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University of Michigan, United States Nithin Sivadas, National Aeronautics and Space Administration, United States

*CORRESPONDENCE Fatemeh Bagheri, fxb1495@mavs.uta.edu

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Solar wind magnetosonic mach number as a control variable for energy dissipation during magnetic storms

Fatemeh Bagheri* and Ramon E. Lopez

Physics Department, University of Texas at Arlington, Arlington, TX, United States

During the main phase of many magnetic storms the solar wind Mach number is low and IMF magnitude is large. Under these conditions, the ionospheric potential saturates, and it becomes relatively insensitive to further increases in the IMF magnitude. On the other hand, the dayside merging rate and the potential become sensitive to the solar wind density. This should result in a correlation between the intensity of the auroral electrojets and the solar wind density. In this study we provide a sample of 314 moderate to strong storms and investigate the correlation between Dst index and the energy dissipated in the ionosphere. We show that for lower Mach numbers, this correlation decreases. We also show that the ionospheric indices of the storms with the lower Mach number are less correlated to the geoeffectiveness of the solar wind during these storms.

KEYWORDS

dst index, force-balance model, geoeffectiveness, magnetic storms, mach number

Introduction

As discussed by Gonzalez et al. (1994), the main feature in the solar wind that is responsible for creating geomagnetic storms is an extended period of southward directed Interplanetary Magnetic field (IMF). During a geomagnetic storm, the ring current is strongly enhanced and causes a decrease in the strength of Earth's horizontal magnetic field which is measured by the Dst or the SYM-H index. The maximum of the magnitude of the Dst has been generally used to classify the intensity of the storms. The total energy in the ring current is related to the Dst index by using Dessler-Parker-Skopke relation (Dessler and Parker, 1959; Sckopke, 1966):

$$\frac{Dst^*}{B_{\circ}} = \frac{2K}{3U_M} \ . \tag{1}$$

where B_{\circ} is the magnetic field at the surface of the Earth, U_M is the magnetic energy of the dipole field beyond the Earth's surface, and Dst* is the corrected Dst by considering the effects of the solar wind pressure and the quiet time ring current $Dst^* = Dst - 7.26\sqrt{P} + 11$ nT (O'Brien and McPherron, 2000).Dayside merging and nightside reconnection produce plasma flow in the ionosphere, which during a geomagnetic storm can besteady and intense. The flow means that there is an ionospheric electric field in Earth's reference





frame, and this electric field drives auroral electrojet currents that close the Birkeland currents driven by reconnection. These currents dissipate energy in the ionosphere through frictional heating that is generally referred to as Joule heating, although actual electromagnetic Joule heating should be calculated in the plasma frame (Vasyliu;nas and Song, 2005). In general, the highlatitude ionospheric energy dissipation rate can be classified into two categories: the energy dissipated by Joule heating and by auroral particle precipitation. The global Joule heating rate and auroral precipitation can be calculated based on doubling the hemispheric rate based on the AE and AL indices (Baumjohann and Kamide, 1984; Østgaard et al., 2002a,b) as,

$$U_{JH}(GW) = 0.64AE$$
 . (2)

$$U_{AP}(GW) = 2(4.4\sqrt{AL} - 7.6).$$
(3)

The physical process behind energy transfer to the magnetosphere-ionosphere system during a geomagnetic storm can be significantly different when the solar wind has a low Mach number (less than about 3.5) (Borovsky et al., 2008; Lavraud and Borovsky, 2008). The difference arises since under the condition of low Mach number the transpolar potential saturates (Lavraud and Borovsky, 2008; Lopez et al., 2010; Myllys et al., 2016), so that the potential becomes less dependent on the IMF Bz magnitude. The saturation effect



can be understood by considering the steady-state momentum equation,

$$\rho \frac{d\vec{V}}{dt} = \rho \vec{V} . \nabla \vec{V} = -\nabla P + \vec{J} \times \vec{B} .$$
(4)

The balance between the two forces, $\vec{J} \times \vec{B}$ and $-\nabla P$, explains the divergence of the magnetosheath flow, which regulates the geoeffective length in the solar wind and the rate of energy transfer to the system. The main point is that when the IMF is large and Mach number is low, the $\vec{J} \times \vec{B}$ term dominates the righthand side of the momentum equation in the magnetosheath. Increasing the IMF under these conditions increases the $\vec{J} \times \vec{B}$ and the divergence of the magnetosheath flow. Consequently, less flow can reach the merging line reducing the geoeffective length in the solar wind. Even though the flow carries more flux, the reduction in the flow that reaches the merging line results in the saturation of the ionosphere potential (Lopez et al., 2010). In this "saturation" regime the energy transfer is controlled by the density of the solar wind, since the divergence of the flow, and thus the geoeffective length, would be inversely proportional to the flow density (Shue and Kamide, 2001; Lopez et al., 2004).

