



Optimal Placement and Sizing of Distributed Generators Based on Multiobjective Particle Swarm Optimization

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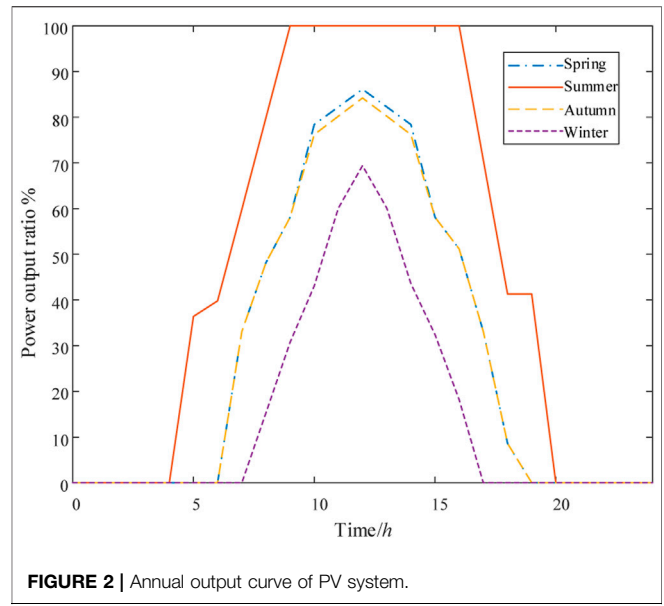
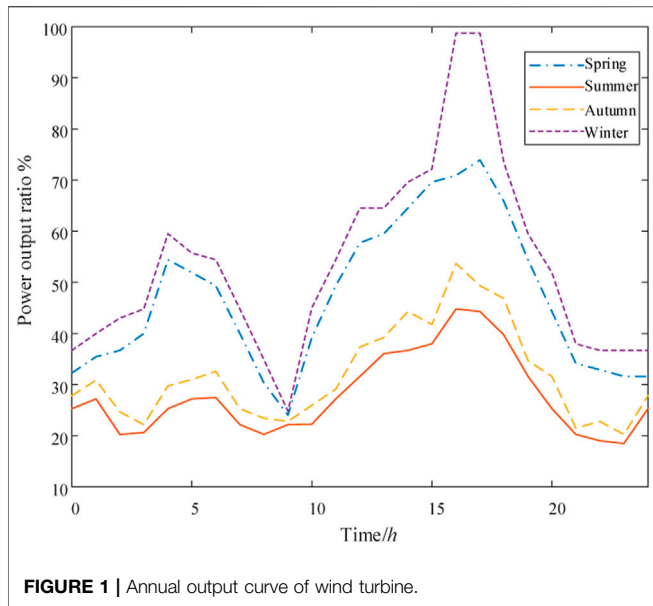
To solve the problems of environmental pollution and energy consumption, the development of renewable energy sources becomes the top priority of current energy transformation. Therefore, distributed power generation has received extensive attention from engineers and researchers. However, the output of distributed generation (DG) is generally random and intermittent, which will cause various degrees of impact on the safe and stable operation of power system when connected to different locations, different capacities, and different types of power grids. Thus, the impact of sizing, type, and location needs to be carefully considered when choosing the optimal DG connection scheme to ensure the overall operation safety, stability, reliability, and efficiency of power grid. This work proposes a distinctive objective function that comprehensively considers power loss, voltage profile, pollution emissions, and DG costs, which is then solved by the multiobjective particle swarm optimization (MOPSO). Finally, the effectiveness and feasibility of the proposed algorithm are verified based on the IEEE 33-bus and 69-bus distribution network.

Keywords: distribution network, distributed generation, optimal sizing and placement, multiobjective particle swarm optimization, metaheuristic optimization

INTRODUCTION

With the rapid development of the world's electric power industry, the total amount of social electricity consumption has risen sharply over the last decade (Yang et al., 2016; Yang et al., 2017; Zhang et al., 2021). Under the traditional grid framework, the power sector mainly builds large centralized power sources such as nuclear power stations, large hydropower stations, and coal-fired power stations and then expands into a large-scale power system (Yang et al., 2019a; Yang et al., 2019b; Yan, 2020). However, its disadvantages are also increasingly prominent (Li et al., 2020; Xi et al., 2020), in particular, highly centralized power supply is gradually difficult to meet the flexibility requirements of power grid operation, and the failure of important power supply nodes seriously affects the overall reliability of power grid's power supply. Moreover, long-distance transmission is also under serious power loss and security problems (Mehleri et al., 2012; Wang et al., 2014; Yang et al., 2018).

To overcome the negative impact of the aforementioned problems, the concept of distributed generation (DG) was put forward in the 1980s (GopiyaNaik et al., 2013; Yang et al., 2015). DG has an

