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# A method for calculating permanent displacement of seismic-induced bedding rock landslide considering the deterioration of the structural plane

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The mechanism of seismic-induced bedding rock landslide is distinct from that of slope instability/landslide in normal gravity conditions; their failure modes are mainly characterized by vibration deterioration effect of rock mass structural plane due to a seismic loading, which has a significant effect on the stability of the bedding rock landslide. Several advanced methods have been proposed to assess earthquake-induced bedding rock landslide. However, the quantitative evaluation of the vibration deterioration effect of structural plane, along with its application in the dynamic stability analysis of bedding rock slopes, remains a challenging topic that requires further study. In this study, on the basis of the analysis of the cyclic shear condition and the cyclic shear test of the structural plane, the expressions to calculate the dilatancy angle and basic friction angle of structural plane under cyclic shear loading are studied. A deterioration formula for structural plane shear strength is proposed, which fully considers the deterioration effect during cyclic shear. Furthermore, a new calculating method of the seismic-induced permanent displacement of the bedding rock landslide, which introduces the deterioration effect of the structural plane, is developed. A case study was used to compare the permanent displacement calculated with the proposed method with those obtained using the Newmark and Qi methods, which demonstrates the effectiveness and applicability of the proposed method.

## KEYWORDS

structural plane, deterioration effect, seismic-induced bedding rock landslide, dynamic analysis model, permanent displacement

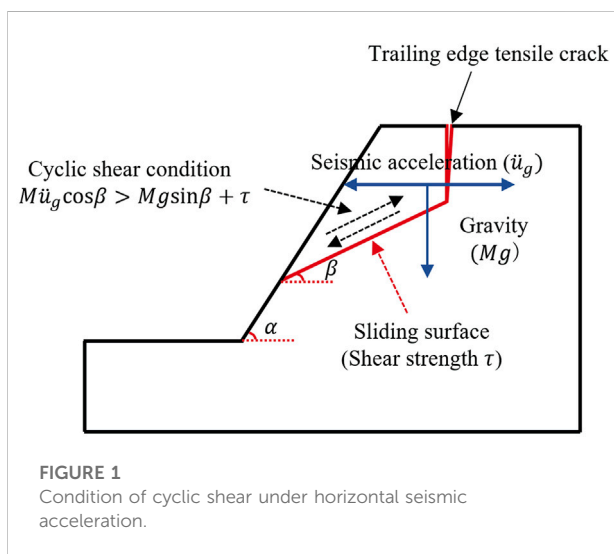
# 1 Introduction

When the magnitude of an earthquake exceeds Ms 4.0, landslides can be induced in sensitive areas; when the magnitude of an earthquake exceeds Ms 6.0, many landslides can be induced simultaneously (Keefer 1984; Rodríguez et al., 1999; Keefer 2000). Larger earthquakes can induce thousands of landslides over a wide area. For example, the Wenchuan Ms 8.0 earthquake in China triggered nearly 200,000 landslides, making it the largest, densest, widest, and most catastrophic seismic-induced landslide events caused by a single earthquake ever recorded. Bedding rock landslide is a common type of rock landslide, and is controlled by the interlayer structural planes of the rock mass. When subjected to an earthquake or dynamic loads, such slopes are prone to the occurrence of overall bedding slip. In recent years, earthquakes have induced many bedding rock landslides, such as the Daguangbao and Tangjiashan landslides caused by the 2008 Wenchuan earthquake (Ms 8.0) in China (Burchfiel et al., 2008; Hu et al., 2009; Huang and Li, 2009; Cui et al., 2021), and the Arato-sawa landslide caused by the 2008 Iwate-Miyagi Naoriku earthquake (Ms 7.0) in Japan (Moriya et al., 2010; Ryoichi et al., 2010; Setiawan et al., 2016). These seismic-induced landslides lead to serious losses of life and property. Therefore, the study of seismic-induced bedding rock landslide is of great and practical significance.

When the seismic loading is strong, the cyclic shear phenomenon occurs along the interlayer structural plane and the slipping body consequently moves along the structural plane. As demonstrated in Figure 1, taking the horizontal seismic acceleration as an example, when the upward component of the horizontal seismic force along the interlayer structural plane ( $M\ddot{u}_g \cos\beta$ ) is greater than the resultant force of the shear strength of the interlayer structural plane and the weight component of the sliding body ( $Mg \sin\beta$ ), a cyclic shear

mode of the slipping body will occur. During this process, the initial morphological characteristics of the interlayer structural planes are destroyed in terms of the shearing or wearing of the undulations, resulting in the deterioration of the shear strength of the interlayer structural plane which directly influences the stability of the slope. Extensive studies have been conducted on the cyclic shear strength of the structural plane (Souley et al., 1995; Homand et al., 2001; Jafari et al., 2003; Premadasa et al., 2012; Mirzaghorbanali et al., 2014; Zheng et al., 2015; Li et al., 2021a; 2021b; Zhou et al., 2021; Li, 2022a; 2022b), and it was found that, when rock mass is sheared along a structural plane, undulations and the friction of the contact sections of the structural plane have a direct effect on the shearing resistance. Under the earthquake action, the seismic loading causes vibration deterioration of the shear characteristics of the structural plane. This is mainly shown in the following aspects: 1) the peak shear strength of the structural plane decreases with the increase of relative shear velocity; 2) under the cyclic shear (from seismic loading), the undulant angle  $\alpha_k$  decreases; and 3) under the seismic loading, the frictional coefficient of the structural plane decreases gradually. In addition, previous studies (Tulinov and Molokov, 1971; Papaliangas et al., 1990; Indraratna et al., 1999; Indraratna et al., 2005; Mroz and Giambanco, 2015; Dong et al., 2020) have demonstrated that under a seismic cyclic shear loading, structural plane undulations are sheared and worn gradually, and a large amount of debris is generated and filled in the inside of the contact sections, which directly affects the frictional characteristics of the structural plane. Therefore, the degradation effect of the frictional characteristics of the structural plane must be considered when performing the stability calculation of bedding rock landslide under a seismic cyclic shear loading.