However, the ring current injection rate does not saturate when the ionospheric potential saturates (Russell et al., 2001). Lopez et al. (2009) argued that the reconnection region moves closer to Earth for higher values of solar wind IMF so that the volume per unit magnetic flux in the closed field line region is less for larger negative Bz. Thus, the flux tubes coming from a reconnection region can penetrate deeper into the inner magnetosphere. In other words, the injection of particles into the inner magnetosphere produces more energization and the ring current energy content, hence Dst continues to be dependent on the magnitude of the southward IMF. Therefore, one can conclude that under the conditions of low Mach number solar wind, the ring current (and the Dst Index) will continue to respond to the changes of the magnitude of the southward component of the IMF. However, the potential of the polar cap and consequently the auroral electrojet intensity do not continue to respond strongly to IMF variations when the $\vec{J} \times \vec{B}$ term becomes dominant in regulating the reconnection potential. Therefore, using the Dst index can be a misleading indicator of the magnitude of energy dissipation in a geomagnetic storms, given that most of the energy dissipated in dissipated in the ionosphere (Borovsky, 2021).

In this paper, we provide a sample of 314 moderate to strong storms (Dst index ≤ -50 nT) and investigate the correlation between the Dst index and the energy dissipated in the polar ionosphere. We show that a lower Mach number leads to a weaker correlation between the ionospheric power and the Dst index. We also study the correlation between ionospheric indices and the ϵ parameter Akasofu (1981), and find that in the lower Mach number events, the ionospheric current is less correlated with ϵ . This result is consistent with the force-balance model and can be explained by the saturation of the ionospheric potential in the lower Mach number events. We begin by presenting the statistics of our sample of geomagnetic storms. This is followed by investigating the correlation between energy dissipation and the Dst* index in Introduction along with a study of the correlation of the SME index with the geoeffectiveness of solar wind in Introduction. We use the SME index instead of AE because it is significantly more representative of the auroral electrojets since it uses many more stations that AE over a broader range of latitude (Gjerloev, 2012)

Selection of storms

A starting point for the studies concerning energy dissipation and the roles of solar wind parameters during geomagnetic storms is to make a comprehensive sample of storms. Toward this goal, we use



FIGURE 4

right- The Pearson correlation coefficient between the ionospheric power and Dst_{min} for different ranges of averaged Mach number. The power and the Mach number are all the main phase-averaged values of the geomagnetic storms. *right*- The scatter plot of the main phased-averaged ionospheric power vs. Dst_{min}; different colors correspond to different values of the Mach number.



FIGURE 5

left- The Pearson correlation coefficient between the main phased-averaged ring current and Dst^{**}_{min} for different ranges of averaged Mach number. *right*- The scatter plot of the main phased-averaged ring current vs. Dst^{**}_{min}; different colors correspond to different values of the Mach number.

the Dst index provided by the World Data Center for Geomagnetism, Kyoto (http://wdc.kugi.kyoto-u.ac.jp/dstdir/). We define the storm onset by the beginning of a sustained and continuous decrease in the Dst index to at least -50 nT. Using a Python script to mark such events, we identified 314 magnetic storms with the Dst index \leq - 50 nT, that occurred between 2000 and 2020. For each storm, we calculated the Dst* index following O'Brien and McPherron (2000) using the OMNI solar wind data provided by CDAWeb (https://cdaweb.gsfc.nasa.gov/index.html/). The statistics of the Dst* values for the storms in our sample are provided through

Figures 1–3 and the list of the storms can be found in Supplementary Table S1.

Correlation between Dst* and the ionospheric power for different values of mach number

As discussed in Introduction, under the condition of low Mach number and high IMF, the ionospheric potential saturates.



However, the ring current injection rate does not saturate (Russell et al., 2001). Lopez et al. (2009). Thus under the condition of low Mach number solar wind, the energy in the ring current (as represented the Dst Index) and the energy dissipated in the ionosphere will become uncorrelated since the ionospheric potential and auroral electrojet intensity will not respond strongly to IMF variations while the ring current will. Therefore, the Dst index can be a misleading indicator of the strength of the geomagnetic storm and the amount of energy dissipated in the geospace system under these conditions.