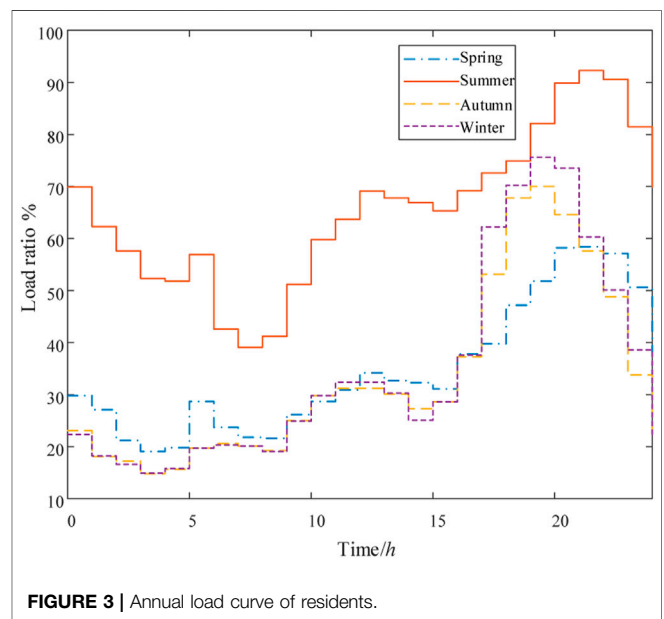


extremely important influence on the planning and operation of the distribution network (Sara et al., 2020; Yang et al., 2020; Ali and Mohammad, 2021). Also, proper access of DG in distribution network can effectively enhance the power quality, reduce the active power loss, improve the voltage distribution, and boost the overall economy and flexibility of the power network operation (Abdurrahman et al., 2020; Bikash et al., 2020; Suresh and Edward, 2020). As the end of power network, the stability and efficiency of distribution network directly affect its overall efficiency (Surajit and Parimal, 2018; Bikash et al., 2019). Therefore, the location and sizing of distributed power generation have become an important research content of power grid planning.

The problem of location and sizing of DG is to optimize its installation point and sizing to maximize the benefits under the constraints of satisfying the given investment and system operation (Kumar et al., 2019; Nagaballi and Kale, 2020). With the increasing requirements for power system reliable operation, the problem of DG location and constant sizing has developed from a single-objective problem that only considers the minimum network loss to a multiobjective optimization problem that comprehensively considers voltage quality, current quality, and environmental factors. Quadratic programming method, genetic algorithm, and other methods have been applied to solve such multiobjective location and constant volume problem. These methods all need to set weights to transform the multiobjective problem into a single-objective problem for proper solutions (Murty and Kumar, 2015); however, these weights are often difficult to determine in actual operation.

Besides, the solution of a large number of planning models is relatively complicated, while the selection of the algorithm directly affects the choice of planning schemes (Aman et al., 2014; Nezhadpashaki et al., 2020; Zeng and Shu, 2020). At present, the solving algorithms mainly include mathematical optimization and metaheuristic algorithm (Doagou-Mojarrad et al., 2013; Satish et al., 2013; Sultana et al., 2016). However,

mathematical optimization algorithm owns relatively low computational efficiency and is only suitable for small-scale distribution networks. Thus, metaheuristic algorithm has received much attention and application in recent years (Aman et al., 2012; Pabu and Singh, 2016; Iqbal et al., 2018). Literature (Chandrasekhar and Sydulu, 2012) adopts genetic algorithm (GA) to optimize the new load nodes for expansion plan of distribution network, and then simulated annealing algorithm is utilized to optimize the generated single plan, which considerably reduces the load size of DG connected to the distribution network and the influence of power flow of the distribution network. Literature (Aman et al., 2013) proposes an improved particle swarm optimization algorithm based on hybrid



simulated annealing method to optimize the location and sizing of distributed power sources. However, the convergence speed of the aforementioned algorithms is relatively slow, and the result is prone to local optimal solutions.

Therefore, an objective function comprehensively considering power losses, voltage profile, pollution emission, and DG cost is proposed in this work, and MOPSO is utilized to solve it. Finally, the proposed method is validated via an IEEE 33-bus and 69-bus distribution network to verify its effectiveness. Then, the Pareto front result is given.

The remaining of this paper is organized as follows: *Mathematical Optimization Model of DG Planning* develops the objective function. In *Multiobjective Particle Swarm Optimization Algorithm*, multiobjective particle swarm optimization (MOPSO) is described. Comprehensive case studies are undertaken in *Case Studies*. At last, *Conclusion* summarizes the main contributions of the paper.

MATHEMATICAL OPTIMIZATION MODEL OF DG PLANNING

Load and DG Power Output Timing Model Wind Turbine Output Timing Model

The output power of wind turbine mainly depends on wind speed, which can be expressed by the following piecewise function (Velasquez et al., 2016):

$$P(v) = \begin{cases} 0 & (v \leq v_{ci} \ \partial v \geq v_{co}) \\ P_r \frac{v - v_{ci}}{v_R - v_{ci}} & (v_{ci} \leq v \leq v_R) \\ P_r & (v_R \leq v \leq v_{co}) \end{cases}, \quad (1)$$

where $P(v)$ is the power output of the wind turbine; v_{ci} denotes the entry wind speed; v_{co} is the cut-out wind speed; v_R means rated wind speed; P_r represents the rated output power. The wind turbine output curve is modeled according to the mean seasonal wind speed, and the output curve is shown in **Figure 1** (Sara et al., 2020).

Photovoltaic System Output Timing Model

The output power P_{PV} of the photovoltaic (PV) system can be approximated by (Velasquez et al., 2016)

$$P_{PV} = P_{stc} \frac{I_{r,t}}{I_{stc}} [1 + \alpha_T (T_t - T_{stc})], \quad (2)$$

where P_{stc} means the output power of the PV system when the solar radiation intensity $I_{stc} = 1000W/m^2$ and the temperature $T_{stc} = 25^\circ C$; $I_{r,t}$ denotes the radiation intensity during actual operation; α_T represents the power temperature coefficient of the PV system; T_t is the actual operating temperature of the photovoltaic power supply. In addition, the output curve of the PV system obtained by fitting the irradiance of typical days in all seasons is shown in **Figure 2** (Sara et al., 2020).

