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Review of experimental investigations of wings in ground effect at low Reynolds numbers

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The ground effect-induced large lift increase and lift-induced drag reduction have long been recognized and utilized in the design and construction of wingin-ground effect (WIG) craft. Various wing planforms have been employed in WIG craft. In this study, the experimental investigations of rectangular wings and delta wings of reverse and regular configurations at low Reynolds numbers are reviewed. For rectangular wings, both chord-dominated and span-dominated ground effects on the aerodynamics, tip vortex, and lift-induced drag are reviewed. For reverse delta wings, in addition to the experimental measurements of the aerodynamics and tip vortex flow at different ground distances, passive flow control utilizing Gurney flap, cropping, and anhedral are reviewed. The impact of ground effect on delta wings is also discussed. Suggestions for future investigations applicable to each wing planform in-ground effect are provided.

KEYWORDS

lift, lift-induced drag, ground effect, reverse delta wing, aerodynamics

1 Introduction

The large lift augmentation and lift-induced drag reduction have long been recognized when an airplane is flying close to the ground, especially during landing and takeoff. The ground proximity also causes an unwanted extra lift or the so-called "floating" experienced by the pilots. The ground effect-induced aerodynamic benefits have also been exploited by large birds, such as albatross, in long-distance flight to conserve energy. The Wright brothers' maiden flight was in fact completely in ground effect. The ground effect-induced large lift increase and lift-induced drag decrease have also been utilized extensively in winged groundeffect vehicles (GEVs) or wing-in-ground effect (WIG) craft. The WIG craft flying just meters above the water surface with various wing planforms and configurations have been designed and constructed since the 1960s. Among them, the Russian Ekranoplans (started with the Caspian Sea Monster, followed by A-90 Orlyonok and, most recently, Chaika A-059) employing a pair of giant rectangular wings of a small aspect ratio have been constructed since the 1960s. Eight power augmented ram (PAR) turbojet engines together with large trailing-edge flaps are necessitated to overcome the huge "hump drag" during takeoff, which inevitably increase the weight and complexity of the Ekranoplan WIG system. Moreover, a large horizontal stabilizer or tail is also required to mitigate the ground proximity-produced longitudinal instability. Extensive reviews on the Ekranoplan-type WIG craft were given by

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Halloran and Sean O'Meara (1999), Rozhdestvensky (2006), and Yun et al. (2010). To overcome the inherent longitudinal instability of the small aspect-ratio rectangular wing-in-ground effect and to eliminate the necessity of the PAR wing, Lippich-type WIG craft (started with X-112, followed by RFB X-114 and, most recently, AirFish-8) employing a reverse delta wing planform with built-in anhedral was pioneered by Dr. Alexander Lippish in the 1970s. The addition of the anhedral to the reverse delta wing not only creates a high-pressure "air tunnel" (as described by Kocivar (1977)) increasing the ram pressure acting on the wing's lower surface but also considerably reduces the hydrodynamic drag during takeoff by submerging only the tips or sponsons of the anhedral wing into the water. The high lift-to-drag ratio of the reverse delta wing in conjunction with a small T-tail makes the Lippisch-type WIG craft operational and popular.

Extensive theoretical, numerical, and experimental investigations of the ground effect on the aerodynamic performance, including the lift-induced drag, and flow field of wings of different planforms have been conducted by researchers elsewhere. Theoretical ground-effect studies of conventional wings using the discrete vortex method can be found in the work of, for example, Plotkin and Kennel (1981), Han and Choi (2005), Gross and Traub (2012), Han and Kinnas (2013), Mondal and Balakrishnan (2014), and Mondal (2015). In comparison to reverse delta wings, the impact of ground effect on rectangular wings has been studied extensively. To limit the scope of this review, this study was concentrated on experimental investigations of the ground effect on the aerodynamics and tip vortex flow including the lift-induced drag of rectangular and delta wing, of both reverse and regular configurations, at low Reynolds numbers. Section 2 focuses on the chord-dominated and span-dominated ground effects on rectangular semi-wings. Both static and unsteady airfoils over flat and wavy grounds were reviewed. The discrepancy arose from stationary and moving ground conditions was also summarized. Section 3 focuses on the experimental investigations of the behavior of the aerodynamics and tip vortex flow of reverse delta wing in ground effect. Passive control schemes involving Gurney flap, cropping, and anhedral were also reviewed. In Section 4, the aerodynamics and the behavior of leading-edge vortices developed over a regular delta wing under the influence of ground proximity were also discussed. The aerodynamics and flow field characteristics of each wing planform outside the ground effect were also reviewed to serve as a comparison. Finally, suggestions applicable to each wing planform were provided in Section 5 for future experimental investigation.

