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Removability conditions for anisotropic parabolic equations in a computational validation

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The article investigates removability conditions for singularities of anisotropic parabolic equations and in particular for the anisotropic porous medium equation and it aims in the numerical validation of the analytical results. The preconditions on the strength of the anisotropy are analyzed, and the analytical estimates for the growth behavior of the solutions near the singularities are compared with the observed growth in numerical simulations. Despite classical estimates used in the proof, we find that the analytical estimates are surprisingly close to the numerically observed solution behavior.

KEYWORDS

parabolic differential equation, anisotropic porous medium equation, anisotropic fast diffusion equation, removable singularity, removability conditions, numerical validation

1 Introduction

In this article, we investigate singularities of solutions of anisotropic parabolic equations, and in particular the ones of the anisotropic porous medium equation. We focus on conditions for the removability of singularities for such solutions and compare analytically obtained removability results with observed solution behavior in numerical simulations.

For quasilinear elliptic equations, the problem can be formulated as follows. Let Ω be an open subset in \mathbb{R}^n . The function u is defined in $\Omega \setminus \{x_0\}$ and satisfied some quasilinear partial differential equation in $\Omega \setminus \{x_0\}$, i. e., except in the point x_0 where a singularity might lie. The removability problem consists of extending the function u to the entire domain Ω so that the extended function \tilde{u} satisfies the same quasilinear equation in Ω , and in finding conditions that guarantee the existence of the extension. If the extension of u to \tilde{u} is possible, we will say that the singularity in x_0 is removable.

Additionally, while dealing with equations of parabolic type like done in this article, singular initial data arise in a natural way. The problem statement remains the same, but it can be formulated in different ways: either as the question of a removable singularity or as the non-existence of a solution with a singularity.

The qualitative behavior of solutions to quasilinear elliptic and parabolic equations near the point singularity was investigated by many authors starting from the seminal paper of Serrin [1]. Further analysis of sufficient conditions for the removability of singularities of solutions has been made by many authors for different classes of nonlinear elliptic and parabolic equations, cf. [2] and the references therein. As for anisotropic elliptic and parabolic equations, their active research began recently. There are many scientists who presented fundamental results in the qualitative theory for such equations. Feo, Vázquez, Volzone, Song, Jian deal with questions about the existence of a fundamental solution [3], self-similar fundamental solutions [4, 5], existence and uniqueness of a

bounded and continuous solution for equations with singular advections and absorptions [6, 7]. Skrypnik and his co-authors obtained removability results for the anisotropic versions of the porous medium equation and for the fast diffusion equation [8], the *p*-Laplacian equation [9] and doubly nonlinear anisotropic parabolic equations [10], including equations with an absorption term [11-16], etc.

The paper is organized as follows. In Section 2, we introduce the statement of the singularity problem for anisotropic parabolic equations. In Section 3, we provide the history of the removability problem for isotropic and anisotropic equations. In Section 4, we present the analytical results on the growth behavior of solutions near the singularities, which are validated and visualized by hands of numerical simulations in Section 5. The paper finishes with a resume and an outlook.

2 Problem statement

We study non-negative solutions to the anisotropic parabolic equation

$$\frac{\partial u}{\partial t} - \sum_{i=1}^{n} \frac{\partial}{\partial x_i} \left(u^{m_i - 1} \frac{\partial u}{\partial x_i} \right) = 0 \text{ with } (x, t) \in \Omega_T, \qquad (1)$$

where $\Omega_T = \Omega \times (0, T)$, Ω is a bounded open set in \mathbb{R}^n with $n \ge 2$, which without loss of generality, contains the origin, i. e., $x_0 = 0 \in \Omega$, and where *T* with $0 < T < +\infty$ is a finite time. The initial condition is

$$u(x,0) = 0 \text{ for all } x \in \Omega \setminus \{0\},$$
(2)

and allows a concentrated essential weight in the origin.

