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## EDITED BY

Lin Jian,  
Ministry of Emergency Management,  
China

## REVIEWED BY

Yidong Lou,  
Wuhan University, China  
Bo Xiong,  
North China Electric Power University,  
China

## \*CORRESPONDENCE

Fuying Zhu,  
✉ fyzhu027@foxmail.com

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# Assessment and analysis of the global ionosphere maps over China based on CMONOC GNSS data

Fuying Zhu<sup>1,2,3\*</sup>, Jian Yang<sup>2,3</sup>, Yun Qing<sup>2,3</sup> and Xinxing Li<sup>2,3</sup>

<sup>1</sup>Electronic Information School, Wuhan University, Wuhan, Hubei, China, <sup>2</sup>Institute of Seismology, China Earthquake Administration, Wuhan, Hebei, China, <sup>3</sup>Key Laboratory of Earthquake Geodesy, China Earthquake Administration, Wuhan, China

The global ionosphere map (GIM) total electron content (TEC) data are extensively employed to statistically study the seismic ionospheric disturbance characteristics. Due to the limitation of spatial coverage of ground-based GNSS receivers, in many regions, the GIM TEC results are obtained by interpolation or extrapolation, and therefore the actual accuracy is different. In this paper, based on the CMONOC GNSS data, a high-precision regional ionospheric map (RIM) model over China is established, and the assessment and analysis of the post-processed IGS GIM over China are conducted. Statistical results show that the average RMS of IGS GIM over China is less than 2 TECu. The comparison of the TEC values calculated by the GIM with the RIM shows that the two models give similar results. The Bias and STD of the difference over most of China is less than 2 TECu except in some low latitude areas. Meanwhile, the correlation between GIM and RIM is better in the daytime than at night, and it is not affected by space electromagnetic disturbance. The assessment results of accuracy in this paper are only applicable to the China region, and the accuracy of other regions needs to be further assessed.

## KEYWORDS

GIM (global ionospheric map), CMONOC, RIM, China, accuracy

## Introduction

The Global Navigation Satellite System (GNSS) has been used as a valuable tool to monitor and estimate ionospheric total electron contents (TECs) (Sardon et al., 1994; Mannucci et al., 1998; Jin et al., 2004; Davies et al., 2016). And analyze the response of the ionospheric to seismic activity (Fujiwara et al., 2004; Liu et al., 2004; Pulinetz et al., 2004; Afraimovich et al., 2008; Liu et al., 2009; Zhao et al., 2010; Heki, 2011; Jin et al., 2015). Since 1998, the International GNSS Service (IGS) has established the Ionosphere Working Group (IWG) (Schaer et al., 1999; Hernández-Pajares et al., 2009) to calculate and model the global ionospheric VTEC data through the data of global satellite observation stations and release the Global Ionosphere Map (GIM) to global users. The IGS GIM, as an important part of GNSS precision products released by IGS, plays an important role in space physics research and satellite navigation applications. In recent years, the IGS GIM become a superset of data to study seismic ionospheric TEC disturbances and a large number of researchers utilize the IGS GIM to conduct studies on ionospheric spatiotemporal variation or earthquake-related ionospheric disturbances (Guo et al., 2005; Le et al., 2011; Zhao et al., 2016; Thomas et al., 2017; Zhu et al., 2018). The analysis of seismic ionospheric disturbance provided a new

breakthrough for the study of earthquake monitoring and prediction (Pulinets et al., 2004; Jin et al., 2015).

China is considered to be one of the countries with the most seismic activities and a dense and continuous GNSS network, the China Crustal Movement Observation Network (CMONOC), has been established, which provides a good condition for the study of ionospheric in China (Cai et al., 2014; Zhe et al., 2017). Considering sharing, coverage, and continuity of the IGS GIMs, the GIMs have been widely used in a large number of seismic studies. The global ionospheric grid products are released by IGS through <ftp://ccids.gsfc.nasa.gov/gnss/products/ionex/> and modeled based on IGS GNSS data, its accuracy depends on the proximity of available GNSS tracking receivers. In addition, some factors such as magnetic storms, solar activities, and local time can also influence the accuracy to a certain extent (Afraimovich and Astafyeva, 2008; Liu et al., 2017). The overall accuracy of the GIM is  $\sim 2\text{--}8$  TECu ( $1 \text{ TECu} = 10^{16} \text{ el/m}^2$ ) (Hernández-Pajares et al., 2009; Roma-Dollase et al., 2018). For the China region, only 3 IGS stations are used and most of the TEC map over China is based on interpolation or extrapolation. Although the GIM offered by different Ionosphere Associate Analysis Centers (IAAC) was frequently assessed and analyzed by some scientists (Lanyi et al., 1988; Xiang et al., 2015; Li et al., 2017; Roma-Dollase et al., 2018; Chen et al., 2019; Zhang and Zhao, 2019; Zhang et al., 2022), and recently a study on accuracy evaluation of global VTEC maps using a simulation technique was conducted (Lin et al., 2022). However, most of the previous studies have focused on accuracy analysis and comparison of different ionospheric models or products from different research institutions worldwide, the actual accuracy of GIM over China region is still not statistically analyzed.

