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# Seismic responses of isolated bridges subjected to near-fault ground motions: simple pulses vs. whole records

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Velocity pulse with strong energy input is the significant feature of near-fault ground motions. Bridges close to or passing across seismic faults may suffer from higher failure risk, which is inseparable from the influence of velocity pulse. This study aims to evaluate the nonlinear response characteristics of bridge structures under various near-fault ground motion conditions. A typical isolated continuous girder bridge is adopted, and two corresponding finite element models, i.e., considering and ignoring the heating effect of lead core bearings (LRBs), are established based on the OpenSees platform. Then, a total of 40 near-fault ground motion records are selected, and the pulses are extracted. Both the energy-based and deformation-based seismic responses are captured and compared to reveal the differences for the isolated bridge subjected to the original waves and the extracted pulses. The results highlight that the accuracy of the seismic evaluation based on the extracted pulses strongly depends on the precondition that the pulse period is close to the fundamental period of the isolated bridge. Hence, inputting the extracted pulses for predicting the in-elastic seismic response of isolated bridges locating at near-fault region is not an adequate replacement for those original waves of near-fault ground motions. In addition, the heating effect of LRBs will be magnified for the seismic response of isolated bridges subjected to the extracted pulses, and it will mainly affect the seismic responses of bearings and piers, i.e., the former increases and the latter decreases.

## KEYWORDS

isolated bridges, near-fault ground motion, velocity pulse, energy dissipation, heating effect of lead core bearings

## 1 Introduction

Bridges are not only the hubs of traffic lines, but also an important part of the lifeline project. Usually, bridges close to or passing across seismic faults are suffering from higher failure risk, which has been widely realized in accordance with the previous investigations on post-earthquake damages (Hall et al., 1995; Kawashima, 2002; Han et al., 2018; Cheng et al., 2019; Hui et al., 2023; Jiang et al., 2024), such as the Northridge Earthquake in 1994, Kobe Earthquake in 1995, ChiChi Earthquake in 1999, Kocaeli Earthquake in 1999, and Wenchuan Earthquake in 2008. The most key factor is that near-fault ground motions containing strong velocity pulses with high energy input will increase the seismic demands

of bridges, and consequently, resulting in severer damages compared with those attacked by far-fault ground motions (Cheng et al., 2016; Pang et al., 2022; Zhong et al., 2023a; Zhong et al., 2023b; Yang et al., 2023). Up to now, near-fault ground motions with velocity pulses and their influences on engineering structures have been vital topics to both researchers and engineers.

In fact, evaluating the seismic behaviors of engineering structures is closely related to the ground motion characteristics and the numerical modeling (Castaldo and Miceli, 2023; Wu et al., 2024). Different from those normal structures, the seismic isolated structures should be more prone to large displacement (Wu et al., 2019). As for the near-fault ground motion records, utilizing simple pulses to evaluate the structural responses has been focused on for a long time due to the impulsive nature (Biggs, 1964), and different mathematical models of simple pulses were presented to describe the significant characteristic of near-fault ground motions (Hall et al., 1995; Makris, 1997; Makris and Chang, 2000; Mavroeidis and Papageorgiou, 2003; He and Agrawal, 2008). These above simple pulse models were found to be able to adequately evaluate the peak response of long-period single degree of freedom (SDOF) systems under near-fault ground motions, and some researchers concluded that the structural seismic responses could be assessed by utilizing those proposed simple pulse models (Mavroeidis and Papageorgiou, 2003; Alavi and Krawinkler, 2004; Mavroeidis et al., 2004). Meanwhile, any numerical model is always affected by epistemic uncertainties (Bertagnoli et al., 2024). Furthermore, simple pulses were deemed that they could adequately estimate the response of a multiple degree of freedom (MDOF) system if they could capture the response of the first mode of the system (Alavi and Krawinkler, 2004). Though this assumption may be valid for short-period structures primarily responding in the form of the first vibration mode, it is questionable for those structures (i.e., bridges and tall buildings) responding with multiple vibration modes coupled, because the response of higher vibration modes cannot be captured by the simple pulse models without high frequencies (Rupakhty and Sigbjörnsson, 2011). Similarly, it is vital to figure out whether the seismic response of isolated bridges subjected to near-fault ground motions can be adequately evaluated by the impulse waves extracted from whole records.

As noted above, near-fault ground motions usually contain strong velocity pulses with high energy input. Estimating the seismic response of isolated bridges in terms of energy offers a new view to reveal the seismic damage process to structures. More and more attentions have been paid to since the energy-based seismic design was first proposed by Housner (1956). The energy-based seismic responses of isolated bridges includes the total input energy, the hysteretic energy dissipations of bearings and piers, kinetic energy, and the damping energy. Kawashima (1998) studied the hysteretic energy dissipations of isolation bearings and piers affected by the ratio of their yield strengths. They found that the energy-based seismic response of piers decreased when the ratio of yield strengths of isolation bearings and piers decreased, and the opposite conclusion was obtained for the isolation bearings. Based on the energy equilibrium theory, Li et al. (2011) established the energy equations of bridges of passenger dedicated line, and studied the seismic energy response and its distribution rules at the nonlinear state via finite element analysis based on the software of ANSYS. It turned out that the seismic input

energy was mainly consumed by the structural hysteretic energy dissipation and damping energy dissipation, and the soil-structure interaction effects and peak ground acceleration significantly affected the seismic input energy, structural hysteretic energy dissipation, and damping energy dissipation. Jiang et al. (Jiang and Zhu, 2006; Jiang et al., 2009; Jiang et al., 2011) presented an energy-based seismic design method for bridges subjected near-fault ground motions, and discussed the influencing factors (i.e., the structural damping, ductility coefficient, and self-vibration period of the structure) for hysteretic energy distribution ratio. However, their research work mainly focused on the SDOF system or the short-period structures primarily responding in the first vibration mode, further studies on long-period structures need to be performed.

This paper tries to reveal the seismic response of isolated bridges subjected to near-fault ground motions by inputting the whole records and the extracted pulses. Meanwhile, the transformation of seismic energy is traced. In the following sections, the calculation method for seismic energy of MDOF system is introduced firstly, including the input energy, the hysteretic energy dissipations of bearings and piers, kinetic energy, and the damping energy. Then, a total of 40 near-fault ground motion records containing velocity pulses are selected, and decomposed as the extracted pulse and the residual ground motion. After that, an illustrative example of isolated bridges is adopted, and two finite element models, which are established to investigate the effect of lead core heating of the LRBs on the seismic response of isolated bridges, are established based on the OpenSees platform. Further, nonlinear dynamic time history analyses are carried out by inputting the original waves and the extracted pulses of near-fault ground motions, and the energy-based and deformation-based seismic responses are both estimated and compared to investigate their differences under different inputs.

## 2 Seismic energy in structures

The kinetic equation of MDOF system excited by ground motions can be expressed as

$$[M]\{\ddot{u}(t)\} + [C]\{\dot{u}(t)\} + [K]\{u(t)\} = -[M]\{r\}\ddot{u}_g(t) \quad (1)$$

where  $\{u(t)\}$ ,  $\{\dot{u}(t)\}$  and  $\{\ddot{u}(t)\}$  are the displacement, velocity and acceleration vectors of the masses;  $[M]$ ,  $[C]$  and  $[K]$  are the mass, damping and stiffness matrixes of the MDOF system;  $\ddot{u}_g(t)$  is the ground acceleration; and  $\{r\} = \{0, \dots, \overset{r}{1}, \dots, 0\}^T$  is a vector with some elements equal to unity which subjected to effective earthquake forces, and the others equal to zero.

The attack of earthquakes to a structure is a process of energy transfer, transform and consumption. The use of energy method helps to reveal the seismic failure mechanism of structures (Housner, 1956; Shi et al., 2020), and the equation of energy balance should always be applicable for a structure under seismic loadings as Eq. 2 (Uang and Bertero, 1990; Decanini and Mollaioli, 2001)

$$E_i(t) = E_k(t) + E_\xi(t) + E_a(t) \quad (2)$$

where  $E_i(t)$  is the input energy;  $E_k(t)$  is the kinetic energy;  $E_\xi(t)$  is the damping energy; and  $E_a(t)$  is the absorbed energy that consists

TABLE 1 Information of the selected 40 near-fault ground motions (Baker, 2007).