Load Timing Model

The load size shows certain regularity due to people's living habits. **Figure 3** shows the typical load curve of residents in all seasons (Velasquez et al., 2016).

Objective Function Power Losses

The power losses index takes into account the total active power loss of 96 h in four typical days, which is established as follows (Velasquez et al., 2016):

$$\min f_1(x) = \sum_{t=1}^T \sum_{i=1}^n \sum_{j=1}^n A_{ij} \cdot (P_i P_j + Q_i Q_j) + B_{ij} \cdot (Q_i P_j - P_i Q_j), \quad (3)$$

$$\begin{cases} A_{ij} = \frac{R_{ij} \cdot \cos(\delta_i - \delta_j)}{V_i V_j} \\ B_{ij} = \frac{R_{ij} \cdot \sin(\delta_i - \delta_j)}{V_i V_j} \end{cases}, \quad (4)$$

where P_i and Q_i are the active power and reactive power injected into node i , respectively; R_{ij} represents the resistance of the transmission line connecting the i th node with the j th node; N means the number of nodes in the distribution network; V_i and δ_i are the voltage and angle of node i , respectively; T is the number of simulation periods; the value is 96.

Voltage Profile

Reasonable access of DG to the distribution network can effectively improve the voltage profile. Therefore, this work adopts the total voltage deviation of 96 h in four typical days to measure the optimization effect, and the voltage profile index is established as follows (Ali and Mohammad, 2021):

$$\min f_2(x) = \sum_{t=1}^T \sum_{i=1}^n (V_{DG,i} - V_{rated})^2, \quad (5)$$

where $V_{DG,i}$ is the voltage of the i th node after DG is configured in the distribution network and V_{rated} is the rated voltage with a value of 1 p.u.

Pollution Emission

In order to reduce the emission of polluting gases, this work adopts the pollution emission considering carbon dioxide, sulfur dioxide, and nitrogen compounds as follows (Ali and Mohammad, 2021):

$$\min f_3(x) = \sum_{t=1}^T \sum_{i=1}^k P_{DG,i} \cdot \eta_{i,k} \cdot (ew_{CO_2} \cdot AE_{pi,CO_2} + ew_{SO_2} \cdot AE_{pi,SO_2} + ew_{NO_x} \cdot AE_{pi,NO_x}), \quad (6)$$

where $P_{DG,i}$ is the rated active power output of the i th DG; $\eta_{i,k}$ means the output efficiency of the i th DG at time t ; k denotes the number of DG in the distribution network; AE_{pi,CO_2} , AE_{pi,SO_2} , and AE_{pi,NO_x} are, respectively, the mass of carbon dioxide, sulfur dioxide, and nitrous oxide released by unit power output of the i th DG. In addition, ew_{CO_2} , ew_{SO_2} , and ew_{NO_x} are the weight coefficients among different gases, and their values are 0.5, 0.25, and 0.25, respectively.

