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A dynamic reconfiguration model and method for load balancing in the snow-shaped distribution network

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The snow-shaped distribution network (SDN) is a cable distribution network composed of eight (or six) 10 kV feeders from four (or three) substations in a regular connection. Compared with the traditional 10 kV distribution network, SDN can support a wide range of load transfer among six or eight feeders. Aiming at the problem of load spatial-temporal unbalanced condition caused by the integration of distributed generators (DGs) and different load types in different feeders, this paper proposes a dynamic reconfiguration strategy for load balancing in SDN considering DGs and energy storage system (ESS). Firstly, the basic structure of SDN is analyzed and the power flow model for its dynamic reconfiguration is developed. Secondly, the dynamic reconfiguration optimization model for load balancing in SDN considering DGs and ESS is proposed to utilize the load transfer capability to mitigate the load unbalanced condition and reduce active power loss. Thirdly, the original nonconvex model is converted into a mixed-integer second-order cone programming (MISOCP) model by applying the second-order cone relaxation and the big-M method, which is solved by CPLEX solver. Finally, the effectiveness of the proposed model and method are verified by an actual case in Tianjin and IEEE 33-node system. The analysis results show that the proposed method can significantly alleviate the load unbalanced spatial-temporal distribution and improve the economic efficiency by regulating the operation of SDN including ESS optimization and dynamic reconfiguration.

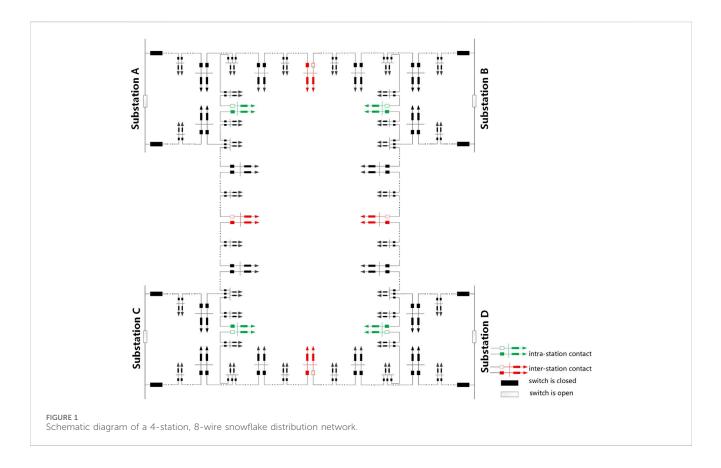
KEYWORDS

the snow-shaped distribution network (SDN), dynamic reconfiguration, load balance, energy storage system (ESS), mixed-integer second-order cone programming (MISOCP)

1 Introduction

The distribution system is the final link in the power system, directly serving the majority of users, and being closely related to population distribution and economic development. With the high-permeability access of DGs and the uneven spatial distribution of industrial, commercial, and residential regions in urban areas, the problem of load unbalanced spatial-temporal distribution has always existed in urban distribution networks. The mismatch between power generation and consumption may cause lower resource utilization, network congestion (Zhao et al., 2022), and increased active power loss, which seriously affects the security and economy of distribution network.

Aiming at the problem of load spatial-temporal unbalanced condition, there are mainly the following solutions. One option is to consider new substations or line expansion (Yao



et al., 2014), but this involves high investment costs and is challenging to implement, especially in areas with limited urban land resources. Through flexible regulation of controllable resources such as energy storage devices and flexible load, load curves can be dynamically adjusted by peak shaving and valley filling to alleviate load imbalance and other problems (Cho et al., 2012; Hosseina and Bathaee, 2016; Li et al., 2022). The effectiveness of this method is affected by the capacity and location of controllable resources. Network topology reconfiguration involves altering the open and closed states of switches in the feeders to balance feeder load, adjust power flow distribution, and improve the economic efficiency of distribution network (Baran and Wu, 1989a; Ji, 1997). Generally, distribution network reconfiguration can be divided into two categories: static reconfiguration and dynamic reconfiguration. Static reconfiguration optimizes the topology of the distribution network under a single time section, which is the basis of dynamic reconfiguration. Dynamic reconfiguration takes into consideration the fluctuation of DGs and load demand to dynamically optimize the distribution network structure in a continuous period (Jabr et al., 2012). The optimization objectives for distribution network reconfiguration are usually to minimize the active power loss (Jakus et al., 2017), improve the system reliability (Lotfi et al., 2020) and voltage stability (Zhang and Wang, 2004; Wang, 2012), and balance the feeder load (Gao et al., 2022). The optimization problem in multi-time dynamic reconfiguration involves both continuous and numerous discrete variables, posing a challenging task. Mathematical optimization methods (López et al., 2016; Tian et al., 2016; Aldik and Venkatesh,

2020), intelligent optimization algorithm (Lotfi and Ghazi, 2021; Lotfi, 2022) and heuristic algorithms (Jakus et al., 2020; Silveira et al., 2021; Montoya et al., 2023; Yu et al., 2023) have been proposed to solve the problem. Heuristic algorithms, not necessitating convexity in the mathematical model, have been widely used in solving non-convex problems. However, the results may be local optimal solutions through heuristic algorithms. With the development of optimization theory, mathematical optimization methods have been extensively applied to solve dynamic reconfiguration problems. Specifically, the convex relaxation technique represented by second-order cone programming (SOCP) is used more and more frequently, which can obtain the globally optimal solution and reduce the computation time.

The above studies address the distribution network load balancing problem with traditional single-radial distribution network, most of them start from the spatial dimension to realize load balancing by adjusting the tie switches state. The dispatching means are relatively single, considered only from the feeder level, with less consideration of scenarios where load and DG output change over time, and seldom with the main objective of load balancing of multiple feeders in multiple substations. However, relative to the previous grid structure, snow-shaped distribution network is upgraded based on a 10 kV single-double ring network by adding new station tie switches. The snowshaped distribution network (SDN) (Wang et al., 2023) constructs a "3-station 6-wire" or "4-station 8-wire" feeder cluster, with the ring main units as the network unit, and each feeder contains multiple tie switches and segment switches. The flexible and controllable ring network structure

of SDN establishes a supportive platform for dynamic reconfiguration to achieve multi-level and multi-directional load transfer, and provides an effective means to promote the spatial-temporal balance of load within feeder clusters. It can comprehensively consider a variety of control means to realize the load transfer between two feeders supplied by the same transformer, different transformers, and different substations, to achieve the "feeder-transformer-substation" three levels of load balancing.

