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Fracture initiation pressure prediction of hydraulic fracturing for layered reservoirs considering borehole deformation

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Accurately predicting fracture initiation pressure is crucial for successfully applying hydraulic fracturing technology in layered reservoirs. However, existing models overlook the effects of rock anisotropy and borehole deformation. In this study, we simplified the layered reservoir to a transversely isotropic medium and developed a model to estimate borehole deformation precisely. Based on this estimated deformation, we created a model to predict fracture initiation pressure in hydraulic fracturing. By comparing previous models and experimental data, we validated the effectiveness of these proposed models. We examined the impacts of various factors on borehole deformation, fracture initiation pressure, and initiation angle. The results revealed that circular boreholes in layered reservoirs deform into elliptical boreholes under in situ stress, with the major axis not aligning with the principal stress direction, which highlights the significant impact of rock anisotropy on borehole deformation. Furthermore, the fracture initiation pressure of hydraulic fracturing either increases or decreases following borehole deformation, depending on specific geological parameters. The calculated initiation angle after borehole deformation is within 10°, closer to previous experimental results, underscoring the notable effect of borehole deformation on hydraulic fracturing. Our research indicates that the impact of borehole deformation on hydraulic fracturing is significant and should not be overlooked. This finding will offer fresh avenues for further study in the field of hydraulic fracturing.

KEYWORDS

borehole deformation, fracture initiation pressure, hydraulic fracturing, anisotropy, initiation angle

1 Introduction

Hydraulic fracturing technology is extensively utilized in layered reservoirs such as shale, tight sandstone, and coal (Abdulelah et al., 2018; Qu et al., 2022a; Lu et al., 2022). This method efficiently enhances reservoir permeability by creating artificial fractures, thereby significantly boosting the extraction of unconventional natural gas (Song et al., 2017; Zhao et al., 2020a; He et al., 2022a; He et al., 2022b; Li et al., 2022; Zhao et al., 2022; Liu et al., 2023). Accurately predicting and minimizing the fracture initiation pressure (FIP) near boreholes in rocks and comprehending fracture extension behavior is crucial (Wu et al., 2020; Huang et al., 2023a). The analysis of FIP through a mechanistic-based theoretical approach is widely acknowledged as an effective method (Shou and Zhou, 2021; Ren et al., 2022) and has been extensively researched by numerous scholars.

Hubbert and Willis. (1957) were the pioneers who proposed a theory to predict FIP. Subsequently, numerous scholars contributed significantly to the development of related theories (Eaton, 1969; Constant and Jr, 1988; Detournay and Cheng, 1988; Oriji and Ogbonna, 2012; Ma et al., 2017; Zhang et al., 2018.). While the accuracy of predicted values has improved over time and can generally meet basic engineering requirements, there are instances where a discrepancy exists between predicted and actual values (Ma et al., 2019). This discrepancy can be attributed to these models' assumption of uniform mechanical properties in all directions. At the same time, shale, tight sandstone, and coal exhibit significant anisotropic characteristics with varying mechanical properties on parallel and perpendicular bedding planes. As a result, these reservoirs typically be simplified as transverse isotropic mediums (Espinoza et al., 2013; Li and Zhang, 2019; Ma et al., 2021). Existing laboratory experiments on fracturing have shown that the FIP of hydraulic fracturing varies as the angle between the bedding plane and the borehole changes, highlighting the significant impact of rock anisotropy, a factor acknowledged by numerous scholars (Qu et al., 2022a; Liu et al., 2022; Zhang et al., 2023). Numerous researchers have conducted theoretical examinations on the influence of rock anisotropy. Aadnoy and Chenvert. (1987) were the first to propose a stability model for boreholes using anisotropic body theory. Since then, numerous researchers have adopted similar approaches to investigate the FIP for boreholes in transversely isotropic formation (Ong and Roegiers, 1995; Gupta and Zaman, 1999; Prioul et al., 2011; Zhu et al., 2014.). Do et al. (2017) developed a model incorporating hydraulic and mechanical anisotropy to predict the FIP of boreholes with permeable and impermeable boundaries. Sesetti and Ghassemi. (2018) also developed a model that considers elasticity and fracture anisotropy to predict FIP for boreholes in transversely isotropic formations. Ma et al. (2022) developed a model that considers the anisotropy of rock strength to predict FIP for both vertical and inclined boreholes. In addition, the heterogeneity of the reservoir influences the propagation of fractures (Wu et al., 2023), resulting in the creation of intricate fractures (Zhou et al., 2020; Huang et al., 2023b), which also significantly impact the extraction of reservoir gas (Zhao and Zhou, 2020b; Song et al., 2020). Therefore, it is crucial to consider the effect of reservoir anisotropy on the efficiency of hydraulic fracturing.

Several scholars have developed models to predict FIP for transversely isotropic reservoirs in hydraulic fracturing. However, these models are specifically designed for the circular borehole. Field logging data shows that circular boreholes can deform due to stress and mechanical anisotropy (Figure 1) (Zoback et al., 2003; Pierdominici et al., 2020; Han et al., 2021). Various studies have investigated the effects of borehole deformation. For instance, Haimson and Lee. (2004) discovered that circular boreholes in sandstone deform significantly and assume an elliptical shape under uneven loading. Zhai et al. (2015) observed that a circular borehole in an on-site coal seam became elliptical after redistributing in situ stresses. Gao and Ren. (2022) found that circular boreholes deform into elliptical boreholes due to stress exertion in hydraulic fracturing. Several researchers have studied the stress distribution around elliptical boreholes and concluded that changes in borehole shape affect the distribution of the stress field, which in turn affects the destructive behavior of the rock (Qi et al., 2018; Chen et al., 2020; Zhong et al., 2021). Scholars have established models based on theoretical mechanics to compute the deformation of circular boreholes and estimate their precise dimensions (Zou et al., 2018; Fang et al., 2022; Han et al., 2023). However, these models primarily consider the impact of stress anisotropy while disregarding the influence of mechanical anisotropy. Consequently, these models are not suitable for anisotropic formations. Moreover, current fracturing models have failed to establish a correlation between borehole deformation and FIP.

In this study, we developed a model to estimate borehole deformation in the layered reservoir. Subsequently, we formulated a mechanical model to predict the FIP in hydraulic fracturing, considering the shape and magnitude of the estimated borehole deformation. Our proposed model was verified by comparing them with previous models. Moreover, we conducted a thorough analysis to evaluate the influence of different factors on the extent of borehole deformation, FIP, and initiation angle.

2 FIP model after borehole deformation

2.1 Analysis of circular borehole deformation

This study defines compressive stress as positive and tensile stress as negative stress. The layered reservoir is assumed to be a homogeneous, continuous, linear transverse isotropic medium that undergoes small deformations. Due to the length of the boreholes being significantly more significant than their diameter, the generalized plan strain condition is applicable. In addition, this study ignores the effects of temperature, chemical environment, and seepage.

