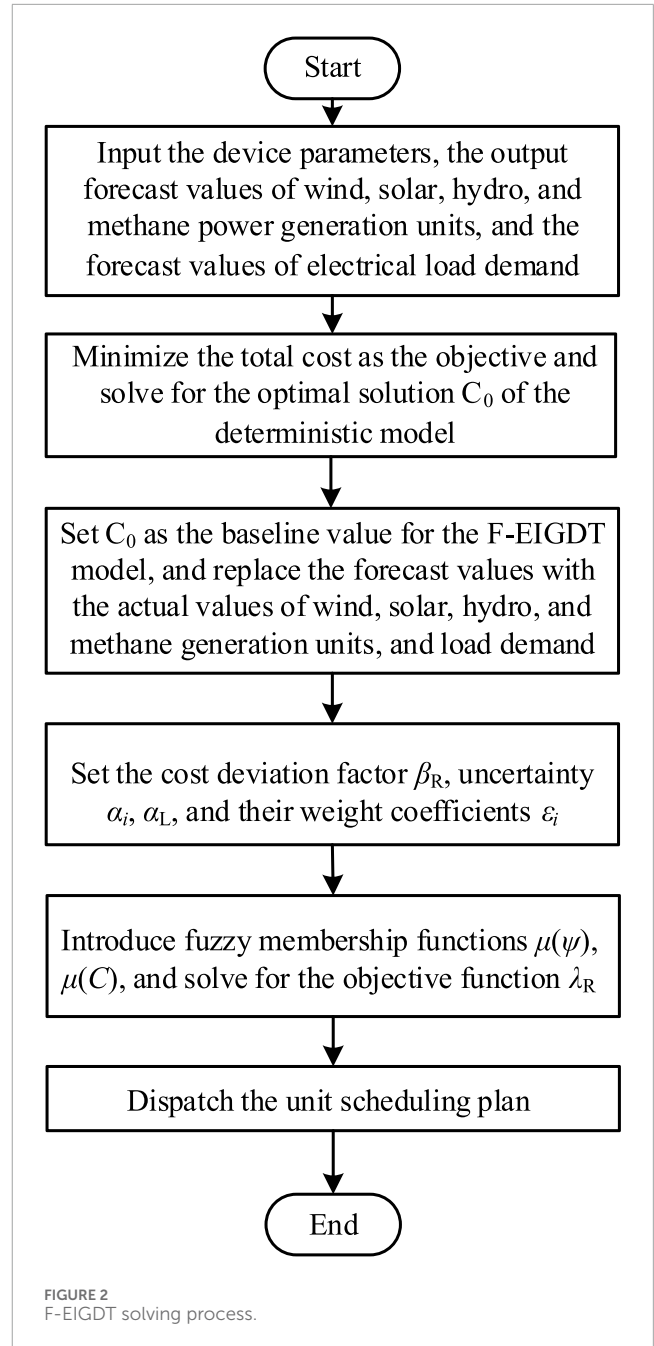
$$\begin{cases} \max \lambda_R \\ \frac{\psi - \psi^{min}}{\psi^{max} - \psi^{min}} \geq \lambda_R \\ \frac{C_C - C}{C_C - C^{min}} \geq \lambda_R \\ \psi = \sum \varepsilon_i \alpha_i \\ C(X, P) \leq C_C \\ C_c = (1 + \beta_R) C_0 \\ P_i^t = (1 - \alpha_i) \tilde{P}_i^t \\ P_{load}^t = (1 + \alpha_L) \tilde{P}_{load}^t \end{cases} \quad (59)$$

Equations (11)–(31), Equations (36)–(45)

At this point, for any objective function $C(X, P)$, it is less than the maximum expected value C_C set by the decision-maker.

4.3 Model linearization

Since there are nonlinear terms in the modeling process, which make it difficult for solvers to solve directly, this paper adopts piecewise linearization (Liang et al., 2024a) and second-order cone relaxation (Lv et al., 2022) based on the characteristics of the nonlinear terms for linearization.



