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Robust stochastic low-carbon optimal dispatch of park-integrated energy system with multiple uncertainties from source and load

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To realize the cascaded utilization of energy, improve the effective utilization of energy, and further reduce the carbon emissions of integrated energy systems a robust stochastic low-carbon optimal dispatch model with economy, environmental protection and reliability is developed for a park-integrated energy system wherein the multiple uncertainties brought by source and load are fully considered. First, a two-stage robust optimization algorithm is employed to handle uncertain wind power generation. A multi-case analysis method for the uncertainties of photovoltaics and load is proposed based on an improved centralized reduction algorithm. Then, considering the depreciation of the weighted average of the comprehensive operation cost, carbon emissions, and energy undersupply rate, a robust stochastic optimal dispatch model can be derived and efficiently solved by using a multi-objective fuzzy optimization algorithm with an improved membership function. Finally, by comparing the four cases, the simulation results show that the computational complexity and calculation time of the system can be reduced, the trimming result errors can be decreased, and a balance between economy, environmental protection, reliability, and robustness can be achieved.

KEYWORDS

low carbon optimal dispatch, robust optimization, multiple uncertainties of source and load, improved centralized reduction, multi-objective fuzzy optimization

1 Introduction

Nowadays, power industry is continuously optimizing its energy structure in response to the national “carbon emission reduction.” Renewable energy is becoming increasingly prevalent because of its low pollutant emissions and sustainable supply (Alabi et al., 2022; Zhang K. et al., 2022; Zhang et al., 2022b; Wang F. et al., 2023; Zhang et al., 2023). However, renewable energy also has shortcomings, such as its random nature and fluctuations, which pose significant challenges to the safety and stability of park-integrated energy system (PIES). Although related research on energy output and load forecasting has improved (Li et al., 2021a; Sun Y. et al., 2021; Tang et al., 2022; Wang S. et al., 2023; Huang et al., 2023; Sun et al., 2023), the uncertainty remains a significant issue in system dispatch.

Over the past few decades, numerous studies have been conducted on the optimal low-carbon dispatch of PIES. By introducing power-to-gas (P2G) equipment into the system, the effectiveness of P2G technology in the PIES for wind power consumption was verified in

(Cui et al., 2022). In (Qin et al., 2022), a refined model of P2G operation was established, and an electricity hydrogen storage system (P2HSS) was constructed; the simulation results showed that the P2HSS could reduce the system carbon emissions and achieve better performance. Carbon trading was taken as a tool utilizing market mechanisms to effectively reduce carbon emissions (Qi and Han, 2023). In (Sun P. et al., 2021), the authors discussed the influence of carbon trading price on system operation. A stepped carbon-trading mechanism was introduced into PIES in (Wang et al., 2022; Zhou et al., 2023), where electricity hydrogen production was completely considered. In (Yang et al., 2023), an optimal dispatch model containing a combined cooling, heating, electricity unit, and carbon capture device was proposed, in which the demand response could help to flexibly shift the load and reduce carbon emissions. In (Li H. et al., 2021), a novel stepped carbon-trading model was constructed by introducing rewards and punishments. In (Liu, 2022), a low-carbon dispatch model for PIES was developed considering whole-life carbon emissions. However, most of the existing results are deterministic models, and low-carbon optimal dispatch under the influence of multiple source- and load-related uncertainties is rarely considered.

For these uncertainties in load prediction and energy output in PIES optimal operation, case analysis, robust optimization, and fuzzy theory have been adopted (Zhang et al., 2022c; Ma et al., 2022; Yan et al., 2022). In (Li et al., 2021c), an interval optimal model under multiple uncertainty conditions was established and the simulation results showed that the number of optimal intervals gradually increased with an increase in the degree of uncertainty fluctuation. In (Wang et al., 2019), the characteristics of the prediction error of wind power and photovoltaic (PV) were analyzed in advance and a robust optimal model considering the prediction errors was provided. A Gaussian process regression method was used to determine the probability distributions of renewable energy and load forecasts, and a min-max rolling optimal model was established in (Dong et al., 2022). In (Mahdavi et al., 2022), the normal probability density function was used to describe the uncertainty of the load. In (Xiong et al., 2022), soyster robust was utilized to handle the uncertainty of photovoltaic and load, and the worst-case scenario was selected as the related output. To reduce the conservatism of robust optimization, a two-stage robust model was proposed, and its effectiveness in improving the system economy and robustness was analyzed in (Gao et al., 2022). The Monte Carlo analysis was used to generate cases of uncertainty in (Di Somma et al., 2017). These studies used a single method, and the characteristics of the uncertainty factors were rarely combinatorically optimized.

In terms of case analysis, wind power output and load cases were combined to obtain integrated cases and their probabilities (Xie and Xu, 2022). In (Qi et al., 2023), a risk aversion dispatch strategy was developed with a minimum objective of the conditional value at risk. The number of integrated cases in (Di Somma et al., 2017; Xie and Xu, 2022; Qi et al., 2023) increased exponentially when the number of uncertain variables increased, which significantly increased the system complexity and computation time. In (Zeng et al., 2020), an overall case generation and reduction method was proposed with the purpose of reducing the tediousness of operations; however,

the influence of each uncertain variable on the reduction process was not considered, thereby increasing the error of the reduction results and easily leading to a single correlation.

The authors primarily focused on a robust stochastic low-carbon optimal dispatch of PIES with multiple uncertainties. The main contributions and novelty are presented as follows.

- (1) For uncertain wind power output, a two-stage robust min-max-min optimization algorithm is utilized, and a multi-case analysis method based on an improved centralized case reduction is proposed. To handle the uncertainty of photovoltaic and load. The combination of the two methods reduces the conservatism of the robust optimization method.
- (2) By introducing the stepped carbon trading mechanism, a robust stochastic low-carbon optimal dispatch method for PIES is constructed with economy, environmental protection and reliability indicator, which is solved using a multi-objective fuzzy optimization algorithm with an improved membership function. This enables the system to achieve comprehensive operation while reducing the subjectivity of setting multiple objective weights.

The remaining of the manuscript is arranged as: In Section 2, the structure of the PIES is described first, and then uncertain models for the load and PV are provided. In Section 3, the development of a robust stochastic low-carbon optimal dispatch strategy of the PIES and a detailed solution process are presented. In Section 4, a case study and comparison analysis are presented to demonstrate the effectiveness of the proposed model. Finally, the paper concludes with a discussion on future research.