No.	Event	Year	Station	$M_s$	$R$ (km)	$T_p$ (s)	$V_{s30}$ (m/s)
1	Imperial Valley-06	1979	EC County Center FF	6.5	7.3	4.5	192
2	Imperial Valley-06	1979	EC Meloland Overpass FF	6.5	0.1	3.3	186
3	Imperial Valley-06	1979	El Centro Array #4	6.5	7.1	4.6	209
4	Imperial Valley-06	1979	El Centro Array #5	6.5	4.0	4.0	206
5	Imperial Valley-06	1979	El Centro Array #6	6.5	1.4	3.8	203
6	Imperial Valley-06	1979	El Centro Array #7	6.5	0.6	4.2	211
7	Imperial Valley-06	1979	El Centro Array #8	6.5	3.9	5.4	206
8	Imperial Valley-06	1979	El Centro Differential Array	6.5	5.1	5.9	202
9	Morgan Hill	1984	Coyote Lake Dam (SW Abut)	6.2	0.5	1.0	597
10	Loma Prieta	1989	Gilroy - Gavilan Coll	6.9	10.0	1.8	730
11	Loma Prieta	1989	LGPC	6.9	3.9	4.4	478
12	Landers	1992	Lucerne	7.3	2.2	5.1	685
13	Landers	1992	Yermo Fire Station	7.3	23.6	7.5	354
14	Northridge-01	1994	Jensen Filter Plant	6.7	5.4	3.5	373
15	Northridge-01	1994	Jensen Filter Plant Generator	6.7	5.4	3.5	526
16	Northridge-01	1994	Newhall - Fire Sta	6.7	5.9	1.0	269
17	Northridge-01	1994	Newhall - W Pico Canyo Rd	6.7	5.5	2.4	286
18	Northridge-01	1994	Rinaldi Receiving Sta	6.7	6.5	1.2	282
19	Northridge-01	1994	Sylmar - Converter Sta	6.7	5.4	3.5	251
20	Northridge-01	1994	Sylmar - Converter Sta	6.7	5.2	3.5	371
21	Northridge-01	1994	Sylmar - Olive View Med FF	6.7	5.3	3.1	441
22	Kobe, Japan	1995	KJMA	6.9	1.0	1.0	312
23	Kobe, Japan	1995	Takarazuka	6.9	0.3	1.4	312
24	Kocaeli, Turkey	1995	Gebze	7.5	10.9	5.8	792
25	Chi-Chi, Taiwan	1999	CHY028	7.6	3.1	2.2	543
26	Chi-Chi, Taiwan	1999	CHY101	7.6	10.0	4.6	259
27	Chi-Chi, Taiwan	1999	TCU049	7.6	3.8	11.7	487
28	Chi-Chi, Taiwan	1999	TCU052	7.6	0.7	8.4	579
29	Chi-Chi, Taiwan	1999	TCU053	7.6	6.0	12.8	455
30	Chi-Chi, Taiwan	1999	TCU054	7.6	5.3	10.5	461
31	Chi-Chi, Taiwan	1999	TCU068	7.6	0.3	12.2	487
32	Chi-Chi, Taiwan	1999	TCU075	7.6	0.9	5.2	573
33	Chi-Chi, Taiwan	1999	TCU076	7.6	2.8	4.0	615
34	Chi-Chi, Taiwan	1999	TCU082	7.6	5.2	9.0	473
35	Chi-Chi, Taiwan	1999	TCU087	7.6	7.0	9.4	474
36	Chi-Chi, Taiwan	1999	TCU101	7.6	2.1	10.0	273
37	Chi-Chi, Taiwan	1999	TCU102	7.6	1.5	9.7	714
38	Chi-Chi, Taiwan	1999	TCU103	7.6	6.1	8.2	494

(Continued on following page)

TABLE 1 (Continued) Information of the selected 40 near-fault ground motions (Baker, 2007).

No.	Event	Year	Station	$M_s$	$R$ (km)	$T_p$ (s)	$V_{s30}$ (m/s)
39	Chi-Chi, Taiwan	1999	TCU122	7.6	9.4	10.9	475
40	Chi-Chi, Taiwan	1999	WGK	7.6	10.0	4.4	259

of the recoverable elastic strain energy  $E_s(t)$  and the irrecoverable hysteretic energy directly related to the damage  $E_h(t)$ . In accordance with Eq. 1, the above items of various energies can be written as

$$E_i(t) = - \int_0^t \{\dot{u}(t)\}^T [M] \{r\} \ddot{u}_g(t) dt \quad (3)$$

$$E_k(t) = \int_0^t \{\dot{u}(t)\}^T [M] \{\dot{u}(t)\} dt \quad (4)$$

$$E_\xi(t) = \int_0^t \{\dot{u}(t)\}^T [C] \{\dot{u}(t)\} dt \quad (5)$$

$$E_a(t) = \int_0^t \{\dot{u}(t)\}^T [K] \{u(t)\} dt \quad (6)$$

Note that Eqs 3–6 should be “relative” energy equations, which are derived by integrating Eq. 1 with respect to  $u$  (Uang and Bertero, 1990). Uang (Uang and Bertero, 1990) compared the uses of “relative” and “absolute” energy equations and concluded that no significant differences observed for a constant displacement ductility in the period range of practical interest, i.e., 0.3–5.0 s. Therefore, the “relative” energy equations are adopted in this study in consideration of calculation efficiency and practicality.

### 3 Near-fault ground motions and their decompositions

#### 3.1 Selected near-fault ground motions

Using the Next-Generation Attenuation (NGA) Project ground motion library, Baker (2007) proposed an algorithm to select ground motions for the Transportation Research Program of the Pacific Earthquake Engineering Research Center (PEER). Besides, some sets of ground motions were also provided, which can be widely adopted to satisfy numerous needs since they were not developed as structure-specific or site-specific (Cheng et al., 2021a).

The set of pulse-like ground motions, which contain strong velocity pulses in the strike-normal components, is adopted in this study. The details of the selected near-fault ground motions are summarized in Table 1. Where  $M_s$  is the moment magnitude of ground motions;  $R$  is the closest distance from the recording site to the fault rupture;  $T_p$  is the period of the velocity pulse in strike-normal direction; and  $V_{s30}$  is the average shear wave velocity in the top 30 m.

#### 3.2 Decomposition of ground motions

One of the most significant characteristics of near-fault ground motions is the strong velocity pulses. Based on wavelet analysis,

Baker (2007) presented an approach to quantitatively identify near-fault ground motions, and meanwhile, the pulse could be effectively extracted from the original ground motion. According to their method, a near-fault ground motion, which is recorded by TCU075 Station in the 1999 Chi-Chi earthquake, is taken as an example to show the decomposition result in Figure 1. Where the peak ground velocities (PGVs) are 88.58, 72.8, and 49.65 cm/s, respectively, corresponding to the original wave, the extracted pulse, and the residual ground motion.

As the critical parameters related to the typical characteristics of near-fault ground motions, i.e., the pulse period  $T_p$  and the PGV/PGA ratio (where PGA stands for the peak ground acceleration), their relationships are explored and compared for the original and extracted ground motions in Figures 2, 3. Note that the  $PGV_O$  and  $PGA_O$  are the peak ground velocity and acceleration of original ground motions, and the  $PGV_P$  and  $PGA_P$  are the peak ground velocity and acceleration of extracted ground motions. Figure 2 displays a trend that the peak ground motions, both PGA and PGV, decrease when the pulse period increases, but the discreteness is relatively large for both the original and extracted ground motions. As revealed in Figure 3, though the PGV/PGA ratio of extracted ground motions shows a strong positive correlation with the pulse period  $T_p$ , the discreteness is still significant for the original ground motions. However, linear fit can be effectively performed between the pulse period  $T_p$  and the PGV/PGA ratio for the extracted ground motions, and the goodness of fit ( $R^2$ ) equals to 0.9629. Hence, it should be both feasible to describe the effect of pulse like on the structural dynamic response with the pulse period  $T_p$  and the PGV/PGA ratio.

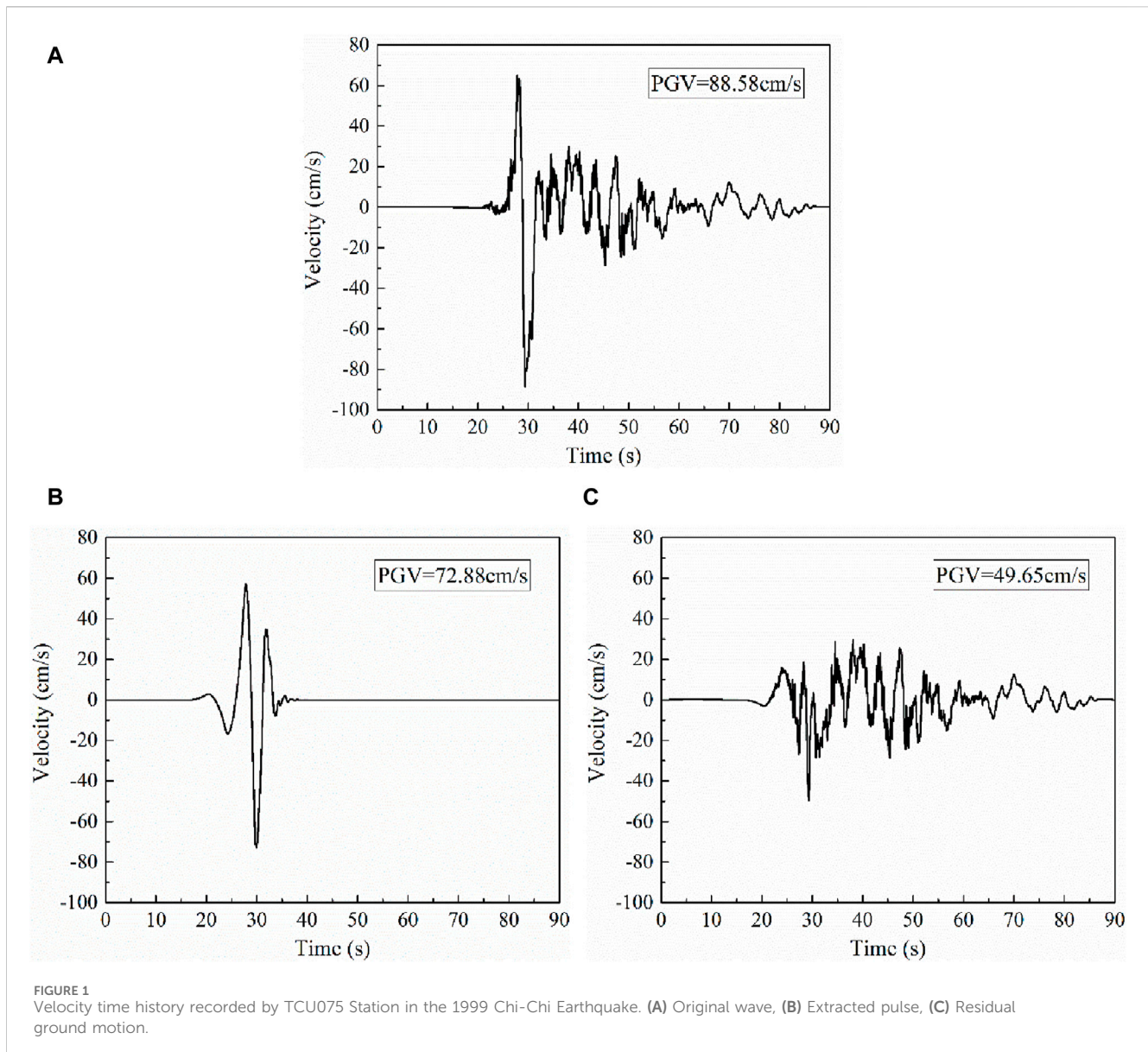
### 4 Illustrative example of isolated bridges

The original and extracted ground motions of the selected near-fault ground motions are adopted to investigate the seismic behavior of isolated bridges. Meanwhile, the temperature-dependent performance of LRBs, which is caused by the lead core heating under seismic loadings, is taken into account.

