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Seismicity-based 3D model of ruptured seismogenic faults in the North-South Seismic Belt, China

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The North-South Seismic Belt produces the most frequent strong earthquakes in the Chinese continental region, such as the MS 8.0 Wenchuan earthquake on 12 May 2008 and Ms 7.0 Lushan earthquake on 20 April 2013. This seismicity results in significant hazards. Fault geometry modeling is crucial for analyzing earthquake preparation and trigger mechanisms, simulating and predicting strong earthquakes, inverting fault slip rates, etc. In this study, a novel method for obtaining geometric models of ruptured seismogenic faults over a large area is designed based on datasets from surface fault traces, fault orientations, focal mechanism solutions, and earthquake relocations. This method involves three steps. 1) An initial model of the fault geometry is constructed from the focal mechanism solution data. This initial model is used to select the earthquake relocation data related to the target fault. 2) Next, a fine model of the fault geometry with a higher resolution than that of the initial model is fitted based on the selected earthquake relocation data. 3) The minimum curvature interpolation method (Briggs, 2012) is adopted to build a 3D model of the subsurface fault geometry according to the three-dimensional coordinates of nodes on all profiles of each fault/segment. Based on this method and data collected in the North-South Seismic Belt, the fine morphologies of different faults along 1,573 transverse profiles were fitted, and a 3D model of 263 ruptured seismogenic faults or fault segments in the North-South Seismic Belt was built using the minimum curvature spatial interpolation method. Since the earthquake number decreases with increasing depth, the model uncertainty increases with increasing depth. Different ruptured faults have different degrees of seismicity, so different fault models may have different uncertainties. The overall fitting error of the model is 0.98 km with respect to the interpreted results, from six geophysical exploration profiles.

KEYWORDS

North-South Seismic Belt, focal mechanism solution, earthquake relocation, ruptured seismogenic fault, 3D model

1 Introduction

As the region with the most frequent strong earthquakes in the Chinese mainland, the North-South Seismic Belt (NSSB) extends more than 800 and 2,000 km in the east-west and northsouth directions, respectively (Figure 1) (Wang et al., 2015). The NSSB has generated numerous strong earthquakes that have caused significant hazards, such as the MS 8.0 Wenchuan earthquake on 12 May 2008, Ms 7.0 Lushan earthquake on 20 April 2013, MS 6.4 Yangbi earthquake on 21 May 2021, and Ms 6.8 Luding earthquake on 5 September 2022 (Dai et al., 2011; Zhou et al., 2015; Yang et al., 2022). This seismic belt extends from the western margin of the Ordos Block in the north, crosses the Qinling Orogenic Belt and Longmenshan Fault Belt, and reaches Myanmar along the Anninghe Fault (ANH. F.) (Figure 1). The relatively stable South China Block and Ordos Block in the eastern Chinese mainland are separated from the Qinghai-Tibetan Plateau in the west by the NSSB (Zhang, 2013). The NSSB is the region of interactions among the Sichuan-Yunnan Block, Bayankala Block, Qinling Orogenic Belt, East Kunlun Orogenic Belt, Qaidam-Longxi Block, Qilian Orogenic Belt, Ordos Block, and Alxa Block (Figure 1) (Zhang et al., 2015).

Seismological studies in the NSSB are of great significance, and three-dimensional models of ruptured seismogenic faults are the basis for several seismological studies. For example, fault geometric models can be used for the inversion of fault slip rates (Li et al., 2010; Wang et al., 2016; Liu et al., 2022), the analysis of seismogenic mechanisms (King, 1986; Barka and Kadinsky-Cade, 1988; Shi et al., 2019) and seismic triggering mechanisms (Lay et al., 2010; Mildon et al., 2019; Ross et al., 2019), the prediction and simulation of strong earthquakes (Silva and Vitor., 2016; Walker et al., 2019; Xin and Zhang, 2021), *etc.* At present, the geometries of ruptured seismogenic faults are imaged mainly by field geological surveys, active-source geophysical surveys, seismic tomography based on passive earthquake data, and earthquake parameter estimation.

