



Human-Lemur Coexistence in a Multiple-Use Landscape

Chloe Chen-Kraus^{1*}, Njaratiana A. Raharinoro², Miravo A. Randrianirinarisoa², David J. Anderson³, Richard R. Lawler⁴, David P. Watts¹ and Alison F. Richard¹

¹ Department of Anthropology, Yale University, New Haven, CT, United States, ² Mention Zoologie et Biodiversité Animale, Université d'Antananarivo, Antananarivo, Madagascar, ³ Department of Biology, Bowdoin College, Brunswick, ME, United States, ⁴ Department of Sociology and Anthropology, James Madison University, Harrisonburg, VA, United States

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*Correspondence:

Chloe Chen-Kraus
chloe.chenkraus@gmail.com

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Human impacts on the natural world are increasing and are generally considered a threat to wildlife conservation and the persistence of species. However, not all human activities are antithetical to conservation and not all taxa are impacted in the same ways. Understanding how wildlife respond to human activities at the population and individual level will help inform management of landscapes where humans and wildlife can coexist. We examined the effects of anthropogenic activities on a critically endangered primate, Verreaux's sifakas (*Propithecus verreauxi*), at a multiple-use reserve in southwest Madagascar. Specifically, we sought to determine which activities the sifakas perceived as disturbances, using the framework of the risk disturbance hypothesis (RDH). The RDH holds that animals will respond to perceived disturbances as they do to predation threats. We therefore predicted that sifakas would be more vigilant, spend more time in high forest strata, reduce their daily feeding time, and occur at lower densities in response to high levels of perceived disturbance. Using data on sifaka behavior and spatial distribution, and the frequencies of anthropogenic activities, we found that sifakas increased vigilance and their height above the ground in response to certain human-related activities, notably those of domestic dogs. Contrary to our predictions, however, we did not find a negative effect of anthropogenic activities on daily activity budgets or population density. The relationship between the occurrence of sifakas and the intensity of tree cutting was actually positive. Our results indicate that sifakas perceive certain anthropogenic activities as threats and respond with immediate behavioral shifts, but that these activities do not have a discernible negative impact on the reserve's population at this time. These results suggest that lemur conservation can be successful even in areas that are subject to moderate human use.

Keywords: risk disturbance hypothesis, sifaka, *Propithecus verreauxi*, disturbance ecology, behavior, distribution, Madagascar

INTRODUCTION

As human impacts on the natural world increase in scope and intensity, understanding the nuances of how human activities affect wildlife populations, especially those of high conservation concern, becomes increasingly important. Detailed information on how wildlife populations are affected by different types and intensities of human activities will inform landscape management plans that can

better support both human use and wildlife conservation. The risk disturbance hypothesis (RDH) proposes that animals respond to some anthropogenic activities as they do to predation threats (Frid and Dill, 2002): they are analogous to predation risk because, in both situations, animals must navigate the trade-off between fitness-enhancing activities, such as foraging efficiently, and avoiding perceived risks. Animals facing anthropogenic disturbance should follow the strategy used by prey confronted with predators and respond when the disturbance stimulus crosses some threshold, after which response strength should increase in positive association with perceived risk. Testable predictions derived from the RDH help structure studies of disturbance ecology: animals facing higher perceived disturbance rates are predicted to: (1) spend more time being vigilant and less time foraging or engaging in other activities, (2) have poorer body condition, (3) exhibit lower reproductive success, and (4) occur at lower densities than animals facing less disturbance (Frid and Dill, 2002).

Testing whether animals respond in the predicted way to a potential disturbance stimulus sheds light on how they actually perceive stimuli. For example, certain roads have been found to disturb pronghorn antelopes (*Antilocapra americana*), which were more vigilant and fed less when close to them (Gavin and Komers, 2006). Similarly, prairie dogs (*Cynomys ludovicianus*) were disturbed by road traffic noise and responded with decreased above ground activity and foraging time and increased vigilance (Shannon et al., 2014). Iberian frogs (*Rana iberica*) occurred at lower densities close to human recreation areas and took longer to reoccupy places that humans approached multiple times rather than once (Rodríguez-Prieto and Fernández-Juricic, 2005).

The RDH has received little attention in the primatology literature, even though many non-human primate species live in landscapes shared with humans and are at risk of extinction due to anthropogenic pressures (Fuentes, 2012; Estrada et al., 2017). Various studies have examined differences in the occurrence or population density of primates in relation to habitat features assumed to be linked to anthropogenic disturbance intensities. These include comparisons of primate densities among areas of national parks with different logging histories (e.g., Kibale National Park: Mammides et al., 2009; Ranomafana National Park: Herrera et al., 2011) and between protected and unprotected forests (e.g., Rovero et al., 2015; McLester et al., 2019). Several studies have quantified disturbances and assessed the relationship with primate density (e.g., Cavada et al., 2019; Farris et al., 2019), but have not explicitly addressed the RDH.

Many studies have examined relationships between human disturbance and individual- or group-level measures such as diet (e.g., *Cebus capucinus*: McKinney, 2011; *Ateles geoffroyi*: Chaves et al., 2012), activity budgets (e.g., *Ateles geoffroyi*: Chaves et al., 2011; *Chlorocebus djamdjamensis*: Mekonnen et al., 2017), glucocorticoid levels (e.g., *Lophocebus albigena*: Jaimez et al., 2012; *Alouatta pigra*: Rangel-Negrín et al., 2014; *Chlorocebus aethiops*: Fourie et al., 2015), and parasite load (e.g., *Indri indri*: Junge et al., 2011; *Avahi laniger*, *Eulemur rubiventer*, *Hapalemur aureus*, *Microcebus rufus*, *Propithecus*

edwardsi, and *Prolemur simus*: Bublitz et al., 2015). These studies typically involve comparisons of animals in broadly defined “disturbed” vs. “undisturbed” habitats (e.g., fragmented vs. continuous forests, protected vs. unprotected areas, forests close to vs. far from human settlement). Few studies measure frequencies of specific anthropogenic activities like trail usage or livestock grazing to determine which activities are perceived as disturbances. Recent work by Cañadas Santiago et al. (2019) examining the effects of anthropogenic noise on Mexican mantled howler monkeys (*Alouatta palliata mexicana*) is a notable exception. They found that human presence and noise had a measurable impact on vigilance levels, locomotion, and vocal behavior.

