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Experimental and numerical research of crack propagation process and energy dissipation law of grouting specimens under radial impact load

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Different air pressures are used to conduct an impact test based on the split Hopkinson pressure bar (SHPB) test system to study the crack evolution process and energy dissipation law of the cemented rock under impact load. The failure mechanism of the specimens is analyzed from the perspective of dynamic failure process and energy dissipation. The spatial distribution of the specimen components visualized by the image reconstruction technology and the LS-DYNA mesoscopic model is established. Results show that the proportion of dissipated energy, the dynamic tensile strength and peak strain of the specimens increase with strain rate increase. The crack evolution process of the model is quantitatively described under an impact load, which is divided into four stages, namely, no crack stage, slow development stage, accelerated propagation stage and penetration stage. Compared with the indoor and simulation test result, the crack evolution process and failure modes are consistent under different strain rates. When the specimens are destroyed, the energy dissipation rate fluctuates from 10% to 13%. The dissipated energy of cement paste accounts for more than 90% of the total dissipated energy. The cement paste damages first and its strength has a great influence on the strength of the grouting specimens. This study provides a reference to evaluate the cemented rock under a dynamic load.

KEYWORDS

grouting specimens, SHPB, crack evolution, energy evolution, Ls-Dyna

1 Introduction

The construction process of underground engineering faces instability problems of rock and Earth mass with the rapid development of the urban underground space (Von et al., 2020; Jong et al., 2021). The sand layer is a common, poor self-stabilization and hazardous harmful geology, and it induces frequent geological disasters, such as sand collapse, landslide, and surface collapse (Wen et al., 2020a; Ye et al., 2022). Grouting reinforcement can effectively enhance the overall mechanical properties and anti-leakage

performance of the sand beds (Liang et al., 2020; Ren et al., 2022). The tensile strength of the sand layer is far less than the compressive strength after grouting reinforcement. The sand bears not only bears quasi-static load but also earthquake, mechanical construction, explosion, and other impact loads. The crack initiation, expansion, penetration, and fracture of the grouting specimens must be studied under radial impact load. The split Hopkinson pressure bar (SHPB) system has been commonly used in dynamic compression, splitting, and fracture testing of the materials in a dynamic load test (Dai et al., 2010; Chen et al., 2014; Liao et al., 2016; Zhu et al., 2022). Most previous experimental studies have focused on strain rate effects (Liu et al., 2019; Yu et al., 2021).

During the dynamic splitting experiments, the failure process of several specimens is captured with a high-speed camera, and the crack propagation law and damage process of the concrete, sandstone, and rock materials are analyzed (Ai et al., 2019; Xing et al., 2018; Lai et al., 2022). The variation rules of the transmitted and dissipated energy of basalt and granite are studied through the SHPB test (Li et al., 2019; Liu et al., 2022). The energy utilization rate of the mortar is also studied through experiments (Sun et al., 2022). Xu et al. (2015) measured the expansion toughness and fracture energy of the rock through simulation. The influence of the angle and thickness of the joints and fractures in the rock mass on the law of energy propagation and dissipation is also explored (Huang et al., 2019; Han et al., 2022). The above-mentioned studies have analyzed the dynamic mechanics or energy dissipation characteristics of rock-like materials, while the energy dissipation characteristics of the grouting specimens under SHPB impact are rarely studied. The impact failure of the grouting specimens can be regarded as the result of energy transformation or energy dissipation among different energies. The process of energy variation reflects the evolution of internal micro-defects, and its failure mechanism can be further revealed from the perspective of energy dissipation (Gong et al., 2022).

The crack initiation and propagation in the specimens are difficult to observe due to the opaque nature of concrete materials. The crack propagation process can be observed through CT scanning, 3D printing, acoustic emission detection and other tests, but these experiments greatly increase the cost and do not scan the instantaneous failure process. The grouting specimen is a heterogeneous material with a complex internal structure, and the three-dimensional numerical model can effectively solve the problem of damage and energy dissipation of internal components, but indoor tests results don't be quantitatively analyzed (Lv et al., 2022; Sun et al., 2022). Previous research results (Li et al., 2012; Ayhan et al., 2022; Dong et al., 2021) have proven that LS-DYNA software can effectively simulate the dynamic impact process and fracture mechanical properties of cement-based materials. Yu et al. (2021) changed the parameters of the HJC constitutive model and studied the influence of the strength of

TABLE 1 Mix proportions of grout.

Groups	m_C /kg	m_W /kg	m_{VAE} /kg	m_A /kg
Grout	803.10	642.48	40.16	4.02

Notes: m_C , m_W , m_{VAE} , and m_A represent the quality of cement, water, VAE emulsion, and defoamer in 1 m³ grout.

aggregate and mortar on the overall performance. Wang et al. (2021) established a 3D mesoscopic model to study the damage and energy dissipation process of concrete. Ai et al. (2013) simulated the mesoscopic failure mechanism of the concrete materials based on LS-DYNA software. A mesospheric aggregate model is established to study the tensile and compressive properties and failure process of concrete at high strain rates (Zhou et al., 2008; Xu et al., 2012). Few studies have reported the heterogeneous grouting-reinforced rock mass on SHPB numerical simulation.

The radial impact test of the same batch grouting specimens is conducted on the SHPB system. The failure process are recorded with a high-speed camera, which is helpful in analyzing the crack evolution law and failure mode. A 3D micro model of the standard size specimens is established by using the grid mapping method. LS-DYNA is used to simulate fracture process of the specimens under high strain rate. Based on the failure mode and the crack evolution process of the LS-DYNA model, the crack development law and its failure mechanisms are further researched to make up for the experimental deficiency. Moreover, the dynamic characteristics and energy dissipation law of the cemented rock are studied. The research results can provide reference for the grouting-reinforced rock mass of the deep roadway under an impact load.

2 Split Hopkinson pressure bar test

2.1 Preparation of the grouting specimens

The grouting specimens are mainly composed of the grouting material and graded gravel. The grouting materials include superfine cement slurry, vinyl acetate-ethylene (VAE), and defoamer. VAE is a type of polymer that serves as the binder. Some holes of the grouting specimens are minimized using the defoamer function. The mixing ratio is determined through indoor orthogonal tests and compared with the grouting injectability and effect and other factors (Avci et al., 2020), as shown in Table 1.

The graded gravel with a controllable particle size are selected as the injected material to simulate the sand layer with a large number of fine cracks. This work aims to minimize the porosity of the poured material and achieve the tightest packing state (Hwang et al., 2007). According to the Fuller gradation curve, the

TABLE 2 Grading of sand particles.