#### 4.1 Basic information of adopted example

A six-span continuous girder bridge, which is the approach part of an isolated bridge, is adopted in this study, and the schematic diagram is displayed in Figure 4. The total length of the adopted continuous girder bridge is 510 m, with each span of 85 m. The steel-concrete composite section, which utilizes Grade C50 concrete and Q345 steel, is applied to the girder. The height of the seven reinforced concrete bridge piers is 19 m, and the Grades of concrete and reinforcing steel are C50 and





HRB335, respectively. The longitudinal reinforcement ratio is calculated to be 1.195%, and the concrete cover is 70 mm. More details about the reinforcement configuration of the pier cross-section can be seen in Figure 4C and Table 2 (Fu et al., 2022).

A total of four LRBs are set along the transverse direction of bridge for each pier, and the parameters of LRBs are summarized in Table 3. Where  $F_y$  is the yield strength;  $K_c$  is the elastic stiffness; and  $\alpha$  is the post-yield stiffness ratio. Note that the adopted LRBs of the side piers (Piers 1 and 7) are different from that of the middle ones (Piers 2–6), which can be seen in Figure 5.

## 4.2 Finite element model

Two finite element models (FEMs) of the isolated bridge are built with the OpenSees to investigate the seismic performance of isolated bridge affected by the lead core heating, as shown in Figure 6. Note that the soil-structure interaction effect is not taken into account here.

The main differences between the two FEMs are the adopted elements of bearings, i.e., the elastomeric bearing (plasticity) element (corresponding to FEM 1 of the adopted bridge) and the LeadRubberX bearing element (corresponding to FEM 2 of the adopted bridge), which are utilized for the conditions that ignoring and considering the lead core heating of the LRBs, respectively.

The girders and bent caps are modelled via the elastic beam column elements, while the piers, which may be inelastic during seismic loadings, are simulated by the nonlinear beam-column element. A total of five elements are adopted for each pier, and the number of Gauss-Lobatto integration points along each element is five. With respect to the cross section of each pier, meshes with 7 cm × 7 cm are utilized. The constitutive laws of concrete and reinforcing steels are simulated with the Concrete 01 and Steel 02 material models, respectively. Analysis of natural vibration characteristics is performed based on the established FEM, and the first five natural periods of vibration are 1.09, 0.87, 0.85, 0.84, and 0.79 s, respectively.

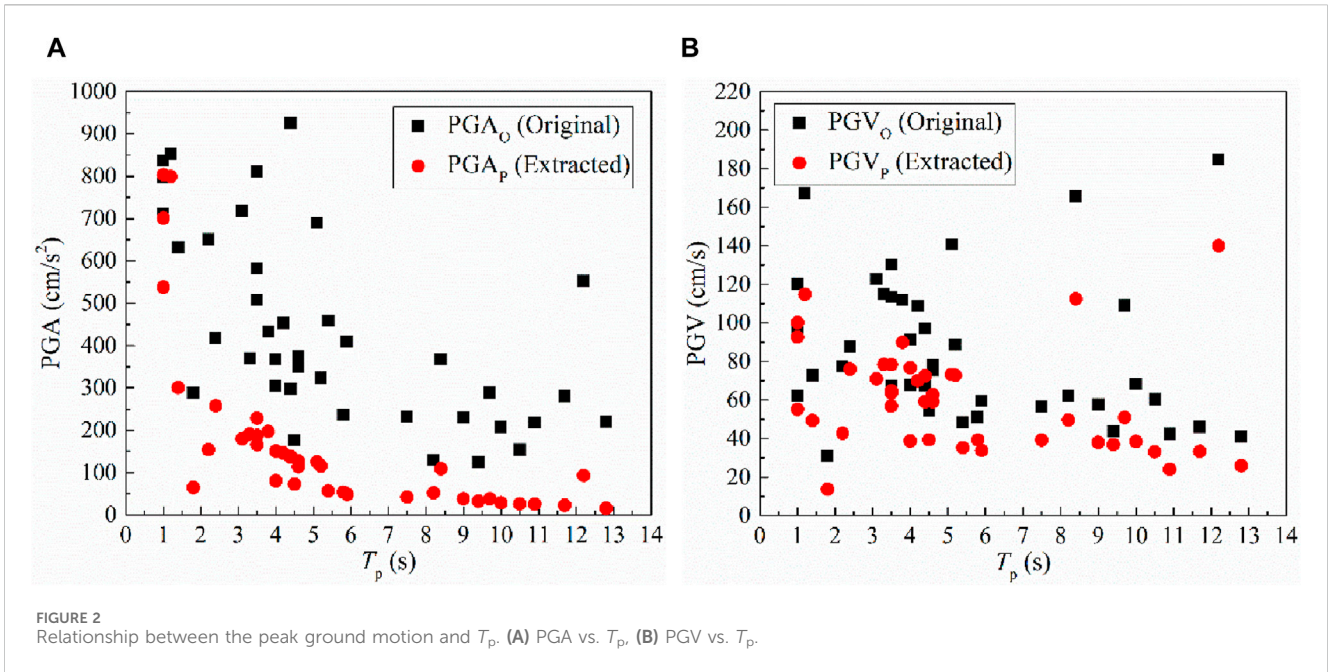


FIGURE 2 Relationship between the peak ground motion and  $T_p$ . (A) PGA vs.  $T_p$ , (B) PGV vs.  $T_p$ .

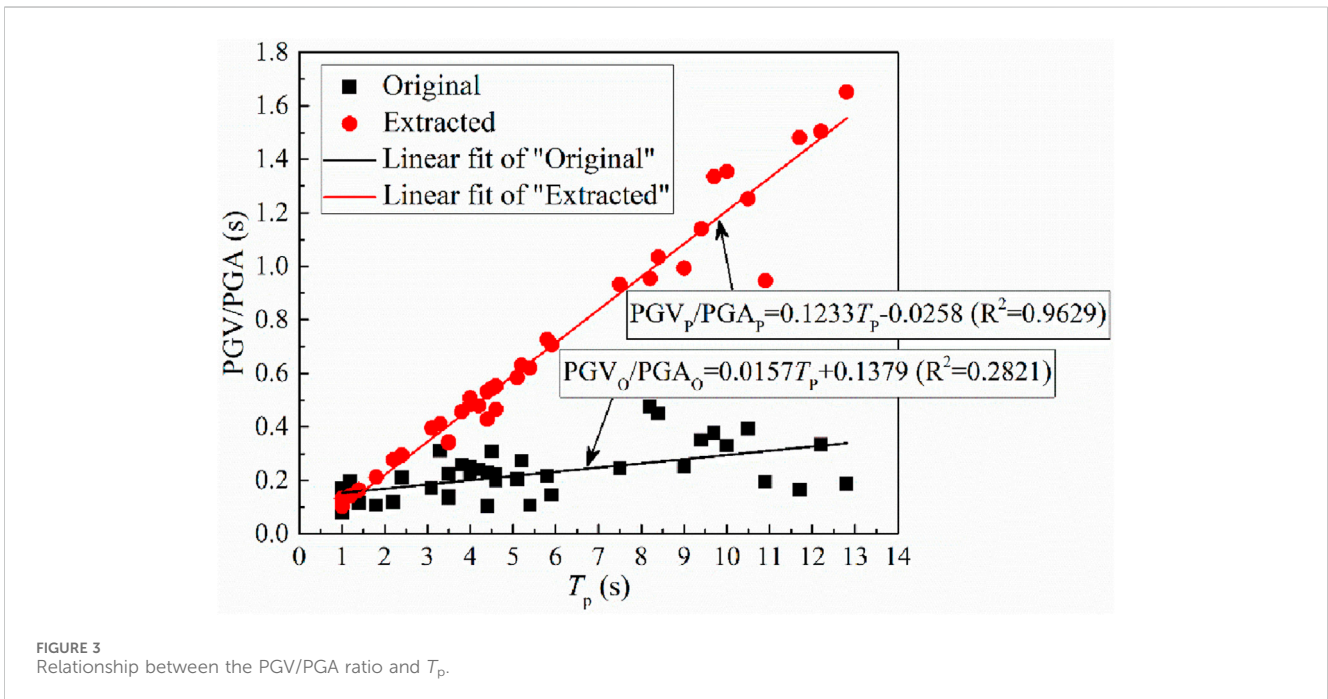


FIGURE 3 Relationship between the PGV/PGA ratio and  $T_p$ .

### 4.3 Nonlinear dynamic time history analyzes

The Rayleigh damping model is adopted, and the damping ratio is 0.05. Nonlinear dynamic time history analyzes are carried out to quantitatively investigate the seismic response of the isolated bridge affected by the lead core heating of the LRBs. Both the original waves and extracted pulses of the selected 40 near-fault ground motions (as shown in Table 1) are adopted, and the energy-based seismic responses of the whole bridge structure and the individual components are calculated and compared.

#### 4.3.1 Energy-based seismic responses

##### 4.3.1.1 Input energies to the whole isolated bridge

The input energies to the whole isolated bridge subjected to different ground motions, including the original waves and extracted pulses, are shown in Figures 7, 8. As can be seen from Figure 7, the input energies of extracted pulses to the whole isolated bridge  $E_{ip}$  are significantly less than that of original waves  $E_{io}$ , and this trend is almost not affected by the lead core heating of LRBs. The results shown in Figure 7B exhibits that the  $E_{ip}/E_{io}$  ratios generally increase first and then, decrease when the pulse period increases, and finally approaches to zero when the pulse period is larger than 6.0 s.