To our best knowledge, this is the first study on the load imbalance problem of substation level, transformer level and feeder level in urban SDN. From both time and space dimension, this paper proposes a multi-objective dynamic reconfiguration model for load balancing through collaborative optimal dispatching of dynamic reconfiguration and distributed energy storage system in SDN. Firstly, the grid structure of SDN is analyzed and the power flow model for its dynamic reconfiguration is developed. Secondly, based on the advantages of multiple inter-station and intra-station connections, a dynamic reconfiguration model in SDN for feeder load balancing is established, considering DGs and ESS. In order to take into account the economic efficiency and load balancing, the weighted combination of the minimum active power loss and load balance index is proposed as the optimization objective function. Thirdly, the original non-convex model is converted into a mixed-integer second-order cone programming (MISOCP) model using convex relaxation theory for an accurate and efficient solution. Finally, the proposed dynamic reconfiguration model and method are analyzed and verified in the 10 kV Tianjin snow-shaped distribution network and IEEE 33-node system.

2 Snow-shaped distribution network structure and model

2.1 Snow-shaped distribution network structure

Under the development of new power distribution system, a flexible and controllable ring network structure named SDN is proposed in Wang et al. (2023), based on the traditional single and double ring distribution network. This structure comprehensively supports the wide range of load transfers between different feeders, feeder clusters, and snowshaped units.

SDN takes the ring main units as ring network nodes, composed of eight (or six) 10 kV feeders from four (or three) substations in a regular connection to form a group of independent feeder clusters. Each substation has two 10 kV outgoing lines, each equipped with an inter-station contact and an intra-station contact. As shown in Figure 1, taking the four-station SDN as an example, the existing four groups of single-loop network wiring only establish contacts between the stations. Building on this foundation, four new intra-station contacts have been added, so that the inter-station and intra-station have established load transfer channels to provide an effective method for spatial-temporal load balancing in the feeder cluster.

2.2 Power flow model for SDN dynamic reconfiguration

In this paper, the branch power flow model for SDN dynamic reconfiguration is developed based on the distflow model which was proposed in Baran and Wu (1989b). This paper introduced 0–1 integer variables $a_{ij}(t)$ to represent the open and closed states of the switches on the branch. The power flow model can be mathematically expressed as follows:

2.2.1 Active and reactive power balance constraints

$$\begin{cases} \sum_{i \in \Omega_{in}(j)} a_{ij}(t) \left(P_{ij}(t) - I_{ij}^{2}(t) R_{ij} \right) + P_{j}(t) = \sum_{k \in \Omega_{out}(j)} a_{jk}(t) P_{jk}(t) \\ \sum_{i \in \Omega_{in}(j)} a_{ij}(t) \left(Q_{ij}(t) - I_{ij}^{2}(t) X_{ij} \right) + Q_{j}(t) = \sum_{k \in \Omega_{out}(j)} a_{jk}(t) Q_{jk}(t) \end{cases}$$
(1)

$$U_{j}^{2}(t) = U_{i}^{2}(t) - 2\left(P_{ij}(t)R_{ij} + Q_{ij}(t)X_{ij}\right) + I_{ij}^{2}(t)\left(R_{ij}^{2} + X_{ij}^{2}\right)$$
(2)

$$I_{ij}^{2}(t) = \frac{P_{ij}^{2}(t) + Q_{ij}^{2}(t)}{U_{i}^{2}(t)}$$
(3)

where $\Omega_{in}(j)$, $\Omega_{out}(j)$ denote the sets of ring nodes in SDN with node *j* as the end ring node and the first ring node, respectively; $P_{ij}(t)$, $Q_{ij}(t)$ denote the active and reactive power flowing from ring node *i* to ring node *j* at moment *t*, respectively; when $a_{ij}(t)$ is 1, it means that the contact switch on the branch *ij* is in the closed state at moment *t*, then branch *ij* needs to be subjected to the constraints; and 0 means it is in the open state. $U_j(t)$ denotes the voltage magnitude at ring node *j* at moment *t*; $P_j(t)$ and $Q_j(t)$ denote the active and reactive power injected at ring node *j* at moment *t*, respectively; R_{ij} and X_{ij} denote the resistance and reactance magnitude of branch *ij*, respectively; and $I_{ij}(t)$ denotes the current magnitude of branch *ij* at moment *t*.

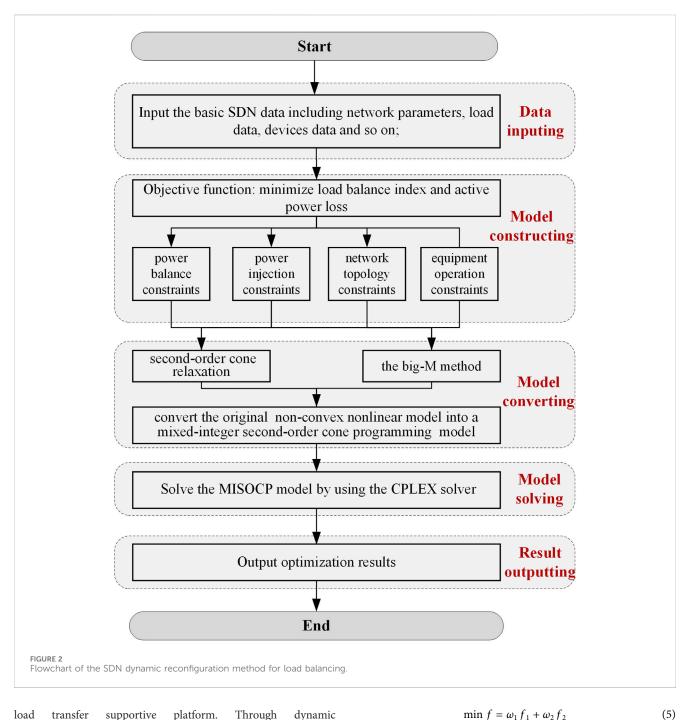
2.2.2 Active and reactive power injection constraints

$$\begin{cases} P_j(t) = P_{\text{DG},j}(t) - P_{\text{load},j}(t) + P_{\text{ESS},dis,j}(t) - P_{\text{ESS},ch,j}(t) \\ Q_j(t) = -Q_{\text{load},j}(t) \end{cases}$$
(4)

where $P_{\text{DG},j}(t)$ denotes the active power output of the distributed PV connected to the ring node *j* at moment *t*; $P_{\text{load},j}(t)$, $Q_{\text{load},j}(t)$ denote the active and reactive power of the load at ring node *j* at moment *t*; and $P_{\text{ESS},dis,j}(t)$, $P_{\text{ESS},ch,i}(t)$ are the discharging and charging power of the energy storage connected to the ring node *j* at moment *t*.