Particle size (mm)	Sorting sieve residue (%)	Accumulated sieve residue (%)	Consumption per liter (kg)
>4.75	0.00	0.00	0.000
4.75–2.36	35.87	35.87	0.534
2.36–1.18	25.10	60.97	0.373
1.18–0.60	17.42	78.39	0.259
0.60–0.30	12.66	91.05	0.189
0.30–0.15	8.95	100.00	0.133
<0.15	0.00	0.00	0.000

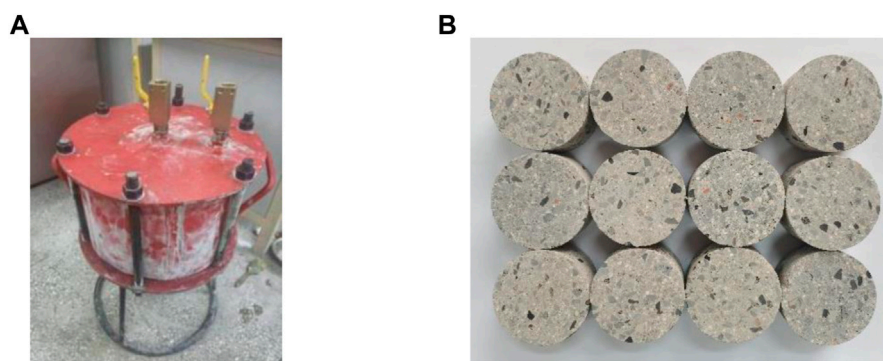


FIGURE 1
Grouting mould and specimens. (A) Grouting mould, (B) Grouting specimens.

gravel gradation is calculated by using Eq. 1, where P is the total amount of the material less than the particle size D_s . D_s and D_m are the screen size and the maximum particle size of the material, respectively.

$$P = 100 \left(\frac{D_s}{D_m} \right)^h \quad (1)$$

The value of h ranges from $1/3$ to $1/2$. When $h = 1/2$, the graded gravel theoretically reaches the maximum density. Accordingly, the value of h in the test is $1/2$. The particle size range is 0.15 – 4.75 mm, and the detailed parameters are shown in Table 2. Given that the 2.36 – 4.75 mm gravel has more impurities and poor quality, this part is replaced with crushed stone of the same particle size.

The specimens are obtained from the indoor grouting experiment. The size of the grouting mould is $\Phi 330$ mm \times 220 mm, as shown in Figure 1A. The mould is removed after the cement paste is consolidated. The specimens are cored and polished according to the requirement of the disk specimens ($\Phi 50$ mm \times 25 mm), placed into the curing box, and cured to the specified age, as shown in Figure 1B.

2.2 Split Hopkinson pressure bar test system and process

The impact test of the grouting specimens is conducted on the SHPB system, which is composed of a nitrogen pressure system, an elastic pressure bar system, and a data acquisition system. The schematic of the device is shown in Figure 2. The bullet, incident bar, and transmission bar are steel bars of $\Phi 37$ mm \times 400 mm, $\Phi 50$ mm \times $2,400$ mm, and $\Phi 50$ mm \times $1,200$ mm, respectively. The bar density is $7,800$ kg/m³, the bar elastic modulus is 210 GPa, the bar diameter of the contact part between the incident bar and the bullet is 37 mm, and the variable section length is 170 mm. Nitrogen is used as the power source, and the strain rate of the specimen is controlled by changing air pressure. The SHPB test uses five different air pressures which are 0.15 , 0.175 , 0.20 , 0.225 , and 0.25 Mpa respectively, and the corresponding strain rates are 24.8 , 29.1 , 33.2 , 39.3 , and 45.1 s⁻¹. Considering the randomness of the meso structure of the grouting specimens, the impact test of each group repeats five times, and the average values are taken as the strain rate and dynamic tensile strength of the specimens. A MIRO M310 high-speed camera of PHANTOM is used to capture the crack

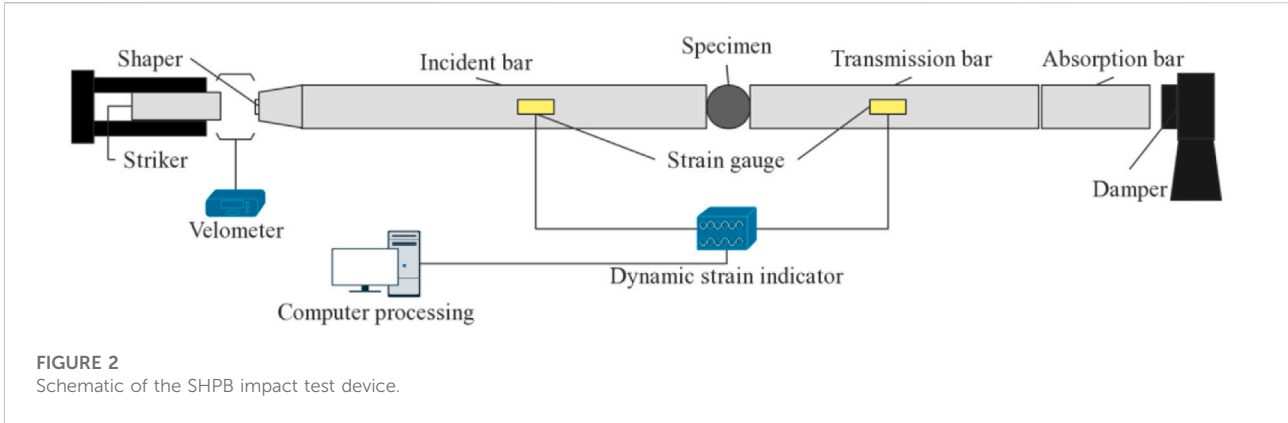


FIGURE 2
Schematic of the SHPB impact test device.

evolution process of the specimens with a resolution of 512×512 pixels and a frame rate of up to 10,800 fps.

Based on the assumption of the 1D stress waves and stress uniformity, the dynamic tensile stress, strain, and strain rate of the specimen are calculated by using Eq. 2 (KHAN et al., 2019), where $\sigma = (P_i + P_t)/2$. Variables P_i and P_t are the forces on the contact surface between the specimen-incident bar and the specimen-transmission bar, respectively, as shown in Eq. 3.

$$\begin{cases} \sigma_t = 2\bar{P} / \pi D_s L_s \\ \varepsilon_t = 2C_0 / D_s \cdot \int_0^t (\varepsilon_i - \varepsilon_r) dt \\ \dot{\varepsilon}_t = 2C_0 / D_s \cdot (\dot{\varepsilon}_i - \dot{\varepsilon}_r) \end{cases} \quad (2)$$

$$P_i = AE(\varepsilon_i + \varepsilon_r), P_t = AE\varepsilon_t \quad (3)$$

where A , E , and C_0 are the cross-sectional area, elastic modulus, and elastic wave velocity of the bar, respectively; D_s and L_s are the diameter and thickness of the specimens; and ε_p , ε_r , and ε_t are the strain signals of the incident, reflected, and transmitted waves, respectively.

2.3 Energy calculation of the split Hopkinson pressure bar test

In the SHPB test, the energy propagates in the form of stress wave. From the perspective analysis of energy composition, the incident energy W_I , reflected energy W_R , and transmitted energy W_T are calculated to study the energy consumption law and failure characteristics of the grouting specimens in the dynamic splitting process, respectively. The calculation formula is shown in Eq. 4 (Li et al., 2020).

$$\begin{cases} W_I = AEC_0 \int_0^t \varepsilon_i^2(t) dt \\ W_R = AEC_0 \int_0^t \varepsilon_r^2(t) dt \\ W_T = AEC_0 \int_0^t \varepsilon_t^2(t) dt \end{cases} \quad (4)$$

The contact surface between the specimen and the bar is small, the interface is coated with vaseline, and the consumed energy by friction can be ignored. According to the energy conservation law, the absorbed energy W_S by the specimen can be calculated by using Eq. 5.

$$W_S = W_I - (W_R + W_T) \quad (5)$$

where W_S is mainly dissipated in crushed dissipation energy W_{FD} , crushed kinetic energy W_K , and other dissipation energy W_O . W_K only accounts for about 5% of the total absorbed energy, and the W_O dissipation energy is negligible (Wen et al., 2019; YAO et al., 2019). Thus, $W_S = W_{FD}$.