Assuming the bedding plane exhibits symmetry along the *z*-axis (Figure 2A), only stresses in the x_1oy_1 plane impact the borehole deformation and FIP, which allows for simplifying the analysis to a planar problem (Heng et al., 2021) (Figure 2B). In Figure 2B, we established the *in situ* stress coordinate system (x_1oy_1) is established along the direction of the *in situ* stress. The x_1 and y_1 axes align with the direction of the *in situ* stresses σ_H and σ_h , respectively. Additionally, we defined a bedding plane coordinate system (x_2oy_2) along the direction of the bedding plane. The x_2 and y_2 axes are parallel and perpendicular to the bedding plane (Figure 2C). We denoted the angle between the x_1 and x_2 axes as α . By employing the coordinate transformation formula (1), we can obtain the stress components in the bedding plane coordinate system.

$$\begin{cases} \sigma_{x1} = \sigma_H \cos^2 \alpha + \sigma_h \sin^2 \alpha \\ \sigma_{y1} = \sigma_H \sin^2 \alpha + \sigma_h \cos^2 \alpha \\ \tau_{xy1} = (\sigma_h - \sigma_H) \sin \alpha \cos \alpha \end{cases}$$
(1)

Where σ_h and σ_H are the minimum and maximum horizontal principal stresses, respectively, MPa; α is the inclination angle of the bedding plane, °.

The borehole deformation under generalized plane strain conditions is illustrated below (Please refer to Appendix A for detailed derivation):

$$\begin{cases} u = \left(\beta_{11}\left(1 + \sqrt{p + 2q}\right)\sigma_{x1} - q\beta_{11}\sigma_{y1}\right)R\cos\theta \\ + \left(\sqrt{p + 2q}\beta_{11} + q\beta_{11} + \beta_{12}\right)\tau_{xy1}R\sin\theta \\ v = \left(\frac{\sqrt{p + 2q} + q}{q}\sigma_{y1} - \frac{\sigma_{x1}}{q}\right)\beta_{22}R\sin\theta \\ + \left(\beta_{12} + \frac{\sqrt{p + 2q} + 1}{q}\beta_{22}\right)\tau_{xy1}R\cos\theta \end{cases}$$
(2)

Where *u* and *v* are the displacement in the directions of x_1 and y_1 axes, m.

The new coordinates points of the borehole wall, resulting from the borehole deformation under the influence of *in situ* stress, are as follows:

$$\begin{cases} x_1 = R\cos\theta - u\\ y_1 = R\sin\theta - v \end{cases}$$
(3)

2.2 Determination of shape after circular borehole deformation

The coordinates points of the borehole wall after the borehole deformation in Equation 3 satisfy the following equation:

$$Ax_1^2 + Bx_1y_1 + Cy_1^2 = 1 \tag{4}$$

where:

$$\begin{cases} A = \frac{e^2 + f^2}{(ce - df)^2}; B = \frac{-2cf - 2de}{(ce - df)^2}; C = \frac{c^2 + d^2}{(ce - df)^2} \\ c = R - \left(1 + \sqrt{p + 2q}\right)\beta_{11}R\sigma_{x1} - q\beta_{11}R\sigma_{y1} \\ d = -\left(\sqrt{p + 2q}\beta_{11} + q\beta_{11} + \beta_{12}\right)R\tau_{xy1} \\ e = R - \left(\frac{\sqrt{p + 2q}}{q} + 1\right)\beta_{22}R\sigma_{y1} + \frac{\beta_{22}}{q}R\sigma_{x1} \\ f = -\left(\beta_{12} + \frac{1 + \sqrt{p + 2q}}{q}\beta_{22}\right)R\tau_{xy1} \end{cases}$$

Equation 4 is the general equation of the ellipse, indicating that circular boreholes in anisotropic reservoirs will deform into elliptical boreholes under the effect of the *in situ* stress. This observation aligns with the logging data (Zoback et al., 2003; Han et al., 2021), indicating that the proposed model is consistent with the actual situation.

The major axis (*a*), minor axis (*b*), and angle β between the major axis of the ellipse and the coordinate axis x_1 can be determined using Equation 4 and relevant mathematical knowledge (β is defined as the deflection angle, the calculation procedure is provided in Appendix B).

$$\begin{cases} a = \sqrt{\frac{2}{A + C - \sqrt{(A - C)^2 + B^2}}}\\ b = \sqrt{\frac{2}{A + C + \sqrt{(A - C)^2 + B^2}}}\\ \beta = \frac{1}{2} \arctan\left(\frac{B}{A - C}\right) \end{cases}$$
(5)

When $\mu_1=\mu_2=i$, $\beta=0$, $E_1=E_2$, $v_{12}=v_{13}$, we can simplify the model to evaluate the deformation of a borehole in an isotropic stratum under positive stress; at this time, the major axis, minor axis, and deflection angle in Equation 5 are as follows:

$$a = R\left(1 - \frac{1 - v^2}{E} \left(3\sigma_{\rm H} - \sigma_{\rm h}\right)\right), b = R\left(1 - \frac{1 - v^2}{E} \left(3\sigma_{\rm h} - \sigma_{\rm H}\right)\right),$$

$$\beta = 0$$
(6)

Equation 6 is consistent with the borehole deformation model in isotropic reservoirs, as Zou et al. (2018) established, indicating the proposed model's precision.

2.3 Stress distribution around the circular borehole after deformation

We analyzed the stress distribution around the elliptical borehole in hydraulic fracturing, considering the relevant parameters of the circular borehole after deformation, established a new coordinate system $(x_3 o y_3)$ (Figure 3), in which the x_3 and y_3 axes are parallel to the major and minor axes of the elliptical borehole, respectively. By applying the coordinate transformation formula (7), we obtained the stress components of the *in situ* stress in this coordinate system:

$$\begin{cases} \sigma_{x2} = \sigma_{\rm H} \cos^2 \left(\alpha + \beta\right) + \sigma_{\rm h} \sin^2 \left(\alpha + \beta\right) \\ \sigma_{y2} = \sigma_{\rm H} \sin^2 \left(\alpha + \beta\right) + \sigma_{\rm h} \cos^2 \left(\alpha + \beta\right) \\ \tau_{xy2} = \left(\sigma_{\rm h} - \sigma_{\rm H}\right) \sin\left(\alpha + \beta\right) \cos\left(\alpha + \beta\right) \end{cases}$$
(7)

We obtained the stress distribution around the elliptical borehole in anisotropic media using the stress analysis method for the planar orifice problem (Please refer to Appendix C for detailed derivation).

$$\begin{cases} \sigma_{x} = \sigma_{x2} + 2\operatorname{Re}\left[\mu_{11}^{2}\varphi_{11}^{'}(z_{1}) + \mu_{22}^{2}\varphi_{22}^{'}(z_{2})\right] \\ \sigma_{y} = \sigma_{y2} + 2\operatorname{Re}\left[\varphi_{11}^{'}(z_{1}) + \varphi_{22}^{'}(z_{2})\right] \\ \tau_{xy} = \tau_{xy1} - 2\operatorname{Re}\left[\mu_{11}^{'}\varphi_{11}^{'}(z_{1}) + \mu_{22}^{'}\varphi_{22}^{'}(z_{2})\right] \end{cases}$$
(8)

Where

$$\begin{cases} \varphi_{11}'(z_1) = \frac{\mu_{22}(\sigma_{y2}a - i\tau_{xy2}b - p_wa) + \tau_{xy2}a + ip_wb - i\sigma_{x2}b}{2\xi_1(\mu_{22} - \mu_{11})\sqrt{z_1^2 - a^2 - \mu_{11}^2b^2}} \\ \varphi_{22}'(z_2) = -\frac{\mu_{11}(\sigma_{y2}a - i\tau_{xy2}b - p_wa) + \tau_{xy2}a + ip_wb - i\sigma_{x2}b}{2\xi_2(\mu_{22} - \mu_{11})\sqrt{z_2^2 - a^2 - \mu_{22}^2b^2}} \end{cases}$$
(9)

Thus on the borehole wall:

$$\xi_k = \cos\theta + i\sin\theta, z_k = a\cos\theta + ib\sin\theta \tag{10}$$

We can obtain the stress distribution around an elliptical borehole in a Cartesian coordinate system by substituting Equation 10, Equation 9 into Equation 8.