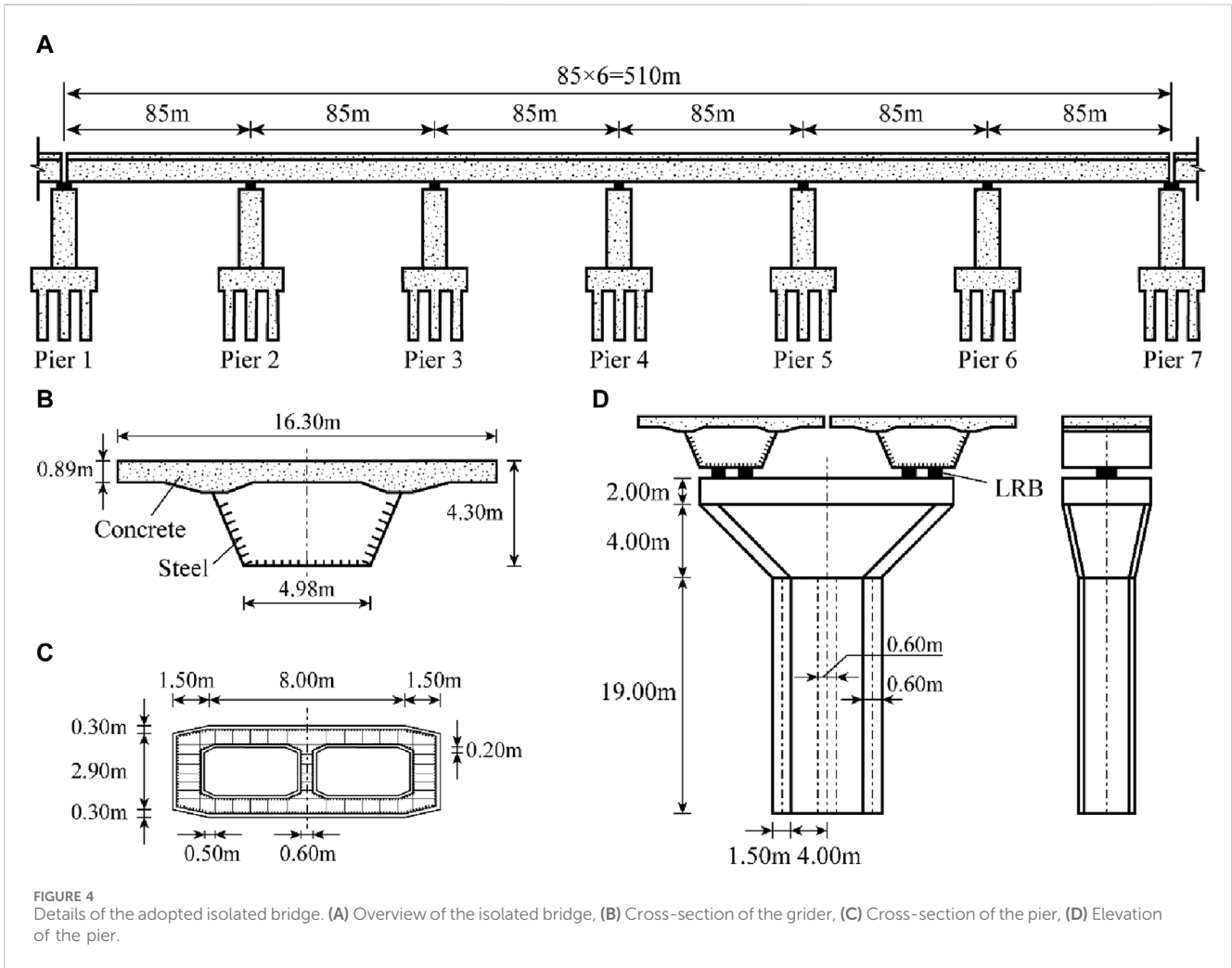


FIGURE 4 Details of the adopted isolated bridge. (A) Overview of the isolated bridge, (B) Cross-section of the girder, (C) Cross-section of the pier, (D) Elevation of the pier.

TABLE 2 Reinforcement configuration of the pier cross-section.

Location	Longitudinal reinforcement		Transverse reinforcement	
	Number	Diameter (mm)	Spacing (mm)	Diameter (mm)
Outer layer	356	28	150	16
Inner layer	138	20	150	16
Middle layer	34	20	—	—

TABLE 3 Parameters of the LRBs.

Type	$F_y$ (kN)	$K_e$ (kN/mm)	$\alpha$	Location
LRB10000Y	449	32.78	0.122	Side piers
LRB19000Y	810	51.97	0.128	Middle piers

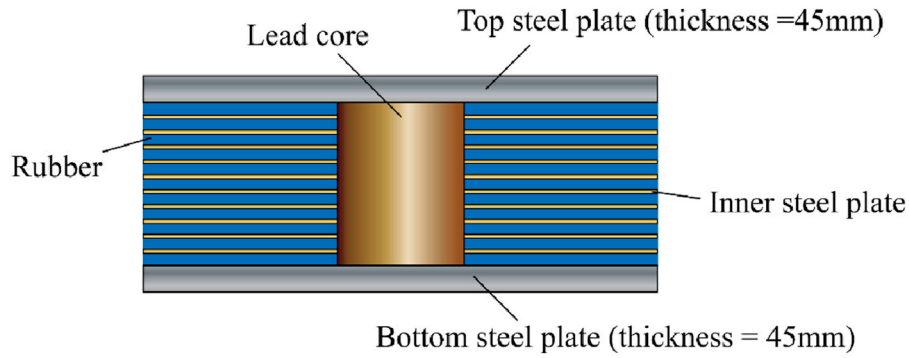
Besides, the  $E_{iP}/E_{iO}$  ratio reaches the maximum (83.81%) when the pulse period is about 2.5 s.

Note that, as displayed in Figure 8, the changing trend of the  $E_{iP}/E_{iO}$  ratio influenced by the  $PGV_P/PGA_P$  ratio is consistent

with that shown in Figure 7, and the critical values of the  $PGV_P/PGA_P$  ratios are 0.3 and 0.7 (the corresponding  $T_p$  values are 2.5 and 6.0 s in Figure 7), respectively, which match well with the linear fitted relationship between the  $PGV_P/PGA_P$  ratio and  $T_p$  in Figure 3. Hence, it should be equivalent to reveal the effect of velocity pulse on the seismic response of the adopted bridge via the pulse period and the  $PGV_P/PGA_P$  ratio. For simplify, only the pulse period is mainly focused on in the following study.

In addition, as displayed in Figures 7A, 8A, by comparing the input energies of original waves to the whole isolated bridge, slight differences can be observed when the lead core heating of





Type of LRB	LRB10000Y	LRB19000Y
Diameter of lead core	239 mm	321 mm
Thickness of rubber	20.5 mm × 11	18 mm × 14
Thickness of inner steel plate	5 mm × 10	5 mm × 13

FIGURE 5 Schematic diagram of the LRBs.