4.3.1 Piecewise linearization

The formulas used for piecewise linearization include Equations 14, 15. The linearization process can be represented as Equations 60–64.

$$L(f(x)) = \sum_{k=1}^n f(a_k) t_k \quad (60)$$

$$x = \sum_{k=1}^n a_k t_k, z \in \{0, 1\} \quad (61)$$

$$\sum_{k=0}^{n-1} z_k = 1, \sum_{k=0}^n t_k = 1 \quad (62)$$

$$t_0 \leq z_0, t_n \leq z_{n-1} \quad (63)$$

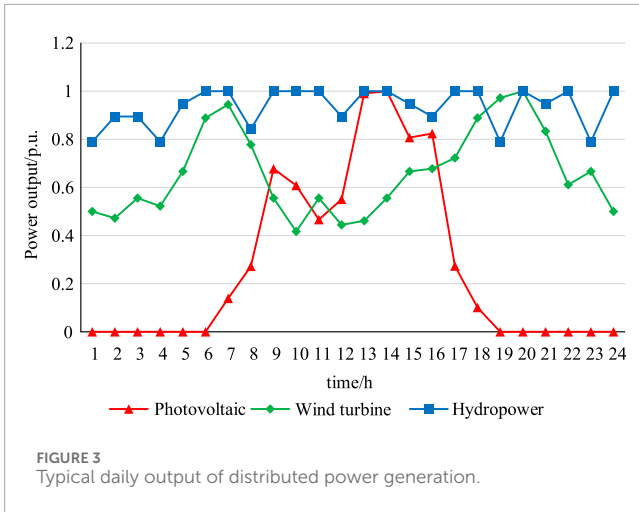


FIGURE 3 Typical daily output of distributed power generation.

$$t_k \geq 0, t_k \leq z_{k-1} + z_k, k = 0, 1, \dots, n - 1 \quad (64)$$

Where a_k is the segmentation point of the piecewise function $f(x)$. $L(f(x))$ is the linearized function of $f(x)$. k is the index of the segmentation point. n is the number of segmentation points. t_k and z are 0/1 variables.

The above expression contains n newly added binary variables z_0, z_1, \dots, z_{n-1} , where the number of these variables is the same as the number of segmentation intervals in the linearized function $L(f(x))$.

4.3.2 Second-order cone relaxation

For the quadratic terms present in the distribution network power flow constraints, we introduce slack variables $\alpha_{t,i}$ and $\beta_{t,ij}$, and apply second-order cone relaxation for convexification, which can be expressed as Equations 65, 66.

$$\alpha_{t,i} = U_{t,i}^2 \quad (65)$$

$$\beta_{t,ij} = I_{t,ij}^2 \quad (66)$$

Therefore, Equations 36–39 can be transformed into Equations 67–70.

$$\sum_{ij \in \Omega_{bc}} (P_{t,ij} - r_{ij}\beta_{t,ij}) + P_{t,i} = \sum_{jh \in \Omega_{bc}} P_{t,jh} \quad (67)$$

$$\sum_{ij \in \Omega_{bc}} (Q_{t,ij} - x_{ij}\beta_{t,ij}) + Q_{t,i} = \sum_{jh \in \Omega_{bc}} Q_{t,jh} \quad (68)$$

$$\alpha_{t,i} = \alpha_{t,i} + 2(r_{ij}P_{t,ij} + x_{ij}Q_{t,ij}) + (r_{ij}^2 + x_{ij}^2)\beta_{t,ij} \quad (69)$$

$$\alpha_{t,i}\beta_{t,ij} = P_{t,ij}^2 + Q_{t,ij}^2 \quad (70)$$

The standard second-order cone form is Equation 71.

$$\left\| \begin{matrix} 2P_{t,ij} \\ 2Q_{t,ij} \\ \beta_{t,ij} - \alpha_{t,i} \end{matrix} \right\|_2 \leq \beta_{t,ij} + \alpha_{t,i} \quad (71)$$

The relaxation error $E_{t,ij}$ can be expressed as Equation 72.

$$E_{t,ij} = \alpha_{t,i}\beta_{t,ij} - P_{t,ij}^2 - Q_{t,ij}^2 \quad (72)$$

4.4 Model solution process

The solution process for the wind-solar-hydro-methane coordinated optimization scheduling model based on F-EIGDT is shown in Figure 2.

- 1) Input the device parameters, the output forecast values of wind, solar, hydro, and methane power generation units, and the forecast values of electrical load demand.
- 2) Minimize the total cost as the objective and solve for the optimal solution C_0 of the deterministic model.
- 3) Set C_0 as the baseline value for the F-EIGDT model, and replace the forecast values with the actual values of wind, solar, hydro, and methane generation units, and load demand.
- 4) Set the cost deviation factor β_R , uncertainty α_i , and their weight coefficients ε_i .
- 5) Introduce fuzzy membership functions $\mu(\psi)$, $\mu(C)$, and solve for the objective function λ_R .
- 6) Dispatch the unit scheduling plan.