2.4 Prediction model of FIP for the elliptical borehole

If the tangential stress exerted on the borehole wall exceeds the tensile strength of the reservoir, the borehole will failure. Therefore, it is essential first to assess the tangential stress of the borehole. By utilizing the coordinate transformation formula (11), we can determine tangential stress distribution at any point along the borehole wall.

$$\begin{cases} \sigma_{\theta} = \sigma_{x} \sin^{2} \varphi + \sigma_{y} \cos^{2} \varphi - 2\tau_{xy} \sin \varphi \cos \varphi \\ \sin \varphi = \pm a \sin \theta / \sqrt{a^{2} \sin^{2} \theta + b^{2} \cos^{2} \theta} \\ \cos \varphi = \mp b \cos \theta / \sqrt{a^{2} \sin^{2} \theta + b^{2} \cos^{2} \theta} \end{cases}$$
(11)



FIGURE 1

Three-dimensional borehole breakout view from ABI image of the PTA2 borehole wall. S_h and S_H are the orientations of the minimum and maximum horizontal principal stresses, respectively (Pierdominici et al., 2020).

Previous research indicated that anisotropic rocks have different tensile strengths in different directions (Ma et al., 2017). Furthermore, the N-E criterion can be used to accurately assess the tensile strength of anisotropic rocks in any direction as follows (Nova and Zaninetti, 1990):

$$T(\theta) = \frac{T_1 T_2}{T_1 \sin^2(\theta - \beta) + T_2 \cos^2(\theta - \beta)}$$
(12)

Where T_1 and T_2 are the tensile strength perpendicular and parallel to the bedding plane, respectively, MPa.

Suppose the tangential stress exceeds the rock's tensile strength. In that case, the rock enters the failure stage (Equation 13). At this moment, the pressure at which the fracturing fluid is injected, known as p_{w} , represents the FIP.

$$\sigma_{\theta} = -\sigma_{t} \tag{13}$$

Where σ_t is the tensile strength of the rock, MPa.

The initiation angle of the fracture can be determined using the following equation (Liang et al., 2022), where θ is the initiation angle.

$$\frac{\partial \sigma_{\theta}}{\partial \theta} = 0, \frac{\partial^2 \sigma_{\theta}}{\partial \theta^2} > 0 \tag{14}$$

3 Model validation

3.1 Model validation by different model comparisons

We have successfully validated the proposed borehole deformation model in Section 2.2. Furthermore, it is necessary to validate the proposed FIP model for the elliptical borehole in the anisotropic medium, and we can achieve it by degrading this model to an isotropic model and comparing it with existing models. The existing models that can be used for comparison are the elliptical model in the isotropic medium proposed by Aadnoy and Angell-olsen. (1995) (Eq. 15) and Ge et al. (2019) (Eq. 16), respectively. The specific forms of these models are as follows:

$$\sigma_{\theta} = \frac{\sigma_{x2} \left((c^{2} + 2c) \sin^{2} \theta - \cos^{2} \theta \right) + \sigma_{y2} \left((1 + 2c) \cos^{2} \theta - c^{2} \sin^{2} \theta \right)}{c^{2} \sin^{2} \theta + \cos^{2} \theta} \\ -p_{w} \left(\frac{c^{3} \left(2c^{2} - 3c + 4 \right) \sin^{4} \theta \cos^{2} \theta + c \left(4c^{2} - 3c + 2 \right) \sin^{2} \theta \cos^{4} \theta}{(c^{2} \sin^{2} \theta + \cos^{2} \theta) \left(+ (2c^{2} - 1) \cos^{6} \theta - (2c - 1) \cos^{6} \theta - c^{2} (c^{2} + 2) \sin^{4} \theta \cos^{2} \theta - c^{2} (c^{2} + 2) \sin^{4} \theta \cos^{2} \theta} \right)}{(15)} \\ \sigma_{\theta} = \sigma_{x2} \frac{1 - m^{2} + 2m - 2\cos 2\theta}{1 - 2m \cos 2\theta + m^{2}} + \sigma_{y2} \frac{1 - m^{2} - 2m + 2\cos 2\theta}{1 - 2m \cos 2\theta + m^{2}} \\ + \frac{3m^{2} - 2m \cos 2\theta - 1}{1 - 2m \cos 2\theta + m^{2}}$$
(16)

When calculating the tangential stress on the wall of the elliptical borehole, we utilize the following values: the borehole radius is 0.12 m, *c* is 1.2, m is 0.6, σ_{x2} is 50MPa, σ_{y2} is 30 MPa, τ_{xy2} is 0, and the fracturing fluid injection pressure is 20 MPa. We determine the tangential stresses on the borehole wall using Aadnoy's, Ge et al.'s, and our proposed model. We presented the results in Table 1. The table demonstrates that the proposed model yields similar results to Aadnoy's and Ge et al.'s models when μ_{11} =1.001i and μ_{22} =0.999i, which indicates the accuracy of our proposed model and its applicability in studying the stress distribution around the elliptical borehole in the anisotropic medium.

3.2 Model validation by experimental data

To validate the dependability of the proposed model, we substituted the experimental conditions and mechanical parameters from the literature (Liu et al., 2022) into our proposed model and Ma et al.'s model. (Ma et al., 2022). We presented the experiment and calculation results in Figure 4. The FIP decreases as the bedding inclination angle increases, and the calculation results align with the experimental findings. The concave



shape of the curve derived from the experimental data aligns with the results of our proposed model, whereas the curve model from Ma et al. exhibits a convex shape. Additionally, our model's calculation results closely match the experimental data, leading to a maximum 47.6% (23°) improvement in accuracy compared to Ma et al.'s model, which indicates the superiority of our model in predicting the FIP of reservoirs with a significant angle between the bedding plane and stress direction, highlighting its advanced predictive nature.

4 Analysis of factors impacting borehole deformation and FIP

We calculated the FIP and initiation angle of the initial circular borehole by substituting the radius (*R*) into Equations 13, 14 to replace the major axis (*a*) and minor axis (*b*) of the elliptical borehole, then calculated the size of the borehole deformation and the deflection angle (β) under various factors using Matlab software, and compared the FIP and the initiation angle of the initial circular borehole and the elliptical borehole. Table 2 presents the related parameters.