Analyses of the effects of anthropogenic activities at multiple scales, spanning individual, group, and population, are rare, yet examining only population-level trends is problematic because more factors are likely in play than at the level of groups or individuals (Tablado and Jenni, 2017). Conversely, individual effects such as changes in behavior need to be interpreted cautiously. Changes in an animal’s behavior do not necessarily correspond to negative impacts on its welfare or conservation of the species to which it belongs (Beale, 2007). Testing predictions of the RDH related to multiple aspects of species ecology and at differing scales – and using data on actual disturbance frequencies, rather than making assumptions about disturbance – will help develop a more holistic understanding of the impacts of human disturbance on species.

We used the RDH to examine how anthropogenic activities affect Verreaux’s sifakas (*Propithecus verreauxi*), critically endangered lemurs found in southwest Madagascar, in a multiple-use protected area. Verreaux’s sifakas (hereafter, “sifakas”; Chen-Kraus et al., 2021) have been studied at Beza Mahafaly Special Reserve (BMSR) for over three decades (Sussman et al., 2012), and the resulting long-term data and zoning of BMSR to allow various types and intensities of human use in different areas made the reserve an ideal place to conduct this research (Chen-Kraus, 2020).

Many reports indicate that the sifakas may indeed respond to humans and domestic animals as they do to natural predators. They growl or give their eponymous “tchi-fak” calls in response to terrestrial predators such as fossa (*Cryptoprocta ferox*) and roar at raptors (Fichtel and Kappeler, 2002), and all three vocalizations have been heard directed at domestic dogs and humans (personal observation). To assess more rigorously which anthropogenic activities sifakas at BMSR perceived as disturbances, we quantified frequencies of anthropogenic activities and tested predictions based on the RDH concerning sifaka vigilance, activity budget, forest strata use, and population density (Table 1). We generated contrasting predictions for areas/groups subjected to low or high disturbance (Table 1). Specifically, we predicted that sifakas would devote more time to vigilance and less to feeding (if they are hiding or fleeing from disturbances) with more frequent disruptive anthropogenic activities, and population density would be lower in those areas. Because sifakas are arboreal primates and human disturbance typically comes from the ground, we also predicted that animals facing frequent disruptive anthropogenic activities would spend

TABLE 1 | Predictions about sifaka behavior and distribution following the risk disturbance hypothesis.

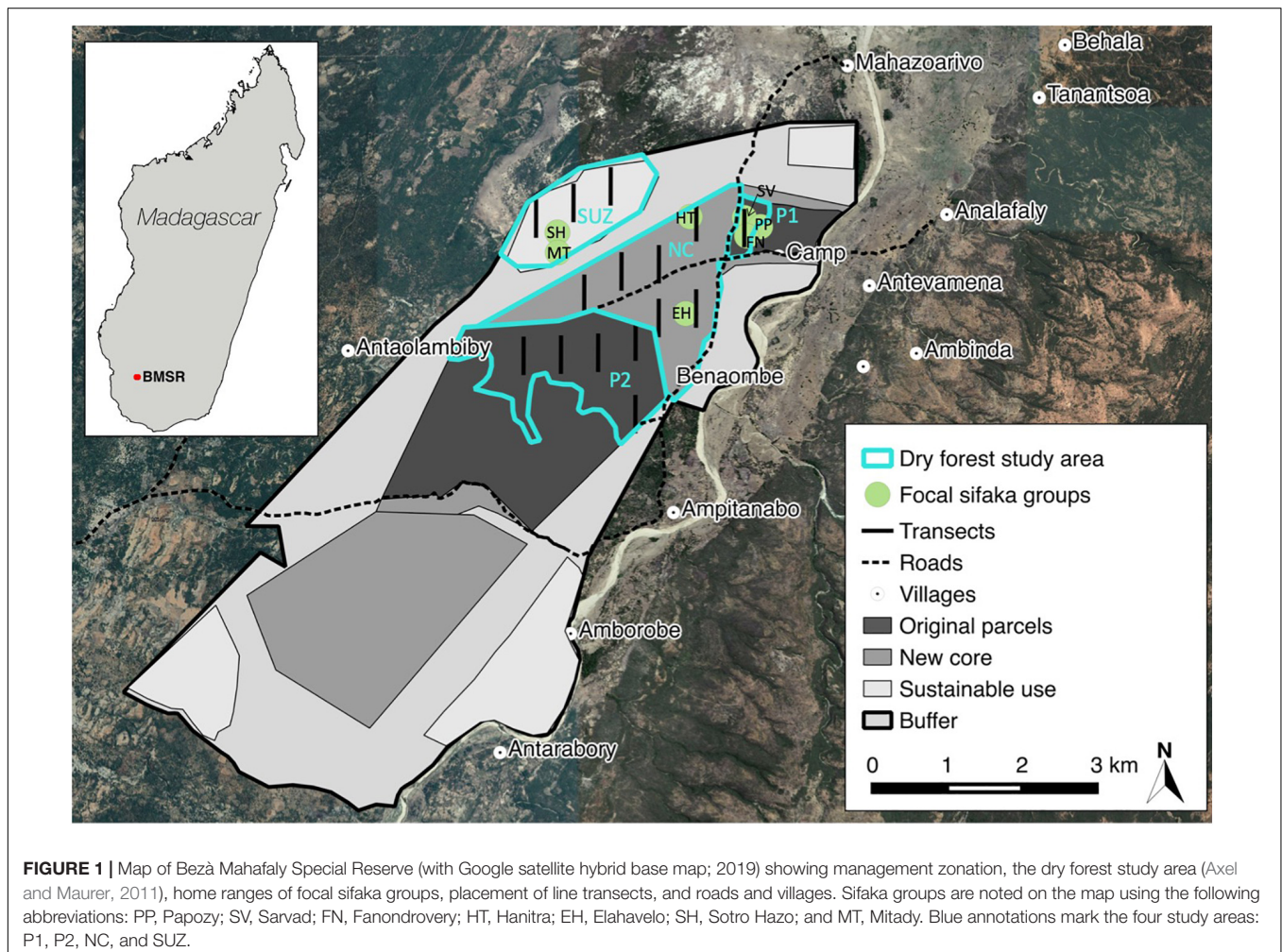
Measures	Low disturbance prediction	High disturbance prediction
Vigilance	Low	High
Activity budget	Feeding: High Moving: Low Resting: Low Socializing: High	Feeding: Low Moving: High Resting: High Socializing: Low
Height	Low	High
Population density	High	Low