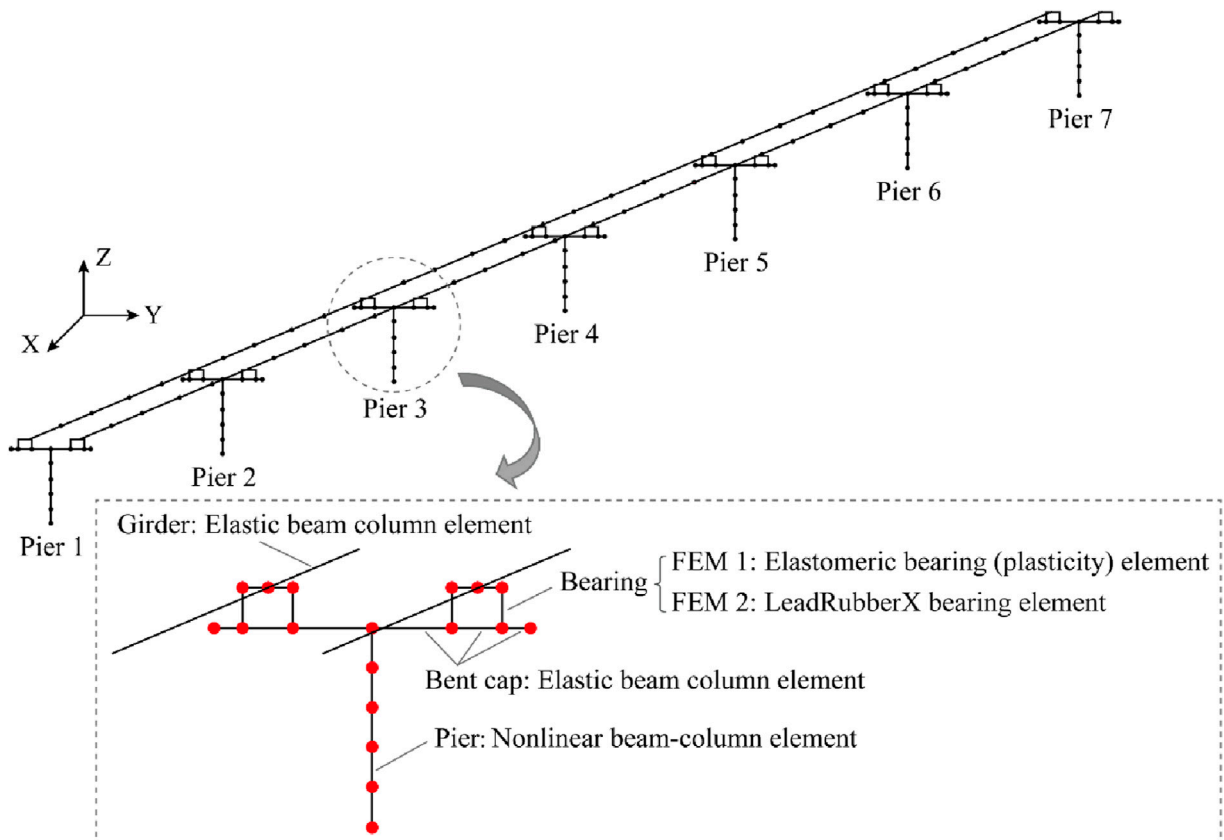
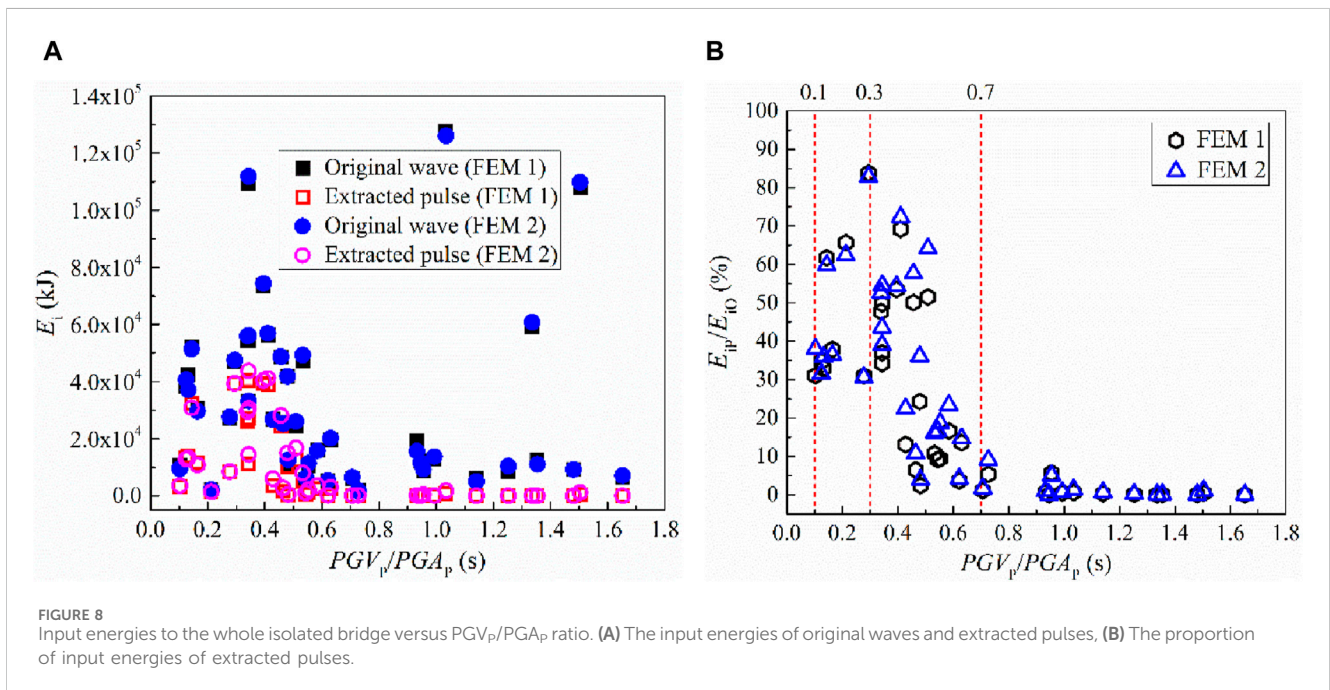
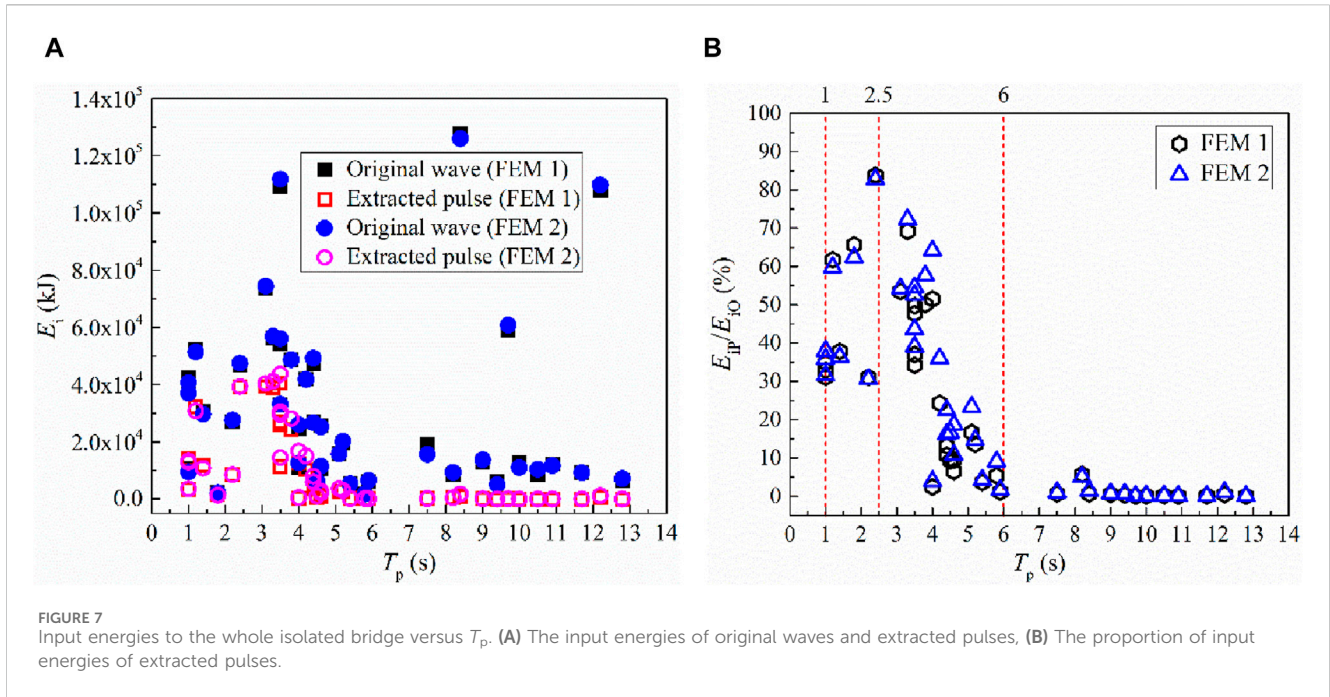


FIGURE 6 FEMs of the isolated bridge.

the LRBs is ignored and considered. However, the  $E_{ip}/E_{iO}$  ratio is significantly larger with the pulse period varying in the range of 2.5–6.0 s after considering the heating effect of lead core, which

can be visually observed from Figures 7B, 8B. Furthermore, the relative energy variations (REVs) calculated by Eq. 7 are illustrated in Figure 9.



$$REV = \frac{E_{FEM2} - E_{FEM1}}{E_{FEM1}} \times 100\% \quad (7)$$

where  $E_{FEM1}$  and  $E_{FEM2}$  are the corresponding energies determined by Eqs 3–6 in accordance with the numerical results based on FEMs 1 and 2.

Note that the relative variation range shown in Figure 9 covers –20%– to 20% for the input energies of original waves, while for the input energies of extracted pulses, the variation range is –10% to 140%. However, the wide variation range corresponding to extracted pulses should be attributed to the low calculated input

energies. For instance, the input energies to the whole bridge are 127,595 kJ and 126,050 kJ under the attack of the original wave of TCU052 ( $T_p = 8.4$  s), respectively, and the relative variation according to Eq. 7 is –1.2%. While the corresponding values are 800 kJ and 1759 kJ when subjected to the extracted pulse of TCU052, and the relative variation according to Eq. 7 is 119.9%.

#### 4.3.1.2 Absorbed energies of bearings

The ratio of absorbed energies of all the bearings under the attack of extracted pulses and original waves, i.e., the  $E_{ABP}/E_{ABO}$  ratio,



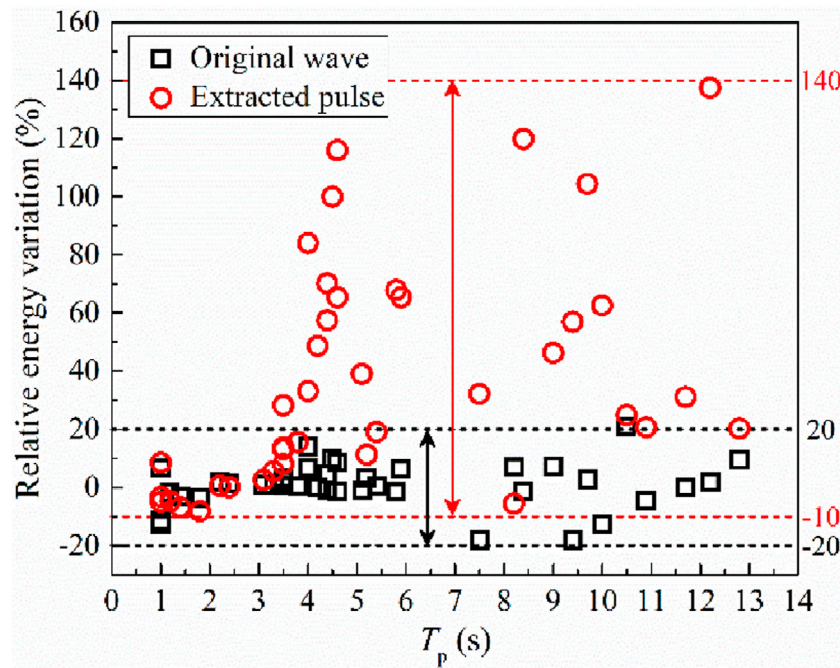


FIGURE 9 Relative variation of input energies to the whole isolated bridge considering the heating effect of lead core.

