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EDITED BY

Qingchao Li,
Henan Polytechnic University, China

REVIEWED BY

Ya Yao,
Missouri University of Science and
Technology, United States
Qiang Li,
China University of Petroleum Beijing, China

*CORRESPONDENCE

Anupam Yadav,
✉ anupam.yadav@gla.ac.in
Mohammad Sina,
✉ m.sina00691@gmail.com

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Prediction of saturation exponent for subsurface oil and gas reservoirs using soft computing methods

Anupam Yadav^{1*}, Saeed Hameed Aldulaimi²,
Farag M. A. Altalbawy³, Praveen K. N. Raja⁴, M. Janaki Ramudu⁵,
Nizomiddin Juraev^{6,7}, Hameed Hassan Khalaf⁸,
Bassam Farman Bassam⁹, Nada Qasim Mohammed¹⁰,
Dunya Jameel Kassid¹¹, Ahmed Elawady^{12,13,14} and
Mohammad Sina^{15*}

¹Department of CEA, GLA University, Mathura, India, ²College of Administrative Sciences, Applied Science University, Manama, Bahrain, ³Department of Chemistry, University College of Duba, University of Tabuk, Tabuk, Saudi Arabia, ⁴Department of Computer Science and Engineering, School of Engineering and Technology, JAIN (Deemed to be University), Bangalore, Karnataka, India, ⁵Department of Computer Science and Engineering, Raghu Engineering College, Visakhapatnam, Andhra Pradesh, India, ⁶Faculty of Chemical Engineering, New Uzbekistan University, Tashkent, Uzbekistan, ⁷Scientific and Innovation Department, Tashkent State Pedagogical University, Tashkent, Uzbekistan, ⁸Department of Engineering, Al-Manara College for Medical Sciences, Maysan, Iraq, ⁹College of Engineering, Al-Esraa University, Baghdad, Iraq, ¹⁰Department of Medical Laboratories Technology, AL-Nisour University College, Baghdad, Iraq, ¹¹Department of Engineering, Mazaya University College, Dhi-Qar, Iraq, ¹²College of Technical Engineering, The Islamic University, Najaf, Iraq, ¹³College of Technical Engineering, The Islamic University of Al Diwaniyah, Najaf, Iraq, ¹⁴College of Technical Engineering, The Islamic University of Babylon, Najaf, Iraq, ¹⁵Department of Petroleum Engineering, Omidiyeh Branch, Islamic Azad University, Omidiyeh, Iran

The most widely used equation to calculate water saturation or suitable shaly water saturation in clean or shaly formation, respectively, is the modified Archie formula. The quality of Archie parameters including saturation exponent affects the preciseness of water saturation, and thus estimated oil and gas in place. Therefore, estimating the saturation exponent by the soft computation methods deems to be necessary. In this study, intelligent models such as multilayer perceptron neural network, least squares support vector machine, radial basis function neural network, and adaptive neuro-fuzzy inference system are developed to predict saturation exponent in terms of petrophysical data including porosity, absolute permeability, water saturation, true resistivity, and resistivity index by utilizing a databank for middle east oil and gas reservoirs. The introduced models are optimized using particle swarm optimization, genetic algorithm, and levenberg marquardt techniques. Graphical and statistical methods are used to demonstrate the capability of the constructed models. Based on the statistical indexes obtained for each model, it is found that radial basis function neural network, multilayer perceptron neural network, and least squares support vector machine are the most robust models as they possess the smallest mean squared error, root mean squared error and average absolute relative error as well as highest coefficient of determination. Moreover, the sensitivity analysis indicates that water saturation has the most effect and porosity has the least effect on the saturation exponent. The

developed models are simple-to-use and time-consuming tools to predict saturation exponent without needing laboratory methods which are tedious and arduous.

KEYWORDS

soft computing methods, sensitivity analysis, archie equation, saturation exponent, oil and gas reservoir

1 Introduction

The preliminary objective of an engineered program of formation analysis in the oil industry is the assessment of oil and gas in place in oil and gas reservoirs, respectively (Kravtsova et al., 2022; Nguyen et al., 2022). Archie's parameters n , m and a are typically constant in a routine formation; however, saturation exponent (n) can be allocated a wide range of numbers from 2 to 20 in water-wet to strongly oil-wet formations in certain conditions. Myriad researchers argue that saturation exponent is strongly dependent on displacement history, wettability, and pore size distribution and it may be assigned a value from 2 to 10 (Hamada et al., 2002). Historically, cementation exponent (m) was a parameter in Archie equation that has accounted for most studies and researches; by the introduction of Pickett Plot to estimate m from the wireline measurements of resistivity and porosity, m becomes more variable which can be estimated by crossplot, while tortuosity factor a and saturation exponent n remain a preferred-not-touch parameters unless, for instance, there are some core measurements that can give a different value from two ($n=2$.) (Al-Hilali et al., 2015).

In the process of log interpretation, one is required to obtain precise values of Archie's parameters in order to determine precise water saturation in reservoir formations (Hamada et al., 2002; Dernaika et al., 2007). Constant assumption of saturation exponent, especially in oil or gas reservoirs with a variety of rocky species, can be the last resort (Abdrashitova et al., 2022; Xiao et al., 2024; Zhao et al., 2024). The common method of calculating saturation exponent obtained through laboratory data is special core analysis which directly leads to Archie parameters from the core, but the problem with these methods is the cost and timing of the relevant experiments (Worthington and Pallatt, 1992; Hamada et al., 2002).