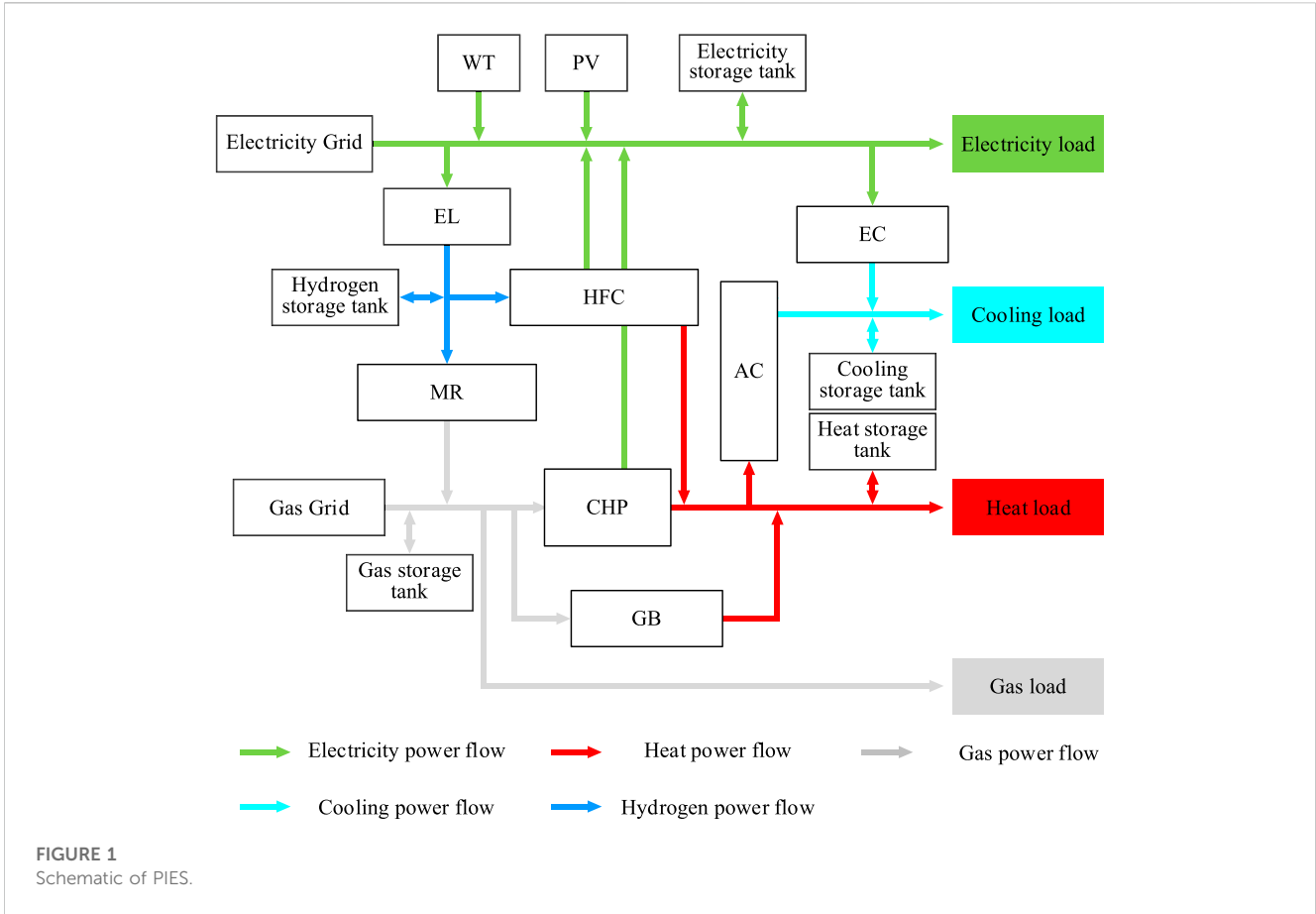
2 System description

2.1 Structure of PIES

A diagram of the proposed PIES is presented in Figure 1. In terms of energy production, upper-level power grid, gas network, and photovoltaic PV and wind turbine (WT) unit are available. The energy conversion components include combined heat and power (CHP) unit, gas boiler (GB), electric chiller (EC), absorption chiller (AC), electrolyzer (EL), methane reactor (MR), hydrogen fuel cell (HFC), and multi-energy storage device. The energy outputs include the cooling, heat, electricity, and gas load. The carbon emissions generated by the PIES are ultimately traded in the carbon trading market.

2.2 Mechanism of stepped carbon trading

To reduce greenhouse gas emissions, a carbon emission trading mechanism is developed as an effective approach. The stepped carbon trading mechanism is a flexible market-based approach to reducing carbon emissions. According to its mechanism: carbon emission reduction targets are divided into different tiers, and participants are rewarded by reaching or exceeding the goals of each tier. The mechanism includes carbon quota allocation, carbon trading and reward and punishment mechanism, which encourages



enterprises and organizations to adopt innovative emission reduction measures to promote low-carbon economic development and achieve sustainable development goals.

The carbon emission sources considered in this study include purchasing electricity from the grid, CHP, GB, and gas load. The hydrogen conversion process of methane reactors can absorb some CO₂, which is primarily consumed through the combustion of gases such as coal and natural gas, resulting in carbon emissions that need to be considered (Zhou et al., 2023).

2.3 Model of wind power with uncertainty

It is well known that wind power output is challenging to characterize accurately in real-world cases owing to various factors, such as wind speed and geographical location. However, obtaining a range of output values is relatively straightforward. Therefore, a boxing interval set u is used to describe the uncertainty caused by wind power. A robust uncertainty adjustment parameter Γ is employed to adjust the conservatism, a larger parameter results in more conservative solution. Conversely, a smaller parameter leads to more liberal the solution. The range of values includes integers within $[0, T]$, where T represents the total number of periods during the dispatch cycle. The wind power reaches the described fluctuation interval that is expressed as:

$$u = \begin{cases} P_{WT,t} = P_{WT,t}^{pre} - v_{WT,t}^- \Delta P_{WT} + v_{WT,t}^+ \Delta P_{WT} \\ v_{WT,t}^-, v_{WT,t}^+ \in \{0, 1\} \\ v_{WT,t}^- + v_{WT,t}^+ \leq 1 \\ \sum_{t=1}^T (v_{WT,t}^- + v_{WT,t}^+) \leq \Gamma \end{cases} \quad (1)$$

where $P_{WT,t}$ and $P_{WT,t}^{pre}$ are the actual and predicted wind power generation, respectively. $v_{WT,t}^-$ and $v_{WT,t}^+$ are upward and downward fluctuating state variables, respectively. ΔP_{WT} is the predicted deviation in wind power generation. T is the dispatch period.

2.4 Multi-case model of uncertainties of PV and load

The predicted values of PV generation, cooling, heating, electricity, and gas load deviate. In this study, the actual values are taken as the sum of the predicted values and deviations, which are expressed as:

$$\begin{cases} P_{PV,i,t} = P_{PV,i,t}^{pre} + \Delta P_{PV,i,t} \\ P_{Load,i,t} = P_{Load,i,t}^{pre} + \Delta P_{Load,i,t} \end{cases} \quad (2)$$

where $P_{PV,i,t}$ and $P_{PV,i,t}^{pre}$ are the actual and predicted PV generation for the i th case, respectively. $\Delta P_{PV,i,t}$ is the predicted deviation of PV generation. $P_{Load,i,t}$ and $P_{Load,i,t}^{pre}$ are the actual and predicted load for the i th case, respectively. $\Delta P_{Load,i,t}$ is the predicted deviation of load.

Without a loss of generality, in this study, photovoltaic generation and load are assumed to follow a normal distribution, and the basic parameters are given as:

$$\begin{cases} \mu_{PV,i,t} = P_{PV,i,t}^{pre} \\ \mu_{Load,i,t} = P_{Load,i,t}^{pre} \\ \sigma_{PV,i,t} = \frac{1}{10} P_{PV,i,t}^{pre} + \frac{1}{50} P_{PVN} \\ \sigma_{Load,i,t} = \frac{1}{20} P_{Load,i,t}^{pre} \end{cases} \quad (3)$$

where $\mu_{PV,i,t}$ and $\mu_{Load,i,t}$ are the mean values of PV generation and load for the i th case, respectively. $\mu_{PV,i,t}$ and $\mu_{Load,i,t}$ are the standard deviation of load output and load for the i th case, respectively. P_{PVN} is the rated capacity of PV unit.

For these uncertainties introduced by photovoltaic power output and load, the corresponding samples are generated through random sampling based on their probability distributions. In this study, the Latin hypercube sampling (LHS) is adopted, which ensures that the samples encompass the entire sample space of the random variable; detailed procedures can be found in (Xiong et al., 2022) and are excluded in this paper.