5 Case study

In this paper, a case study is conducted on a coal mine in Shanxi and its adjacent distribution system. The computer configuration used in this study is an Intel Core i7-14700F processor with a 64-bit Windows 11 operating system. The proposed model is simulated using MATLAB_R2024b software, with the YALMIP toolbox calling the GUROBI solver (version 11.0.3).

5.1 Parameter settings

This study focuses on a typical summer day. The wind speed, solar radiation, temperature, and water flow data for the typical day are clustered using the K-means algorithm. The predicted output of the photovoltaic, wind turbine, and hydroelectric power generation for the typical day are shown in Figure 3. The mine needs to conduct maintenance on underground production equipment between 11:00 and 16:00, during which no coal mining occurs. The time-of-use electricity prices are shown in Table 1. The equipment parameters are listed in Table 2, and other parameter information is in Table 3. For the renewable energy forecasts, many methods can achieve good prediction accuracy, so the forecast error range for wind, solar, hydro, and methane generation is set to [-10%, +10%]. The coal mine has a strong production schedule with minimal load fluctuations, so the error range for the overall load forecast of the mine is set to [-3%, +3%]. The forecast deviation for the overall load of the urban distribution network is set to [-5%, +5%].

TABLE 1 Time of use tariff.

Type	Peak	Flat	Off-peak
Period	08:00–11:00 18:00–23:00	07:00–08:00 11:00–18:00	23:00–07:00
Electricity price/(¥/kWh)	0.7659	0.5295	0.3058

TABLE 2 Power supply access to urban distribution network nodes and capacity.

Node	Access type	Capacity/kVA
4	Methane	500
5	Photovoltaic	1,000
14	Wind turbine	500
21	Hydropower	1700

TABLE 3 Additional parameters.

Parameter	Value	Parameter	Value
c_1	9.95×10^{-5}	$\mu_{pv}/(\text{¥/kWh})$	0.0235
d_1	380.34	$\mu_{wt}/(\text{¥/kWh})$	0.0196
ε_{wt}	0.45	$\mu_{hy}/(\text{¥/kWh})$	0.0286
ε_{pv}	0.27	$\mu_{meth}/(\text{¥/kWh})$	0.0250
ε_{hy}	0.14	$C_{meth}/(\text{MJ/m}^3)$	35.9
ε_{meth}	0.14	$C_{tank}/(\text{¥/m}^3)$	1,500

5.2 Scheduling results under deterministic scenarios

In the deterministic scenarios, two cases are set to study the impact of the gas regulation characteristics on the system's optimal scheduling:

Scenario 1: No consideration of the virtual regulation characteristics of methane (no methane storage tank installed).

Scenario 2: Consideration of the virtual regulation characteristics of methane (methane storage tank installed).

The system relaxation error using the second-order cone relaxation method adopted in this study is shown in Figure 4. The maximum magnitude of branch power relaxation error is on the order of 10^{-6} , indicating that second-order cone relaxation is feasible without loss of accuracy.

The system scheduling costs under different scenarios are shown in Table 4.

From Table 4, it can be seen that in Scenario 2, where a methane storage tank is configured, the system operating cost decreases from 75,258.6 RMB in Scenario 1 to 69,651.5 RMB, a reduction of approximately 7.45%. This indicates that the introduction of the methane storage tank significantly improved the system's operational efficiency and regulation capability. At the same time, the environmental management cost slightly increased from 322.5 RMB to 366.7 RMB. Although the investment cost for the methane storage tank in Scenario 2 reached 6,584.1 RMB (the investment cost here is the equivalent annual cost of the total investment in the methane storage tank), the total cost of Scenario 2 is only 1,021.2 RMB higher than that of Scenario 1. Therefore, equipping the system with a methane storage tank helps to enhance the flexibility of methane storage and supply, while also improving the economic performance of the system to some extent.

Figure 5 shows the variation in methane power generation under different scenarios. The power generation is determined by the methane quality input to the methane power generation units. Specifically, Scenario 1 is significantly affected by the coal mine maintenance between 11:00 and 16:00, leading to a shortage of methane supply and resulting in notably lower power generation. In contrast, Scenario 2 introduces the methane storage tank, which enables the reserve and scheduling of methane resources, thereby providing supplementation when methane supply is insufficient. In this way, Scenario 2 effectively mitigates the limitations of power generation caused by methane supply fluctuations, significantly improving the flexibility and responsiveness of the power generation system.