The literature indicates several reports on the determination of saturation exponent. Al-Hilali (Al-Hilali et al., 2015) introduced a simple petrophysics-based workflow to estimate water saturation exponent rigorously, and concluded that it can be put into practice in any shaly-sand, and carbonate reservoirs. Najafi and Goodarzi (2011) presented two novel techniques, namely, homogenous distribution of parameters (HDP), and modified genetic algorithm (MGA) to specify Archie's equation parameters simultaneously, and further compared them with other traditional methods. Hamada (2010) put forth a new methodology to calculate Archie's equation factors based on the 3-dimensional graph of three different parameters including water saturation, formation porosity, and formation water resistivity. The author additionally provided a comparison with other methods to ascertain the accuracy magnitude belonging to each method. Mardi et al. (2012) put forward an artificial network based approach to calculate saturation exponent, cementation factor, and water saturation.

In the past, empirical equations and some analysis techniques were used for many topics, including mechanics (Yu et al., 2023), coal (Su et al., 2023), carbon capture and storage (Feng et al., 2024), fluid mechanics (Li et al., 2024a), and gas hydrates (Li et al., 2023). Recently, novel methods based on soft computation has successfully been presented through extensive applications in chemical and petroleum disciplines (Gharbi, 1997; Aminian et al., 2000). These methods are immensely stronger than traditional statistical and classical regression techniques in obtaining precise relationships between input and output datapoints (Mohebbi and Kaydani, 2015). One main method is the use of artificial neural network (ANN) for highly non-linear and classification problems, renowned for its fast estimation, and generalization capability after effectively network training (Gharbi, 1997). Generally, saturation exponent might be accurately predicted in terms of petrophysical (well-log) data through the use of ANNs. Nonetheless, during the learning/training stage, a databank with small datapoints can often result in the overfitting issue resulting in poor capability, and non-generalization. Furthermore, a great deal of time and effort is generally needed to procure the network optimum structure using an iterative-based and tedious approach (Saxena and Saad, 2007; Dehghani et al., 2008). Another helpful methodology is the fuzzy inference system known as FIS. Throughout FIS modeling, membership functions are used to distribute linguistic fuzzy data, and classical set principle is progressed (Zeng and Singh, 1996). This metaheuristic algorithm can capture the non-linear and complex behavior observed, for instance, in multi-dimensional input and output environments (Li et al., 2024b; Li et al., 2020). It is also immensely powerful when dealing with systems characterized with not vividly specified disciplines, and high uncertainties which are usually detected in geoscience systems (Mohebbi and Kaydani, 2015). A more strong technique recognized as adaptive neuro-fuzzy inference system (ANFIS) utilizes the combined features of learning power associated in ANN, and explicit information illustration linked with FIS (Nowroozi et al., 2009).

Recent attempts on soft computation schemes have resulted in developing a supervised machine learning technique, namely, support vector machine (SVM) wherein its relating learning technique is incorporated for the purpose of pattern recognition and data analysis (Schölkopf et al., 1999). SVM has gained much attention for its magnificent performance when handling classification and harsh regression problems (Kamari et al., 2016). SVM has been widely implemented hugely in engineering, and science areas such as porosity and permeability prediction by lithology, well log data, recognition, text/speech detection, and pattern identification in medical science (Choisy and Belaid, 2001; Gao et al., 2001). EL-Sebakhy (El-Sebakhy, 2009) carried out SVM approach to calculate reservoir fluid PVT behavior with the objective of canceling out the limitations associated with the classical neural networks. Chamkalani et al. (Chamkalani et al., 2013) made use

TABLE 1 Statistical parameters with regard to input and output parameters.

Parameters	Symbol	Unit	Min	Max	Avg
Porosity	PHI	Dimensionless (%)	1.26	32.13	13.925
Absolute permeability	Ka	mD	0.017	4,479.557	148.585
Water saturation	Sw	Dimensionless	0.018	1	0.641
True resistivity	RT	Ohm.m	0.3731	2984.047	38.932
Resistivity Index	RI	Ohm.m	0.25	360	7.641
Saturation exponent	n	-	0	10.12	1.731

of least square SVM (LSSVM) to put forth a new scaling equation aiming at predicting asphaltene precipitation with adequate results.

The effect of input parameters on the output variable can be identified by the concept of “sensitivity analysis” (Helton et al., 2005; Patelli et al., 2010). Sensitivity analysis is imperative when one attempts to verify a model, and uncovers how much robust the results of a model is (Christopher Frey and Patil, 2002). Disparate methodologies are used for sensitivity analysis and uncertainty including response surface, differential analysis, fast probability integration, sampling-based techniques, and Fourier amplitude sensitivity test (Iman et al., 1981).

In this study, at first a sensitivity analysis is performed in order to determine the sensitive parameters *via* relevancy factor. Then, several modeling approaches such as radial basis function neural network (RBF-ANN), multilayer perceptron neural network (MLP-ANN), ANFIS and LSSVM are put forth to estimate saturation exponent. For this purpose, first, special core analysis (SCAL) reports are collected from 28 wells from a number of middle eastern oil and gas reservoirs and the data needed to estimate the saturation exponent is extracted from existing methods, including 653 saturations exponent datapoints as a function of porosity (PHI), absolute permeability (Ka), water saturation (Sw), true resistivity (RT), and resistivity index (RI). Next, around 75% and 25% of the gathered datapoints are divided in two subsets including training and testing, respectively, for the intelligent modeling process. The reliability and accuracy of the generated models are then examined via statistical and graphical approaches.