3 Robust stochastic low-carbon optimal dispatch model of PIES

Considering the uncertainties from sources and loads, a robust stochastic low-carbon optimal dispatch model is developed for the PIES. The model is divided into two stages: First, the multi-case analysis and multi-objective fuzzy optimization algorithm with an improved membership function are used to obtain the energy storage charging and discharging plan, grid interaction plan, and energy storage equipment output plan. Next, the robust min-max-min optimization algorithm is employed to minimize the energy purchase cost in the worst-case scenario. The proposed robust stochastic low-carbon optimal dispatch model is given by

$$\begin{aligned} \min \sum_{s=1}^N \rho_s & \left(\lambda \left(\left(\max_{u \in U} \min_y C_{buy,s}(u, y) + C_{op,s}(x) + F_{CO_2,s}(x) \right), E_s(x), C_{sus}(x) \right) \right) \\ \text{s.t. } & H_{buy,s}(x, u, y) = 0, G_{buy,s}(x, u, y) \leq 0 \\ & H_{op,s}(x) = 0, G_{op,s}(x) \leq 0 \\ & H_{CO_2,s}(x) = 0, G_{CO_2,s}(x) \leq 0 \\ & H_{E,s}(x) = 0, G_{E,s}(x) \leq 0 \\ & H_{sus,s}(x) = 0, G_{sus,s}(x) \leq 0 \end{aligned} \quad (4)$$

where N is the number of typical cases. ρ_s is the probability of occurrence of typical s cases. $C_{buy,s}$, $C_{op,s}$, $F_{CO_2,s}$, E_s , and $C_{sus,s}$ are the energy purchase cost, operation and maintenance cost, carbon trading cost, carbon emission, and energy undersupply rate of typical s cases, respectively. λ is a function of multi-objective fuzzy optimization satisfaction. x is the first-stage optimization variable, including the energy storage charging and discharging plan, grid interaction plan, and energy storage equipment output plan. y is a second-stage optimization variable that includes the unit output and grid interaction. U is a set of uncertainties in wind power generation.

3.1 Objective function

For a typical case of photovoltaic and load case, the objective function is described in detail to develop a robust stochastic low-carbon optimal dispatch model for PIES.

The first objective is to obtain the minimum operational cost within a dispatch period:

$$\min F = \min(C_{buy} + C_{op} + F_{CO_2}) \quad (5)$$

where F denotes the comprehensive operational cost. F_{CO_2} represents carbon trading cost. C_{buy} and C_{op} represent the system energy purchase cost and the operation and maintenance cost, respectively; these can be expressed as:

$$\begin{cases} C_{buy} = \sum_{t=1}^T (c_{buy,e,t} P_{buy,e,t} + c_{buy,g,t} P_{buy,g,t} - c_{sell,e,t} P_{sell,e,t}) \\ C_{op} = \sum_{t=1}^T \left(c_{WT} P_{WT,t} + c_{PV} P_{PV,t} + c_{CHP} P_{CHP,g,t} + c_{GB} P_{GB,g,t} \right. \\ \quad \left. + c_{EL} P_{EL,e,t} + c_{HFC} P_{HFC,H_2,t} \right. \\ \quad \left. + c_{MR} P_{MR,H_2,t} + c_{EC} P_{EC,e,t} + c_{AC} P_{AC,h,t} \right. \\ \quad \left. + \sum_{n=1}^5 c_{ES,n} (P_{ES,n,t}^{cha} + P_{ES,n,t}^{dis}) \right) \end{cases} \quad (6)$$

where $c_{buy,e,t}$ and $c_{buy,g,t}$ are the electricity purchase price and gas purchase price at time t , respectively. $c_{sell,e,t}$ is the electricity selling price. $P_{buy,e,t}$ is the power purchased at time t . $P_{buy,g,t}$ is the purchasing power of gas at time t . $P_{sell,e,t}$ is the selling power at time t . $P_{PV,t}$ is the actual PV generation at t . $P_{CHP,g,t}$ is the natural gas power input to the CHP system at time t . $P_{GB,g,t}$ is the natural gas power input to the GB at time t . $P_{EL,e,t}$ is the electric power input to EL. $P_{MR,H_2,t}$ is the hydrogen energy input to the MR. $P_{HFC,H_2,t}$ is the hydrogen energy input to the HFC. $P_{EC,e,t}$ is the electrical power input to the EC. $P_{AC,h,t}$ is the heat power input to the AC. $P_{ES,n,t}^{cha}$ and $P_{ES,n,t}^{dis}$ are the charging and discharging powers of the n th energy storage device, respectively.

The second objective is to achieve minimal total carbon dioxide emissions, which are expressed as follows:

$$\min E = E_{buy} + E_{CHP_GB} + E_{gload} - E_{MR} \quad (7)$$

where E is the total carbon emissions, E_{buy} is the carbon emissions caused by purchased power, E_{gload} is the carbon emissions caused by gas load, E_{CHP_GB} is the total carbon emissions from the CHP and GB, and E_{MR} is the amount of CO_2 absorbed by the MR hydrogen into natural gas. Detailed descriptions are as follows:

$$\begin{cases} E_{buy} = \sum_{t=1}^T (a_1 + b_1 P_{buy,e,t} + c_1 P_{buy,e,t}^2) \\ E_{CHP_GB} = \sum_{t=1}^T (a_2 + b_2 P_{total,t} + c_2 P_{total,t}^2) \\ P_{total,t} = P_{CHP,e,t} + P_{CHP,h,t} + P_{GB,h,t} \\ E_{MR} = \tau_{MR} \sum_{t=1}^T P_{MR,g,t} \end{cases} \quad (8)$$

where $P_{CHP,e,t}$ and $P_{CHP,h,t}$ are the electricity and heat power outputs of the CHP system, respectively. $P_{GB,h,t}$ is the heat power output of the GB. $P_{total,t}$ is the sum of the power output of the CHP system and GB. a_1 , b_1 , c_1 and a_2 , b_2 , and c_2 are the carbon emission factors of the CHP and GB coal-fired units, respectively. τ_{MR} is the CO_2 absorption parameter of the hydrogen-to-natural gas conversion

process in the MR equipment. $P_{MR,g,t}$ is the natural-gas power output of the MR.

The third objective is the energy undersupply rate of system, which is shown as

$$\min C_{us} = \frac{\sum_{t=1}^T (\Delta P_{load,e,t} + \Delta P_{load,h,t} + \Delta P_{load,g,t} + \Delta P_{load,c,t})}{\sum_{t=1}^T (P_{load,e,t} + P_{load,h,t} + P_{load,g,t} + P_{load,c,t})} \quad (9)$$

where C_{us} is the energy undersupply rate, which refers to a supply shortage when the electrical input and gas input suddenly drop to 50% of the original amount. $P_{load,e,t}$ is the electricity load at time t . $P_{load,h,t}$ is the heat load at time t . $P_{load,g,t}$ is the gas load at time t . $P_{load,c,t}$ is the cooling load at time t . $\Delta P_{load,e,t}$, $\Delta P_{load,h,t}$, $\Delta P_{load,g,t}$, $\Delta P_{load,c,t}$ are the shortages of supply for the electricity, heat, gas, and cooling load, respectively.

3.2 Constraints

(1) Wind turbine (WT) output constraints

$$0 \leq P_{WT,t}^{pre} \leq P_{WT,t}^{rate} \quad (10)$$

where $P_{WT,t}^{rate}$ is the rated power of WT unit during the t period.

(2) PV generation constraints

$$0 \leq P_{PV,t}^{pre} \leq P_{PV,t}^{rate} \quad (11)$$

where $P_{PV,t}^{pre}$ is the predicted PV power generation during the t period. $P_{PV,t}^{rate}$ is the rated power of the PV unit during the t period.

(3) CHP constraints

$$\begin{cases} P_{CHP,e,t} = \eta_{CHP}^e P_{CHP,g,t} \\ P_{CHP,h,t} = \eta_{CHP}^h P_{CHP,g,t} \\ P_{CHP,g}^{\min} \leq P_{CHP,g,t} \leq P_{CHP,g}^{\max} \\ \Delta P_{CHP,g}^{\min} \leq P_{CHP,g,t+1} - P_{CHP,g,t} \leq \Delta P_{CHP,g}^{\max} \end{cases} \quad (12)$$

where η_{CHP}^e and η_{CHP}^h are the energy conversion efficiencies of CHP electricity and heat power, respectively. $P_{CHP,g}^{\max}$ and $P_{CHP,g}^{\min}$ are the upper and lower limits of the natural gas power input to the CHP system, respectively. $\Delta P_{CHP,g}^{\max}$ and $\Delta P_{CHP,g}^{\min}$ are the upper and lower limits of the natural gas power creep input to the CHP system, respectively.