Scenario 2 is selected to analyze the virtual energy storage state of the methane storage tank. The variation in the methane gas state in the storage tank is shown in Figure 6.

From Figure 6, it can be seen that the State of Charge (SOC) of the methane storage tank changes with methane injection and release. Between 01:00 and 07:00, and 17:00 and 19:00, the amount of methane injected into the storage tank is less than the amount released, causing the SOC to decrease. From 07:00 to 12:00 and 14:00 to 17:00, the SOC changes more steadily. At 12:00 and 21:00, the amount of methane injected into the storage tank is significantly greater than the release amount, resulting in a noticeable increase in SOC at those times. Additionally, between 19:00 and 22:00, the injection efficiency of methane increases, and the SOC of the storage tank gradually rises. Through dynamic regulation of methane injection and release, the methane storage tank promotes the efficient utilization of methane.

As shown in Figure 7, the system's electric power mainly consists of wind, solar, hydro, and purchased power from the grid. Methane power generation acts as a supplementary unit to traditional wind, solar, and hydro generation, compensating for the shortfalls in

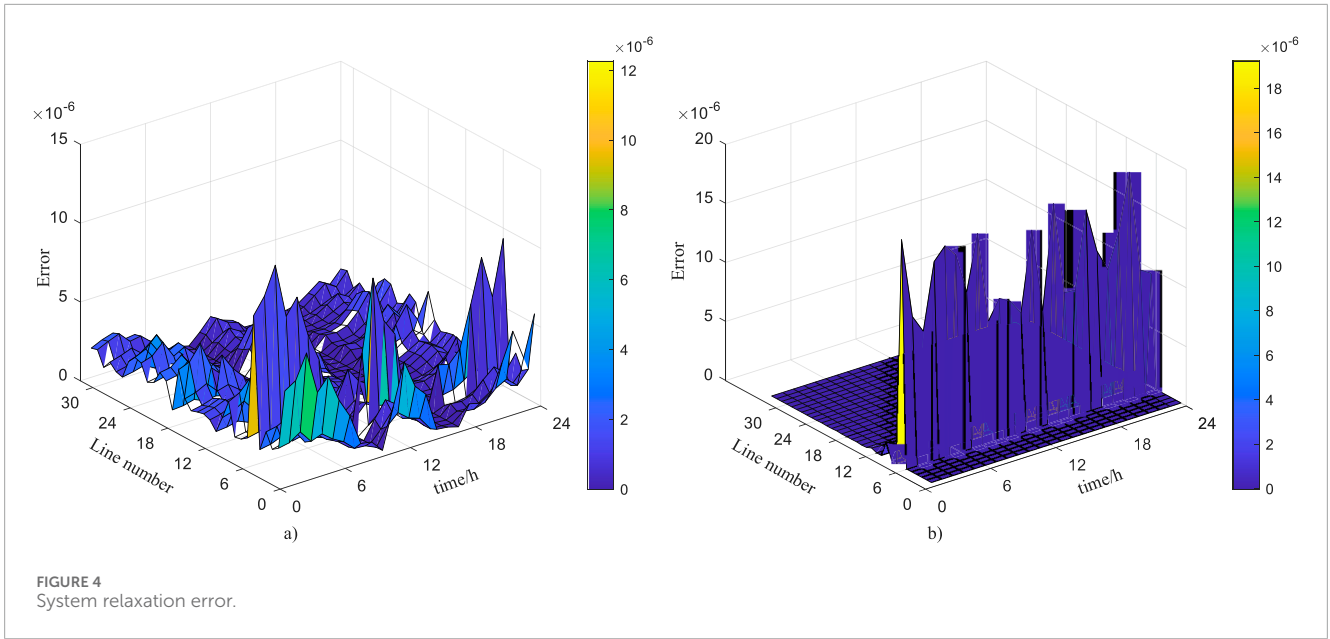
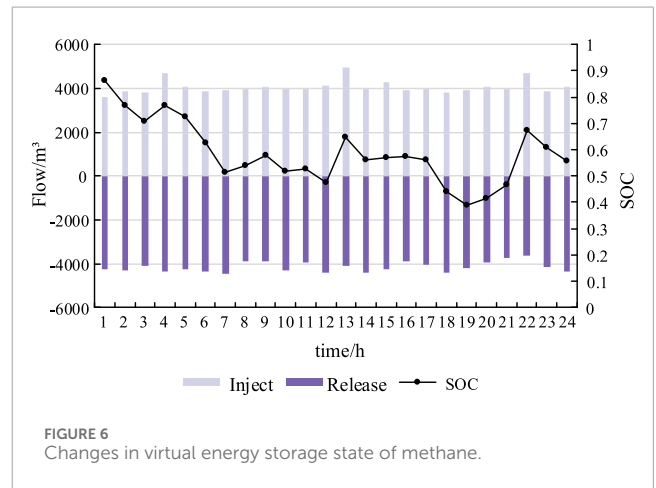
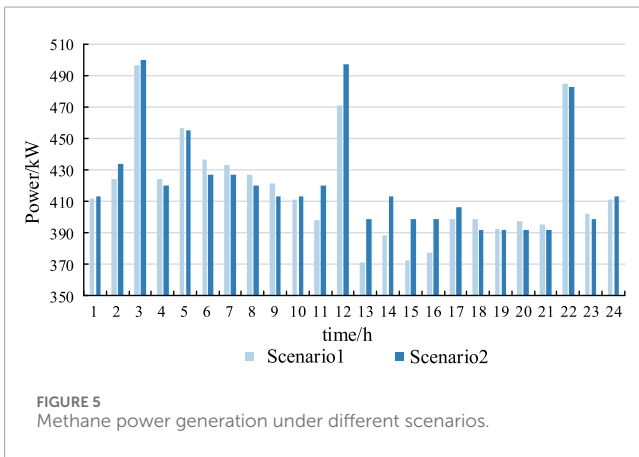