Wang and Zhang (1982) found that the movement rate and cumulative displacement of rock blocks have a direct deterioration effect on the dynamic frictional coefficient, and initially tried to incorporate the degradation effect of the structural plane into the calculation method of the sliding displacement of rock slopes. Crawford and Curran (1981, 1982) also proposed a method of calculating the seismic permanent displacement of rock slope introducing the deterioration effect of cumulative displacement and motion velocity on structural plane. Based on the work by Wang and Zhang (1982) and Crawford and Curran (1981, 1982), Qi (2007) proposed a seismic permanent displacement calculation method of planar sliding and wedge sliding problem considering the effect of shear rate and cumulative relative displacement on the deterioration of structural surface roughness. Through the experimental analysis of direct shear experiment and shaking table test, Bakun-Mazor et al. (2012) found that, under the strong ground motion, the dynamic analysis of rock slopes should consider the effect of shear velocity on the friction force of the structural plane. By integrating the influencing factors of



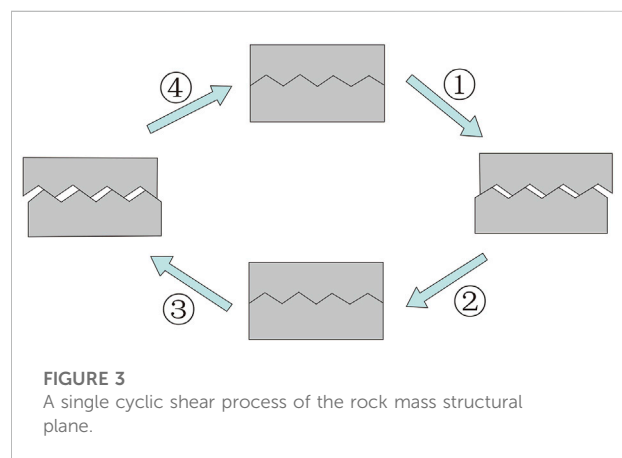
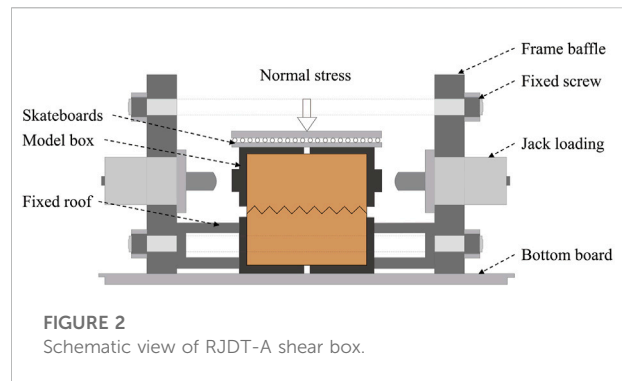
vibration wear and relative velocity, Ni et al. (2013) presented mathematical expressions for the vibration degradation effect of a structural face through experimental research, and applied them to the calculation of the dynamic stability analysis of rock slopes using numerical simulation method. Liu et al. (2016) found that the shear strength of structural plane was reduced due to the wear of wave angle and relative velocity between rock blocks during the process of earthquake action, and a mathematical model to calculate the deterioration of the structural plane and a numerical calculation procedure were established. Based on the Newmark and residual thrust methods, Cen (2017) proposed a theoretical model and dynamic analysis with time-history, considering the entire shear process deterioration effect of bedding rock landslide. Dong et al. (2020) proposed deterioration formulas for structural plane shear strength parameters under cyclic shear loading, and on the basis of the cyclic structural plane shear test, they proposed a calculation method for rock landslide displacement by introducing the deterioration effect of the structural plane. However, existing researches on bedding rock landslide stability calculation introducing the effect of structural plane degradation have not yet yielded a definitive and well-recognized method, and the analysis of the dynamic stability of bedding rock landslide with consideration of structural plane vibration degradation required in-depth study.

In conclusion, the effect of seismic loading on the stability of bedding rock landslide lies in the influence of seismic loading on inertial force and the deterioration effect of seismic loading on shear strength (frictional coefficient) of interlayer structural plane. The present study, firstly, investigated the shear-strength deterioration effect of a structural plane. Then, based on the simplified dynamic calculation model of the bedding-rock landslide and introducing the vibration-induced deterioration effect of the structural plane, a new calculating method of the seismic-induced permanent displacement of the bedding rock landslide is further developed. And the motivation of this study is to further improve the understanding of seismic-induced landslide mechanisms by means of a relatively systematic investigation into the dynamic characteristics, instability mechanisms, and stability evaluation methods of bedding-rock landslides under seismic loading.

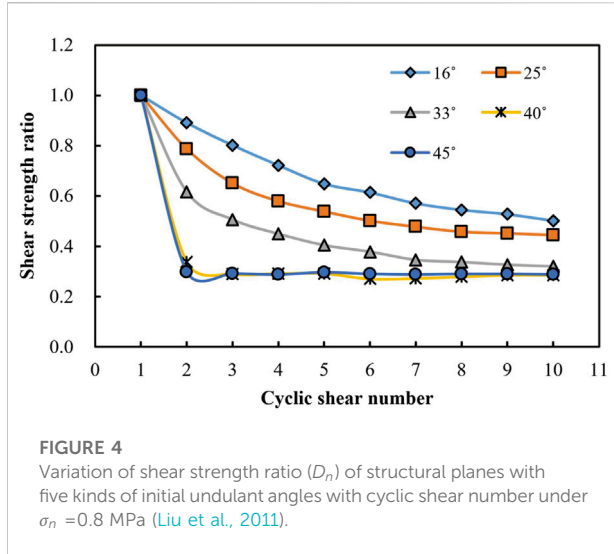
## 2 Deterioration of the structural plane under the cyclic shear

### 2.1 Cyclic shear test on structural plane

It is difficult to obtain and sample natural structural planes with complex surface undulations, and the consistency related to the sampling cannot be guaranteed. However, it has been proved that it is feasible to use rock structure samples prepared from cement mortar and other similar materials to replace the surface



morphology and undulation of natural structural planes (Einstein et al., 1983; Plesha, 1987; Yang et al., 2001; Jafari et al., 2003; Li et al., 2008; Du et al., 2011). When using simulated structural planes to replace natural structural planes for direct shear tests, the wear degree and failure mode of simulated structural planes are similar to those of natural structural planes. The existing research results (Ladanyi and Archambault 1970; Yang et al., 2001; Jafari et al., 2003; Shen and Zhang, 2010) show that although there are differences between the sawtooth structural plane and the natural structural plane, the shear test with sawtooth structural plane is usually reasonable and can catch the surface morphology and undulations of the structural plane. Using cement mortar as the similar material, Liu et al. (2011) prepared sawtooth structural plane specimens with different initial undulant angles of 16°, 25°, 33°, 40° and 45°, respectively. Using an RJDT-A shear testing device (Figure 2), Liu et al. (2011) carried out cyclic shear tests on structural planes under four kinds normal stresses of 0.8, 1.6, 2.4, and 3.2 MPa, respectively. Due to the limitations of the RJDT-A shear testing device, the relative maximum shearing displacement was set to be  $\pm 10$  mm, and the cyclic number was set to be 10 repetitions. In the shear process, the lower shear box remains stationary, and the specimen is sheared by the



horizontal motion of the upper shear box. A single cyclic shear process of the rock mass structural plane is illustrated in Figure 3.