Eq. (1) can be seen as a diffusion equation for the concentration u = u(t, x), and the diffusion parameters depend on the concentration u as well as on the direction in \mathbb{R}^n via the different exponents $m_i - 1$. The exponents m_i , which are not necessarily integers, have a strong physical background. In fact, they come from fluid dynamics in anisotropic media. If the conductivities of the media are different in different directions, the exponents m_i are different from each others [17].

In the special case $m_1 = m_2 = ...m_n = 1$, Eq. (1) reduces to the isotropic heat equation. But for $m_i > 1$, i = 1, ..., n, the diffusion parameters tend to zero with decreasing concentrations. Thus, the diffusion process degenerates near zero concentrations. In this case, Eq. (1) is degenerate parabolic, and it is called an anisotropic porous medium equation [18]. On the other hand, for $m_i < 1$, i = 1, ..., n, the equation is singular parabolic and called anisotropic fast diffusion equation [19].

As we see, the anisotropy of Eq. (1) is realized via the exponents $m_i - 1$ in the concentration-dependent diffusion parameters u^{m_i-1} . The case $m_i > 1$ means that the diffusion strength increases with a growing positive concentration u, where $m_i < 1$ leads to a diffusion strength that increases up to infinity for decreasing u tending to 0. Therefore for small u and $m_i < 1$, we expect the faster leveling behavior the smaller u is in x_i -direction.

Here, we consider the case when anisotropy exponents are restricted by two conditions, namely first, a lower bound

$$\min_{1\le i\le n}m_i>1-\frac{2}{n},\tag{3}$$

and next, an upper bound depending on the mean of the exponents

$$\max_{1 \le i \le n} m_i < m + \frac{2}{n} \text{ where } m = \frac{1}{n} \sum_{i=1}^n m_i.$$
 (4)

As a first idea, conditions (3) and (4) mean that the exponents m_i might be commonly large but might not differ too much or be too small, comp. Section 4.2, where the admissible anisotropies are investigated in more detail. These conditions cover also the case where one part of the exponents m_i is greater than 1 and the other part m_i is less than 1.

Remark 1. In all known related publications, the cases of degenerate $(m_i > 1, i = 1, ..., n)$ and singular $(m_i < 1, i = 1, ..., n)$ parabolic equations were considered independently from each other even in the isotropic case, i.e. for $m_1 = m_2 = ... = m_n = m$. The used methods for proving the results depend on either the degenerate or singular character of equations.

Remark 2. Without loss of generality, we will assume that the point $x_0 = 0 \in \mathbb{R}^n$ carries a singularity, otherwise we can make a change of variable by a simple translational shift.

Remark 3. Initial condition (2) can be written in the following way

$$u(x,0) = \delta(x), \qquad x \in \Omega.$$

In this case, it will be about the non-existence of solutions to the Cauchy problem with a singular initial condition, and not about the removability conditions.

Here, we are interested in solving the problem (1, 2) numerically and testing the analytical results from [8] which guarantee that the singularity at (0, 0) is removable.

3 History of the problem

The first theorem on removable singularities was obtained by Riemann. In his doctoral dissertation [1851, see Riemann [20]], he established the removability of an isolated singular point for a harmonic function of two real variables. In the general case, the necessary and sufficient condition of the removable singularity at the point x_0 for a harmonic function u in $\mathbb{R}^n \setminus \{x_0\}$ has the form

$$u(x) = o(\varepsilon(x - x_0)) \text{ as } x \to x_0.$$
(5)

Here

$$\varepsilon_n(x-x_0) = \begin{cases} \frac{|x-x_0|^{2-n}}{(2-n)\sigma_n}, & n > 2, \quad \sigma_n - \text{surface areas of} \\ & \text{the unit sphere in } R^n \\ \frac{1}{2\pi} \ln \frac{1}{|x-x_0|}, & n = 2 \end{cases}$$

(6)