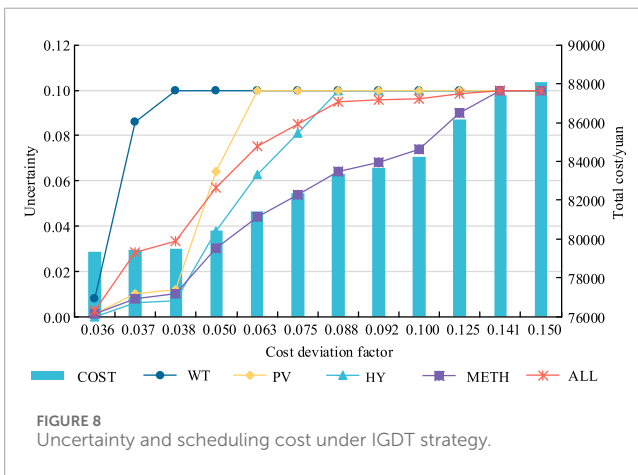
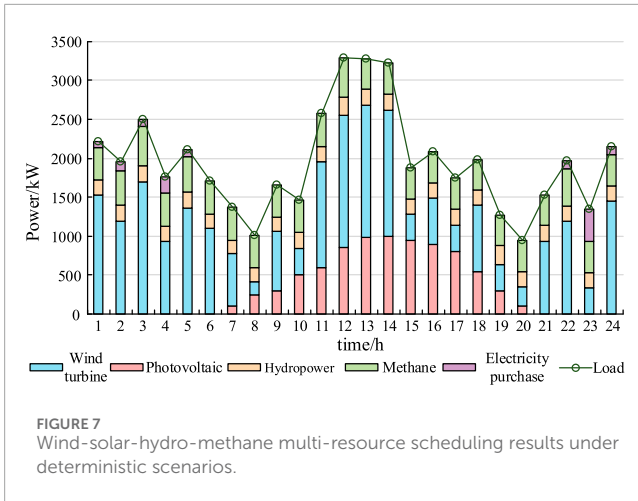
TABLE 4 System scheduling costs in deterministic scenarios.

Scenario	Operating cost/¥	Methane storage tank investment cost/¥	Environmental governance cost/¥	Total cost/¥
1	75258.6	0	322.5	75581.1
2	69651.5	6584.1	366.7	76602.3



renewable generation. During the 22:00–05:00 period, when the output of wind, solar, and hydro generation is low, there is a power shortage. At the same time, due to the impact of peak and valley electricity prices, most of the power deficit is made up by purchasing electricity from the grid. By adjusting methane power generation, the system can effectively address the randomness and intermittency of wind and solar power, enhancing the overall regulation capability of the system and promoting the efficient coupling and coordinated operation of methane generation with wind, solar, and hydro power.