2 Rectangular wing planform in ground effect

The ground effect on rectangular wings and airfoils is of both fundamental and practical importance. For a rectangular wing

planform with isolated end effects, the ground effect-produced lift increases, resulting from the ram pressure or the dynamic air cushion developed in the narrowed flow passage between the airfoil's lower surface and the ground surface, can be attributed to the so-called chord-dominated ground effect (CDGE). For finite wings, the lift-induced drag reduction and the outboard movement of the wingtip vortices as the ground is approached are mainly referred to as the span-dominated ground effect (SDGE). The combined chord-dominated and span-dominated ground effects give rise to an increased liftto-drag ratio of the winged GEV as compared to its outside ground effect counterpart. The CDGE on the aerodynamics and flow structure of the airfoils have been investigated extensively. However, due to the different ground boundary conditions, Reynolds numbers, airfoil profiles, flow facilities, and analysis methods employed, there exists a large scatter in the published CDGE-induced sectional lift C_l and drag C_d coefficients and the flow field characteristics of the airfoil. By contrast, investigations on the impact of span-dominated ground effect on the tip vortices, especially the lift-induced drag, are limited. A large discrepancy also exists in the archived vortex flow and liftinduced drag in ground proximity. In this section, typical experimental CDGE investigations were reviewed first, followed by the impact of SDGE on the tip vortices and the associated lift-induced drag. The CDGE investigation started with flat surface, both stationary and moving, followed by wavy ground or wall. Both static and unsteady airfoils in ground effect were considered. The SDGE investigation was focused on the aerodynamic and tip vortex characteristics, especially the calculation of lift-induced drag, in ground effect. To facilitate the review of ground effect on rectangular wings and airfoils, the outside-ground effect was summarized first and serves as a comparison.

2.1 CDGE

2.1.1 Flat ground

The aerodynamics and flow structure of airfoils of various profiles subjected to both stationary and moving flat ground surfaces at different low Reynolds numbers were investigated extensively by Carter (1961), Turner (1966), Hayashi and Endo (1978), Suh and Ostowari (1988), Tomaru and Kohama (1990), Hsiun and Chen (1996), Steinbach (1997), Moore et al. (2002), Barber et al. (2002), Ahmed and Sharma, (2005), Ahmed et al. (2007), Ghadimi et al. (2012), Luo and Chen (2012), Qu et al. (2014), Qu et al. (2015a), He et al. (2018), Lee et al. (2018), and Tremblay-Dionne and Lee (2021).

Carter's (1961) towing tank study showed that the ground proximity caused an increased lift-curve slope while the profile drag remained virtually unaffected. α is the angle of attack. Turner (1966) reported that the stationary ground proximity produced a drastic increase in C_l of the airfoil. A 33% C_l

increment was obtained at h/b = 33% (where h is the distance between the airfoil's trailing edge and the ground, and b is the wingspan) as compared to its outside ground effect counterpart. Hayashi and Endo (1978) found both numerically and experimentally that in stationary ground effect the flow separation occurred earlier, resulting in a larger wake behind a NACA 4412 airfoil at $\alpha = 15^{\circ}$ and a chord Reynolds number $Re = 3.2 \times 10^5$. Suh and Ostowari (1988), however, indicated that the stationary ground effect produced a reduced C_d accompanied by increased flow separation, leading to an increased C_l/C_d . Steinbach (1997) also observed that the flow separation was enlarged and the drag was reduced as the moving ground was approached. The moving ground was achieved via boundarylayer suction. Hsiun and Chen (1996) simulated numerically the flow separation over a NACA 4412 airfoil at $\alpha \le 10^{\circ}$ for $Re = 3.2 \times$ 10^5 and concluded that both C_l and C_d were a strong function of the stationary ground clearance. Steinbach (1997) pointed out that C_l was affected by the boundary layer developed on the stationary ground surface for $h \le 5\%$ airfoil chord *c*, and that the slip boundary condition should be considered.

