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\*CORRESPONDENCE Yuto Ishikawa 🖾 ishikawa yuto.f6@s.mail.nagoya-u.ac.jp Takuma Yoshihara 🗠 21ef106@ms.dendai.ac.jp Keita Okamura 🖂 6223024@ed.tus.ac.jp

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# Individual subject evaluated difficulty of adjustable mazes generated using quantum annealing

Yuto Ishikawa<sup>1\*</sup>, Takuma Yoshihara<sup>2\*</sup>, Keita Okamura<sup>3\*</sup> and Masayuki Ohzeki<sup>4,5,6</sup>

<sup>1</sup>Department of Computer Science, Nagoya University, Nagoya, Japan, <sup>2</sup>Department of Engineering, Tokyo Denki University, Adachi, Japan, <sup>3</sup>Department of Physics and Astronomy, Tokyo University of Science, Noda, Japan, <sup>4</sup>Graduate School of Information Sciences, Tohoku University, Sendai, Japan, <sup>5</sup>Department of Physics, Tokyo Institute of Technology, Meguro, Japan, <sup>6</sup>Sigma-i Co., Ltd., Shinagawa, Japan

In this study, the maze generation using quantum annealing is proposed. We reformulate a standard algorithm to generate a maze into a specific form of a quadratic unconstrained binary optimization problem suitable for the input of the quantum annealer. To generate more difficulty mazes, we introduce an additional cost function  $Q_{update}$  to increase the difficulty. The difficulty of the mazes was evaluated by the time to solve the maze of 12 human subjects. To check the efficiency of our scheme to create the maze, we investigated the time-to-solution of a quantum processing unit, classical computer, and hybrid solver. The results show that  $Q_{update}$  generates difficult mazes tailored to the individual. Furthermore, it show that the quantum processing unit is more efficient at generating mazes than other solvers. Finally, we also present applications how our results could be used in the future.

#### KEYWORDS

quantum annealing, combinatorial optimization, maze generation, bar-tipping algorithm, time-to-solution

# 1 Introduction

A combinatorial optimization problem is minimizing or maximizing their cost or objective function among many variables that take discrete values. In general, it takes time to solve the combinatorial optimization problem. To deal with many combinatorial optimization problems, we utilize generic solvers to solve them efficiently. Quantum annealing (QA) is one of the generic solvers for solving combinatorial optimization problems (Kadowaki and Nishimori, 1998) using the quantum tunneling effect. Quantum annealing is a computational technique to search for good solutions to combinatorial optimization problems by expressing the objective function and constraint time requirements of the combinatorial optimization problem by quantum annealing in terms of the energy function of the Ising model or its equivalent QUBO (Quadratic Unconstrained Binary Optimization) and manipulating the Ising model and QUBO to search for low energy states (Shu Tanaka and Seki, 2022). Various applications of QA are proposed in traffic flow optimization (Neukart et al., 2017; Hussain et al., 2020; Inoue et al., 2021), finance (Rosenberg et al., 2016; Orús et al., 2019; Venturelli and Kondratyev, 2019), logistics (Feld et al., 2019; Ding et al., 2021), manufacturing (Venturelli et al., 2016; Haba et al., 2022; Yonaga et al., 2022), preprocessing in material experiments (Tanaka et al., 2023), marketing (Nishimura et al., 2019), steel manufacturing (Yonaga et al., 2022), and decoding problems (Ide et al., 2020; Arai et al., 2021a). The model-based Bayesian optimization is also proposed in the literature (Koshikawa et al., 2021). A comparative study of quantum annealer was performed for benchmark tests to solve optimization problems (Oshiyama and Ohzeki, 2022). The quantum effect on the case with multiple optimal solutions has also been discussed (Yamamoto et al., 2020; Maruyama et al., 2021). As the environmental effect cannot be avoided, the quantum annealer is sometimes regarded as a simulator for quantum many-body dynamics (Bando et al., 2020; Bando and Nishimori, 2021; King et al., 2022). Furthermore, applications of quantum annealing as an optimization algorithm in machine learning have also been reported (Neven et al., 2012; Amin et al., 2018; Khoshaman et al., 2018; Kumar et al., 2018; OMalley et al., 2018; Arai et al., 2021b; Sato et al., 2021; Urushibata et al., 2022; Goto and Ohzeki, 2023; Hasegawa et al., 2023). In this sense, developing the power of quantum annealing by considering hybrid use with various techniques is important, as mentioned in several previous studies (Hirama and Ohzeki, 2023; Takabayashi and Ohzeki, 2023).