3 Numerical simulation

3.1 Establishment of the split Hopkinson pressure bar model

When the SHPB model was established, the specimen is composed of cement mortar and gravel. This model considers the 1.18–2.36 mm gravel and 2.36–4.75 mm crushed stone because of the limitation of computer performance. A single gravel occupies a few grids due to the small size and large number of gravel inside the model, so it is simplified as a sphere. The pre-divided mesh avoids some problems, such as high magnitude and poor quality of grids, which can meet the roughness of the grit surface. The spherical aggregate can reliably simulate the response of the cement-based materials under impact load and greatly simplify the modeling and calculation time compared with the random shape aggregate model (Zhou et al., 2007; Kim et al., 2011; Xu et al., 2012).

The CT slices of the specimen are imported into AVIZO. The processing process is shown in Figure 3A. Approximately 2.36–4.75 mm crushed stone and 1.18–2.36 mm gravel are selected, and their number and volume of are obtained (Table 3).

According to the material information extracted from the above CT images, large and small gravels are randomly placed

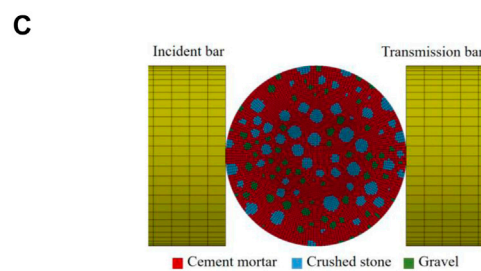
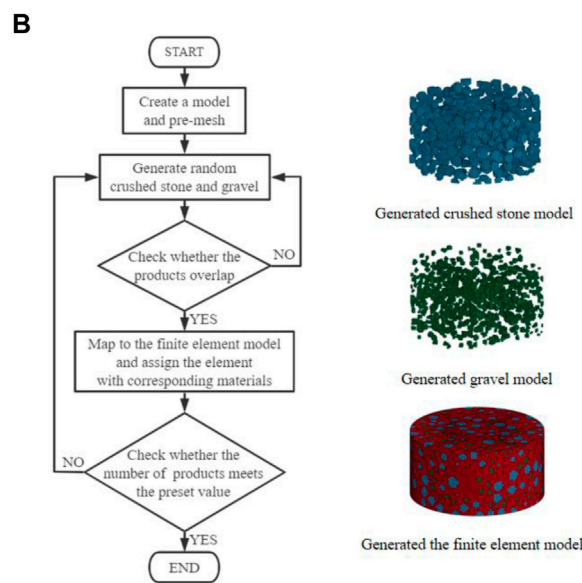
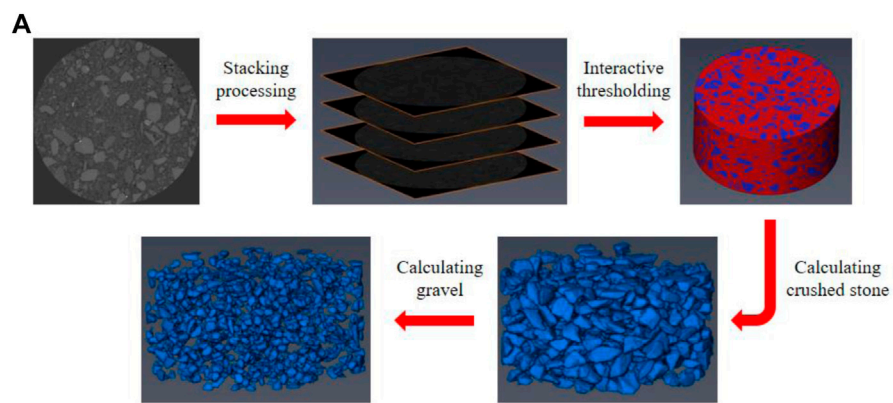


FIGURE 3

The meso-scal FEM model of grouting specimen. (A) AVIZO processing, (B) Flow chart of generating mesoscale finite element model of the grouting specimen, (C) Simplified model of the SHPB simulation test.

by using the Monte Carlo method. Finally, the model places 491 crushed stones, and the number of units is 73,300, accounting for 23.27%. The model places 876 gravels, and

the number of units is 16,128, accounting for 5.12%. The placement processes of sand and gravel are shown in Figure 3B.

TABLE 3 Specimen internal component.

Component	Number	Volume/mm ³	Proportion %
Crushed stone	491	11,809	24.07
Gravel	876	2,589.5	5.28

The established 3D model of the SHPB test and its physical and geometric parameters are consistent with the test. The model placement is shown in Figure 3C. The model adopts a solid164 unit, a mapping grid division, and a set of automatic surface contact between the bars and the erosion contact between bars—the specimen and its each component. The initial velocity of the bullet when loading is consistent with the test.

3.2 Holmquist–johnson–cook constitutive model

The HJC model can better describe the dynamic response of the materials at high strain rates. This constitutive model is proposed for the cement-based materials and comprehensively considers the damage evolution, compaction, and crushing effects and hardening characteristics (Xu et al., 2016). The HJC model includes yield surface, state, and damage evolution equations. The yield surface equation takes into account the damage and strain rate, and it is expressed by the dimensionless equivalent stress. The state equation describes the relationship between the hydrostatic pressure and the volumetric strain in a piecewise manner. The damage equation is described by the cumulative plastic strain (equivalent plastic strain ϵ_p and plastic volumetric strain μ_p), as shown in Figure 4.

The HJC model has 21 parameters. According to the method illustrated in the literature (Xie et al., 2019), the basic physical parameters of RO, G, F_C , T, P_{crush} , and μ_{crush} are obtained from the laboratory test, and crushed stones and gravel parameters are provided by the manufacturer. The parameters of the state and damage equations can be found in the literature (Wang et al., 2021;

Lv et al., 2018). The rest of the parameters are determined through the simulation test. The material parameters are shown in Table 4.

The failure mode during calculation is controlled by using the element erosion technology to avoid the negative volume or large deformation of the element. When the element exceeds a certain threshold, it will be deleted because of failure, and the isolated failure element will manifest crack. The inherent failure criterion of the HJC model is the minimum fracture strain and the damage degree, and the maximum principal strain is set as 0.1 (LV et al., 2019). If the given value exceeds the element erosion criterion, the cement mortar, crushed stone, and gravel are considered to the failure.

4 Test verification and result analysis

4.1 Validity verification

In the SHPB and simulation tests, the measurement of the point of stress wave is set on the central unit of the incident and transmission bars, and the similarity of waveforms between them can verify the correctness of the model (Lv et al., 2022). The typical waveform of the dynamic tensile test is shown in Figure 5.