However, subsurface fault shapes cannot be identified by surface geological surveys (Valoroso et al., 2014). Active-source geophysical surveys always have with low data coverage due to their high cost (Hubbard and Shaw, 2009; Dong et al., 2010; Li Y. et al., 2019). For seismic tomography, the resolution of data depends on the distribution of seismic rays (Dorbath et al., 1996; Dilla et al., 2018). Unevenly distributed hypocenters and limited seismic stations result in low-resolution seismic tomography (Liu et al., 2021; Zhao et al., 2021).

There are two independent methods for modeling ruptured seismogenic faults based on earthquake parameters. One method is based on hypocenters, and the other method is based on focal mechanism solutions. In the first method, the fault geometry is fitted by the distribution of hypocenters along a fault based on the relationship between the rupture area of the ruptured seismogenic fault and the magnitude of the earthquakes, as well as the attenuation of seismic wave energy (Wells and Coppersmith, 1994; Lin et al., 2007; Schaff and D., 2009). In subduction zones, the majority of earthquakes are located along the Benioff zone, so the plate boundary can be modeled based on hypocenter fitting. The slab surfaces at the main subduction zones on Earth have been obtained via this method (Hayes and Wald, 2009; Zhang et al., 2013). However, an initial or coarse model of fault geometry is necessary to select the earthquakes induced by the target fault when modeling the geometry of smallscale ruptured seismogenic faults because some earthquakes near the target fault may be triggered by the other faults (Schaff et al., 2002; Hayes and Wald, 2009). The 3D geometry of the Gualdo Tadino Fault in Italy was fitted based on aftershock relocations, which were selected based on the constraints of seismic reflection profiles (Ciaccio et al., 2005). A three-dimensional model of the Longmenshan Fault in China was built based on the surface ruptures and aftershock relocations due to the Wenchuan earthquake in 2008, and the hypocenters used in the fitting process were also selected under the constraints of a deep seismic-reflection profile and logging data (Li et al., 2010).

In the focal mechanism solution-based method, the fault geometry can be modeled by the dip variations estimated from focal mechanism solutions at different depths, according to the relationship between seismic wave propagation and the rupture process of ruptured seismogenic faults (Aki, 1966; Nolet, 1980; Sliver et al., 1982; Kuang et al., 2021). The variations in the dip of the rupture planes of a fault were mapped according to 24 focal mechanism solutions in the western Corinth Rift in Greece (Maxime et al., 2014). Frepoli et al. (2017) also inferred the dip angle of Apennine faults in central Italy based on focal mechanism solutions. Duan et al. (2018a) estimated the dip variations along the Dujiangyan Fault in the NSSB of China based on focal mechanism solutions. However, the number of focal mechanism solutions is always much lower than the amount of earthquake relocation data due to the limited number of seismic stations. Therefore, compared with a fault model based on earthquake relocations, a model based on focal mechanism solutions often has a lower resolution, which cannot reflect the detailed fault geometry (Ciaccio et al., 2005; Frepoli et al., 2017).

By integrating surface traces, focal mechanisms, earthquake relocations, logging data, and seismic reflection profiles, a threedimensional fault model was developed for southern California in the United States (Plesch et al., 2007). Similarly, a threedimensional fault model was built for the main ruptured seismogenic faults in the Sichuan–Yunnan region under the comprehensive constraints of fault traces, focal mechanism solutions, precise locations of small earthquakes, a crustal velocity model, seismic reflection profiles, and magnetotelluric data; this work was accomplished by the China Seismic Experimental Site project (http://www.cses.ac.cn/). However, this model does not cover the whole NSSB, and some major faults in this seismic belt, such as the Haiyuan Fault, Xiangshan-



