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# Daily runoff and its potential error sources reconstructed using individual satellite hydrological variables at the basin upstream

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Basin-scale hydropower operation and water resource allocation rely on *in situ* river discharge measured at a river mouth, which is referred to as runoff. Due to labor intensiveness and tight financial constraints, satellite hydrological variables have been advocated for reconstructing monthly runoff *via* regressing with nearby measured monthly river discharge over the past two decades. Nevertheless, daily runoff reconstruction by regressing with upstream satellite hydrological variables on a daily scale has yet to be examined. A data standardization approach is proposed for daily runoff reconstructed using satellite hydrological data upstream of the Mekong Basin. It was found that the accuracy of reconstructed and predicted daily runoff against *in situ* runoff was substantially increased, in particular, the troughs (peaks) during dry (wet) seasons, respectively, when compared to that of the direct linear regression. The backwater impact on the runoff accuracy is negligible after standardization, implying the possibility of choosing the basin exit at the entrance of the river delta. Results generated from the data standardization *via* neural network-based models do not improve consistently or even a bit worse than that of the linear regression. The best forecasted runoff, yielding the lowest relative error of 8.6%, was obtained from the upstream standardized water storage index. Detrended cross-correlation analysis indicated that the reconstructed and forecasted runoff from the data standardization yielded a cross-correlation larger than 0.8 against *in situ* data within most window sizes. Further improvement lies in the methodology for mitigating the influence due to climate variability and extreme events.

## KEYWORDS

daily runoff estimate, Mekong Basin, GRACE water storage, GPM-TRMM precipitation, ENSO

## 1 Introduction

Basin-scale water allocation and management require *in situ* discharge time series measured at a river mouth, which is termed runoff when divided by the basin area. Its recorded extreme values are useful for predicting hazards that potentially occur around nearby-affected regions. The declining number of global discharge stations has promoted the usage of remotely sensed (RS) data products for discharge reconstruction since the 1990s (Sneeuw et al., 2014), owing to its near-global coverage.

Localized passive RS data, such as vegetation index, temperature (Yue et al., 2007), estuary dimension (Smith, 1997; Gleason and Smith, 2014), and flood extent mapping (Pan and Nichols, 2013), correlate nearby discharge data directly. Nonetheless, the weaknesses of these localized passive RS data are 1) unevenly sampled with a low temporal resolution, 2) susceptible to land surface materials, and 3) no direct causation with discharge data. As a result, satellite hydrological variables (e.g., precipitation) having evenly sampled on a daily basis with direct causation to discharge are more suitable than the localized passive RS data in reconstructing discharge at a basin scale.

Precipitation, stage, and water storage are the hydrological variables that can be calculated from the Global Precipitation Measurement–Tropical Rainfall Measurement Mission (GPM-TRMM) and its follow-on satellite (Huffman et al., 2007) and satellite altimetry (Frappart et al., 2006) and gravimetry (Wahr et al., 2004), respectively. For instance, the GPM-TRMM recorded monthly precipitation has been utilized for hydrologic prediction (Su et al., 2008; He et al., 2018), hydrologic extremes (Harris et al., 2007; Naumann et al., 2012; Mutuga et al., 2014; Tekeli and Fouli, 2016) and their climatic variabilities (Yan et al., 2020), and *in situ* precipitation assessment (Li et al., 2013; Yan et al., 2014; Tao et al., 2016). Nonetheless, the potential usage of daily GPM-TRMM precipitation data is yet to be explored (Su et al., 2011; Shirmohammadi-Aliakbarhani and Akbari, 2020), let alone its potential for reconstructing daily runoff time series.

Stage and water storage time series are, respectively, recorded by satellite altimetry (e.g., Sentinel, Envisat, and Jason-3) and gravimetry [e.g., gravity recovery and climate experiment (GRACE)]. This altimetric-derived stage has been utilized to monitor inland water surface in small rivers in Indonesia (Sulistioadi et al., 2015), global lakes (Calmant et al., 2008), and Mekong Basin (MB)'s reservoirs (Liu et al., 2016). A power function fitting of the altimetric-derived stage with the *in-situ* runoff (Beven, 2001; Tourian et al., 2013) allows runoff reconstruction (Birkinshaw et al., 2010). A similar procedure applies to runoff relating to basin-averaged monthly water storage (Riegger and Tourian, 2014; Sproles et al., 2015). Runoff can also be determined through the water balance equation, with precipitation and evapotranspiration given (Syed et al., 2009; Chen et al., 2019). However, the potential

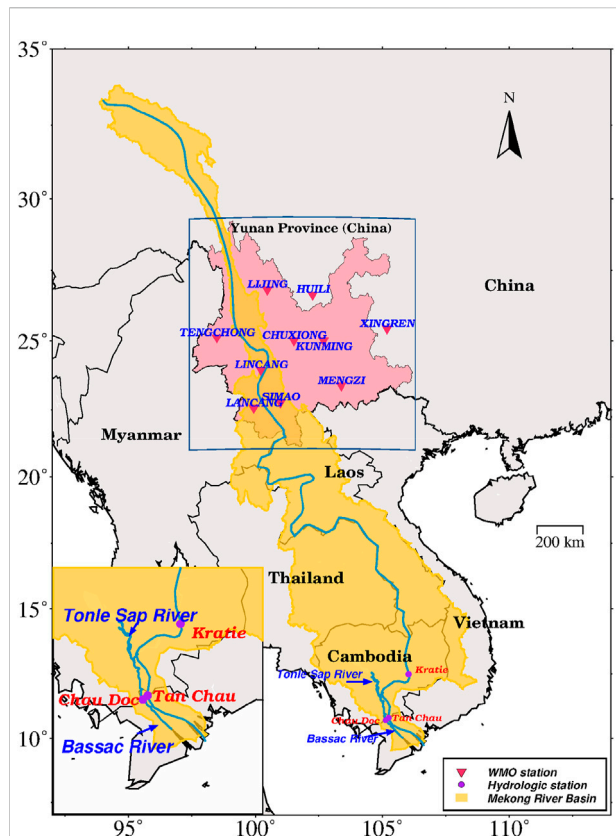
usage of daily GRACE water storage data relating to daily runoff remains elusive. It is of note that unless data assimilation has been considered, direct daily GRACE data generation is not feasible without the tradeoff between spatial and temporal resolution.

In general, there are three types of hydrological models: conceptual models [e.g., Hydrologiska Byråns Vattenavdelning (HBV) model (Grillakis et al., 2010) and topography-based hydrological model (TOPMODEL) (Beven et al., 1984)], physically-based models [e.g., MIKE Système Hydrologique Européen (SHE) (Singh et al., 1999) and Soil and Water Assessment Tool (SWAT) (Easton et al., 2010)], and empirical models [e.g., linear regression, hydraulic functions, time series model, and neural network-based (NNB) model (Wang et al., 2009)]. The first two types of hydrological models require a significant amount of data within the basin, including runoff, precipitation, digital elevation model, drainage locations, and soil moisture, to mention a few (Devia et al., 2015). They are also computationally expensive (Reggiani and Rientjes, 2005). Several iterations are needed to get the parameters fine-tuned. Therefore, the empirical models are more suitable in hydrological practice due to their simplicity that is derived from input (e.g., precipitation and water storage) and output (e.g., runoff) time series only. The linear regression and hydraulic functions for reconstructing runoff have been described earlier. For instance, the *in-situ* runoff relates to GPM-TRMM precipitation data *via* linear regression (Zhou et al., 2019), whereas *in situ* runoff relates to the monthly basin-averaged water storage (or stage) *via* a hydraulic functional fitting (e.g., the power function) (Riegger and Tourian, 2014; Sproles et al., 2015).

Time series and NNB models are also ubiquitously employed. NNB model always generates a more accurate forecasted discharge than that from other methods (Wang et al., 2009). Nevertheless, most studies employing time series and NNB models used the *in-situ* discharge data as input rather than RS data or satellite hydrologic variables. Furthermore, data containing potential biases are not considered in advance while directly input into the model in different orders to train various numerical results. Hence, a method that generates a unique numerical result with a potential reduction of hidden biases is highly desirable.

Data standardization is a technique to detect hidden biases by subtracting the raw time series from the averaged one (Jones and Hulme, 1996; Ferreira et al., 2018). The regression between two standardized data variables should reduce potentially-hidden biases partially, in particular, in extreme conditions (Fok and He, 2018). This method is utilized in this research.

The reconstructed and forecasted runoff based on data standardization is expected to reduce the discrepancies of the peak and trough values against the *in-situ* one in this study. This is because a cascade effect is generated due to all artificial reservoir operations along the basin that distorts the *in-situ* runoff on a seasonal basis (Räsänen et al., 2017). This was



**FIGURE 1**  
The Mekong Basin (yellow area) overlaying Yunnan, China (pink area), with World Meteorological Organization (WMO) meteorological stations (red triangle) along with hydrologic stations within the river delta (purple dot).

found to be systematic for each season every year (Hecht et al., 2019). Hence, this effect can be partly reduced by data standardization, highlighting potential biases for a particular data time period (Fok and He, 2018). Notably, most reliable satellite hydrological variables were available only after 2002, in particular, GRACE water storage, avoiding the necessity for comparing the changes of reconstructed runoff before and after that time.

Given the presence of a time-lagged relationship between the upstream hydrological variables and the downstream water level (Biancamaria et al., 2011) and/or runoff (Hirpa et al., 2013), this study aims at regressing standardized satellite hydrological variables obtained at the MB upstream with the standardized *in situ* runoff on a daily scale. To demonstrate the improvement of the proposed approach, their accuracies are compared with the results generated from the direct linear regression and the NNB models. Comparison between the runoff reconstructed at and far away from the estuary also allows us to assess the backwater impact on reconstructing and forecasting runoff. Our results are finally compared with the

best published daily (Tourian et al., 2017) relative error in the recent literature.

## 2 Study area

Across different latitudes, Mekong Basin is separated into upstream (i.e., Lancang river in China) and downstream (i.e., exit at Jinghong to river delta) (Figure 1) with distinct climate zones. Yunnan province appears as an important transition between upstream and downstream that shares a similar wet season driven by the Indian monsoon to that of the downstream (Colin et al., 2010; Tang et al., 2014). Climate variability [e.g., El Niño Southern Oscillation (ENSO)] abruptly alter the spatiotemporal precipitation pattern for the entire basin, consequently affecting the amount of runoff discharged into the ocean (Xue et al., 2011; Räsänen and Kumm, 2013).