3 A snow-shaped distribution network dynamic reconfiguration model for load balancing

In urban distribution networks, different types of loads have different spatial-temporal asynchrony, and some feeders have heavy load during peak-load period. SDN constructs feeder clusters with four (or three) stations and eight (or six) lines, providing a flexible



load transfer supportive platform. Through dynamic reconfiguration, it can realize the flexible spatial-temporal transfer of load in feeder clusters to mitigating the coexistence of light and heavy loads to decrease the security risks in SDN operation and improve economic efficiency.

3.1 Objective function

Considering the economic operation and load balance of SDN, the linear weighted combination of the minimum feeder load unbalanced condition and total active power loss is proposed as the optimization objective function, which is formulated as follows:

$$=\omega_1 f_1 + \omega_2 f_2 \tag{5}$$

$$f_{1} = \sum_{t=1}^{T} \sum_{ij \in \Omega_{t}} \left(\frac{S_{ij}(t)}{S_{ij,\max}} \right)^{2} = \sum_{t=1}^{T} \sum_{ij \in \Omega_{t}} \frac{P_{ij}^{2}(t) + Q_{ij}^{2}(t)}{S_{ij,\max}^{2}}$$
(6)

$$f_{2} = \sum_{t=1}^{I} \sum_{i \neq \Omega_{l}} I_{ij}^{2}(t) R_{ij}$$
(7)

Where, the optimization objective function is formulated in Eq. 5 feeder load balance index f_1 and the total active power loss f_2 are formulated in Eqs 6, 7, respectively. The quantity ω_I is used as the coefficient of the load balance index. The quantity ω_2 is used as the coefficient of the total active power loss, and $\omega_1 + \omega_2 = 1$; the load balance index f_1 is defined as the square sum of the ratio between the transferred reactive power and the maximum transmission capacity

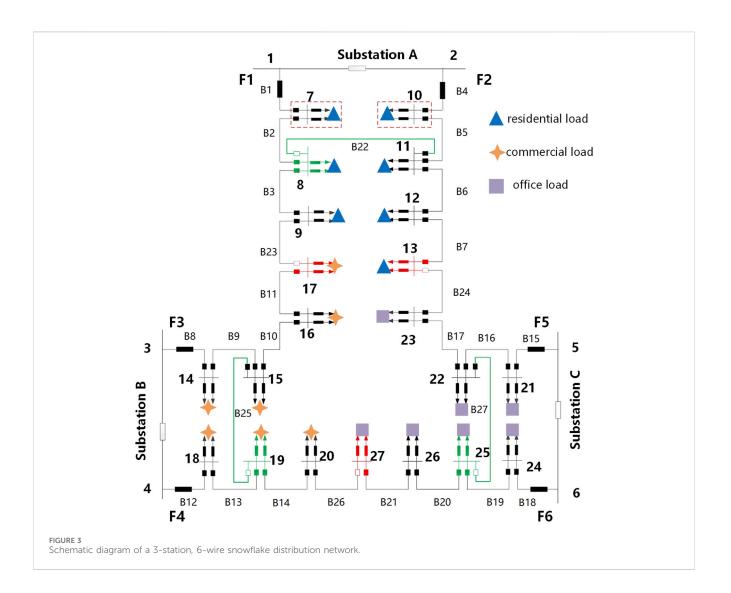


TABLE 1 Parameters of distributed PV and ESS.

Туре	Node	Rated power/MW	Rated capacity/MWh	Charging/discharging efficiency
PV	8, 9	1.2	_	_
ESS	22, 26	1.5	6	0.9

of the branch; Ω_l is the set of all branches in the SDN; and $S_{ij}(t)$ is the apparent power of branch *ij* at moment *t*, $S_{ij,\max}$ is the maximum apparent power of branch *ij*. *T* is the total period horizon, which is 24 h.

3.2 Constraints

The network dynamic reconfiguration problem proposed in this paper is a multi-objective optimization problem in mathematics, requiring compliance with the pertinent constraints.

(1) Active and reactive power balance constraints are given by Eqs 1-3.

- (2) Active and reactive power injection constraints are given by Eq. 4.
- (3) Security operation constraints

$$\begin{cases}
P_{i,\text{sub,min}}(t) \leqslant P_{i,\text{sub}}(t) \leqslant P_{i,\text{sub,max}}(t) \\
Q_{i,\text{sub,min}}(t) \leqslant Q_{i,\text{sub}}(t) \leqslant Q_{i,\text{sub,max}}(t)
\end{cases}$$
(8)

$$I_{ij}^2(t) \leqslant I_{ij,\max}^2 \tag{9}$$

$$U_{i,\min} \leqslant U_i(t) \leqslant U_{i,\max} \tag{10}$$

Equation 8 represents the constraints on substation output power. The current limit for branch *ij* at time *t* is expressed in Eq. 9. Equation 10 indicates the node voltage constraints. Where, $P_{i,sub}(t)$ and $Q_{i,sub}(t)$ are the active and reactive output power of the substation in ring node *i* at time *t*, respectively; $P_{i,sub,max}(t)$ and

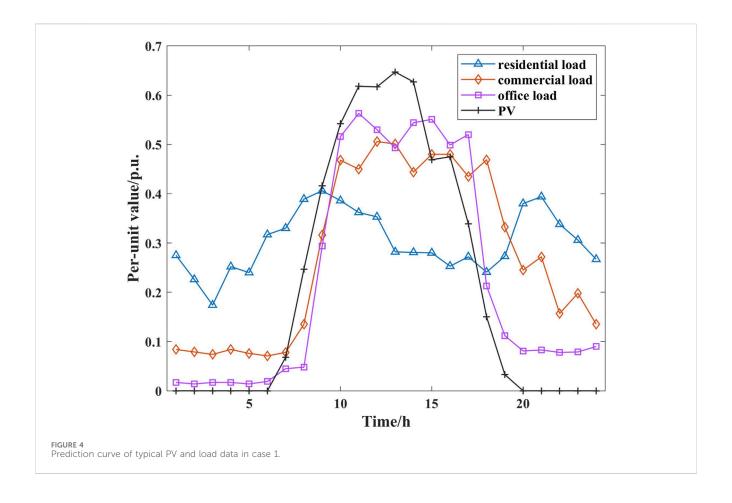


TABLE 2 Load balance index and active power loss optimization results.