In summary, although the methane storage tank slightly increases the total operational cost of the system, it can dynamically adjust methane resources, enabling efficient storage and scheduling of methane, effectively mitigating the impact of methane supply fluctuations on power generation capability, and promoting the efficient utilization of methane. At the same time, methane power generation serves as an effective supplement to traditional wind,



solar, and hydro generation, working in synergy to meet the operational demands of the system.

5.3 Scheduling results under uncertainty

Scene 2 is selected for the study of wind, solar, hydro, and methane uncertainty. To explore the impact of uncertainty in wind, solar, hydro, and methane on system scheduling, the following five combinations are set:

- Combination 1: Only consider the uncertainty of wind turbines.
- Combination 2: Only consider the uncertainty of photovoltaics.
- Combination 3: Only consider the uncertainty of hydropower.
- Combination 4: Only consider the uncertainty of methane.
- Combination 5: Consider the combined uncertainty of wind, solar, hydro, and methane.

5.3.1 IGDT scheduling results

Under the IGDT strategy, the variations of each uncertainty and scheduling cost with the cost deviation factor under different combinations are shown in Figure 8. The uncertainties of wind, solar, hydro, methane, and the combined uncertainty correspond to combinations 1–5, respectively.

Figure 8 illustrates the total scheduling cost of the system and the uncertainty variations of each distributed energy source under different cost deviation factors based on the IGDT strategy. As the cost deviation factor increases, the total scheduling cost rises non-linearly, and the uncertainty of each distributed energy source gradually increases, eventually reaching the maximum robustness level (uncertainty of 0.1). Methane and hydropower have relatively low uncertainties due to their stable power generation capability and flexible regulation. In contrast, photovoltaic and wind turbines are significantly affected by weather and climate, resulting in higher cost uncertainties and greater sensitivity to the deviation factor. Additionally, once the system reaches maximum robustness, further increasing the scheduling cost offers limited improvement in robustness and significantly reduces the economic performance. Therefore, the optimal scheduling strategy should choose a moderate deviation factor that enables the system to achieve a reasonable level of robustness at a lower cost.

Furthermore, for each target cost deviation set by the decision-maker, each distributed energy source has its corresponding maximum uncertainty fluctuation range. This relationship provides key reference for the expansion planning and coordinated scheduling of multi-energy systems, helping to formulate more robust power scheduling schemes in highly heterogeneous and stochastic environments. It enables efficient energy management that balances both system robustness and economic performance, further promoting the efficient integration and optimized utilization of wind, solar, hydro, and methane resources.

5.3.2 F-EIGDT scheduling results

Under the F-EIGDT strategy, the uncertainty and scheduling cost variations with cost deviation factors under different combinations are shown in Figure 9.

Figure 9 illustrates the trend of uncertainty and total system scheduling cost of different distributed energy sources under the F-EIGDT strategy as the cost deviation factor changes. The trend is similar to that in Figure 8, except that under the F-EIGDT strategy, the increase in cost is lower than that under the traditional IGDT. This indicates that the introduction of fuzzy logic enhances the system's ability to handle uncertainty. In particular, when the cost deviation factor is 0.092, the system reaches its strongest robustness level, and the total scheduling cost is reduced by 4.3% compared to IGDT. When the actual output of wind, solar, and hydro power fluctuates within 10% of the forecasted values, the system can effectively mitigate the fluctuations in the output of wind, solar, and hydro, while ensuring that the total scheduling cost does not exceed 83,649.71 yuan, significantly improving operational economics. This shows that F-EIGDT, through fuzzy logic and fuzzy set theory, addresses various uncertainties, overcoming the limitations of traditional IGDT in the absence of probabilistic information. It enables the system to achieve higher robustness and economic performance in complex scenarios such as wind and solar output deviations and methane supply fluctuations.

The methane power generation and methane storage tank SOC (State of Charge) under the IGDT and F-EIGDT strategies are shown in Figure 10.