To investigate the relationship between the energy dissipated in the polar ionosphere and the Dst index, we analyze our 314 magnetic storms with Dst* \leq -50 nT for the period between 2000 and 2020. Using the 1-min data from SuperMag for the SME index and the 1-hr solar wind data from OMNI, we estimate the energy dissipated in the ring current, the Joule heating, and the auroral particle precipitation for each storm. For this study, we only estimate the energy involved in the storm's main phase. To eliminate the influence of the lagtime in the study of the solar wind data and geomagnetic indices, we consider Dst rather than SYM-H as Dst is measured hourly while SYM-H is a 1-min data. This is important since the lagtime between solar wind data and the geomagnetic indices is about 20-35 min (Maggiolo et al., 2017), which has a significant effect when using 1-min data. In addition, O'Brien and McPherron (2000) used Dst rather than SYM-H, and to use those results, we need to use the same index that they used to derive the formula.

As discussed by Burton et al. (1975), the changes in the ring current energy content (hence the changes in the Dst*) is

comprised of two terms: the injection term and the proportional loss of the energetic particles,

$$\frac{dDst^*}{dt} = Q(t) - \frac{Dst^*}{\tau}$$
(5)

where τ is the decay time. Empirical studies have been done to determine the decay time (Prigancová and Feldstein, 1992; Valdivia et al., 1996; Mac-Mahon and Gonzalez, 1997; Lu et al., 1998; O'Brien and McPherron, 2000; Xu and Du, 2010). In this paper, we consider τ as described by O'Brien and McPherron (2000),

$$\tau(hrs) = 2.4 \exp \frac{9.74}{4.69 + VB_s} \tag{6}$$

where *V* is the solar wind speed, and B_s is the southward IMF component, assuming it is zero if B_z was northward. Thus, we estimate the ring current injection rate, the Joule heating, and the auroral precipitation from equations Eq 5 and Eqs. 2, 3, respectively.

We categorized the storms based on the average value of the magnetosonic Mach number in the main phase of each storm. For each category, we calculated the average of energy dissipated via the ring current injection rate, the Joule heating, and the auroral precipitation over the main phase of storms. Then, we find the Pearson correlation between the Dst* index and the ionospheric power (averaged over the main phase) and between the Dst* index and ring current power. Moreover, since each category a different number of storms (i.e. different sample size), we calculated the standard error for Pearson correlation using the Fisher's r-to-z transformation method which results in asymmetical confidence intervals. As illustrated in Figure 4left panel, a lower Mach number leads to a smaller correlation for the ionospheric power. But the ring current injection rate does not show this behavior Figure 5-left panel. In both cases, in the last category related to storms with the Mach number ≥ 6.5 , the standard error in Pearson correlation is relatively high. This is due to the fact that there are only 10 storms in this category therefore the correlation for this sample is not quit reliable compared to the other categories. In Figures 4, 5 right panels show the scatter plot of the main phase-averaged ionospheric power and ring current vs. $\text{DSt}^{\star}_{\text{min}}$ for all storms. Since the changes in the correlations in Figure 4 are within the error bars, we perform a Monte-Carlo simulation to generate the test statistic distribution for the null hypothesis of the non-positive trend in correlations of Figure 4. Excluding the last category, we can reject the null hypothesis with the confidence level of 95% (Supplementary Figure S1). Therefore, based on Figures 4, 5, we can conclude that for a smaller value of Mach number, the dependence of the amount of ionospheric Joule heating and auroral dissipation on storm size as defined by Dst* is less, so that for the lowest Mach number storms, the ionospheric dissipation is less dependent on Dst*. This is related to the saturation of the ionospheric potential. As the voltage imposed across the



ionosphere saturates, the ionospheric currents and the joule heating and the auroral particle precipitation also saturate. However, since Dst* does not saturate, it continues to respond to the magnitude of the southward IMF while the ionospheric power does not. Other factors besides the magnitude of the IMF control the saturation value of the potential and hence the amount of ionospheric dissipation. Also, the fraction of the total energy which dissipated in the ring current is less than the fraction that dissipated in the ionosphere. In Figure 6, the fraction of energy dissipated in the ring current as a function of the main phase-averaged Mach number is presented. As seen, this fraction is almost less than 1/3 of the total energy transferred to the magnetosphere-ionosphere system. Also, it increases for lower values of the Mach number since the ring current injection rate continues to increase with IMF Bz while the polar cap currents saturate.