4.1 Effect of the in situ stress

The *in situ* stress significantly influences the deformation and FIP of the borehole. This study set various values of horizontal stress differences to investigate the borehole deformation and distribution of FIP (Figures 5, 6). Figure 5A shows that the length of the major and minor axes and the deflection angle of the deformed elliptical

borehole decrease with increasing $\sigma_{\rm h}$. Further analysis shows that the difference between the length of the major and minor axes first increases and then decreases as increasing $\sigma_{\rm h}$, reaching a maximum value at 43 MPa. Notably, the deflection angle of the elliptical borehole is invariably greater than zero, indicating that the direction of the major axes of the deformed elliptical borehole is not consistent with the direction of the in situ stress in anisotropic reservoirs. Figure 5B shows that the FIP and initiation angle of both elliptical and circular boreholes increase with increasing σ_h ; when σ_h is larger than 43.9MPa, the FIP of elliptical boreholes is slightly larger than that of circular boreholes. However, when $\sigma_{\rm b}$ is less than 43.9 MPa, the FIP of elliptical boreholes is smaller than that of circular boreholes, which suggests that borehole deformation arising under in situ stress can either increase or decrease borehole stability, depending on specific geological parameters. The initiation angle of the elliptical borehole is smaller than that of the circular borehole. The difference gradually decreases with increasing $\sigma_{\rm h}$, which implies that considering the deformation of the boreholes in the calculations yields fracture initiation directions that are closer to the direction of the maximum principal stresses, which is more consistent with the existing experimental results (Heng et al., 2019; Liu et al., 2022).

According to the observations in Figure 6A, the length of both major and minor axes of the elliptical borehole decreases with increasing $\sigma_{\rm H}$. Furthermore, the difference between the major and minor axes' lengths and the deflection angle increases with increasing $\sigma_{\rm H}$. Figure 6B shows that the FIP and initiation angle of both elliptical and circular boreholes increase with increasing $\sigma_{\rm H}$. When $\sigma_{\rm H}$ is less than 43.3 MPa, the FIP of elliptical boreholes is marginally more extensive than that of circular boreholes. However, when $\sigma_{\rm H}$ exceeds 43.3 MPa, the FIP of elliptical boreholes becomes smaller than that of circular boreholes. The initiation angle of



elliptical boreholes is always smaller than that of circular boreholes, and the difference between the two gradually increases with increasing $\sigma_{\rm H}$. A comparison between Figures 5, 6 indicates that an increase in the horizontal stress difference results in an increase in the deflection angle and the initiation angle, as well as a decrease in the FIP, which suggests that the study of the effect of *in situ* stress on borehole deformation and FIP can be simplified to study the impact of horizontal stress differences. However, it is essential to note that it is impossible to establish a direct relationship between the horizontal stress difference and the size of borehole deformation.

4.2 Effect of the bedding inclination angle

The bedding inclination angle (α), defined in this study as the angle between the directions of the bedding plane and the maximum principal stress, was investigated for its effects on borehole deformation and FIP. Figure 7A illustrates that as the α increases, the major axis of the deformed elliptical borehole lengthens. In contrast, the minor axis shortens, and the deflection angle increases and then decreases, reaching a maximum value of 44.33° at 22°. Significantly, there is a distinct alteration of the deflection angle at α when it comes to 22°, signifying a complete exchange of the major and minor axes of the deformation elliptical boreholes. These modifications demonstrate the bedding inclination angle's significant impact on borehole deformation.

It can be seen from Figure 7B that for both elliptical and circular boreholes, the FIPs decrease with increasing α . The difference in FIPs between them first increases and then falls with increasing α , reaching a maximum value of 9.99 MPa at 26°. Based on this observation, we advised choosing formations for field hydraulic fracturing that significantly differ between the directions of the bedding plane and the principal stress to reduce the FIP effectively. Furthermore, the initiation angle for circular boreholes first increases and then decreases as α increases, always resulting in negative values. The maximum initiation angle is approximately 12.4°. However, the initiation

angle for elliptical boreholes follows a wavy distribution. It first increases and then decreases as α increases when α is less than 36°, resulting in positive values. The maximum initiation angle is around 10.44°. When α is greater than 36°, the initiation angle first increases and then decreases, but in this case, it results in negative values. Further analysis reveals that the maximum difference between the initiation angles of circular and elliptical boreholes is approximately 17.25°, which indicates that without considering borehole deformation, there may be a significant error in calculating the initiation angle. Therefore, evaluating the effect of borehole deformation when determining the initiation fracture location in hydraulic fracturing is crucial.

4.3 Effect of the elastic anisotropy

Previous research has shown that alterations in the elastic anisotropy ratio (E_1/E_2) surrounding the borehole result in modifications in the stress distribution around the borehole (Ding et al., 2018). Furthermore, variations in the parameters E1, E2, v12, and v12 in anisotropic materials result in changes in the shear modulus G_2 . The St. Venant relationship elucidates the connection among these parameters above (Espada and Lamas, 2017; Dambly et al., 2019):

$$\frac{1}{G_{12}} = \frac{1}{E_1} + \frac{1}{E_2} + \frac{2\nu_{12}}{E_2}$$
(17)

The influence of elastic anisotropy ratio on borehole deformation and FIP was studied using the Saint-Venant relationship, as shown in Figures 8, 9. In Figure 8, we set E_2 as constant; an increase in E_1/E_2 results in an increase in the major axis length of the deformed elliptical borehole. Additionally, the minor axis length first increases and then decreases, while the difference between the two axes decreases and then increases, reaching its minimum value at E_1/E_2 =1.4. The deflection angle follows a similar pattern, first increasing and decreasing, with the maximum deflection angle occurring at E_1/E_2 =1.15. At this ratio, the deflection angle changed to 90°,

θ(°)	$\sigma_{ heta}$ (MPa)			
	Aadnoy's model	Ge's model	Our proposed model	
			μ ₁₁ =1.01i, μ ₂₂ =0.99i	μ ₁₁ =1.001i, μ ₂₂ =0.999i
0	24	24	23.9994	24.0000
5	24.7195	24.7195	24.7191	24.7195
10	26.8283	26.8283	26.8282	26.8283
15	30.1842	30.1842	30.1845	30.1842
20	34.5734	34.5734	34.5740	34.5734
25	39.7379	39.7379	39.7387	39.7379
30	45.4054	45.4054	45.4060	45.4054
35	51.3134	51.3134	51.3137	51.3134
40	57.2276	57.2276	57.2273	57.2276
45	62.9508	62.9508	62.9502	62.9508
50	68.3265	68.3265	68.3257	68.3265
55	73.2361	73.2361	73.2352	73.2361
60	77.5940	77.5940	77.5932	77.5940
65	81.3413	81.3413	81.3408	81.3413
70	84.4398	84.4398	84.4397	84.4398
75	86.8656	86.8656	86.8659	86.8656
80	88.6051	88.6051	88.6058	88.6051
85	89.6510	89.6510	89.6519	89.6510
90	90.0000	90.0000	90.0010	90.0000

TABLE 1 Comparison of tangential stress on the wall of the elliptical borehole.

indicating a complete exchange of positions between the elliptical major and minor axes. These changes mean the significant influence of the elastic anisotropy ratio on the borehole deformation. The FIP of elliptical and circular boreholes decreases with increasing E_1/E_2 . However, the variation in FIP for elliptical boreholes is significantly higher, at 44.29%, compared to only 15.18% for circular boreholes, which suggests that the influence of E_1/E_2 on deformed elliptical boreholes is more significant and deserves more attention. Furthermore, the difference between FIP for elliptical and circular boreholes initially decreases and then increases with increasing E_1/E_2 . When $E_1/E_2 < 1.1$, the FIP for elliptical boreholes is higher than that for circular boreholes, indicating that a lower elastic anisotropy ratio promotes more excellent stability for circular boreholes after deformation. The initiation angle for circular boreholes increases with increasing E_1/E_2 , reaching a maximum value of approximately 16.99°, which indicates that the fracture initiation directions largely coincide with the direction of the maximum principal stresses. In the case of elliptical boreholes, however, the initiation angle initially increases and then decreases as the E_1/E_2 increases. It is worth noting that for $E_1/E_2 < 1.2$, the initiation angle is about 100°, suggesting that when elastic anisotropy is low, the fracture initiation direction of deformed elliptical boreholes is closer to the direction of minimum principal stress.