As shown in Figure 10, under the IGDT strategy, the methane power generation fluctuates significantly, with frequent adjustments causing notable peaks and valleys. For example, power changes are

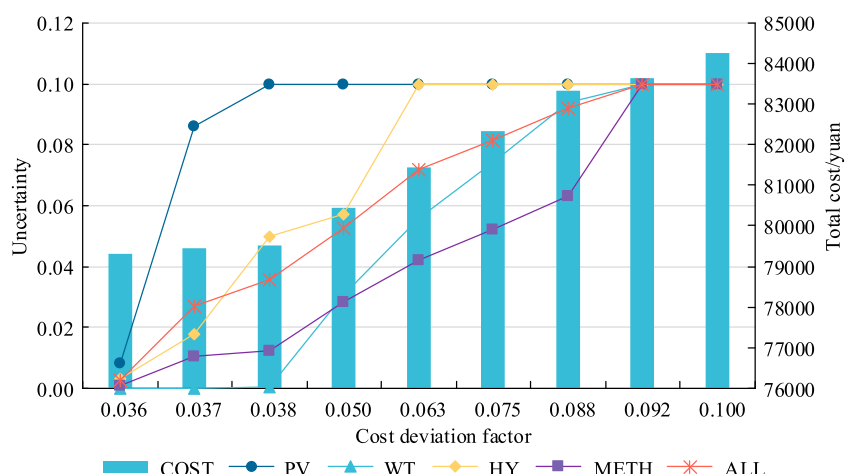


FIGURE 9 Uncertainty and scheduling cost under F-EIGDT strategy.

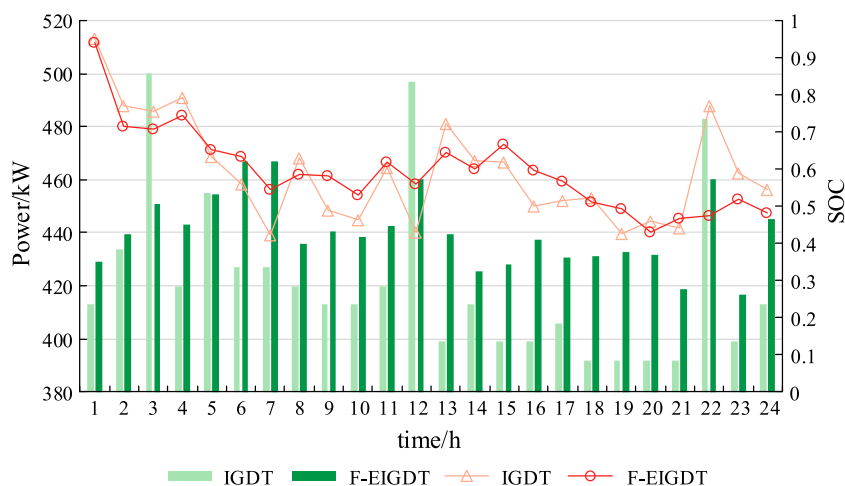


FIGURE 10 Methane power generation and methane storage tank SOC status under different strategies.

TABLE 5 Comparison of different optimization strategies.

Strategy	Total operating cost/¥	Maximum uncertainty/%	Solving time/s
Stochastic optimization	87412.6	4.6	22.6
IGDT	83649.7	9.2	4.73
F-EIGDT	83649.7	10.0	7.52

sharp at 03:00, 12:00, and 23:00, and the methane storage tank SOC (State of Charge) also experiences rapid fluctuations, indicating poor operational stability. This is because IGDT lacks the precise handling of uncertainty information and relies solely on worst-case scenarios for scheduling, resulting in frequent changes in gas power generation and storage tank charging/discharging operations. In contrast, the F-EIGDT strategy introduces fuzzy logic and fuzzy set theory, effectively smoothing the adjustment process of gas power

generation, reducing the amplitude of SOC fluctuations, and keeping it within a relatively stable range. This strategy significantly enhances the system's robustness and economic performance when facing fluctuations in wind and solar output, load forecasting errors, and methane supply uncertainties. It improves the stability of gas storage tank operations and reduces the economic cost caused by frequent adjustments, providing a better solution for the stable operation of multi-energy systems.

In conclusion, F-EIGDT can effectively smooth the fluctuations of gas power generation, reducing the amplitude of power fluctuations and enhancing the stability of system scheduling. By optimizing the trend of gas storage tank SOC changes, it reduces the dramatic fluctuations in gas injection and release, ensuring the stability and reliability of gas storage tank operations. Furthermore, F-EIGDT comprehensively considers various uncertainties, such as wind and solar output deviations, load forecasting errors, and methane supply fluctuations, enabling the scheduling scheme to achieve high robustness while maintaining superior economic performance.