Correlation between geoeffectiveness and ionospheric indices for different values of mach number

Geoeffectiveness refers to the efficiency of energy coupling from the solar wind into the magnetosphere. As discussed before, during storms with a low Mach number, the ionospheric potential saturates, so that further increases in IMF magnitude results in more magnetosheath flow diversion away from the merging line, decreasing the geoeffective length, and limiting the global merging rate. However, as mentioned earlier, the fact that the ring current injection rate does not saturate suggests that for the low Mach number storm events, geoeffectiveness should be less correlated to the ionospheric potential as compared to events with high Mach number. Again, the fundamental physical mechanism that produces the saturation effect is the shift to a magnetically dominated magnetosheath, where JxB is the largest force diverting the plasma flow. As the solar wind Mach number decreases, the geoeffective length becomes smaller as the JxB force adds to and eventually overtakes the -gradP force diverting the magnetosheath flow away from the dayside merging line. This produces a reduction in geoeffectiveness and a reduced correlation between the IMF and the power dissipated in the geospace system. To show this, in this section, we investigate the relationship between the ionospheric current and the geoeffectivness during magnetic storms.

To define the geoeffectiveness, we should have accurate measurements of the total amount of energy entering the magnetosphere from the solar wind. Although this is not a simple task, different parameters have been defined to estimate the energy input to the magnetosphere. One of them is the ϵ parameter which is defined in (SI units) as

$$\epsilon = \left(\frac{4\pi}{\mu_0}\right) \nu B^2 \sin^4\left(\theta/2\right) l_0^2 , \qquad (7)$$

where ν is the solar wind speed, *B* is the magnitude of the IMF, l_0 is a characteristic length scale representing the coupling area available for solar wind-magnetosphere interactions, usually approximated as $7R_E$, (Perreault and Akasofu, 1978), μ_0 is the permeability of free space, and θ is defined as

$$\tan^{-1}\left(|B_Y|/B_Z\right). \tag{8}$$

The ϵ parameter is a measure of the rectified Poynting flux in the solar wind times the magnetospheric collecting area. If



The best linear fit of the averaged-SME index and the averaged- ϵ for events with the Mach number: *left*- \leq 3.5 *right*- between 3.5-4.5.



the IMF was purely southward, the term $\sin^4 (\theta/2)$ reaches its maximum value, and therefore the energy coupling of solar wind and magnetosphere increases significantly. For IMF that is not purely southward, the term $(\sin^4 (\theta/2))$ reduces the energy input. In this representation, for northward IMF (as long as it is not purely northward) there is still some transfer of energy to the magnetosphere, but at a much reduced rate. The l_0^2 term in this equation is a constant length scale, corresponding essentially to the geoeffective length since it is the projection into the solar wind of the area over which the solar winf Poynting flux can enter the magnetosphere. Although the magnetopause area is known to vary with solar wind conditions (Mac-Mahon and Gonzalez, 1997), the value of l_0^2 is generally held constant during a storm. Therefore, the ϵ parameter does not exactly quantify the energy coupling of solar wind and the magnetosphere, but rather, it shows an *estimation* of the energy transmitted into the magnetosphere.

In addition to ϵ , there are some other parameters to quantify the energy coupling. For instance, one can parameterize solar wind energy input with νB_S , where ν is the solar wind velocity, and B_S is the southward component of the IMF (O'Brien and McPherron, 2000). Another one, defined by Bargatze et al. (1985) which is similar to ϵ in terms of having the sin⁴ (θ /2), but it is a more complex equation. Similarly, Newell et al. (2007) and Borovsky (2008) have published functions to estimate the



he best linear fit of the averaged-SME index and the averaged- ϵ for events with the Mach number > 6.5



magnitude of solar wind-magnetosphere coupling, but these functions share significant similarities with ϵ .

In this section, we discuss the relationship between ϵ , and the SME index during our set of storm events. We use 1-min data of

the SME index and 1-min data of ϵ both provided by SuperMag collaborators and can be found at http://supermag.jhuapl.edu/ indices/(Gjerloev, 2012). For the first step of studying 314 storms that we have in our sample, we calculate the best linear fit for the SME index as a function of ϵ during the main phase of each storm. Then, similar to the previous section, we categorized the storms based on the average value of the magnetosonic Mach number in the main phase of these linear fits between both data sets. As illustrated in figure Figure 7, as the averaged Mach number increases, the average of the slopes also increases.