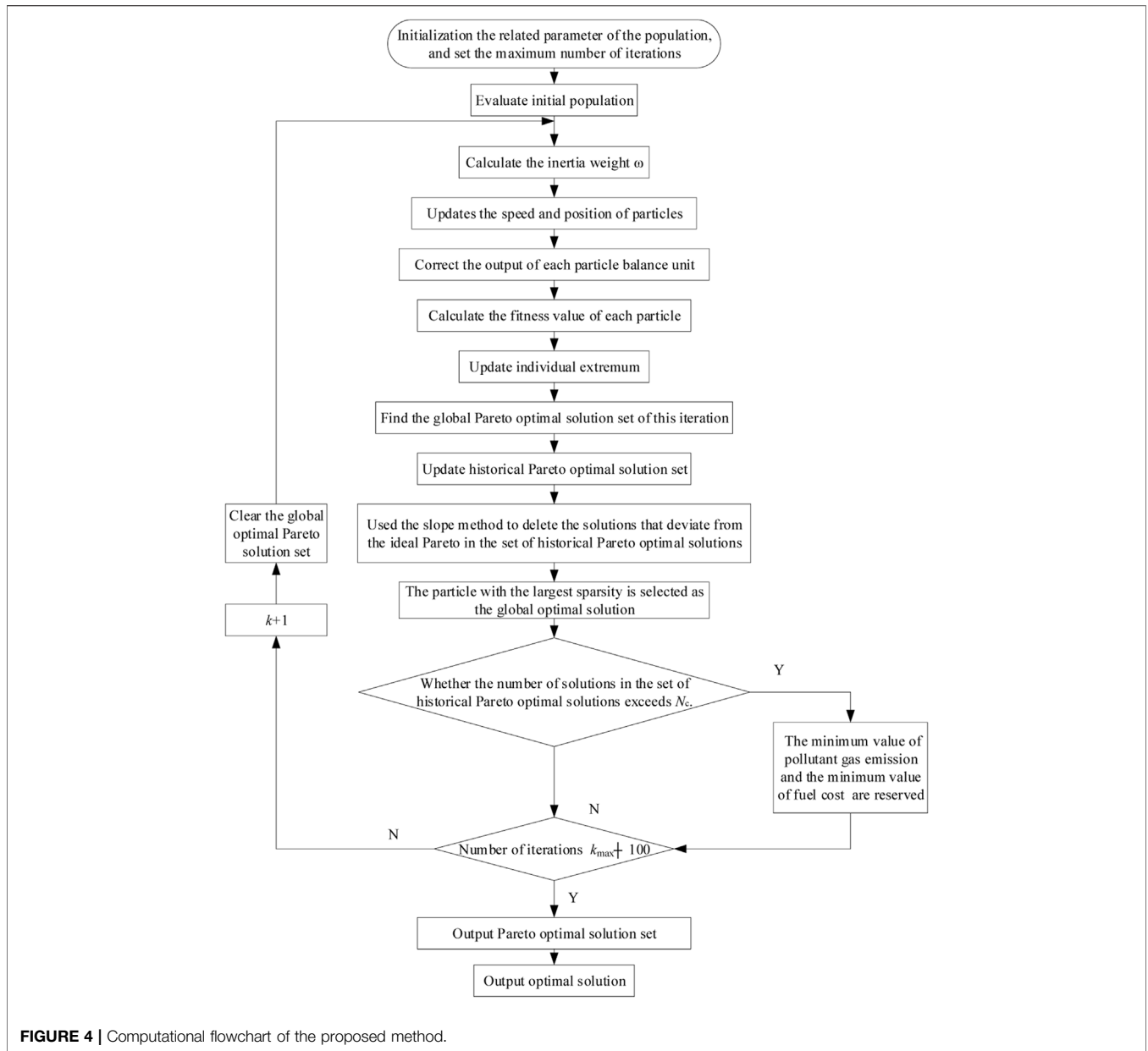


FIGURE 4 | Computational flowchart of the proposed method.

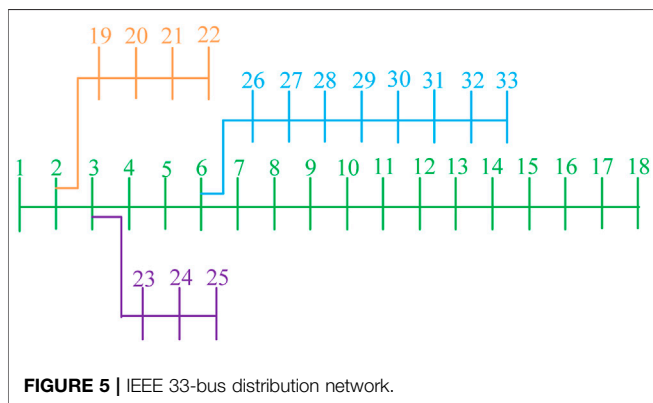


FIGURE 5 | IEEE 33-bus distribution network.

Economic Indicators

The economic cost of DG planning determination includes the investment cost and average operation and maintenance cost of all units, which can be expressed by the following formula (Ali and Mohammad, 2021):

$$\min f_4(x) = \sum_{i=1}^k (1.3C_{\text{capital},i} \cdot P_{\text{DG},i} + C_{\text{maintenance},i} \cdot P_{\text{DG},i} \cdot t_{\text{operation}}), \tag{7}$$

where $C_{\text{capital},i}$ and $C_{\text{maintenance},i}$ are the investment and average operation and maintenance cost of the i th DG, respectively. It is worth noting that $t_{\text{operation}}$ is the running time of DG. The total

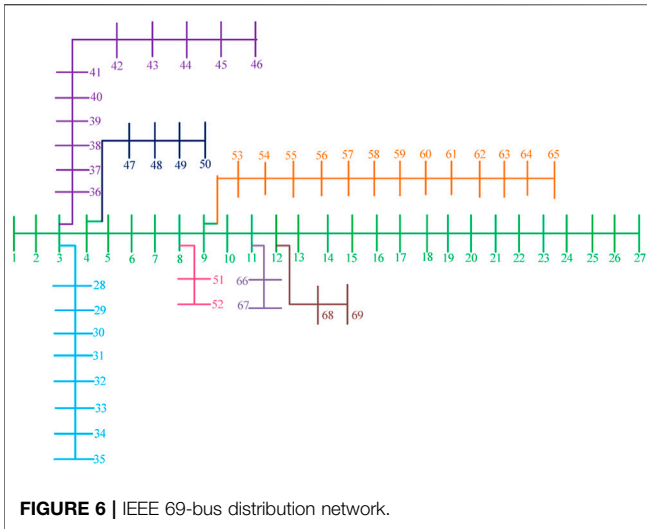


FIGURE 6 | IEEE 69-bus distribution network.

working time of each unit is considered to be 20 years, and the annual working time is 300 days; that is, $t_{operation} = 144,000$ h. In addition, the cost and pollution emission statistics of different types of DG are detailed in the literature (Ali and Mohammad, 2021).

Constraints

In order to ensure the safe and stable operation of the system, the following constraints are designed (Bikash et al., 2020; Ali and Mohammad, 2021):

Power Balance Constraints

$$\sum_{i=1}^n P_i = \sum_{i=1}^n P_{load,i} + P_L - \sum_{i=1}^n P_{DG,i}, \tag{8}$$

$$\sum_{i=1}^n Q_i = \sum_{i=1}^n Q_{load,i} + Q_L - \sum_{i=1}^n Q_{DG,i}, \tag{9}$$

where $P_{load,i}$ and $Q_{load,i}$ denote the active and reactive loads at the i th node, respectively; $P_{DG,i}$ and $Q_{DG,i}$ mean the active power and reactive power output by the i th node DG, respectively; P_L and Q_L are the active power losses and reactive power losses in the distribution network, respectively.

Power Constraints of Transmission Lines

$$S_l \leq |S_l^{max}|, \tag{10}$$

where S_l is the apparent power flowing through l th line and S_l^{max} is the maximum apparent power allowed to flow through l th line.