In this study, we propose the generation of the maze by quantum annealing. In the application of quantum annealing to mazes, algorithms for finding the shortest path through a maze have been studied (Pakin, 2017). Automatic map generation is an indispensable technique for game production, including rogue-like games. Maze generation has been used to construct random dungeons in rogue-like games by assembling mazes (mok Bae et al., 2015). Therefore, considering maze generation as one of the rudiments of this technology, we studied maze generation using a quantum annealing machine. Several algorithms for the generation of the maze have been proposed. In this study, we focused on maze-generating algorithms. One can take the bar-tipping algorithm (Alg, 2023a), the wall-extending algorithm (Alg, 2023b), and the hunt-and-kill algorithm (Alg, 2023c).

The bar-tipping algorithm is an algorithm that generates a maze by extending evenly spaced bars one by one. For the sake of explanation, we will explain the terminology here. A path represents an empty traversable part of the maze and a bar a filled non-traversable part. Figure 1 shows where the outer wall, bars, and coordinate (i, j) are in a 3  $\times$  3 maze. The maze is surrounded by an outer wall, as shown in Figure 1. It requires the following three constraints. First, each bar can be extended by one cell only in one direction. Second, the first column can be extended in four directions: up, down, left, and right, while the second and subsequent columns can be extended only in three directions: up, down, and right. Third, adjacent bars cannot overlap each other. We explain the detailed process of the bar-tipping algorithm using the 3  $\times$  3 size maze. In this study, a maze generated by extending the  $N \times N$  bars is called  $N \times N$  size maze. First, standing bars are placed in every two cells in a field surrounded by an outer wall, as shown in Figure 1. Second, Figure 2 shows each step of bar-tipping algorithm. Figure 2A shows the first column of bars extended. The bars in the first column are randomly extended in only one direction with no overlaps, as shown in Figure 2A. The bars can be extended in four directions (up, down, right, and left) at this time. Figure 2B shows the second column of bars being extended. Third, the bars in the second column are randomly extended in one direction without overlap, as shown in Figure 2B. The bars can be extended in three directions (up, down, and right) at this time. Figure 2C shows the state in which the bars after the second column are extended. Fourth, the bars in subsequent columns are randomly



extended in one direction, likewise the bars in the second column, as shown in Figure 2. Figure 2D shows the complete maze in its finished state. Following the process, we can generate a maze, as shown in Figure 2D.

If multiple maze solutions are possible, the maze solution is not unique, simplifying the time and difficulty of reaching the maze goal. These constraints must be followed for the reasons described below. The first constraint prevents a maze from generating a maze with multiple maze solutions and closed circuits. Figure 3A shows a maze state that violates the first constraint. The step violating the first constraint because one bar in the upper right corner is extended in two directions, as shown Figure 3A. The second constraint prevents generating a maze from a maze with closed circuits and multiple maze solutions. Figure 3B shows a state that violates the second constraint. The second constraint is violated, it has a closed circuit and multiple maze solutions, as shown in Figure 3B. The third constraint prevents maze generation from a maze with multiple maze solutions. Figure 3C shows a state that violates the third constraint. The bars overlap in the upper right corner, making it the third constraint as Figure 3C.

Next, we describe the wall-extending algorithm. It is an algorithm that generates a maze by extending walls. Figure 4 shows the extension starting coordinates of the wall-extending algorithm. Figure 5A shows the initial state of the wall-extending algorithm. First, as an initial condition, the outer perimeter of the maze is assumed to be the outer wall, and the rest of the maze is assumed to be the path, as shown in Figure 5A. Coordinate system is different from the bar-tipping algorithm, and all cells are labeled coordinates. As shown in Figure 4, the coordinates where both x and y are even and not walls are listed as starting coordinates for wall extending. The following process is repeated until all starting coordinates



#### FIGURE 2

Step of bar-tipping algorithm. (A) Step1: bars in first column are extended. (B) Step2: bars in second column are extended. (C) Step3: bars in subsequent column are extended. (D) Step4: a complete maze through these steps.