2 Database

The databank used in this paper contains 653 core saturation data as a function of porosity (PHI), absolute permeability (Ka), water saturation (Sw), true resistivity (RT), and resistivity index (RI). Table 1 tabulates the statistics associated with the utilized data. Notice that within the realm of petrophysics which is the globe of measuring, estimating, and calculating underground geological formation data, it is widely accepted that rock saturation exponent is related to rock porosity, absolute permeability, water saturation, true resistivity and resistivity index, though the direction and magnitude are quite different for these parameters. This is why the input parameters in this study include porosity, absolute permeability, water saturation, true resistivity, and resistivity index.

3 Model details

3.1 Prediction methods

These days, machine learning is being used in various fields to predict key parameters (Zhou et al., 2022; Hu et al., 2024; Jiao et al., 2024). This paper is to apply machine learning algorithms to establish prediction models to model saturation exponent as a function of porosity, absolute permeability, water saturation, true resistivity and resistivity index. A brief introductory of the utilized machine learning algorithms is put forth below.

3.1.1 Artificial neural network (ANN)

As a robust modeling methodology, artificial neural network (ANN) is capable of adopting to surrounding variation, efficiency enhancement, and training/learning from experience (Mohanraj et al., 2015). The most rudimentary element in ANN structure is recognized as neurons which are organized in disparate layers, and linked by connections. Two typical sorts of ANNs are named multilayer perceptron (MLP-ANN) and radial basis function (RBF-ANN) networks. MLP-ANN is generally characterized as three different layers of input, hidden, and output. Each hidden layer contains a number of neurons which are required to become optimized. In fact, the number of hidden layers, and neurons in each of them, and ultimately the optimal structure of MLP-ANN are attained through optimization techniques. When handling simple problems, one-hidden layer bearing MLP-ANN may be satisfactory; however, one should use a multi-hidden layer MLP-ANN when the data under study exhibit complicated behavior (Hemmati-Sarapardeh et al., 2016). The neurons prevailing in each hidden layer are connected with the neurons existing in the preceding and subsequent layers through interconnecting weight vectors. Each node value is multiplied via weight vector to estimate the proceeding node value located in the hidden/output layers associated with the implemented interconnection. Then, these values are summed up. Subsequently, a transfer function attempts to screen the summation of the achieved resultant with a bias coefficient. The screened value is ultimately assigned to a desirable neuron (Hemmati-Sarapardeh et al., 2018). It is worth noting that while “Linear” function is mainly put into practice in output layer, “Sigmoid” and “Tanh” transfer functions are generally utilized in intermediate

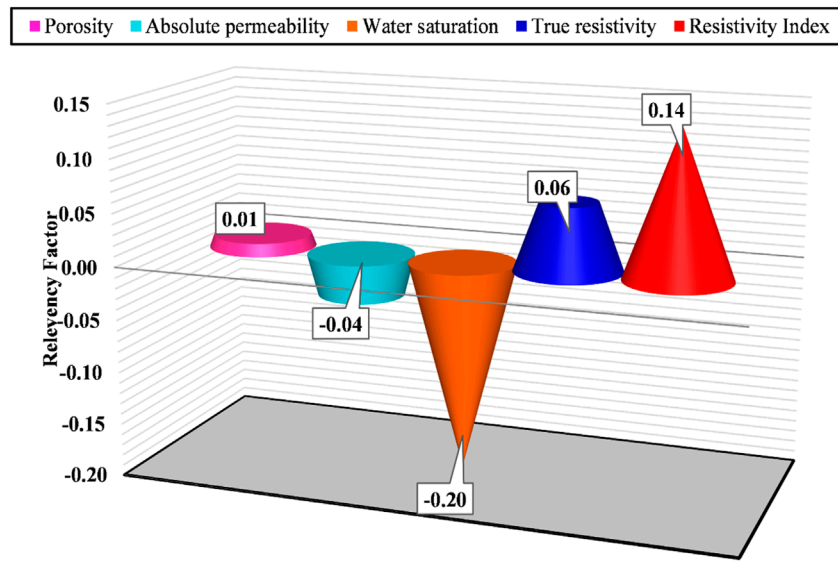


FIGURE 1 Sensitivity analysis on the saturation exponent.

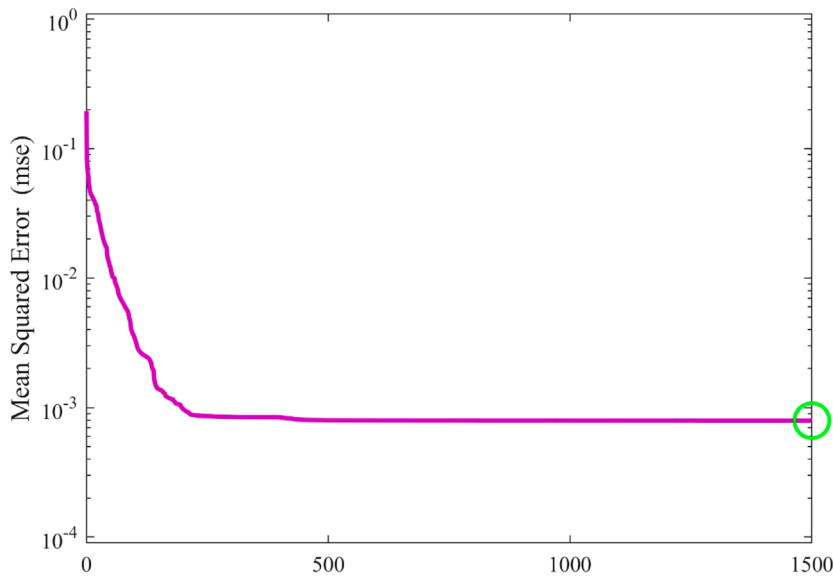


FIGURE 2 Mean squared error (MSE) versus iteration number for Levenberg Marquardt-trained MLP-ANN model.