Voltage Constraint

The voltage of the j th node after DG configuration can be calculated by (Abdurrahman et al., 2020)

$$V_{DG,j}^{min} \leq V_{DG,j} \leq V_{DG,j}^{max}, \tag{11}$$

where $V_{DG,j}^{max}$ and $V_{DG,j}^{min}$ are the voltage upper and lower limits of the j th node after DG configuration and their values are 1.05 and 0.9, respectively (Suresh and Edward, 2020).

Distributed Power Supply Sizing Constraints

$$P_{DG}^{min} \leq P_{DG} \leq P_{DG}^{max}, \tag{12}$$

$$P_{DG}^{min} = 0.1 \sum_{i=1}^n P_{load,i}, \tag{13}$$

$$P_{DG}^{max} = 0.8 \sum_{i=1}^n P_{load,i}, \tag{14}$$

where P_{DG}^{max} and P_{DG}^{min} are the upper and lower limits of the total active power output of P_{DG} .

MOPSO ALGORITHM

Particle Swarm Optimization Algorithm

Particle swarm optimization is a heuristic algorithm that mimics bird foraging, which can conduct intelligent guidance optimization through cooperation and competition among particles (Doagou-Mojarrad et al., 2013).

Suppose a population has m particles, each particle has an N -dimensional variable, and the position and flight speed of the i th particle in the k th iteration are $X_i^k = [x_{i,1}^k, x_{i,2}^k, \dots, x_{i,n}^k]$ and $V_i^k = [v_{i,1}^k, v_{i,2}^k, \dots, v_{i,n}^k]$, respectively. Through evaluating the fitness value of the objective function, the individual optimal position $P_i^k = [p_{i,1}^k, p_{i,2}^k, \dots, p_{i,n}^k]$ and the population optimal position $G_i^k = [g_{i,1}^k, g_{i,2}^k, \dots, g_{i,n}^k]$ of each particle are

TABLE 1 | Optimization results of MOPSO.

Generator	Bus location	DG sizing (kVA)	Losseses function (MW)	Voltage function (p.u.)	Emission function (kg)	DG cost (¥)
The first PV	3	649.201	2108.5	53.2049	1.87×10^7	3.45×10^7
The second PV	32	401.55				
The first wind turbine	31	334.646				
The second wind turbine	22	453.685				
Microturbine	8	16.5259				
Fuel cell	9	382.853				

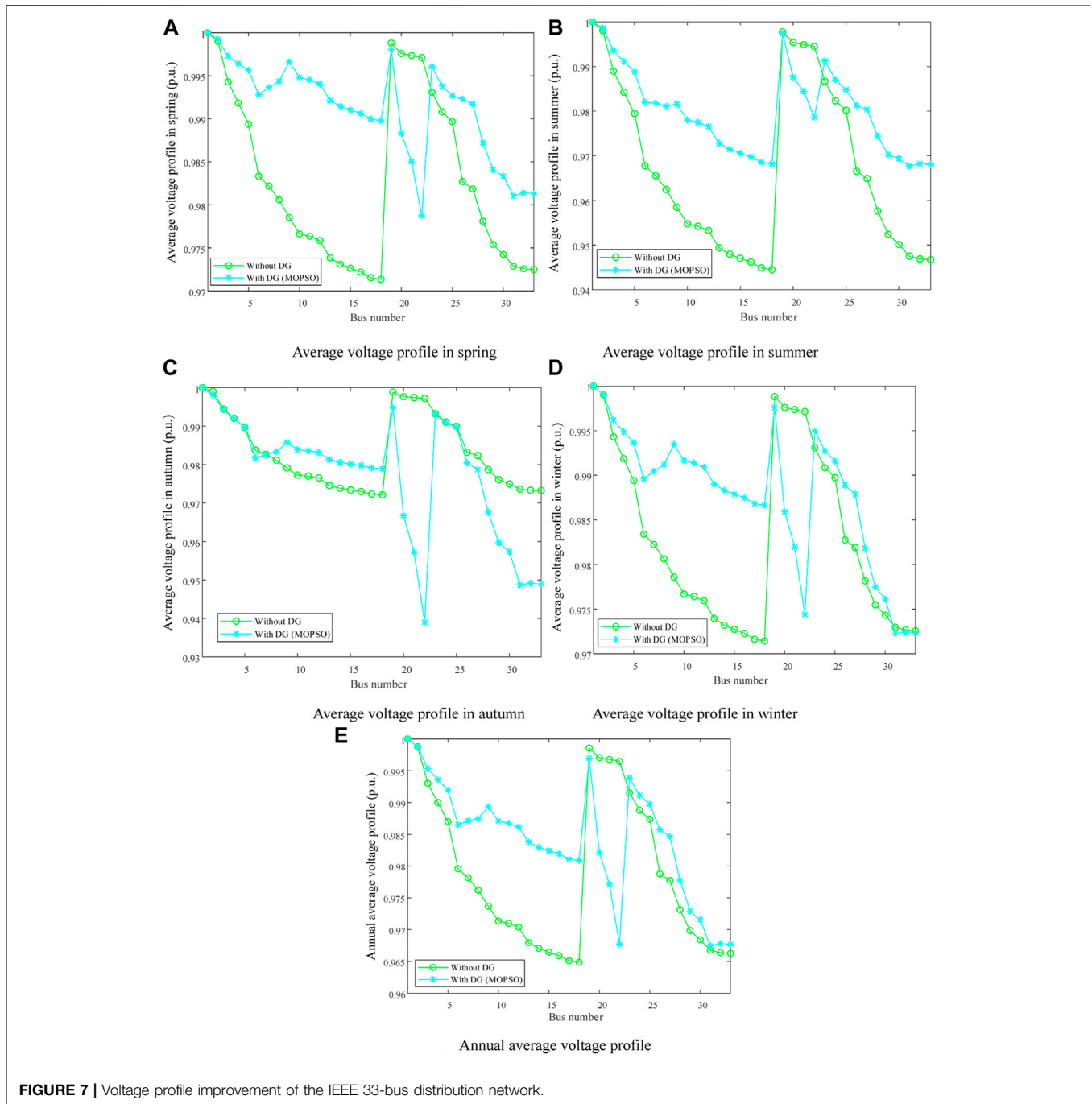


FIGURE 7 | Voltage profile improvement of the IEEE 33-bus distribution network.