Tectonic setting and basic data distribution for fault modeling in the North–South Seismic Belt, China. ETOPO1 (Amante, 2009) is used as the topographic base map. The black solid lines represent the surface fault traces, (Xu et al., 2016), which contain 263 faults (segments): Y-B. F., Yingxiu-Beichuan Fault; G-A. F., Guanxian-Anxian Fault; W-W. F., Wenchuan-Wenmao Fault; XSH. F., Xianshuihe Fault; ZMH. F., Zemuhe Fault; ANH. F., Anninghe Fault; DKL. F., Dongkunlun Fault; YK. F., Yuke Fault; JPS. F., Jinpingshan Fault; L-X. F., Lijiang-Xiaojinhe Fault; DKL. F., Dongkunlun Fault; YK. F., Yuke Fault; JPS. F., Jinpingshan Fault; L-X. F., Lijiang-Xiaojinhe Fault; L-J. F., Ebian-Jinyang Fault; XJ. F., Xiaojiang Fault; DR. F., Dari Fault; HY. F., Haiyuan Fault; L-D. F., Lintan-Dangchang Fault; L-L. F., Lixian-Luojiabao Fault; LQS. F., Longquanshan Fault; ME. F., Malkan Fault; MJ. F., Minjiang Fault; TZ. F., Tazang Fault; XQL. F., Xiqinling Fault. The green dashed lines represent the faults whose subsurface geometries are modeled in this study. The red crosses represent the positions of focal mechanism solutions (Zheng, 2019; Guo et al., 2022). The blue dots represent the relocated epicenters of earthquakes from the Sichuan Earthquake Administration. The black dotted lines represent geophysical exploration profiles: #1, an electrical structure profile across the Haiyuan Fault (Min, 2014); #2, a seismic profile across the Yingxiu-Beichuan Fault (Wu et al., 2010); #3, a seismic profile across the Yingxiu-Beichuan Fault (Wu et al., 2014); #4, a seismic profile across the Yingxiu-Beichuan Fault (Wu et al., 2014); #4, a seismic profile across the Yingxiu-Beichuan Fault and Guanxian-Anxian Fault (Wu et al., 2014); #5, a seismic profile across the Yingxiu-Beichuan Fault and Guanxian-Anxian Fault (Wu et al., 2014); #5, a seismic profile across the Yingxiu-Beichuan Fault and Guanxian-Anxian Fault (Wu et al., 2014); #5, a seismic profile across the Yingxiu-Beichuan Fault and Guanxian-Anxian Fault (Wu et al., 2014); #5, a seismic

Tianjingshan Fault, and Weihe Fault (Lu et al., 2019), are not included. At present, a 3D fault geometric model that covers the whole NSSB is still lacking.

The coverage of active-source geophysical profiles in the NSSB, such as electrical, magnetic and seismic profiles, are very limited. Therefore, these geophysical interpretations

cannot be taken as constraints for relocation data selection. In this study, the initial model of fault geometry is modeled based mainly on the focal mechanism solutions and partly on the available geological and geophysical data. The detailed shapes of the ruptured seismogenic faults are modeled by fitting the selected hypocenters according to the initial model. Finally, TABLE 1 Information on the six collected geophysical profiles in the NSSB.

Crossing fault name	Profile type	Source	Index in Figure 1
Haiyuan Fault	Electrical Resistivity	Min (2014)	#1
Yingxiu-Beichuan Fault and Guanxian-Anxian Fault	Seismic Wave Velocity	Dong et al. (2010)	#2
Yingxiu-Beichuan Fault	Seismic Wave Velocity	Wu et al. (2014)	#3
Yingxiu-Beichuan Fault	Seismic Wave Velocity	Wu et al. (2014)	#4
Yingxiu-Beichuan Fault and Guanxian-Anxian Fault	Seismic Wave Velocity	Dong et al. (2010)	#5
Longquanshan Fault	Seismic Wave Velocity	Dong et al. (2010)	#6

we evaluate the uncertainty of the fault model based on the six geophysical exploration profiles.

2 Data and methods

2.1 Input data

The necessary input data for 3D modeling of the main ruptured seismogenic faults in the NSSB include fault traces on the Earth's surface, fault orientations, focal mechanism solutions, and relocated hypocenters. The fault orientations and focal mechanism solutions are used to construct the initial fault geometry model and choose relocated hypocenters related to the target fault. The selected relocated hypocenters are used to fit the fault geometry. In addition, geophysical interpretation profiles are also necessary to test the model uncertainty.

