



Quantitative Analysis of Phase Separation Using the Lattice Boltzmann Method

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Phase separation is widely observed in multiphase systems. In this study, it has been investigated using Shan–Chen lattice Boltzmann method. The adhesion parameter in SC model leads to the desired fluid–fluid phenomenon, which was varied to specify the strength of separation between two phases to present emulsified performance in oil production. In order to describe such behaviors quantitatively, graphical distributions were described with time and were corresponded with a statistical index–Fourier structure factor that is able to predict complex phase separation behaviors, thereby providing a measurement for calculating such random distribution during the process of separation as well as evaluating heterogeneous degrees of the entire domain. The repulsive interactions are specified as low, intermediate, and high values. Phase separations with clear boundaries have been observed and each stage of separation evolvement has been discussed in this study. Magnitudes of structure factors are increased with higher degrees of fluctuations.

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INTRODUCTION

One of phase separation principles is to utilize inherent immersion in an anti-solvent way of separating, for example, emulsification (Mukherjee et al., 2019) (Fournanty et al., 2008), nuclear condensates (Zhang et al., 2019), droplet formation, and movement in microchannels. So, the underlying principle of phase separation involves utilizing the two or more fluids, such that they separate into their respective phases (Dauyeshova et al., 2018). Its fully understanding will serve as the emulsified behavior occurring in heavy oil cold production and other areas.

To understand this mechanism which can be used to manipulate the breakdown or onset of such instability, many studies have been conducted via experimental works (Peters et al., 1990) (Goldburg and Huang, 1975) (Giaconia et al., 2007). Although experiments show that critical parameters of chemical emulsifiers are associated with rheology of the oil–water interface (Moerman et al., 2018) (Wang et al., 2014) (Cui et al., 2021) (Man et al., 2018), the theoretical work for this purpose that has been developed for production scenarios remains problematic (Wu et al., 2021) (Cui et al., 2020).

However, it is impractical to obtain micro systematic and completely separate evolutions using molecular dynamics due to massive computational power, and macroscopic behaviors are not sensitive. The lattice Boltzmann method (LBM) can describe microscopic behaviors of the fluid and represent macro scale behaviors. Such a mesoscopic scheme has become a useful tool to study a variety of industrial processes including the aforementioned processes. Phase separation in lattice Boltzmann evolves from an immiscible fluid with the respective equilibrium state of each component. The Shan–Chen model proposed interaction forces acting on fluid particles, which

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will be discussed later. Statistical behaviors will also be used to analyze instability due to the tangential velocity difference of the fluids, from initial random distribution to band-like structures and to the growth of droplets over the entire domain.

The structure factor of droplet evolvement via self-assembly in larger droplets is to the degree of spatial heterogeneity. In this study, it was applied to emulsification used in oil recovery engineering. Regarding the binary mixtures, we emphasize the strength of heterogeneity from emulsions inducing phase separation. If the interfacial properties and the pore size are included, we discuss how to control the spatial heterogeneity and phase separation.

METHODOLOGY

Shan-Chen Multiphase LBM

The SC LBM has been implemented in two dimensions for the multiphase system. The distribution function is introduced for fluid components. And it satisfies the following lattice Boltzmann equation:

$$f_{i}(\mathbf{r} + \boldsymbol{c}_{i}\Delta t, t + \Delta t) - f_{i}(\mathbf{r}, t) = -\frac{1}{\tau} [f_{i}(\mathbf{r}, t) - f_{i}^{eq}(\mathbf{r}, t)], \quad (1)$$

where $f_i(r, t)$ is the density distribution function which represents fractions of fluid molecules with a specific velocity c_i at a specific

position and time t when time and space are discretized by Δt and Δx ; τ is a relaxation time which is related to the kinematic viscosity as follows:

$$\mu = c_s^2 \rho \, (\tau - 0.5). \tag{2}$$

The equilibrium distribution function $f_i^{eq}(\mathbf{r}, t)$ can be calculated as

$$f_{i}^{eq}(\mathbf{r},t) = \omega_{i} \rho \left[1 + \frac{3(c_{i} \cdot \boldsymbol{u}^{eq})}{c_{s}^{2}} + \frac{9(c_{i} \cdot \boldsymbol{u}^{eq})^{2}}{2c_{s}^{4}} - \frac{3\boldsymbol{u}^{eq^{2}}}{2c_{s}^{2}} \right], \quad (3)$$