## 2.2 Shear strength deterioration effect

Introducing the shear strength ratio  $D_n$  of the structural plane as the shear strength deterioration index, Liu et al. (2011) obtained the variation law of shear strength of structural plane. The peak shear strength of the  $n$ th cyclic shear is expressed as  $\tau_n$ , then the  $D_n$  is defined as:

$$D_n = \frac{\tau_n}{\tau_1} \quad (1)$$

The shear strength ratio  $D_n$  ( $0.0 \leq D_n \leq 1.0$ ) reflects the shear strength degradation after several shear cycles: the closer  $D_n$  is to 1, the lesser the influence of strength deterioration induced by cyclic shear is. On the contrary, the closer  $D_n$  is to 0, the greater the influence of strength deterioration induced by cyclic shear is.

Figure 4 demonstrates the variation of shear strength ratios  $D_n$  of structural planes with five kinds of initial undulant angles with cyclic shear number under  $\sigma_n = 0.8$  MPa. It is found that the peak shear strength of structural plane specimens with five kinds of initial undulant angles decreases with the increase cyclic shear number, though the decreasing trend is different. The  $D_n$  with an initial undulant angle of  $16^\circ$  decreases at the lowest rate with the increase of cyclic shear number and keeps a steady decreasing trend, while the  $D_n$  with an initial undulant angle of  $45^\circ$  decreases at the highest rate with the increase of cyclic shear number and remains basically unchanged after the 2-th cyclic shear. And the decreasing speed of  $D_n$  increases with the increase of initial undulant angle. On the whole, the higher the undulations of the structural plane are, the lower the shear resisting force of the undulations is, and the occurrence of more significant shearing

or wearing damage in the cycle shear is more likely. Thus, for a specimen with higher undulant angles, the shearing or wearing damage of the surface undulations is mainly in the early stage of cyclic shear, and the degree of shearing or wearing damage changes insignificantly in the subsequent cyclic shear, and for a specimen with smaller undulant angle, the undulations on the surface has strong shear resisting force, the shearing or wearing damage is mainly caused by multiple shear or cumulative wear. Thus, the  $D_n$  of the specimens with smaller undulant angle decrease more slowly with the increase of the cyclic shear number.

## 2.3 Shear strength of structural plane introducing the relative shear velocity effect

When the shear movement of rock mass occurs, the shear resisting force mainly consists of the undulations of the structural plane and the friction of the contact sections:

$$\varphi = \varphi_b + \alpha_k \quad (2)$$

where  $\varphi$  denotes the friction angle of the structural plane,  $\varphi_b$  denotes the basic friction angle, and  $\alpha_k$  denotes the undulant angle.

On the basis of many direct shear tests on the rough structural plane, Barton and Choubey (1977) proposed to replace the undulant angle with the dilatancy angle:

$$\alpha_d = \frac{JRC}{2} \lg \frac{JCS}{\sigma_n} \quad (3)$$

where  $\alpha_d$  denotes the dilatancy angle,  $JRC$  denotes the roughness coefficient,  $JCS$  denotes the uniaxial compressive strength of the intact rock, and  $\sigma_n$  denotes the normal stress.

Furthermore, Barton (1973) further proposed the following shear strength equation for structural plane:

$$\tau = \sigma_n \tan \left( JRC \cdot \lg \frac{JCS}{\sigma_n} + \varphi_b \right) \quad (4)$$

where  $\tau$  denotes the peak shear strength of structural plane.

Then, Eqs. 3, 4 can be combined as follows:

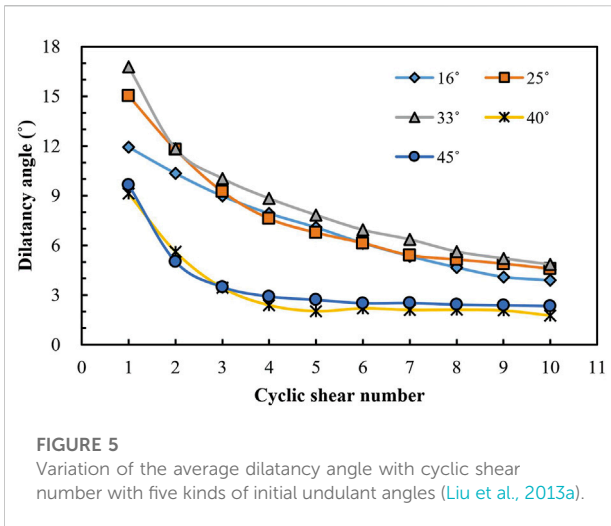
$$\tau = \sigma_n \tan (2\alpha_d + \varphi_b) \quad (5)$$

And after  $n$ th cyclic shear, the friction angle of the structural plane can be obtained:

$$\varphi = 2\alpha_n + \varphi_n \quad (6)$$

where  $n$  denotes the cyclic shear number,  $\alpha_n$  and  $\varphi_n$  denote the average dilatancy angle and the basic friction angle after the  $n$ th cyclic shear, respectively.

So, after  $n$ th cyclic shear, the peak shear strength of structural plane can be obtained:



**FIGURE 5**  
Variation of the average dilatancy angle with cyclic shear number with five kinds of initial undulant angles (Liu et al., 2013a).

$$\tau = \sigma_n \tan(2\alpha_n + \varphi_n) \tag{7}$$

According to the strength characteristic test of structural plane under different shear velocity, Li et al. (2006) concluded that the peak shear strength of structural plane decreases with the increase of relative shear velocity. Thus, an exponential decay functional relationship exists between the peak strength and the relative shear velocity. According to the research of Wang and Zhang (1982) and Li et al. (2006), Liu (2017) further proposed to express the relative velocity coefficient as follows:

$$\gamma(t) = \gamma_r + (1 - \gamma_r)e^{-a|\dot{x}(t)|} \tag{8}$$

where  $\dot{x}(t)$  denotes the relative shear velocity of the structural plane (m/s),  $\gamma_r$  denotes the convergence value of the relative shear velocity correlation coefficient, and  $a$  denotes the undetermined factor. Referring to the research of Ni et al. (2013),  $\gamma_r = 0.9$ ,  $a = 25$ .