- 1) The surface trace of each fault (Figure 1) is extracted from the Seismotectonic Map of China and Adjacent Regions compiled by Xu et al. (2016), which is provided by the Data Exchange and Sharing Management Center of Active Fault Exploration in the Institute of Geology, China Earthquake Administration.
- 2) The fault orientations are derived from seismic, electrical and magnetic exploration. These data are compiled and provided by the Sichuan Earthquake Administration, China.
- 3) The focal mechanism solutions are from the National Earthquake Data Sharing Project by the China Earthquake Administration (Zheng, 2019) and the Focal Mechanism Data Set of the Chinese Mainland and Its Adjacent Areas (2009–2021), which was compiled by the Institute of Geophysics, China Earthquake Administration (Guo et al., 2022). There are 7,427 focal mechanism solutions within the NSSB in this study (Figure 1).
- 4) The earthquakes relocations are from the catalog of the China Seismic Experimental Site (http://www.cses.ac.cn/), including the relocated hypocenters of 127,009 earthquakes with magnitudes larger than ML 1.5 in the NSSB from January 2009 to March 2019 (Figure 1). These relocations are derived

by the Sichuan Earthquake Administration using absolute and relative earthquake location methods based on the seismic phase observed by the seismic networks in the NSSB. The uncertainties of these relocated hypocenters are given as follows: the root mean square (RMS) of the travel times for 80% of the earthquakes is within 0.3 s, the horizontal error for 80% of the samples is limited to 2 km, and the vertical error for 80% of the samples is within 4 km, which are the statistics based on absolute earthquake locations.

5) Fault interpretation results along six geophysical profiles across different faults (Figure 1) are collected. The details of these profiles are listed in Table 1.

2.2 Modeling method

The geometric and kinematic parameters of ruptured seismogenic faults can be indicated well by focal mechanism solutions (Ciaccio et al., 2005; Frepoli et al., 2017), and earthquakes are mainly concentrated on ruptured seismogenic faults (Schaff et al., 2002; Hayes and Wald, 2009). Therefore, the geometry of a ruptured seismogenic fault can be modeled based on focal mechanism solutions and earthquake relocations. Our modeling method includes three main steps (Figure 2). 1) First, an initial fault model with a coarse resolution is constructed along the fault strike based on the focal mechanism solution, surface fault trace the collected fault orientation. 2) The relocated hypocenters of earthquakes due to the specific ruptured seismogenic fault are selected under the constraint of the initial fault model. The fault geometries along different crosssections (the solid black line in Figure 3C) that are perpendicular to the fault strike are fitted based on the relocation data. 3) A three-dimensional model of the fault geometry is built by compiling all the fault shapes along different fault-crossing profiles.

2.2.1 Initial model of fault geometry along strike

To construct the fault model, the width of the fault along each fault strike-orthogonal profile needs to be delineated to extract the focal mechanism solutions and the relocated hypocenters, which are the basis for fault geometry modeling. The width of the



FIGURE 2

The workflow of 3D fault geometry modeling. The main stages are as follows: 1) the potential maximum fault width is derived from the maximum crustal thickness and minimum fault dip in the research region. The more precise fault width can be judged according to the distributions of the relocated hypocenters within the maximum fault width. The fault dip variations are gridded within the judged fault width based on the dips reflected by the nodal planes of focal mechanism solutions which are selected according to the surface fault traces and orientations. The low-resolution initial model of fault geometry along fault strike is constructed according to the fault dip variations. 2) The cross-section interval along each fault strike is evaluated by setting relocated hypocenter number is not less than 200 on each section within fault width. The highest hypocenter density, is used to calculate the characteristic depths on each section. The high-resolution fine fault geometry along each cross-section is modeled by fitting the characteristic depths. 3) The 3D fault geometry is modeled based on the fine geometries along different sections, and the uncertainty of the 3D model is estimated by taking the fault geometries from geophysical interpretation results as references.