more time in higher forest strata. We were committed to collecting only non-invasive data in this study, so were unable to measure body condition. Although non-invasive techniques for assessing body condition exist, such as measuring urinary C-peptide (Girard-Buttoz et al., 2011), we did not use them in this study, in part because of the very small volume of urine produced by these dry forest lemurs. Nor did we investigate the relationship between disturbance and reproductive success, given the long generation time of sifakas.

MATERIALS AND METHODS

Study Site and Subjects

Beza Mahafaly Special Reserve is located in southwest Madagascar, with its center at approximately 44.595°E and 23.681°S. **Figure 1** shows the location of BMSR, zonation of the reserve, and locations of transects and study groups. BMSR has long been informally protected by local custom, with no hunting of lemurs and minimal harvesting of wood. The formal protected area was established in partnership with the surrounding communities 1986, comprising two separate parcels: Parcel 1, consisting of gallery and dry deciduous forest, and Parcel 2, made up of dry deciduous and spiny forest (Axel and Maurer, 2011; Richard and Ratsirarson, 2013). Both areas are designated as strictly protected zones, but Parcel 1 is the primary site of long-term research and receives better protection enforcement than Parcel 2. In 2015, BMSR was expanded to include new core areas where extractive practices were prohibited, sustainable-use zones where moderate extraction of forest resources was permitted, and buffer zones. We focused our research in the continuous dry deciduous forest portion of BMSR, as defined by Axel (2011), where the canopy is lower



than in gallery forest abutting the Sakamena River to the east and dominant tree species include *Acacia bellula* (Fabaceae), *Salvadora angustifolia* (Salvadoraceae), *Euphorbia tirucalli* (Euphorbiaceae), and *Grewia* species (Malvaceae) (Axel, 2011). The dry forest area includes parts of the original Parcels 1 and 2 (P1 and P2), the northern new core (NC), and northwest sustainable use zone (SUZ; **Figure 1**). Limiting our study to a single forest type reduced the effects of variation in forest structure and productivity on sifaka behavior and distribution.

Predators of sifakas at BMSR include Madagascar harrier hawks (*Polyboroides radiatus*), Madagascar buzzards (*Buteo brachypterus*), domestic dogs (*Canis lupus familiaris*), wildcats (*Felis* sp.), Dumeril's ground boa (*Acrantophis dumerili*), and, occasionally, fossa (*Cryptoprocta ferox*) (Brockman et al., 2008; Richard et al., 2016; Sauther et al., 2020); however, previous research has not assessed variation in predation pressure across the reserve. People living in the villages surrounding BMSR use the forest in several key ways. They mostly travel by way of footpaths through the forest, although there are two main dirt roads that bisect the reserve (**Figure 1**). Zebu carts and bicycles are common on the roads, while cars are rare. Pastoralism is one of the main subsistence livelihoods in the region and people value the forest as a place to graze their goats, sheep, and zebu, and keep them safe from cattle rustlers. People also enter the forest to collect dry wood for fuel as well as fruits and medicinal plants (Richard and Ratsiraron, 2013).

Data Collection

Sifaka Behavior

We selected six focal sifaka groups (two in P1, two in NC, and two in SUZ) that were average or above-average size for the population as a whole (initially five to eight individuals; Richard et al., 1993), to maximize the number of study subjects. Groups Sarvad and Papozy, located in P1, were already habituated and included five and six individuals, respectively, at the study's outset in July 2016. Because no groups outside P1 were habituated at that time, we located two new focal groups in SUZ (Sotro Hazo, $n = 5$, and Mitady, $n = 8$) and two in NC (Elahavelo, $n = 5$, and Hanitra, $n = 7$). After 1 week of full-day follows of each group, the sifakas responded to our presence in ways that resembled those of the habituated groups in P1: they ceased head-tossing and alarm calling at us, and generally seemed disinterested in our presence even when we were within 2–3 m. Between the initial habituation period and the start of data collection in June 2017, a BMSR guide spent 1 day each month following each group to note changes in composition and ensure animals remained accustomed to being followed. In June 2017 and June 2018, all data collectors (CCK, NAR, MAR, DJA) spent 1–3 full days with each newly habituated group before beginning data collection. This period also allowed us to practice collecting behavioral data and ensure that we were coding behaviors in the same way.

Eight weeks into data collection in 2017 we dropped group Sarvad from the study because it had lost three of its five members (two transferred to other groups and one died), and added an already habituated neighboring group, Fanondrovery, with seven individuals. For behavioral analyses, we combined the data from the first 8 weeks of data collection on Sarvad with data collected on Fanondrovery following the switch; we

henceforth refer to this “group” as “SV-FN.” The two groups inhabited the same area of P1, had partially overlapping home ranges and were both close to the road, a major source of anthropogenic activity. We assumed that they faced similar anthropogenic activity types and frequencies and had access to similar food types. We could not test these assumptions, however, because we did not collect data on the two groups at the same time.

We recorded continuous behavioral data on all individuals over 1 year of age in each group during 198 days between June and November of 2017 and 2018. We watched each group an average of 261 h (range = 255.0–267.3 h) and recorded data on 51 individuals for a mean of 30.7 h of observation per individual ($SD = 20.8$). In 2017, CCK and NAR collected data with the assistance of a BMSR guide. In 2018, we worked in two teams, with the help of two additional field assistants (MAR and DJA) and an additional guide, recording data on two separate sifaka groups each day. At the start of each field season and weekly thereafter, we recorded data on the same individuals at the same time in order to confirm high inter-observer reliability.