Scenario	Load balance index f_1 (p.u.)	Reduction rate of f_1 (%)	Active power loss f ₂ (kWh)	Reduction rate of f_2 (%)
Scenario 1	28.71	—	1700.36	_
Scenario 2	24.48	↓14.73%	1552.16	↓8.72%

 $P_{i,\text{sub,min}}(t)$ are the maximum and minimum active output power of the substation in ring node *i* at time *t*, respectively; $Q_{i,\text{sub,max}}(t)$ and $Q_{i,\text{sub,min}}(t)$ are the maximum and minimum reactive output power of the substation in ring node *i* at time *t*, respectively; $I_{ij,\text{max}}$ is the maximum current magnitude of branch *ij*; $U_{i,\text{max}}$ and $U_{i,\text{min}}$ are the maximum and minimum voltage magnitude in ring node *i*, respectively.

(4) Network topology constraint

$$\sum_{ij\in\Omega_l} a_{ij}(t) = N_{\text{bus}} - N_{\text{sub}}$$
(11)

Equation 11 indicates that the network structure is guaranteed to be open-loop operation in the process of dynamic reconstruction. Where, $N_{\rm bus}$ and $N_{\rm sub}$ denote the number of ring nodes and substations in the SDN, respectively.

(5) Contact switch state constraints

$$\alpha_{ij}(t) - \beta_{ij}(t) = a_{ij}(t) - a_{ij}(t-1)$$
(12)

$$\alpha_{ij}(t) + \beta_{ij}(t) \le 1 \tag{13}$$

$$\sum_{t \in T} \left(\alpha_{ij}(t) + \beta_{ij}(t) \right) \le K_{ij}^{\max}$$
(14)

Equation 12 represents the switching state equation relationship, and $\alpha_{ij}(t)$ and $\beta_{ij}(t)$ are both 0–1 variables that represent the sign bits of the contact switches closed and open on the branch *ij* at moment *t*. When $\alpha_{ij}(t) = 1$, the state of the contact switch on the branch *ij* changes from open to closed at moment *t*. When $\beta_{ij}(t) = 1$, the state of the contact switch on the branch *ij* changes from closed to open at time *t*; Eq. 13 indicates that the variables $\alpha_{ij}(t)$, $\beta_{ij}(t)$ cannot take 1 because the switching state can only be changed once at the same time; Eq. 14 indicates a constraint on the number of switching actions in a certain period, K_{ij}^{max} is the maximum number of switching actions. The dynamic reconfiguration process should avoid frequent changes in the switching state to ensure the service life of the switches.

Time	Open switches on branches
1	B2-B3-B7-B9-B26-B27
2	B2-B3-B7-B9-B26-B27
3	B2-B3-B7-B9-B26-B27
4	B2-B3-B7-B9-B26-B27
5	B2-B3-B7-B9-B26-B27
6	B2-B3-B7-B9-B26-B27
7	B2-B3-B7-B9-B26-B27
8	B2-B3-B7-B9-B26-B27
9	B2-B3-B7-B9-B26-B27
10	B9-B11-B17-B20-B22-B27
11	B9-B11-B17-B20-B22-B27
12	B9-B11-B17-B20-B22-B27
13	B9-B11-B17-B20-B22-B27
14	B9-B11-B17-B20-B22-B27
15	B9-B11-B17-B20-B22-B27
16	B9-B11-B17-B20-B22-B27
17	B9-B11-B17-B20-B22-B27
18	B2-B7-B9-B11-B14-B27
19	B2-B7-B9-B11-B14-B27
20	B2-B7-B9-B11-B14-B27
21	B2-B7-B9-B11-B14-B27
22	B2-B7-B9-B11-B14-B27
23	B2-B7-B9-B11-B14-B27
24	B2-B7-B9-B11-B14-B27

TABLE 3 Results of dynamic reconfiguration in scenario 2 (case 1).

(6) Energy storage operation constraints

$$S_{\text{ESS},i}(t) = S_{\text{ESS},i}(t-1) + \eta_{ch} P_{\text{ESS},ch,i}(t) - \frac{P_{\text{ESS},dis,i}(t)}{\eta_{dis}}$$
(15)

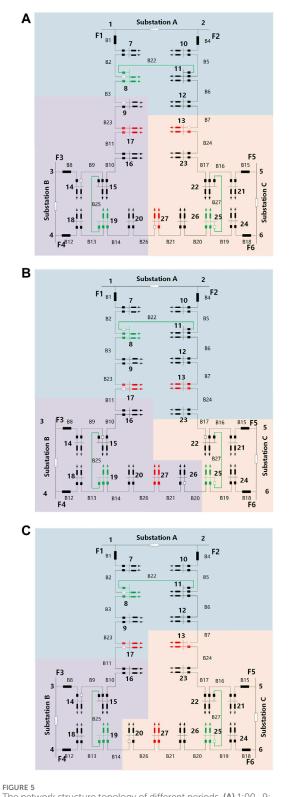
$$E_{\text{ESS},i} \cdot C_{\text{ESS}}^{\min} \le S_{\text{ESS},i}(t) \le E_{\text{ESS},i} \cdot C_{\text{ESS}}^{\max}$$
(16)

$$\begin{cases} 0 \le P_{\text{ESS},dis,i}(t) \le P_{\text{ESS},i} \cdot \mu_{dis}(t) \\ 0 \le P_{\text{ESS},ch,i}(t) \le P_{\text{ESS},i} \cdot \mu_{ch}(t) \end{cases}$$
(17)

$$0 \le \mu_{dis}(t) + \mu_{ch}(t) \le 1$$
 (18)

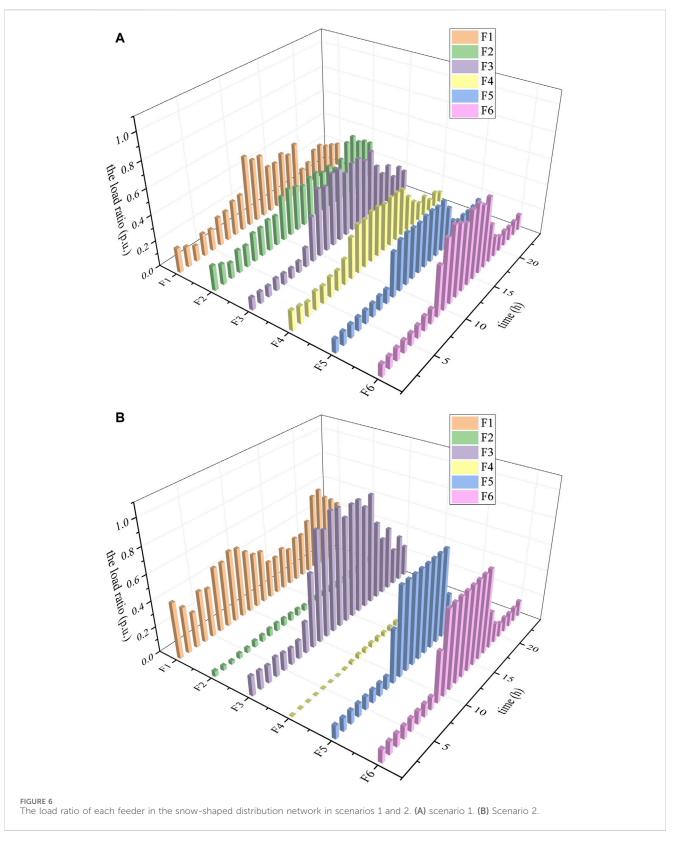
$$S_{\text{ESS},i}(0) = S_{\text{ESS},i}(T) = E_{\text{ESS},i} \cdot C_{\text{ESS}}^{\min}$$
(19)