Therefore, combining Eqs. 7, 8, the shear strength of the structural plane introducing the relative shear velocity effect can be obtained as follows:

$$\tau = \gamma(t) \cdot \sigma_n \tan(2\alpha_n + \varphi_n) \tag{9}$$

## 2.4 Dilatancy angle and basic friction angle during cyclic shear

According to Eq. 9, the key to determining the shear strength of a structural plane during the cyclic shear is to derive variation laws of the dilatancy angle and the basic friction angle. Therefore, this section will focus on the analysis of the variation laws of the dilatancy angle and the basic friction angle during the cyclic shear.

### 2.4.1 Dilatancy angle of the structural plane

Figure 5 demonstrates the variation of the average dilatancy angle with cyclic shear number for the cases of different initial undulant angles (Liu et al., 2013a). It can be found that with the increase of initial undulant angle, the dilatancy angle at the first cyclic shear of the structural plane increases firstly and then decreases ( $16^\circ < 25^\circ < 33^\circ, 16^\circ > 40^\circ > 45^\circ$ ). This is mainly due to the difference of shear failure modes between structural planes with high undulant angle and those with medium undulant angle, and the initial undulant angles of the  $40^\circ$  and  $45^\circ$  structural planes are more serious. On the whole, for structural planes with different initial undulant angles, the dilatancy angle gradually decrease, first rapidly, then more gradually and incline be stable slowly with the increase of cyclic shear number.

On the basis of above experimental results, Liu et al. (2013b) further found that there exists a negative exponential distribution relationship between the average dilatancy angle of the structural plane and the cyclic shear number, and the following expression is proposed:

$$\alpha_n = \alpha_0 (Ae^{-n/B} + C) \tag{10}$$

where  $\alpha_0$  denotes initial undulant angle of the structural plane. It is worth noting that when  $\sigma_n = 0$  or the shear is not performed,  $\alpha_n = \alpha_0$ .

The wear coefficient  $R_s$  of the average shear dilatancy angle can be further expressed as:

$$R_s = \frac{\alpha_n}{\alpha_0} = Ae^{-n/B} + C. \tag{11}$$

When  $n = 0$ ,  $R_s = 1$ , and  $A + C = 1$ , Eq. 11 can be adapted as:

$$R_s = Ae^{-n/B} + C = A(e^{-n/B} - 1) + 1 \tag{12}$$

Therefore,

$$\alpha_n = \alpha_0 R_s = \alpha_0 [A(e^{-n/B} - 1) + 1] \tag{13}$$

Based on Liu et al. (2013b) study, under the same uniaxial compressive strength of the intact rock  $\sigma_c$ , there exists a linear relationship between the parameter  $A$  or  $B$  and normal stress  $\sigma_n$ . Thus, the equations of  $A$  and  $B$  can be assumed as follows:

$$A = a\sigma_n + b \tag{14}$$

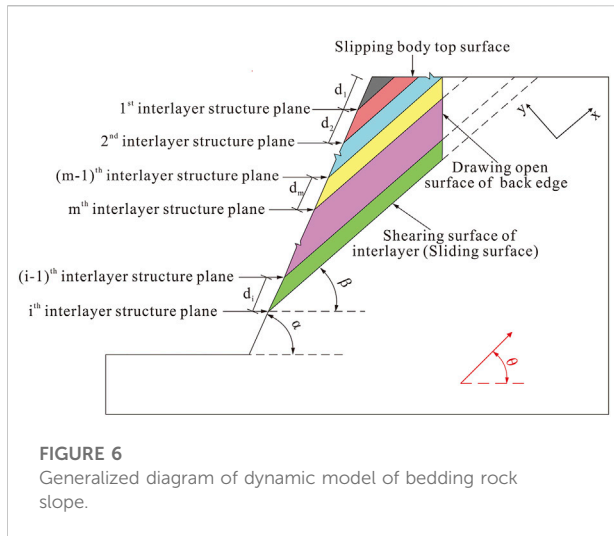
$$B = c\sigma_n + d \tag{15}$$

where parameters  $a$ ,  $b$ ,  $c$ , and  $d$  denote constants that are linked to uniaxial compressive strength of the intact rock  $\sigma_c$ . The relationships between  $a$ ,  $b$ ,  $c$ , and  $d$  and the uniaxial compressive strength of the intact rock  $\sigma_c$  can be determined by regression analysis.

### 2.4.2 Basic frictional angle of the structural plane

Based on Dong et al. (2020), the average shear dilatancy angle of the structural plane can reflect the degradation of undulations during the cyclic shearing, and the basic frictional angle and the





**FIGURE 6**  
Generalized diagram of dynamic model of bedding rock slope.

average shear dilatancy angle have the same variation trend. Thus, the following equation exists:

$$\frac{\alpha_0 - \alpha_n}{\alpha_0 - \alpha_r} = \frac{\varphi_0 - \varphi_n}{\varphi_0 - \varphi_r} \tag{16}$$

where  $\alpha_0$  and  $\varphi_0$  are the initial undulant angle and initial basic friction angle of the structural plane, respectively;  $\alpha_r$  and  $\varphi_r$  are the residual dilatancy angle and residual basic friction angle, respectively.

According to Eq. 16, the basic frictional angle of the structural plane after the  $n$ th cyclic shear can be obtained:

$$\varphi_n = \frac{\alpha_n(\varphi_0 - \varphi_r) - \varphi_0\alpha_r + \varphi_r\alpha_0}{\alpha_0 - \alpha_r} \tag{17}$$

where  $\varphi_0$  can be converted by the inclination experiment of the smooth structural plane.