Moore et al. (2002) further reported that both C_l and C_d of a NACA 0012 airfoil at $Re \le 8 \times 10^5$ were increased with decreasing ground distance in a rolling road wind tunnel. For $\alpha \leq 3^\circ$, the C_l reduction was attributed to the abnormal suction effect developed on the airfoil's lower surface due to the convergentdivergent passage developed between the airfoil and the ground surface. They divided the ground effect into two distinct regimes: ram effect for $h/c \le 10\%$ and normal ground effect for h/c > 10%. In the ram effect, an almost sealed envelope is created between the wing's trailing edge and the ground surface. As h/c increases above 10%, the wing enters what is normally considered to be the normal ground effect. Barber et al. (2002) indicated numerically that there was a large C_l discrepancy between moving and stationary ground effect in close ground proximity at Re = 8.2×10^6 and $\alpha = 2.9^\circ$, and that only a small C_l difference existed for h/c > 10%. A recirculation region was visible beneath the airfoil's leading edge at h/c = 2.5% over the stationary ground. The numerical results were also supplemented by limited particle image velocimetry (PIV), flow field measurements at $Re = 6.1 \times$ 104. They concluded that viscous effects are significant for the ground-effect flight and it is unlikely that inviscid solutions will give an accurate representation of the ground-effect aerodynamics.

Ahmed and Sharma (2005) reported experimentally that the surface pressure coefficient C_p increased on the airfoil's lower surface as the stationary ground was approached, leading to an increased C_l . Also, the flow accelerated over the airfoil due to flow diversion from the lower surface especially for higher α , resulting in a thicker wake and hence higher drag. Ahmed et al. (2007) further showed that in moving ground effect the C_l of a NACA 4412 airfoil at $Re = 3 \times 10^5$ increased with decreasing h/c for high α while decreased with reducing h/c for small α . Only a minor loss of upper surface suction exhibited as the airfoil approached

the ground for all α . The high-pressure drag originated from the airfoil's lower surface which led to increased pressure drag at small h/c for all α tested. They also claimed that as the flow moved toward the trailing edge, the velocity close to the surface reduced to overcome the adverse pressure gradient. Luo and Chen (2012) investigated the stationary ground effect on a NACA 0015 airfoil through load cells and C_p measurements at $Re = 1.87 \times 10^5$. They found that the C_l decreased with h/c reducing from 30% to 15% for $\alpha \leq 6^\circ$ due to the convergent–divergent channel effect, and that the C_l generally lay within the magnitude estimated from the thin airfoil theory.

To resolve and quantify the discrepancy arose from the ground boundary conditions, Re, airfoil profiles, flow facilities, and test methods, the aerodynamic and flow field characteristics of a NACA 0012 airfoil subjected to both stationary ground and moving ground effects were investigated in the same wind tunnel flow facility at an identical Reynolds number via PIV and C_p measurements by Tremblay-Dionne and Lee (2021). The moving ground was set up via a moving belt with a surface speed equal to that of the freestream velocity. The laminar boundary layer developed over the stationary ground (simulated by an elevated thin metal plate) had a normalized thickness of δ/c = 1.6%, corresponding to h/c = 1.6%. The ground distance h was the distance between the airfoil's trailing edge and ground surface (Figure 1A). Tremblay-Dionne and Lee (2021) concluded that for the stationary ground effect, the existence of the longitudinal boundary layer developed on its surface narrowed the flow passage underneath the airfoil, decelerating the flow, and producing a higher C_l than the moving ground (Figure 2A). The change in the sectional pitch-moment coefficient C_m with h/cwas depicted in Figure 2C. In ground effect, a nose-up (or nosedown) C_m in the small (or large)- α also exhibited. They also concluded that in close stationary ground proximity the formation of a ground vortex or circulation region beneath the airfoil's leading-edge region (Figure 2G) speeded up the flow, leading to a lower C_l than the moving ground. For $h/c \ge$ 20%, no ground vortex was observed (Figure 2H).