where Eqs 15–19 are the constraints of energy storage operation $S_{\text{ESS},i}(t)$ denotes the power of energy storage connected to the ring node *i* at moment *t*; η_{ch} and η_{dis} are the charging and discharging efficiency of energy storage, both of which are taken as 90% in this paper; $P_{\text{ESS},i}$ and $E_{\text{ESS},i}$ are the rated power and rated capacity of energy storage at ring node *i*; $\mu_{ch}(t)$ and $\mu_{dis}(t)$ denote the charging and discharging states of energy storage at moment *t*. When the energy storage is charging, $\mu_{ch}(t)$ is 1, $\mu_{dis}(t)$ is 0; when discharging, $\mu_{dis}(t)$ is 1, $\mu_{ch}(t)$ is 0;



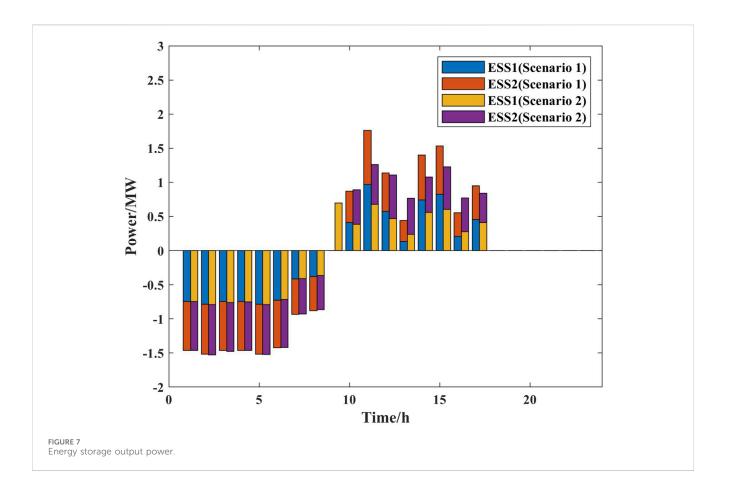
The network structure topology of different periods. (A) 1:00–9: 00. (B) 10:00–17:00. (C) 18:00–24:00.

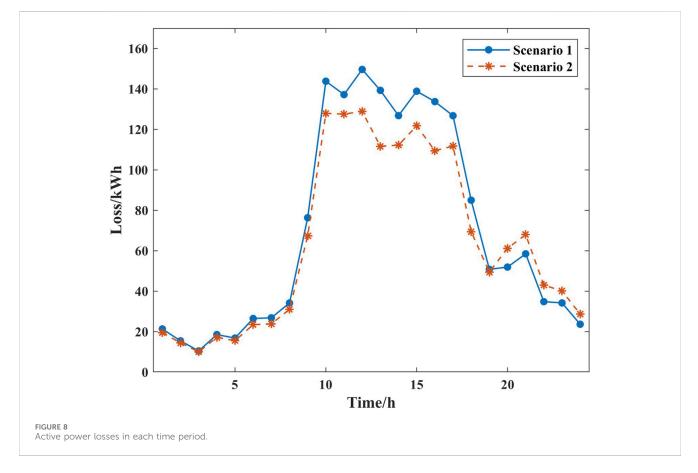
 $C_{\text{ESS}}^{\text{max}}$ and $C_{\text{ESS}}^{\text{min}}$ denote the maximum and minimum value of the energy storage charging state at the moment *t*, which are 0.9 and 0.1, respectively.

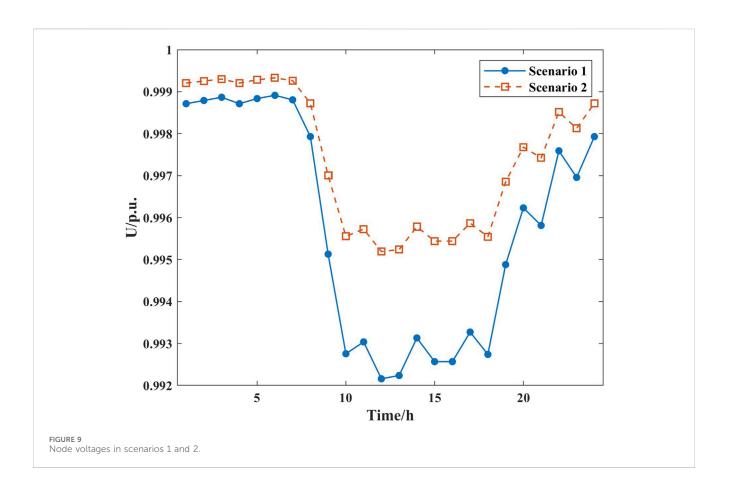


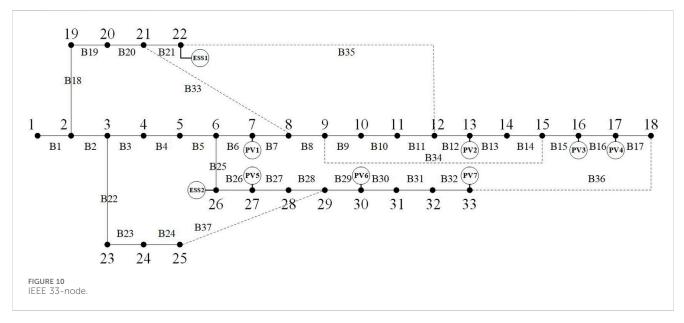
4 Solution methodology

The dynamic reconfiguration model for SDN is a highly nonconvex nonlinear programming problem, which may have multiple locally optimal points and is difficult to solve to obtain the globally optimal solution. In order to solve this problem accurately and efficiently, the original non-convex nonlinear programming (NLP) can be converted into a mixed integer second-order cone programming (MISOCP) by applying the second-order cone relaxation and the big-M method.