Two observers in a team alternated data collection throughout the day using 20-min continuous focal samples, rotating sampling among group members so that both observers watched each animal at least twice per day. We recorded data on the focal animal's behavioral *state* (feeding, moving, resting, and socializing) and on behavioral *events* like vigilance and alarm calling (**Table 2**), using the Animal Observer application (Caillaud, 2012) on iPads. For feeding and resting, the two behavioral states comprising most of the activity budget, we estimated the animal's height above the ground in 2.5 m intervals (terrestrial, $> 0\text{--}2.5$ m, $> 2.5\text{--}5$ m, $> 5\text{--}7.5$ m, etc.). When the focal animal stopped its activity suddenly, became alert—with eyes wide and body stiff—and fixed its gaze in a particular direction for > 3 s, we recorded this as vigilance. Vigilance events were rare and always brief (almost always less than 10 s), which is why they were recorded as behavioral events, not states. Sometimes vigilance was accompanied by an alarm call (Fichtel and Kappeler, 2011). We did not record aerial-directed vigilance, since our focus was on vigilance events in response to anthropogenic activities on the ground.

Recording the duration of behavioral states is complicated during continuous behavioral sampling because it can be unclear when states like “resting” or “moving” begin and end, especially since animals often pause or move briefly before resuming an activity. We used “inactive” as a place-holder category when the focal animal paused. We later re-coded “inactive” states using the following procedures: (1) We re-coded “inactive” periods lasting less than 10 s between moving states as “moving,” and those less than 10 s between feeding on the same plant as “feeding.” (2) We re-coded all other inactive states as “resting.” (3) Because the animals often moved briefly during long bouts of feeding or resting, we re-coded moving states shorter than 10 s that fell between either feeding on the same plant or between resting bouts as “feeding” or “resting,” respectively. We included behavioral *events* that only lasted several seconds in the behavioral *state* preceding the event for our analysis of activity budget.

TABLE 2 | Definitions of behaviors included in the analyses.

Behavior	Definition
Moving	Animal is changing location, either leaping or climbing over a distance > 1 m.
Feeding	Animal is actively looking for or manipulating food items (leaves, fruits, lianas, and flowers) either with hands or mouth.
Resting	Animal is stationary for longer than 10 s; the animal may either have its eyes open or closed.
Socializing	Animal is interacting with another individual either giving/receiving grooming or playing (wrestling).
Vigilance	Animal suddenly stops activity, is alert (eyes wide and body stiff) and is looking in a specific direction for at least 3 s

Sifaka Spatial Distribution and Density

We stratified the dry forest study area by management zone and created a 500m fishnet grid over each zone, using ArcGIS (version 10.2.2). We then established 15 random points (P1: $n = 1$, NC: $n = 6$, P2: $n = 5$, SUZ: $n = 3$) along the north-south grid lines as start points for line transects, with a minimum distance of 500m between neighboring transects, approximating the upper limit of sifaka home range diameter at BMSR (Ratoniherson, 2015). While this does not entirely eliminate the possibility of detecting the same group on more than one transect during a survey, we minimized this possibility by surveying neighboring transects within several hours of each other.

Two team members conducted surveys along the 15 transects every other month between August 2016 and June 2018. Surveyors walked the transects in the morning (between 06:30 and 12:00 h, a time of high sifaka activity), at a pace of ~ 1.5 km/hr (following Ross and Reeve, 2011). Although the forest at BMSR is relatively low, with less foliage and higher lemur densities than at other sites, sifakas can be very quiet and inconspicuous. To increase the distance from the transect at which we could detect animals, we imitated sifaka “lost calls,” to which they respond with either their own lost call or a “tchi-fak call” (Fichtel and Van Schaik, 2006). The lead surveyor (a BMSR guide with over 25 years of experience censusing sifakas) imitated a lost call every 50 m along the transect and, when the survey team saw or heard a group, they noted their current location on the transect and went to find it. Surveyors marked the GPS location of the approximate center of the group and recorded the number of individuals, the sex and age-class of each, and the cue to detection (call or sight). They spent no more than 10 min collecting these data before returning to the marked location on the transect and continuing to walk (following Müller et al., 2000).

Anthropogenic Activities

We recorded all instances of the four major categories of potential disturbance due to anthropogenic activity that we saw or heard during sifaka focal observations: (1) presence and activities of humans other than the observers, (2) presence and movements of livestock, (3) presence of domestic dogs, which often accompany people and livestock herds, and (4) sound of vehicles (including cars and zebu carts). We recorded these in conjunction with behavioral changes using Animal Observer. Recording auditory signs of human-related activities allowed us to record more events that were likely perceived by, and potentially disruptive to, the sifakas than what we could detect visually (see also Chen-Kraus, 2020). Some had extended durations (e.g., presence of a livestock herd). When this occurred during a 20-min sampling

period, we counted it as a single record even if it lasted for the entire sample duration. Similarly, if we heard the livestock first, and then detected them visually within the same sampling period, we recorded the disturbance only once. If the activity was still ongoing during the next sample period, we counted it as a new record. If two or more such episodes occurred in the same sample period (e.g., the sifakas encountered a livestock herd, moved away, and then encountered another herd), we counted these as separate records. We were unable to capture the same level of detail for human activities along transects. Instead, during each survey between April 2017 and June 2018 we recorded the number of tree stems cut within 5 m of the transect line during the previous 2 months as a proxy for the intensity of human use.

Data Analysis

Sifaka Behavior

We performed all data analyses using R version 3.6.0 (R Core Team, 2019). To examine the impact of anthropogenic activities on vigilance, we coded vigilance as a binary variable for each 20-min focal period ($n = 4700$), which was necessary to reduce issues with data being skewed toward no or few vigilance events per sampling period. We ran a binomial generalized linear mixed effects model (GLMM) using the “nlme” package with the frequency of the four activity types (human, vehicle, livestock, and dog) and sifaka group ID as fixed effects and individual ID as a random effect.