fault is estimated through the following two steps. 1) According to the maximum crustal thickness (70 km) of the NSSB (Chen et al., 2015; Wang et al., 2017) and the minimum dip (30°) of the modeled faults, the maximum width of the fault is set to 120 km based on the trigonometric function. In this way, all the potential seismicity data related to the target fault should be within this maximum fault model width. 2) Then, a bounding region that covers the target fault can be judged according to the intensity of the relocated hypocenter distribution because the seismicity decreases with distance from the target ruptured seismogenic fault. The approximate shape of the target fault can be inferred by combining the fault orientations and the dip angle reflected by the majority of the focal mechanism solutions. The abscissa spanning between the surface outcrop point and the other intersection point between the bounding region and the fault model is regarded as the width of the target fault, which can be modeled according to seismicity data. While ensuring that the width is not underestimated, this process also eliminates the need to introduce the seismicity data of adjacent faults because of setting an overly large width.

The focal mechanism solutions are extracted within this width. Based on the fault strike according to the surface

traces, the proper nodal plane can be chosen from the focal mechanism solution. The focal mechanism solutions, which clearly differ from the main trend and are probably caused by the other adjacent ruptured seismogenic faults, are removed from the dataset. The percentages of the removed focal mechanism solutions at different profiles vary, ranging between 10% and 20%. The gridded fault dip variations along the fault plane are interpolated according to the dips based on the extracted focal mechanism solutions *via* the kriging interpolation method. The grid size (*c*) is estimated by the following equation (Hengl, 2006):

$$c = 0.25\sqrt{\frac{A}{N}},\tag{1}$$

where A is the area of the fault plane and N is the number of focal mechanism solutions. Finally, the initial model of the fault geometry can be derived based on the fault dip variations along the fault plane.

2.2.2 Fine model of fault geometry along crosssections

Relative to the initial model in the former step, the fine model of the fault geometry is based on fitting the relocated hypocenters



Three-dimensional modeling process for subsurface geometry taking the middle segment of the Yingxiu-Beichuan Fault as an example. (A) Fault dip variations according to the focal mechanism solutions; (B-C) Fine model of fault geometry along profile by fitting the selected and relocated hypocenters; (D) 3D model of the fault plane.

along different fault-strike-orthogonal profiles. These profiles have the same interval along the fault strike. A small crosssection interval means a high model resolution along strike, but it also means few earthquake relocations and a low vertical resolution for the fault geometry along each profile. Therefore, to obtain a fault model with enough details in both the horizontal and vertical directions based on the finite number of relocated hypocenters, we should balance the number of cross-sections and that of earthquake relocations on each profile. The profile length is determined by the horizontal width of the initial model of fault geometry. According to our multiple tests, one suitable choice is that the minimum number of earthquake relocations along each profile is 200. Based on this condition, the profile interval along strike and the profile number can be obtained when the minimum number of earthquake relocations along each profile is slightly larger than 200. When there are not more than 200 relocated hypocenters related to one fault, the fault geometry is fitted along only one profile at the fault center and orthogonal to the strike. Then, the three-dimensional fault model is derived by extending this along-profile geometry according to the surface trace.

To fit the detailed fault shape along one profile, the relocated earthquake hypocenters within the region surrounded by two neighboring profiles are extracted. Then, an enveloping plane (the black dashed lines in Figure 3B) is constructed by taking the initial model line as the symmetry axis (the red dashed line in Figure 3B). To obtain enough relocated hypocenters whose source earthquakes are related to the target fault and to exclude as many hypocenters not related to the target fault as possible, this envelope should have as high a hypocenter density and as large an area as possible. The density of the relocated hypocenters in the envelop region usually first increases and then decreases with increasing envelope width because

Fault name	Fitted fault length/km	Number of focal mechanism solutions	Number of earthquake relocations	Number of fitted profiles	Maximum fitted depth/km
Yingxiu-Beichuan Fault	560.4	2,500	16,606	62	27.4
Xianshuihe Fault	405.3	297	4,331	32	29.4
Anninghe Fault	362.2	173	2043	30	26.9
Wenchuan-Wenmao Fault	318.5	1744	11,664	45	22.4
Guanxian-Anxian Fault	310.2	1759	9,485	41	30.3
Honghe Fault	169.2	84	1,310	22	18.0
Zemuhe Fault	144.7	66	1,182	23	21.4
Xiaojiang Fault	101.7	108	1,123	18	23.5

TABLE 2 Geometry modeling parameters for the main faults.