The residual equivalent frictional angle ( $\varphi_s^*$ ) can be defined as follows:

$$\varphi_s^* = \arctan(\tau_r/\sigma_n) \tag{18}$$

where  $\tau_r$  is the residual shear stress,  $\varphi_s^*$  is the residual equivalent frictional angle. Since the equivalent friction angle ( $\varphi_s^*$ ) is mainly composed of residual basic friction angle ( $\varphi_r$ ) and the residual dilatancy angle ( $\alpha_r$ ), and the residual basic frictional angle ( $\varphi_r$ ) can be obtained:

$$\varphi_r = \varphi_s^* - \alpha_r = \arctan(\tau_r/\sigma_n) - \alpha_r \tag{19}$$

Thus, according to Eqs. 17, 19, the expression of basic friction angle  $\varphi_n$  can be expressed as:

$$\varphi_n = \frac{(\alpha_0 - \alpha_n)[\arctan(\tau_r/\sigma_n) - \alpha_r] + (\alpha_n - \alpha_r)\varphi_0}{\alpha_0 - \alpha_r} \tag{20}$$

### 3 Calculation method for permanent displacement

#### 3.1 Dynamic analysis model

A simplified dynamic calculation model of a bedding rock slope is illustrated in Figure 6, assuming that the potential sliding body produces unstable sliding along the rock stratum of the  $i$ th layer,  $d_i$  denotes the exposed length of  $i$ th rock stratum,  $\alpha$  denotes the slope gradient,  $\beta$  denotes the dip angle of the rock stratum,  $\ddot{u}_g$  denotes the seismic acceleration, and  $\theta$  denotes the angle between the direction of seismic acceleration and the horizontal direction.

It should be noted that the quadrilateral area is composed of slope surface, sliding surface, slipping body top surface, and tensile crack surface of back edge of the rock slope. And the area of potential sliding body is determined by:

$$S_i = \frac{1}{2} \left( \sum_{n=1}^i d_n \right)^2 \frac{\sin \alpha \sin(\alpha - \beta)}{\sin \beta} - \frac{1}{2} \left( \sum_{n=m}^i d_n \right)^2 \frac{\tan \beta \sin^2(\alpha - \beta)}{\sin^2 \beta} \tag{21}$$

The gravity of the potential sliding body in layer  $i$  is  $G_i$ ,

$$G_i = \gamma_i (S_i - S_{i-1}) \tag{22}$$

where  $\gamma_i$  is the volumetric weigh of the  $i$ th rock stratum. And the total gravity of the sliding body  $G_{it}$  is:

$$G_{it} = \sum_{n=1}^i G_n \tag{23}$$

According to the force equilibrium analysis in dynamic analysis model, in the Y direction

$$N = G_{it} \cos \beta + \frac{G_{it}}{g} \ddot{u}_g \sin(\theta - \beta) \tag{24}$$

and in the X direction

$$T = G_{it} \sin \beta + \frac{G_{it}}{g} \ddot{u}_g \cos(\theta - \beta) \tag{25}$$

where  $T$  denotes the parallel (shear) reaction forces,  $N$  denotes the orthogonal (normal) reaction forces,  $g$  denotes the acceleration owing to gravity. The seismic loading can act as both driving force and resisting force. Thus, Eqs. 24, 25 are vector equations, and the  $\ddot{u}_g$  changes with its symbol: when the seismic loading acts as the driving force, the symbol of  $\ddot{u}_g$  is positive, and when the seismic loading acts as the resisting force, the symbol of  $\ddot{u}_g$  is negative.

#### 3.2 Critical acceleration

For the bedding rock landslide, the influence of cohesion ( $c$ ) is mainly focused on the first cyclic shear process. Once the sliding mass generates cyclic shear under strong ground motion,

the influence of cohesion ( $c$ ) on shear strength is commonly ignored (Dong et al., 2020). The critical acceleration  $a_c$  can be defined as the minimum seismic acceleration that leads to the potential sliding body to overcome available shear resistance and to move. If  $\ddot{u}_g > a_c$ , the potential sliding body will overcome the available shear resistance and obtain sliding displacement. According to Eqs. 9, 25, the safety factor ( $F_s$ ) of sliding body can be expressed as:

$$F_s = \frac{\text{available shear resistance}}{\text{driving force}} = \frac{\tau}{T} = \frac{\gamma(t) \cdot \sigma_n \tan(2\alpha_n + \varphi_n)}{G_{it} \sin \beta + \frac{G_{it}}{g} \ddot{u}_g \cos(\theta - \beta)} \quad (26)$$

The safety factor  $F_s = 1$  is the critical condition for landslide instability, so assuming  $F_s = 1$ , the critical seismic acceleration is expressed as follows:

$$a_c = \frac{g[\gamma(t) \tan(2\alpha_n + \varphi_n) \cos \beta - \sin \beta]}{\cos(\theta - \beta) - \gamma(t) \sin(\theta - \beta) \tan(2\alpha_n + \varphi_n)} \quad (27)$$

### 3.3 Vibration balance equation

Based on Figure 6, the X-direction vibration balance equation can be expressed as follows:

$$M\ddot{u}_g \cos(\theta - \beta) + Mg \sin \beta - \gamma(t)N \tan(2\alpha_n + \varphi_n) = M\ddot{s} \quad (28)$$

where  $M$  is the mass of the potential sliding body, and

$$M = \frac{G_{it}}{g} \quad (29)$$

And according to Eqs. 24, 28, 29 the acceleration of the potential sliding body can be expressed as follows:

$$\begin{aligned} \ddot{s} &= \ddot{u}_g \cos(\theta - \beta) + g \sin \beta \\ &\quad - \left\{ \gamma(t) \left[ g \cos \beta + \ddot{u}_g \sin(\theta - \beta) \right] \tan(2\alpha_n + \varphi_n) \right\} \\ &= \ddot{u}_g \left[ \cos(\theta - \beta) - \gamma(t) \sin(\theta - \beta) \tan(2\alpha_n + \varphi_n) \right] \\ &\quad - g \left[ \gamma(t) \cos \beta \tan(2\alpha_n + \varphi_n) - \sin \beta \right] \end{aligned} \quad (30)$$

### 3.4 Calculation procedure of permanent displacement

After obtaining the dilatancy angle and basic friction angle after  $n$ th cyclic shear, the calculation procedures of permanent displacement are as follows:

- 1) The seismic acceleration  $\ddot{u}_g$  is divided into  $n\Delta t$  with time-history, and the critical acceleration  $a_c$  can be obtained based on Eq. (27)

- 2) When the seismic acceleration  $\ddot{u}_g > a_c$ , sliding displacement of the slope may be produced under seismic acceleration. The original acceleration of the sliding body ( $\ddot{s}$ )<sub>0</sub> can be acquired based on Eq. 30.
- 3) The occurrence of sliding depends on whether ( $\dot{s}$ )<sub>1</sub> is greater than zero. If ( $\dot{s}$ )<sub>1</sub> > 0, the time-history displacement ( $s$ )<sub>m1</sub> can be integrated; if ( $\dot{s}$ )<sub>1</sub> < 0, the next time-history can be integrated until  $m_1$ -th time-history, where ( $\dot{s}$ )<sub>m1</sub> ≥ 0.
- 4) Repeating the step (3) until the  $n$ th time-history, and finally obtaining the permanent displacement ( $s$ )<sub>n</sub> = ( $s$ )<sub>n-1</sub> + ( $\dot{s}$ )<sub>n</sub>Δt.