(4) GB constraints

$$\begin{cases} P_{GB,h,t} = \eta_{GB} P_{GB,g,t} \\ P_{GB,g}^{\min} \leq P_{GB,g,t} \leq P_{GB,g}^{\max} \\ \Delta P_{GB,g}^{\min} \leq P_{GB,g,t+1} - P_{GB,g,t} \leq \Delta P_{GB,g}^{\max} \end{cases} \quad (13)$$

where η_{GB} is the energy conversion efficiency. $P_{GB,g}^{\max}$ and $P_{GB,g}^{\min}$ are the upper and lower limits of the natural gas power input to the GB, respectively. $\Delta P_{GB,g}^{\max}$ and $\Delta P_{GB,g}^{\min}$ are the upper and lower limits of the natural gas power creep input to the GB, respectively.

(5) EL constraints

$$\begin{cases} P_{EL,H_2,t} = \eta_{EL} P_{EL,e,t} \\ P_{EL,e}^{\min} \leq P_{EL,e,t} \leq P_{EL,e}^{\max} \\ \Delta P_{EL,e}^{\min} \leq P_{EL,e,t+1} - P_{EL,e,t} \leq \Delta P_{EL,e}^{\max} \end{cases} \quad (14)$$

where $P_{EL,H_2,t}$ is the hydrogen energy output from EL and η_{EL} is the energy conversion efficiency. $P_{EL,e}^{\max}$ and $P_{EL,e}^{\min}$ are the upper and lower limits of the electric power input to the EL, respectively. $\Delta P_{EL,e}^{\max}$ and $\Delta P_{EL,e}^{\min}$ are the upper and lower limits of the electric power creep of the input to the EL, respectively.

(6) MR constraints

$$\begin{cases} P_{MR,g,t} = \eta_{MR} P_{MR,H_2,t} \\ P_{MR,H_2}^{\min} \leq P_{MR,H_2,t} \leq P_{MR,H_2}^{\max} \\ \Delta P_{MR,H_2}^{\min} \leq P_{MR,H_2,t+1} - P_{MR,H_2,t} \leq \Delta P_{MR,H_2}^{\max} \end{cases} \quad (15)$$

where η_{MR} is the energy conversion efficiency of the MR. P_{MR,H_2}^{\min} and P_{MR,H_2}^{\max} are the upper and lower limits of the hydrogen energy input to the MR, respectively. $\Delta P_{MR,H_2}^{\min}$ and $\Delta P_{MR,H_2}^{\max}$ are the upper and lower limits of the hydrogen energy-climbing input to the MR, respectively.

(7) HFC constraints

$$\begin{cases} P_{HFC,e,t} = \eta_{HFC}^e P_{HFC,H_2,t} \\ P_{HFC,h,t} = \eta_{HFC}^h P_{HFC,H_2,t} \\ P_{HFC,H_2}^{\min} \leq P_{HFC,H_2,t} \leq P_{HFC,H_2}^{\max} \\ \Delta P_{HFC,H_2}^{\min} \leq P_{HFC,H_2,t+1} - P_{HFC,H_2,t} \leq \Delta P_{HFC,H_2}^{\max} \end{cases} \quad (16)$$

where $P_{HFC,e,t}$ and $P_{HFC,h,t}$ are the electricity and heat power outputs of the HFC, respectively. η_{HFC}^e and η_{HFC}^h are the energy conversion efficiencies of the electricity and heat power of the HFC, respectively. P_{HFC,H_2}^{\max} and P_{HFC,H_2}^{\min} are the upper and lower limits of the hydrogen energy input to the HFC, respectively. $\Delta P_{HFC,H_2}^{\max}$ and $\Delta P_{HFC,H_2}^{\min}$ are the upper and lower limits of the hydrogen energy creep of the input to the HFC, respectively.

(8) EC constraints

$$\begin{cases} P_{EC,c,t} = \eta_{EC} P_{EC,e,t} \\ P_{EC,e}^{\min} \leq P_{EC,e,t} \leq P_{EC,e}^{\max} \\ \Delta P_{EC,e}^{\min} \leq P_{EC,e,t+1} - P_{EC,e,t} \leq \Delta P_{EC,e}^{\max} \end{cases} \quad (17)$$

where $P_{EC,c,t}$ is the cooling power output of the EC. η_{EC} is the energy conversion efficiency. $P_{EC,e}^{\max}$ and $P_{EC,e}^{\min}$ are the upper and lower limits of the electrical power of the input EC, respectively. $\Delta P_{EC,e}^{\max}$ and $\Delta P_{EC,e}^{\min}$ are the upper and lower limits of the electrical power creep of the input EC, respectively.

(9) AC constraints

$$\begin{cases} P_{AC,c,t} = \eta_{AC} P_{AC,h,t} \\ P_{AC,h}^{\min} \leq P_{AC,h,t} \leq P_{AC,h}^{\max} \\ \Delta P_{AC,h}^{\min} \leq P_{AC,h,t+1} - P_{AC,h,t} \leq \Delta P_{AC,h}^{\max} \end{cases} \quad (18)$$

where $P_{AC,c,t}$ is the cooling power output of AC. η_{AC} is the energy conversion efficiency. $P_{AC,h}^{\max}$ and $P_{AC,h}^{\min}$ are the upper and lower limits of the heat power of the input AC. $\Delta P_{AC,h}^{\max}$ and $\Delta P_{AC,h}^{\min}$ are the upper and lower limits of the heat-power creep of the input AC, respectively.

(10) Energy storage device constraints

$$\begin{cases} E_{n,t} = E_{n,t-1} + P_{ES,n,t}^{cha} \eta_{ES,n}^{cha} - P_{ES,n,t}^{dis} / \eta_{ES,n}^{dis} \\ 0 \leq P_{ES,n,t}^{cha} \leq B_{ES,n,t}^{cha} P_{ES,n,t}^{cha} \\ 0 \leq P_{ES,n,t}^{dis} \leq B_{ES,n,t}^{dis} P_{ES,n,t}^{dis} \\ B_{ES,n,t}^{cha} + B_{ES,n,t}^{dis} = 1 \\ E_n^{\min} \leq E_{n,t} \leq E_n^{\max} \end{cases} \quad (19)$$

where n is the type of energy, and $n \in \{e, h, g, H_2, c\}$. e, h, g, H_2, c are electricity, heat, gas, hydrogen and cold energy, respectively. $E_{n,t}$ is the capacity of the n th energy-storage device. E_n^{\max} and E_n^{\min} are the upper and lower capacity limits of the n th energy storage device, respectively. $\eta_{ES,n}^{cha}$ and $\eta_{ES,n}^{dis}$ are the charging and discharging efficiencies of the n th energy-storage device, respectively. $B_{ES,n,t}^{cha}$ and $B_{ES,n,t}^{dis}$ are the charging and discharging 0–1 state variable of the n th energy storage device, respectively. $P_{ES,n,t}^{cha}$ and $P_{ES,n,t}^{dis}$ are the maximum power of the n th energy storage device, respectively.

(11) Power balance constraints

$$\begin{cases} P_{buy,e,t} - P_{sell,e,t} + P_{CHP,e,t} + P_{HFC,e,t} + P_{WT,t} + P_{PV,t} + P_{ES,e,t}^{dis} \\ = P_{load,e,t} + P_{EL,e,t} + P_{ES,e,t}^{cha} \\ 0 \leq P_{buy,e,t} \leq k_1^e P_{buy,e}^{\max} \\ 0 \leq P_{sell,e,t} \leq k_2^e P_{sell,e}^{\max} \\ 0 \leq k_1^e + k_2^e \leq 1 \end{cases} \quad (20)$$

where $P_{sell,e}^{\max}$ and $P_{buy,e}^{\max}$ are the upper limits of the electricity selling and purchasing through the upper-level grid during the t period, respectively. The upper limit of electricity purchasing $P_{buy,e}^{\max}$ is set to 3500 kW. k_1^e and k_2^e are both 0-1 variables. When $k_1^e = 1$, it indicates that PIES purchases electricity from the upper-level grid. When $k_2^e = 1$, it indicates that PIES sells electricity to the upper-level grid.