In this paper, in order to examine the actual accuracy of the IGS GIMs over China, we first established high-precision regional ionospheric maps (RIMs) over the China region, and then

conducted the assessment and analysis study by investigating and comparing the IGS GIMs with RIMs. In addition, we also evaluated their correlation them during geomagnetic disturbances.

## Data and method

In this paper, the GNSS data used to calculate TEC over China was provided by the CMONOC, which includes more than 260 continuous GNSS stations and 3 IGS stations. The distribution of these GNSS stations is illustrated in Figure 1, the red pentacles denote the IGS stations. The GIMs are computed based on the IGS network where more than 2,000 ground-based GNSS receivers are distributed worldwide (Schaer et al., 1999; Hernández-Pajares et al., 2009). The IGS has ensured open access, high-quality GNSS data products since 1994 and the GIMs data can be retrieved from the IGS website through the link (<https://igs.org/>). There are twelve analysis centers that generate and deliver long-term GIMs. Different agencies may use different reference frames and techniques to estimate VTEC and differential code biases (DCB). After computation, three validation centers (JPL, ESA, and UPC) combine them into a common IGS GIM, which has a temporal resolution of 2 h and a spatial resolution of  $5.0^\circ \times 2.5^\circ$  in geographic longitude and geographic latitude. More details about the IGS GIM algorithm can be found in related papers (Feltens and Roth, 1998; Hernández-Pajares et al., 2009).

## Model of regional ionospheric map over China

GNSS has been widely employed to monitor variations in the Earth's ionosphere by estimating total electron content (TEC) using

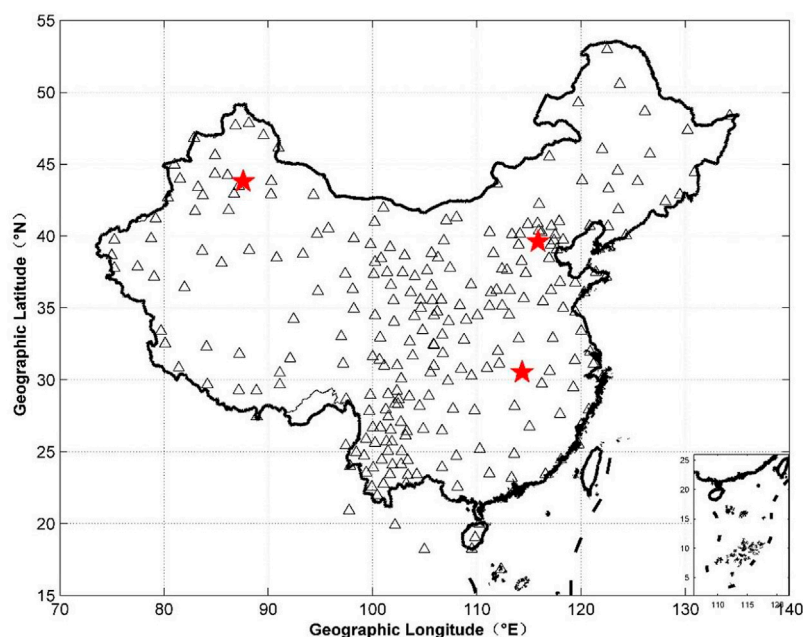


FIGURE 1

The distribution of 260 continuous GNSS stations (triangles) and 3 IGS GNSS stations (red pentacles) in China.

TABLE 1 RIM modeling parameter.

Observation	GPS
Data type	Carrier phase smooth pseudorange
Sampling rate	30 s
Height of ionospheric thin layer	350 km
Mini elevation angle	10°
Earth radius	6371 km
Projection function	MSLM
VTEC function model	Spherical harmonics functions
Order of spherical harmonics function	6-order and 6-degree
Temporal resolution	2 h
Spatial resolution	1°×1°
Coordinate system	Solar geomagnetic coordinate system
The modeling results	RIM + DCB

dual-frequency observations (Mannucci et al., 1998; Schaer, 1999; Jin et al., 2004; Davies and Hartmann, 2016). In this study, we first modeled the RIM VTEC two-dimensional ionospheric maps over the China area. The RIM model in China can be expressed by the Spherical Harmonics as:

$$VTEC(\beta, s) = \sum_{n=0}^{n_{max}} \sum_{m=0}^n \tilde{P}_{nm}(\sin \beta) (\tilde{A}_{nm} \cos ms + \tilde{B}_{nm} \sin ms) \quad (1)$$

Where  $\beta$  is the geomagnetic latitude of IPP (Ionospheric Pierce Point),  $s = \lambda - \lambda_0$  is the solar-fixed longitude of the IPP,  $\lambda$  and  $\lambda_0$  are the longitude of the IPP and the apparent solar time, respectively. Meanwhile,  $\tilde{A}_{nm}$  and  $\tilde{B}_{nm}$  are the estimated unknown parameters for the RIM model, mainly including the ionosphere spherical harmonics function coefficients and the DCBs (Differential Code

Bias) of the GNSS satellites.  $\tilde{P}_{nm}$  is  $n$ th degree and  $m$ th order regularization of the Legendre polynomial. Considering the DCBs of GNSS satellites and ground receivers is also a non-negligible error in ionospheric modeling (Schaer, 1999), therefore, according to Formula 1, the ionosphere sphere harmonic function coefficients and the DCBs of the GNSS satellites are simultaneously estimated from GNSS dual frequency observations by the least squares (LS) method. The specific solution strategy and modeling parameters are shown in Table 1.