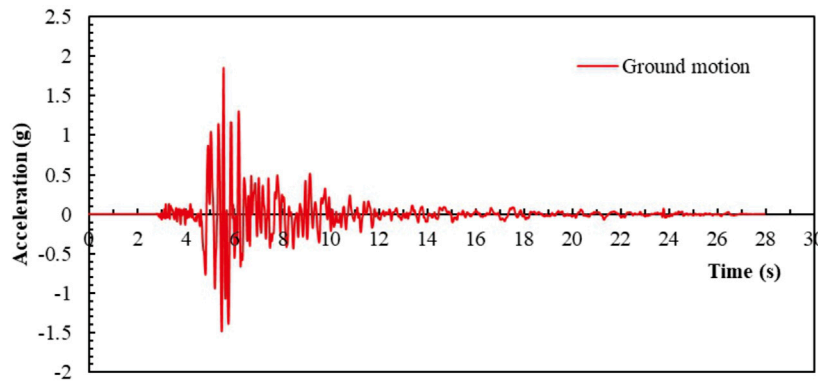
## 4 Case study

It is very difficult to find the monitoring data of sliding displacement of bedding rock slope under seismic loading. Thus, in order to illustrate the effectiveness and applicability of the proposed calculating method for permanent displacement, referring to the experimental research results of Liu et al. (2013b), a calculation case study was conducted. In the case study, the main parameters are as follows: the normal stress was 1.6 MPa, the basic friction angle was 30.5°, the initial undulant angle was 16°, the uniaxial compressive strength of the intact rock was 30 MPa, the residual shear strength was 0.798 MPa, the residual dilatancy angle was 7.744°, and the cyclic shear number  $n=10$ .

Based on dynamic analysis model in Figure 6, assuming that the slope gradient was 30°, the dip angle of rock stratum was 15°, the weight of rock mass was 23 kN/m<sup>3</sup>, the thickness of each layer of the rock stratum was equal, the length of the exposed surface of each layer was 10 m. Under the seismic loading, the average relative shear velocity  $\dot{x}(t)$  of interlayer structural plane is 8 mm/s, and according to Eq. 8, the relative velocity coefficient  $\gamma(t)$  was approximately 0.98. And the landslide slid from the fifth interlayer structural plane. The horizontal acceleration ( $\theta = 0$ ) is used as the seismic acceleration in Figure 7.

### 4.1 Calculation of dilatancy angle and basic friction angle

Based on the experimental results of wear coefficient of the average dilatancy angle ( $R_s$ ) for specimens with the initial undulant angle of 16° (Table 1), by fitting the experimental results as Eqs. 14, 15, the correlation parameters  $A$  and  $B$  were obtained with Eq. 11, and Figures 8A,B demonstrate the fitting relationship between correlation parameters  $A$  and  $B$  and the normal stress  $\sigma_n$  with different uniaxial compressive strengths of the intact rock  $\sigma_c$ . Then, the fitting relationship between correlation parameters  $a$ ,  $b$ ,  $c$ , and  $d$  and the uniaxial compressive strength of the intact rock  $\sigma_c$  were obtained by regression analysis, and the results are demonstrated in Figures



**FIGURE 7**  
Seismic acceleration used in the case study.

8C,D, with the expressions of  $A$  and  $B$  being obtained, as indicated below:

$$A = (0.0039\sigma_n - 0.0263)\sigma_c - 0.0233\sigma_n + 1.2222 \quad (31)$$

$$B = (0.0839 - 0.0074\sigma_n)\sigma_c - 0.3031\sigma_n + 1.3562 \quad (32)$$

Based on Eqs. 31, 32, after 10-th shear cycles, the values of parameters  $A$  and  $B$  were 0.583 and 3.033, respectively. According to Eqs. 13, 20, the variations of the dilatancy angle and basic friction angle with the increase of cyclic shear number were obtained (Figure 9). The dilatancy angle and basic friction angle gradually decreased and tended to be stable with the increase of the cyclic shear number. After 10-th cyclic shear, the calculated final dilatancy angle was  $7.015^\circ$ . From Eq. 20, the basic friction angle after 10-th cyclic shear was  $17.728^\circ$ .

## 4.2 Calculation of permanent displacement

After obtaining the dilatancy angle and basic friction angle, based on the analysis steps of permanent displacement, the variations of critical acceleration and permanent displacement with the cyclic shear number are obtained respectively (Figure 10), where the number of cycle shear is 0, indicating that the deterioration effect of the structural plane is not considered. With the increase of the cyclic shear number, the critical acceleration decreases gradually, especially when cyclic shear number is greater than 5, the critical acceleration decreases slowly and tends to be stable. The permanent displacement increases gradually with the increase of cyclic shear number. And the permanent displacement of the slope is obtained to be 0.015 m when the deterioration effect is not considered. Before the 5-th cyclic shear, the permanent displacement increases linearly with the cyclic shear number, and then the permanent

displacement increases slowly and gradually tends to be stable, and the calculated final permanent displacement is 0.420 m after 10-th cyclic shear.

## 4.3 Comparison with other methods

### 4.3.1 Newmark method

Newmark (1965) introduced seismic loading into rock slope stability analyses and further proposed Newmark sliding rigid block method. For the Newmark method, the critical acceleration is:

$$k_y = \tan(\varphi - \beta) \quad (33)$$

$$a_c = k_y g \quad (34)$$

where  $k_y$  denotes the yield coefficient,  $\varphi$  denotes the frictional angle between the sliding body and the sliding surface, and  $\beta$  denotes the dip angle of the rock stratum. For the Newmark method, the permanent displacement is determined by the double integral of the part where the seismic acceleration is greater than the critical acceleration  $a_c$ .