layers. These functions are mathematically expressed as Eqs 1–3:

$$\text{Tanh} = \text{Tan sig} : g(x) = \frac{e^x - e^{-x}}{e^{-x} + e^x} \quad (1)$$

$$\text{Sigmoid} = \text{Logsig} : g(x) = \frac{e^x}{e^x + 1} \quad (2)$$

$$\text{Linear} = \text{Purelin} : g(x) = x \quad (3)$$

In which e is the Euler number and x being the input value. Taking into account “Sigmoid” and “Linear”

transfer functions related to intermediate and output layers respectively, and a general network structure with solely one hidden layer, one may compute the output according to Eq. 4:

$$\text{Output} = b_2 + (\text{Logsig}(b_1 + x \times w_1)) \times w_2 \quad (4)$$

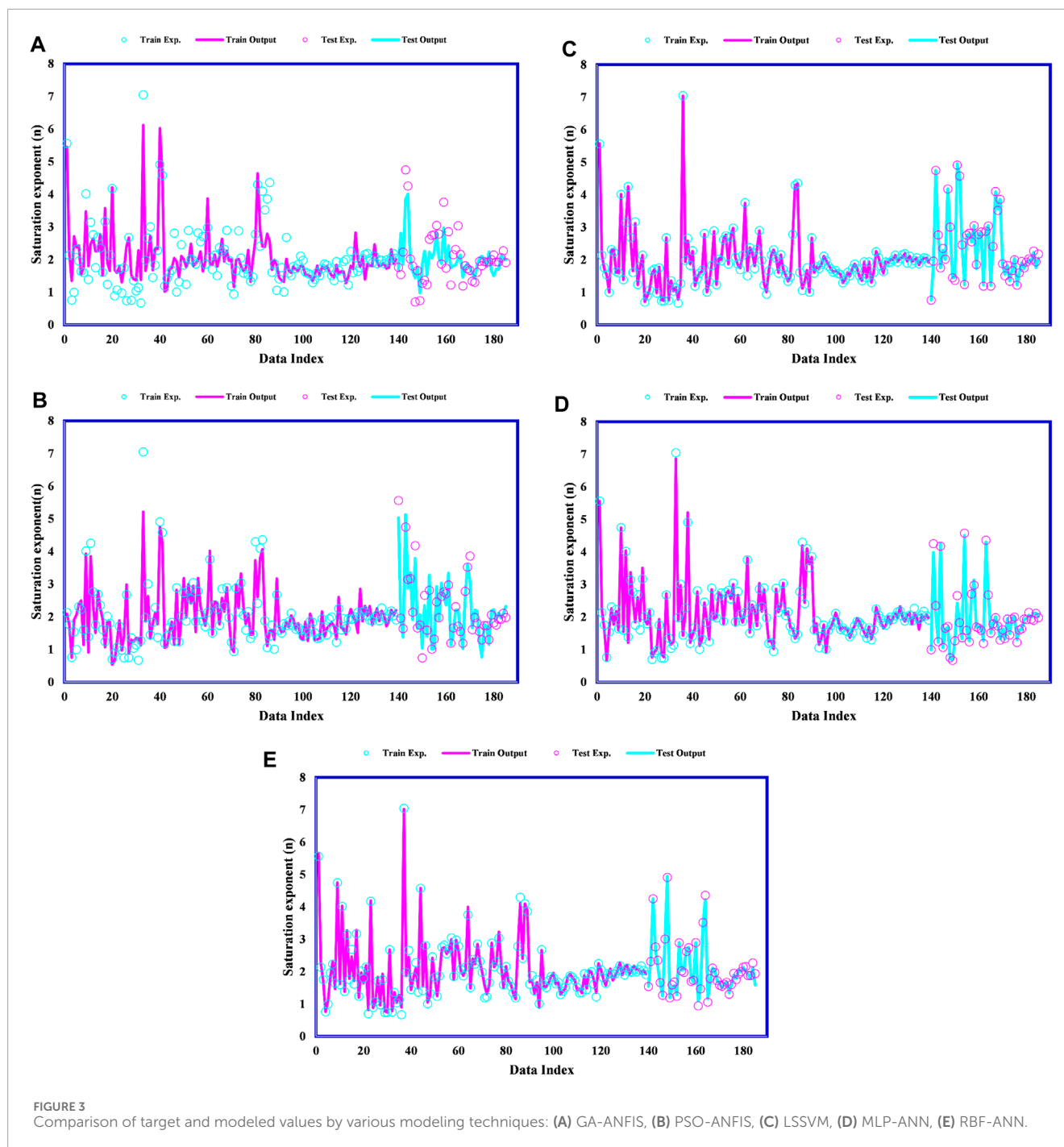
Wherein w_1/b_1 and w_2/b_2 represent weight bias coefficients relating to intermediate and output layers, correspondingly.

TABLE 2 Optimum bias and weight values based upon the developed MLP-ANN modeling technique.