Based on the above parameter model, we obtained the ionospheric VTEC maps over the China region (15°–55°N, 70°–140°E), which have a 1 h temporal resolution and a spatial resolution of 1° × 1° in longitude and latitude. As an example, Figure 2 illustrates the spatial distribution of the TEC and RMS of the RIM at 0600 UT on 23 October 2021. It can be clearly seen that the ionospheric TEC RMS over China region is within 1 TECu, and its accuracy gradually decreases from the middle to the north and south sides, which should be related to the spatial distribution of GNSS stations. Especially in the northern border area, the worst accuracy is about 1.4TECu, which is consistent with previous research results (Zhang and Zhao, 2019). At the same time, we also compared the calculated GNSS DCB with the final results of IGS, and the results are shown in Figure 3. The mean value of the difference between them is 0.028 ns, and the maximum deviation is 0.5 ns, which verifies that the RIM model we have established is reliable.

### Assessment method of GIM accuracy

The observation period selected for accuracy assessment in this paper is from 1 September to 30 December 2021. Considering that the ionospheric TEC cannot define an accurate truth value, we consider the RIM results calculated based on the dense COMONOC data as a reference. When assessing the accuracy of GIM, it is generally necessary to check its internal coincidence accuracy and actual accuracy at the same

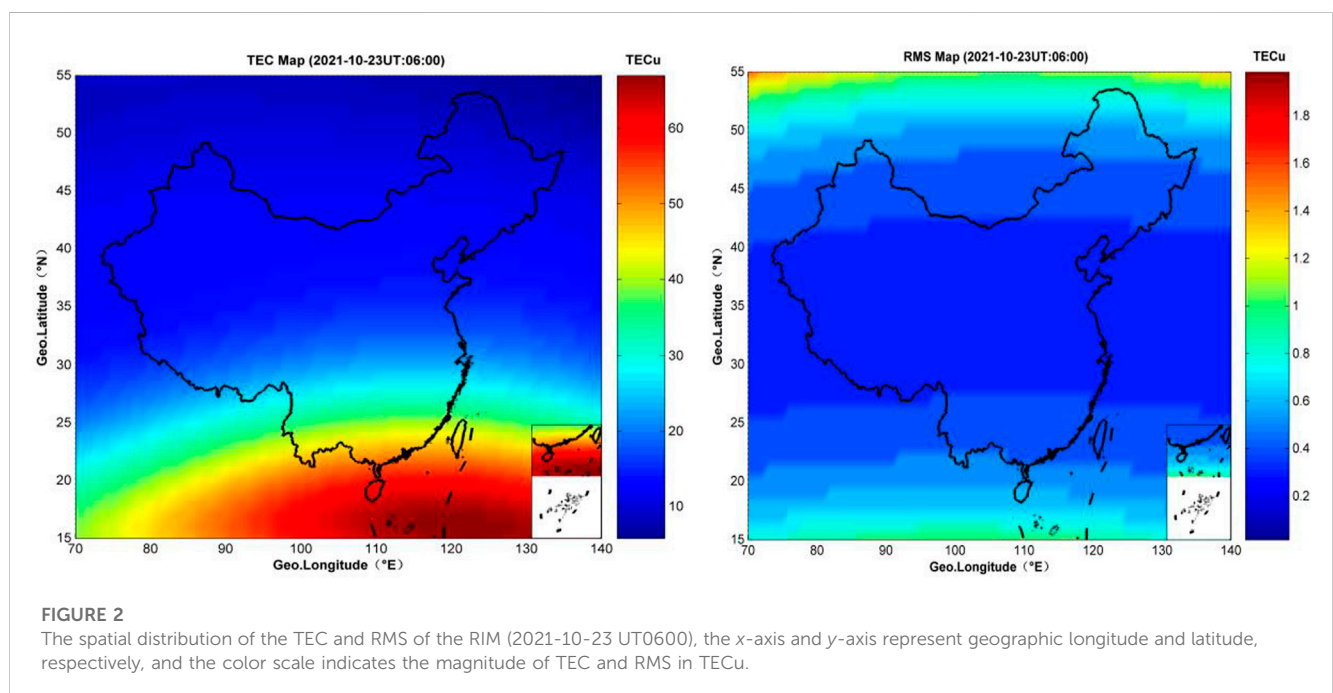


FIGURE 2 The spatial distribution of the TEC and RMS of the RIM (2021-10-23 UT0600), the x-axis and y-axis represent geographic longitude and latitude, respectively, and the color scale indicates the magnitude of TEC and RMS in TECu.