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is the fundamental solution of Laplace's equation that exhibits the solution with the "minimal" singularity at $x = x_0$. It's easy to see how the condition (Equation 5) works if we expand the harmonic function into a series of spherical harmonics under the following form

$$u(x) = \tilde{u}(r,\sigma) = \sum_{i=0}^{\infty} \varepsilon^{(i)}(r)\psi_i(\sigma) + \sum_{i=0}^{\infty} r^i \tilde{\psi}_i(\sigma), \qquad (7)$$

where r, σ are the spherical coordinates in $\mathbb{R}^n \setminus \{x_0\}$, and $\psi_i(\sigma)$, $\tilde{\psi}_i(\sigma)$ spherical harmonics of degree *n*. If we assert that the condition (Equation 5) is satisfied, i.e., $\tilde{u}(r, \sigma) = o(\varepsilon(r))$ as $r \to 0$, then the first term on the right side in Equation (7) is missing. It means that *u* is a harmonic function in the whole \mathbb{R}^n . So this condition shows that there is no solution of Laplace's equation which is singular at the point x_0 and satisfies condition (Equation 5). It is obvious that the question of the removability of the singularity is conditioned by the growth of *u* near this point. If for example $\tilde{u}(r,\sigma) = \mathcal{O}(\varepsilon^b(r))$ as $r \to 0$, for some nonnegative integer *b*, then *u* admits an asymptotic expansion of the following form

$$u(x) = \tilde{u}(r,\sigma) = \sum_{i=0}^{b} \varepsilon^{(i)}(r)\psi_i(\sigma) + \sum_{i=0}^{\infty} r^i \tilde{\psi}_i(\sigma),$$

and stays harmonic in $\mathbb{R}^n \setminus \{x_0\}$. Therefore, a crucial step in studying the singularity problem is the knowledge of an a priori estimate of *u* near the singularity.

Then for a long time, the only study of singularity problems dealt with linear equations and with radial solutions of Laplace's equation with nonlinear sources or absorptions. In fact, the first breakthrough is due to Serrin [1] who obtained the first general results on quasilinear equations. His precise condition on removability of singularity for nonnegative solutions of the p-Laplacian equation

$$\sum_{i=1}^{n} \frac{\partial}{\partial x_i} \left(|\nabla u|^{p-2} \frac{\partial u}{\partial x_i} \right) = 0 \text{ for } x \in \Omega \setminus \{x_0\},$$

reduces to

$$u(x) = o(\varepsilon(x - x_0))$$
 as $x \to x_0$ for $p \le n$,

where $\varepsilon(x - x_0)$ is the fundamental solution of the *p*-Laplacian equation and is described by the formula

$$\varepsilon(x - x_0) = \begin{cases} |x - x_0|^{-\frac{n-p}{p-1}}, & \text{for } p < n, \\ \ln \frac{1}{|x - x_0|}, & \text{for } p = n. \end{cases}$$
(8)

Around 1980, the sharp development of the theory of nonlinear partial differential equations allowed another breakthrough in the study of nonradial singular solutions of Laplace's equations with nonlinear sources and absorptions. This was initiated by Gidas and Spruck [21], Lions [22] and Veron [23]. After this first period, many articles have been published taking into account the different aspects of the singularity problem for the above-mentioned equations and also for parabolic equations. We refer to the monograph by Veron [2] for an account of these results.

During the last decade, there have been growing interest and substantial developments in the qualitative theory of second-order anisotropic elliptic and parabolic equations e.g., [5, 24-30], in particular results for anisotropic porous medium equation can be found in Ciani and Henriques [31], Feo et al. [4], Henriques [32], Song and Jian [3], Song [6], and Song [7]. The study of these equations is complicated by the fact that a general qualitative theory for them has not been constructed, in addition, the explicit form of the fundamental solution is unknown in most of the cases. Therefore, the problem arises of obtaining precise conditions for the removability of the singularities for anisotropic elliptic and parabolic equations. Due to the fact that it is not possible to construct the fundamental solution of Equation (1) in an explicit form similar to Equations 6, 8, until recently it was not clear how to formulate the precise or at least sufficient condition for the removability of the singularity for the solution of this equation. This question was successfully solved in Namlyeyeva et al. [10], where is proved that the singularity at the point (x_0, t_0) with $x_0 = 0 \in \mathbb{R}$ and $t_0 = 0$ for the solution of the equation