Mazes violated the constraints. (A) A maze violate the first constraint. (B) A maze violate the second constraint. (C) A maze violated the third constraint.

change to walls, as shown in Figure 5C. The coordinates were randomly chosen from the non-wall extension start coordinates. The next extending direction is randomly determined from which the adjacent cell is a path. Figure 5B shows how the path is

extended. The extension will be repeated while two cells ahead of the extending direction to be extended are a path, as shown in Figure 5B. Figure 5C shows all starting coordinates changed to walls. These processes are repeated until all the starting coordinates



change to walls, as shown in Figure 5C. Figure 5D shows a maze created by wall-extending. Following the process, we can generate a maze, as shown in Figure 5D.

As a third, the hunt-and-kill algorithm is explained below. It is an algorithm that generates a maze by extending paths. Figure 6 shows the extension starting coordinates of the hunt-andkill algorithm. Figure 7A shows the initial state of the hunt-and-kill algorithm. The entire surface is initially walled off, as shown in Figure 7A. Coordinates, where both x and y are odd, are listed as starting coordinates for path extension, as shown in Figure 6. As with the wall-extending algorithm, all cells are set to coordinates. Figure 7B shows the state in which the path is extended. A coordinate is chosen randomly from the starting coordinates, and the path is extended from there, as shown in Figure 7B. Figure 7C shows the coordinate selection and re-extension after the path can no longer be extended. If the path can no longer be extended, a coordinate is randomly selected from the starting coordinates, which are already paths, and extension starts again from it, as shown in Figure 7C. This process is repeated until all the starting coordinates turn into paths to generate the maze. Figure 7D shows the complete maze with the hunt-and-kill algorithm. Following the process, we can generate a maze, as shown in Figure 7D.

Of the three maze generation algorithms mentioned above, the bar-tipping algorithm is relevant to the combinatorial optimization problem. In addition, unlike other maze generation algorithms, the bar-tipping algorithm is easy to apply because it only requires the consideration of adjacent elements. Thus, we have chosen to deal with this algorithm. Other maze generation algorithms could be generalized by reformulating them as combinatorial optimization problems. The wall-extending and hunt-and-kill algorithms will be implemented in future studies, considering the following factors. The former algorithm introduces the rule that adjacent walls are extended and so are their walls. The number of connected components will be computed for the latter, and the result will be included in the optimization.

Using the bar-tipping algorithm, we reformulated it to solve a combinatorial optimization problem that generates a maze with a longer solving time and optimizes it using quantum annealing. Quantum annealing (DW\_2000Q\_6 from D-Wave), classical computing (simulated annealing, simulated quantum annealing, and algorithmic solution of the bar-tipping algorithm), and hybrid computing were compared with each other according to the generation time of mazes, and their performance was evaluated. The solver used in this experiment is as follows: DW\_2000Q\_6 from D-Wave, simulated annealer called SASampler and simulated quantum annealer called SQASampler from OpenJij (Ope, 2023), D-Wave's quantum-classical hybrid solver called hybrid\_binary\_quadratic\_model\_version2 (BQM), and classical computer [MacBook Pro(14-inch, 2021), OS: macOS Monterey Version 12.5, Chip: Apple M1 Pro, Memory: 16 GB]. This comparison showed that quantum annealing was faster. This may be because the direction of the bars is determined at once using quantum annealing, which is several times faster than the classical algorithm. We do not use an exact solver to solve the combinatorial optimization problem. We expect some diversity in the optimal solution and not only focus on the optimal solution in maze generation. Thus, we compare three solvers, which generate various optimal solutions.

In addition, we generate mazes that reflect individual characteristics, whereas existing maze generation algorithms rely on randomness and fail to incorporate other factors. In this case, we incorporated the maze solution time as one of the other factors to solve the maze. The maze solving time was defined as the time (in seconds) from the start of solving the maze to the end of solving the maze.

The study is organized as follows. In the next Section, we explain the methods of our experiments. In Section 3, we describe the results of our experiments. In Section 4, we summarize this study.