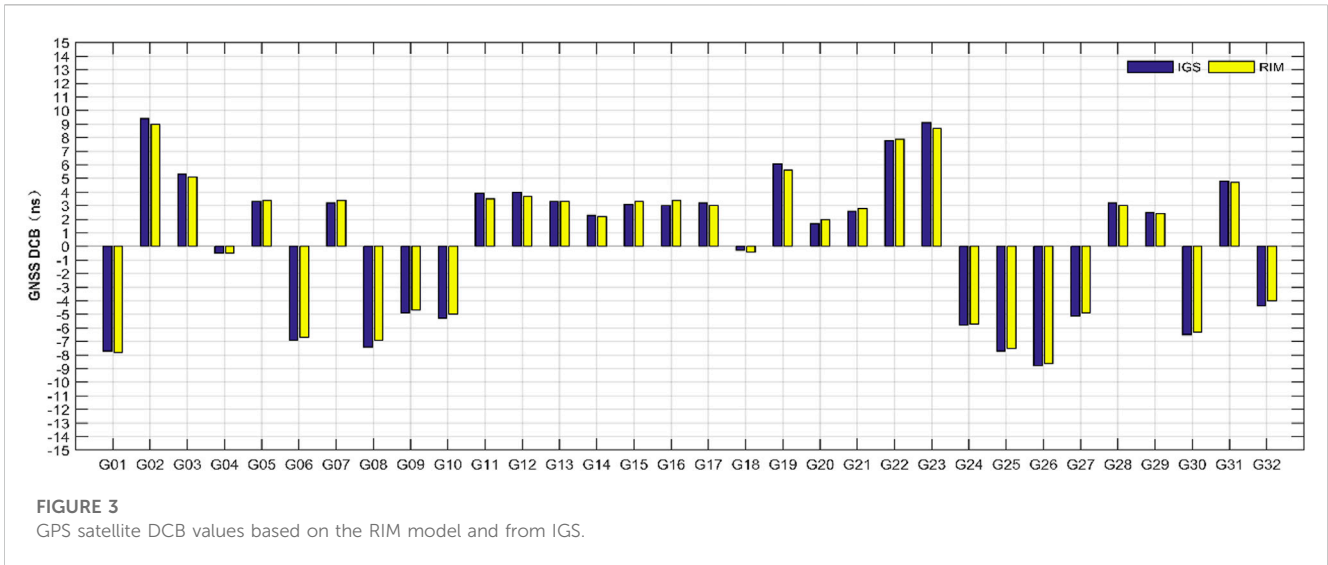


FIGURE 3  
GPS satellite DCB values based on the RIM model and from IGS.