The measured waveforms through the laboratory and the simulation tests are in good agreement, and the characteristic errors of the two pulse peaks and durations are within 5%. The bearing loads at both ends of the specimen are basically the same, achieving dynamic balance and eliminating the influence of inertia effect (Dai et al., 2010). The feasibility of impact failure based on LS-DYNA is verified according to the test results.

4.2 Analysis of the test results

4.2.1 Stress–strain curve of the specimens under three strain rates

Figure 6 shows the stress–strain curves of the specimens under three impact rates. A good correspondence can be

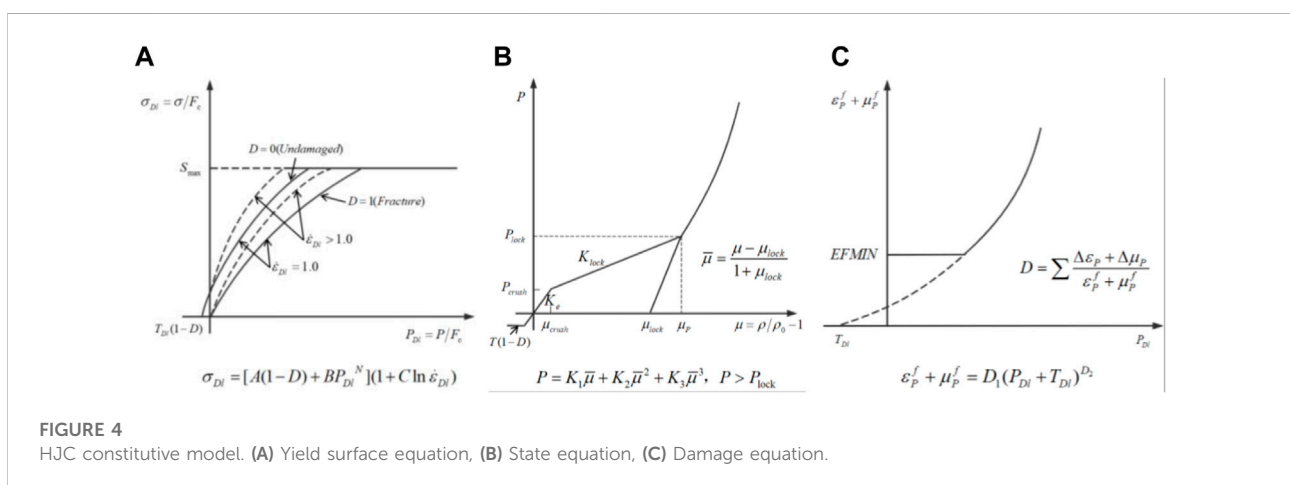


TABLE 4 Parameters of the HJC constitutive model.

Parameters	Cement mortar	Crushed stone	Gravel	Parameters	Cement mortar	Crushed stone	Gravel
MID	1	2	3	SFMAX	7	4	7
RO (kg/m ²)	1970	2,660	1,650	PC (MPa)	5.3	40	12.4
G (GPa)	0.81	20.8	1.36	UC	0.0043	0.001	0.0075
A	0.58	0.9	0.66	PL (GPa)	0.104	3	0.255
B	1.335	1.8	1.335	UL	0.15	0.1	0.1
C	0.007	0.02	0.0023	D1	0.04	0.04	0.04
N	0.575	0.84	0.845	D2	1	1	1
FC (MPa)	15.9	120	37.2	K1 (MPa)	8.5×10^4	3.9×10^4	3×10^4
T (MPa)	1.33	10	2.79	K2 (MPa)	-1.71×10^5	-2.23×10^5	-2×10^5
EPSO	1	1	1	K3 (MPa)	2.08×10^5	5.5×10^5	1.9×10^5
EFMIN	0.003	0.01	0.01	FS	0	0	0

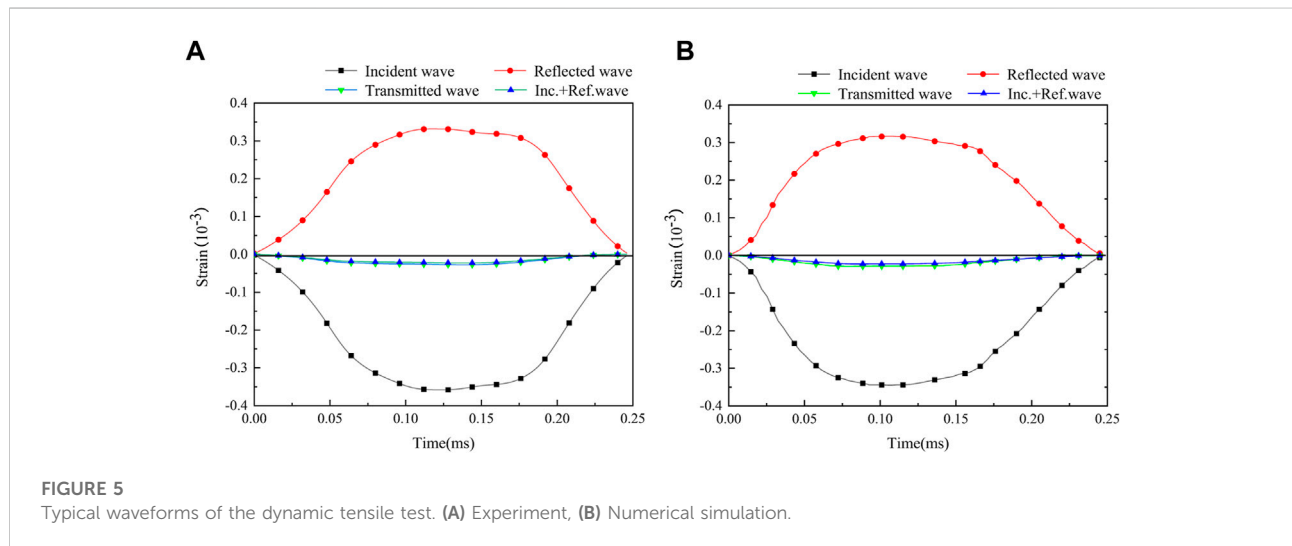


FIGURE 5 Typical waveforms of the dynamic tensile test. (A) Experiment, (B) Numerical simulation.

observed between the test and the simulation curves. The dynamic tensile strength and peak strain of the specimens increase with the increase in the strain rate, and the envelope area of the curve gradually increases, which is a strain rate-dependent material. The high tensile performance of the specimens at a high strain rate has a close connection with the input energy. The input energy increases with the increase in strain rate, and the specimen is unable to release a large amount of energy in a short period of time, resulting in tensile strength increase.

4.2.2 Crack evolution process of the specimen

In addition to the strength characteristics, the crack propagation process on the specimen surface is also the key to the dynamic damage evolution process. Figure 7 shows the whole process of dynamic splitting of the grouting specimens captured

with a high-speed camera. The stress wave of the specimen transmitters from the left side and the contact time is defined as zero. The selected pictures are used to analyze the failure process.