$$\frac{\partial u}{\partial t} - \sum_{i=1}^{n} \left(u^{(m_i-1)(p_i-1)} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right)_{x_i} = 0,$$

with $p_i \ge 2, m_i \ge 1$, and $i = 1, \dots, n$, (9)

is removable if the following condition holds

$$u(x,t) = o(z(x,t))$$
 as $(x,t) \to (x_0,0)$,

where is $z(x, t) = \left(\sum_{i=1}^{n} |x_i - x_i^0|^{\alpha_i} + t^{\beta}\right)^{-n}$, and the exponents are given by

$$\alpha_i = \frac{1}{p + n(p(m-d) - m_i(p_i - 1))}$$

and $\beta = \frac{1}{n(p(m-d) - 1) + p}$





with

$$m = \frac{1}{n} \sum_{i=1}^{n} m_i, \ p = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{p_i}, \ \text{and} \ d = \frac{1}{n} \sum_{i=1}^{n} \frac{m_i}{p_i}$$

The anisotropic doubly nonlinear parabolic (Equation 9) reduces to the anisotropic *p*-Laplacian evolution equation if $m_1 = m_2 = ... = m_n = 1$. Further for $p_1 = p_2 = ... = p_n = 2$, we obtain the degenerate case of Eq. (1). Other results on the removability of singularities for anisotropic equations concern special cases of Eq. (9) with absorption [11] and gradient absorption terms [12] and for anisotropic elliptic equations [9, 13–15]. But at this stage of the study, we are not interested in equations with additional terms.

4 Results and visualization

4.1 Removability result for anisotropic parabolic equation

Before presenting sufficient conditions for the removability of singularities, let us formulate the definition of a weak solution of the problem (Equation 1, 2), and let us define removable singularities.

Definition 1. We write $V_m(\Omega_T)$ for the class of functions $\varphi \in C(0, T, L^2(\Omega))$ with

$$\sum_{i=1}^n \iint_{\Omega_T} |\varphi|^{m_i-1} \left| \frac{\partial \varphi}{\partial x_i} \right|^2 \, \mathrm{d} x \mathrm{d} t < \infty.$$

Definition 2. A weak solution with a singularity at the point (0,0) of the problem (Equations 1, 2) is a function $u(x,t) \ge 0$ satisfying the inclusion $u\psi \in V_m(\Omega_T) \cap L^2(0, T, W^{1,2}(\Omega))$ and the integral identity

$$\int_{\Omega} u(x,\tau)\varphi\psi \,dx - \int_{0}^{\tau} \int_{\Omega} u \frac{\partial(\varphi\psi)}{\partial t} \,dxdt + \sum_{i=1}^{n} \int_{0}^{\tau} \int_{\Omega} u^{m_i - 1} u_{x_i} \frac{\partial(\varphi\psi)}{\partial x_i} \,dxdt = 0$$
(10)

for any $0 < \tau < T$, any test function $\varphi \in V_m(\Omega_T) \cap L^2(0, T, W_0^{1,2}(\Omega))$ and any $\psi \in C^1(\overline{\Omega}_T)$ vanishing in a neighborhood of (0, 0).

Definition 3. We say that the solution of the problem (Equations 1, 2) has a removable singularity at the point (0, 0) if the integral identity (Equation 10) holds for $\psi \equiv 1$.

According to Def. 3, the *u* is integrable over the neighborhood of the point (0, 0) supporting the singularity. Hence, the singularity cannot be too strong or not too widely opened, i.e. $u = O\left(\frac{1}{r^{\alpha}}\right)$ with restricted exponent α . Here *u* is formally L_1 in the combined space for *x* and *t*, and that means that a solution with singular initial values decreases fast enough for growing *t*.