determined, and the velocity and position of particle I in the next iteration are determined by (Doagou-Mojarrad et al., 2013)

$$\begin{cases} v_{i,j}^{k+1} = \omega \cdot v_{i,j}^k + c_1 r_1 \cdot (p_{i,j}^k - x_{i,j}^k) + \\ c_2 r_2 \cdot (g_{i,j}^k - x_{i,j}^k) \quad j = 1, 2, \dots, n \\ x_{i,j}^{k+1} = x_{i,j}^k + v_{i,j}^{k+1} \end{cases} \quad (15)$$

where r_1 and r_2 denote random numbers obeying uniform distribution on the interval (0,1); c_1 and c_2 represent learning

factors, both of which are normal numbers. ω is the inertia weight used to balance the global and local optimization capabilities among particles. The value of ω is usually calculated using (Doagou-Mojarrad et al., 2013)

$$\omega = \omega_{\max} - \frac{\omega_{\max} - \omega_{\min}}{K} k, \quad (16)$$

where K is the maximum number of iterations; k is the current iteration times; $\omega_{\max} = 0.9$; $\omega_{\min} = 0.4$.

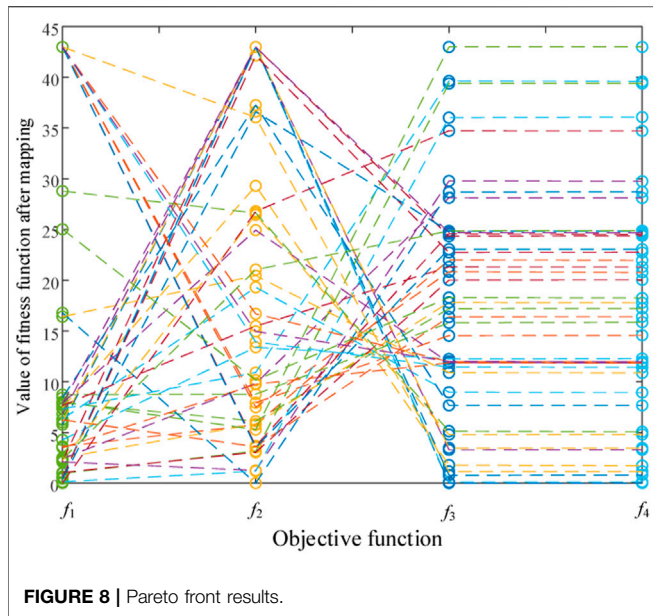


FIGURE 8 | Pareto front results.

MOPSO Algorithm

In order to constantly update a set of Pareto optimal solutions obtained by MOPSO during iterations, this work designs the historical Pareto optimal solution set and the global Pareto optimal solution set during iterations with the help of archiving technology. Global Pareto optimal solution set holds all Pareto optimal solutions generated during the current iteration.

Assuming that a population contains m particles and each particle has N_{obj} objective function value, the global Pareto optimal solution set generated by each iteration is found by the following (Doagou-Mojarrad et al., 2013):

- 1) Let $i = 1$.
- 2) Compare particle x_i with particle x_j for all $j = 1, 2, \dots, m$ and $j \neq i$.
- 3) If j exists so that particle x_j dominates x_i , then particle x_i is marked as the inferior solution.
- 4) If $i > m$, turn to 5). Otherwise, let $i = i + 1$ and turn to (2).
- 5) Remove all marked solutions, and the remaining solutions constitute the global Pareto optimal solution set of this iteration.

Historical Pareto optimal solution set: this solution set is used to hold the Pareto optimal solution throughout the iteration.

Update the historical Pareto optimal solution set in each iteration: the global Pareto optimal solution set generated in this iteration is merged into the historical Pareto optimal solution set, and noninferior solutions are found according to the Pareto dominant condition, while all inferior solutions are deleted.

With the increase of iteration numbers, the number of solutions in the historical Pareto optimal solution set increases rapidly. To improve the running speed of the algorithm, the number of solutions in the historical Pareto optimal solution set is limited to the present value N_C . When the number of solutions in the historical Pareto optimal solution set exceeds N_C , the sparsity ranking method based on crowding distance is adopted to reduce the number of solutions in the solution set to N_C (Nagaballi and Kale, 2020).

In MOPSO, the individual optimal solution and the global optimal solution of the population need to be redefined. In this work, the individual optimal solution and global optimal solution of MOPSO algorithm are defined as follows.

Individual optimal solution: if the particle generated during this iteration dominates the individual optimal solution of the previous iteration, the individual optimal solution of the particle is updated to the particle generated during this iteration. Otherwise, the individual optimal solution of the particle remains.