When $\dot{\epsilon}$ is 24.8 s^{-1} , the center of the specimen showed a fine crack of about $93 \mu\text{s}$. At $186 \mu\text{s}$, the main crack in the center widens and expands to both ends. At $279 \mu\text{s}$, the main crack basically penetrates, and the failure zones of both ends are relatively small. In comparison with $\dot{\epsilon} = 24.8 \text{ s}^{-1}$ and $\dot{\epsilon} = 33.2 \text{ s}^{-1}$, the crack at the center changes to about $93 \mu\text{s}$. At $279 \mu\text{s}$, the main crack expands to two ends. Meanwhile, secondary cracks appear at two ends. Furthermore, two ends appears at two wedge-shaped failure zones at $651 \mu\text{s}$.

In comparison with $\dot{\epsilon} = 33.2 \text{ s}^{-1}$, when $\dot{\epsilon}$ is 45.1 s^{-1} , the failure law is almost the same before $186 \mu\text{s}$, and the

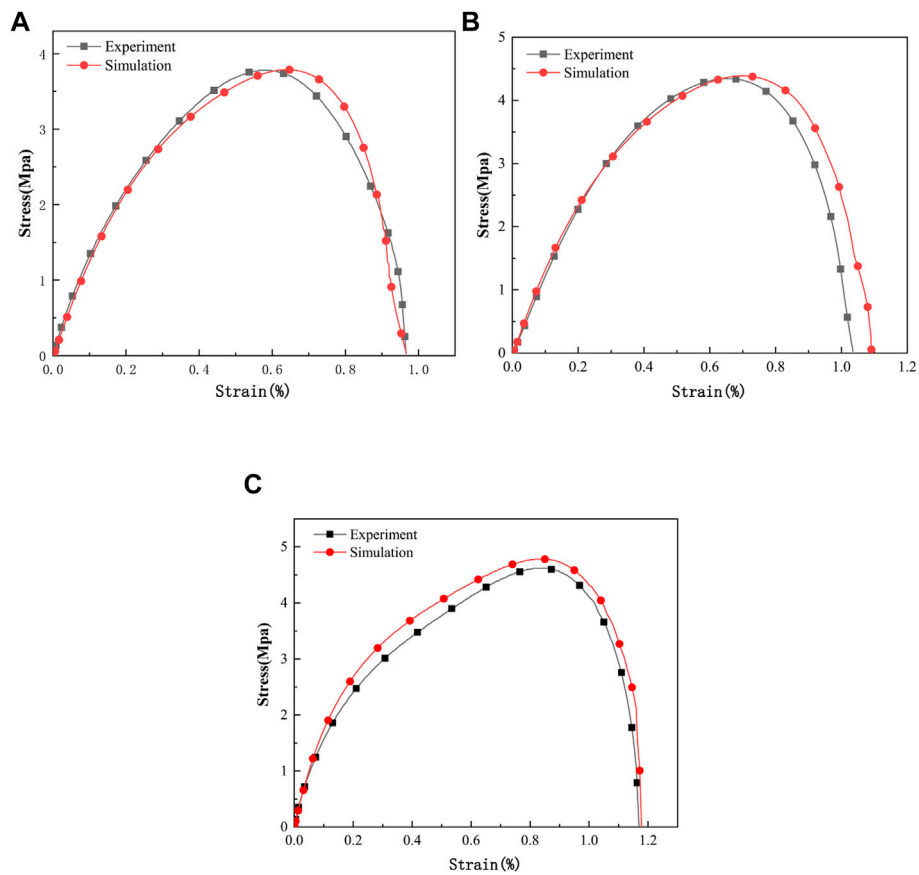


FIGURE 6

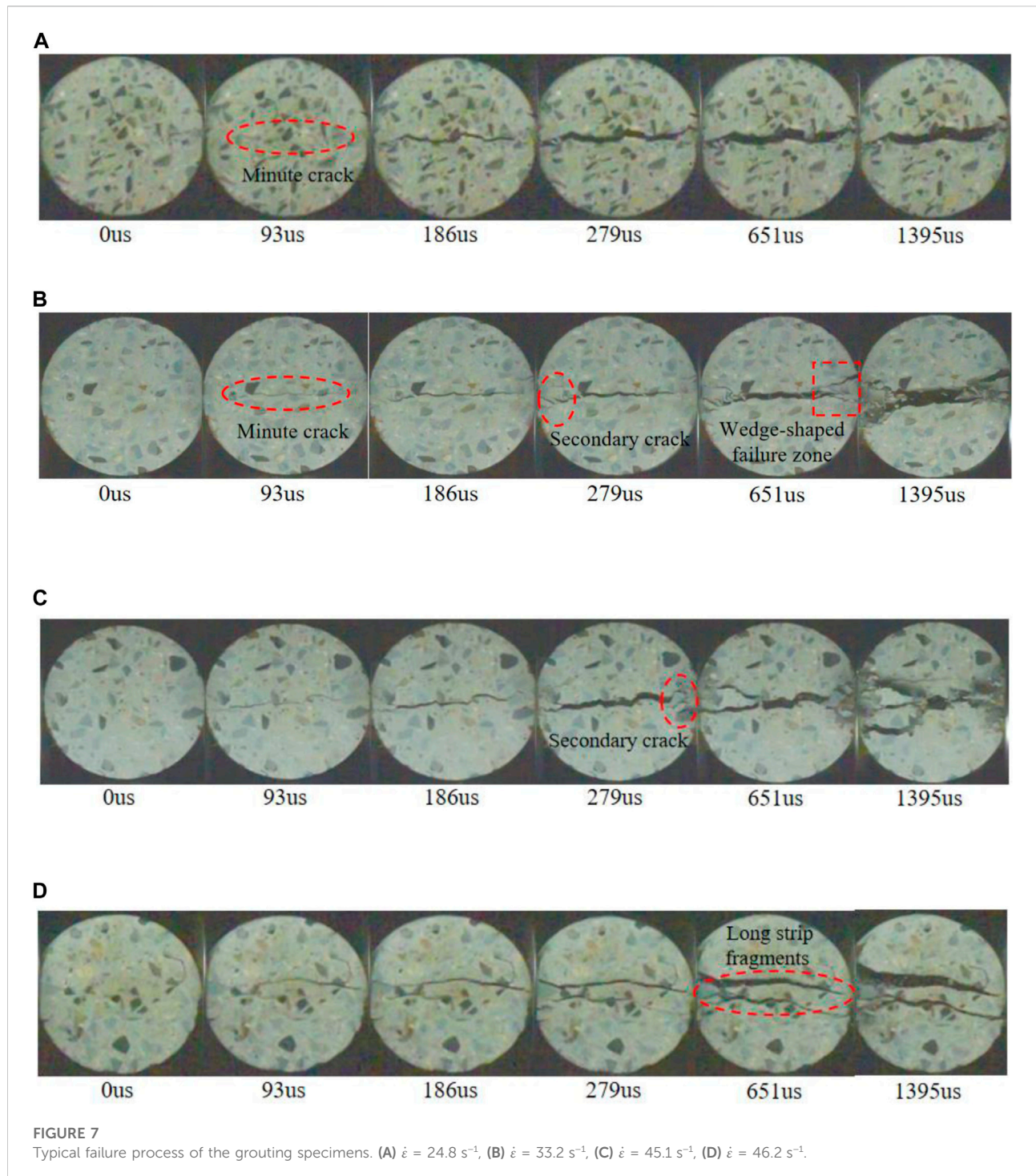
Three stress–strain curves of the experiment and simulations. (A) $\dot{\epsilon} = 24.8 \text{ s}^{-1}$, (B) $\dot{\epsilon} = 33.2 \text{ s}^{-1}$, (C) $\dot{\epsilon} = 45.1 \text{ s}^{-1}$.

corresponding primary crack is significantly wider at $279 \mu\text{s}$. The number of secondary cracks at two ends increases. At $1,395 \mu\text{s}$, the center failure is more serious, the wedge-shaped failure zone at two ends becomes larger, and the breakage degree is more serious. Excessive input energy induces a large number of secondary cracks, and the failure zone near the incident bar significantly increases. When $\dot{\epsilon}$ is 46.2 s^{-1} , two penetrating cracks successively appear in the central position, the failure zones at both ends decrease, and the failure surface of the specimen increased, which are helpful to absorb more energy.