Neuron	Input layer 1					Output layer		
	Weight					Bias	Weight	Bias
1	-0.05239	0.003446	-0.07232	-0.23252	0.375631	2.681785	59.78298	58.2503
2	-73.8865	41.36111	-13.7969	-22.6315	34.5756	60.39265	18.43787	
3	5.829087	-3.79052	5.273297	-14.1798	5.713449	9.4904	-0.70786	
4	-0.02521	-0.28369	1.203023	-2.44554	-28.8115	-35.0474	-405.401	
5	0.013985	0.340031	-1.26759	2.762413	30.0377	35.37726	-111.376	
6	-72.85	40.69215	-13.5779	-25.5255	34.49124	56.65753	-18.4753	
7	-0.07138	-0.39576	2.964897	-0.03899	2.127022	-3.60434	47.1938	
8	-0.07292	0.001222	-0.40556	-0.33324	0.379454	-3.30804	-56.0531	

TABLE 3 Properties of generated models for the purpose of predicting saturation exponent.

MLP-ANN		ANFIS	
No. Input neuron layer	5	Membership Function	Gaussian
No. Hidden neuron layer 1	8	Number of data used for training	139
No. Output neuron layer	1	Number of data used for testing	46
Hidden layer activation function	Logsig	Optimization method	PSO-GA
Output layer activation function	Purelin	Population size	90
Optimization method	Levenberg-Marquardt	Iteration	1,500
Number of data used for training	139	C1	1
Number of data used for testing	46	C2	2
Number of max iterations	1,500	LSSVM	
		Kernel function	RBF
		γ	65532.7266
RBF-ANN		σ^2	0.12285
No. Input neuron layer	5	Number of data used for training	139
No. Hidden neuron layer 1	50		
No. Output neuron layer	1	Number of data used for testing	46
Hidden layer activation function	RBF		
Output layer activation function	Purelin	Population size	85
Optimization method	Levenberg-Marquardt		
Number of data used for training	139	Iteration	1,500
Number of data used for testing	46		

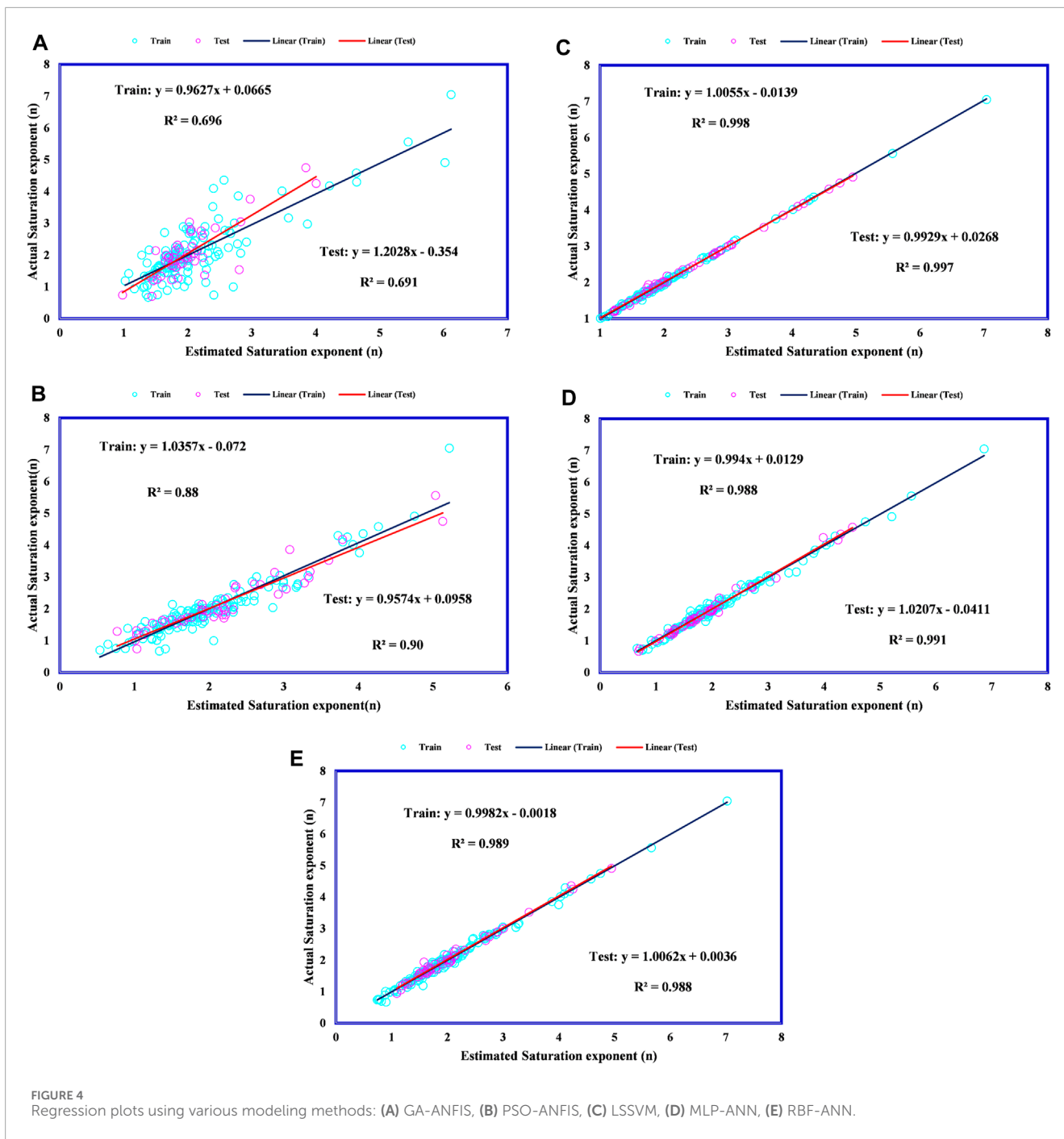


3.1.2 Adaptive neuro-fuzzy inference system (ANFIS)

Network-based or adaptive neuro-fuzzy inference system (ANFIS) has widely been implemented in chemical and petroleum engineering disciplines as a predictive modeling approach. In order to overcompensate fuzzy system and neural network, Jang put forth ANFIS as a five-layered algorithm. ANFIS topology may be trained through back propagation and hybrid learning algorithms (Afshar et al., 2014).