For moving ground, the ground vortex was always absent (Figures 2D,E). The absence of the ground vortex enabled an increase in velocity as the flow speeded up to meet the velocity at the ground surface, causing the flow to remain uniform beneath the airfoil as it approached the moving ground surface. The moving ground effect, however, generated a larger near wake and C_d (Figure 2B) than the stationary ground effect, suggesting an earlier flow separation. The change in C_l can also be reflected in the C_p distribution on the airfoil surface at different h/c at $\alpha = 6^{\circ}$ (Figure 2I). The moving ground effect generated a larger C_p exerting on the airfoil's lower surface, leading to a higher C_l and C_d than the stationary ground effect. Only a minor change in C_p developed on the airfoil's upper surface was noticed regardless of h/c, α , and ground boundary conditions. Figure 2I also confirms at $\alpha = 1^{\circ}$, there was a negative C_p which appeared on the airfoil's lower surface originated from the convergent-divergent flow



Schematics of airfoil and wing models and definition of ground distance h. (A) NACA 0012 airfoil, (B) wavy wall, (C) baseline rectangular semiwing (BW), (D) reverse delta wing (RDW), (E) RDW and h, (F) RDW with joint cropping, anhedral, and Gurney flap, (G) cropped RDW, and (H) anhedral RDW, and **(H)** λ = wavelength. A = 2a = wave amplitude. δ_{TE} = flap deflection angle.

passage developed underneath the airfoil in close ground proximity. Additional experiments investigating the impact of different moving ground surface speeds on airfoils of different profiles are desired.

In addition to a statice airfoil operating close to a flat ground surface, Lee et al. (2018) also investigated the aerodynamic property of a NACA 0012 airfoil oscillated sinusoidally with $\alpha(t) = 11^{\circ} + 6^{\circ} \sin \omega t$ motion at a reduced frequency κ (= $\omega c/2U$ = $\pi fc/U$, where f is the oscillation frequency and U is the freestream velocity) = 0.05 in

stationary ground effect via the integration of C_p at Re = 9.81×10^4 . A substantial change in the dynamic- C_l loops, especially during the downstroke, occurred for $h/c \leq 30\%$, leading to a significantly reduced C_l -hysteresis as compared to the OGE case (Figure 3A). The dynamic-stall vortex was found to be weakened and broke down earlier with reducing h/c_{1} , rendering an enlarged separated flow than their OGE counterpart. The degree of nose-down pitching moment also increased with reducing ground distance (Figure 3B). Additional experiments covering attached-flow, light- and



deep-stall oscillations at different κ are needed. Individual and combined heave and pitch motions in ground effect also demand consideration. It is noteworthy that the impact of

joint heave and pitch motion on the aerodynamic property of the airfoil outside the ground effect was investigated by Lee and Su (2015). For the WIG craft, the wavelength, amplitude,



and the wave travelling speed of the ocean waves serve as experimental guidelines.

2.1.2 Non-uniform ground

Since the WIG craft frequently fly over non-uniform ground, for example, a bump, a wavy terrain, and rough ocean waves, it causes unsteady and non-uniform flow beneath the wing which affects the stability and predictability of its flight dynamics, especially in the vertical plane. Only a limited number of publications are available for the WIG craft flying over non-flat grounds. Most of the non-uniform ground effect were studied by using the simplified sinusoidal wavy ground of various wavelengths and amplitudes. Representative theoretical and numerically work have been conducted by, for example, Ando et al. (1992), Morishita and Ashihara (1995), Im and Chang (2000), Rozhdestvensky (2006), Matveev (2015), and He et al. (2019). The experimental investigation of wavy ground effect was conducted by Tremblay-Dionne and Lee (2019a and 2019b).