In summary, when the grouting specimens are fractured, the cracks initiate from the center to two ends, and tensile stress produced by the pulse wave is perpendicular to the loading direction at the center of the specimens. When the tensile stress exceeds its tensile strength, the crack initiates and then expands to both ends along the loading direction. The width of the main crack also increases. Before the first pulse finishes ($279 \mu\text{s}$), the main crack did not fully cut-through the specimens, and the wedge failure zone is small at two ends. When the compressive and shear stresses are

combined with the specimen's contact surfaces, two ends of a secondary crack first emerge and form a wedge failure zone, which eventually connected with the main crack and penetrated the whole specimen. The crack initiation time of the high strain rate is earlier than low strain rate in the middle of the specimen. The crack width and the failure zone at two ends increase with the increase in the strain rate. When the strain rate changes from 24.8 to 33.2 s^{-1} , the failure mode of the specimens is similar, namely, the center split and the main crack. When $\dot{\epsilon}$ is 46.2 s^{-1} , the failed fragment of the specimen is similar to a strip with two main cracks, consistent with the results in the literature (Khan et al., 2019).

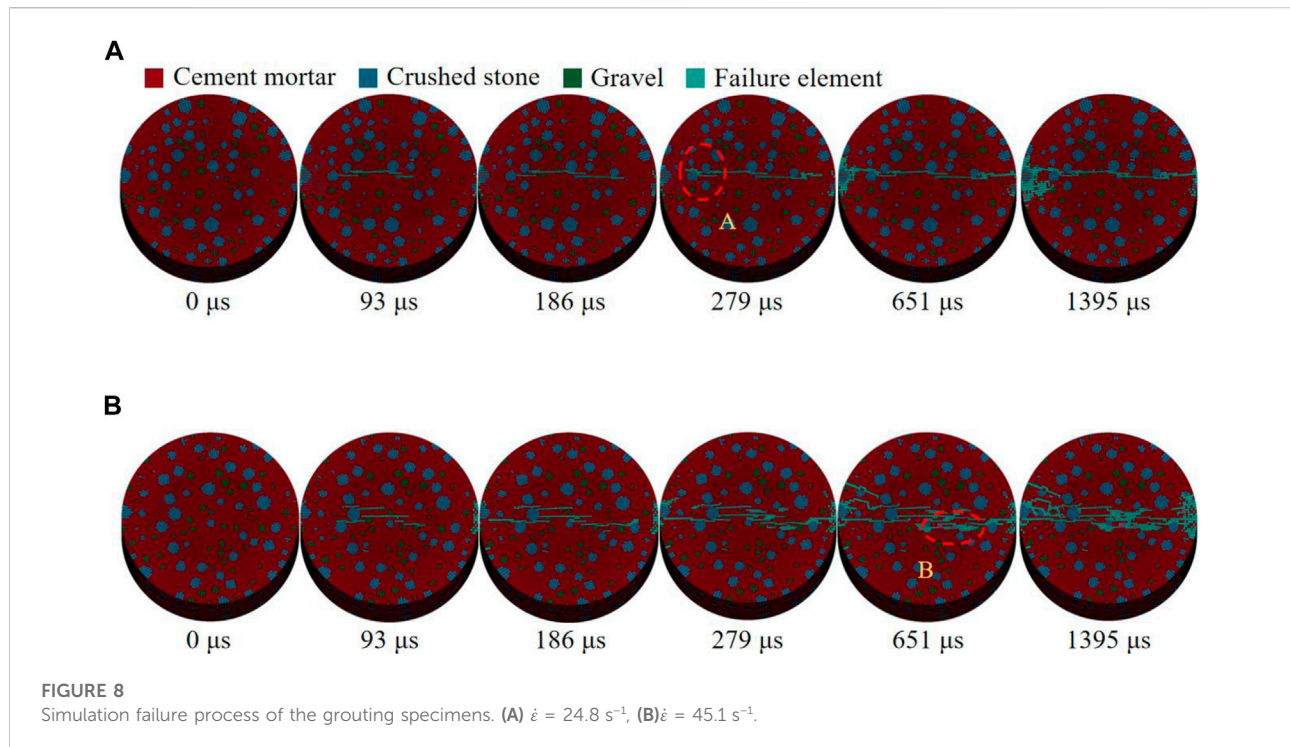
When the path of crack expansion encounters the crushed stone and gravel, cracks mostly expand along the edge of the gravel, and rarely penetrates the crushed stone and gravel. Because the strength of crushed stone and gravel are higher than cement mortar, also the water film layer of the gravel surface results in higher water cement ratio, and the structure of interfacial transition zone is loose, which results in cracks extension along the edge of gravel.



4.2.3 Crack evolution process of the model

When the strain rates change from 24.8 to 33.2 s^{-1} , the failure modes of the specimens are roughly similar. The strain rates of 24.8 and 45.1 s^{-1} are shown in the simulation process due to the paper limitation (Figure 8). The simulation results are in good agreement with the experimental results, which verifies the

correctness of the 3D mesoscopic model. When the model is impacted, its central element first failed, and few failure elements can be observed at both ends. The crack rapidly spread from the center to both ends. After 279 μs , the number of failure elements at both ends and the range of wedge failure zone rapidly increased. When $\dot{\epsilon}$ is 45.1 s^{-1} , the input energy is larger, and



the number and range of central failure units are greater than 24.8 s^{-1} strain rate. According to the failure results, the main crack width in the center is wider, the number of secondary cracks is higher, and the failure zone is greater when $\dot{\epsilon}$ is 45.1 s^{-1} .

The cracks extend along the cement paste which is in good agreement with the experimental results (such as area A). Spreading through the gravel crack is almost perpendicular to the gravel surface, and the crack width is obviously bigger than that around the gravel. When the extension of crack encounter the gravel, a few cracks which are perpendicular to the gravel coarse gradually (such as area B), According to the theory of stress intensity factors in fracture mechanics (Cai et al., 2018), crack shape, size and the far field stress can affect the stress field intensity of crack tip. When the intensity factor of crack tip reaches the fracture toughness of gravel, the crack continues to expand through the gravel, and release energy in the form of fracture energy.

The 3D cracks inside the specimen have complex a topological structure, making it difficult to extract spatial cracks and quantitatively analyze the crack growth process. However, the numerical model is suitable for quantitative analysis of the crack growth process. The crack growth is show in Figure 9A, the cracks still expands from the center of the specimens to both ends. After the main crack is basically connected, the failure zone also expands at two ends, which is consistent with the cracks growth process on the model surface. This model is divided into 315,000 meshes, and the number of failure elements is counted at each calculation time.