Because we recorded the height of the focal animal in 2.5 m intervals only during feeding and resting states, we coded the heights of all other behaviors as the last recorded height class of the animal during the focal period. We calculated mean height for each 20-min focal using the mid-point values for each height class record (e.g., 3.75 m for the 2.5–5 m height class), accounting for the duration of time the animal was in each height class (Chen-Kraus, 2020). Average height was relatively normally distributed. We ran a maximum likelihood linear mixed effects model (LMM) for average height per focal ($n = 4698$) using the “nlme” package in R with the frequency of the four anthropogenic activity types and group ID as fixed effects and individual ID as a random effect.

Group members commonly appeared to synchronize their behavior, and so we aggregated the time focal individuals spent in each of the four behavioral states during each focal day and calculated the proportion of time the group as a whole spent feeding, moving, resting, and socializing. Here we only analyze the proportion of time spent feeding, because the proportions of time devoted to the four states were statistically inter-dependent. The proportion of time spent feeding was relatively normally distributed. We ran a maximum likelihood LMM for the daily

proportion of time feeding ($n = 198$) with the frequency of the four anthropogenic activity types as fixed effects and group ID as a random effect. We examined residual vs. fitted plots for all three models to make sure the error structure did not strongly deviate from normal.

Sifaka Spatial Distribution and Density

We used the measure tool in QGIS version 2.12.1 to measure the perpendicular distance between the GPS point of each sifaka group and the transect line. We right-truncated these data, using a 5% truncation distance to remove observations of groups farthest from the transect lines (Thomas et al., 2010). The truncation distance, w , is the half-width of the transect area in which we estimated the density of sifaka groups. We modeled detection with the “distance” package in R, using uniform key, half-normal key, and hazard-rate functions with cosine, simple polynomial, and Hermite polynomial adjustments (Thomas et al., 2010; Buckland et al., 2015). Because reliance on auditory cues allowed us to count groups farther from the transect than if we had relied on sight alone, we included cue type (call or sight) as a covariate in the models.

We used Akaike Information Criterion (AIC) values to identify the best ($\Delta\text{AIC} \leq 2$) model and Cramér-von Mises test statistics (Buckland et al., 2015) to test model fit. We used the “distance” package to calculate \hat{P}_a , the probability that a group within distance w of the transect was detected, for each model. For line transects \hat{P}_a is a value between 0 and 1 that is estimated by dividing the area under the curve of the detection function by the half-width of the transect survey area (w).

$$\hat{P}_a = \frac{\int_0^w \hat{g}(x) dx}{w}$$

We then estimated density (\hat{D}) for each model using the following equation:

$$\hat{D} = \frac{n}{2wL\hat{P}_a}$$

where, n is the number of animals detected, w is the truncation distance (the half-width of the transect area), L is the length of the transect, and \hat{P}_a is the probability of detection (Buckland et al., 2015).

We compared the estimated sifaka density for each zone with the total number of cut trees/km recorded in the zone during the study period to examine whether sifaka density co-varied with cutting intensity. Due to the small sample of zones ($n = 4$), we did not conduct statistical tests and simply present the raw counts of cut trees and estimates of sifaka density. Cutting intensities within zones varied considerably (Chen-Kraus, 2020), so we also assessed the relationship between the number of sifaka groups per transect and the frequency of cut trees per transect. Not all transects were surveyed an equal number of times, and we adjusted for effort by dividing the total number of encounters with sifaka groups on each transect by the number of times the transect was surveyed. We similarly calculated the average number of cut trees per transect per survey month. The sifaka group and cut tree data were not normally distributed, so we ran a Spearman rank correlation between the average number of cut trees and the adjusted numbers of sifaka groups.

RESULTS

Sifaka Behavior

Vigilance

The frequency of dog, livestock, and human activities were all significant predictors of vigilance (Table 3). Sifakas were approximately three times more likely to be vigilant when they encountered dogs than when they were not experiencing any disturbance, twice as likely when livestock were present, and 1.6 times more likely when humans other than observers were present. Group identity also had a significant effect. Group Mitady was more likely than all others to exhibit vigilance. The among-individual standard deviation, a measure of the variance of the random effect, was 0.24.

Height Above Ground

The sifakas spent significantly more time high in trees than close to the ground when dogs were present. Other anthropogenic activity types were not significantly associated with variation in use of height strata (Table 4). The group effect was again significant. Group SV-FN spent more time at lower heights

TABLE 3 | Vigilance GLMM parameter estimates, including both raw and exponentiated (odds ratio) estimates.

		Vigilance			
	Predictors	Estimate \pm SE	Odds ratios	CI	p
Anthropogenic activity	(Intercept)	-2.53 ± 0.16	0.05	0.04–0.08	<0.001
	Dogs	1.10 ± 0.28	3.01	1.73–5.22	<0.001
	Humans	0.47 ± 0.13	1.59	1.23–2.06	<0.001
	Livestock	0.66 ± 0.18	1.94	1.36–2.76	<0.001
	Vehicles	0.02 ± 0.29	1.02	0.58–1.81	0.941
Group ID	Elahavelo	-0.20 ± 0.24	0.81	0.51–1.30	0.391
	Hanitra	-0.02 ± 0.24	0.98	0.61–1.57	0.937
	Mitady	0.48 ± 0.21	1.62	1.07–2.45	0.022
	Sotro Hazo	0.40 ± 0.21	1.49	0.98–2.27	0.063
	SV-FN	-0.38 ± 0.23	0.69	0.43–1.09	0.110

Group Papozy is the reference group. P -values < 0.05 are bolded.

than all other groups while groups Elahavelo and Sotro Hazo spent more time at higher strata. The among-individual standard deviation in height was 0.29.

Activity Budget

The only significant fixed effect in the activity budget model was the frequency of vehicles. Contrary to our prediction the animals spent 1.7 times more time feeding during samples when we heard vehicles (Table 5). The among-group standard deviation in proportion time spent feeding was 3.29.

Sifaka Spatial Distribution and Density

We covered 82.5 km during the transect surveys and encountered groups on 65 occasions, with peak detection within 5 m of the transects (Figure 2). We retained 61 group encounters in our sample, detected at a distance less than the truncation distance, w (98 m; Supplementary Table 1). The mean number of individuals detected per group was 4, with a range of 1–10. The number of groups detected along each transect was variable within zones (Supplementary Table 2).