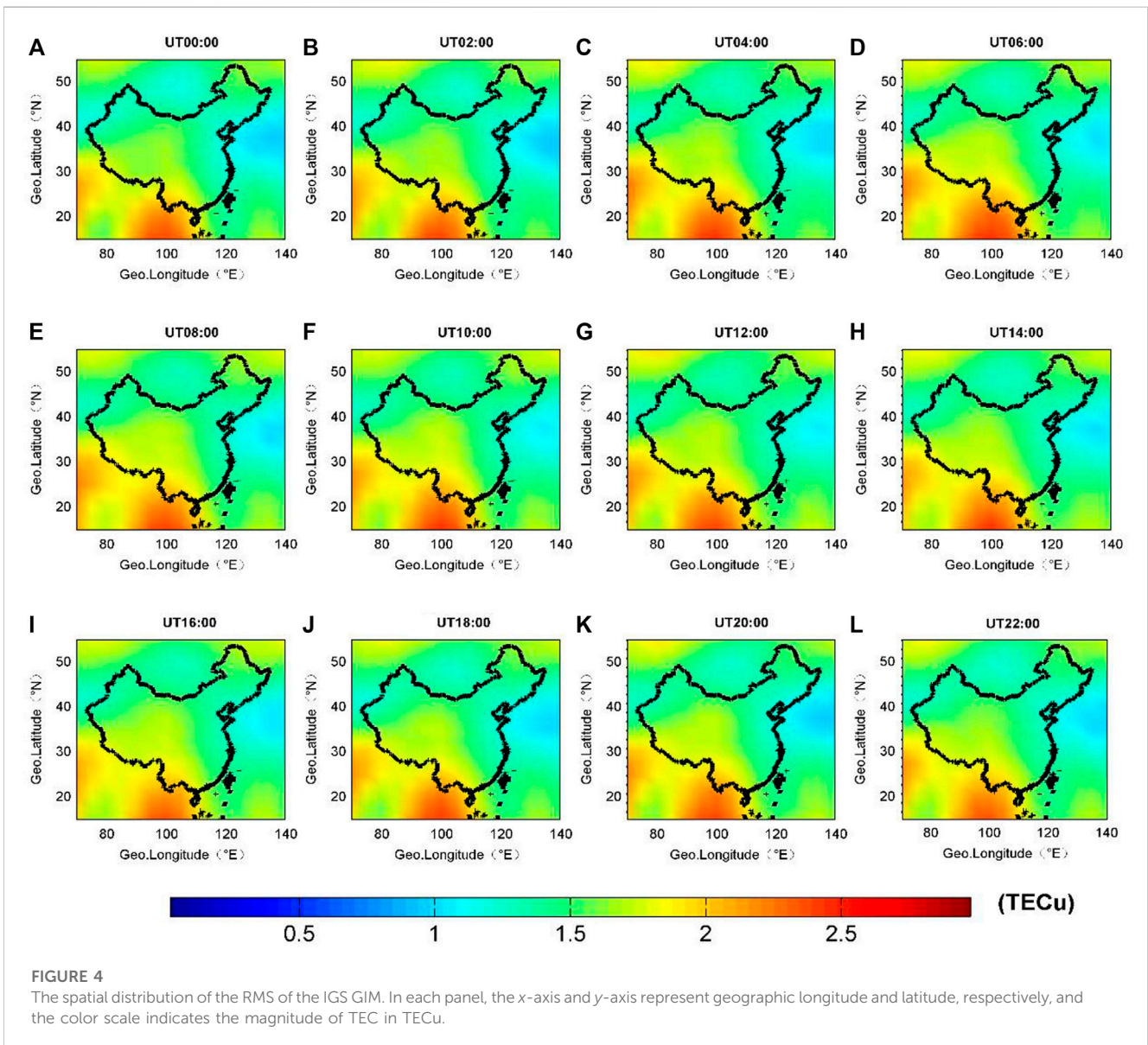
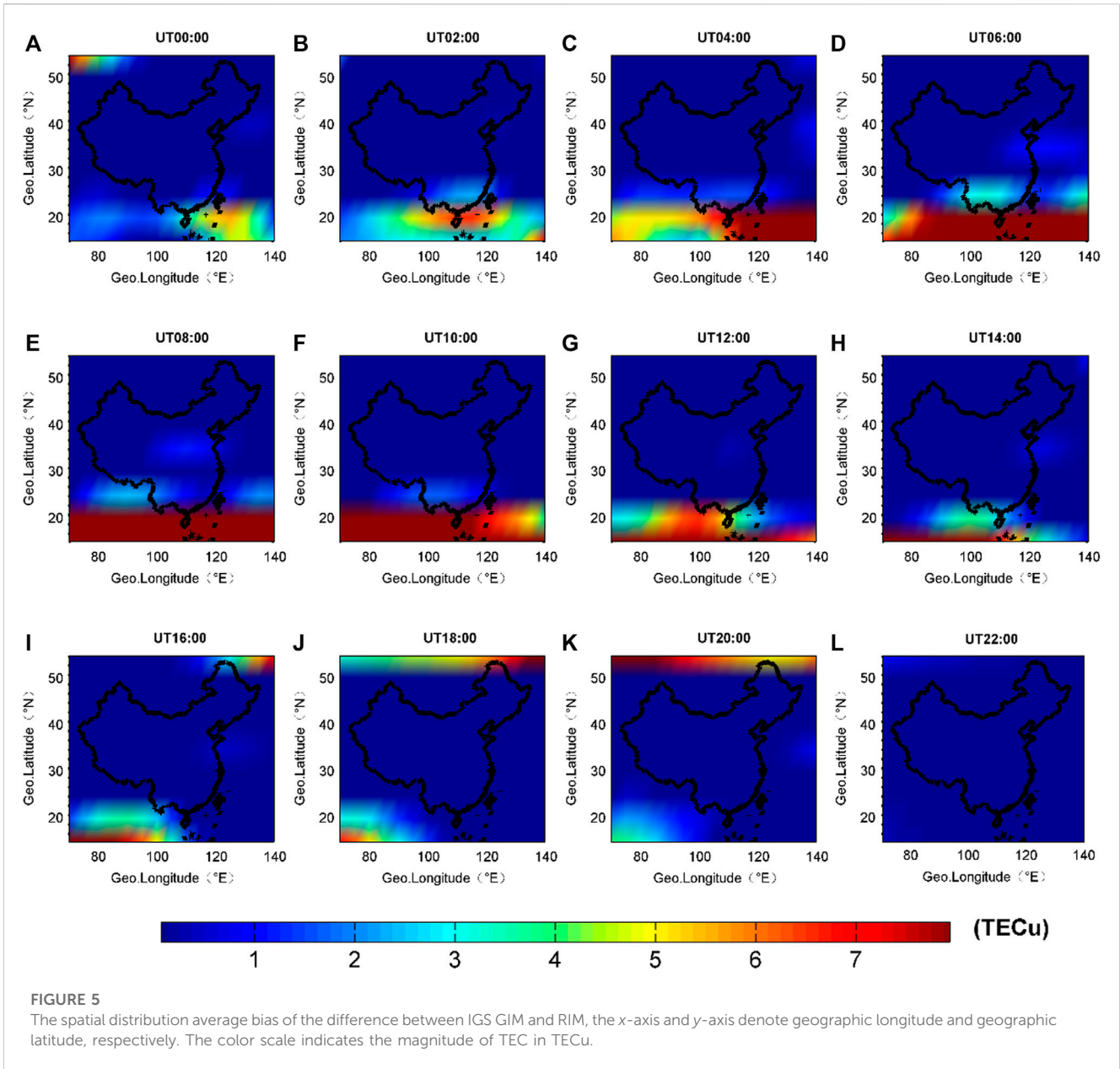