3.1.3 Least squares support vector machine (LSSVM)

Support vector machine (SVM) method categorized under machine learning discipline is mainly used for problem classification and regression analysis (Yao et al., 2006; Baylar et al., 2009). SVM-based techniques are more advantageous than ANN-based techniques because: overfitting issues are less likely to happen; the resultant model is more generalized and number of tuning coefficients are small; and network topology is not

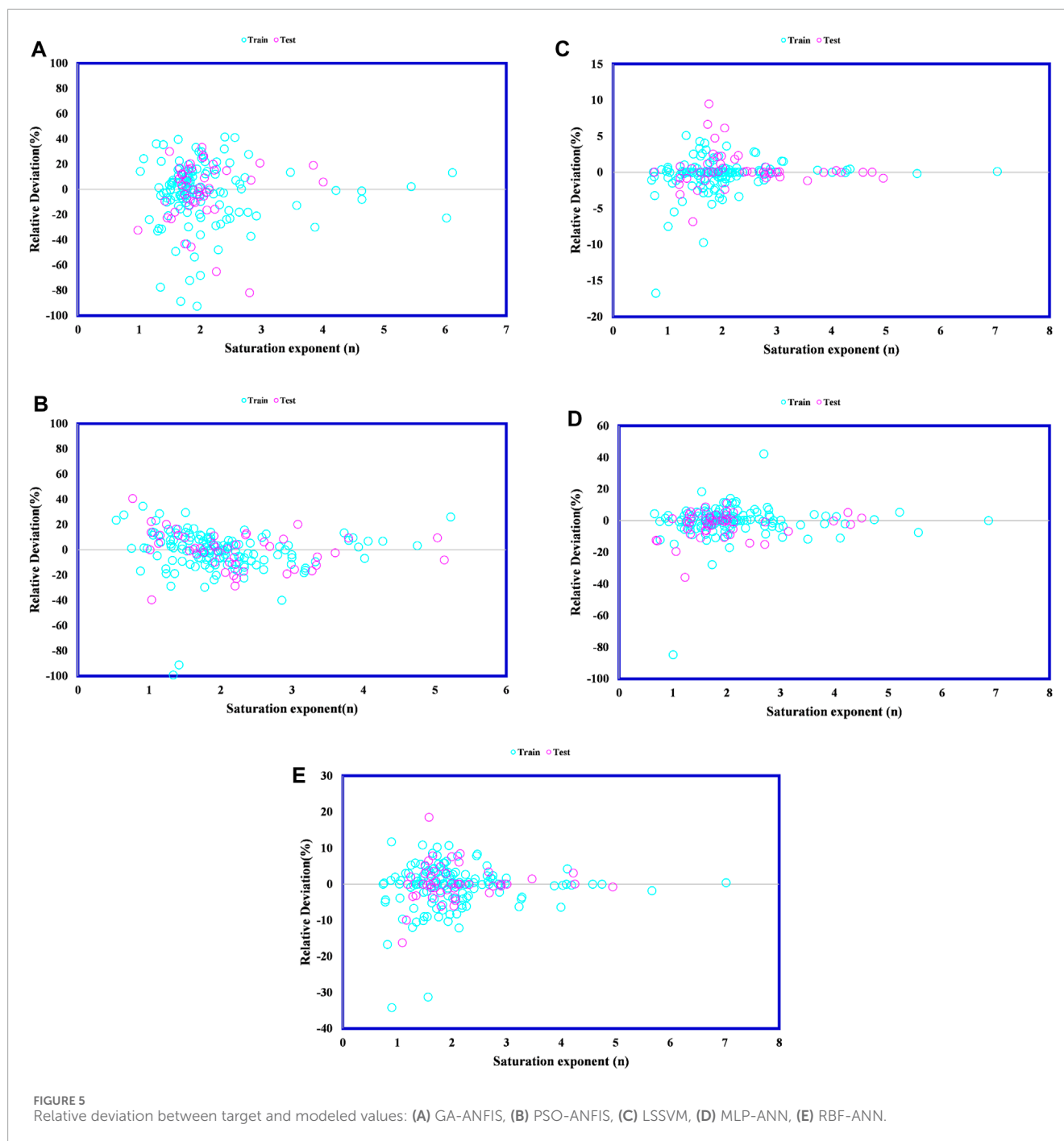


required to be determined. However, recent examinations have shown that the major shortcoming of SVM technique is the largescale quadratic programming problem (Van Gestel et al., 2002). To overcome the mentioned difficulty, a newer form of SVM, namely, least square SVM (LSSVM) has been developed. In this method, each embattled phenomenon is modeled using linear programming rather than quadratic equations. Consequently, any problem may be dealt with less intricacy (Ghiasi et al., 2014).