In Figure 9, we set E_1 as constant. As E_1/E_2 increase, the length of the major and minor axes of the elliptical borehole increase and decrease, respectively, and the difference between them constantly increases. Furthermore, the deflection angle increases and then decreases, reaching a maximum value of 19.69° at $E_1/E_2=1.45$. However, the total change in the deflection angle is about 6%. Comparing this with Figure 8A, it is clear that there are different distribution patterns in terms of the size of the borehole deformation and the deflection angle. Therefore, we considered that the specific values of E_1 and E_2 are the main factors affecting the borehole deformation, not just the E_1/E_2 . By comparing and analyzing Figure 8B and Figure 9B, we found that the FIP values in both figures are identical when E_1/E_2 is the same, which indicates that when calculating the FIP, only the elastic anisotropy ratio needs to be considered, without specifying the actual values. However, the distribution pattern of the initiation angle differs between the two figures. In Figure 9B, the initiation angle for circular boreholes decreases with increasing E_1/E_2 . In contrast, the initiation angle for elliptical boreholes first increases and then falls, which suggests that the specific values of E_1 and E_2 are essential factors affecting the initiation angle.



4.4 Effect of Poisson's ratio anisotropy

This section investigated the influence of Poisson's ratio anisotropy on borehole deformation and FIP. In Figure 10, we set v_{13} as constant; as v_{12}/v_{13} increases, the major axis length of the borehole increases, while the minor axis length first increases and then decreases, reaching its maximum value at v_{12}/v_{13} =2.45. Furthermore, the deflection angle decreases continuously, with a maximum change of up to 59%. The maximum difference in deformation of the major and minor axes of the elliptical borehole is 0.28 mm. These results indicate that Poisson's ratio anisotropy has minimal influence on the borehole deformation but significantly influences the deflection angle. As shown in Figure 10B, the FIP decreases with increasing v_{12}/v_{13} for both the elliptical and circular boreholes. Furthermore, the difference between them first increases and then decreases, reaching a maximum value of 7.59 MPa at v_{12}/v_{13} =2.7. This observation indicates that high Poisson's ratio anisotropy can reduce the FIP after borehole deformation. Therefore, when conducting hydraulic fracturing in the field, reservoirs with high Poisson's ratio anisotropy could be selected to arrange the boreholes to minimize the FIP effectively. Moreover, the initiation angles of both elliptical and circular boreholes decrease with increasing v_{12}/v_{13} , and the initiation angle of elliptical boreholes is consistently smaller than that of circular boreholes. This finding suggests that borehole deformation brings the direction of fracture initiation closer to the direction of the maximum principal stress, consistent with existing experimental results (Heng et al., 2019; Liu et al., 2022).

In Figure 11, we set v_{12} as a fixed value and observed that as v_{12}/v_{13} increases, the length of the major and minor axes of the elliptical borehole increases and decreases, respectively. The maximum change in size is about 0.06 mm. Additionally, the deflection angle continues to decline. Compared to Figure 10A, it is clear that Poisson's ratio anisotropy ratio has no significant influence on the length of the major and minor axes of the elliptical borehole. However, it does have a notable effect on the deflection angle.

TABLE 2 Basic parameters in MATLAB

Parameters/unit	Numerical value
In situ stress ($\sigma_{\rm H}/\sigma_{\rm h})/{\rm MPa}$	50/30
The tensile strength $(T_{\rm m}/T_{\rm b})/{\rm MPa}$	11.83/5.24
The elastic modulus $(E_1/E_2)/MPa$	7,200/3,600
The Poisson's ratio (v_{12}/v_{13})	0.25/0.2
The shear modulus $(G_{12})/MPa$	1800
the inclination angle of the bedding $\text{plane}(\alpha)/^\circ$	45
the radius of the borehole(R)/mm	108

Nevertheless, we cannot predict the trend of the deflection angle solely based on Poisson's ratio anisotropy ratio trends. Furthermore, the analysis of Figure 10B reveals that as the v_{12}/v_{13} increases, the FIPs of elliptical and circular boreholes decrease. The difference between them initially decreases and then stabilizes. Moreover, the initiation angle of elliptical boreholes decreases while circular boreholes increase, albeit with a more minor change. We compared this to Figure 10B and could predict the FIP trend based on Poisson's anisotropy ratio. However, we could not predict the trend of the initiation angle.

4.5 Effect of strength anisotropy

Based on Equation 5, the strength anisotropy does not affect the borehole deformation but affects the FIP. To examine this effect, we kept the rock material's tensile strength constant while adjusting the bedding plane's tensile strength to achieve varying degrees of anisotropy. Figure 12 illustrates the relationship between the strength anisotropy ratio (T_m/T_b), FIP, and initiation angle for both elliptical and circular boreholes. As Tm/Tb increases, the FIP and angle decrease for both elliptical and circular boreholes. Additionally, the difference in FIPs between elliptical and circular boreholes decreases while the difference in initiation angles increases. Despite their lack of impact on borehole deformation, these findings highlight the significance of considering strength anisotropy in calculating FIPs and initiation angles for deformed elliptical boreholes.

5 Discussion

The analysis of logged data suggests that in layered reservoirs, circular boreholes can be transformed into elliptical boreholes under *in situ* stress (Zoback et al., 2003; Pierdominici et al., 2020; Han et al., 2021). Various researchers have created models to forecast the extent of borehole deformation (Zou et al., 2018; Fang et al., 2022; Han et al., 2023), but these models do not account for the impact of elastic anisotropy in layered reservoirs, which could affect the accuracy of the forecasts (Ma et al., 2019). Our study factors in layered reservoirs' elastic and stress anisotropy (Abdulelah et al., 2018; Qu et al., 2022b; Lu et al., 2022), and develops a model to anticipate the extent of deformation in vertical or horizontal boreholes. By substituting the reservoir parameters into the model, we discover that circular boreholes in layered reservoirs



FIGURE 5

(A) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with $\sigma_{\rm h}$. (B) Variation of the FIP and initiation angle for circular and elliptical boreholes with $\sigma_{\rm h}$.



(A) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with $\sigma_{\rm H}$. (B) Variation of the FIP and initiation angle for circular and elliptical boreholes with $\sigma_{\rm H}$.



FIGURE 7

(A) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with bedding inclination angle. (B) Variation of the FIP and initiation angle for circular and elliptical boreholes with bedding inclination angle.



FIGURE 8

(A) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with E_1/E_2 (E_2 =3.6 GPa). (B) Variation of the FIP and initiation angle for circular and elliptical boreholes with E_1/E_2 .



FIGURE 9

(**A**) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with E_1/E_2 (E_1 =7.2 GPa). (**B**) Variation of the FIP and initiation angle for circular and elliptical boreholes with E_1/E_2 .