(12) Heat balance constraints

$$P_{CHP,h,t} + P_{HFC,h,t} + P_{GB,h,t} + P_{ES,h,t}^{dis} = P_{load,h,t} + P_{AC,h,t} + P_{ES,h,t}^{cha} \quad (21)$$

(13) Gas balance constraints

$$\begin{cases} P_{buy,g,t} + P_{MR,g,t} + P_{ES,g,t}^{dis} = P_{load,g,t} + P_{CHP,g,t} + P_{GB,g,t} + P_{ES,g,t}^{cha} \\ 0 \leq P_{buy,g,t} \leq P_{buy,g}^{\max} \end{cases} \quad (22)$$

where $P_{buy,g}^{\max}$ is the limit for purchasing gas from the upper-level gas grid. The upper limit of gas purchasing $P_{buy,g}^{\max}$ is set to 3000 kW.

(14) Hydrogen balance constraints

$$P_{EL,H_2,t} + P_{ES,H_2,t}^{dis} = P_{MR,H_2,t} + P_{HFC,H_2,t} + P_{ES,H_2,t}^{cha} \quad (23)$$

(15) Cooling balance constraints

$$P_{AC,c,t} + P_{EC,c,t} + P_{ES,c,t}^{dis} = P_{load,c,t} + P_{ES,c,t}^{cha} \quad (24)$$

3.3 Solution to optimal model

The number of typical scenes generated by the traditional centralized reduction method is artificially adjustable, which can reduce computational complexity. However, it does not consider the

impact of various uncertain variables such as dimensions and value ranges on the typical scene set and probability obtained through centralized reduction. Therefore, an improved centralized reduction method is proposed to handle sampled scene sets. For the developed optimal dispatch model, Latin hypercube sampling is adopted for scene generation, and because its initial scene set is large, an improved centralized reduction approach is developed to process the sampling scene set. In this method, the uncertain variables are sampled using a Latin hypercube. The obtained scene set is then normalized. The system sampling scene set under the improved centralized reduction method is combined. Finally, the heuristic synchronous back-substitution method is used to improve and reduce the typical scene set and its probability, which is expressed as:

$$S^{IC} = \sum_{\substack{w=1,v=1 \\ u=1,j=1}}^m \left(\begin{matrix} \frac{S_i^{PV}}{P_{PV,max} - P_{PV,min}}, \frac{S_j^{Pload}}{P_{load,e,max} - P_{load,e,min}} \\ \frac{S_u^{Pload}}{P_{load,h,max} - P_{load,h,min}} \\ \frac{S_v^{Pload}}{P_{load,g,max} - P_{load,g,min}}, \frac{S_w^{Pload}}{P_{load,c,max} - P_{load,c,min}} \end{matrix} \right) \quad (25)$$

$$S^{IC} \xrightarrow{\text{Improved concentrated reduction}} \sum_{i=1}^k (S_{pare,i}^{IC}, p_i^{IC}) \quad (26)$$

where m is the number of sampled cases. k denotes the number of reduction target cases. S^{IC} represents the set of cases sampled by the improved centralized reduction method. $P_{PV,max}$, $P_{PV,min}$, $P_{load,e,max}$, $P_{load,e,min}$, $P_{load,h,max}$, $P_{load,h,min}$, $P_{load,g,max}$, $P_{load,g,min}$, $P_{load,c,max}$, and $P_{load,c,min}$ are the maximal and minimal values of power concentration of the sampled cases generated by PV and load, respectively. $(S_{pare,i}^{IC}, p_i^{IC})$ is the i th typical case and its probability obtained by the improved centralized reduction method.

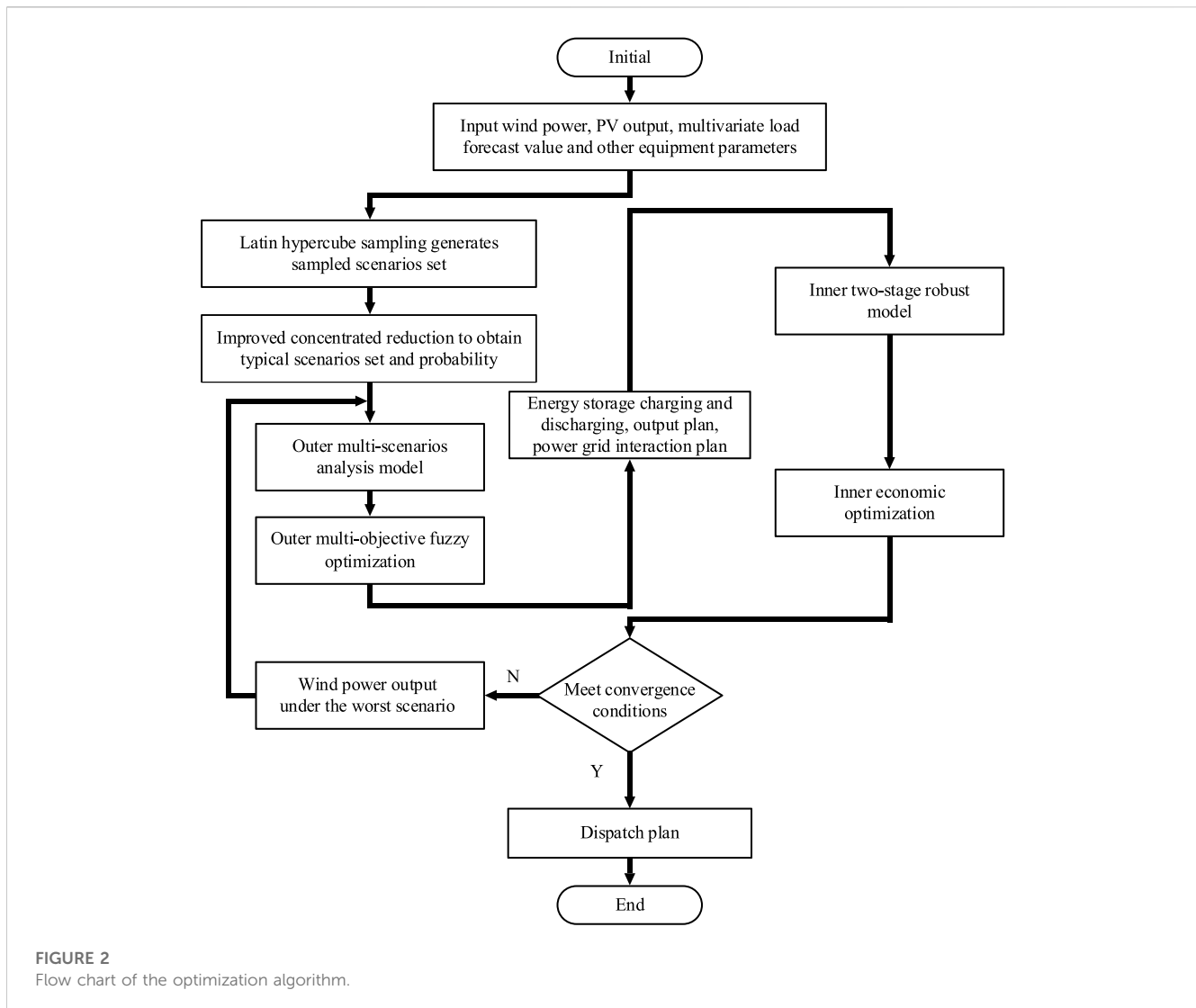
An evaluation index called the comprehensive probability distance (CPD) is proposed to evaluate the performance of the proposed reduction strategy:

$$CPD = \sum_{i=1}^k \left(\sum_{j=1}^k D_{ij} \right) p_i \quad (27)$$

where D_{ij} means Euclidean distance between case i and case j .