Global optimal solution: the global optimal solution is selected from the historical Pareto optimal solution set. According to the sparsity of each particle in the solution set, the particle with the largest sparsity was selected as the global optimal solution of the current iteration.

So far, the filtering mechanism of Pareto is described as follows (Doagou-Mojarrad et al., 2013):

$$k_{i,i+1} = \frac{(f_{2,i} - f_{2,i+1}) / (f_{2,max} - f_{2,min})}{(f_{1,i} - f_{1,i+1}) / (f_{1,max} - f_{1,min})}, \tag{17}$$

$$k_{i-1,i+1} = \frac{(f_{2,i-1} - f_{2,i+1}) / (f_{2,max} - f_{2,min})}{(f_{1,i-1} - f_{1,i+1}) / (f_{1,max} - f_{1,min})}, \tag{18}$$

where $k_{i,i+1}$ denotes the normalized slope between the Pareto optimal solution i and its adjacent solution $i + 1$; $k_{i-1,i+1}$ means the normalized slope between the two solutions $i - 1$ and $i + 1$ adjacent to the Pareto optimal solution i . If $k_{i,i+1} > k_{i-1,i+1}$, then the Pareto optimal solution i is close to the ideal Pareto optimal front, and such a solution is retained. If $k_{i,i+1} \leq k_{i-1,i+1}$, it indicates that the Pareto optimal solution i deviates far from the ideal Pareto optimal front, and such a solution is deleted. In addition, the flowchart of MOPSO is given in Figure 4 (Doagou-Mojarrad et al., 2013).

TABLE 2 | Optimization results of MOPSO.

Generator	Bus location	DG sizing (kVA)	Losseses function (MW)	Voltage function (p.u.)	Emission function (kg)	DG cost (¥)
The first PV	14	217.713	2607.21	47.4124	1.59×10^7	4.12×10^7
The second PV	61	11.3952				
The first wind turbine	26	164.807				
The second wind turbine	12	329.529				
Microturbine	5	326				
Fuel cell	20	49.9061				

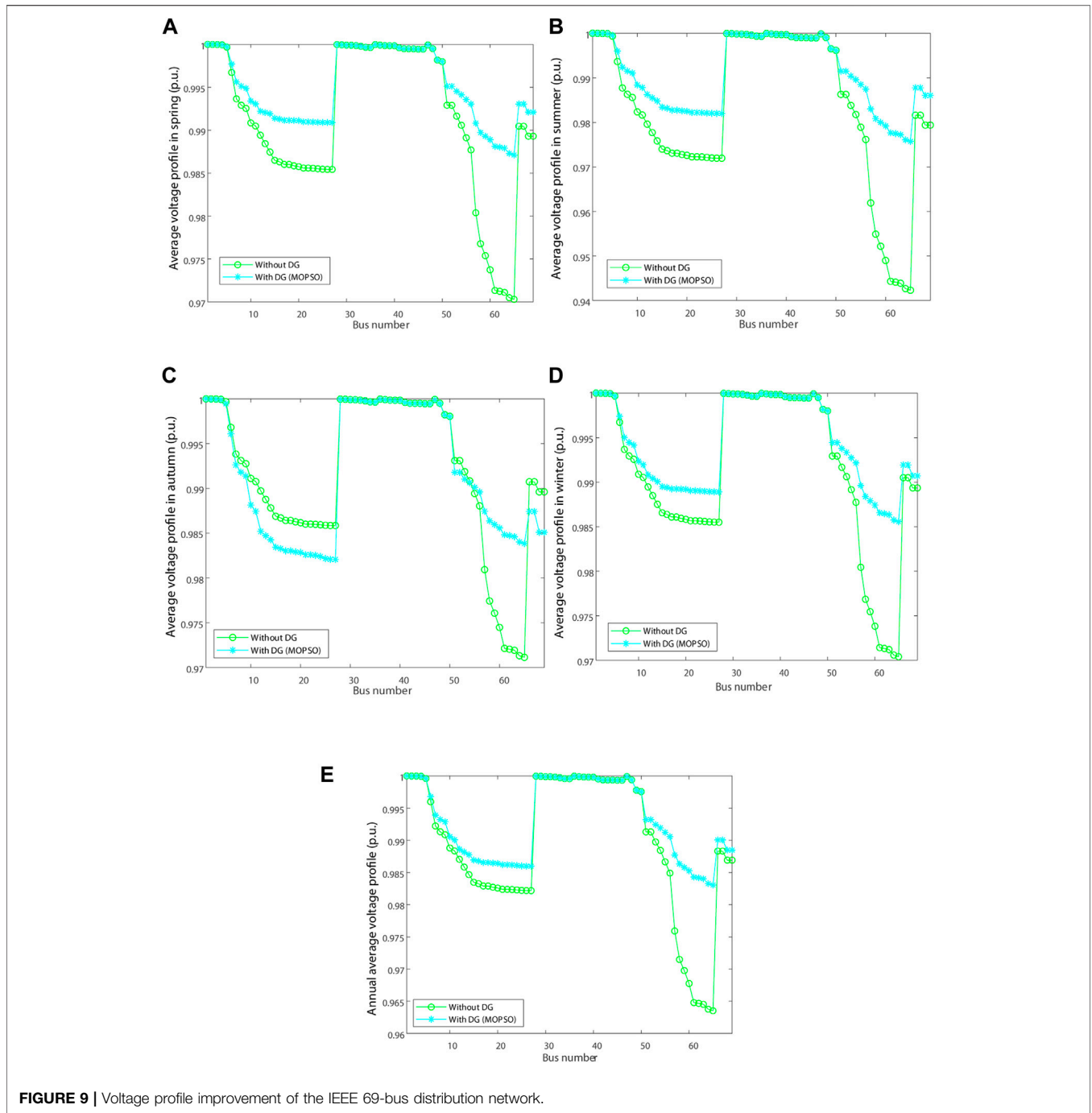


FIGURE 9 | Voltage profile improvement of the IEEE 69-bus distribution network.