5.4 Comparison of results

To verify the superiority of the proposed F-EIGDT in handling the uncertainty of wind, solar, hydro, and gas power, this section compares the F-EIGDT, IGDT, and stochastic optimization methods. The cost deviation factor of 0.092 from F-EIGDT is selected as the fluctuation range for the companion resources in the stochastic optimization method. Monte Carlo scenario generation and K-means clustering methods are used to generate five typical scenarios, and the maximum prediction deviation in different scenarios is represented using the definition of integrated uncertainty in the IGDT model. The comparison results of the three strategies are shown in Table 5.

From Table 5, it can be seen that stochastic optimization has a lower computational efficiency. Due to its insufficient consideration of system uncertainty, it results in the highest operating costs and the worst robustness, with a maximum prediction deviation of only 4.6%. IGDT, through worst-case-based optimization, significantly reduces operating costs and improves robustness, with a maximum prediction deviation of 9.2%, and the highest solving efficiency. In comparison, F-EIGDT, after introducing fuzzy logic to handle uncertainty, not only keeps operating costs consistent with IGDT but also increases the maximum uncertainty to 10.0%, demonstrating stronger robustness and risk resistance. Although the solving time is slightly higher, it remains within a reasonable range. Overall, the F-EIGDT strategy achieves a better balance between robustness, economy, and computational efficiency, making it a superior choice for addressing complex uncertainty scenarios in the system.

6 Conclusion

This paper proposes a wind-solar-hydro-gas coordinated optimal scheduling method with adjustable methane power generation. By analyzing the actual energy supply network of coal mines in depth, we construct a refined methane power generation and virtual methane storage model, and propose an optimized scheduling framework that incorporates the dynamic regulation characteristics of gas resources. In addition, to address the multiple uncertainties of wind-solar power generation and gas supply, this paper introduces the F-EIGDT, which significantly improves the system's scheduling robustness and economic performance in complex uncertain environments. The analysis and verification are conducted through a case study of a coal mine in Shanxi. The results show that:

- 1) A refined model for gas power generation and virtual gas storage is developed, closely aligned with the actual coal mine

production. This model fully considers the key influencing factors in the gas extraction process and integrates gas storage and utilization, forming a virtual storage mechanism focused on dynamic gas regulation. Through detailed modeling, the flexibility and fast response capability of the gas power generation units are quantitatively evaluated.

- 2) The proposed wind-solar-hydro-gas coordinated optimization scheduling model makes full use of the dynamic regulation characteristics of the gas storage tank, combining coal mine safety constraints and network operation requirements to achieve time-shifting and flexible utilization of gas resources. The case study results show that this method effectively mitigates the challenges caused by the randomness and intermittency of wind-solar power generation, enhances the system's comprehensive regulation capability, optimizes energy utilization efficiency, and reduces operational costs to some extent.
- 3) The F-EIGDT method with fuzzy logic significantly improves the decision-making robustness under multiple uncertainty factors. By applying fuzzy logic, the stability and economy of the decision-making plan are enhanced when facing actual operational fluctuations. Experimental results show that F-EIGDT outperforms traditional stochastic optimization methods in smoothing gas power generation, reducing gas storage tank fluctuations, and optimizing system operation costs.

In summary, the wind-solar-hydro-methane coordinated optimization scheduling method proposed in this paper, combined with virtual gas storage and F-EIGDT, provides an innovative solution for addressing the challenges of complex system uncertainties. Future research will focus on expanding this method's application to larger-scale multi-gas power generation systems, exploring the integration of more uncertainty handling techniques, and continuously optimizing model parameters with actual operational data to promote the wide application and sustainable development of coordinated optimization scheduling methods in energy systems.

Data availability statement

The original contributions presented in the study are included in the article/supplementary material, further inquiries can be directed to the corresponding author.

Author contributions

WC: Writing—original draft, Conceptualization, Investigation, Methodology. XW: Conceptualization, Supervision, Writing—review and editing. RT: Formal Analysis, Methodology, Software, Writing—original draft. YJ: Methodology, Software, Writing—review and editing. HL: Formal Analysis, Writing—review and editing. YY: Investigation, Writing—review and editing.

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Conflict of interest

Authors WC, XW, RT, YJ, HL, and YY were employed by State Grid Jincheng Power Supply Co., Ltd.

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