### 2 Methods

### 2.1 Cost function

To generate the maze by quantum annealer, we need to set the cost function in the quantum annealer. One of the important features of the generation of the maze is diversity. In this sense, the optimal solution is not always unique. Since it is sufficient to obtain a structure consistent with a maze, the cost function is mainly derived from the necessary constraints of a maze, as explained below. Three constraints describe the basis of the algorithm of the bar-tipping algorithm. The cost function will be converted to a QUBO matrix to use the quantum annealer. To convert the cost function to a QUBO, the cost function must be written in a quadratic form. Using the penalty method, we can convert various constraints written



in a linear form into a quadratic function. The penalty method is a method to rewrite the equality constant as a quadratic function. For example, the penalty method can rewrite an equation constant x = 1 to  $(x - 1)^2$ . Thus, we construct the cost function for generating the maze using the bar-tipping algorithm below.

The constraints of the bar-tipping algorithm correlate with each term in the cost function as described below. The first constraint of the bar-tipping algorithm is that the bars can be extended in only one direction. It prevents making closed circuits. The second constraint of the bar-tipping algorithm is that the bars of the first column be extended randomly in four directions (up, right, down, and left), and the second and subsequent columns can be extended randomly in three directions (up, right, and down). It also prevents the creation of closed circuits. The third constraint of the bar-tipping algorithm is that adjacent bars must not overlap. Following the constraint in the bar-tipping algorithm, we can generate a maze with only one path from the start to the goal.

The cost function consists of three terms to reproduce the bar-tipping algorithm, according to

the three constraints, and determine the start and goal.

$$E(\{x_{i,j,d}, X_{m,n}\}) = \sum_{i,i'} \sum_{j,j'} \sum_{d,d'} Q_{(i,j,d),(i',j',d')} x_{i,j,d} x_{i',j',d'} + \lambda_1 \sum_i \sum_j \left(\sum_d x_{i,j,d} - 1\right)^2 + \lambda_2 \left(\sum_m \sum_n X_{m,n} - 2\right)^2,$$
(1)

where  $x_{i,j,d}$  denotes whether the bar in *i*-th row, *j*-th column extended in direction *d* (up: 0, right: 1, down: 2, left: 3). When the bar in coordinate (*i*, *j*) is extended in direction,  $x_{i,j,d}$  takes 1, otherwise takes 0. Due to the second constraint of the bar-tipping algorithm, the bars after the second column cannot be extended on the left side; only the first column has (d = 3). Furthermore,  $Q_{(i,j,d)(i',j',d')}$  in Equation (1) depends on *i*, *j*, *d*, *i'*, *j'*, and *d'* and is



expressed as follows

$$Q_{(i,j,d),(i',j',d')} = \begin{cases} 1 \ (i = i' - 1, j = j', d = 2, d' = 0) \\ 1 \ (i = i' + 1, j = j', d = 0, d' = 2) \\ 0 \ \text{otherwise.} \end{cases}$$
(2)