### 4.3.2 Qi method

Based on the vibration degradation law of the undulant angle by using the research results of Plesha (1987), Qi (2007) proposed a permanent displacement calculation method of rock slope, in which the variation of undulant angle is:

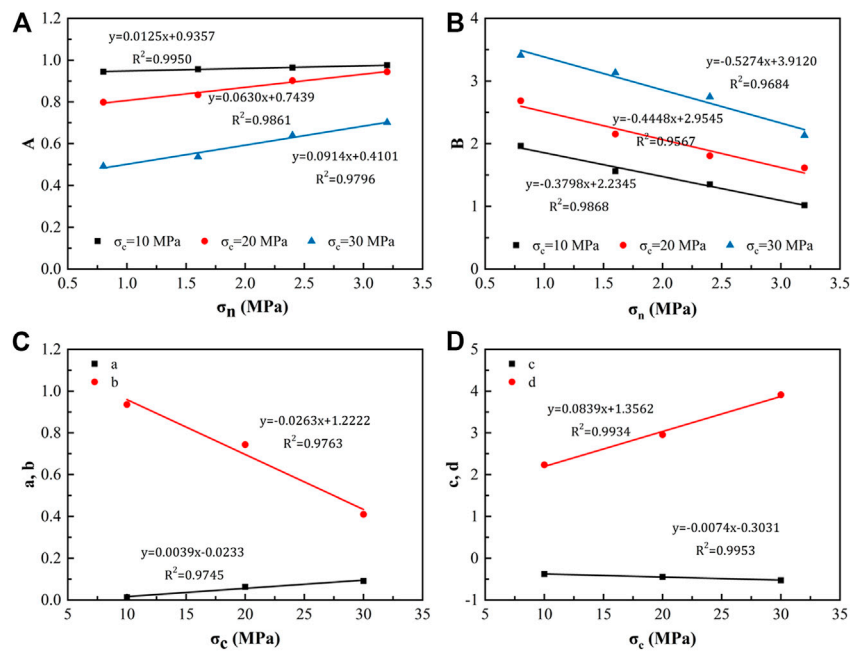
$$\alpha_k = (\alpha_k)_0 \exp(-cW^p) \quad (35)$$

where  $(\alpha_k)_0$  denotes the initial undulant angle,  $W^p$  denotes the plastic work, and  $c$  denotes the structural plane damage coefficient ( $m^2/J$ ). Hutson and Dowding (1990) experimentally verified the accuracy of Eq. 35 and proposed the empirical expression of the damage coefficient  $c$ :

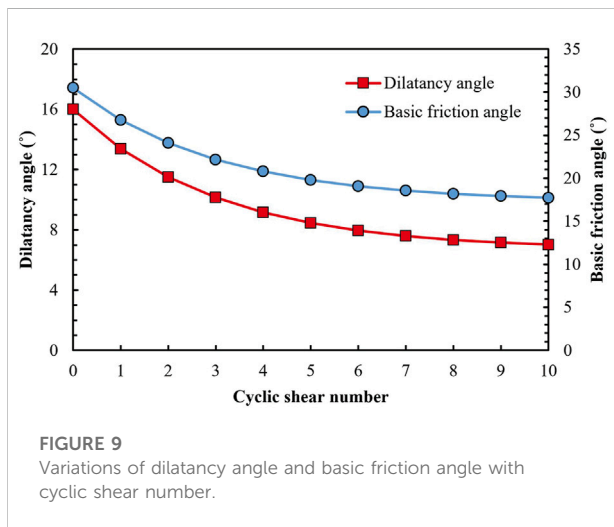


TABLE 1 Experimental results of  $R_s$  of specimens with the initial undulant angle of  $16^\circ$  (Liu et al., 2013b).

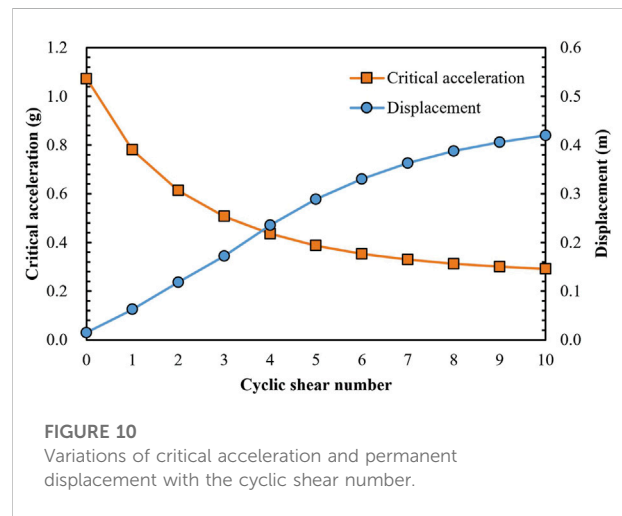
Specimen number	$\sigma_c = 10$ MPa				$\sigma_c = 20$ MPa				$\sigma_c = 30$ MPa			
	J01	J06	J11	J16	J21	J26	J31	J36	J41	J46	J51	J56
$\sigma_n$ nth	0.8 MPa	1.6 MPa	2.4 MPa	3.2 MPa	0.8 MPa	1.6 MPa	2.4 MPa	3.2 MPa	0.8 MPa	1.6 MPa	2.4 MPa	3.2 MPa
0	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
1	0.651	0.577	0.516	0.404	0.739	0.650	0.602	0.577	0.901	0.880	0.818	0.716
2	0.398	0.288	0.224	0.141	0.643	0.479	0.383	0.310	0.776	0.739	0.654	0.555
3	0.245	0.175	0.140	0.075	0.560	0.386	0.276	0.200	0.703	0.656	0.566	0.478
4	0.163	0.118	0.101	0.053	0.494	0.325	0.212	0.146	0.657	0.611	0.514	0.425
5	0.123	0.081	0.069	0.043	0.440	0.272	0.174	0.106	0.620	0.573	0.469	0.384
6	0.099	0.065	0.051	0.030	0.378	0.231	0.142	0.079	0.592	0.541	0.441	0.353
7	0.085	0.055	0.038	0.026	0.331	0.199	0.121	0.063	0.573	0.525	0.417	0.329
8	0.075	0.053	0.036	0.021	0.283	0.170	0.107	0.056	0.556	0.504	0.393	0.312
9	0.068	0.049	0.032	0.019	0.253	0.162	0.091	0.061	0.544	0.494	0.382	0.297
10	0.069	0.046	0.031	0.019	0.236	0.160	0.080	0.059	0.535	0.484	0.369	0.283



**FIGURE 8** Fitting relationships of main parameters. (A) Fitting relationships between A and  $\sigma_n$ ; (B) Fitting relationships between B and  $\sigma_n$ ; (C) Fitting relationships between a, b and  $\sigma_c$ ; (D) Fitting relationships between c, d and  $\sigma_c$ .