The top detection model used a hazard-rate function with polynomial adjustment and included detection cue (call or sight) as a covariate (Supplementary Table 3 and Figure 3). The top model fit the data well (Cramér-von Mises goodness of fit test; $\omega^2 = 0.075$, $p = 0.720$). No other model received substantial support (Supplementary Table 3).

Based on the top model, sifaka density was highest in P1, followed by NC, and lowest in SUZ (Table 6). These results did

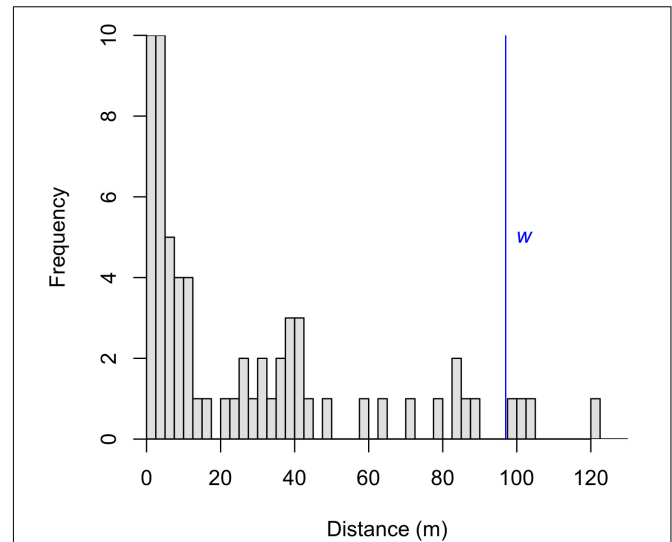


FIGURE 2 | Detection frequency of all sifaka groups encountered during transect surveys based on the distance of each group from the transect line. Truncation distance, w , used to create detection functions is noted in blue.

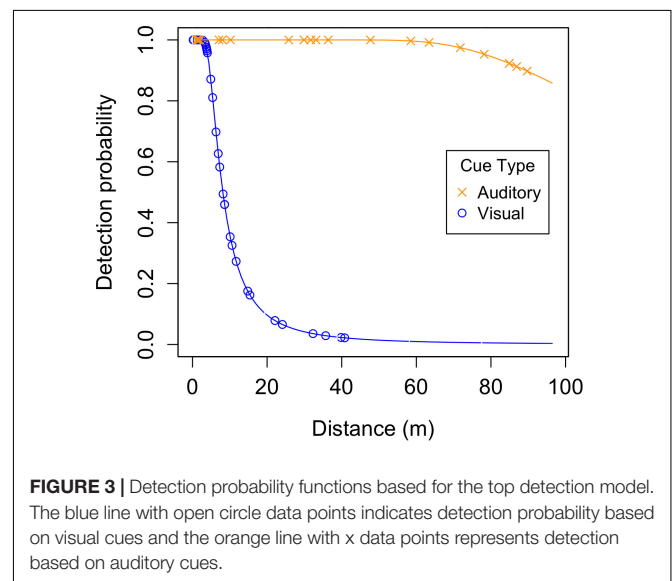


FIGURE 3 | Detection probability functions based for the top detection model. The blue line with open circle data points indicates detection probability based on visual cues and the orange line with x data points represents detection based on auditory cues.

TABLE 4 | Height LMM parameter estimates with 95% confidence intervals.

Predictors	Height		p	
	Estimates	CI		
(Intercept)	6.03	5.71–6.35	<0.001	
Anthropogenic activity	Dogs	0.99	0.24–1.73	0.009
	Humans	0.05	–0.23–0.34	0.729
	Livestock	–0.18	–0.60–0.23	0.382
	Vehicles	0.04	–0.44–0.52	0.869
Group ID	Elahavelo	1.25	0.78–1.73	<0.001
	Hanitra	0.22	–0.25–0.70	0.361
	Mitady	0.22	–0.21 to –0.66	0.311
	Sotro Hazo	0.58	0.14–1.03	0.010
	SV-FN	–0.65	–1.08 to –0.23	<0.001

Group Papozy is the reference group. P -values < 0.05 are bolded.

TABLE 5 | Activity budget LMM parameter estimates.

Predictors	Proportion time feeding		p
	Estimates	CI	
(Intercept)	34.90	31.58–38.22	<0.001
Dogs	0.34	–1.57–2.24	0.731
Humans	–0.43	–0.98–0.12	0.133
Livestock	–0.31	–1.04–0.43	0.415
Vehicles	1.67	0.67–2.66	0.001

Proportion time sifaka groups spent feeding in a given day is the response variable. CI indicates the 95% confidence interval. P -values < 0.05 are bolded.

not align with the inverse relationship predicted between sifaka density and tree cutting by zone. Estimated density was highest in P1 where cutting intensity was lowest, but was also high in NC, which had the highest cutting intensity.

The average number of cut trees recorded per transect survey ranged from 0 to 9.75, while the number of groups per transect adjusted for the number of surveys ranged from 0 to 1.71. The correlation between the adjusted number of sifaka groups detected per survey and the number of cut trees per transect was statistically significant ($R = 0.52$, $p = 0.048$), but the direction of the relationship was positive, the opposite of what we expected (Figure 4). With the highest group density and no cut trees, P1 was an outlier.

TABLE 6 | Parameter estimates of the top ranked detection model (Hazard-rate model with polynomial adjustment and cue as a covariate) for estimating sifaka density compared to cut tree measures for each zone.

Zone	Sifaka density (ind/km ²)			Total cut stems/km
	Estimate ± SE	95% CI	CV	
NC	122 ± 57	43–343	0.5	56.7
P1	194 ± 65	89–423	0.3	0
P2	56 ± 26	19–166	0.5	40.8
SUZ	1 ± 1	0–42	1	2.7

Density values indicate mean density estimate (individuals/km²) ± SE with 95% confidence intervals and the coefficient of variation (CV).