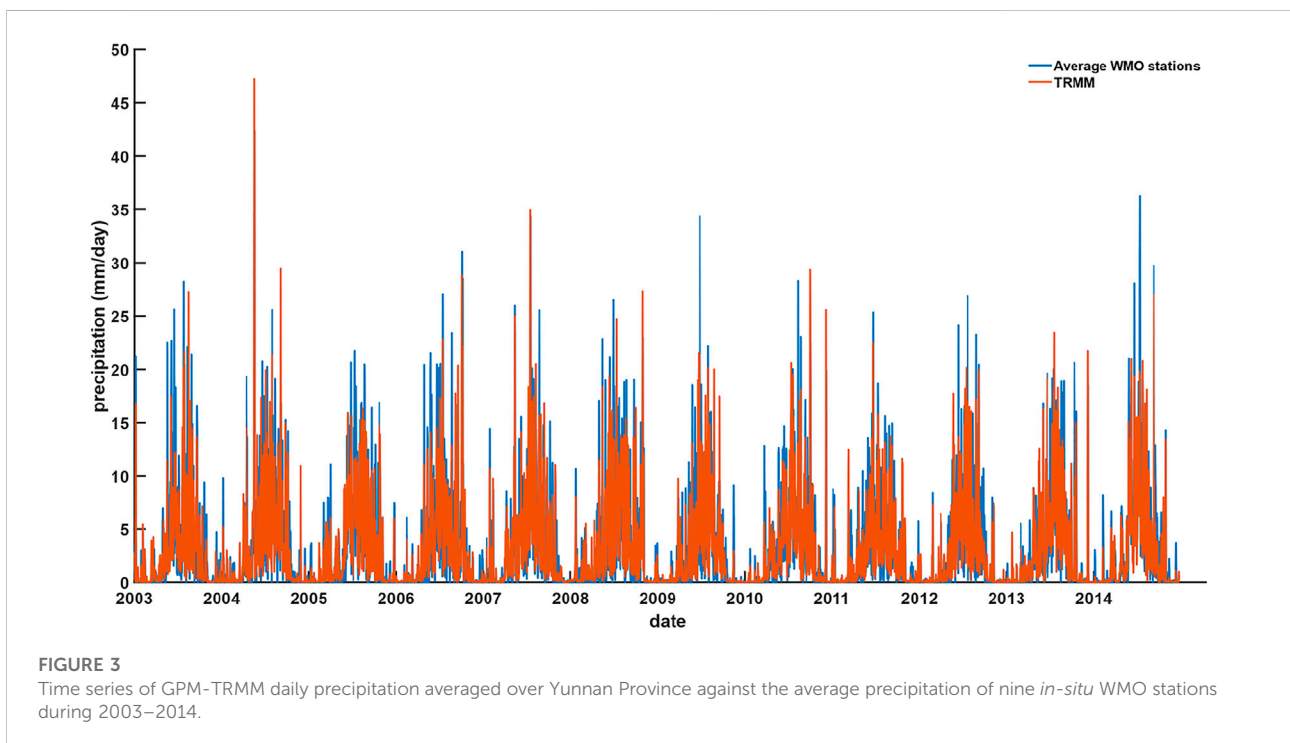
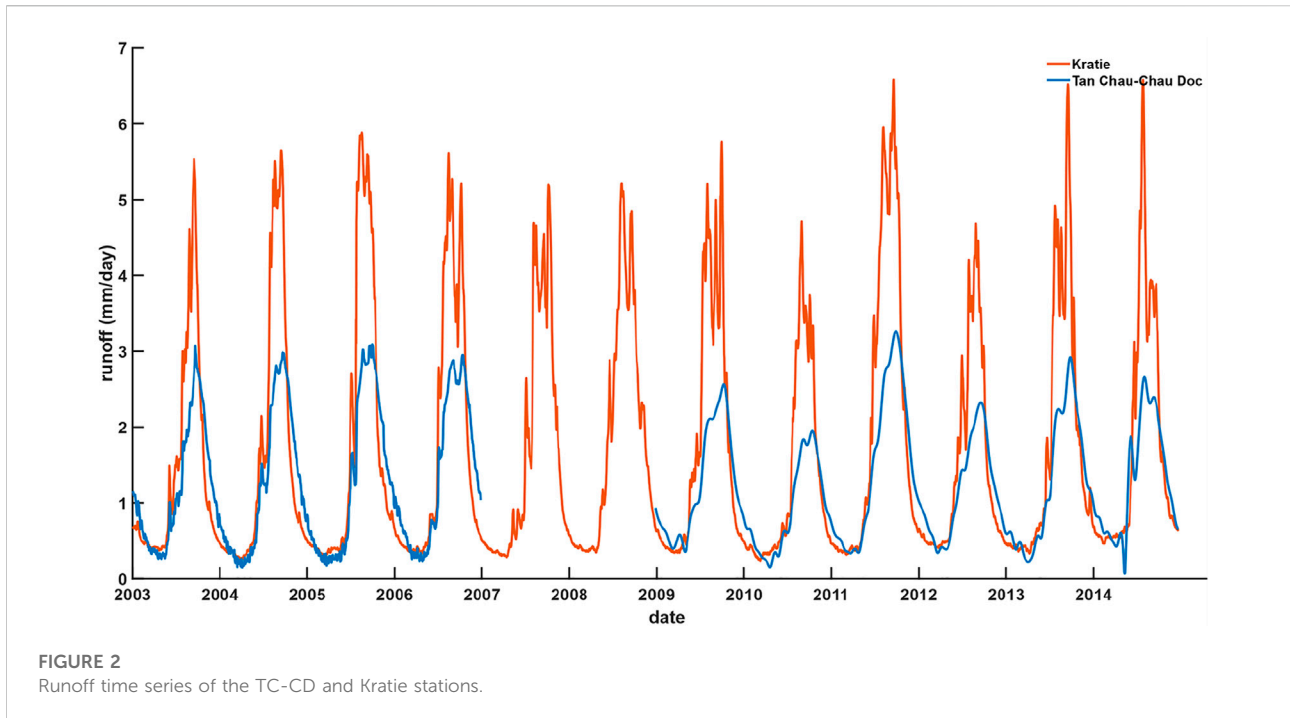
The natural settings of the basin are also critical to runoff temporal variability. For instance, Tonle Sap Lake, as a natural reservoir, provides storage water discharged into the ocean during the dry season (Chang et al., 2020) while storing water itself during the wet season. In addition, the backwater from the ocean substantially contaminates the pure hydrological signals of the water level and runoff measured at Mekong estuary channels (Peng et al., 2020).

The artificial settings of the basin are attributed to human activities. These activities, including dam operation, dikes construction, groundwater extraction, and sand mining (Loc et al., 2021), also speed up the backwater from the ocean (Eslami et al., 2019). Among all these activities, dam operation is the main reason for the apparent shift of the long-term seasonal runoff before and after 2002, owing to a drastic increase in dam construction during the 1990s (Cochrane et al., 2014; Lu et al., 2014; Li et al., 2017).

## 3 Data

### 3.1 *In situ* discharge and precipitation data

Three *in situ* discharge gauge stations (i.e., Tan Chau, Chau Doc, and Kratie), bought from the website of Mekong River Commission at <http://www.mrcmekong.org>, were employed in this study. Stations located at different distances from the estuary mouth allow an assessment of the ocean tidal backwater effect. Tan Chau and Chau Doc stations are located at Tien River and Han River, respectively, whereas Kratie station is located at the main stream. Tan Chau and Chau Doc (called TC-CD hereinafter) stations' time series were added up correspondingly so as to approximate the basin runoff. It is of note that the Butterworth filter was used to suppress short-period ocean tidal signals (e.g., diurnal or semidiurnal) for the TC-CD



time series (Peng et al., 2020) in order to minimize the tidal backwater effect in the river delta (Arias et al., 2012; Gugliotta et al., 2019). To generate daily discharge of the TC-CD station (in

the unit of millimeters per day), the daily TC-CD discharge (in the unit of cubic meters per second) is divided by the total basin area. No pre-processing step was applied to the Kratie station

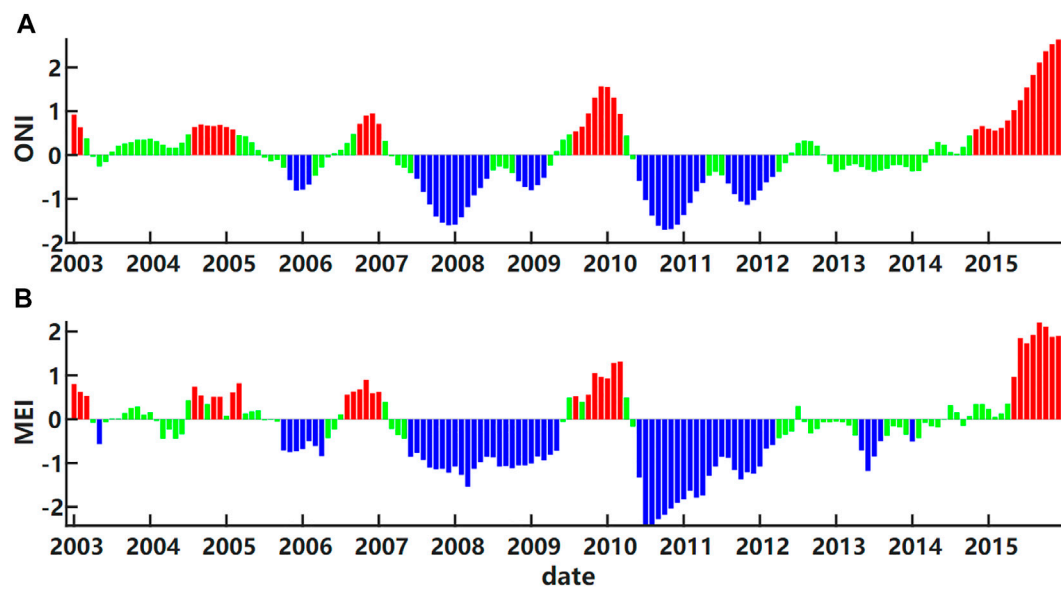


FIGURE 4

The (A) Oceanic Niño Index and (B) Multivariate ENSO Index time series, indicating the neutral (green bar), La Niña (blue bar), and El Niño (red bar) events.

time series, except for the dividing basin area excluding the Cambodia plain.

Daily runoff time series for the Kratie and TC-CD stations are displayed, with highly unstable maximum and minimum values from 2009 to 2014 (Figure 2). It is of note that the TC-CD time series is not continuous due to instrument upgrades during 2007–2008. Therefore, the daily runoff and the satellite hydrological variables were consistently used for time lag determination during 2003–2006, while used for the reconstruction (forecast) during 2009–2012 (2013–2014), respectively.

Nine *in situ* precipitation data, obtained from World Meteorological Organization (WMO) stations available at <https://www.ncei.noaa.gov/maps/daily/>, were averaged over Yunnan to evaluate the precipitation data from GPM-TRMM. No apparent offset was observed; therefore, no calibration is required in this study (Figure 3). It was found that the averaged *in situ* precipitation data against that of GPM-TRMM quantitatively revealed a good consistency, with a Pearson correlation coefficient of 0.695 and an RMS error of 3.53 mm/day.

### 3.2 Two satellite hydrological variables

Daily precipitation time series map gridded at  $0.25^\circ \times 0.25^\circ$  during 1998–2014 was produced from version 7 3B42 of GPM-TRMM multi-satellite precipitation analysis datasets, available at <https://disc.gsfc.nasa.gov/>. *In situ* precipitation from the Global

Precipitation Climatology Center have been partly used to calibrate these data worldwide (Huffman et al., 2007). Daily Stokes's coefficients with nearly  $4.5^\circ \times 4.5^\circ$  grid resolution during 2003–2014 calculated by the Institute of Geodesy at Graz University of Technology (IGGUT) (Kvas et al., 2019) was available at <http://icgem.gfz-potsdam.de/series>. These data were employed in this study.

### 3.3 ENSO index

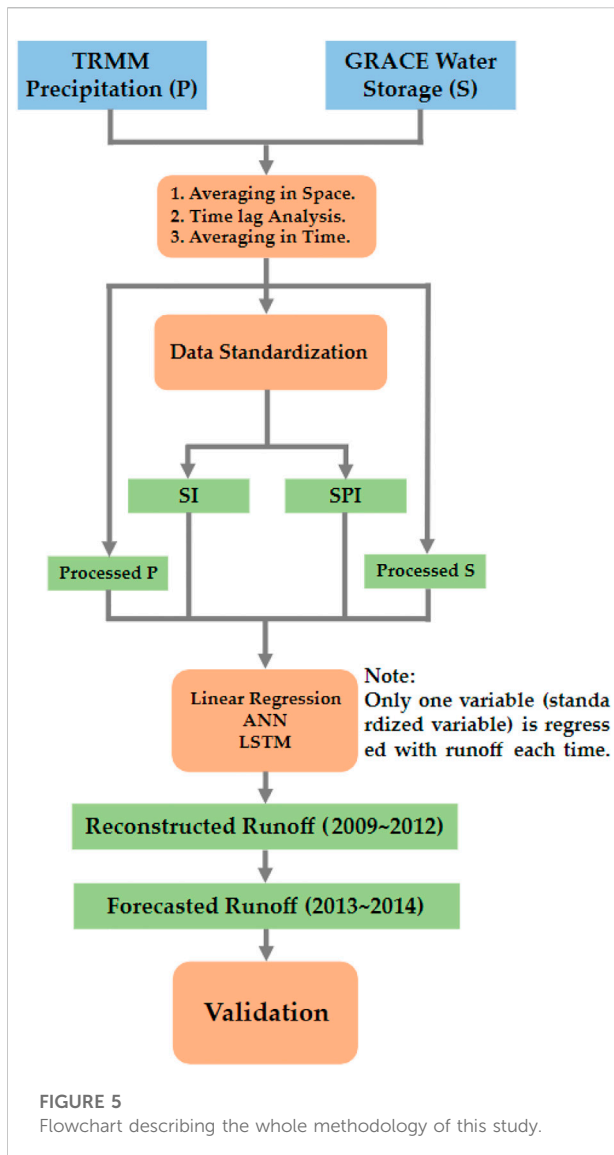
ENSO events cause hydrological extremes in the Mekong Basin (Räsänen and Kummu, 2013). The warm (cold) phase representing El Niño (La Niña) can be distinguished by pressure difference and sea surface temperature anomalies (Kiem and Franks, 2001). Oceanic Niño Index and Multivariate ENSO Index, available at <https://www.esrl.noaa.gov/psd/data/climateindices/list/>, were served to qualitatively examine whether the indices were correlated substantially with the runoff, especially for the extended La Niña duration during 2010–2011 (Figure 4).