TABLE 3 The RMSE between the geophysical interpretation results and the fitting results based on 2–4 order polynomial by the method of this study.

Profile index	Fault name	RMSE of the ruptured seismogenic fault models/km			
		By 2 order polynomial	By 3 order polynomial	By 4 order polynomial	
#1	Haiyuan Fault	2.43	2.05	2.11	
#2	Guanxian-Anxian Fault	1.52	1.07	1.02	
#2	Yingxiu-Beichuan Fault	0.83	0.44	0.39	
#3	Yingxiu-Beichuan Fault	1.08	0.67	0.51	
#4	Yingxiu-Beichuan Fault	1.33	0.61	0.63	
#5	Yingxiu-Beichuan Fault	1.77	1.15	1.33	
#5	Guanxian-Anxian Fault	1.02	0.64	0.60	
#6	Longquanshan Fault	1.80	1.21	1.37	

the earthquakes caused by fault activity are located near the fault plane. Therefore, the envelope with the maximum relocated hypocenter density is the optimal one. In particular, when there are other active faults near the target fault, hypocenters associated with other faults should be artificially removed.

The depths of nodes with equal intervals along the initial model of fault geometry are fitted based on the selected hypocenters. The spacing of nodes is taken as 2.5 km (Zhang et al., 2013; Duan et al., 2018b). The characteristic depth of each node is estimated by the weighted average method (Zhang et al., 2013), which can be expressed as:

$$Z_{(x)} = \sum_{i=1}^{i=n} \left(\frac{\Omega_i \mu_i}{\sum_{i=1}^{i=n} \Omega_i} \right), \tag{2}$$

where $Z_{(x)}$ is the characteristic depth of the *x*-th node, *n* is the number of earthquake relocation data on the profile, μ_i is the focal depth of the *i*-th earthquake, and $\Omega_i(M_i, x_i)$ is the weight of

the *i*-th earthquake. According to the relationship between earthquake magnitude and the main rupture plane area of the fault (Wells and Coppersmith, 1994) and the attenuation law of seismic waves (Winkler and Nur, 1982), the weight $\Omega_i(M_i, x_i)$ can be estimated by the following equation (Zhang et al., 2013):

$$\Omega_i = 10^{M_i} \exp\left(-\frac{(x - x_i)^2}{2D}\right),$$
 (3)

where x is the abscissa of the target node, x_i is the abscissa of the *i*-th earthquake relocation on the profile, M_i is the magnitude of the earthquake, and D is the interval of the cross-sections on the fault. The estimated final positions of nodes are shown as solid diamonds in Figure 3B. The use of 2-4 order polynomial fitting is suggested, and the cubic polynomial is the most widely adopted one in similar modeling research (Hayes et al., 2009; Zhang et al., 2013; Duan et al., 2018b). Therefore, we also apply a cubic polynomial to fit all the nodes along the profile to refine the model of fault geometry (the solid red line in Figure 3B), and reliability of it is establish by comparing the effect of 2-4 order polynomial fitting in the 3.2 uncertainty and discussion.



2.2.3 Three-dimensional model and its uncertainty of fault geometry

Some of the faults are composed of different segments according to the surface traces. In this case, the unit of the three-dimensional fault geometry modeling is the fault segment. Otherwise the unit is the whole fault. Then, the minimum curvature interpolation method (Briggs, 2012) is adopted to build the 3D model of the subsurface fault geometry according to the three-dimensional coordinates of nodes on all profiles of each fault/segment. The uncertainty of this 3D model is estimated by comparing the modeled fault geometry with the published fault geometry, where the latter is based on active-source geophysical explorations. The fault depth differences between our model and the reference result at the points along the profile with a constant horizontal interval are used to estimate the root mean square error (RMSE) of our model. The RMSE can be calculated as follows:

RMSE =
$$\sqrt{\frac{\sum_{i=1}^{n} (y_i - y'_i)^2}{n}}$$
, (4)

where y_i and y'_i are the fault plane depth at the *i*-th point from our model and the reference result, respectively, and *n* is the number of comparison points. A smaller RMSE means a smaller uncertainty in our fitted fault model.