Theorem 1. Assume that the conditions in Equations (3, 4) are fulfilled. Let *u* be a weak solution of the problem (1, 2) with a singularity at the point (0, 0). Then the singularity of the solution *u* is removable if

$$u(x,t) = o(v(x,t))$$
 as $(x,t) \to (0,0),$ (11)

where
$$v(x,t) = \left(\sum_{i=1}^{n} |x_i|^{k_i} + t^k\right)^{-n}$$
 with

$$k_i = \frac{1}{2 + n(m - m_i)} \text{ and } k = \frac{1}{n(m - 1) + 2}$$

The condition (Equation 11) can be rewritten in the following form

$$\lim_{(x,t)\to(0,0)}\frac{u(x,t)}{v(x,t)} = 0.$$
 (12)

It is natural to expect that v(x, t) determines the asymptotic behavior of the fundamental solution. We know about the existence of the fundamental solutions [3], and for anisotropic fast diffusion equation, the existence and uniqueness of the selfsimilar fundamental solutions [4]. Since the explicit form of the fundamental solution is unknown, we are dealing with a sufficient condition of the removability for Eq. (1), and not with a precise one.

4.2 Admissible anisotropies

The conditions (Equations 3, 4) restrict the possible exponents m_i , i = 1, ..., n from below and from above. Whereas (Equation 3) contains a constant restriction from below (Equation 4) rather restricts the deviation from the mean value *m* of the exponents.

In the two-dimensional case with n = 2, conditions (Equations 3, 4) read

$$m_i > 0$$
 and $m_i < m + 1$ for $i = 1, 2$.

Figure 1 illustrates the set of all admissible exponents in the case n = 2. We start with the inclined line $m_1 + m_2 = 2m$ with all pairs (m_1, m_2) with the same mean value m. Due to $m_i < m + 1$, each exponent may not deviate further than 1 from m, and we get a stripe, cf. thick line, and gray stripe in Figure 1.

A similar consideration provides the set of admissible exponents in the three-dimensional case with n = 3. Then, inequalities (Equations 3, 4) read

$$n_i > \frac{1}{3}$$
 and $m_i < m + \frac{2}{3}$ for $i = 1, 2, 3$.

The left plot in Figure 2 starts with the plane $m_1 + m_2 + m_3 = 3m$ containing all triples (m_1, m_2, m_3) with the same mean value. The marked dot gives the isotropic triple (m, m, m). The plane is restricted by the planes $m_i = m + \frac{2}{3}$, which are parallel to the axis-planes of the coordinate system. In the shown situation in Figure 2, left, the lower restriction is not present. If the lower restriction $m_i > \frac{1}{3}$ becomes active, we get a slightly more complicated admissible area, cf. the right plot in Figure 2.

The right plot in Figure 2 presents the three-dimensional set of admissible triples (m_1, m_2, m_3) . Additionally, the intersections which were already shown in the left plot, are drawn. These are the rotated triangle for $m = \frac{2}{3}$, a hexagon for m = 1, a two next triangles in gray for $m = \frac{5}{3}$ and $m = \frac{7}{3}$.

Larger $m > \frac{5}{3}$ with inactive condition (Equation 3) lead to triangles and the set of admissible exponent triples is a triangular prism around the diagonal of the positive part of \mathbb{R}^3 . In total, we see a prismatic beam with a triangle cross section and a diagonal



FIGURE 2

Left: Construction of all admissible triples (m_1, m_2, m_3) with m = 1. The hatched plane gives all triples with m = 1, and the gray triangle is the sub-area restricted by $m_i < m + \frac{2}{3}$, i = 1, 2, 3. **Right**: Set of admissible anisotropies in the three-dimensional case n = 3. The gray intersections show the admissible areas for $m = \frac{2}{3}$, m = 1, $m = \frac{5}{3}$ and $m = \frac{7}{3}$. Remark the restrictions $m_i > \frac{1}{3}$ for i = 1, 2, 3.



in the symmetry axis of the beam. This triangle beam is restricted for small exponents m_i by planes following condition (Equation 3). Analogous beams are found for higher dimensions n > 3, too.