FIGURE 10

(A) Variation of the lengths of the major and minor axes and deflection angle for the elliptical borehole with v_{12}/v_{13} (v_{13} =0.2). (B) Variation of the FIP and initiation angle for circular and elliptical boreholes with v_{12}/v_{13} .



and i/nitiation angle for circular and elliptical boreholes with v_{12}/v_{13} .



also transform into elliptical boreholes, which is consistent with previous findings (Zou et al., 2018; Fang et al., 2022; Han et al., 2023). Unexpectedly, our calculations indicate that the major axis direction of the deformed boreholes is incongruent with the direction of the in situ stress, differing from the previous model but aligning more closely with the logging data (Pierdominici et al., 2020), which highlights the superiority of our proposed model.

Using models and logging data, we have demonstrated that circular boreholes deform into elliptical boreholes under the influence of in situ stress and elastic anisotropy. Previous studies have indicated that the change in borehole shape impacts the FIP (Qi et al., 2018; Zheng et al., 2023). Several models have been developed to predict the FIP of elliptical boreholes (Chen et al., 2020; Zhong et al., 2021), but these models do not consider the effect of mechanical anisotropy in layered reservoirs. We have developed an improved FIP prediction model based on the forecasted borehole deformation and validated its accuracy by comparing it with the models of Aadnoy and Angell-olsen (1995) and Ge et al. (2019). Zang et al. (2023) observed, through digital image correlation during SC-CO₂ fracturing in the laboratory, that there is a strain concentration near the borehole before fracturing, which can cause borehole deformation, which suggests that our proposed model can also be used to predict the FIP of bedding shales for hydraulic fracturing in laboratory experiments (Liu et al., 2022). Based on the experimental findings by Liu et al. (2022), we have conducted a comparative analysis of our model and that of Ma et al. (2022). The results indicate a 47.6% enhancement in our model's accuracy, demonstrating our proposed model's advanced capability.

We compared the impacts of in situ stress, bedding inclination, and anisotropy parameters on FIP and initiation angle in circular and elliptical boreholes. Our findings indicate that elliptical boreholes may exhibit higher or lower initiation pressures than circular boreholes, depending on specific geologic parameters, which differs from previous models (Chen et al., 2020; Zhong et al., 2021; Zheng et al., 2023) due to the absence of a relationship between the amount of borehole deformation and FIP in the previous models. Furthermore, our proposed model predicts a deviation angle between the fracture initiation direction and the maximum principal stress direction of no more than 10°. In contrast, the deviation angle in the previous model is significantly larger (Heng et al., 2021; Ma et al., 2022). However, the experimental results demonstrate that the fracture initiation direction in anisotropic rocks aligns closely with the direction of maximum stress (Heng et al., 2019; Liu et al., 2022), highlighting the superior predictive performance of our model in determining the initiation angle.

The model proposed in this study is a two-dimensional model suitable only for horizontal or vertical boreholes. In contrast, inclined boreholes are more commonly encountered in on-site hydraulic fracturing operations (Ma et al., 2022; Zheng et al., 2023). Furthermore, the proposed model solely focuses on the tensile failure mode of the rock matrix. Previous experiments have demonstrated that layered rocks in hydraulic fracturing can exhibit various failure modes, including tensile and shear failure modes of the rock matrix and tensile and shear failure modes of the bedding plane (Li et al., 2018; Heng et al., 2021). Therefore, future research should optimize the proposed model by considering these two aspects to enhance its universality.

6 Conclusion

We formulated a model for predicting the vertical borehole deformation in layered reservoirs and developed a novel model for forecasting fracture initiation pressure (FIP) in hydraulic fracturing based on the expected deformation. We validated the proposed model's accuracy against previous models and experimental data. Furthermore, we examined the impact of *in situ* stress, bedding inclination, and reservoir anisotropic parameters on borehole deformation. We compared FIP and initiation angle changes in undeformed and deformed boreholes under varying conditions. The key findings of our study are summarized as follows.

- 1. The circular vertical boreholes in layered reservoirs change to elliptical due to *in situ* stress, and the major axis of elliptical boreholes deviates from the direction of the maximum principal stress.
- 2. Depending on the specific geological conditions, the borehole deformation can increase or decrease the FIP in hydraulic fracturing. Additionally, alterations in factors such as *in situ* stress, bedding inclination angle, and elastic modulus can result in more pronounced variations in FIP in elliptical boreholes than circular ones.
- 3. The initiation angles of elliptical boreholes are within 10°, which are notably lower when compared to that of circular boreholes, and the alteration in the *in situ* stress, bedding inclination angle, and elastic modulus result in minor modifications in the initiation angles of elliptical boreholes in comparison to those of circular boreholes. The borehole deformations can better explain the fracture propagation in hydraulic fracturing.

Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

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YW: Methodology, Writing-original draft. MW: Investigation, Writing-original draft. ZN: Software, Writing-original draft. ZC: Data curation, Writing-original draft. RM: Formal Analysis, Writing-original draft. JZ: Writing-original draft, Writing-review and editing, Conceptualization, Validation.

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Appendix A

The intrinsic equation, stress equilibrium equation, and strain compatibility equation in the bedding plane coordinate system under generalized plane strain are as follows (Qi et al., 2018).

$$\begin{pmatrix} \varepsilon_{x} \\ \varepsilon_{y} \\ \gamma_{xy} \end{pmatrix} = \begin{pmatrix} \beta_{11} & \beta_{12} & 0 \\ \beta_{12} & \beta_{22} & 0 \\ 0 & 0 & \beta_{33} \end{pmatrix} \begin{pmatrix} \sigma_{x} \\ \sigma_{y} \\ \tau_{xy} \end{pmatrix}$$
(A1)

Where $\beta_{11} = \frac{1}{E_1} - \frac{v_{12}^2}{E_2}$; $\beta_{12} = -\frac{v_{12}(1+v_{32})}{E_2}$; $\beta_{22} = \frac{1}{E_2} - \frac{v_{32}^2}{E_2}$; $\beta_{22} = \frac{1}{G_{12}}$

$$\frac{\partial \sigma_{x}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} = 0; \quad \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{y}}{\partial y} = 0$$
(A2)

$$\frac{\partial^2 \varepsilon_x}{\partial y^2} + \frac{\partial^2 \varepsilon_y}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$
(A3)

Where E_1 and E_2 are the elastic modulus in the directions of x_1 axis, and y_1 -axis, respectively, GPa; G_{12} is the elastic modulus in x_1oy_1 coordinate system, GPa; v_{12} and v_{32} are the Poisson's ratio in the directions of x_1 -axis, and y_1 -axis, respectively.