The coefficients of  $\lambda_1$  and  $\lambda_2$  are constants to adjust the effects of each penalty term. The first term prevents the bars from overlapping and extending each other face-to-face. It represents the third constraint of the bar-tipping algorithm. Here, due to the second constraint, bars in the second and subsequent columns cannot be extended to the left. Therefore, the adjacent bars in the same row cannot extend and overlap. This corresponds to the fact that d cannot take 3 when  $j \ge 1$ . Thus, there is no need to reflect, considering the left and right. In particular, the first term restricts the extending and overlapping between the up and down adjacent bars. For example, the situation in which one bar in (i, j)extended down (d = 2) and the lower bar in (i + 1, j) extended up (d = 0) are represented by  $x_{i,j,2}x_{i+1,j,0} = 1$  and  $Q_{(i,j,2),(i+1,j,0)}$ take 1. In the same way, thinking of the relation between the bar in (i, j) and the upper bar in (i - 1, j),  $Q_{(i, j, 0), (i-1, j, 2)} = 1$ . Thus,  $Q_{(i,j,0),(i-1,j,2)}x_{i,j,0}x_{i-1,j,2}$  takes 1, and the value of the cost function taken will increase. By doing this, the third constraint is represented as a first term. The second term is a penalty term that limits the direction of extending to one per bar. It represents the first constraint of the bar-tipping algorithm. This means that for a given coordinate (i, j), the sum of  $x_{i,j,d}$  [d = 0, 1, 2(, 3)] must take the value 1. Here, the bars in the second and subsequent columns cannot extend to the left by the second constraint. Thus, d takes (0, 1, 2, 3) when i = 0, and d takes (0, 1, 2) when  $i \ge 1$ . The third term is the penalty term for selecting two coordinates of the start and the goal from the coordinates (m, n). This means that for a given coordinate (m, n), the sum of  $X_{m,n}$  takes 2. In other words, two coordinates were selected as the start and the goal. The start and the goal are commutative in the maze. They are randomly selected from the two coordinates determined by the third term.  $X_{m,n}$  denotes whether or not to set the start and goal at the *m*-th row and n-th column of options of start and goal coordinates. When the (m, n) coordinate is chosen as the start and goal,  $X_{m,n}$  takes 1. Otherwise, it takes 0. There are no relations between  $X_{m,n}$  and  $x_{i,i,d}$  in Equation (1). This means that the maze structure and the start and goal determination coordinates have no relations. Figure 8 shows the coordinates (m, n) that are the options of the start and the goal. As Figure 8 shows, (m, n) is different from the coordinate setting bars; it is located at the four corners of the bars, where the bars do not extend.  $X_{m,n}$  and  $x_{i,j,d}$  are different.  $X_{m,n}$  are options of start and goal, and  $x_{i,j,d}$  are options of coordinates and directions to extend the bars. We have shown the simplest implementation of the maze generation following the bar-tipping algorithm by quantum annealer. Following the above a maze depending on randomness is generated. To generate a unique maze independent of randomness, we add the effect to make the maze more difficult in the cost function, and the difficulty is defined in terms of time (in seconds).

#### 2.2 Update rule

We propose an additional  $Q_{update}$  term to increase the time to solve the maze. We introduce a random term that takes random elements to change the maze structure. It is added to the Equation (1). First,  $Q_{update}$  term, the additional term which includes the new QUBO matrix  $Q_{update}$ , is given by

$$\lambda_{update1} \sum_{i,i'} \sum_{j,j'} \sum_{d,d'} Q_{update(k,k')} x_{i,j,d} x_{i',j',d'} + \lambda_{update1} \sum_{i} \sum_{j} \sum_{d} \sum_{m} \sum_{n} Q_{update(k,l)} x_{i,j,d} X_{m,n} + \lambda_{update1} \sum_{i} \sum_{j} \sum_{d} \sum_{m} \sum_{n} Q_{update(l,k)} X_{m,n} x_{i,j,d} + \lambda_{update2} \sum_{m,m'} \sum_{n,n'} Q_{update(l,l')} X_{m,n} X_{m',n'},$$

$$(3)$$

where

$$\begin{cases} k = d + (3N + 1)i & (j = 0) \\ k = d + 3j + 1 + (3N + 1)i & (j \neq 0) \\ l = (3N + 1)N + (N + 1)m + n. \end{cases}$$
(4)

Figure 9 shows the structure of  $Q_{update}$  and roles. Here, k', l' are the replacement of *i*, *j*, *m*, *n*, and *d* in *k*, *l* with *i'*, *j'*, *m'*, *n'*, and *d'*. *N* in Equation (4) is the size of the maze. The coefficients  $\lambda_{update1}$  and  $\lambda_{update2}$  are constants to adjust the effect of terms. The elements of  $Q_{update}$  related to the relation between the start and goal determination and the maze generation. This is located in part B, C in Figure 9 and multiplied by the  $\lambda_{update1}$ . The elements of  $Q_{update}$  related to the relation between the start and goal determination and the maze generation. This is located in part B, C in Figure 9 and multiplied by the  $\lambda_{update1}$ . The elements of  $Q_{update}$  related to the relation between the start and goal determination and the maze generation, part B, C in Figure 9 is multiplied by the  $\lambda_{update1}$ . The elements of  $Q_{update}$  related to the start and goal determination and the maze generation, part B, C in Figure 9 is multiplied by the  $\lambda_{update1}$ . The elements of  $Q_{update}$  related to the start and goal determination and the maze generation, part B, C in Figure 9 is multiplied by the  $\lambda_{update1}$ . The elements of  $Q_{update}$  related to the start and goal determination, part D in Figure 9 is multiplied by the  $\lambda_{update2}$ .