**FIGURE 9** Variations of dilatancy angle and basic friction angle with cyclic shear number.



**FIGURE 10** Variations of critical acceleration and permanent displacement with the cyclic shear number.

$$c = -0.114JRC \left( \frac{\sigma_n}{\sigma_c} \right) \tag{36}$$

In the Qi method, the basic friction angle  $\phi_b$  is:

$$\tan \phi_b = \frac{\cos(\theta - \beta)a_c + \sin \beta \cos \beta}{\cos \beta + \sin(\theta - \beta)a_c} \tag{37}$$

The initial critical acceleration  $a_c(0, 0)$  is expressed as:

$$a_c(0, 0) = -\frac{\sin(\beta - \varphi)}{\cos(\theta - \beta + \varphi)} \tag{38}$$

Considering the cumulative displacement and relative velocity effect, the expression of critical acceleration with displacement is proposed as follows:

$$a_c = Pa_c(0, 0) \tag{39}$$

where  $P$  is the reduction coefficient, between 0 and 1.

TABLE 2 Calculation results using different methods.

Methods	Calculation results	
	Critical acceleration/g	Displacement/m
Newmark method	0.613	0.095
Proposed Method	0.291	0.420
$P = 1$	0.613	0.107
$P = 0.65$	0.398	0.266
Qi method $P = 0.5$	0.306	0.393
$P = 0.4$	0.245	0.507

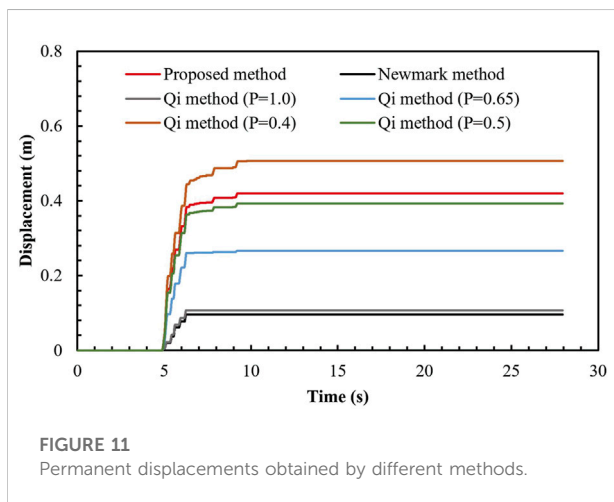


FIGURE 11 Permanent displacements obtained by different methods.

And the acceleration of the sliding body is expressed as:

$$\ddot{x} = \frac{g \cos(\theta - \beta + \varphi)}{\cos \varphi} (\ddot{u}_g - a_c). \tag{40}$$

The seismic acceleration  $\ddot{u}_g$  is divided into  $n\Delta t$  with time-history. The occurrence of sliding depends on whether the velocity of the sliding body  $(\dot{x})_1$  is greater than zero. If  $(\dot{x})_1 > 0$ , the time-history displacement  $(x)_{m1}$  can be integrated; if  $(\dot{x})_1 < 0$ , the next time-history can be integrated until  $m1$ -th time-history, where  $(\dot{x})_{m1} \geq 0$ . Then, repeating the above steps until the  $n$ th time-history, and finally obtaining the permanent displacement  $(x)_n = (x)_{n-1} + (\dot{x})_n \Delta t$ .

### 4.4 Comparison

The comparative calculation results of critical acceleration are presented in Table 2. The critical acceleration of the Newmark method is 0.613 g. For the Qi method, when  $P = 1$ , the critical acceleration obtained is the same as that obtained with the Newmark method, and it can be found that the critical

acceleration of the Qi method reduces with a decreasing of reduction coefficient  $P$ . This is because the shear strength gradually deteriorates during the cyclic shear process, and the ground motion load required to initiate a landslide is reduced. In the proposed method, the critical acceleration is smaller than that obtained with the Newmark method, and is between those of the Qi method with  $p = 0.4$  and  $p = 0.5$ . It is worth noting that, the critical acceleration obtained with the Newmark method remains constant under seismic loading, while the critical acceleration reduces gradually with the deterioration of the structural plane in the proposed method and the Qi method, which is more in line with actual observations.

The calculation results of permanent displacement are shown in Table 2; Figure 11. In the proposed method, the cumulative displacement curve obtained is between those of the Qi method with  $p = 0.4$  and  $p = 0.5$ , and in contrast the cumulative displacement is closer to the Qi method with  $p = 0.5$ . However, the permanent displacement obtained by Qi method and the proposed method is larger than that provided by the Newmark method, which illustrates that the deterioration effect of the structural plane has a significant effect on the calculation of permanent displacement, and the calculation methods that considers the deterioration effect are more conservative and reliable in terms of evaluating the stability of seismic-induced landslides.

## 5 Conclusion

In this study, based on the analysis of the cyclic shear condition under seismic loading, a new method for calculating the permanent displacement of the bedding-rock landslide was proposed by introducing the degradation effect of structural plane, and the following main conclusions can be obtained:

- 1) When the upward component of the horizontal seismic force along the interlayer structural plane is greater than the resultant force of the shear strength of the interlayer structural plane and the weight component of the sliding body, a cyclic shear mode of the slipping body will occur.
- 2) Under the cyclic shear loading, the deterioration of the structural plane mainly consists of the relative shear velocity effect, dilatancy angle degradation and basic frictional angle degradation.
- 3) To verify the effectiveness and applicability of the proposed calculating method for permanent displacement, using a case study, the calculated displacement results using the proposed method were compared with those obtained using the Newmark and Qi method. It was found that under seismic loading, the degradation effect of the structural plane has a direct effect on the permanent displacement and stability of the bedding rock landslide. The calculation method proposed in this paper potentially serves as reference for engineering design, calculation, and application.

## Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

## Author contributions

YP and SD were responsible for the main manuscript writing and idea discussions; Other authors were responsible for the prepare the paper language, figures, and tables. All authors have reviewed and agreed to the published version of the manuscript.

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## Conflict of interest

Author ZL was employed by the company Changjiang Institute of Survey, Planning, Design and Research Corporation.

The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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