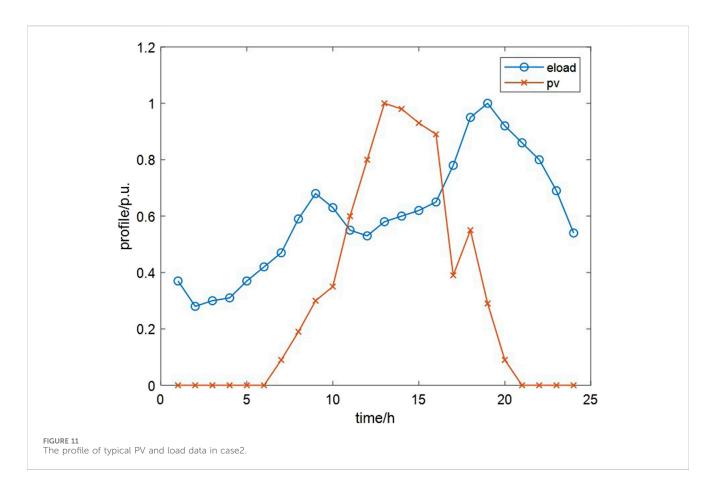
Equations 20, 21 are obtained by introducing auxiliary variables $i_{ij}(t)$, and $u_{ij}(t)$ for variable transformation, and Eq. 22 is obtained by relaxation through the big-M method. *M* is an arbitrarily large positive number that is not infinite.

$$i_{ij}(t) = I_{ij}^2(t)$$
 (20)

$$u_i(t) = U_i^2(t) \tag{21}$$

$$\begin{cases} -a_{ij}(t)M \le P_{ij}(t) \le a_{ij}(t)M \\ -a_{ij}(t)M \le Q_{ij}(t) \le a_{ij}(t)M \end{cases}$$
(22)

With the above constraints Eqs 20–22, the trend constraint Eq. 1 is transformed into Eq. 23, and Eq. 2 is relaxed by the big-M method to obtain Eq. 24.



Scenario	Load balance index f_1 (p.u.)	Reduction rate of f_1 (%)	Active power loss f_2 (kWh)	Reduction rate of f_2 (%)
Scenario 1	4.4324	—	1744.55	—
Scenario 2	2.4266	↓45.25%	1256.51	↓27.98%

$$\begin{cases} \sum_{i \in \Omega_{in}(j)} \left(P_{ij}(t) - i_{ij}(t) R_{ij} \right) + P_j(t) = \sum_{k \in \Omega_{out}(j)} P_{jk}(t) \\ \sum_{i \in \Omega_{in}(j)} \left(Q_{ij}(t) - i_{ij}(t) X_{ij} \right) + Q_j(t) = \sum_{k \in \Omega_{out}(j)} Q_{jk}(t) \end{cases}$$

$$u_j(t) - u_i(t) \ge -M(1 - a_{ij}(t)) - 2\left(P_{ij}(t) R_{ij} + Q_{ij}(t) X_{ij} \right) \\ + i_{ij}(t) \left(R_{ij}^2 + X_{ij}^2 \right) \\ u_j(t) - u_i(t) \le M(1 - a_{ij}(t)) - 2\left(P_{ij}(t) R_{ij} + Q_{ij}(t) X_{ij} \right) \\ + i_{ij}(t) \left(R_{ij}^2 + X_{ij}^2 \right) \end{cases}$$

$$(23)$$

Equation 7 is transformed to Eq. 25 accordingly.

$$f_{2} = \sum_{t=1}^{T} \sum_{i j \in \Omega_{l}} i_{ij}(t) R_{ij}$$
(25)

Equation 3 is transformed into Eq. 26 by the second-order cone relaxation, which is further transformed into the standard second-order cone form as shown in Eq. 27:

$$i_{ij}(t) \ge \frac{P_{ij}^2(t) + Q_{ij}^2(t)}{u_i(t)}$$
(26)

$$\left\| \begin{array}{c} 2P_{ij}(t) \\ 2Q_{ij}(t) \\ i_{ij}(t) - u_i(t) \\ \end{array} \right\|_2 \leq i_{ij}(t) + u_i(t)$$
 (27)

Similarly, the linearization of Eq. 6 is achieved by introducing the auxiliary variable $f_{ij}(t)$ for variable substitution. Equation 28 is obtained by using variable substitution of $\frac{P_{ij}^2(t)}{S_{ij,\max}^2}, \frac{Q_{ij}^2(t)}{S_{ij,\max}^2}$.

$$f_{ij}(t) = \frac{P_{ij}^2(t)}{S_{ij,\max}^2} + \frac{Q_{ij}^2(t)}{S_{ij,\max}^2}$$
(28)

Equation 6 is transformed into Eq. 29.

$$f_{1} = \sum_{t=1}^{T} \sum_{i \neq \Omega_{l}} f_{ij}(t)$$
(29)

Equation 28 is transformed into Eq. 30 with the second-order cone relaxation, which is further transformed into the standard second-order cone form as shown in Eq. 31:

$$f_{ij}(t) \ge \frac{P_{ij}^2(t)}{S_{ij,\max}^2} + \frac{Q_{ij}^2(t)}{S_{ij,\max}^2}$$
(30)

Time	Open switches on branches
1	B6-B10-B14-B17-B25
2	B6-B10-B14-B17-B25
3	B6-B10-B14-B17-B25
4	B6-B10-B14-B17-B25
5	B6-B10-B14-B17-B25
6	B6-B10-B14-B17-B25
7	B6-B10-B14-B17-B25
8	B6-B10-B14-B17-B25
9	B6-B10-B14-B17-B25
10	B6-B10-B14-B17-B25
11	B7-B14-B15-B27-B35
12	B7-B14-B15-B27-B35
13	B7-B14-B15-B27-B35
14	B7-B14-B15-B27-B35
15	B7-B14-B15-B27-B35
16	B7-B14-B15-B27-B35
17	B4-B10-B13-B25-B36
18	B4-B10-B13-B25-B36
19	B4-B10-B13-B25-B36
20	B4-B10-B13-B25-B36
21	B4-B10-B13-B25-B36
22	B4-B10-B13-B25-B36
23	B4-B10-B13-B25-B36
24	B4-B10-B13-B25-B36

TABLE 5 Results of dynamic reconfiguration in scenario 2 (case 2).

$$\left\| \begin{array}{c} 2\frac{P_{ij}(t)}{S_{ij,\max}} \\ 2\frac{Q_{ij}(t)}{S_{ij,\max}} \\ 1 - f_{ij}(t) \end{array} \right\|_{2} \le 1 + f_{ij}(t)$$
(31)

The flowchart of SDN dynamic reconfiguration method for load balancing in this paper is shown in Figure 2. And the specific operation process includes the following five steps:

- Step 1: Data inputting. Input the basic SDN data including network parameters, load data, devices data, and so on;
- Step 2: Model constructing. Construct SDN dynamic reconfiguration model for load balancing to minimize load balance index and active power loss, which set the constraints including active and reactive power balance constraints, active and reactive power injection constraints, security operation constraints, network topology constraints and so on;

- Step 3: Model converting. Convert the NLP model into a MISOCP model which can be solved easily by applying the second-order cone relaxation and the big-M method;
- Step 4: Model solving. Use the CPLEX solver to solve the MISOCP model;
- Step 5: Results outputting. Output the optimization results.