## 4 Methodology

### 4.1 Overview

Figure 5 describes the flow of the methodology, which includes: 1) post-processing steps (i.e., spatial averaging over Yunnan, time lag analysis, and temporal averaging process); 2)





data standardization; 3) reconstructed and forecasted runoff *via* linear regression and NNB models; and 4) validation.

## 4.2 Data pre- and post-processing

While no data preprocessing for GPM-TRMM daily data is required, GRACE daily data preprocessing is needed. The GPM-TRMM daily data are resampled at  $1^\circ \times 1^\circ$ . The daily geocenter time series datasets generated from IGGUT were added to the first-degree Stokes's coefficients before converting them into  $1^\circ \times 1^\circ$  gridded data *via* interpolation. The second-degree coefficients were preserved, as no external daily time series of second-degree coefficients are available.

For data post-processing steps, all satellite hydrological variables within the boundary of Yunnan were averaged per

day in space to produce an individual time series for each hydrological variable. Then, a 55-day and a 5-day moving averaging process were applied to TRMM precipitation and GRACE water storage, respectively, followed by shifting a lagged time between the upstream satellite hydrological variables and *in situ* runoff, owing to the presence of hysteretic properties among the hydrological variables influenced by climate, hydrogeology, and topography (Sproles et al., 2015). The time lag was determined *via* a cross-correlation analysis (Oppenheim, 1999). Finally, the runoff reconstruction and forecast *via* the direct linear regression between the satellite hydrological variables and runoff were performed. These results served as benchmarks against the proposed data standardization.

Precipitation is discrete, following non-normal statistical distribution. McKee et al. (1993)'s standardization process was used. This process transforms the GPM-TRMM daily data during 1998–2014 into a standardized form, called standardized precipitation index (SPI), that follows a normal distribution (Naresh Kumar et al., 2009). A 3-month (i.e., 90 days) time scale of SPI was selected (Lloyd-Hughes and Saunders, 2002). However, water storage on land should be continuous. Therefore, conventional data standardization was used for GRACE water storage data, except that the median values every day were adopted to standardize the water storage (Fok and He, 2018), which is written as

$$SI_{i,j} = \frac{S_{i,j} - \text{median}(S_j)}{\hat{\sigma}(S_j)} \quad (1)$$

where  $S_{i,j}$  stands for water storage at  $j$ -th day of year  $i$ , with  $\text{median}(S_j)$  and  $\hat{\sigma}(S_j)$  representing the median and sampled standard deviation of water storage.

## 4.3 Linear regression model

Previous research studies have found that runoff lagged the upstream GPM-TRMM precipitation (Zhang et al., 2007; Du et al., 2020) and GRACE water storage (Riegger and Tourian, 2014) by a month or more. Thus, the time lag between the upstream GPM-TRMM precipitation (GRACE water storage) and the runoff must be determined before further calculation. To calculate the time lag, a cross-correlation analysis was conducted during 2003–2006. This is performed by shifting the time that maximizes the correlation coefficient between the GPM-TRMM precipitation (GRACE water storage) and the runoff.

A simple model that linearly relates the upstream GPM-TRMM precipitation (or GRACE water storage),  $X_{t-\tau}$ , to *in situ* runoff,  $RO_t$ , at day  $t$  is formulated as

$$R_t = c_1 X_{t-\tau} + c_2 \quad (2)$$

where  $c_1$  and  $c_2$  are the least-squares determined parameters that are subsequently employed to reconstruct runoff during

2009–2012. It is of note that the above-determined time lag  $\tau$  shifts  $X$  forward.

To regress the upstream SPI and SI inferred from GPM-TRMM and GRACE, the standardization of *in situ* runoff is achieved through

$$SR_{i,j} = \frac{R_{i,j} - \text{median}(R_j)}{\hat{\sigma}(R_j)}, \quad (3)$$

similar to Eq. 1. The analogous  $c_1$  and  $c_2$  relating the upstream SPI (or SI) to SR are then estimated via Eq. 2, which was then employed to estimate the SR from SPI and SI. Finally, the reconstructed and forecasted SR time series were transformed back into runoff time series via Eq. 3.

### 4.4 NNB models

The result from our proposed approach was then compared to that of artificial neural network (ANN) (Hassoun, 1995) and long short-term memory (LSTM) models (Rumelhart et al., 1986) in order to further evaluate our approach. No matter short- or long-term discharge forecast, previous research studies showed that the results from these NNB models outperform that from the linear regression and conceptual and time series models (Wang et al., 2009; Sahoo et al., 2019; Samantaray and Ghose, 2019).

Regarding the settings of NNB models, the neural network structure of LSTM and ANN was set the same with two hidden layers because Cybenko (1989) stated that two hidden layers were sufficient for a continuous time series. By choosing a scaled exponential linear unit (Klambauer et al., 2017) as an activation function and assigning upstream GPM-TRMM precipitation and GRACE water storage (or SPI and SI) as input and *in situ* runoff as output, training was performed using adaptive moment (i.e., Adam) optimizer (Kingma and Ba, 2014). The two abovementioned models were trained ten times in which mean value was used for each time epoch because random initial weights and the validation set members render numerical values differently.

### 4.5 Assessment metrics

To evaluate the performance in a relative manner, normalized root-mean-square error (NRMSE) (Fok et al., 2020), Nash–Sutcliffe efficiency model coefficient (NSEMC) (Nash and Sutcliffe, 1970), Pearson correlation coefficient (PCC) (Pearson, 1920), detrended fluctuation analysis (DFA) (Peng et al., 1994) scale factor, and detrended cross-correlation analysis (DCCA) (Podobnik and Stanley, 2008) exponent were served as the assessment metrics. They were employed for assessing reconstructed and forecasted runoff against *in situ* datasets.

Defining the *in situ* and reconstructed (or forecasted) runoff at day  $k$  as  $Y_{obs}(k)$  and  $Y_f(k)$  with the average of  $Y_{obs}$  and  $Y_f$  as  $\bar{Y}_{obs}$  and  $\bar{Y}_f$ , and the maximum and minimum value of  $Y_{obs}$  as  $\max(Y_{obs})$  and  $\min(Y_{obs})$ , respectively, the NRMSE transforms RMSE into relative error with a range between 0 and 1. It is written as

$$NRMSE = \frac{\sqrt{\frac{1}{N} \sum_{k=1}^N (Y_f(k) - Y_{obs}(k))^2}}{\max(Y_{obs}) - \min(Y_{obs})}. \quad (4)$$

The NSEMC, ranging from  $-\infty$  to 1, assesses the performance of the reconstructed or forecasted runoff in terms of gain in efficiency. It is written as

$$NSEMC = 1 - \frac{\sum_{k=1}^N (Y_f(k) - Y_{obs}(k))^2}{\sum_{k=1}^N (Y_f(k) - \bar{Y}_{obs})^2}. \quad (5)$$

The PCC, ranging between  $-1$  and  $1$ , assesses temporal consistency between two time-varying variables, which is written as

$$PCC = \frac{\frac{1}{N} \sum_{k=1}^N (Y_{obs}(k) - \bar{Y}_{obs})(Y_f(k) - \bar{Y}_f)}{\sqrt{\frac{1}{N} \sum_{k=1}^N (Y_{obs}(k) - \bar{Y}_{obs})^2} \sqrt{\frac{1}{N} \sum_{i=1}^N (Y_f(k) - \bar{Y}_f)^2}} \quad (6)$$

DFA and DCCA were also used to test the stationarity of a time series and the long-term memory between two non-stationary time series, respectively. During the DFA, the *in-situ* runoff time series  $Y_{obs}(k)$  of length  $N$  was first transformed into a new time series  $Y'_{obs}(k) = \sum_{t=1}^k (Y_{obs}(t) - \bar{Y}_{obs})$ . Then, the new time series was divided into several intervals with the window size  $n$ . The trend of each interval was thus subtracted from  $Y'_{obs}(k)$  through the least-square method to represent the detrended fluctuation function:

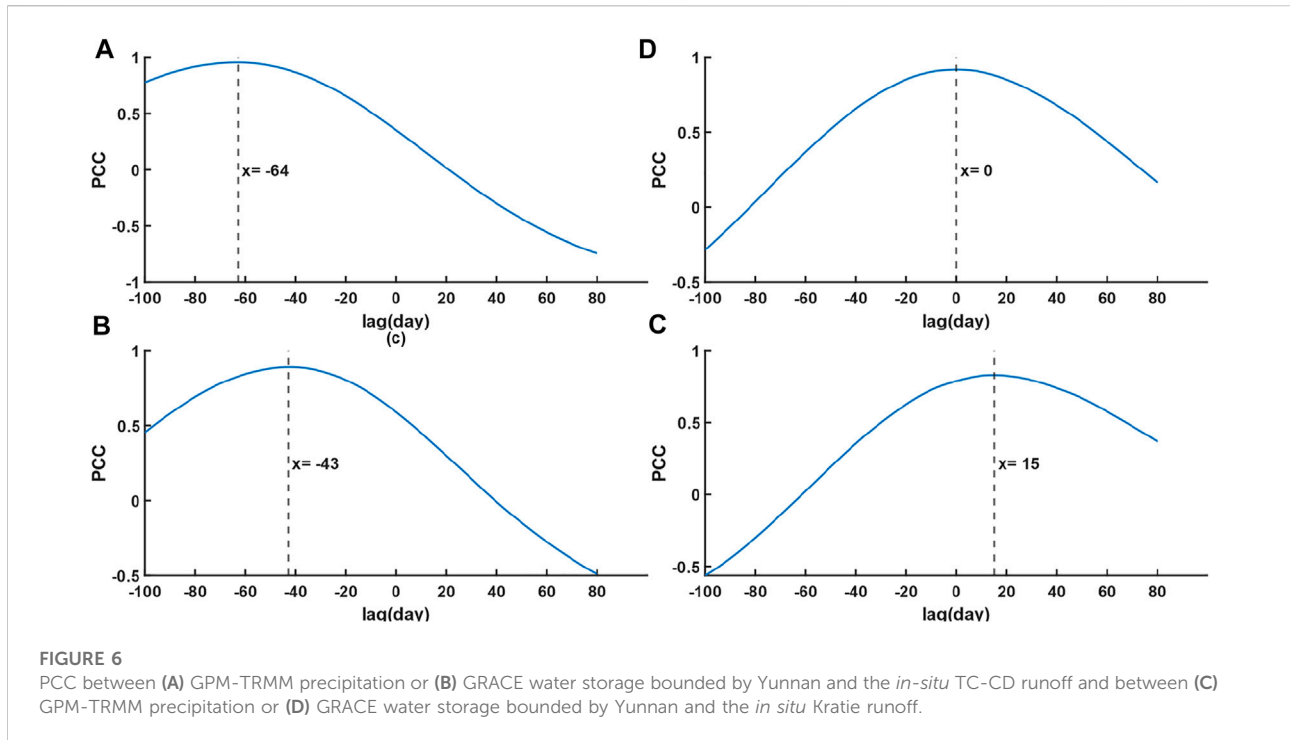
$$F_{DFA}(Y_{obs}(k), n) = \sqrt{\frac{1}{N} \sum_{k=1}^N [Y'_{obs}(k) - \tilde{Y}'_{obs}(k)]^2}, \quad (7)$$

where  $\tilde{Y}'_{obs}(k)$  is the trend of  $Y'_{obs}(k)$ . Normally, the window size  $n$  is power law auto-correlated with the detrended fluctuation (i.e.,  $F_{DFA}(Y_{obs}(k), n) \propto n^{\alpha_{DFA}}$ ). If the original time series is stationary (non-stationary), the scale factor  $\alpha_{DFA}$  will be larger (smaller) than 0.5. In particular, the original time series is white noise when  $\alpha_{DFA}$  equals 0.5.