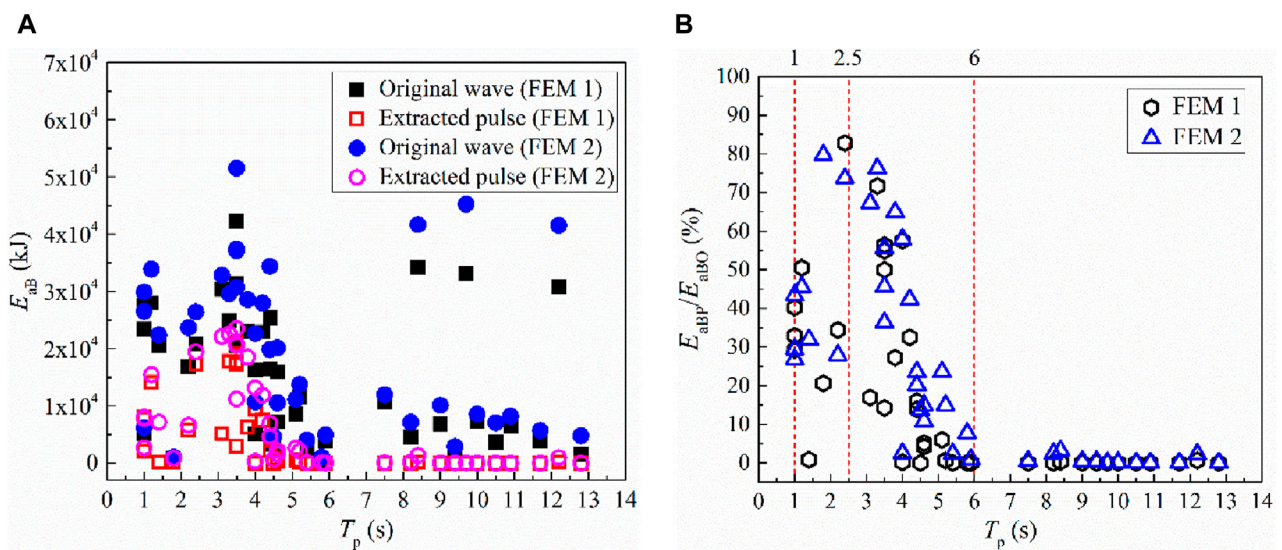


FIGURE 10 Absorbed energies of all the bearings. (A) Original waves vs. extracted pulses, (B) The  $E_{abP}/E_{abO}$  ratio.

affected by the pulse period is displayed in Figure 10. When the heating effect of lead core is considered during nonlinear dynamic time history analyses, both the absorbed energies of all the bearings under the original waves and extracted pulses increase, and the increased amplitude is much larger under extracted pulses.

Table 4 summarizes the subdivided relative energy variation for counting the concentrated range. The energy variations less than 50% account for 85.0% for the adopted bridge attacked by the

original waves. However, the proportion that the variation ranges of absorbed energies of all the bearings exceeding 100% reach 67.5% for the adopted bridge subjected to extracted pulses.

#### 4.3.1.3 Absorbed energies of piers

Figure 11 displays the absorbed energies of all the piers ( $E_{aP}$ ), which trend to decrease when the heating effect of lead core is considered for the isolated bridge, whether excited by the original

TABLE 4 Change of absorbed energies of all the bearings after considering the lead core heating.

Variation range (%)	Original waves			Extracted pulses		
	Count	Proportion (%)	Summation (%)	Count	Proportion (%)	Summation (%)
0~25	17	42.5	42.5	8	20.0	20.0
25%~50	17	42.5	85.0	3	7.5	27.5
50%~100	3	7.5	92.5	2	5.0	32.5
>100	3	7.5	100	27	67.5	100

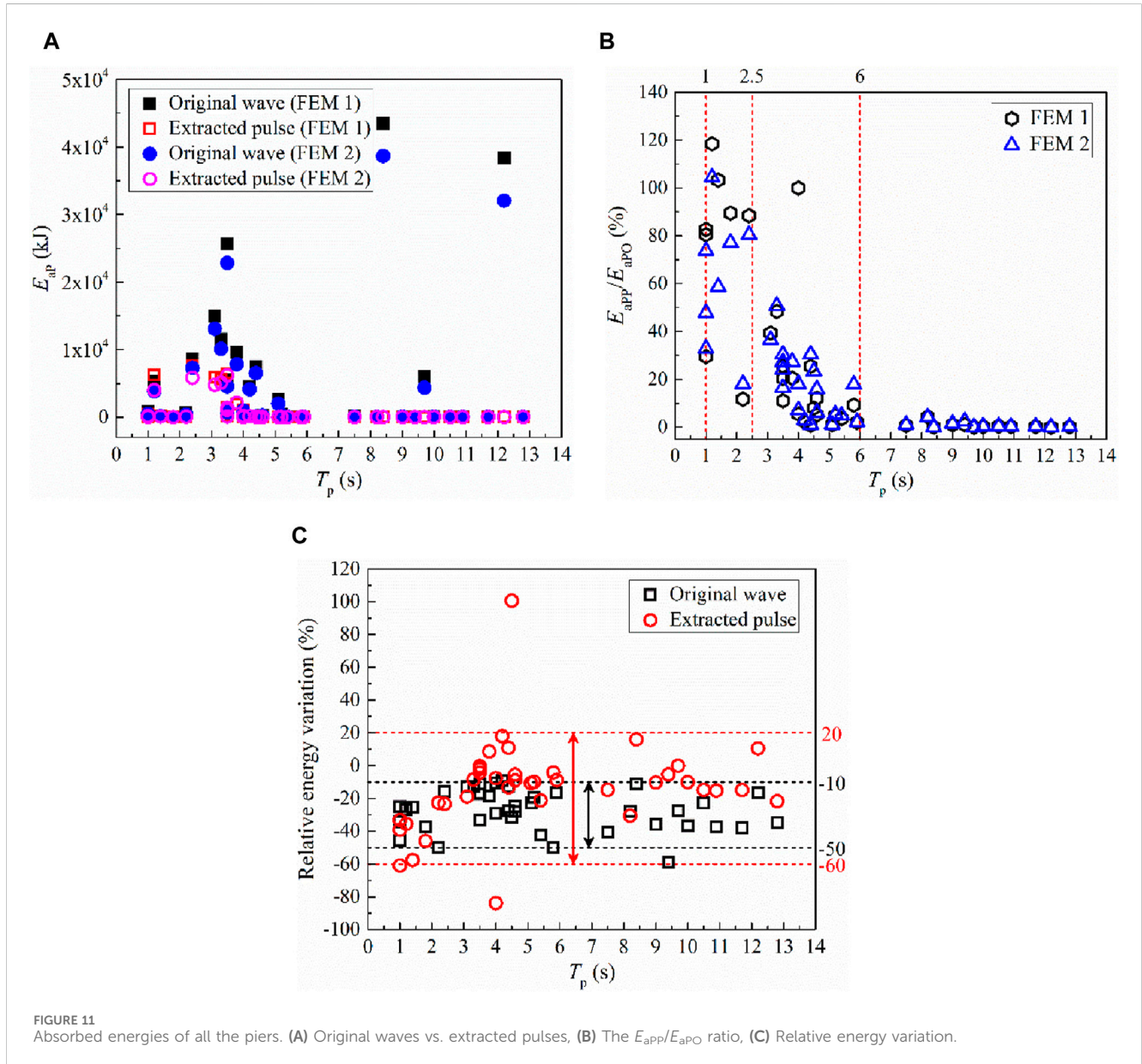


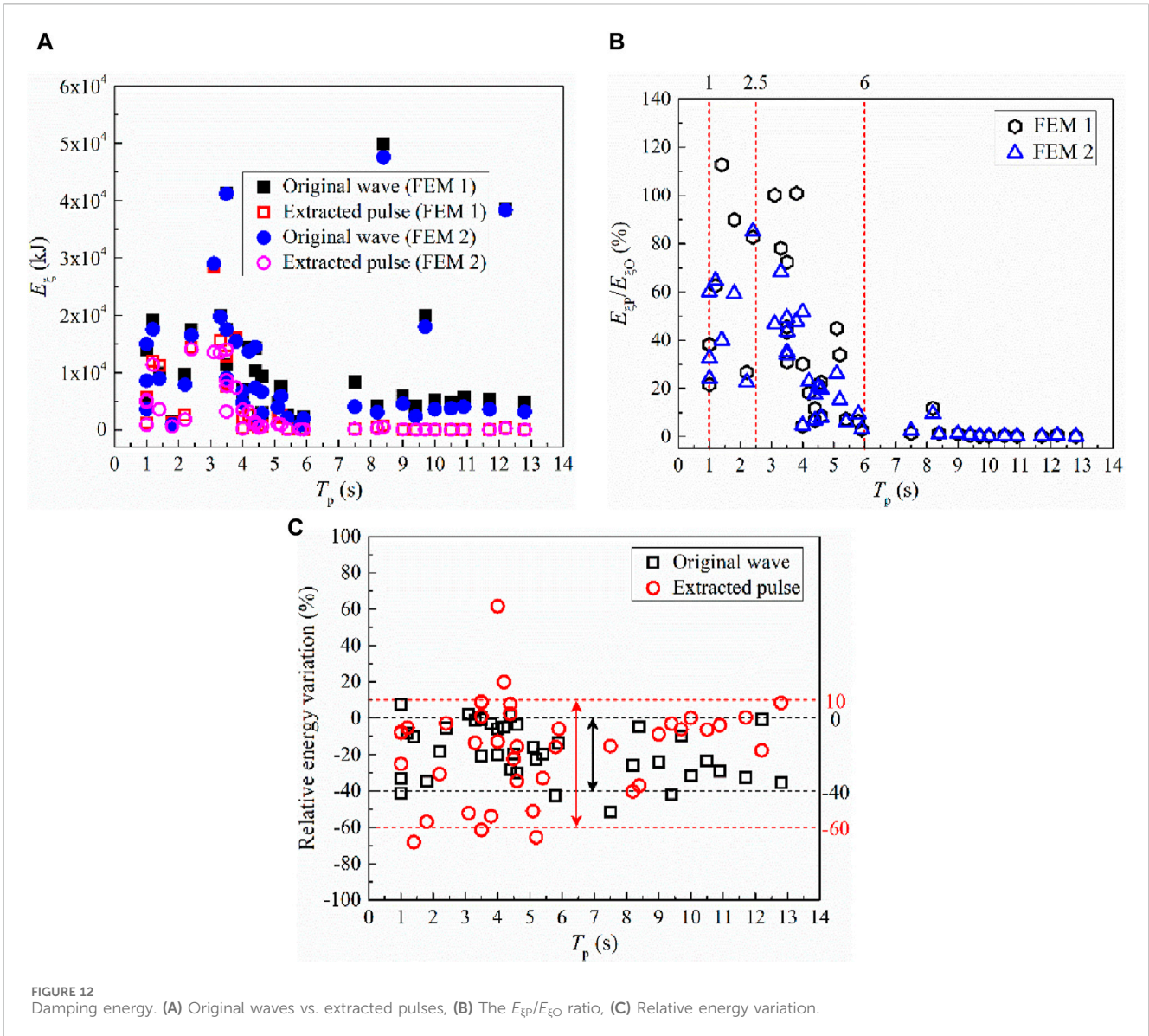
FIGURE 11 Absorbed energies of all the piers. (A) Original waves vs. extracted pulses, (B) The  $E_{app}/E_{apo}$  ratio, (C) Relative energy variation.

waves or the extracted pulses. Meanwhile, the extracted pulses are easy to cause a wider relative variation of  $E_{ap}$ , and the variation ranges are about  $-60\%$ – $20\%$ , as displayed in Figure 11C.