3 Results and discussion

3.1 3D model of ruptured seismogenic faults in the NSSB

The middle segment of the Yingxiu-Beichuan Fault is taken as an example to illustrate the fault modeling steps and selection of some parameters. Previous studies suggest that the fault dip angle is between 50° and 70° here, and the strike ranges from 210° to 230° (Lei and Zhao, 2009; Li et al., 2013; Nie et al., 2013; Si et al., 2014; Wang et al., 2014; Li et al., 2016; Meng et al., 2020). According to these conditions, 67 focal mechanism solutions in total are selected for this fault section, as shown in Figure 3A. Finally, the along-strike initial geometric model of the middle section of the Yingxiu-Beichuan Fault is modeled by interpolation of these focal mechanism solutions (Figure 3A).



In total, 18transverse profiles perpendicular to the middle segment of the Yingxiu-Beichuan Fault are constructed with a 10-km interval (Figure 3C). On average, 425 hypocenters are distributed along each profile, with a maximum of 926 and a minimum of 237. The central profile (Figure 3B) is selected to show the modeling results. The envelope region is 9 km wide; in other words, the distance between the upper and bottom black dashed lines in Figure 3B is 9 km. There are nine calculation nodes with an interval of 2.5 km whose characteristic depths (the red solid diamonds in Figure 3B) are fitted by 926 relocated hypocenters (the black hollow circle in Figure 3B), and the maximum burial depth of this fine model (red solid line in Figure 3B) is 23.8 km. Finally, the three-dimensional fault plane model (Figure 3D) of the middle segment of the Yingxiu-Beichuan Fault is obtained based on the fine models of fault geometry along the 18 transverse profiles (the solid black line in Figure 3C).

To model the 3D geometries of the 263 main ruptured seismogenic faults (fault segments) in the NSSB, the fine fault shapes along a total of 1,573 transverse profiles are fitted. The final 3D model covers all the main ruptured seismogenic faults, such as the Yingxiu-Beichuan Fault, Xianshuihe Fault, and Haiyuan Fault (Figure 4). The fitted fault length at the Earth's surface, the number of fitted cross-sections, the maximum depth of the fault model, and some other parameters of the main faults in the 3D model are listed in Table 2; the detailed statistics are reported in Supplementary Table A1.

3.2 Uncertainty and discussion

Uncertainty is mainly caused by two aspects in our ruptured seismogenic fault geometry model, on the one hand, the uncertainty is determined by the order of polynomial used to fit the characteristic depth, on the other hand, is caused by the input data. For the former, the effect of 2-4 order polynomial fitting has been tested, the overall fitting error of them are 1.47 km, 0.98 km and 1.00 km respectively comparing geophysical interpretation results (Table 3). Comparatively, the 2 order polynomial is the worst, the 3 order is the best, and the fitting effects of the 3 order and 4 order polynomials are similar.

As for the latter, there are different uncertainties such as the uncertainties in the focal mechanism solutions and the relocated hypocenters, and the number of hypocenters related to other faults used in the modeling. According to statistics, the focal mechanism solutions and relocated hypocenters used in this study decrease in number with increasing depth below a specific depth (Figure 3B). Fewer relocated hypocenters at the fault bottom means that the weight of the relocated hypocenters on the upper part becomes higher (Eq. 3), so the fitted node depth at the fault bottom will be shallower than that in reality. This process trends to yield listric fault models (Figures 5, 6). Therefore, the uncertainty at the bottom of the model tends to be larger than that of the shallow part (Figures 5, 6). The qualities of seismicity data also vary among different crosssections or along different faults, so the model uncertainty also varies along strike or between different faults (Table 4).