DCCA was further used to examine the cross-correlation between two non-stationary time series. For instance, the detrended co-fluctuation function of  $Y_{obs}(k)$  and  $Y_f(k)$  under the windows size  $n$  was written as

$$F_{DCCA}(Y_{obs}(k), Y_f(k), n) = \sqrt{\frac{1}{N} \sum_{k=1}^N [Y'_{obs}(k) - \tilde{Y}'_{obs}(k)][Y'_f(k) - \tilde{Y}'_f(k)]}, \quad (8)$$

where  $\tilde{Y}'_f(k)$  is the trend of  $Y'_f(k)$ . Similarly, the square of window-size  $n$  is power law cross-correlated with  $F_{DCCA}(Y_{obs}(k), Y_f(k), n)$



(i.e.,  $F_{DCCA}(Y_{obs}(k), Y_f(k), n) \propto n^{\lambda_{DCCA}}$ ). If the exponent  $\lambda_{DCCA}$  is larger than 0.5, two time series are considered with persistent long-term cross-correlation. To further quantify this cross-correlation, DCCA cross-correlation coefficient,  $\rho_{DCCA}$ , was used as (Zebende, 2011)

$$\rho_{DCCA}(Y_{obs}(k), Y_f(k), n) = \frac{F_{DCCA}^2(Y_{obs}(k), Y_f(k), n)}{F_{DFA}(Y_{obs}(k), n)F_{DFA}(Y_f(k), n)}. \quad (9)$$

The  $\rho_{DCCA}$  ranges from  $-1$  to  $1$ . Similar to PCC,  $\rho_{DCCA} > 0$  represents that the two time series are positively correlated, while  $\rho_{DCCA} < 0$  indicates they are anti-correlated. Denoted that the value of window size  $n$  ranges from 30 to 1995 days with a step of 15 days, 30–1,395 days with a step of 15 days and 30–720 days with a step of 15 days for observed, reconstructed, and forecasted variables, respectively. The choice of window size and step was based on the length of variables.

## 5 Results

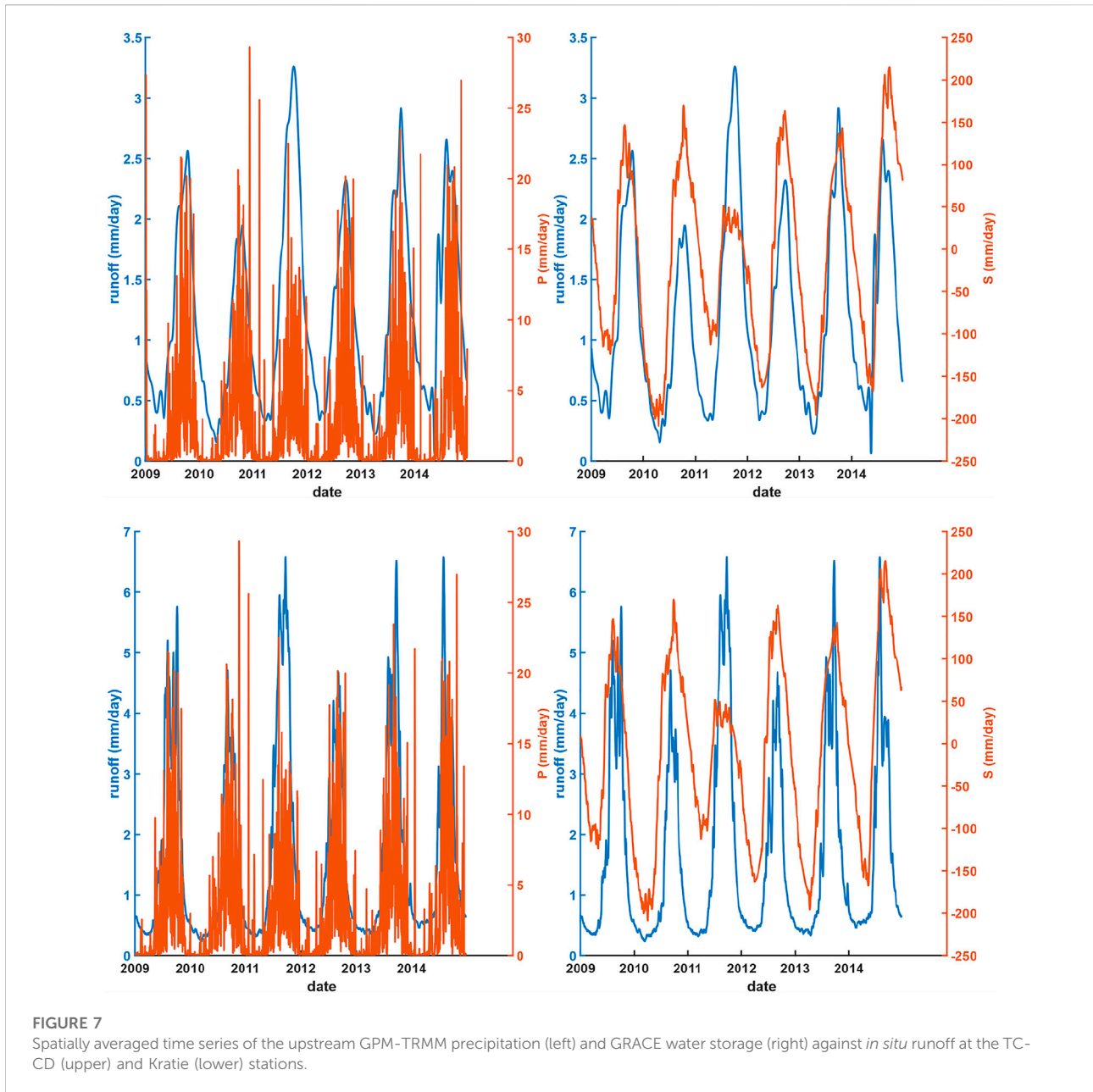
Through cross-correlation analysis, lagged time between the *in-situ* runoff at the TC-CD (and Kratie) station and the upstream GPM-TRMM precipitation (or GRACE water storage) during 2003–2006 was determined, respectively (Figure 6), through the obtained maximum PCC between them. The lagged time was found to be  $-64$  days (or 0 day),

while the lagged time for that of the Kratie station was found to be  $-43$  days (or 15 days), respectively. This implies the fundamental difference between the Kratie and TC-CD station locations chosen as runoff because the TC-CD stations' pair recorded an additional regulation influence due to the natural reservoir—Tonle Sap Lake. However, GRACE water storage is synchronized with (15 days' lag) *in-situ* runoff at the TC-CD (Kratie) station, which might be attributable to regionalized smoothing in the pre-processing steps. Nonetheless, all lagged time calculated results were used to shift the time series against the *in-situ* runoff for reconstructing runoff.

The fluctuation pattern of the upstream GPM-TRMM precipitation and GRACE water storage are largely in agreement with the *in-situ* runoff (Figure 7). However, a lagged time is exhibited between the upstream GRACE water storage and *in situ* runoff during the dry season. This may be potentially due to different storage-runoff properties between the upstream and the total basin runoff, resulting in a slower decrease in storage against the runoff. Furthermore, an even more obvious lagged shift of water storage is apparent in 2014, potentially attributed to the end-of-commission of GRACE when the occurrence of the data quality degradation.

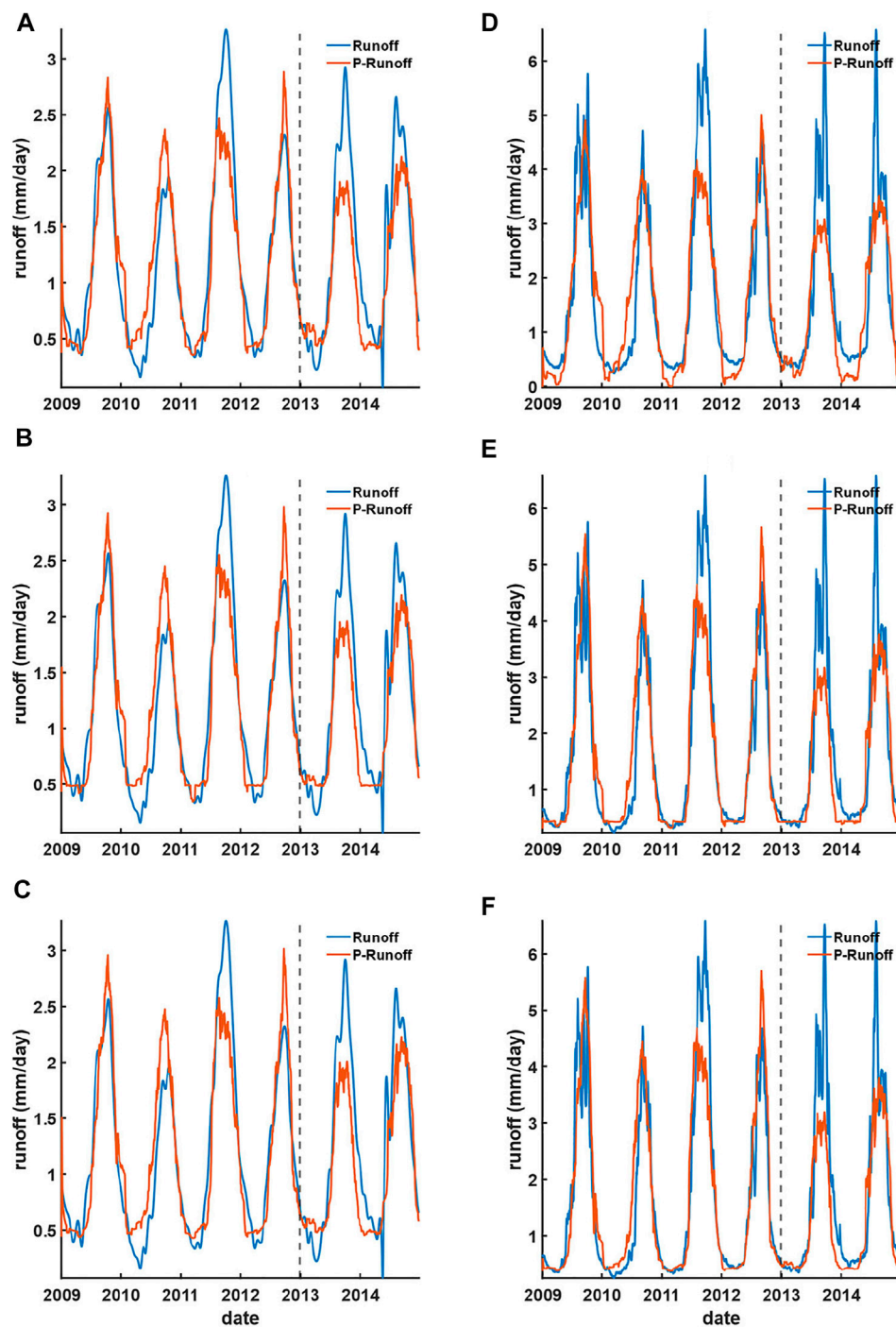
The accuracies and performances of the reconstructed (from 2009 to 2012) and forecasted (from 2013 to 2014) runoff are then assessed using the upstream GPM-TRMM precipitation, GRACE water storage, and their standardizations, generated from the linear regression, ANN, and LSTM models (Figures 8, 9). We observed that the runoff reconstructed and forecasted at the TC-CD station





using the upstream GPM-TRMM precipitation performed similarly among different models (Figure 8), while it performed differently at the Kratie station. Those runoff time series generated from NNB models performed better than that of linear regression, particularly capturing the troughs better against *in situ* runoff at Kratie station during the dry season (Figures 8D–F). Nevertheless, no runoff among the models captured the peaks very well. This is particularly apparent in 2011, 2013, and 2014. This should be attributable to La Niña events in 2011, 2013, and 2014 (Figure 3) that might potentially alter the usual hydrological conditions between the upstream and the downstream. This is further discussed qualitatively in the next section.