In addition, no matter the heating effect of lead core is considered or not, the absorbed energies of all the piers obtained

based on the excitations of extracted pulses ( $E_{app}$ ) are larger than that of original waves ( $E_{apo}$ ) when the pulse period approximately equals to 1.0 s, which may be caused by the resonance since the first-order period of the isolated bridge is 1.09 s. Subsequently, the  $E_{app}/E_{apo}$  ratio varies from 15% to 90% when the pulse period changes in





the range of 1.0–2.5 s, and gradually decreases as the pulse period increases to 6.0 s. Also, the absorbed energies of all the piers under the excitations of extracted pulses are very close to zero since the pulse period exceeds 6.0 s.

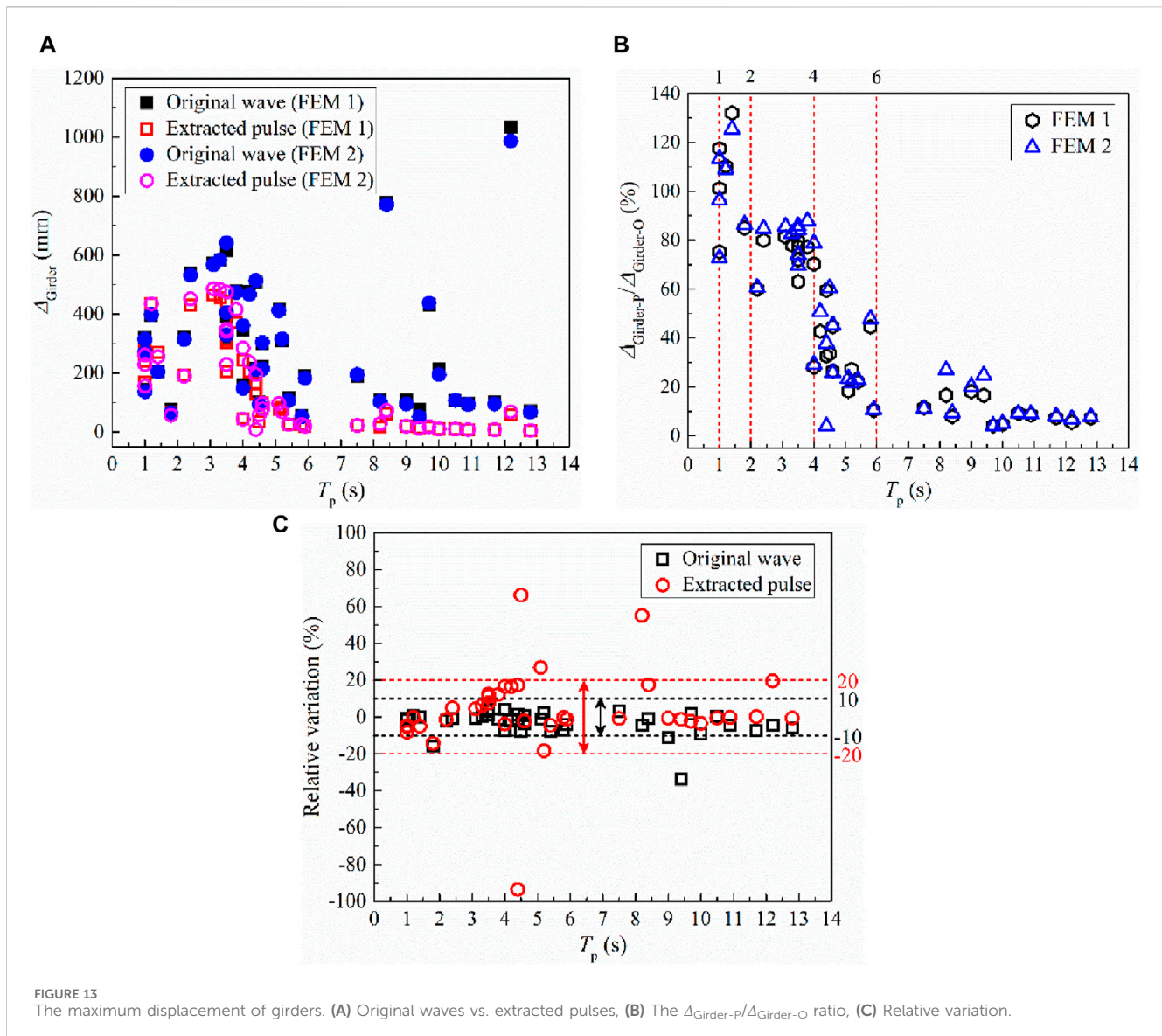
#### 4.3.1.4 Damping energies

The calculated damping energies are shown in Figure 12 for the adopted isolated bridge subjected to different kinds of seismic loadings. Generally, the ratio of damping energies excited by the extracted pulses ( $E_{dp}$ ) and original waves ( $E_{E0}$ ) increases first and then decreases until zero, and the critical values of pulse period are 1.0, 2.5, and 6.0 s. Besides, the damping energies excited by the extracted pulses are even larger than that obtained by the original waves when the heating effect of lead core is ignored. Moreover, based on the results shown in Figures 12A, C, the damping energies tend to decrease when the heating effect of lead core is considered, and the variation range is wider for the isolated bridge subjected to extracted pulses.

### 4.3.2 Deformation-based seismic responses

#### 4.3.2.1 The maximum displacement of girders

The maximum displacement of girders is slightly magnified when considering the lead core heating of LRBs, as can be observed in Figures 13A, C. When the adopted isolated bridge is excited by the extracted pulses and the original waves, the ratio of the corresponding maximum displacements of girders ( $\Delta_{GirderP}/\Delta_{GirderO}$ ) generally presents a trend of first increasing and then decreasing with the increase of pulse period, whether the lead core heating of LRBs is taken into account. As shown in Figure 13B, most of the ratios exceeds 100% when the pulse period is close to 1.09 s, i.e., the first-order period of the isolated bridge. Meanwhile, the ratios obtained based on FEM 1 are generally larger than that obtained based on FEM 2 in the condition that the pulse period is shorter than 1.5 s, while the opposite phenomenon can be observed after that.



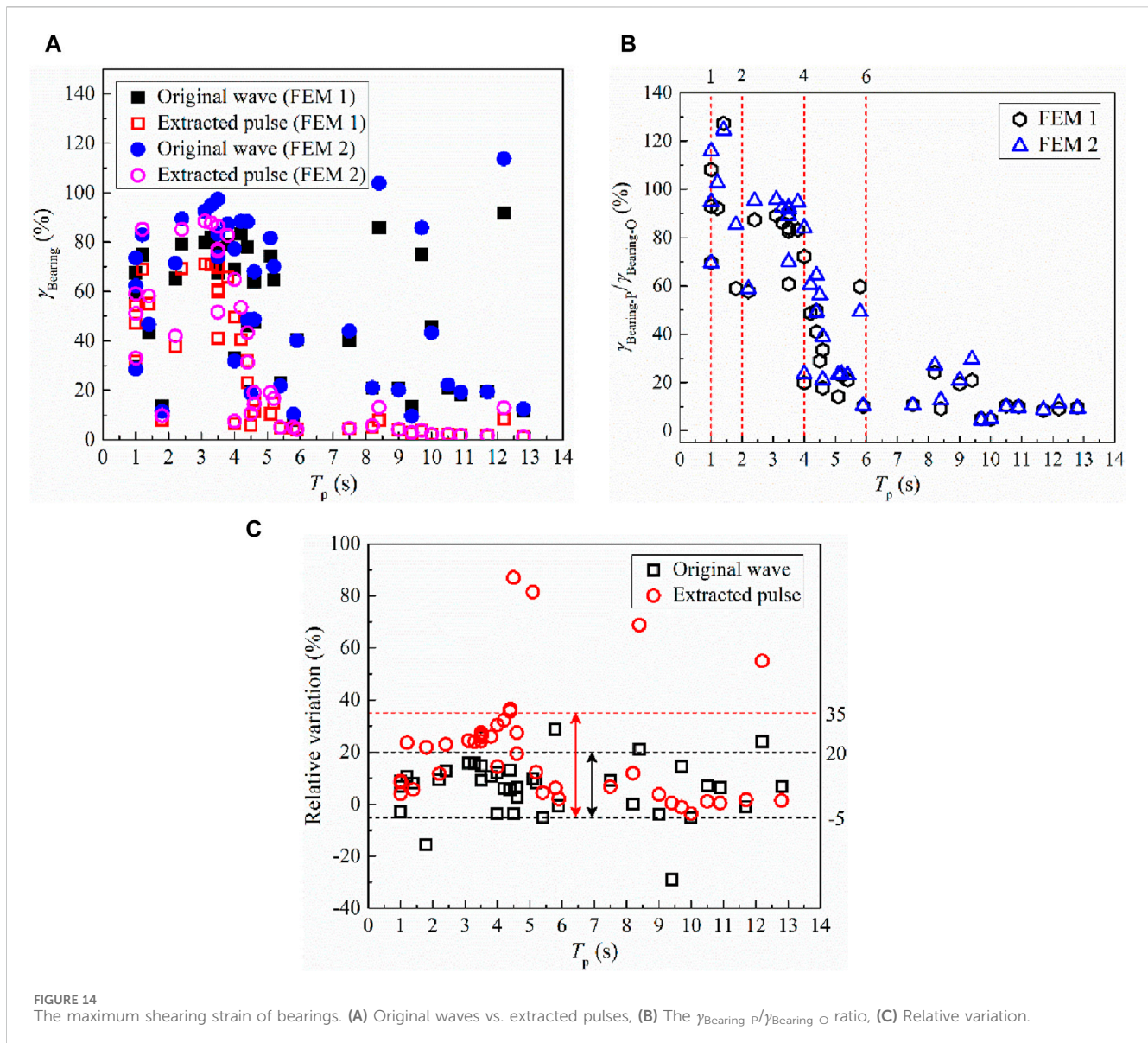
#### 4.3.2.2 The maximum shearing strain of bearings