It is noteworthy that the min-max-min structure in a robust stochastic low-carbon optimal dispatch model cannot be solved directly. Therefore, the algorithm of column and constraint generation algorithm (CCG) is employed to decompose the main problem and sub-problem and solve them alternately; the large M method and duality theory can be used to transform the sub-problem into a single objective optimization issue, and a more detailed description can be found in (Ma et al., 2022), which is excluded here owing to the length-limit of the paper.

Furthermore, a new multi-objective fuzzy optimization algorithm with an improved membership function is developed, in which a continuously differentiable inverse sigmoid function in the definition domain is adopted. Based on the maximum and minimum satisfaction approaches, the minimum value of the three objective membership functions is set as satisfaction, and a single objective issue that satisfies all constraints and maximum satisfaction was derived (Wang et al., 2019).



The main steps of the proposed optimization model are as follows.

Step 1: The predicted values of the cooling, heat, electricity, gas loads, and PV generation are input and a large number of sample cases is generated using Latin hypercube sampling, which conformed to the corresponding probability distribution.

Step 2: A small number of typical representative scenes and their probabilities are obtained using a heuristic synchronous back-substitution method.

Step 3: A two-stage robust min-max-min optimization algorithm is developed to deal with the uncertainty of wind power. Typical cases are substituted into the model to build a robust stochastic low-carbon optimal dispatch model based on system equipment parameters and system structure.

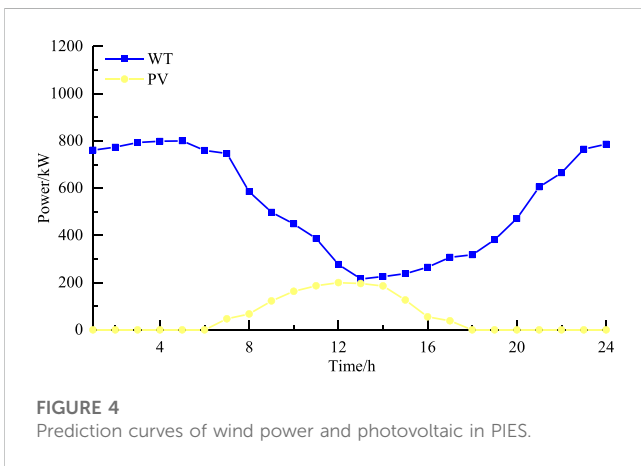
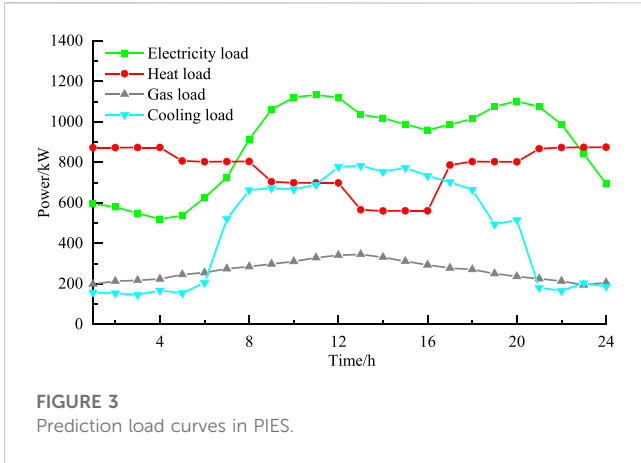
Step 4: The fuzzy multi-objective optimization algorithm with an improved membership function is used to obtain the solution. A commercial solver, Gurobi, is employed based on Matlab 2020a.

The flow of the proposed optimization approach is illustrated in Figure 2.

4 Case study

4.1 Basic data

In this study, the optimal dispatch period is 24 h. The multidimensional load, the predicted output of wind and PV power in the PIES, and the purchase and sale prices of electricity at different times are illustrated in Figures 3–5. The natural gas price is set to 0.35 yuan/(kWh). Table 1 lists the basic parameter settings for each device, and Table 2 lists the parameter settings for each energy storage device. The carbon emission quota for unit power generation is set to 0.798 kg/(kWh). The carbon emission quota for the unit heat supply is set as 0.385 kg/(kWh) (Qin et al., 2022). The interval length of the stepped carbon trading mechanism was set to 2000 kg. Based on the data from (Dong et al., 2022), the price increase rate is set to 25% and the base price of carbon trading is set to 0.252 yuan/kg.



Using the proposed method, a set of 1,000 sampled cases is generated, as shown in Figure 6. The sampled case set contains $1,000 \times 120$ data points, representing the size of the PV generation and the load of cooling, heat, electricity, and gas at every hour. A synchronous back-substitution method is adopted to improve and reduce the 1,000 scene sets. Eight typical scenes and their probabilities are shown in Figure 7.

To further demonstrate the performance of the improved case reduction method, the results are compared with those obtained by separate reduction and traditional centralized reduction with CPD. A comparison of the results is presented in Table 3; Figure 8.

From Table 3; Figure 8, the CPD of each uncertain variable is found to be more significant than that of centralized reduction and improved centralized reduction using the separate reduction method, because the heuristic synchronous backtracking algorithm calculates the probability distance between each scene in the generated scene set and the rest of the scenes. The scene pair with the smallest probability distance is selected and reduced by adding the probability of one scene to the other. This process was repeated until the number of scenes is reduced to one or fewer. As the number of scenes decreases, the CPD of the remaining scene pairs becomes the maximum CPD value for the same number of scene pairs in the original scene set.

For the traditional centralized reduction and improved centralized reduction methods, the CPD of the gas load is smaller when using the improved centralized reduction, while the CPDs of the electrical load and cooling load are larger when using the traditional centralized reduction because the value ranges of the photovoltaic, heat load, and gas load are relatively small, and the value ranges of the electric load and cooling load are relatively large. The traditional centralized reduction method has a greater impact on the probability distance of the scene set in the reduction process owing to the relatively large value ranges of the electric and cooling loads. The reduction process is more correlated with the electric and cooling loads; therefore, the reduction is more inclined to be conducted according to the trend of separate reduction of the electric and cooling loads. Therefore, the difference between the CPD under the traditional centralized reduction mode of the electric load and cooling load, and the CPD under the separate reduction mode is smaller. After adopting the improved centralized reduction mode, the uncertain variables in the scene set are normalized to obtain the normalized scene set, which significantly reduced the influence of the length of the value range of the uncertain variables on the reduction process. Simultaneously, the dimensionality of the uncertain variables can be eliminated. The influences of different variables on the reduction process are more balanced. Therefore, with the increase in the CPD of photovoltaic, heat load, and gas load, the correlation of the reduction process can be improved such that the error of the reduction result is reduced and a single correlation of the reduction result is avoided.

4.2 Analysis of simulation results

In this section, the advantages of a multi-objective low-carbon optimal PIES in terms of economic and environmental protection and reliability are discussed. Without loss of generality, the load demand and wind and PV power outputs are considered as the predicted values. The following four models were constructed with different objectives.