The runoff generated using GRACE water storage (Figure 9) yields a similar result but appears better in capturing the peaks visually than that of GPM-TRMM precipitation. This might be attributable to the well-known hydraulic relationship between water storage and runoff on land. However, in terms of the accuracy evaluation statistics (Tables 1, 2), the overall consistency of runoff generated using GRACE water storage is still a bit worse than that of GPM-TRMM precipitation. This might be caused by a moderately strong spatiotemporal smoothing in the GRACE data preprocessing, making GRACE-reconstructed runoff able to visually capture the rise and

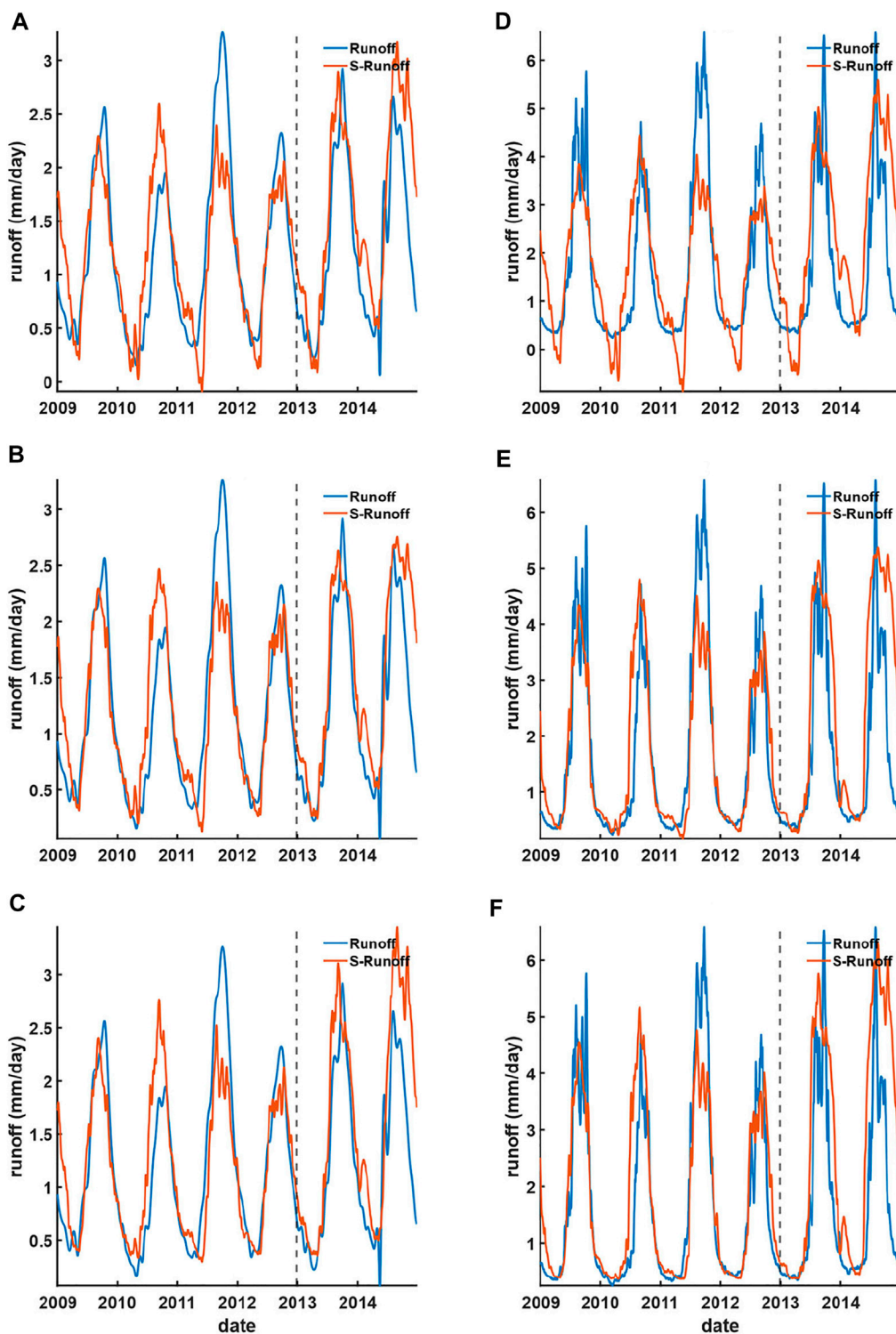


**FIGURE 8**

Reconstructed (during 2009–2012) and forecasted (during 2013–2014) runoff using the upstream GPM-TRMM precipitation based on (A) linear regression, (B) ANN, and (C) LSTM models against the TC-CD station and (D) linear regression, (E) ANN, and (F) LSTM models against the Kratie station.

fall during the dry and wet season time period but unable to capture the extreme peaks and troughs at an accurate timing on a daily scale.

From the concept, the runoff reconstructed at the Kratie station should be better than that of the TC-CD station, since the location of the Kratie station should be less influenced by



**FIGURE 9**  
 Reconstructed (during 2009–2012) and forecasted (during 2013–2014) runoff using the upstream GRACE water storage based on (A) linear regression, (B) ANN, and (C) LSTM models against the TC-CD station and (D) linear regression, (E) ANN, and (F) LSTM models against the Kratie station.

TABLE 1 Evaluation of runoff reconstruction and forecast at the TC-CD stations.

Data/Index	Method	Reconstruction			Forecast		
		NRMSE	NSEMC	PCC	NRMSE	NSEMC	PCC
P	Linear regression	0.0996	0.8426	0.9180	0.1421	0.7410	0.9187
	ANN	0.0990	0.8446	0.9199	0.1373	0.7582	0.9198
	LSTM	0.0990	0.8445	0.9202	0.1387	0.7533	0.9158
S	Linear regression	0.1381	0.6976	0.8352	0.1850	0.5607	0.8879
	ANN	0.1266	0.7457	0.8636	0.1654	0.6490	0.8883
	LSTM	0.1302	0.7309	0.8551	0.2033	0.4698	0.8925
SPI	Linear regression	0.1047	0.8260	0.9197	0.0928	0.8895	0.9471
	ANN	0.1078	0.8157	0.9182	0.0936	0.8875	0.9466
	LSTM	0.1069	0.8187	0.9191	0.0937	0.8873	0.9463
SI	Linear regression	0.1048	0.8258	0.9190	0.0936	0.8876	0.9461
	ANN	0.1095	0.8098	0.9173	0.0966	0.8802	0.9431
	LSTM	0.1087	0.8128	0.9170	0.0945	0.8854	0.9461

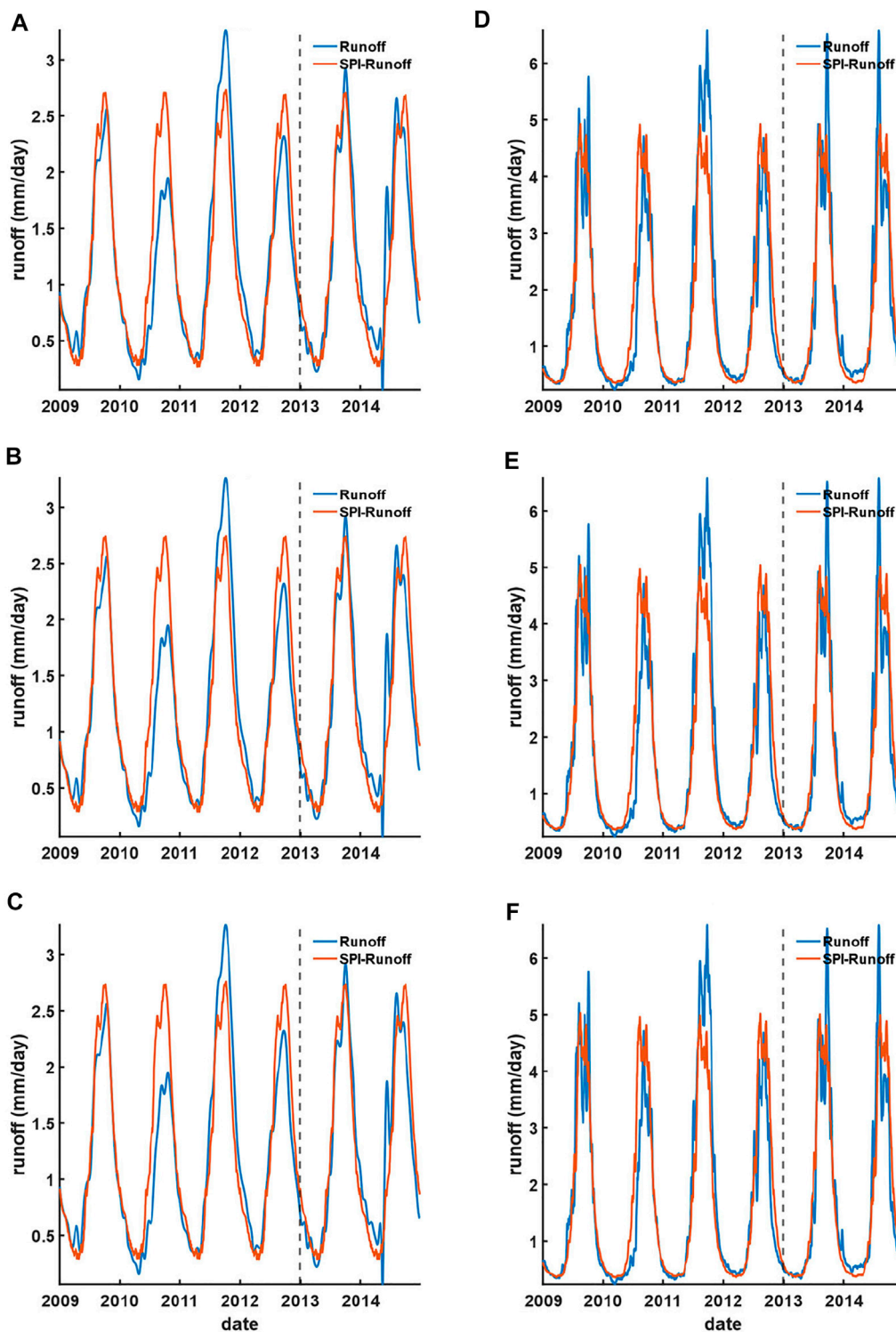
TABLE 2 Evaluation of runoff reconstruction and forecast at the Kratie station.

Data/Index	Method	Reconstruction			Forecast		
		NRMSE	NSEMC	PCC	NRMSE	NSEMC	PCC
P	Linear regression	0.1121	0.7996	0.8942	0.1460	0.6753	0.8582
	ANN	0.1026	0.8321	0.9132	0.1401	0.7012	0.8829
	LSTM	0.1020	0.8339	0.9144	0.1393	0.7045	0.8843
S	Linear regression	0.1467	0.6565	0.8103	0.2151	0.2950	0.7900
	ANN	0.1195	0.7720	0.8787	0.2247	0.2306	0.8056
	LSTM	0.1208	0.7670	0.8783	0.2547	0.0116	0.8115
SPI	Linear regression	0.1023	0.8332	0.9139	0.0874	0.8836	0.9405
	ANN	0.1049	0.8246	0.9114	0.0881	0.8819	0.9398
	LSTM	0.1048	0.8248	0.9110	0.0890	0.8793	0.9384
SI	Linear regression	0.1035	0.8289	0.9117	0.0865	0.8860	0.9417
	ANN	0.1109	0.8037	0.9028	0.0875	0.8834	0.9405
	LSTM	0.1061	0.8203	0.9093	0.0864	0.8864	0.9426

backwater due to the long distance away from the estuary. However, comparing the runoff reconstructed and forecasted at the TC-CD station with that at the Kratie station in terms of accuracy evaluation statistics, the runoff reconstructed at the Kratie station is worse than that of the TC-CD station. It is of note that the Butterworth filter was applied to suppress the short-period tidal backwater effect in the river delta (Peng et al., 2020), which might improve the overall accuracy. Another reason is that the Kratie station does not really represent the entire Mekong Basin due to ignorance of the Cambodian plain area where Tonle Sap Lake is located. In addition, mountainous areas with steep slopes located around the Kratie station might be another error