The stress function F (x, y) was introduced based on Equation (A2) and by substituting it into Equations (A1) and A3 yields (Aadnoy and Chenevert, 1987).

$$\beta_{22}\frac{\partial^4 F}{\partial x^4} + \left(2\beta_{12} + \beta_{33}\right)\frac{\partial^4 F}{\partial x^2 \partial y^2} + \beta_{11}\frac{\partial^4 F}{\partial y^4} = 0 \tag{A4}$$

By introducing linear differential operators $D_k = \partial/\partial y - \mu_k \partial/\partial x$ (k = 1, 2, 3, 4), the fourth-order partial differential equation can be derived, which is entirely equivalent to Equation (A4). Hence, these are the roots of the Eigen equation. $\beta_{11}\mu^4 + (2\beta_{12} + \beta_{12})\mu^2 + \beta_{22} = 0$ (A5)

$$\beta_{11}\mu^{*} + (2\beta_{12} + \beta_{33})\mu^{*} + \beta_{22} = 0 \tag{A5}$$

Equation (A5) has two pairs of conjugate complex roots:

$$z_k = x + \mu_k y, \bar{z}_k = x + \bar{\mu}_k y, (k = 1, 2)$$
(A6)

We expressed the stress function F(x, y) as follows:

$$F = 2\text{Re}[F_1(z_1) + F_2(z_2)]$$
(A7)

where Re is the real part of the complex number, and $F_1(z_1)$ and $F_2(z_2)$ are arbitrary analytic functions of the complex variables z_1 and z_2 . To simplify calculations, we introduced the following functions can be:

$$\varphi_1(z_1) = F'_1(z_1), \varphi_2(z_2) = F'_2(z_2)$$
 (A8)

Substituting Equation (A8) into Equation (A7) and subsequently taking the derivative yields:

$$\begin{cases} \frac{\partial F}{\partial y} = 2\operatorname{Re}\left[\mu_1\varphi_1(z_1) + \mu_2\varphi_2(z_2)\right] \\ \frac{\partial F}{\partial x} = 2\operatorname{Re}\left[\varphi_1(z_1) + \varphi_2(z_2)\right] \end{cases}$$
(A9)

Based on Equation (A9), the stress component in the anisotropic medium can be represented by the analytical function as:

$$\begin{cases} \sigma_{x} = \sigma_{x1} + 2\text{Re}\left[\mu_{1}^{2}\phi_{1}^{\prime}(z_{1}) + \mu_{2}^{2}\phi_{2}^{\prime}(z_{2})\right] \\ \sigma_{y} = \sigma_{y1} + 2\text{Re}\left[\phi_{1}^{\prime}(z_{1}) + \phi_{2}^{\prime}(z_{2})\right] \\ \tau_{xy} = \tau_{xy1} + 2\text{Re}\left[\mu_{1}\phi_{1}^{\prime}(z_{1}) + \mu_{2}\phi_{2}^{\prime}(z_{2})\right] \end{cases}$$
(A10)

Where σ_{x1} and σ_{y1} are the normal stress in the directions of x_1 -axis and y_1 -axis, respectively, MPa.

The stress boundary condition can be determined by the external force p_x and p_y applied as:

$$2\operatorname{Re}[\mu_{1}\varphi_{1}(z_{1}) + \mu_{2}\varphi_{2}(z_{2})] = -\int p_{x}ds$$

$$2\operatorname{Re}[\varphi_{1}(z_{1}) + \varphi_{2}(z_{2})] = \int p_{y}ds$$
(A11)

The equations to express the external forces p_x and p_y can be derived based on the boundary conditions shown in Figure 1 as follows:

$$\begin{cases} p_{x} = \sigma_{x1}R\cos\theta\frac{d\theta}{ds} + \tau_{xy1}R\sin\theta\frac{d\theta}{ds} \\ p_{y} = \tau_{xy1}R\cos\theta\frac{d\theta}{ds} + \sigma_{y1}R\sin\theta\frac{d\theta}{ds} \end{cases}$$
(A12)

Where *R* is the radius of the borehole and the slotting depth, m. Substituting Equation (A12) into Equation (A11) and subsequently making the arc integral yields:

$$\begin{cases} 2\operatorname{Re}[\mu_{1}\varphi_{1}(z_{1}) + \mu_{2}\varphi_{2}(z_{2})] = -\sigma_{x1}R\sin\theta + \tau_{xy1}R\cos\theta\\ 2\operatorname{Re}[\varphi_{1}(z_{1}) + \varphi_{2}(z_{2})] = \tau_{xy1}R\sin\theta - \sigma_{y1}R\cos\theta \end{cases}$$
(A13)

Equation (A13) can be expanded into a Fourier series focusing on θ as follows:

$$\begin{cases} 2\operatorname{Re}[\mu_{1}\varphi_{1}(z_{1}) + \mu_{2}\varphi_{2}(z_{2})] = \sum_{m=1}^{\infty} (a_{m}e^{i\theta m} + \bar{a}_{m}e^{-i\theta m}) = 2\operatorname{Re}\sum_{m=1}^{\infty} (\bar{a}_{m}e^{-i\theta m}) \\ 2\operatorname{Re}[\varphi_{1}(z_{1}) + \varphi_{2}(z_{2})] = \sum_{m=1}^{\infty} (b_{m}e^{i\theta m} + \bar{b}_{m}e^{-i\theta m}) = 2\operatorname{Re}\sum_{m=1}^{\infty} (\bar{b}_{m}e^{-i\theta m}) \end{cases}$$
(A14)

where \mathbf{i} and e are the imaginary unit and natural number, respectively. By comparing Equations (A13) and (A14) one obtains:

$$\begin{cases} \bar{a}_{1} = \frac{(\tau_{xy1} - i\sigma_{x1})R}{2}, \bar{b}_{1} = \frac{(i\tau_{xy1} - \sigma_{y1})R}{2} \\ \bar{a}_{m} = \bar{b}_{m} = 0, m \ge 2 \end{cases}$$
(A15)

To ascertain the analytical function $\varphi_k(z_k)$ (k=1, 2) based on the stress boundary conditions, it is essential to map the circular domain on the complex plane z_k (i.e., the $x_2 o y_2$ plane) to the outer region of the unit circle on the ξ_k plane, with the corresponding mapping function is:

$$z_{k} = \frac{R(1 - i\mu_{k})}{2}\xi_{k} + \frac{R(1 + i\mu_{k})}{2}\frac{1}{\xi_{k}},$$

$$\xi_{k} = \frac{z_{k} + \sqrt{z_{k}^{2} - R^{2}(1 + \mu_{k}^{2})}}{R(1 - i\mu_{k})}, (k = 1, 2)$$
(A16)

Thus, on the borehole wall:

$$z_k = R(\cos\theta + \mu_k \sin\theta), \xi_k = e^{i\theta}, (k=1,2)$$
(A17)

As the distance is augmented, the pressure induced by the surface forces that act on the well wall gradually decreases, the intricate analytical function can be posited as follows:

$$\varphi_k(z_k) = \sum_{m=1}^{\infty} A_{km} \xi_k^{-m} = \sum_{m=1}^{\infty} A_{km} e^{-im\theta}, (k=1,2)$$
(A18)

The specific form of the analytic function can be derived by comparing Equations (A18) and (A16) as:

$$\begin{cases} \varphi_{1}(z_{1}) = \frac{R(\mu_{2}\sigma_{y1} - i\mu_{2}\tau_{xy1} + \tau_{xy1} - i\sigma_{x1})}{2(\mu_{1} - \mu_{2})\xi_{1}} \\ \varphi_{2}(z_{2}) = \frac{R(\mu_{1}\sigma_{y1} - i\mu_{1}\tau_{xy1} + \tau_{xy1} - i\sigma_{x1})}{2(\mu_{2} - \mu_{1})\xi_{2}} \end{cases}$$
(A19)

The deformation of the borehole caused by *in situ* stress can be determined using the intrinsic equation:

$$\begin{cases} u = \beta_{11}\sigma_{x1}x + \beta_{12}\sigma_{y1}x + 2\operatorname{Re}[p_1\varphi_1(z_1) + p_2\varphi_2(z_2)] \\ v = \beta_{12}\sigma_{x1}y + \beta_{22}\sigma_{y1}y + 2\operatorname{Re}[q_1\varphi_1(z_1) + q_2\varphi_2(z_2)] \end{cases}$$
(A20)

where $p_i = \beta_{11}\mu_i^2 + \beta_{12}$, $p_i = (\beta_{12}\mu_i^2 + \beta_{22})/\mu_i$, (i=1,2).