5 Case study

5.1 Case 1 (3-station, 6-wire SDN)

5.1.1 Case introduction

The validity of the model and method proposed in this paper is verified with a 3-station, 6-wire snow-shaped distribution network. The structure diagram of SDN is shown in Figure 3, including 3 substations, 6 feeders, 21 ring main units, and 27 branches. Green ring main units indicate intra-station contact switches and red ring main units indicate inter-station contact switches. The rated voltage is 10 Vk, with an allowable voltage range of 0.93 p.u. to 1.07 p.u. The maximum allowable branch current is 577 A. Substation A provides power to residential loads, Substation B provides power to commercial loads, and Substation C provides power to office loads. Table 1 lists the parameters of PV and ESS. The prediction curve of typical PV and load data is shown in Figure 4. The heavily loaded feeders involve F1, F3, F5, F6, and the lightly loaded feeders involve F2, F4.

Different types of loads have different patterns of curve change. Residential load mainly includes the electricity consumed by residents' electrical equipment, which experiences steady growth with economic development and notable seasonal fluctuations. Commercial load mainly includes air-conditioning, lighting, power, and other electrical loads in commercial areas. Peak electricity consumption hours are concentrated and stable throughout the day. Office load is closely related to the working hours, and the peak electricity consumption is mainly concentrated during these hours with a great difference between peak and valley.

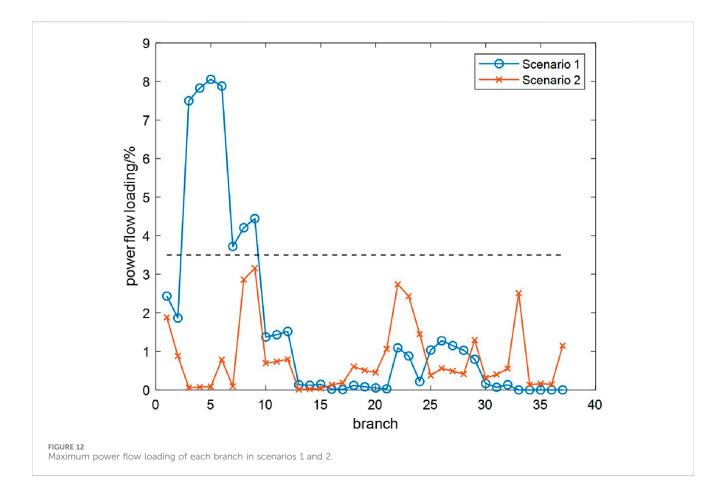
The maximum number of switch actions per day is set to 4. By using the hierarchical hierarchy process (AHP), the load balance index and active power loss weighting coefficients ω_1 , and ω_2 in the objective function are 0.846 and 0.154, respectively. The proposed method in this paper is implemented in using MATLAB R2020a, where the MISOCP model is modeled by YALMIP programming and solved by the CPLEX solver.

5.1.2 Analysis of dynamic reconfiguration results

The following two scenarios are set up for the analysis and comparison. Scenario 1 is the benchmark scenario, which considers the PVs and ESS. Based on scenario 1, dynamic reconfiguration is considered in scenario 2.

The effectiveness of the dynamic reconfiguration model and method of SDN are verified as follows.

- Step 2: Model constructing. Construct SDN dynamic reconfiguration model for load balancing to minimize load balance index and active power loss,
- Step 3: Model converting. Convert the NLP model into a MISOCP model through the second-order cone relaxation and the big-M method;



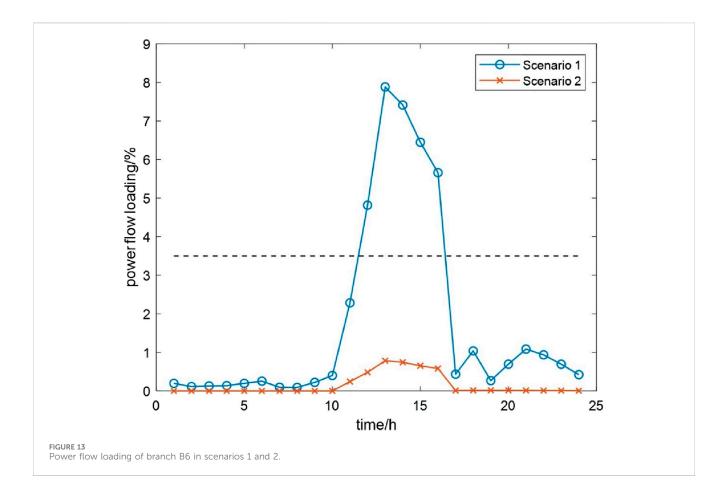
The optimization results of load balance index and active power loss for SDN in scenarios 1 and 2 are listed in Table 2. The load balance index is 28.71 in scenario 1 and 24.48 in scenario 2, which is reduced by about 14.73%. The maximum load ratio of the feeder is reduced from 92.46% to 59.24%, which is reduced by about 33.22%. The all-day active power loss of SDN is reduced from 1,700.36 kWh to 1,552.16 kWh, a reduction of about 8.72%. With the collaborative optimization of energy storage and dynamic reconfiguration, the load balancing in SDN is greatly improved and the active power losses are reduced.

In scenario 1, the switches on contact lines B22, B23, B24, B25, B26, and B27 are in the open state before reconfiguration. In scenario 2, the states of sectional contact switches are optimized through dynamic reconfiguration to achieve a wide range of spatial load transfer, thus enhancing overall load balance in SDN. The results of dynamic reconfiguration in scenario 2 are shown in Table 3.