where c_i is the discrete velocity. For the D2Q9 model, they are given by

And where ω_i is the weighting factor:

$$\omega_i = \begin{cases} 1/4, \ i = 0\\ 1/18, i = 1 \sim 6\\ 1/36, i = 7 \sim 18 \end{cases}$$
(4)

where $c_s = c/\sqrt{3}$, $c = \Delta x/\Delta t$ is the ratio for lattice spacing Δx , and the time step is Δt . In **Eq. 2**, ρ is the density of fluid, which can be obtained from $\rho = \sum f_i$. Macroscopic velocity u^{eq} is given by



$$u_i^{eq} = u + \frac{\tau_i F_i}{\rho_i},\tag{5}$$

where u is a velocity which is defined as

$$u = \frac{\sum_{i} \frac{f_i c_i}{\tau_i}}{\sum_{i} \frac{\rho_i}{\tau}}.$$
 (6)

In Eq. 5, $F_i = F_{i,c}$ is the force acting on the fluid component, including fluid-fluid cohesion $F_{i,c}$ and excluding fluid-solid adhesion.

Fluid–Fluid Cohesion

The cohesive force acting on the fluid component is defined as

$$F_{i,c}(\mathbf{r},t) = -G_c \rho_c(\mathbf{r},t) \sum_i \omega_i \rho_{c'}(\mathbf{r} + \mathbf{c}_i \Delta t, t) \mathbf{c}_i,$$
(7)

where ρ_c and $\rho_{c'}$ denote two different fluid components, and G_c is a parameter that controls the strength of the cohesion force.

RESULTS AND DISCUSSIONS

Qualitative Analysis

In this study, the initial density is set to be 1. The periodic boundary conditions are used for all boundaries in the 301×301

mesh. Initially, droplets are distributed uniformly in the domain. Small droplets grow up gradually by dispersion leading to a high degree of heterogeneity because larger droplets are able to minimize surface energy. Small droplets became less by coalesce due to dispersion and local flow behaviors. In the entire domain, the interface between two phases was decomposed into several high-density zones and low-density zones. Later, phase zones can further coalesce and grow up resulting minimized total lengths of the interface under surface tension. When the computations reached to the equilibrium state, two phases will separate completely. Small structures tend to have a spherical shape with a smooth surface before evaporating by diffusion (Reis and Phillips, 2007).

Various interactive forces have effects on speeds of phase separations. The density ratio and viscosity radio between two phases are represented as ρ^* and τ^* , respectively. As expected, higher interactive strengths lead to more clear and quick separations. A two-phase system with small interaction may fail to separate. In **Figure 1**, the system with the intermediate interactive strength is able to represent similar structures like those in the system with a low interactive strength earlier. At the final stage (**Figure 1D**), phase separation was shown as top and bottom bands. Initially, intermediate and final stages of phase separations with the highest interaction show the most clear interface boundary. Initial random structures have grown up into larger band-like structures and then coalesce. Under surface





FIGURE 4 Temporal evolution of mean structure factors over entire domain in the phase separation system with interactive strengths of G = -1 at four times: (A) 100 ts, (B) 200 ts, (C) 300 ts, and (D) 1800 ts.

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FIGURE 5 | Temporal evolution of mean structure factors over entire domain in the phase separation system with interactive strengths of G = -30 at four times: (A) 100 ts, (B) 200 ts, (C) 300 ts, and (D) 1800 ts.



(A) 100 ts, (B) 200 ts, (C) 300 ts, and (D) 1800 ts.

tension, the bands reshape into small droplets or bubbles for minimizing surface energy. At last, the domain was full of stably moving big droplets. If the simulation time is long enough, all droplets will merge into one. When we observe the separation behaviors at one specific time in a row, the interaction with a small interactive strength requires more time to evolve until the separation process is complete.

Phase separation happens in a system with an intermediate specified interactive force; see Figure 2. A clearer structure involving separated behaviors can be seen quickly. Distinctive

band structures are formed with random swings but are hardly evolved into further structures within the simulation time.