3.2 Optimization methods

3.2.1 Particle swarm optimization (PSO)

Eberhart and Kennedy (Eberhart and Kennedy, 1995) developed a population-based technique known as particle swarm optimization (PSO) behaviorally suggestive to population of animals including birds and insects. In this method, locations and velocities are initially assigned so as to initialize the preliminary population. Subsequently, each particle is evaluated via regression and statistical



function analysis. During the simulation, particle location and velocity values are always being modified until a stopping criterion called fitness rate is reached, which terminates the mathematical procedure of PSO algorithm (Eberhart et al., 1996; Coulibaly and Baldwin, 2005).

3.2.2 Genetic algorithm (GA)

As an evolutionary method, genetic algorithm (GA) was initially introduced for the purpose of problem optimization. Promising evolution of GA has been achieved using Mendel, Weisman, and Darwin's theory genetics in this methodology (Bäck, 1997). The

major property of GA algorithm is the detection of a different zone in a particular region (Hassan et al., 2005). This technique makes use of inversion, crossover, mutation as the genetic operators. The balanced between formation exploitation an exploration of new zones are supported by the genetic operations. GA strategy's first stage is to initialize a population and specify the problem. Then, the generated potential solution via the initial population is scrutinized using a pre-defined fitness function. In the next step, the populations are categorized in accordance with each fitness value. Then, individual population is made through mutation and crossover operators. Honoring the stopping criterion marks the end of GA algorithm.

TABLE 4 Statistical parameters for various modeling methods in this study.

Model		R^2	ARE (%)	MSE	RMSE	STD
MLP-ANN	Train	0.988	3.780	0.009746113	0.0987	0.1242
	Test	0.991	2.716	0.006937962	0.1377	0.0947
	Total	0.989	3.515	0.00904787	0.1377	0.1174
RBF-ANN	Train	0.990	3.946	0.009183527	0.0958	0.0679
	Test	0.988	3.405	0.008492303	0.0922	0.0687
	Total	0.989	3.811	0.009011655	0.0922	0.0680
PSO-ANFIS	Train	0.888	11.605	0.089156981	0.2986	0.2184
	Test	0.908	11.453	0.08663808	0.2943	0.1764
	Total	0.893	11.567	0.08853066	0.2943	0.2087
GA-ANFIS	Train	0.696	21.409	0.273356261	0.5228	0.3752
	Test	0.692	19.197	0.20856232	0.4567	0.2983
	Total	0.690	20.859	0.257245335	0.4567	0.3570
LSSVM	Train	0.999	1.194	0.001050471	0.0324	0.0261
	Test	0.998	1.455	0.002328602	0.0483	0.0397
	Total	0.998	1.259	0.001368276	0.0483	0.0302

3.2.3 Levenberg-Marquardt (LM)

Levenberg-Marquardt (LM) methodology was presented when the traditional Newton technique was amended for the purpose of problem minimization efficiently. In this method, Hessian matrix, expressed below, is implemented within the equation of Newton-like weight update (Eq. 5):

$$x_{k+1} = x_k - (JJ^T + \eta I)^{-1} eJ^T \quad (5)$$

In which η , x , e and J denote a scalar controlling learning process, weight of neural network, vector representing residual error, and Jacobian matrix, respectively (Daliakopoulos et al., 2005). Although LM optimization may only be implemented for small networks since it seeks large computations and memory occupations (Maier and Dandy, 1998), myriad reported applications in the literature report this technique promising and worthwhile (Anctil et al., 2004). The observed advantages of LM method over other techniques include higher convergence speed, less possibility of local minima entrapment, and larger stability and efficiency (Toth et al., 2000).

4 Model development

In the present paper, the acquired databank was initially categorized into two subsets of train (around 75% of the entire dataset), and testing (around 25% of the entire dataset), respectively. Training dataset was utilized to construct the model, then to validate the developed model, test dataset was made use of. It is worth

noting that to cancel out the effect of large variations existing in the databank, the data were first normalized according to the formula defined below (Eq. 6):

$$n_{norm} = \frac{n - n_{min}}{n_{max} - n_{min}} \quad (6)$$

Wherein n , n_{max} , n_{min} , and n_{norm} indicate actual datapoint, dataset maximum value, dataset minimum value, and normalized datapoint.

To conduct assessment of the generated models in this paper, a number of statistical formulations including mean squared error (MSE), standard deviation of error (SD), root mean squared error (RMSE), and coefficient of determination (R^2), mathematically indicated below, are used (Eqs 7–10):

$$MSE = \frac{\sum_{i=1}^N (n_i^{exp} - n_i^{cal})^2}{N} \quad (7)$$

$$R^2 = \frac{\left(\sum_{i=1}^N (n_i^{exp} - \bar{n}^{exp})(n_i^{cal} - \bar{n}^{cal}) \right)^2}{\sum_{i=1}^N (n_i^{exp} - \bar{n}^{exp})^2 \sum_{i=1}^N (n_i^{cal} - \bar{n}^{cal})^2} \quad (8)$$

$$RMSE = \left(\frac{\sum_{i=1}^N (n_i^{exp} - n_i^{cal})^2}{N} \right)^{0.5} \quad (9)$$

$$SD = \left(\frac{1}{N-1} \sum_{i=1}^N \left(\frac{n_i^{\text{exp}} - n_i^{\text{cal}}}{n_i^{\text{exp}}} \right)^2 \right)^{0.5} \quad (10)$$

In the above four equations, N is the datapoint, and superscripts cal, and exp indicate calculated by the developed model and experimental saturation exponent, respectively. The mean value for each dataset is denoted by \bar{n} .