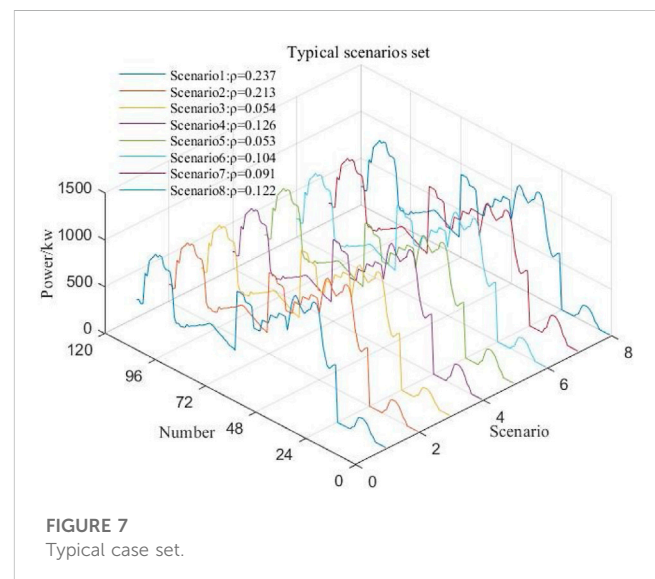
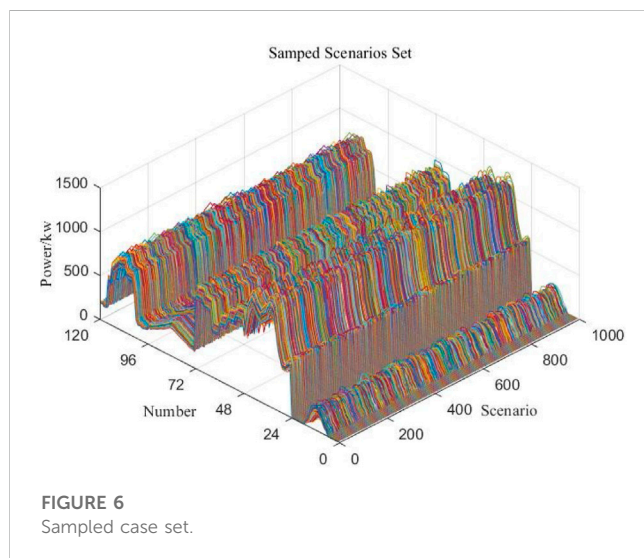
Model 1: PIES economic model to minimize optimal comprehensive operation cost.

TABLE 1 Equipment parameters.

Name	Capacity/kW	Efficiency (%)	Upper limit of climbing speed/(kW·h ⁻¹)	Lower limit of climbing speed/(kW·h ⁻¹)
CHP	1,500	30(electricity)/40(heat)	300	-300
GB	400	95	80	-80
EL	500	87	100	-100
MR	435	60	87	-87
HFC	435	35(electricity)/60(heat)	87	-87

TABLE 2 Energy storage parameters.

Name	Capacity/kW	Lower limit of capacity/kW	Lower limit of capacity/kW	Upper limit of climbing speed/(kW·h ⁻¹)	Lower limit of climbing speed/(kW·h ⁻¹)
Electricity storage tank	450	45	405	90	-90
Heat storage tank	500	50	450	100	-100
Gas storage tank	150	15	135	30	-30
Hydrogen storage tank	200	20	180	40	-40
Cooling storage tank	300	30	270	60	-60



Model 2: PIES low carbon model to minimize carbon emissions.

Model 3: PIES reliability model to minimize the energy undersupply rate.

Model 4: PIES multi-objective low-carbon optimal dispatch model considering economic and environmental protection and reliability indicator.

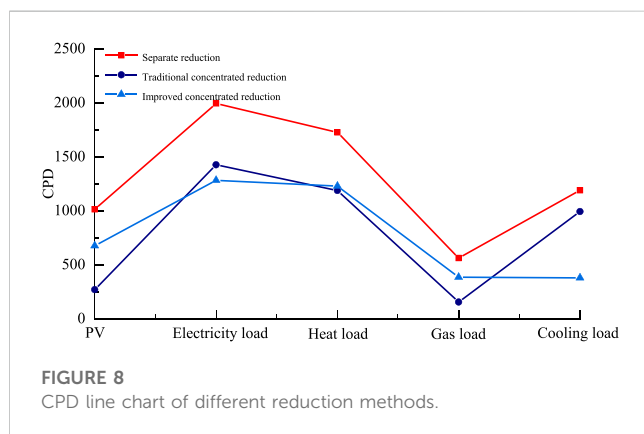
The optimization results are summarized in Table 4. Table 4 demonstrates that the carbon emissions of the PIES are 13.21%

higher than the minimum emissions, and the energy undersupply rate is 12.47% higher. The system cost is 12.71% higher than the optimal economic cost. The energy undersupply rate is 24.48% higher. The energy undersupply rate is the lowest, and the system cost is 31.22% higher. The carbon emission is 49.38% higher. Compared with the single economic objective, the carbon emissions and energy undersupply rate increased by 3.30% and decreased by 3.60%, respectively. Compared with the single carbon emission objective, the system cost and energy undersupply rate decrease by 2.07% and 12.89%, respectively.

TABLE 3 Evaluation results of different reduction methods.

Programs	CPD			Length of interval
	Separate reduction	Traditional centralized reduction	Improved centralized reduction	
PV	1,013.29	269.46	675.56	336.0515
Electricity load	1993.17	1,425.13	1,281.10	904.64
Heat load	1725.39	1,186.97	1,227.66	544.56
Gas load	561.84	154.02	384.22	241.67
Cooling load	1,189.53	992.39	378.06	815.68

The bold values represent the optimization scheduling results of the model proposed in this paper.



Compared with the single minimum energy undersupply rate objective, the system cost reduces by 15.88%, and carbon emissions reduce by 21.71%, which is more suitable for meeting the engineering requirements.

Figure 9 shows the optimal results for Model 1. Wind power resources are abundant whereas the electric load is relatively low at 1:00–7:00 and 23:00–24:00. To absorb abundant wind power and promote economic operations, surplus wind power is sold through a higher-level power grid. Some part of it is input into the EL equipment for hydrogen production. Hydrogen is the first input into HFC because of its high energy-conversion efficiency. The remaining hydrogen is converted into natural gas via the MR or stored in a hydrogen storage tank. When energy prices are high, wind power generation is low at 8:00–22:00. The system mainly satisfies its electricity and heat-load demand through the CHP output, thereby reducing the system operation cost.

Figure 10 shows the optimal results for Model 2. The system relies on CHP to meet its load requirements of the electricity and heat throughout the day, compared to when the system operates in the economically optimal mode. When the economic objective is pursued, a portion of the abundant wind power is consumed by inputting the EL equipment for hydrogen production. Hydrogen can be used by HFC to output a large amount of electricity and heat, thereby improving the operating economy of the system. When carbon emissions are minimized, the system sells all surplus wind power through the higher-level power grid; thus, carbon emissions can be reduced. This is because the factor of carbon emission for purchased electricity is higher, resulting in all surplus wind power being sold in Model 2.

Figure 11 shows the optimal results for Model 3. Compared to the system in the economically optimal mode and the carbon emissions minimum mode, the surplus wind power is entirely consumed using the EL device for hydrogen production. A large amount of electricity and heat power are generated using HFC. However, owing to equipment capacity limitations, more than one HFC thermal power generation is required to satisfy the load demand. Therefore, the system relies primarily on an upper-level grid to satisfy its electricity load demand. A small number of CHP units are used to satisfy the heat demand. When the goal is to minimize the energy undersupply rate, the average energy conversion efficiency of the power-consuming units is higher than that of the gas-consuming units. Therefore, when the system needs to meet the same load demand, it must purchase less electricity than gas. To meet the electricity load demand, it tends to purchase electricity from the upper-level grid and meet the heat-load demand of the system using HFC. This reduces the output of the CHP units and causes a decrease in the purchase of gas by the system from the upper-level gas grid and a lower dependence on external energy purchases. Consequently, the operational reliability of the system improves.

Figure 12 shows the optimal results for Model 4. Compared with Models 1, 2, and 3, Model 4 comprehensively considers the multi-energy complementarity and collaborative optimization of wind power hydrogen production, CHP, and other equipment; it completely utilizes the existing wind and photovoltaic resources, interacts with external energy prices, such as time-of-use electricity and gas prices, and balances the three indicators of economic and environmental protection and reliability to obtain the optimal dispatch plan.

4.3 Comparison of optimal models

In this subsection, four cases are presented. Additionally, the comparison of the advantages of the robust stochastic optimization model and its verification are explained.