When the interactive strength is risen to a high level with the magnitude of -100 shown in **Figure 3**, the exceptional separated structures are shown. Many smaller band structures are displayed in the earlier stage (**Figure 3B**). Subsequently, such "bands" are further combined (**Figure 3C**) and then reshaped into some round bubbles (**Figure 3D**).

Structure Factor

Structure factor is used by the Fourier transform of spatial distributions of droplets or bubbles to present instabilities observed. Here, the first structure factor evolution will be showed as the function of simulation time. The structure factor shows heterogeneity changes due to phase separation (Zou et al., 1994). The structure factor is defined based on the fluctuation–dissipation theorem within integration of the imaginary part of the density response function. For a discrete system we are studying, it is given by

$$S(k,t) = \frac{1}{N} \left| \sum_{r} \left[q(\mathbf{r},t) - \overline{q(t)} \right] e^{ik\cdot r} \right|,\tag{8}$$

where N is the total number of grid points in the domain. $q(\mathbf{r}, t) = n^1(\mathbf{r}, t) - n^2(\mathbf{r}, t); \quad k = \frac{2\pi}{L} (m\mathbf{i} + n\mathbf{j}), m.n = 1, 2, ..., L$, and L is the linear lattice size. $\overline{q(t)}$ is the special average of $q(\mathbf{r}, t)$ at time t.

Structure factor is a quantitative measure of the structure along a prescribed direction. A value at a given wave number indicates the presence of heterogeneity in the periodic domain. Here, we present the first structure factors along the x and y directions. These structure factors are associated with heterogeneities developed to the size of the computational domain.

The onset of phase separation is defined as the time when the structure factor is above zero. In order to evaluate fluctuations from phase separation behaviors, graphic distributions are used corresponding to structure factors at selective times. Initially, random uniformed structures are specified in the domain, with a low value of structure factors; see Figure 4A. Then, small droplets start to merge with the neighboring ones, and therefore, relative bigger droplets or chunks were distributed with an increasing fluctuation presenting by higher structure factors, in Figure 4B. In Figure 4C, the structure factor of low interactive strengths is observed to be a peak. As separation continues, some droplets become larger than others, which results in uneven structures in the domain. These larger and more nonuniformed structures were verified by maximum of the mean structure factor value at the approximate 300th step. In Figure 4D, high- and low-density phases at the 1800th step were alternately distributed, and values of mean structure factors in Figure 4 remain.

Structure factors of the system with medium interactive strengths are shown in **Figure 5**. Similarly, the initial random uniformed distribution is shown in **Figure 5A**, which corresponds to low structure factors in **Figure 5**. And such low-level fluctuations are able to stay longer until approximately 200 steps as shown in **Figure 5B** due to increasing repulsive interaction compared to the low interactive strength. When large droplets further combine with neighboring same materials, some laminated structures appeared, and mean structure factors reach a peak at the approximate 800th step (Figure 5C). Although similar band structures are seen as those in the system with the low interactive strength, a clearer boundary between two phases is revealed.

When the interactive strength is increased to 100, quite clear phase separation is observed as shown in **Figure 6**. Highest values of mean structure factors among three systems are shown. From the beginning, distinct boundaries enclosing large droplets or chunks were taken shape as shown in **Figures 6A and B**. But, structure factors are low because degree of heterogeneity at these stages is relatively small. At the approximate 300th step (**Figure 6C**), structure factors are gradually fortified as a variety of sizes of droplets or chunks. Additionally, structure factors in this systems exhibit a smooth profile that is different from previous two systems with curved trends. This suggests that a two-phase system with strong repulsive interaction involves continuous fluctuations rather than abrupt changes.

CONCLUSION

Phase separation is studied via the LBM-SC model and analyzed quantitatively using structure factors.

- Evolution of phase separation is observed in spatial distribution in four stages within periodic domains.
- Uniformed droplets aggregate into larger ones under interactive forces.
- The structure factors of the binary mixture develop in time that corresponds to changes of fluctuation due to phase separations.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material; further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

XL has worked on simulation and draft development, JF has contributed to double checking data and description, and BJ has funded and guided this research work.

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Conflicts of Interest: Authors XL, JF, and BJ were employed by SINOPEC

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