DISCUSSION

The RDH provided a useful framework for this study, although support for predictions derived from the hypothesis was mixed (Table 7). This suggests that sifakas at BMSR perceive some anthropogenic activities as disturbances, but are not threatened by others. They responded to the presence of dogs, livestock, and humans by becoming more vigilant (Table 7). The variation in effect sizes we found imply that sifakas perceived dogs as the highest threat, followed by livestock and then humans. The fact that only dogs affected their height in the trees (Table 7) also indicates that dogs were perceived as the most threatening disturbance. Researchers at Ranomafana National Park in eastern Madagascar identified a significant negative effect of dog presence on lemur occurrence, which they suggest may be due to harassment, predation and/or disease transmission (Farris et al., 2019). Even if sifakas are responding to dogs as true predation threats, we also view dogs as an anthropogenic disturbance since they would not be present in the area were it not for humans,

and they tend to be in the forest because they are accompanying humans and livestock herds.

Although sifakas changed their behavior in response to some anthropogenic activities, we found no support for predictions regarding their overall activity budgets (Table 7). In particular, we did not find the expected decrease in feeding time in response to any anthropogenic activity type. Previous work addressing the impact of disturbance on feeding has produced inconsistent results. Chaves et al. (2011) found that spider monkeys (*Ateles geoffroyi*) spent more time feeding when they were in disturbed areas, but Mekonnen et al. (2017) reported the opposite for Bale monkeys (*Chlorocebus djambamensis*). In both these studies, the authors assumed forest fragments were “disturbed” and continuous forest “undisturbed.” Surprisingly, the frequency of vehicle noise had a significant positive relationship with the amount of time the sifakas spent feeding. This was almost certainly not a causal relationship, and probably resulted from some aspect of unmeasured ecological variation combined with proximity to roads. Groups Papozy, SV-FN, and Elahavelo spent more time feeding than other groups. They also were closest to roads, and heard vehicles more frequently than other groups did as a result. In contrast, feeding time was lowest for group Sotro Hazo, which was farthest from a road. Variation in feeding time likely resulted from variation in food abundance and quality: distance to the Sakamena River, on the eastern edge of BMSR, affects soil moisture and type (Ratsirarson and Sussman, 2006; Rifkin, 2018) and, probably, the quantity and quality of sifaka foods. Further research is needed to quantify fine-scale ecological variation across the sifaka home ranges, over and above human activities, to give a more complete picture of sifaka responses to human activities.

Habituation might have influenced our results if it made it less likely that the sifakas would respond to anthropogenic

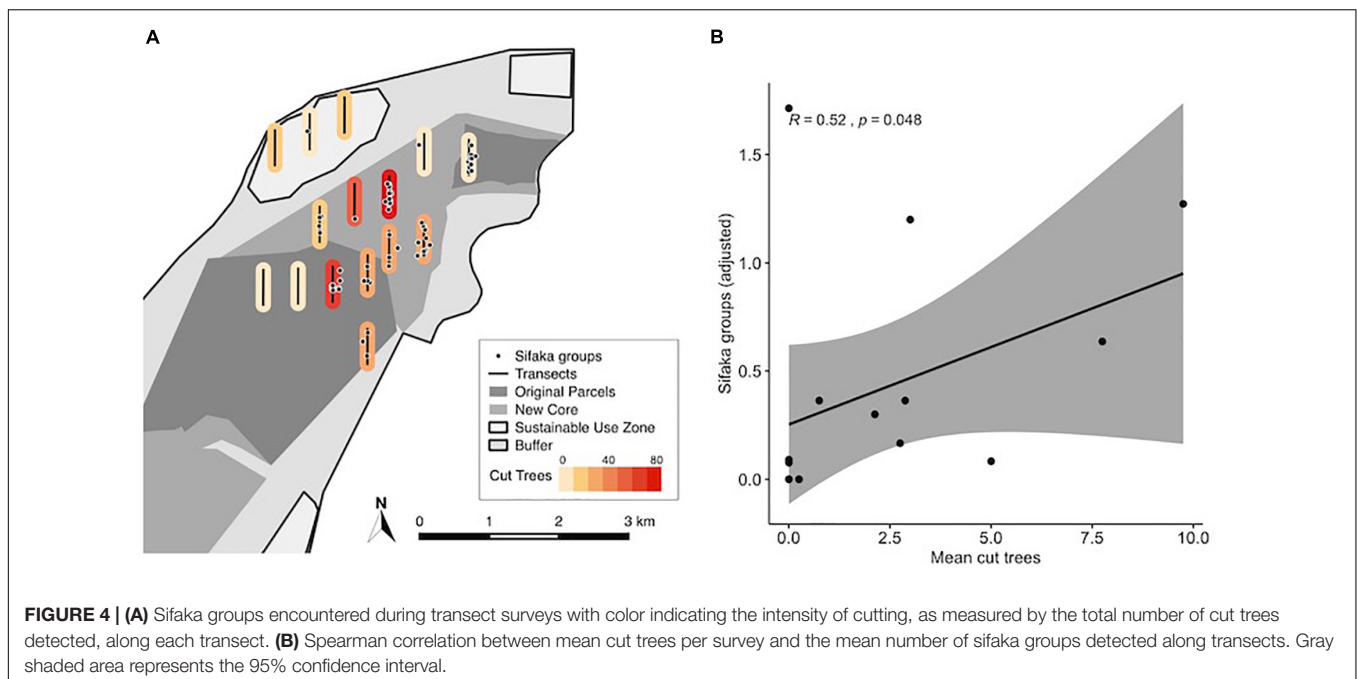


TABLE 7 | Summary of predictions and results.