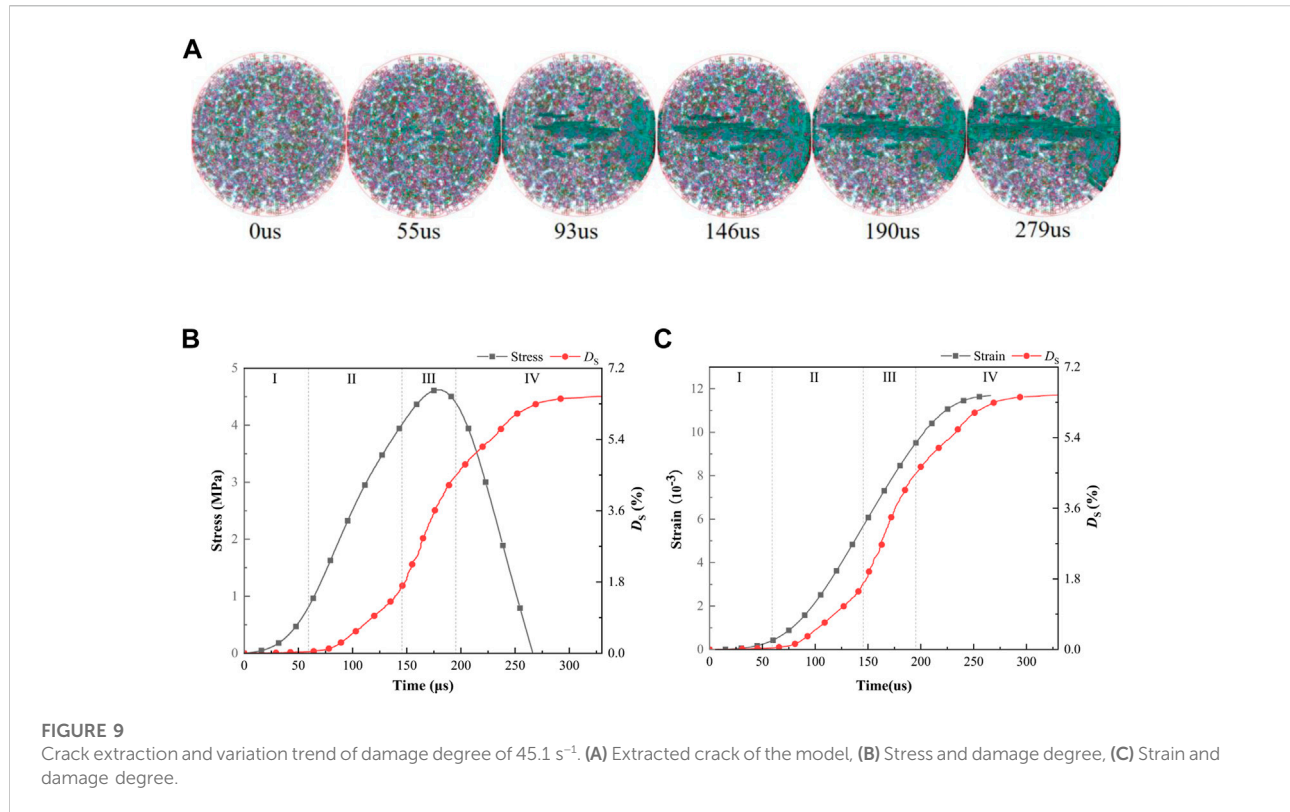
The damage degree parameter is introduced to describe the damage degree of the model, namely, $D_S = N_S/N_A$, where N_S is the number of failure elements, and N_A is the total number of model elements at given time. The relationship is plotted between stress, strain, and crack volume base on 45.1 s^{-1} , as shown in Figures 9B,C. According to the crack evolution process curves, the damage process of the model can be divided into four stages:

Stage I (no crack stage): $0\text{--}53 \mu\text{s}$, the stress level of the model is low, and the model does not occur crack. At the moment, the strain of the model is small.

Stage II (slow development stage): $53\text{--}146 \mu\text{s}$, the model occurs few cracks at first, and it continue to expand with the stress increase. At this time, crack number and strain value are still small. At $146 \mu\text{s}$, the number of failure elements and D_S reaches 5,374 and 1.7% respectively.

Stage III (accelerated growth stage): $146\text{--}190 \mu\text{s}$, the stress exceeds 4.03 MPa, the crack rapidly expands, and the growth rate of D_S significantly increases. After reaching the peak stress, the stress rapidly declines, but the strain continues to increase. The number of internal failure elements and D_S reaches 13,583 and 4.3% at $190 \mu\text{s}$, respectively.

Stage IV (crack penetration stage): After $190 \mu\text{s}$, the stress reaches the peak and then decreases sharply, the cracks of the specimen continue to expand until failure. The number of internal failure elements gradually slows growth. At $330 \mu\text{s}$, the number of failure elements reaches 20,430, and D_S reaches 6.5%. The crack evolution process of the model is roughly similar



to the strain curve. Thus, the crack volume can approximately reflect the strain value.

4.2.4 Analysis of the energy dissipation process

Energy is the driving force behind material failure (Wen et al., 2020b; Wei et al., 2022), and energy dissipation causes everything from microscopic damage to macroscopic fragmentation of the model. The energy dissipation rate is defined as λ , namely, $\lambda = W_s/W_I$, to compare the degree of absorbed energy under different strain rates. Approximately 0.175 and 0.225 MPa impact air pressures are applied based on the original tests to comprehensively analyze the impact failure characteristics and energy change law of the model. In order to obtain the incident energy, The test parameters are substituted into Eqs 4, 5, and the absorbed energy and transmitted energy at five strain rates are obtained, as shown in Table 5.

In Table 5, the incident energy value gradually increases with the increase in strain rate. The incident energy, transmitted energy, and absorbed energy at five strain rates in Table 5 are fitted to obtain the energy relationship curves, as shown in Figure 10. The fitting curves of the incident energy and transmitted energy show increasing trends. The growth scope of the transmitted energy slows down with the increase in incident energy, as shown in Figure 10A. When the incident energy impacts on the model are low, the microcracks are less,

and the crack propagation scope is small. The crack number and damage range continuously increase with the increase in incident energy, and the cracks weakens the propagation of transmitted waves, resulting in a slow increase in transmitted energy. The energy dissipated by the crushed specimen linearly grows with the development of the incident energy, as shown in Figure 10B. The energy dissipation rate (λ) is basically constant with the increase in the incident energy. The fluctuation value changes from 10% to 13%, as illustrated in Table 5, which shows the strain rate independence.