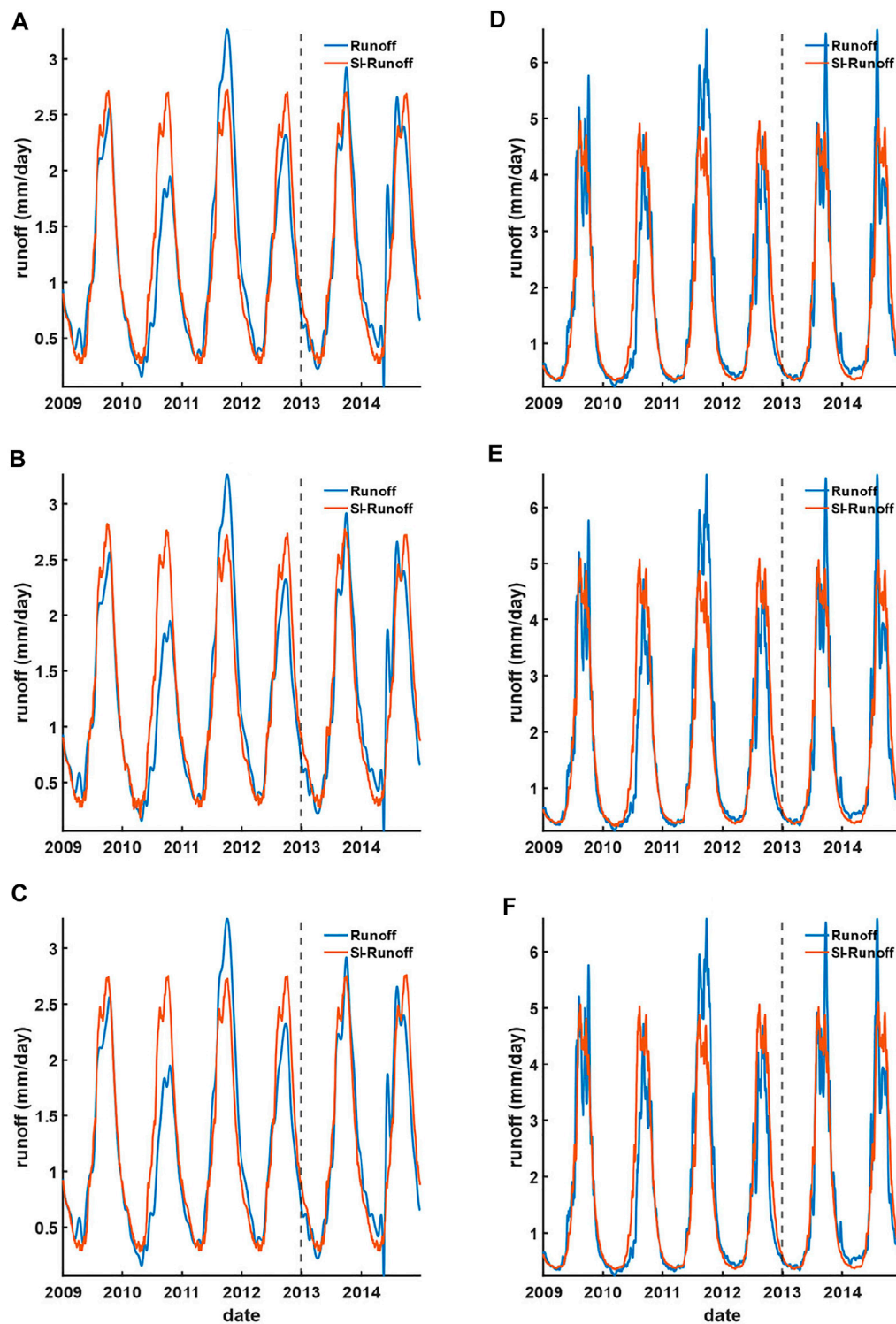
source. It is also of note that the runoff peaks at the Kratie station are highly fluctuated compared to those of the TC-CD station. This might be caused by a cascade of inconsistent dam operations by humans among different countries and places during summer. These fluctuating peaks cannot be observed from the relatively smoothed satellite hydrological variables by nature and, hence, result in lower relative accuracy.

In any occasion, runoff reconstructed and forecasted using GPM-TRMM precipitation and GRACE water storage yield the PCC (NRMSE) of 0.92 (~10%) and 0.85 (~13%), respectively, no matter at the TC-CD and Kratie stations (Tables 1, 2). Overall, the abovestated resulting evaluation statistics are comparable to



**FIGURE 10**  
 Reconstructed (from 2009 to 2012) and forecasted (from 2013 to 2014) runoff using the upstream GPM-TRMM SPI against *in situ* runoff at the TC-CD and Kratie stations based on (A and D) linear regression, (B and E) ANN, and (C and F) LSTM models, respectively.





**FIGURE 11**  
 Reconstructed (from 2009 to 2012) and forecasted (from 2013 to 2014) runoff using the upstream GRACE SI against *in situ* runoff at the TC-CD and Kratie stations based on (A and D) linear regression, (B and E) ANN, and (C and F) LSTM models, respectively.

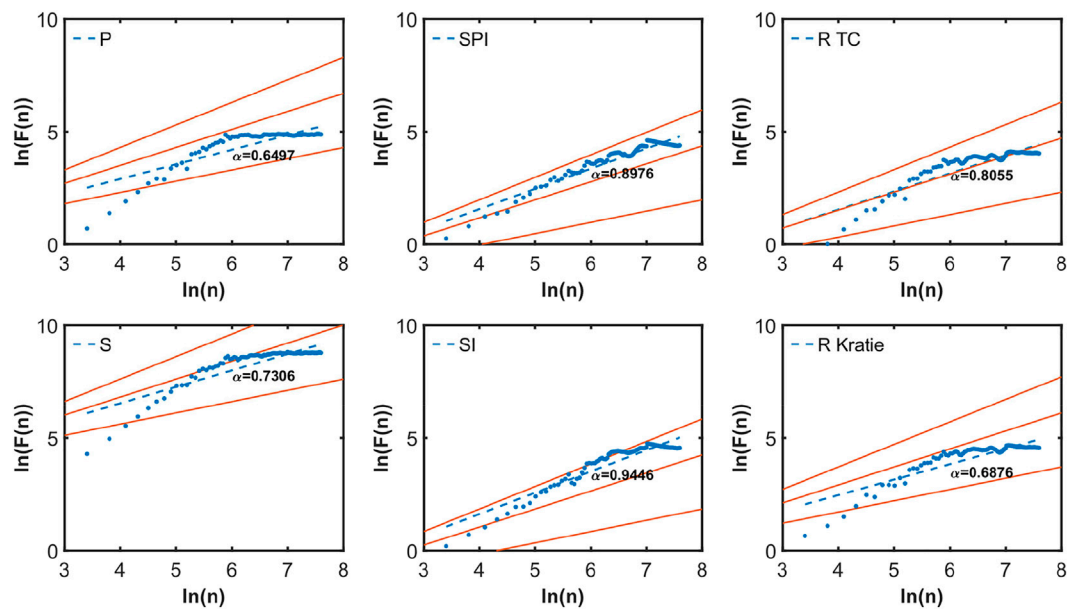


FIGURE 12

Double logarithmic plots of the fluctuation functions of DFA versus window-size  $n$  derived from P, S, SPI, SI, and *in-situ* runoff at the TC-CD and Kratie stations. The slopes of dashed blue lines represent the fitted  $\alpha_{DFA}$ , and the three red solid lines from top to bottom denote  $\alpha_{DFA} = 1$ ,  $\alpha_{DFA} = 0.8$ , and  $\alpha_{DFA} = 0.5$ , respectively.

TABLE 3  $\alpha_{DFA}$  of different hydrological variables or index.

Data/Index	Station	$\alpha_{DFA}$
<i>In-situ</i> R	TC-CD	0.81
	Kratie	0.69
P	Yunnan	0.65
S	Yunnan	0.73
SPI	Yunnan	0.90
SI	Yunnan	0.94

the best published daily relative error of 12% by [Tourian et al. \(2017\)](#).

The reconstructed runoff using standardized data is better than that generated from the satellite hydrological variables directly *via* linear regression ([Tables 1 and 2](#)). This is manifested from the runoff reconstructed from SPI and SI, yielding a better agreement in the wet and dry seasons against *in situ* runoff, no matter in the TC-CD and Kratie stations ([Figures 10, 11](#)).

Compared to the runoff generated directly using upstream GPM-TRMM precipitation against *in situ* TC-CD and Kratie stations, the reconstructed runoff based on SPI is worsened (improved) at most by 0.9% (1%), respectively, while that of the forecasted runoff is improved by 5% consistently ([Tables 1 and 2](#)). For the resulting runoff using GRACE water storage

against *in situ* TC-CD and Kratie stations, the reconstructed runoff based on SI is consistently improved at most by 3% and 4%, respectively, while that of the forecasted runoff is improved at most by 10% and 16%, respectively. This indicates that systematic influences can be minimized *via* data standardization ([Ferreira et al., 2018](#)), while the improvement for the standardized GRACE water storage (i.e., SI) is significantly better than that of SPI. Assessing the relative accuracy (in terms of NRMSE), both the reconstructed and forecasted runoffs' relative accuracies are presented with less than 11%. Those are slightly better than the best relative accuracy published in the recent literature (i.e., 12%) ([Tourian et al., 2017](#)). Notably, no matter reconstructed using SPI and SI at the TC-CD or Kratie stations, the relative accuracy in terms of NRMSE for the forecasted runoff is still ~9%, indicating that the backwater effect on TC-CD should be further minimized after the data standardization process. In other words, the basin exit can be chosen as close as the estuary mouth, such that the runoff could best represent the total discharge of the entire basin.

To test the stationarity of different hydrological variables, their logarithmic fluctuation functions versus logarithmic window size is shown in [Figure 12](#) and [Supplementary Figures S1 and S2](#), with the scale factor  $\alpha_{DFA}$  (also known as Hurst component) fitted through the least-square method ([Tables 3–5](#)). The observed hydrological data time series shared obvious crossovers at the window size of around 1 year, except for standardized data removing seasonal trends ([Figure 12](#)). Below

TABLE 4  $\alpha_{DFA}$  of different reconstructed and forecasted runoff at the TC-CD station and  $\lambda_{DCCA}$  of different reconstructed and forecasted runoff against the TC-CD station.

Data/Index	Method	Reconstruction		Forecast	
		$\alpha_{DFA}$	$\lambda_{DCCA}$	$\alpha_{DFA}$	$\lambda_{DCCA}$
P	Linear regression	0.84	0.85	1.27	1.32
	ANN	0.85	0.86	1.29	1.32
	LSTM	0.85	0.86	1.30	1.32
S	Linear regression	0.95	0.90	1.34	1.41
	ANN	0.91	0.89	1.35	1.40
	LSTM	0.93	0.88	1.34	1.40
SPI	Linear regression	0.86	0.86	1.31	1.31
	ANN	0.86	0.87	1.31	1.31
	LSTM	0.86	0.87	1.31	1.31
SI	Linear regression	0.86	0.86	1.31	1.31
	ANN	0.86	0.87	1.31	1.31
	LSTM	0.85	0.86	1.31	1.31