These are to control the maze difficulty without breaking the bartipping algorithm's constraints. Equation (3) is represented by the serial number k of each coordinate (i, j) at which bars can extend, and the sum l of the total number of coordinates at which the bars can extend and the serial number of coordinates (m, n), which are options for the start and the goal. Furthermore, The second term and the third term in Equation (3) allow the maze to consider the relation between the structure of the maze and the coordinates of the start and the goal.

Second, Qupdate, the new QUBO matrix, is given by

$$Q_{update} := p(t)Q_{update} + \left\{1 - p(t)\right\}Q_{random},\tag{5}$$

where  $Q_{random}$  is a matrix of random elements from -1 to 1 and p(t) depends on time t (in seconds) taken to solve the previous maze and is expressed as follows:

$$p(t) = \frac{1}{1 + e^{-at}}.$$
(6)

The  $Q_{update}$  is a matrix that was made with the aim of increasing the maze solving time through the maze solving iteration. The

initial Qupdate used in the first maze generation is a random matrix, and the next Qupdate that is used in the second or subsequent maze generation is updated using Equation (5), the maze solving time t, and the previous  $Q_{update}$ . The longer the solving time t of the maze is, the higher the percentage of the previous  $Q_{update}$ in the current  $Q_{update}$  and the lower the percentage of  $Q_{random}$ ; inversely, when t is small, the ratio of the previous  $Q_{update}$  is small, and the percentage of  $Q_{random}$  is significant. In other words, the longer the solving time t of the previous maze, the more characteristics of the previous term Qupdate remain. Here, a is a constant to adjust the percentage. The p(t) is a function that increases monotonically with t and takes 0 to 1. Thus, Qrandom, which the random element in Qupdate, increase as time t increases. After the maze is solved, the next maze QUBO is updated by Equation (5) using the time taken to solve the maze. The update is carried out only once before the maze generation. Repetition of the update will make the maze gradually difficult for individuals.

The sum of Equations (1) and (3) is always used to generate a new maze annealing from a maximally mixed state.

# 2.3 Experiments

#### 2.3.1 Generation of maze

We generate mazes by optimizing the cost function using DW\_2000Q\_6. Since the generated maze will not be solved, the update term is excluded for this experiment.  $\lambda_1 = 2$  and  $\lambda_2 = 2$  were chosen.



#### FIGURE 8

Black cells represent outer walls and inner bars (i, j). Red cells represent options of start and goal coordinates (m, n).

### 2.3.2 Computational cost

We compare the generation times of  $N \times N$  maze in DW\_2000Q\_6 from D-Wave, simulated annealer called SASampler and simulated quantum annealer called SQASampler from OpenJij, D-Wave's quantum-classical hybrid solver called hybrid\_binary\_quadratic\_model\_version2 (hereinafter referred to as "Hybrid Solver") and classical computer [MacBook Pro(14-inch, 2021), OS: macOS Monterey Version 12.5, Chip: Apple M1 Pro, Memory: 16 GB] based on bar-tipping algorithm coded with Python 3.11.5 (hereinafter referred to as "Classic"). The update term was excluded from this experiment. We set  $\lambda_1 = 2$  and  $\lambda_2 = 2$ . DW\_2000Q\_6 was annealed 1,000 times for 20  $\mu$ s, and its QPU annealed time for maze generation as calculated using time-to-solution (TTS). SASampler and SQASampler were annealed with 1,000 sweeps. These parameters were constant throughout this experiment. Regression curves fitted using the least squares method were drawn from the results to examine the dependence of computation time on maze size.

#### 2.3.3 Effect of update term

The solving time of  $9 \times 9$  maze generated without  $Q_{update}$ and using  $Q_{update}$  was measured. This experiment asked 12 human subjects to solve mazes one set (30 times). To prevent the players from memorizing maze structure, they can only observe the limited  $5 \times 5$  cells. In other words, only two surrounding cells can be observed. The increase rate from the first step of simple moving average of 10 solving times was plotted on the graph. For this experiment,  $\lambda_1 = 2$ ,  $\lambda_2 = 2$ ,  $\lambda_{update1} = 0.15$ ,  $\lambda_{update2} = 0.30$ , and a = 0.05 were chosen. For two  $\lambda_{update}$ , we chose larger values that do not violate the constraints of the bar-tipping algorithm. We chose a value in which Equation (6) will be ~0.8 (80%) when t = 30 s as a constant a.