FIGURE 4  
The spatial distribution of the RMS of the IGS GIM. In each panel, the x-axis and y-axis represent geographic longitude and latitude, respectively, and the color scale indicates the magnitude of TEC in TECu.



time (Chen et al., 2019; Zhang and Zhao, 2019; Zhang et al., 2022). In order to clearly demonstrate the spatial-temporal distribution of the IGS GIM accuracy, we first statistically study the internal coincidence accuracy of GIM by calculating the root mean square (RMS) of the GIM over China, where RMS can be expressed as follows:

$$RMS = \sqrt{\sum_{i=1}^N (VTEC_{RIM}^i - VTEC_{obs}^i)^2} / N \quad (2)$$

where N is the epoch number,  $VTEC_{RIM}$  stands for the VTEC value of RIM for each grid point. The ionospheric VTEC value ( $VTEC_{obs}$ ) directly calculated from GNSS satellite observation data is taken as the true value after the difference code deviation is removed, and it is compared with the modeling result ( $VTEC_{RIM}$ ). On the other hand, considering the high accuracy of RIM, in order to check the outside precision of GIM, for each

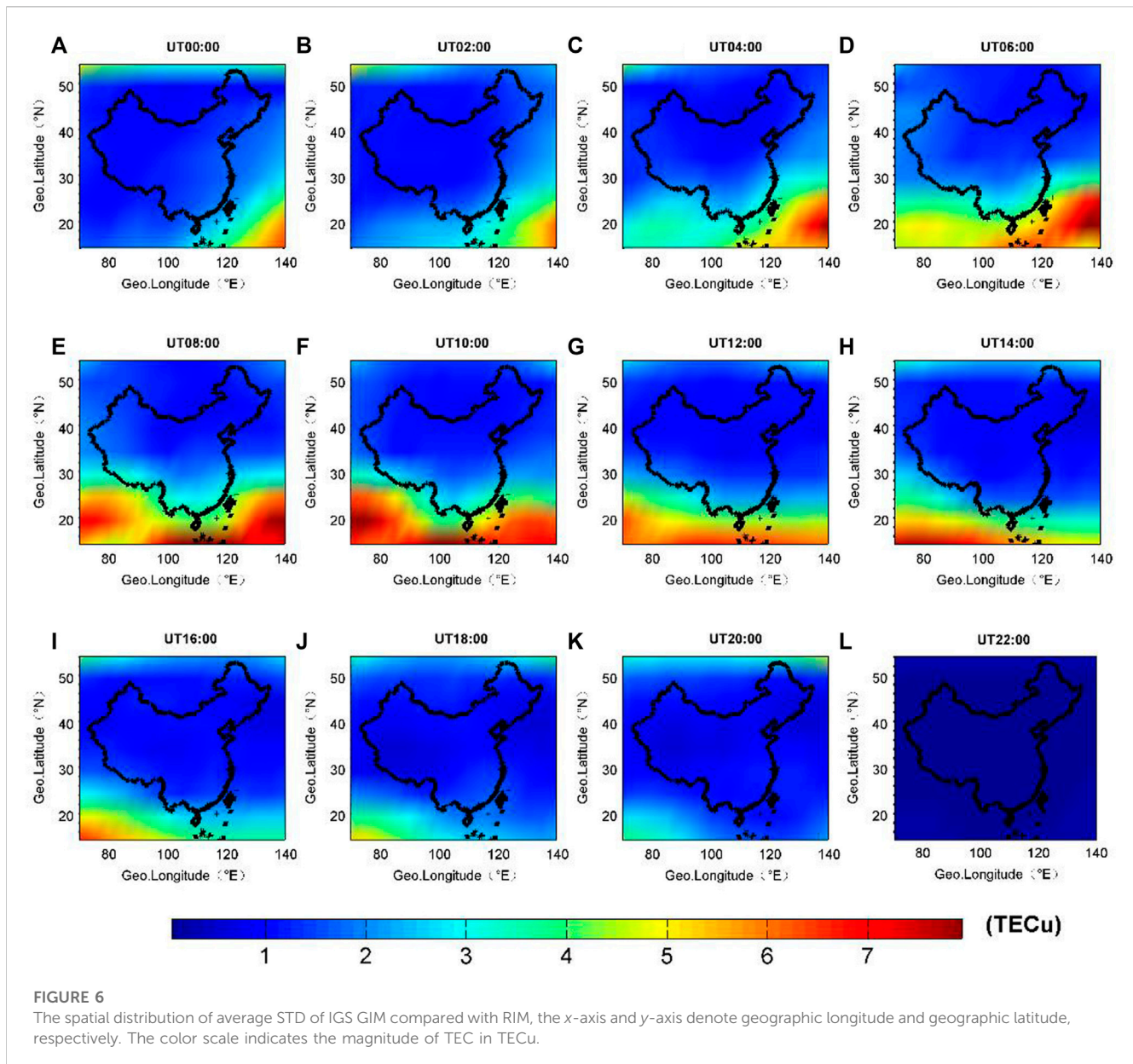
grid point, we also studied in detail the Bias and the standard deviation (STD) of the IGS GIM relative to RIM, where the average Bias and STD are expressed as follows:

$$Bias = \sum_{i=1}^N (VTEC_{GIM}^i - VTEC_{RIM}^i) / N \quad (3)$$

$$STD = \sqrt{\sum_{i=1}^N (VTEC_{GIM}^i - VTEC_{RIM}^i - Bias)^2} / N \quad (4)$$

## Results and discussion

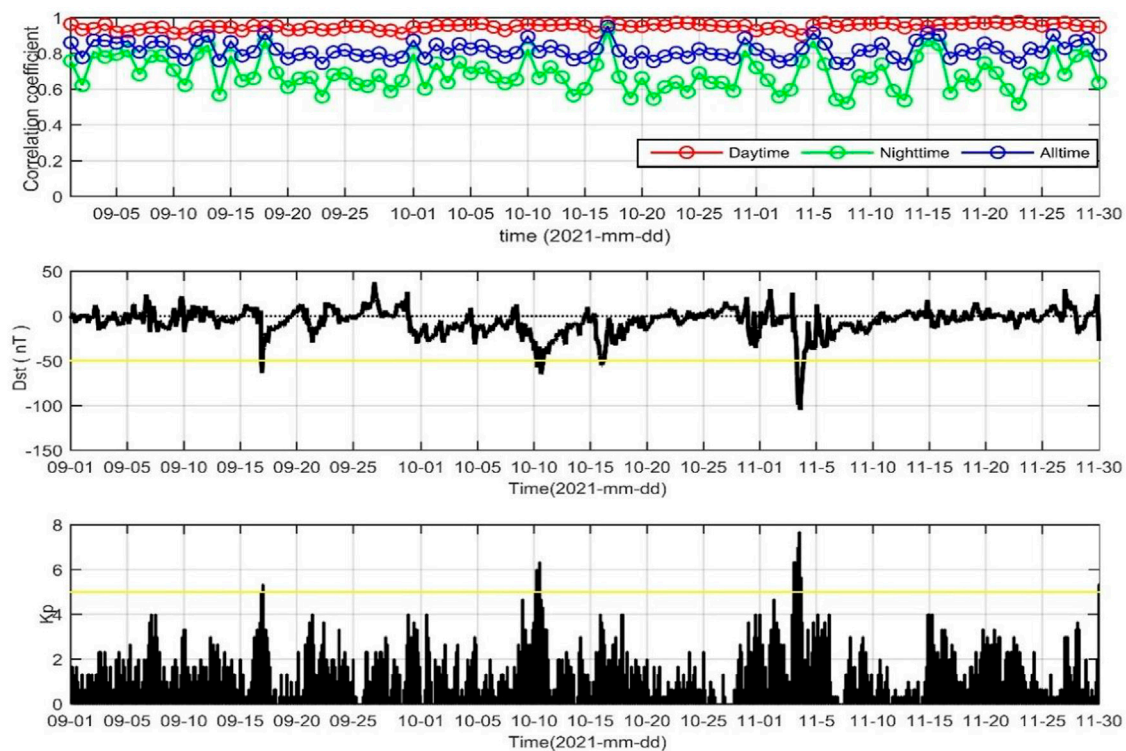
Firstly, we investigated the spatial-temporal characteristics of the GIM RMS over the China area. For the GIM, the RMS values can



be obtained in the GIM files. The scope of our investigation is 15–50°N and 70–140°E. We utilize the RMS values of each grid point at different times from 1 September to 30 November 2021 and then calculate its average. Figure 4 shows the spatial distribution of the average RMS of the IGS GIM. It can be clearly seen that the spatial distribution of RMS values at different times is very similar. The RMS value of most areas is ~2 TECu except for low latitude areas, which is consistent with the previously published conclusion (Zhang and Zhao, 2019). Larger RMS values occur in low-latitude areas outside China's borders (See Figures 4A–L) and the RMS value in the surrounding area of the three IGS stations is relatively small, this is because the VTEC value of the area far from the IGS station is obtained based on interpolation or extrapolation, as the distance from the puncture point increases, its accuracy will inevitably decline.