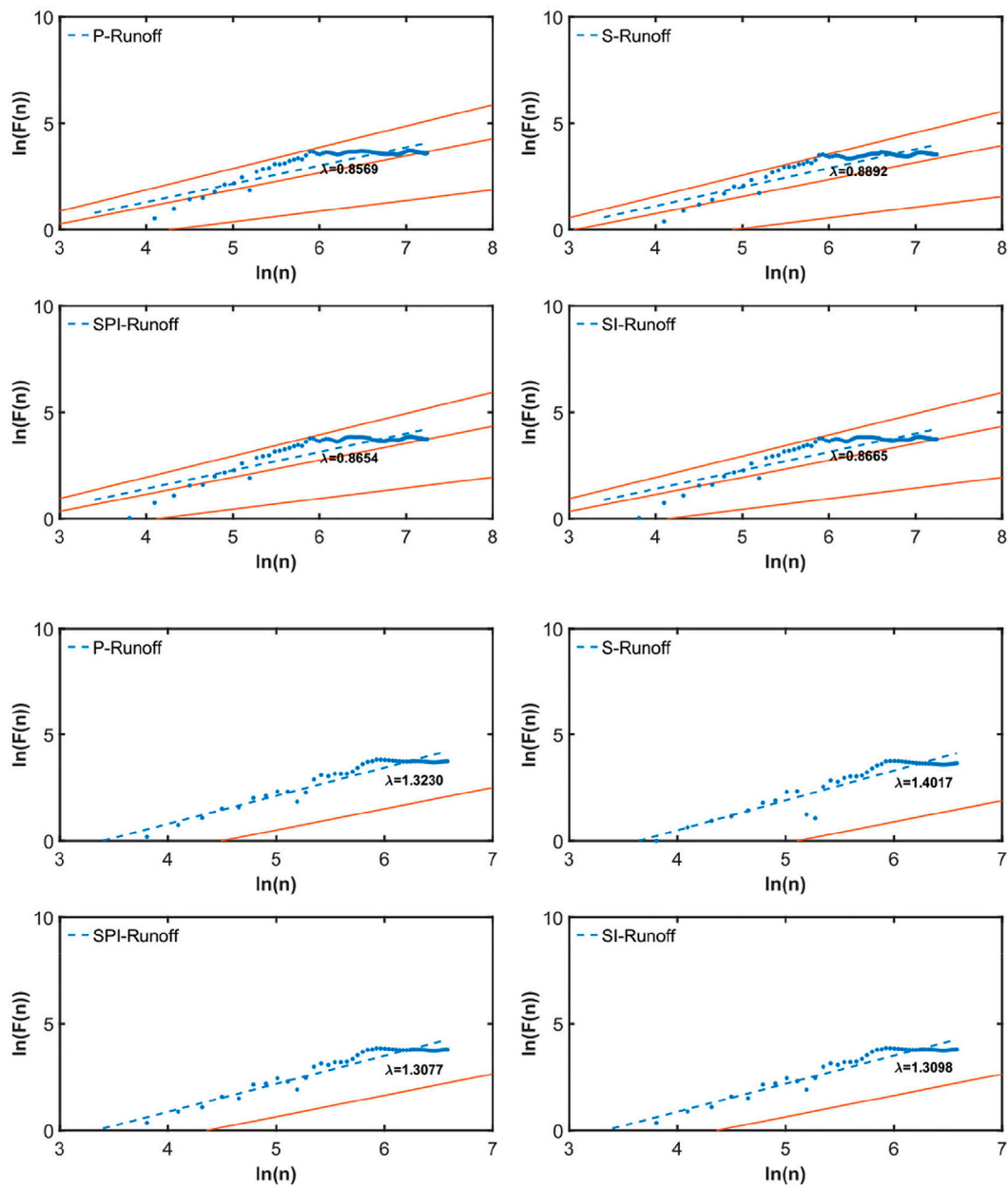
TABLE 5  $\alpha_{DFA}$  of different reconstructed and forecasted runoff at the Kratie station and  $\lambda_{DCCA}$  of different reconstructed and forecasted runoff against the Kratie station.

Data/Index	Method	Reconstruction		Forecast	
		$\alpha_{DFA}$	$\lambda_{DCCA}$	$\alpha_{DFA}$	$\lambda_{DCCA}$
P	Linear regression	0.84	0.84	1.27	1.31
	ANN	0.86	0.85	1.31	1.32
	LSTM	0.85	0.84	1.28	1.31
S	Linear regression	0.95	0.89	1.34	1.37
	ANN	0.94	0.89	1.35	1.34
	LSTM	0.90	0.84	1.333	1.39
SPI	Linear regression	0.79	0.80	1.22	1.20
	ANN	0.79	0.80	1.23	1.21
	LSTM	0.80	0.80	1.23	1.21
SI	Linear regression	0.79	0.80	1.22	1.20
	ANN	0.80	0.80	1.22	1.20
	LSTM	0.79	0.80	1.22	1.20

the crossover, the scale factor is larger than 1.2, indicating a strong short-term correlation (Bunde et al., 2012). Particularly, the scale factors of forecast runoff at the TC-CD and Kratie stations were also higher than 1 (Supplementary Figures S1, S2). One of the reasons might be the time span in the forecast was so short (i.e., 2 years) that the long-term correlation was weak. Nevertheless, the  $\alpha_{DFA}$  of most hydrological variables or indices ranged between 0.6 and 0.9, showing their persistent stationarity. This is consistent with previous studies that the Hurst component of precipitation and runoff in other rivers is

commonly around 0.8 (Kantelhardt et al., 2006; Koscielny-Bunde et al., 2006; Bogachev and Bunde, 2012).

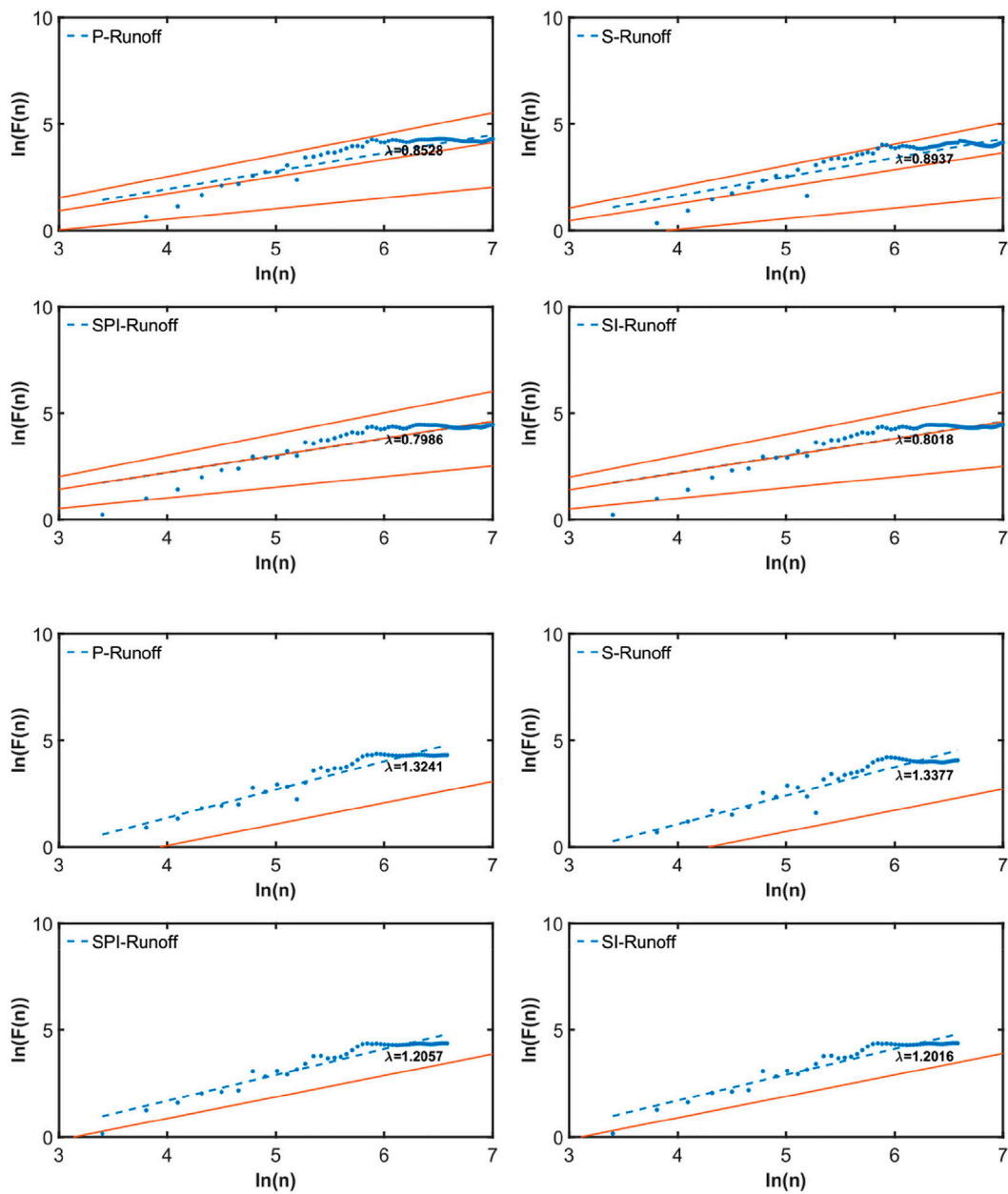
To examine the long-term cross-correlation between our reconstructed (forecasted) and *in-situ* runoff, the exponent  $\lambda_{DCCA}$  of DCCA was also obtained (Tables 4 and 5). The  $\lambda_{DCCA}$  of reconstruction were higher than 0.5, which means the reconstruction time series are persistent cross-correlated against *in-situ* runoff at the TC-CD and Kratie stations. Similar to  $\alpha_{DFA}$ , the  $\lambda_{DCCA}$  of forecasted time series were extremely high (i.e., >1.2) due to the limited time span, as mentioned earlier (Figures 13 and 14).



**FIGURE 13**  
 Power-law cross-correlations between ANN-reconstructed (upper four subplots) and ANN-forecasted (lower four subplots) runoff and *in-situ* TC-CD runoff. The slopes of dashed blue lines represent the fitted  $\lambda_{DCCA}$ , and the three red solid lines from top to bottom denote  $\lambda_{DCCA} = 1$ ,  $\lambda_{DCCA} = 0.8$ , and  $\lambda_{DCCA} = 0.5$ , respectively.

For further quantifying the cross-correlations between reconstructed (forecasted) and *in-situ* runoff, the DCCA cross-correlation coefficients  $\rho_{DCCA}$  were also provided. Within most of the window sizes, both reconstructed and forecasted runoff derived from the observed P showed higher  $\rho_{DCCA}$  against *in-situ* runoff at TC-CD (left subplots in Figure 15) and Kratie (left subplots in Figure 16) compared to that from the

observed S. However, this discrepancy almost disappeared when it comes to SPI and SI (right subplots in Figures 15 and 16). We speculated the data standardization process removed the relatively high seasonality of the observed S and, hence, reduced the systematic component of observations. In addition, the  $\rho_{DCCA}$  of the reconstructed (forecasted) runoff generated from different methods (i.e., linear regression,



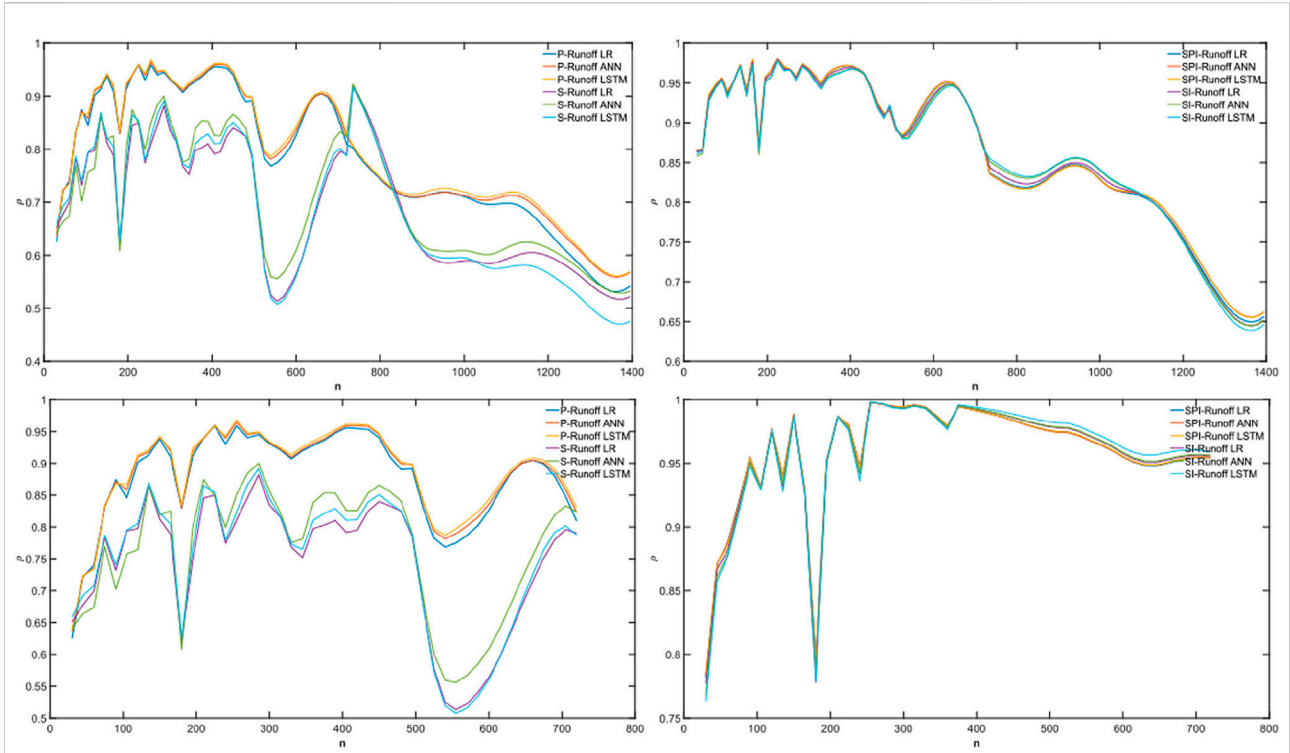
**FIGURE 14**  
 Power-law cross-correlations between ANN-reconstructed (upper four subplots) and ANN-forecasted (lower four subplots) runoff and *in-situ* Kratie runoff. The slopes of dashed blue lines represent the fitted  $\lambda_{DCCA}$ , and the three red solid lines from top to bottom denote  $\lambda_{DCCA} = 1$ ,  $\lambda_{DCCA} = 0.8$ , and  $\lambda_{DCCA} = 0.5$ , respectively.