By comparing Equations (A17) and (A19) into Equation (A20) and subsequently simplifying, a specific formula for the displacement yields:

$$\begin{cases} u = \operatorname{Re} \left[\begin{pmatrix} (\beta_{11}(\mu_{1} + \mu_{2} - i\mu_{1}\mu_{2}) + i\beta_{12})\tau_{xy1} \\ + (\beta_{11}\mu_{1}\mu_{2} - \beta_{12})\sigma_{y1} - i\beta_{11}(\mu_{1} + \mu_{2})\sigma_{x1} \end{pmatrix} R(\cos\theta - i\sin\theta) \right] \\ + \beta_{11}\sigma_{x1}R\cos\theta + \beta_{12}\sigma_{y1}R\cos\theta \\ v = \operatorname{Re} \left[\begin{pmatrix} \left(\frac{\beta_{22}(i\mu_{1} + i\mu_{2} + 1))}{\mu_{1}\mu_{2}} - \beta_{12} \right)\tau_{xy1} \\ + \frac{\beta_{22}(\mu_{1} + \mu_{2})}{\mu_{1}\mu_{2}}\sigma_{y1} + i\left(\frac{\beta_{22}}{\mu_{1}\mu_{2}} - \beta_{12}\right)\sigma_{x1} \end{pmatrix} R(\cos\theta - i\sin\theta) \\ + \beta_{12}\sigma_{x1}R\sin\theta + \beta_{22}\sigma_{y1}R\sin\theta \end{cases}$$

(A21)

The relationship satisfied by the two roots of Equation (A5) is as follows:

$$\mu_1^2 + \mu_2^2 = -\frac{2\beta_{12} + \beta_{33}}{\beta_{11}}, \\ \mu_1^2 \mu_2^2 = \frac{\beta_{22}}{\beta_{11}}$$
(A22)

To eliminate the **Re** sign in Eq. 22, one may assume that $\mu_1\mu_2 = -q$, $\mu_1 + \mu_2 = i\sqrt{p+2q}$, and that *p* and *q* are natural numbers (Heng et al., 2021). As a result, Equation (A21) can be simplified to Eq. 2.

Appendix B

The equation for an ellipse is typically represented in the following standard form:

$$\frac{X^2}{a^2} + \frac{Y^2}{b^2} = 1$$
 (B1)

By rotating the coordinate axes of the standard equation by β , the general equation of the ellipse (Eq. 4) can be obtained. The relationship between the corresponding coordinates can be expressed as follows:

$$\begin{cases} X = x_1 \cos \beta + y_1 \sin \beta \\ Y = y_1 \cos \beta - x_1 \sin \beta \end{cases}$$
(B2)

Substituting Eq. (B2) into Eq. (B1) and simplifying yields:

$$\left(\frac{\cos^{2}\beta}{a^{2}} + \frac{\sin^{2}\beta}{b^{2}}\right) x_{1}^{2} + \left(\frac{\sin 2\beta}{a^{2}} - \frac{\sin 2\beta}{b^{2}}\right) x_{1} y_{1}$$

$$+ \left(\frac{\sin^{2}\beta}{a^{2}} + \frac{\cos^{2}\beta}{b^{2}}\right) y_{1}^{2} = 1$$
(B3)

We compared Equations (B3) and (4) yields:

$$\begin{cases} \frac{\cos^2 \beta}{a^2} + \frac{\sin^2 \beta}{b^2} = A\\ \frac{\sin 2\beta}{a^2} - \frac{\sin 2\beta}{b^2} = B\\ \frac{\sin^2 \beta}{a^2} + \frac{\cos^2 \beta}{b^2} = C \end{cases}$$
(B4)

The solution to Eq. (B4) provides the values for the major axis *a*, the minor axis *b*, and the angle β between the directions of the major axis and the x_2 axes of the elliptical borehole. These values are illustrated in Equation 5.

Appendix C

To acquire the flexibility matrix of the medium in the x_3oy_3 coordinate system, we transform on the flexibility matrix in the x_2oy_2 coordinate system as follows (Ma et al., 2022):

$$\begin{bmatrix} C' \end{bmatrix} = \begin{bmatrix} M_{\sigma} \end{bmatrix}^T \begin{bmatrix} C \end{bmatrix} \begin{bmatrix} M_{\sigma} \end{bmatrix}$$
(C1)

where [C] is the flexibility matrix in the x_2oy_2 coordinate system, [C'] is the flexibility matrix in the x_3oy_3 coordinate system, and [M_{σ}] is the bond matrix with the following form:

$$\begin{bmatrix} C' \end{bmatrix} = \begin{pmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{pmatrix}$$
(C2)

$$[M_{\sigma}] = \begin{pmatrix} m^2 & n^2 & 2mn \\ n^2 & m^2 & -2mn \\ -mn & mn & m^2 - n^2 \end{pmatrix}$$
(C3)

where $m = \cos \beta$, and $n = \sin \beta$.

Equation (A5) can be modified in the following form:

$$c_{11}\mu^4 - 2c_{13}\mu^3 + (2c_{12} + c_{33})\mu^2 - 2c_{23}\mu + c_{22} = 0$$
 (C4)

It is typical for the Eigen Equation (C4) to exhibit two pairs of conjugate complex roots denoted as and $\bar{\mu}_{kk}$ (where *k*=1, 2).

The stress equations are derived using the method described in Appendix A, but the stress boundary conditions are changed. We can modify Equation 12 by considering the effects of fracturing fluid injection pressure and *in situ* stress (Zheng et al., 2023).

$$\begin{cases} p_{x} = (\sigma_{x2} - p_{w})b\cos\theta\frac{d\theta}{ds} + \tau_{xy2}a\sin\theta\frac{d\theta}{ds} \\ p_{y} = \tau_{xy2}b\cos\theta\frac{d\theta}{ds} + (\sigma_{y2} - p_{w})a\sin\theta\frac{d\theta}{ds} \end{cases} (C5)$$

Where p_w is the injection pressure of fracturing fluid, MPa.

The final analytical functions obtained from Equation (C5) based on the calculation process in Appendix A are as follows:

$$\begin{cases} \varphi_{1}(z_{1}) = \frac{\mu_{22}(ip_{w}a - i\sigma_{y2}a - \tau_{xy2}b) + p_{w}b - \sigma_{x2}b - i\tau_{xy2}a}{2(\mu_{2} - \mu_{1})\xi_{1}} \\ \varphi_{2}(z_{2}) = \frac{\mu_{11}(ip_{w}a - i\sigma_{y2}a - \tau_{xy2}b) + p_{w}b - \sigma_{x2}b - i\tau_{xy2}a}{2(\mu_{1} - \mu_{2})\xi_{2}} \end{cases}$$
(C6)

Equation 9 can be obtained by taking the derivatives of φ_1 (z_1) and φ_2 (z_2) in Equation (C6) for z_1 and z_2 , respectively.