5 Results and discussion

To indicate to what an extent each input variable affects the output variable, sensitivity analysis is performed here. For this purpose, we use the concept of relevancy factor which can lie within -1 to 1 . The relevancy factor is an index, demonstrating the direct and indirect relationship of each input parameter with the target variable. In addition, its value determines the magnitude of such effects. In this way, a positively and negatively derived relevancy factor means direct and indirect, respectively, of the input parameter under study with the target variable. Moreover, a larger value of this parameter for a specific input variable simply shows that it is more influential over the output parameter. Relevancy factor is defined as (Eq. 11):

$$r_j = \frac{\sum_{i=1}^n (x_{j,i} - \bar{x}_j)(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_{j,i} - \bar{x}_j)^2 \sum_{i=1}^n (y_i - \bar{y})^2}} \quad (11)$$

The findings associated with sensitivity analysis on the saturation exponent using the relevancy concept is illustrated in Figure 1. As may be seen, among disparate input parameters, water saturation and porosity are the most and least effective factors on the saturation exponent. Moreover, we can conclude in contrast to absolute permeability and water saturation parameters, porosity, true resistivity and resistivity index factors are directly related with the saturation exponent.

In the present communication, disparate intelligent modeling techniques such as RBF-ANN, MLP-ANN, GA-ANFIS, PSO-ANFIS, and LSSVM were made use of to model saturation exponent (n) aided by a number of optimization methods including PSO, GA, and LM. Levenberg Marquardt (LM) technique was linked with MLP-ANN. MSE values *versus* iterations within the MLP-ANN structure are demonstrated in Figure 2. As can be seen, the MSE value approaches to lower values as the number of iterations grow and the minimum MSE is found at the iteration number equal to 1,500.

The adjusted bias and weight coefficients obtained by LM method for the output and hidden layers are tabulated in Table 2. Again, these are the optimum values for the LM structure.

In the RBF-ANN technique, we selected radial basis function as the hidden layer transfer function, and LM as the optimizing algorithm. The details of the constructed models are indicated in Table 3. This table illustrates number of neurons, internal functions, and tuning parameters for each modeling technique put forth in this study. Notice that these are the structure details that were obtained for the optimum structures.

The modeled and target saturation exponent values are plotted *versus* data index by various models in Figure 3.

Figure 3 demonstrates the robustness of the presented models in predicting the saturation exponent. To more thoroughly showcase the capability of these introduced models, regression plots for both the testing and training datasets are provided in Figure 4, illustrating the performance of the developed modeling techniques. These plots visually depict the correlation between the predicted and actual values, allowing for a clear assessment of the models' accuracy and reliability. The training dataset results indicate how well the models have learned from the provided data, while the testing dataset results offer insights into their generalizability to unseen data. The close alignment of the regression lines to the 45-degree line in the plots suggests a high degree of accuracy in the predictions.

Any model with a higher coefficient of determination (R^2) is considered more reliable; in this context, the datapoints are more closely aligned around the 45-degree line. The results indicate that GA-ANFIS is less accurate compared to other models such as MLP-ANN, RBF-ANN, and LSSVM, which exhibit higher R^2 values. Following RBF-ANN, MLP-ANN, and LSSVM, the ANFIS-PSO model is the next most precise, with R^2 values of 0.90 and 0.88 for the testing and training datasets, respectively.

Figure 5 displays the relative error against the target saturation exponent points for all the developed models. Among these models, MLP-ANN, RBF-ANN, and LSSVM show results that are tightly clustered around the zero line. Additionally, several statistical parameters such as Mean Squared Error (MSE), Root Mean Squared Error (RMSE), Standard Deviation (STD), and R^2 are presented in Table 4 for the developed models. According to this table, LSSVM, RBF-ANN, and MLP-ANN have the lowest values of SD, RMSE, and MSE compared to other developed models, which means that the aforementioned models are the most accurate amongst all models.

6 Conclusion

In the present study, several modeling techniques such as RBF-ANN, LSSVM, MLP-ANN, MLP-ANN, PSO-ANFIS, and GA-ANFIS were implemented to predict the saturation exponent parameter in terms of well log data. These modeling techniques were optimized through the use of PSO, GA, and ML algorithms. A databank of petrophysical data gathered for a number of middle eastern oil and gas reservoirs was used for this purpose. The gathered databank was split into two subsets to test and train the constructed models. Several statistical factors along with graphical plots were employed to assess the generated models. The results demonstrated that LSSVM, RBF-ANN, and MLP-ANN are the most accurate models with regard to prediction of saturation exponent as they are characterized with $R^2=0.9815-0.9983$ and $RMSE=0.0409-0.1410$. The sensitivity analysis additionally indicated that saturation exponent has the highest dependency upon the water saturation.

Data availability statement

The raw data supporting the conclusions of this article will be made available by the authors, without undue reservation.

Author contributions

AY: Conceptualization, Writing–original draft, SA: Software, Writing–review and editing, Data curation. FA: Writing–review and editing, Data curation, PR: Writing–original draft, Formal Analysis, Supervision. MR: Writing–original draft, Formal Analysis, Software. NJ: Writing–original draft, Funding acquisition, Resources. HK: Writing–original draft, Conceptualization, Funding acquisition, Project administration, Visualization. BB: Investigation, Writing–original draft, NQ: Writing–original draft, Investigation, Supervision. DK: Writing–original draft, Methodology, Project administration, Validation. AE: Project administration, Validation, Writing–review and editing. MS: Writing–review and editing, Project administration, Visualization.

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