Consequently, the analytical and numerical considerations presented in this article, are valid for moderate differences between the exponents m_i in Eq. (1). Otherwise, the mean value m itself, generating the non-linearity in Equation 1 is not limited.

5 Numerical validation

Here, we present the numerical solution of Eq. (1) with the initial condition (Equation 2). It is solved by finite

differences, and the singularity in the initial condition was replaced by a particular value conserving the integral. Of course, finite differences are not the ideal method to handle highly oscillating or highly changing values, and rather finite elements with their integrative aspect over each element would be appropriate.

But on the other hand, finite differences are a method which is not related to the removability condition in Eq. (10), which is an integral identity directly connected to the weak formulation of Eq. (1) and thus to finite elements. Therefore, we regard finite differences as a properly unbiased method. By the way, no qualitative difficulties occurred with the numerical solution in Matlab (as used here), Python, or Octave.



FIGURE 4

Numerical solution with increasing times, continuation, same $m_1 = 1.3$ and $m_2 = 0.6$. Left: Further smoothing for $t = 0.6 \cdot 10^{-3}$. Right: For $t = 0.9 \cdot 10^{-3}$, the initial values have been nearly completely leveled out.



Figures 3, 4 show the time evolution of the concentrated initial value in Eq. (2) for n = 2. After a small time, the expected leveling behavior together with an anisotropy close to the origin is observable.

Next, we test the limit behavior given in Equation 11 as a removability condition. We compare the numerical solution u = u(t, x) for certain times t > 0 with the estimate function v used in Eq. 12 to give an upper bound in the limit $x \rightarrow 0$ and $t \rightarrow 0$. Figure 5 shows the claimed small-obehavior of u, s. conditions (Equations 11, 12). Please remark that the comparison for t = 0 is not reasonable due to the vanishing initial values outside the origin. Although the small-o behavior of the estimate is numerically reproduced, the computed solution goes a little faster to 0 than the estimate. This coincides with the reformulation of the removability condition (Equation 12).

We observe that the quotient u/v of condition (Eq. 12) is indeed bounded and tends numerically to zero when (x, t) approaches the point (0, 0) carrying the singularity at the initial time. Furthermore, we see that the qualitative tendency observed in the numerical data u is well estimated by the analytical estimate v because the quotient approaches linearly zero in all directions.

Remark that no numerical artifacts are remarkable although the finite differences are a very rough numerical method. Together with the argument that the finite difference method is not biased as e. g. finite elements would be due to the condition in Eq. (10), which would make a non-removable singularity numerically not accessible at the same time, we rate the numerical simulation as a good validation and strong support of the power of the analytical estimate v in condition (Eq. 11).

6 Resume and outlook

We have shown that the removability conditions from [8] for the anisotropic porous medium equation and fast diffusion equation can be numerically reproduced and validated for the admissible anisotropies, whereat the conditions on feasible anisotropies allow not too large differences in the exponents m_i on the one hand but sufficiently multifaceted situation for modeling various physical situations.

Further research will focus on expanding the considerations of removability conditions to more general partial differential equations, e.g. anisotropic version of the evolution p-Laplacian equation. Another interesting question is whether some anisotropies with large differences between the exponents might lead to a comparable behavior of the solutions or whether some extenuated assertations about the growth and decay behavior of the solution can be found.

Data availability statement

The original contributions presented in the study are included in the article/supplementary material, further inquiries can be directed to the corresponding author.

Author contributions

MS: Conceptualization, Formal analysis, Writing - original draft, Writing - review & editing. DL: Conceptualization,

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