Structure of  $Q_{update}$ . Part A is related to maze generation. Part B and part C are related to the relation between maze generation and the start and goal determination. Part D is related to the start and goal determination.



### 2.4 Applicatons

The cost function in this study has many potential applications by generalizing it. For example, it can be applied to graph coloring and traffic light optimization. Graph coloring can be applied by allowing adjacent nodes to have different colors. Traffic light optimization can address the traffic light optimization problem by looking at the maze generation as traffic flow. Roughly speaking, our cost function can be applied to the problem of determining the next state by looking at adjacent states.

 $Q_{update}$  can be applied to the problem of determining the difficulty of the next state from the previous result. The selection of personalized educational materials is one of the examples. Based on the solving time of the previously solved problems, the educational materials can be selected at a difficulty suitable for the individual. This is the most fascinating direction in future studies. As described above, we should emphasize that  $Q_{update}$  proposed in this study also has potential use in various fields related to training and education.

### **3** Results

### 3.1 Generation of maze

Figure 10 shows execution examples of  $9 \times 9$  and  $15 \times 15$  mazes generated by optimizing the cost function using DW\_2000Q\_6.

### 3.2 Computational cost

Fits of the form  $aN^2 + bN + c$  is applied to each of the datasets using the least squares method. The results are as follows. Figure 11



shows the relation between TTS for maze generation and maze size on DW\_2000Q\_6. DW\_2000Q\_6 is  $\mathcal{O}(N)$  or  $\mathcal{O}(N^2)$ . Even if it is quadratically dependent on the maze size, its deviation is smaller than the other solvers. Figure 12 shows the relation between maze generation time and maze size on Classic, SASampler, and SQASampler. Classic  $[(0.855\pm0.090)N^2+(0.6\pm1.5)N+(2.2\pm5.1)]$ , SASampler  $[(28.8 \pm 1.2)N^2 + (36 \pm 20)N + (129 \pm 71)]$ , and SQASampler  $[(172.8 \pm 4.4)N^2 + (287 \pm 73)N - (1.5 \pm 2.5) \cdot 10^2]$  exhibit quadratic dependence on the maze size  $\mathcal{O}(N^2)$ . Most of the



#### FIGURE 12

(A) The time to reach the ground state as a function of the maze size in Classic. The error bars represent a 95% confidence interval. The regression curve is  $[(0.855 \pm 0.090)N^2 + (0.6 \pm 1.5)N + (2.2 \pm 5.1)]$ . (B) Time to reach the ground state as a function of the maze size in SASampler. The error bars represent a 95% confidence interval. The regression curve is  $[(28.8 \pm 1.2)N^2 + (36 \pm 20)N + (129 \pm 71)]$ . (C) Time to reach the ground state as a function of the maze size in SQASampler. The error bars represent a 95% confidence interval. The regression curve is  $[(172.8 \pm 4.4)N^2 + (287 \pm 73)N - (1.5 \pm 2.5) \cdot 10^2]$ .





solvers introduced here are  $\mathcal{O}(N^2)$  since they are extending  $N \times N$  bars to generate a maze. Figure 13 shows the comparison of maze generation time between DW\_2000Q\_6 and Classic. DW\_2000Q\_6 has a smaller coefficient  $N^2$  than the classical algorithm, and after N = 5, DW\_2000Q\_6 shows an advantage over Classic in the maze generation problem. The improvement using quantum annealing occurred because it determines the direction of  $N \times N$  bars at once. Figure 14 shows the relation between maze generation time and maze size on Hybrid Solver. Linear and quadratic fits applied to the dataset indicate that the Hybrid Solver is  $\mathcal{O}(1)$  or  $\mathcal{O}(N)$  [ $(3.29\pm0.83)\cdot10^2N+(2.99325\pm0.00090)\cdot10^6$ ] between N = 1 and N = 18 and then shifted to  $\mathcal{O}(N^2)$  [ $(6.899\pm0.065)\cdot10^3N^2 - (0.4\pm3.2)\cdot10^3N + (6.90\pm0.39)\cdot10^5$ ]. The shift in the computational cost of Hybrid Solver may have resulted from a change in its algorithm.