As the ratio of the horizontal shearing deformation and the total thickness of rubber layer, the shearing strain is an effective indicator to describe the seismic response of bearings, as displayed in Figure 14. It is obvious that the maximum shearing strain of bearings will be magnified when the lead core heating of LRBs is considered, and this trend can be both observed from the conditions that the isolated bridge under the excitations of original waves and extracted pulses. Note that the relative variations are larger when subjected to the extracted pulses, as shown in Figure 14C. In addition, this above magnification is unrelated to the pulse period. As can be seen from Figures 14A, B, the maximum shearing strains of bearings obtained based on the input of extracted pulses are less than that of original waves, especially when the pulse period is larger than 6.0 s. The inverse pattern can be found when the pulse period changes in the range of 1.0–1.5 s.

#### 4.3.2.3 The maximum drift ratio of piers

The drift ratio of pier, which can be calculated by dividing the tip lateral displacement by the pier height, is adopted and compared. Figure 15 illustrates the effects of lead core heating of LRBs on the maximum drift ratios of bridge piers when subjected to the original waves and extracted pulses. As can be seen from Figures 15A, C, the maximum drift ratio of piers decrease slightly when considering the effect of lead core heating of LRBs. Besides, no matter the heating effect of lead core is considered, the maximum drift ratio obtained by extracted pulses will be larger than that by original waves when the pulse period is close to 1.09 s (i.e., the first-order period of the isolated bridge). Then, the opposite trend can be observed, and the ratio of the maximum drifts obtained by extracted pulses and original waves decreases sharply with the increase of the pulse period. When the pulse period is larger than 6.0 s, the ratio is less than 20%, as can be seen in Figure 15B.





Moreover, previous studies (Li et al., 2018; Cheng et al., 2021b) usually divide the damage states of bridge piers into several different levels, i.e., no damage, slight damage, moderate damage, severe damage, and collapse, and the corresponding threshold values of drift ratio are 0.7%, 1.5%, 2.5%, and 5.0%, respectively (Dutta, 1999). As can be seen from Figure 15A, it can be inferred that the seismic damage of bridge piers may be markedly underestimated by utilizing the extracted pulses.

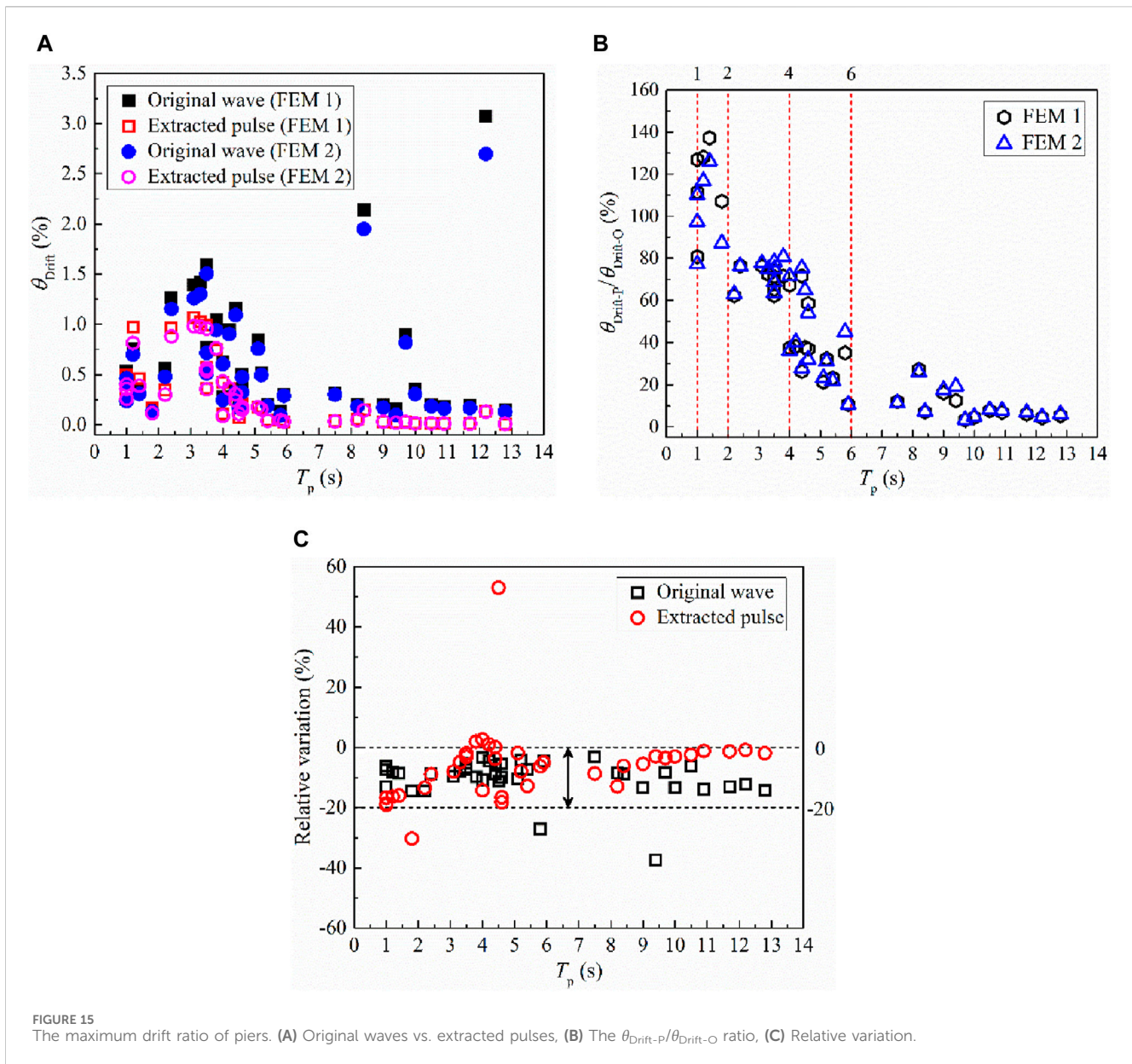
## 5 Conclusion

This study presents a systematic numerical investigation on the seismic responses of isolated bridges under original records of near-fault ground motions and the corresponding extracted pulses. A typical isolated continuous girder bridge was adopted, and two sets of finite element models considering and ignoring the effect of lead core heating of LRBs were established based on the OpenSees

platform. The seismic behaviors of the isolated bridge were evaluated by inputting the original waves and the extracted pulses. Based on the nonlinear dynamic time history analyses, both the energy-based and deformation-based seismic responses were captured and compared in detail. The main conclusions are summarized as below:

- (1) The lead core heating of the LRBs mainly affects the seismic responses of bearings and piers, including the absorbed energies and the maximum shearing strain of bearings, the absorbed energies and maximum drift ratio of piers. Considering the heating effect of lead core will enhance the seismic responses of bearings and decrease the seismic responses of piers, as well as the damping energies, which are consistent for the isolated bridge subjected to the original waves and the corresponding extracted pulses. Besides, the lead core heating of the LRBs will be magnified for the seismic response of isolated bridges subjected to the extracted pulses.





- (2) The ratios of the seismic responses (i.e., the absorbed energy of bearings  $E_{aB}$ , the absorbed energy of piers  $E_{aP}$ , the damping energy  $E_{\xi}$ , the maximum displacement of girders  $\Delta_{\text{Girder}}$ , the maximum shearing strain of bearings  $\gamma_{\text{Bearing}}$ , and the maximum drift ratio of piers  $\theta_{\text{Drift}}$ ) obtained by extracted pulses and original waves generally increase first and then, decrease when the pulse period increases, and finally approach to zero when the pulse period is larger than 6.0 s. Besides, these ratios reach the maximum when the pulse period is about 1.0–2.5 s.
- (3) Compared with the input of whole records of near-fault ground motions, the accuracy of the seismic evaluation based on the extracted pulses strongly depends on the precondition that the pulse period is close to the fundamental period of the isolated bridge. In addition, isolated bridges respond with multiple vibration modes coupled when subjected to seismic excitations.

Hence, inputting the extracted pulses for predicting the in-elastic seismic response of isolated bridges locating at near-fault region is not an adequate replacement for those original waves of near-fault ground motions.

### Data availability statement

The raw data supporting the conclusions of this article will be made available by the authors, without undue reservation.

### Author contributions

Y-XH: Conceptualization, Funding acquisition, Methodology, Supervision, Writing–review and editing. JW: Formal Analysis,

Investigation, Software, Visualization, Writing—original draft. J-LL: Formal Analysis, Investigation, Methodology, Validation, Writing—review and editing. T-TX: Writing—review and editing, Supervision, Validation.

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## Conflict of interest

Authors Y-XH, J-LL were employed by Ningxia Communications Construction Co., Ltd. Author JW was employed by Ningxia Haiping Expressway Management Co., Ltd.

The remaining author declares that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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