At 0:00–9:00, the switches on branches B2, B3, B7, and B9 open, and the switches on branches B22, B23, B24, and B25 close. The loads of ring node 8 on feeder F1 are transferred to feeder F2 through intra-station contact on branch B22; The loads of ring nodes 9,15,16 and 17 are transferred to feeder F4 through inter-station contact on branch B23 and intra-station contact on branch B25; The loads of ring node 13 on feeder F2 are transferred to feeder F5 through inter-station contact on branch B24; At 10:00–17:00, B11, the switches on branches B11, B17, B20 and B22 open, switches on branches B2, B3, B7, and B26 close. The loads of ring node 23 on feeder F5 are transferred to feeder F2 through inter-station contact on branch B24; The loads of ring nodes 26 and 27 on feeder F6 are transferred to feeder F4 through inter-station contact on branch B26; At 18:00–24:00, the switches on branches B2, B7, and B14 open, switches on branches B17, B20, and B22 close. The different network structure topology of different periods is shown in Figure 5. Different colored parts indicate the power supply ranges of different substations.

The load ratio of each feeder in the snow-shaped distribution network in scenarios 1 and 2 is shown in Figure 6. In scenario 1, feeder 5 and feeder 6 are equipped with ESS. ESS absorbs electricity at the time of low power consumption, and releases electricity at the time of peak power consumption to smooth the load curve, reduce the curve volatility, and alleviate the peak load on feeder F5 and feeder F6. However, the regulation capability is limited, and the load ratios of feeders F3, F5, and F6 remain high during the time period of 8:00–18:00, up to 92.46%, and the heavy load situation is serious. In scenario 2, based on dynamic reconfiguration, the load on the feeder with high load rate is transferred to other feeder with low load rate through multiple switch contacts in the snow-shaped network feeder cluster, and the maximum load rate is reduced to 59.24%, realizing a more balanced feeder load of the whole network.

In scenario 1 and 2, the ESS output power is shown in Figure 7, which both show the trend of charging and then releasing. ESS charges during the load valley time (01:00–08: 00) and then discharges the stored energy during the peak load period (10:00–17:00). The energy is transferred across time, achieving peak shaving and valley filling effects on the load



curve and thereby smoothing it. During the peak load period (10: 00–17:00), the active power output of ESS in scenario 1 and 2 are different. In scenario 1, the optimal dispatching of ESS can only smooth the load curve on feeder F5 and feeder F6 in substation C because of node 22 in feeder 5 and node 26 in feeder 6 equipped with ESS. In scenario 2, node 26 is in feeder 4 at 10:00–17: 00 through dynamic reconfiguration. During the load valley time (01:00–08:00), the optimal dispatching of ESS can smooth the load curve on feeder F6 in substation C. During the load valley time (10:00–17:00), the optimal dispatching of ESS can smooth the load curve on feeder F5 in substation C. During the load valley time (10:00–17:00), the optimal dispatching of ESS can smooth the load curve on feeder F4 in substation B and feeder F5 in substation C through dynamic reconfiguration. The collaborative optimization of energy storage and dynamic reconfiguration achieves the "feeder-transformer-substation" three levels of load balancing.

The active power losses for each hourly period before and after the dynamic reconfiguration of SDN are shown in Figure 8. The voltage fluctuations at typical nodes before and after the dynamic reconfiguration are shown in Figure 9.

From Figures 8, 9, it can be seen that network dynamic reconfiguration in SDN effectively reduces the system active power loss, enhances the voltage level and improves the power quality. The active power loss decreases from 1700.36 kWh to 1552.16 kWh throughout the day, a reduction of about 8.72%. For instance, considering ring node 14, the node voltage increases after dynamic reconfiguration, alleviating voltage offset and enhancing the system's voltage safety margin.

5.2 Case 2 (IEEE 33-node)

The proposed method is tested on a standard test style such as IEEE 33-node. This test system is a 12.66 kV distribution network which is shown in Figure 10. The profile of typical PV and load data is shown in Figure 11. Similar to Section 5.1, this section sets up two scenarios for comparison. Scenario 1 is the benchmark scenario, which considers the PVs and ESS. Based on scenario 1, dynamic reconfiguration is considered in scenario 2. The values of ω_1 and ω_2 in case 2 are the same as in case 1.

Table 4 lists the optimization results of load balance index and active power loss in scenarios 1 and 2. The overall load balance index is 4.4324 in scenario 1 and 2.4266 in scenario 2, which is reduced by about 45.25% by conducting the feeder load balancing method based on dynamic reconfiguration. The all-day active power loss of SDN is reduced from 1256.51 kWh to 1744.55 kWh, a reduction of about 27.98%, which is a considerable improvement of economic efficiency.

The results of dynamic reconfiguration in scenario 2 are shown in Table 5.

Figure 12 shows the maximum power flow loading of each branch over a day for scenarios 1 and 2. The maximum power flow loading is reduced in scenario 1 by conducting dynamic reconfiguration. The unbalanced condition of the feeder load is exacerbated due to the high penetration of distributed renewable energy in scenario 1, as shown in Figure 13. The proposed dynamic reconfiguration-based feeder load balancing method, which is implemented in scenario 2, maintains the power flow loading within the desired level and significantly mitigates the feeder load unbalanced condition caused by the increasing distributed renewable energy.

6 Conclusion

Based on the characteristics of SDN frame structure, this paper establishes a multi-objective dynamic reconfiguration model for load balancing through collaborative optimal dispatching of dynamic reconfiguration and distributed energy storage system in SDN. And the second-order cone relaxation and big-M method are employed to convert the original NLP model into a MISOCP model which can be tractably solved. Case studies in an urban 10 kV distribution network and IEEE 33-node system are performed to show the effectiveness of the proposed model, the following conclusions can be drawn:

- The optimization results show that the safety and economy of SDN operation are both included in our formulated model to mitigate the feeder load unbalance, reduce the active power loss and improve voltage profile.
- (2) Through adjusting the switching state combinations of tie switches and segment switches at the spatial level as well as by optimizing the charging and discharging states of the energy storage at the temporal level, the model proposed in this paper maximizes the advantages of inter connection and intra connection among feeder clusters in SDN, achieving the large-scale space-time load transfer, and fully excavating the power supply capacity of the distribution network.

This paper focuses on the dynamic reconfiguration strategy in SDN for feeder load balancing, flexibly transferring load through intra-station and inter-station contacts in all directions to improve system security and economic efficiency. Further research will consider additional elements such as flexible loads and electric vehicles to fully exploit the operational potential of SDN.

Data availability statement

The original contributions presented in the study are included in the article/supplementary material, further inquiries can be directed to the corresponding author.

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FL: Conceptualization, Supervision, Writing-review and editing. XW: Data curation, Methodology, Software, Writing-original draft, Writing-review and editing. ZW: Writing-review and editing. JD: Writing-review and editing.

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Conflict of interest

Authors ZW and JD were employed by State Grid Tianjin Electric Power Company.

The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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