#### 3.3 Effect of update term

Here, 12 human subjects are asked to solve the maze one set (30 times), and the maze is shown to increase in difficulty as it adapts to each human subject. Figure 15A shows the increase rate from the first step of simple moving average of 10 solving time of maze generated without  $Q_{update}$  and individual increase rate. The solving time of the maze without  $Q_{update}$  was slightly getting shorter overall. Figure 15B shows the increase rate from the first step of simple moving average of 10 solving time of the maze generated using  $Q_{update}$  and individual increase rate. The solving time of the maze using  $Q_{update}$  was getting longer overall. Most of the players increased their solving time, but some players decreased or did not change their solving time. In addition, nine players' average of the solving time of the maze generated using  $Q_{update}$  time of the maze generated using  $Q_{update}$  be using time. In addition, nine players' average of the solving time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time. In addition, nine players' average of the solving time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time. In addition, nine players' average of the solving time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze generated using  $Q_{update}$  be using time of the maze g



increased than that of the maze generated without  $Q_{update}$ . These show that  $Q_{update}$  has the potential to increase the difficulty of the mazes.

# 4 Discussion

In this study, we show that generating difficult (longer the maze solving time) mazes using the bar-tipping algorithm is

also possible with quantum annealing. By reformulating the bartipping algorithm as the combinatorial optimization problem, we generalize it more flexibly to generate mazes. In particular, our approach is simple but can adjust the difficulty in solving mazes by quantum annealing.

In Section 3.2, regarding comparing computational costs to solve our approach to generating mazes using TTS, DW\_2000Q\_6 has a smaller coefficient of  $N^2$  than the classical counterpart. Therefore, as *N* increases, the computational cost of DW\_2000Q\_6

can be expected to be lower than that of the classical simulated annealing for a certain time. Unfortunately, since the number of qubits in the D-Wave quantum annealer is finite, the potential power of generating mazes by quantum annealing is limited. However, our insight demonstrates some advantages of quantum annealing against its classical counterpart. In addition, we observed that the hybrid solver's computational cost was constant up to N = 18. This indicates that hybrid solvers will be potentially effective if they are developed to deal with many variables in future.

In Section 3.3, we proposed  $Q_{update}$  to increase the solving time using quantum annealing. We demonstrated that introducing  $Q_{update}$  increased the time to solve the maze and changed the difficulty compared with the case where  $Q_{update}$  was not introduced. At this time, the parameters ( $\lambda_{update1}$ ,  $\lambda_{update2}$ , and *a*) were fixed. Difficult maze generation for everyone may be possible by adjusting the parameters individually.

One of the directions in the future study is in applications of our cost function in various realms. We should emphasize that  $Q_{update}$  proposed in this study also has the potential use in various fields related to training and education. The powerful computation of quantum annealing and its variants open the way to such realms with high-speed computation and various solutions.

### Data availability statement

The original contributions presented in the study are included in the article/supplementary material, further inquiries can be directed to the corresponding authors.

# **Ethics statement**

Ethical approval was not required for the studies involving humans because the data was obtained through collaboration among the participants of a group workshop developing an application using quantum annealing. The studies were conducted in accordance with the local legislation and institutional requirements. Written informed consent for participation was not required from the participants or the participants' legal guardians/next of kin in accordance with the national legislation and institutional requirements because the data was obtained through collaboration among the participants of a group workshop developing an application using quantum annealing.

# Author contributions

YI: Writing – original draft, Writing – review & editing, Conceptualization, Data curation, Formal analysis, Investigation, Software, Validation, Visualization, Methodology. TY: Writing – original draft, Writing – review & editing, Conceptualization, Validation, Methodology. KO: Writing – original draft, Writing – review & editing, Conceptualization, Validation, Methodology. MO: Supervision, Writing – review & editing, Funding acquisition, Project administration.

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# **Conflict of interest**

MO is employed by Sigma-i.

The remaining authors declare that the research was conducted without any commercial or financial relationships that could be construed as a potential conflict of interest.

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