Based on the Monte-Carlo simulation, the probability of having a positive trend in Figure 7 is 0.8 (Supplementary Figure S2). Although the trend is visible in Figure 7, but given the values of the slopes, there is not a significant change in the average of slopes for the storms with the Mach number \leq 3.5 and with those which has the Mach number between 3.5-4.5. Therefore, the other way to see such a trend is by using the averaged SME index. For each storm, we calculate the average value of the SME index and ϵ during the main phase. Then, similar to the previous sections, for each category of storms (based on the average value of the Mach number), we calculate the Pearson correlation of the averaged-SME index and the averaged-e. Figures 8-10 shows the linear relationship between $\langle SME \rangle$ and $\langle \epsilon \rangle$. As also illustrated in figure Figure 11, for the higher Mach number, the correlation coefficient is greater. The error bar in this plot is the standard error for Pearson correlation using Fisher's r-to-z transformation method. Again, similar to the previous sections, we perform a Monte Carlo simulation to generate the test statistic distribution for the null hypothesis of the nonpositive trend in correlations of Figure 11. Based on our simulation, we can reject the null hypothesis of a nonpositive trend at 99% confidence level (Supplementary Figure S3). This result is consistent with the theory of force-balance. As the Mach number decreases, the ionospheric potential, which controls the ionospheric current for a given conductance, becomes less correlated with the magnitude of the southward IMF, which controls the value of epsilon. Thus, the ionospheric current and epsilon are less correlated as seen in Figure 11. In other words, the ionospheric potential dependency on $\langle \epsilon \rangle$ is smaller as seen in Figure 7.

Conclusion

As discussed in the Introduction, the role of the force balance in the magnetosheath is essential to the understanding of the physics of energy transfer to the magnetosphere-ionosphere system during geomagnetic storms. Lower values of solar wind magnetosonic Mach number are responsible for the reduction of the reconnection line geoeffective length and the saturation of the polar cap potential. The current paradigm for classifying geomagnetic storms is based on the Dst index. However, this paradigm is missing the critical physical process: the ring current injection rate does not saturate while the transpolar potential saturates (Russell et al., 2001; Lopez et al., 2009). We show that for lower Mach numbers, the correlation between the ionospheric power and the Dst index decreases. Therefore, the Dst index is a weak predictor of the ionospheric power for storms with low Mach numbers, which tend to be the large storms when the prediction of ionospheric power dissipation would be particularly important for space weather.

Furthermore, we also show that the ionospheric indices, and hence the power dissipated in the ionosphere, and estimates of the power provided to the magnetosphere by the solar wind are less correlated for the lower Mach number. This result is consistent with the force-balance model since in the saturation regime, by increasing the solar wind energy input, the ionospheric potential remains the same, and the energy dissipates in the ring current and causes the enhancement of the ring current injection rate.

The uncertainty in data can affect the correlation coefficients reported in this paper. Regression bias may exist in this study's statistics as discussed by sivadasregression. However, the prior assumption in this paper is that the data used in this paper are reliable. Moreover we are averaging over the entire main phase of the storm, and issues like errors in the propagation time of the solar wind data from L1 to Earth should not produce any significant systematic error. Therefore we have confidence in the calculations presented.

One might argue that since these events are magnetic storms in which ionospheric outflow and plasmaspheric plumes are commonly produced, that mass loading of the dayside could reduced the merging rate and account for some or even most of our results. The question of whether local conditions can significantly affect the global integrated merging rate has been the topic of considerable discussion. The two basic positions have been forward by Borovsky and Birn (2014), who argued for local control of the total merging rate, and Lopez (2016), who argued for the dominance of global control based on the force-balance model. However, recent theoretical (Dorelli, 2019) and observational (Zou et al., 2021) evidence strongly favor the global control argument, which is based on the force-balance model and which is consistent with the results represented here.

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Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material further inquiries can be directed to the corresponding author.

Author contributions

FB did this research as a Ph.D. student under the supervision of RL. All authors contributed to manuscript revision, read, and approved the submitted version.

Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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Supplementary material

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fspas.2022. 960535/full#supplementary-material

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