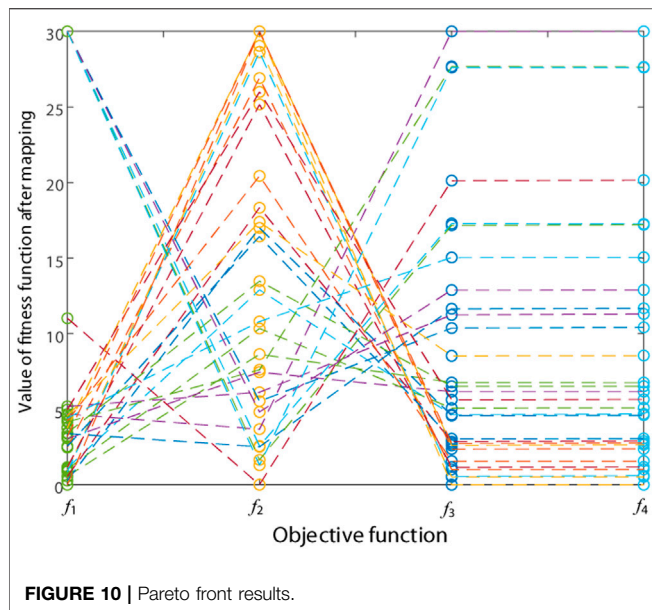
CASE STUDIES

As shown in **Figure 5** and **Figure 6**, DG planning research on an IEEE 33-bus and 69-bus distribution network is carried out to verify the effectiveness of the proposed method, including PV system (two nodes installed), wind turbine (two nodes installed), fuel cell (one node installed), and microturbine (one node installed). It is worth noting that fuel cell and micro-gas turbine can carry out power output stably. When PV system and wind turbine are used together, the defect of fluctuating

output power can be well compensated. In addition, in four typical days, the total active power loss of the network is 4061.87 kW, while the total voltage deviation is 66.1991 p.u. and the proposed method was coded in MATLAB 2017b.

IEEE 33-Bus Distribution Network

The simulation results obtained by MOPSO and the voltage distribution of the optimized IEEE 33-bus distribution network are shown in **Table 1** and **Figure 7**, respectively. It can be seen from **Table 1** that, after MOPSO optimization,



the power losses and voltage profile of the distribution network are significantly improved after different types of DG are configured because DG is always installed near the load. It is worth noting that the voltage distribution of the whole system is improved, although the addition of the fan makes the voltage of some nodes deteriorate. In addition, the Pareto front obtained by MOPSO properly distributes the weight of the objective function under the improved ideal point decision method, which effectively carries out the tradeoff optimization of each objective function and avoids the influence brought by the subjective setting of the weight coefficient. Besides, the multiobjective decision-making method described in literature (Zeng and Shu, 2020) is adopted in this work, while the weight coefficients of each objective function obtained are 0.31, 0.15, 0.28, and 0.26, respectively.

In addition, since four different indexes are optimized in this work, Pareto solution set graph cannot be drawn in the Cartesian coordinate system, so the method of mapping the Pareto solution set from the Cartesian coordinate system to a parallel lattice coordinate system is adopted. The Pareto solution set obtained after MOPSO runs 10 times is given in **Figure 8**. Different optimization objectives are mapped to different columns of the parallel lattice coordinate system. In addition, the ordinate represents the fitness function value after mapping, and the dotted line connects the parallel lattice coordinate components of the same objective vector in different columns. In general, MOPSO can show strong searching ability, as well as obtaining widely distributed and uniform Pareto fronts.

IEEE 69-Bus Distribution Network

The optimization results obtained by each algorithm and the voltage distribution of IEEE 69 node distribution network optimized by each algorithm are shown in **Table 2** and

Figure 9, respectively. It can be seen that, after MOPSO optimization, power loss and voltage distribution of distribution network with different types of DG are significantly improved. Pareto front results are given in **Figure 10**. The weight coefficients of each objective function obtained are 0.28, 0.11, 0.28, and 0.33, respectively.

CONCLUSION

In this work, MOPSO is used to optimize the location and sizing of DG, which contributions are outlined as follows:

1. The objective function with four indexes of distribution network losses reduction index, voltage profile index, environmental emission reduction index, and economic indicators is established to comprehensively optimize the distribution network.
2. Based on an IEEE 33-bus and 69-bus distribution network, it is effectively verified that MOPSO has strong global searching efficiency and high convergence speed. Also, it can effectively avoid falling into local optimum under complex objective function.
3. Four types of DG, PV station, wind turbine, fuel cell, and microturbine are installed, and the connection of microturbine and fuel cell can stabilize the instability of PV station and wind turbine. The experimental results show that the power losses of the distribution network optimized by MOPSO decrease by 51.91%, and the voltage profile is also significantly improved.

In future studies, more advanced solution algorithms and multiobjective decision-making method will be devised to solve this problem.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material; further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

DY: conceptualization and writing—reviewing and editing. JJ: writing—original draft preparation and investigation. WW: writing—reviewing and editing. WC: supervision. DA: supervision. KL: conceptualization and resources. BY: writing—reviewing and editing, software.

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