2014); and (G) is from Profile #3 (Wu et al., 2014).

In addition, it is impossible to remove all the relocated hypocenters related to other faults based on the initial fault model, even though we attempt to do so. Therefore, this incomplete removal also introduces uncertainty to the fault geometry models.

The uncertainty of the three-dimensional ruptured seismogenic fault model in the NSSB is estimated by taking the fault geometries from the six collected geophysical interpretation profiles as the reference. The RMSEs of the 3D model are shown in Table 4. Since the fault model can also be

constructed based only on focal mechanisms, which is the same as our initial model of fault geometry, or only by fitting hypocenters along the profile without earthquake selection, Table 4 also provides the RMSEs of the fault model when using these two simplified methods. Among the three modeling methods, the approach designed in this study derives the smallest RMSE overall, which is 0.98 km. The fault geometries based on geophysical profile interpretations and the three different fitting methods are plotted on the geophysical profiles (Figures 5, 6). The comparison results suggest that the

Profile index	Fault name	RMSE of the ruptured seismogenic fault models/km			
		By the method of this study	By the hypocenter-based method	By the focal mechanism solution-based method	
#1	Haiyuan Fault	2.05	6.54	1.67	
#2	Guanxian-Anxian Fault	1.07	2.04	0.91	
#2	Yingxiu-Beichuan Fault	0.44	1.70	5.35	
#3	Yingxiu-Beichuan Fault	0.67	2.36	3.01	
#4	Yingxiu-Beichuan Fault	0.61	1.85	2.21	
#5	Yingxiu-Beichuan Fault	1.15	3.74	1.82	
#5	Guanxian-Anxian Fault	0.64	2.41	2.66	
#6	Longquanshan Fault	1.21	4.36	1.88	

TABLE 4 The RMSE between the geophysical interpretation results and the fitting results based on different methods.

method of this study can best match the geophysical interpretation results among the three kinds of fitted results in most cases.

4 Conclusion

A new method for 3D modeling of ruptured seismogenic fault geometry based on seismicity is designed in this study. The focal mechanism solutions related to the target ruptured seismogenic fault are chosen by comparing their internal consistency or the consistency of each with the collected fault orientations, and the selected solutions are used to construct the initial model of fault geometry. The initial geometric model is further adopted to determine the earthquake relocation data related to the target fault. Subsequently, these earthquake relocations are employed to refine the fault model. This method can avoid the disadvantage of constructing only a low-resolution fault model when using focal mechanism solutions alone due to the limited amount of data. Moreover, it can also reduce the modeling uncertainty by removing the ambiguity of hypocenters with respect to other nearby fault or faults under the constraint of the initial geometric models.

Combining the surface traces of ruptured seismogenic faults in the NSSB, the initial geometric models of 263 faults (segments) are modeled based on the focal mechanism solutions under the constraints of prior data on fault orientations obtained from seismic, electrical and magnetic exploration. Moreover, detailed fault geometries along a total of 1,573 strike-perpendicular profiles are fitted based on the selected hypocenters. Finally, the minimum curvature interpolation method is adopted to build a threedimensional model for the ruptured seismogenic faults in the NSSB. When taking six geophysical interpretation profiles as a reference, the average RMSE of this model is 0.98 km which is smaller than those of the other two traditional methods. The model uncertainty at the bottom is higher than that near the top because of the limited number of earthquakes, and the uncertainties for different sections of each fault may also differ because of the unevenly distributed earthquake data.

Data availability statement

The datasets presented in this study can be found in online repositories. The names of the repository/repositories and accession number(s) can be found in the article/ Supplementary Material.

Author contributions

YR: Methodology, Validation, Modeling, Writing - Original Draft, Writing-Review Editing YB: Conceptualization, Methodology, Validation, Formal analysis, Writing-Original Writing-Review Draft. Editing MR: Modeling, ML: Writing-Review Editing providing, Data Writing-Review Editing ZW: Writing-Review Editing All authors contributed to manuscript revision, read, and approved the submitted version.

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Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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Supplementary material

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