	PREDICTIONS		RESULTS				SUPPORT FOR PREDICTIONS?
	High disturbance		Human	Livestock	Dog	Vehicle	
Vigilance	↑		↑	↑	↑	n.s.	YES
Height	↑		n.s.	n.s.	↑	n.s.	SOME
Feeding	↓		n.s.	n.s.	n.s.	↑	NO
				Cut trees			
Density	↓			↑			NO

Arrows indicate the direction of significant effects and "n.s." indicates the anthropogenic activity type was not a significant predictor of the outcome variable of interest.

activities in general. Indeed, the goal of habituating animals in the first place is to reduce behavioral responses to researcher (human) presence (Williamson and Feistner, 2003). Because the groups in P1 had been habituated for decades longer than the groups in NC and SUZ, and habituation is an ongoing process, their tolerance thresholds to disturbance might have been higher (Bejder et al., 2009; Blumstein, 2016). Animals located outside the long-term study area and farther from roads might have been more fearful and changed their activities (e.g., fed less) on days we were with them because of less extensive histories of encounters. As a possible example of such an effect, Jack et al. (2008) found that wild white-faced capuchin monkeys (*Cebus capucinus*) in the less habituated of their study groups showed more agitation than those in better habituated groups, even after being followed for 4 weeks, though they did not assess differences in activity budgets. A different study of the same species that employed radiotelemetry, however, found that the presence of researchers did not affect activity budgets (Crofoot et al., 2010). It seems unlikely that differences in habituation had a significant impact on the sifakas' behavior, since animals in all groups regularly fed and rested within 2–3 m of observers. Their responses surely differ from those of unhabituated animals outside the reserve, especially in areas where they are hunted, and unhabituated animals likely perceive a broader range of anthropogenic activities as threats. Group composition, particularly the presence of infants, also might influence responses to disturbance. Almost all groups had infants at the same time however, making a robust test of whether this occurs difficult without additional research.

Finally, groups might respond differently to anthropogenic activities for idiosyncratic reasons unrelated to habituation history. Groups Mitady and Sotro Hazo appeared more skittish than the others and were more likely to be vigilant, even when we could not detect any anthropogenic activity in the area. This difference could be related to the history of disturbance in SUZ prior to our study and the expansion of the reserve. Alternatively, group members might have been perceiving and responding to disturbances that we could not detect. Furthermore, sifakas in areas more extensively modified by humans may perceive a higher predation risk if the modifications result in higher visibility.

Our estimates of sifaka density for P1 are similar to the numbers of individuals counted during monthly censuses (Richard et al., 2016), but density estimates for other zones are low compared to point survey estimates (Axel and Maurer, 2011). We expected to under-estimate densities, due to missing some

groups near the transect lines and under-counting the number of individuals in some detected groups. However, density might really have declined following several years of poor rainfall since the point surveys Axel and Maurer conducted in 2006–2007 (Axel and Maurer, 2011). Regardless of how our estimates compare to previous ones, we are confident that our detection of sifakas during transect surveys was consistent between the different areas and that estimates are comparable among zones.

Contrary to our predictions, density was not inversely related to the frequency of tree cutting (Table 7). The two zones with the highest densities (P1 and NC) had the lowest and highest frequencies of tree cutting, respectively. Unexpectedly, the relationship between the average number of sifaka groups and cut trees by transect was positive. This conflicts with findings for other primate species. For example, Cavada et al. (2019) found lower densities of *Colobus angolensis palliatus*, *Procolobus gordonorum*, and *Cercopithecus mitis monoides* in areas with high human activity compared to less disturbed areas in the Udzungwa Mountains of Tanzania. Comparing lemur densities between two areas with different disturbance histories in Ranomafana National Park, however, Herrera et al. (2011) found no statistical difference in encounter rates with *Propithecus edwardsi* between a "disturbed" (formerly logged) site and an unlogged site.

There are several potential, non-mutually exclusive, explanations for the positive relationship between sifaka density and tree cutting. First, forest areas that are good sifaka habitat may also be relatively rich in important resources for people and livestock. In fact, many of the trees cut along the transects were species that sifakas use as food resources. If human resource extraction rates are low, sifaka food abundance could still be high, implying that people and sifakas can share the habitat sustainably. Second, sifakas may prefer areas where people selectively cut trees because low levels of cutting open light gaps, resulting in increased leaf protein and fruit production (Ganzhorn, 1995). Folivores select leaves with higher protein, especially in areas where the average protein content of the forest is low (Ganzhorn et al., 2017). Moreover, sifakas prefer young leaves over mature ones (Norscia et al., 2006), and may be attracted to small light gaps with abundant new growth. Also, while sifakas are considered folivores, fruit constitutes a substantial portion of their diet (Simmen et al., 2003; Norscia et al., 2006). Alternatively, the time scale of this study might not have allowed us to detect sifaka movements away from areas where we recorded tree cutting because of time lags between disturbances and range shifts. However, restrictions on human

use within the surveyed zones have increased over the last decade and the intensity of disturbance is likely lower now than before the expansion of the reserve. Therefore, it seems reasonable to conclude that sifakas are not deterred by current levels of tree cutting at BMSR. Lastly, it must be noted that tree cutting represents only one type of human use. Future research would benefit from including data on other human-related activities, like signs of recent livestock grazing, in the areas of the line transects.

In summary, anthropogenic activities did not have the expected negative impact on sifaka activity budgets or population density and had only limited, short-term behavioral effects. These findings suggest that BMSR's multiple use management plan may help protect sifakas while also allowing limited human use of the forest. Guided by the predictions of the RDH, our results paint a more detailed picture of how sifakas are impacted by human activities than if we had just measured one aspect of sifaka ecology. Future research is needed to assess long-term fitness consequences of human-associated activities, however. As Gill et al. (2001) bluntly argue, "human disturbance of wildlife is important only if it affects survival or fecundity and hence causes a population to decline." The priority for future research must therefore be determining whether sifaka survival and reproduction vary among areas experiencing different disturbance intensities. Due to the slow life histories of sifakas (Richard et al., 2002) accumulating data to address this question will take time, but will be possible with continued monitoring of the focal groups and transects established in this study.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/**Supplementary Material**, further inquiries can be directed to the corresponding author/s.

ETHICS STATEMENT

Ethical review and approval was not required for the animal study because it did not involve animal handling and was purely observational.

AUTHOR CONTRIBUTIONS

CC-K conceived the study, conducted the field work, analyzed the data, and wrote the manuscript. NR helped to refine

the field methods and conducted field work. MR and DA conducted field work. RL, DW, and AR provided feedback throughout the development, execution, data analysis, and manuscript drafting stages of the study. NR, MR, DA, RL, DW, and AR provided feedback on the final manuscript. All authors contributed to the article and approved the submitted version.

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SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fevo.2022.779861/full#supplementary-material>

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