As we all know, RMS only represents the internal coincidence accuracy of the IGS GIM. In order to effectively assess the true accuracy, we compared IGS GIM with high-precision RIM, and statistically analyzed the average value of Bias at each grid point at each time, as shown in Figures 5A–L. The spatial distribution of ionospheric bias is similar to RMS. That is the average Bias value of most China areas is within 2.5TECu except for some areas. During the daytime, the maximum deviation of GIM appears in the low latitude area near the border of China, and it is distributed in bands (Figures 5C–G). At night, especially at UT1800–UT2000, the maximum bias of GIM appears around 55° N at the northernmost end (See Figures 5J, K), which is also in a zonal distribution.

Figure 6 illustrates the spatial distribution of GIM STD compared with the RIM. From Figures 6A–L, one can see that



**FIGURE 7**

The variations of correlation coefficient and geomagnetic index Dst, Kp from 1 September to 30 November 2021.

the spatial distribution of the average STD is very similar to the spatial distribution characteristics of the average RMS, in other words, the GIM STD of the whole inland region of China is better than 2 TECu. However, the STD value is the largest outside the border region of China, especially in the low-latitude region (See Figures 6E–G). In view of this, the results of pre-seismic ionospheric disturbances found in low-latitude areas in previous studies may need further verification and discussion. Considering that there is almost no GPS observation in the low latitude area, the RIM accuracy of the solution will also be reduced. In addition, the ionospheric activity in the low latitude area is more active, so the accuracy in the low latitude area does not necessarily reflect the actual level of GIM. Therefore, the accuracy level of GIM over China's interior in this paper is more practical.

Finally, in order to investigate whether the accuracy of the IGS GIMs is related to geomagnetic disturbances or not, we also investigated the distribution of correlation coefficients at several points during a geomagnetic disturbance in detail, the coordinates of these investigated five points are (110°E, 10°N), (110°E, 20°N), (110°E, 30°N), (110°E, 40°N), and (110°E, 50°N). It is well known that the accuracy of GIM varies with latitude: In this paper, we statistically investigate the mean value of the correlation coefficient of five points at different latitudes of daytime and nighttime, and finally, the time series of their correlation coefficients are statistically compared. Figure 7 gives the variations of the correlation coefficient and geomagnetic Dst, Kp index from 1 September to 30 November 2021. From Figure 7, we can clearly see that there were significant magnetic disturbances in the space environment on 18 September, 12 October, and 4 November.

However, the correlation coefficient does not change significantly at the above time. This means that the accuracy level of GIM is independent of spatial electromagnetic disturbance. At the same time, we also found that the correlation between the GIM and RIM was significantly higher during the daytime than at nighttime.

Considering the IGS GIMs are interpolated in both space and time and the used GNSS receiver is very sparse in the China region, we checked and assessed the actual accuracy of the IGS GIM over the China region. With the increasing number of global GNSS continuous observation stations, the precision and reliability of IGS GIM are getting higher and higher. Although the IGS GIM calculation only uses three GNSS observation data in the China region, the GIM TEC results over China are generally reliable, but in some low latitude regions, the difference is relatively larger. That is because, on the one hand, the external low-latitude regions in China lack any observation data, and the accuracy of ionospheric RIM calculated in this area is not high. On the other hand, near the equator, the ionosphere changes are more responsible. If only the inland areas of China are investigated, the actual accuracy of GIM will be much higher. Therefore, we suggest that the accuracy level of GIM TEC may be further improved by adding more station observations to areas with sparse observation data.

## Conclusion

This paper presents a statistical work to assess and analyze the IGS GIM over the China region. High-precision RIMs are calculated based on the dense COMONC GNSS observation and used as reference values.

The major findings presented herein are summarized as follows: the accuracy of the IGS GIM over the China area is investigated and compared. The Bias and STD of the difference between the GIM and the RIM over China are less than 2 TECu except for some low latitude areas. Meanwhile, the correlation between GIM and RIM is better in the daytime than at night, and it is not affected by space electromagnetic disturbance. The results in this paper support the precision description given by IGS and verify the accuracy of GIM, which maybe have important reference significance for the application of GIMs over China.

This paper mainly only gives some statistical results about China regions which confirmed partly the actual accuracy of the IGS GIM, however, it does not represent the actual accuracy of other regions in the world. In order to better study the temporal and spatial variation characteristics of the ionosphere, it is necessary to conduct a more comprehensive and detailed assessment and analysis of the GIM in the future.

## Data availability statement

The dataset supporting the conclusion of this article will be made available by the authors upon request, without undue reservation.

## Author contributions

FZ conceptualized the research, conducted analysis, and drafted the manuscript. JY processed the GNSS data, YQ contributed to language editing and gave valuable comments on the manuscript, and XL reviewed the manuscript. All authors read and critically reviewed the manuscript for publication.

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## Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

The reviewer YL declared a shared affiliation with the author FZ to the handling editor at the time of review.

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