ANN, and LSTM) showed a decreasing trend when the window sizes were larger than about 750 (350) days. It is consistent with the previous analysis that reconstruction and forecast were relatively weak on long-term variance (e.g., extreme peaks and troughs in Figures 9–11). In addition, extremely low values of  $\rho_{DCCA}$  at some lower window sizes (e.g., 180 days) might result from the remaining errors in observed P and S time series, such as high-frequency noise.

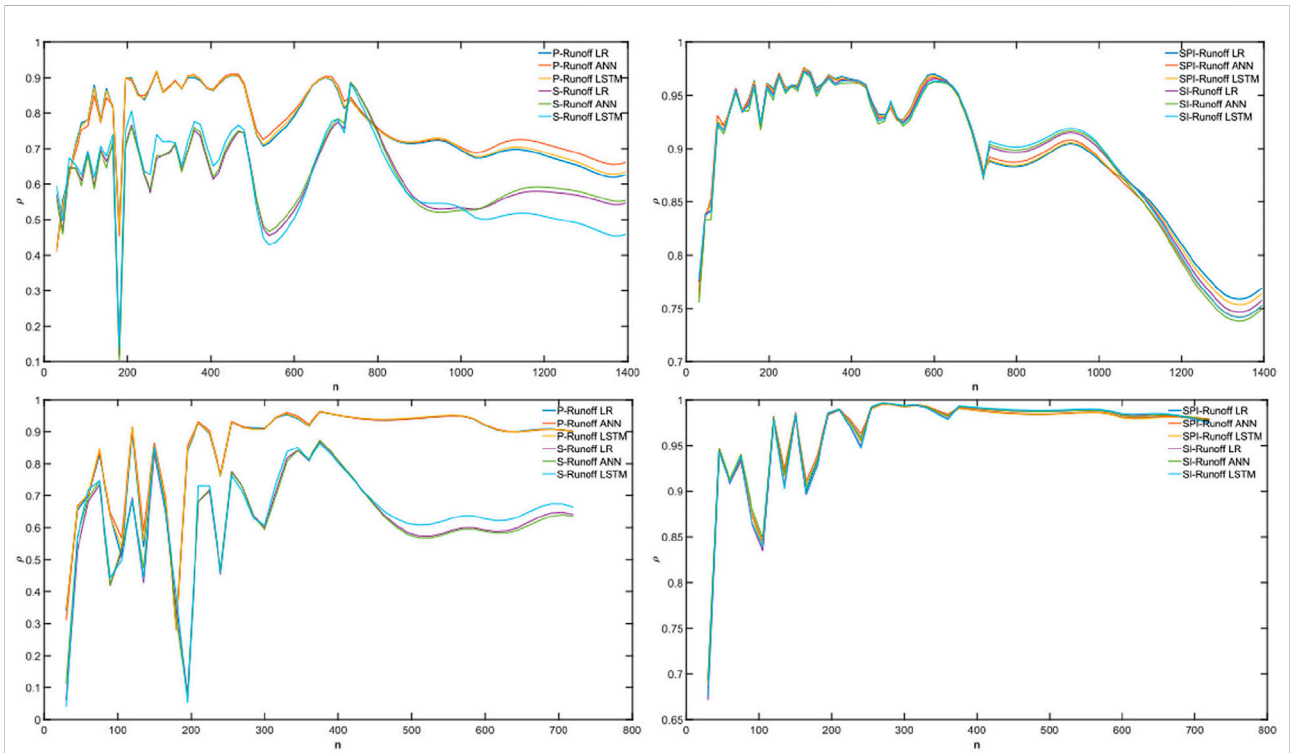
## 6 Discussion

Even though the SPI- and SI-reconstructed runoff yield substantial improvements in capturing the peaks (troughs) during wet (dry) seasons against the *in-situ* runoff, substantial discrepancies during the wet season still exist. We analyze the SPI and SI during 2009–2014 against the standardized *in situ* runoff for potential reasons (Figure 17).

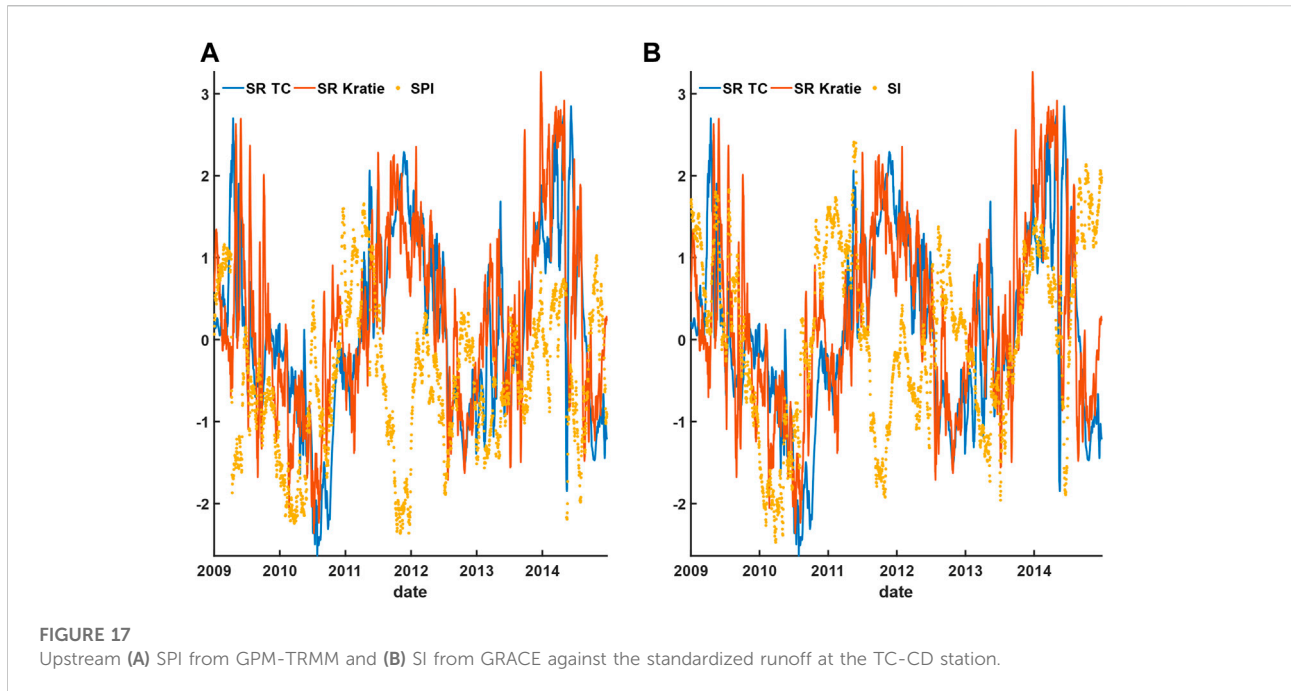




**FIGURE 15**  
 $\rho_{DCCA}$  between reconstructed runoff derived from P, S (upper-left), reconstructed runoff derived from SPI, SI (upper-right), forecasted runoff derived from P, S (lower-left), and forecast runoff derived from SPI, SI (lower-right) and *in-situ* TC-CD runoff.



**FIGURE 16**  
 $\rho_{DCCA}$  between reconstructed runoff derived from P, S (upper-left), reconstructed runoff derived from SPI, SI (upper-right), forecasted runoff derived from P, S (lower-left), and forecast runoff derived from SPI, SI (lower-right) and *in-situ* Kratie runoff.



Plotting the SPI and SI with the *in-situ* SR at the TC-CD and Kratie stations, Figure 17 both the SPI and SI time series display fluctuation patterns irregularly when compared to the *in-situ* SR. It is of note that the lagged time has been applied. We found the presence of the reverse pattern of SPI and SI when compared to SR during different time periods within 2009–2014. The time duration sessions for the reverse pattern of SPI and SI are basically the same, which are June–September 2010, January–April 2011, July 2011–February 2012, September–December 2012, and June–December 2014.

For the period between June–September 2010 and January–April 2011, the reverse patterns of these periods should be caused by the presence of the strongly alternating El Niño and La Niña events during 2009–2010 and 2010–2011, respectively. It is of note that the moderately strong ENSO events should take 6–9 months before the start of runoff response in the Mekong Basin (Fok et al., 2018). Those reverse patterns indicate the downstream was relatively wet while the upstream was dry during 2009–2011. Apparently, the normal precipitation and water storage patterns were distorted, making the hydrological conditions between the downstream and the downstream more distinguishable (Biancamaria et al., 2011).

Though ENSO indices can be speculated to be incorporated into the linear regression model for a better runoff reconstruction and forecast, the reverse patterns between September–December 2012 and June–December 2014 are not shown to be related to ENSO (Figure 17). We speculate that the reverse patterns between September–December 2012 and June–December 2014 might be due to the regional climate of the Mekong Basin. Monsoon indices, such as the Indian summer

monsoon index and the western North Pacific monsoon index, can be potentially utilized to explain these anomalies. In addition, the SPI and SI appear to have an offset against SR, indicating the chosen mean (or median) value of each day within the year for the entire time series would have a substantial impact on the interpretation as well. The abovementioned result and discussion detailed the limitations of this study.

## 7 Conclusion

Daily runoff in the Mekong Basin was reconstructed and forecasted *via* direct linear regression and neural network-based models, using upstream daily satellite hydrological variables (i.e., precipitation from GPM-TRMM and water storage from GRACE) and their respective standardized forms (i.e., SPI and SI). Our proposed standardization approach further reduces the discrepancy for the peaks and troughs during wet and dry seasons, respectively, when compared to the direct correlation between the *in-situ* runoff and individual satellite hydrological variables.

Comparing the runoff from our proposed approach against the *in-situ* runoff at the TC-CD and Kratie stations, we found that the backwater effect on the TC-CD station can be negligible so long as the low-pass filter has been applied to the *in-situ* time series in order to suppress the short-period ocean tides. This implies it is possible to choose the basin exit as close as the entrance of the river delta, such that the runoff could best represent the total discharge of the entire basin. For instance, the neglect of the Cambodian plain area would

render an incomplete description of the entire Mekong Basin. Moreover, the runoff reconstructed and forecasted from neural network-based models using the standardized data does not guarantee improvement over that from the direct linear regression. This implies the standardized input and output, potentially including exogenic variables, might be unfavorable to explore the full capabilities of neural network-based models in reconstructing and forecasting runoff. In summary, the reconstructed and forecasted runoff based on standardized data can be improved at most by 5% and 16%, respectively. The runoff forecasted from the SI resulted in the lowest NRMSE (i.e., 0.086 or 8.6%). Results from DFA and DCCA also indicated that the standardization process would increase the consistency of reconstructed and forecasted runoff among different methods by minimizing the systematic errors of observed hydrological variables (i.e., P and S).

Nonetheless, substantial discrepancies are still obvious using our proposed approach. The chosen median standardized values should be one of the potential reasons to be further investigated. Relating ENSO and monsoon index (e.g., the Indian summer monsoon index and the western North Pacific monsoon index) quantitatively to the standardized runoff, SPI and SI should help discover the potential for further improvement in the reconstructed and forecasted runoff during abnormal conditions. This further improvement should lie in the methodology for mitigating the climate variability in both the satellite hydrological variables and *in situ* runoff.

## Data availability statement

Publicly available datasets were analyzed in this study. The corresponding links were given in [Section 3](#).

## Author contributions

Conceptualization: HF; methodology: HF and LZ; software: LZ and YC; validation: HF, YC, and LZ; formal analysis: HF; investigation: HF; resources: HF; data curation: LZ; writing—original draft preparation: HF; writing—review and editing: HF and YC; visualization: YC; supervision: HF; project administration: HF; funding acquisition: HF. All

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authors have read and agreed to the published version of the manuscript.

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## Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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## Supplementary material

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/feart.2022.821592/full#supplementary-material>

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