The energy curve of the model is drawn using the strain rate of 45.09 s^{-1} as an example and the three energies determined utilizing Eqs 4, 5, as shown in Figure 11A. The three energies curves show a slow growth, continuous linear growth and stabilization trend. The incident energy greatly increased. The maximum transmission energy is only 0.165 J, and the growth rate is the smallest due to the low tensile strength of the specimen (4.62 MPa). The failure process of the specimen is analyzed using the stress–strain curve and failure characteristics of the specimen. When time is 0–53 μs , the incident energy slowly increases, and the stress pulse wave enters the rising elastic deformation stage. The dissipated energy of this stage is almost zero, no crack initiated, and the model stores a large amount of elastic energy. From 53 to 190 μs , the incident energy and reflected energy rapidly increase, but the transmitted energy slightly increases. When the stress of the model is greater than the tensile strength,

TABLE 5 Calculation results of energy.

Impact pressure (MPa)	Strain rate (s ⁻¹)	Tensile strength (MPa)	W _I (J)	W _R (J)	W _T (J)	W _S (J)	λ
0.15	24.8	3.78	15.713	13.867	0.068	1.778	0.113
0.175	29.1	4.07	22.333	19.678	0.109	2.546	0.114
0.2	33.2	4.35	30.817	27.059	0.141	3.617	0.117
0.225	39.3	4.50	36.435	32.180	0.157	4.098	0.112
0.25	45.1	4.62	40.608	35.755	0.165	4.688	0.115

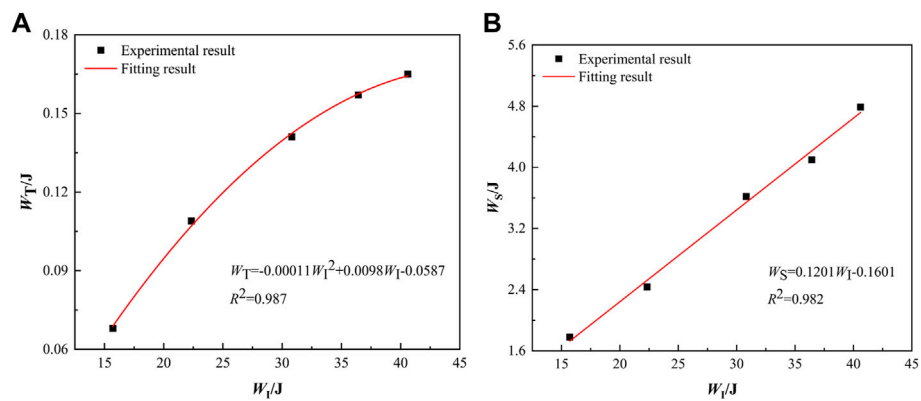


FIGURE 10 Energy relation curve. (A) Relationship between W_I and W_T , (B) Relationship between W_I and W_S .

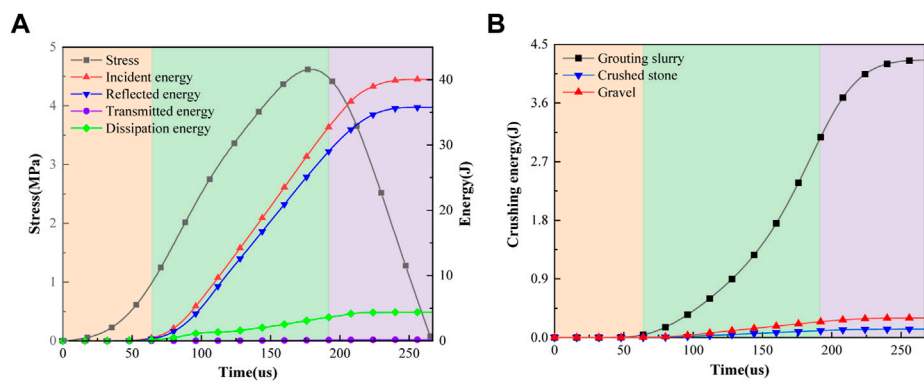


FIGURE 11 Energy curve of the grouting specimen. (A) Energy dissipation curve of the specimen, (B) Breakup energy curves of each component.

the dissipated energy of the specimen increases due to crack growth. From 190 to 267 μs, the stress of the model decreases after reaching the peak strength, and the original and new cracks in the specimen continued to expand. The release of elastic energy also aggravates the failure of the model, and the

dissipation energy slightly increases and then tended to a constant value.

The energy evolution process of each material component of the specimen model cannot be measured in a laboratory. However, the dissipated energy of the different components

can be described by using a 3D meso-numerical model. Take $\dot{\epsilon} = 45.1 \text{ s}^{-1}$ as an example, as shown in Figure 11B. The dissipation energy in the model is 4.78 J, which is within 5% of the experimental value of 4.69 J. Before 53 μs , each component of the model is in the elastic stage and basically did not consume energy. From 53 to 190 μs , the dissipated energy of the cement mortar increases. Internal cracks and fine cracks start to appear when the local stress in the cement mortar exceeds its tensile strength. The strength of the crushed stone and gravel is higher than that of the cement mortar, and most of the particles are not failure, so the number of failure units is few. The dissipation energy of the crushed stone and gravel slowly increases, and the dissipation energy of the gravel is slightly greater than that of the crushed stone. From 190 to 267 μs , the model significantly breaks, and the dissipated energy of the cement mortar, gravel and crushed stone accounted for 90.8%, 6.5%, and 2.7% of the dissipated energy of the model, respectively.

When the strain rate is 24.8–45.1 s^{-1} , the proportion of dissipated energy of the cement mortar is above 90%. When the specimen fails, the cement mortar is the first to be significantly damaged. Crushed stone and gravel are bonded by using a cement mortar. Thus, the strength of the cemented specimen is most affected by the strength of the cement mortar.

5 Conclusion

Different strain rate dynamic splitting tensile tests of the cemented specimens are carried out by using the SHPB test device. The dynamic failure process and energy dissipation law of the cemented specimens are studied. A 3D mesoscopic numerical model is established by using the SHPB, and the accuracy of the numerical simulation is verified by comparing with the SHPB test result. The main conclusions are as follows:

- (1) The dynamic tensile strength and peak strain of the cemented specimens increase with the increase in strain rate. It is a strain rate-related material.
- (2) When the specimens are destroyed by impact load, the cracks initiated at the center and spread to both ends of the specimen along the load direction. The wedge-shaped failure zone at both ends expands after the first pulse wave completed. When the strain rates changed from 24.8 to 33.2 s^{-1} , the failure morphology of the specimens is similar with the splitting failure and the main crack at the center. When the strain rate is 46.2 s^{-1} , the failure mode of the specimens is a strip fragment with two main cracks at the center.
- (3) The crack growth process in the model is quantitatively describe based on LS-DYNA software. The damage of the specimen is divided into four stages: no crack stage, slow crack development stage, accelerated crack growth stage and

crack penetration stage. When the specimen broke, the energy dissipation rate fluctuates from 10% to 13%, and the dissipated energy of the cement mortar accounts for more than 90% of the total dissipated energy. The cement mortar is destroyed first and most severely, and its strength has a great influence on the strength of the grouting specimen.

- (4) In comparison with the indoor SHPB test result, the 3D meso-model of the grouting specimens established based on the 3D reconstruction technology and LS-DYNA software can better simulate the crack evolution process and failure mode of the specimen, which can quantitatively analyze the energy consumption of the internal components. (XU and WEN, 2016), (LI and XU, 2009).

Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

Author contributions

C-XZ proposed the research methods and ideas of this article, J-XS completed the experiment of this article, JG and F-EW completed the writing of this article.

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Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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