Case 1: Source and load uncertainty are not considered;

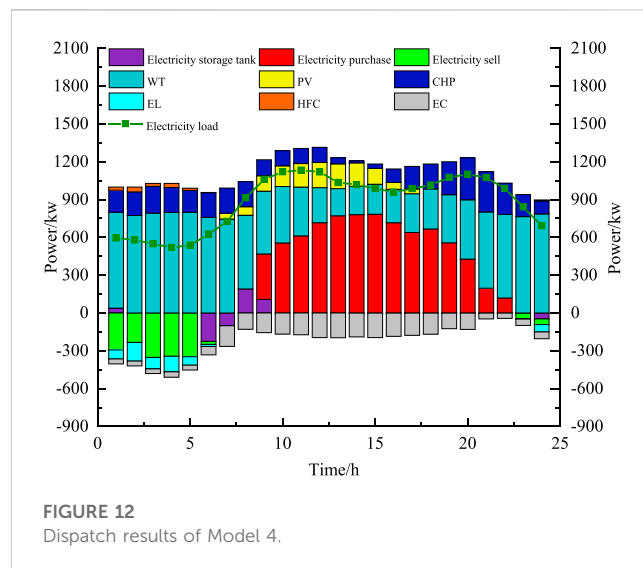
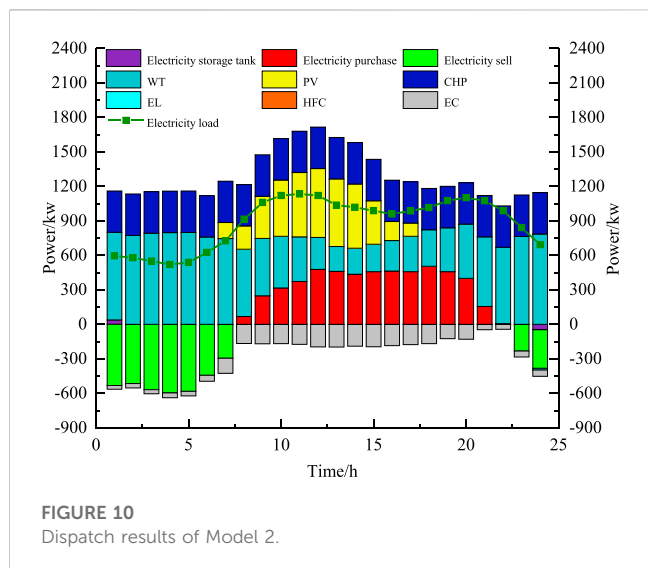
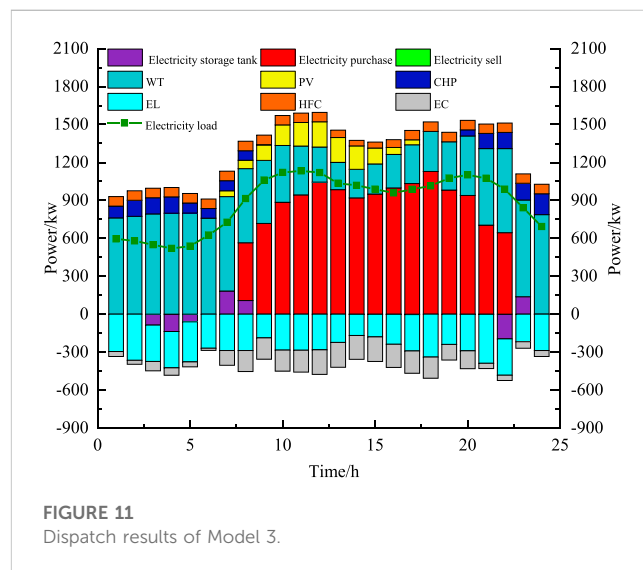
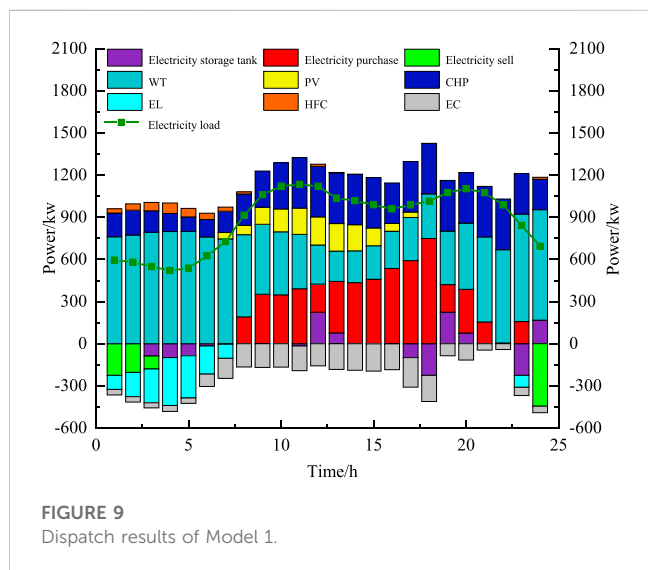
Case 2: A multi-case analysis method is utilized for the uncertainties from the source and load.

Case 3: A two-stage robust optimization algorithm is utilized for source and load uncertainties.

TABLE 4 Multi-objective results of different dispatch models.

Single objective	Single-objective optimization results			Multi-objective fuzzy optimization results
	Comprehensive operation cost/CNY	Carbon emissions/kg	Energy undersupply rate/%	
Comprehensive operation cost/CNY	20475.1	23077.1	26866.3	22599.5
Carbon emissions/kg	16784.0	14825.5	22146.5	17338.2
Energy undersupply rate%	38.05	42.11	33.83	36.68

The bold values represent the optimization scheduling results of the model proposed in this paper.



Case 4: A two-stage robust optimization algorithm is employed for the uncertain wind power output, and a multi-case analysis method is used for the uncertainty of the photovoltaic output and load.

The comparison results of the different cases are listed in Table 5. In Case 1, uncertainty is considered; therefore, the

results of the comprehensive operation cost and carbon emissions are the best, while the energy undersupply rate is not reliable. The worst case for each uncertain variable is considered in Case 3 to maximize the multi-objective result. The proposed robust stochastic optimization method represents the actual operation

TABLE 5 Multi-objective results of different cases.

Cases	Multi-objective fuzzy optimization results		
	Comprehensive operation cost/CNY	Carbon emissions/kg	Energy undersupply rate/%
1	22599.5	17338.2	36.68
2	23311.6	18369.2	37.84
3	23904.0	18753.3	38.28
4	22839.7	17842.3	37.22

The bold values represent the optimization scheduling results of the model proposed in this paper.

situation. Multi-objective results are obtained between those of Cases 1 and 3. Thus, the method improves the shortcomings of the over-conservative two-stage robustness and has more reference values.

5 Conclusion

In this study, a robust stochastic low-carbon optimal dispatch strategy for PIES was constructed with economy and environmental protection and reliability factor, in which the uncertain source load factors were entirely considered and a stepped carbon-trading mechanism was introduced with multiple objectives. The optimal dispatch scheme was solved under the worst wind power cases by using a two-stage robust min-max-min optimization algorithm, with a focus on the uncertain wind power. A multi-scene analysis based on improved centralized reduction was proposed, which reasonably considered the impact of uncertain variables on the reduction process for photovoltaic and load uncertainty, compared to separate reduction and traditional concentrated reduction. Finally, a multi-objective fuzzy optimization algorithm with an improved membership function was adopted to solve the multi-objective optimal dispatch model, which can reduce the subjectivity of multi-objective weights to some extent. The simulation results demonstrated the usefulness and effectiveness of the proposed method, which could provide a reference for future applications of the PIES.

However, it should be pointed out that the proposed method in this paper still has certain subjectivity and conservatism. Therefore, in the future, some interesting research topics, such as further reducing conservatism by using distributed robust methods, further weakening the subjectivity of selecting the multi-objective weight and establish a more refined model, etc., which are some ongoing research directions.

Data availability statement

The original contributions presented in the study are included in the article/Supplementary material, further inquiries can be directed to the corresponding author.

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Author contributions

XZ: Building models and simulation analysis. SZ and HZ: Literature collection and drafting. XD: Reviewing and editing. All authors contributed to the article and approved the submitted version.

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Conflict of interest

XZ, SZ, and HZ was employed by State Grid Jiangsu Electric Power Co., Ltd.

The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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