Im and Chang (2000) studied numerically the aerodynamic loads of an oscillating NACA 0012 airfoil over a moving sinusoidal wall of an amplitude a = 2.5%c and 10%c and a wavelength $\lambda = 1.5-5c$ at $Re = 3.2 \times 10^5$. The normal force coefficient C_n increased as the airfoil was moving toward the crest of the wavy ground and decreased as it moved away from the crest. The C_m was all negative. No C_d was reported in their inviscid-flow calculation. Matveev (2015) modelled the complex flight dynamics due to the wavy ground effect on the vehicle aerodynamics by using potential flow theory. The influence of heave-pitch motion on C_b $C_{n\nu}$ and C_n was studied for flights over wavy surfaces over a range of a and λ . For "extreme" ground effect flow, the dominant lift component was found to be generated on the lower side of the wing, and the flow under the wing became nearly two-dimensional. The influence of the flow in the wake and above the wing on the upper-wing flow were ignored.

Lee and Tremblay-Dionne (2018) measured the aerodynamic and flow properties of a static NACA 0015 airfoil over a wavy ground with $\lambda/c = 1$ and 2a = 0.1c at $Re = 2.45 \times 10^5$ through C_p and PIV measurements in a subsonic wind tunnel. The schematic of the wavy ground and the definition of wavelength λ , peak-to-peak amplitude A = 2a, ground distance h, and measuring position x'are given in Figure 1B. They observed that there exhibited a cyclic variation in C_l and C_m over an entire wavelength (Figures 4A,B). For $\lambda/c = 1$, x'_{6} is located at the wave valley while x'_{0} and x'_{11} are located at the wave peak. The C_m value had an opposite trend to the variation in C_l as well as an almost all-negative value. The maximum C_l occurred at the wave peak (produced by the wavy groundinduced ram pressure) and the minimum C_l occurred at the wave valley (resulting from the unusual suction pressure developed on the airfoil's lower surface due to the converging-diverging flow passage developed underneath it) reduced with increasing ground distance. The wavy ground effect-produced gain in the mean C_l was, however, at the expense of longitudinal stability. Figure 4C demonstrates the great change in C_p on the airfoil's lower surface over one wavelength.

2.2 SDGE

2.2.1 OGE

In this section, the span-dominated ground effect on the wingtip vortices and the lift-induced drag generated by a



rectangular semi-wing was reviewed. It is known that outside the ground effect or in a free stream the growth and development of the tip vortices and their impact on the aerodynamics and flight hazards are of both fundamental and practical importance and have been investigated extensively by researchers elsewhere (see, Devenport et al. (1996), Chow et al. (1997), and Ramaprian and Zheng (1997)). An excellent review on airplane trailing vortices outside the ground effect was given by Spalart (1998). Various control techniques, such as winglets, spoilers, stub/subwing, porous tips and leading edges, static and rapidly actuated segmented Gurney flaps, plasma actuators, and zero mass-flux fluidic perturbations, have also been attempted to modify the strength, structure, and trajectory of the wingtip vortices (see, Duraisamy and Baeder (2003), Matalanis and Eaton (2007), Breitsamter and Allen (2009), Hasebe et al. (2011), Greenblatt et al. (2009), Greenblatt (2012), and Lee and Su (2012)). More recently, an alternative wingtip vortex control was proposed by Lee and Choi (2015) by using a tip-mounted small-chord half-delta wings (HDW) of different slenderness Λ , root chords c_r , and deflections.

Lee and Choi (2015) reported that, regardless of Λ and c_r , the addition of a small HDW to the tip of a rectangular semi-wing at $Re = 2.45 \times 10^5$ triggered the breakdown of the tip vortex, producing a greatly diffused and circulation flow-like tip vortex (Figure 5B) as compared to its baseline-wing



counterpart (Figure 5A). The streamwise vorticity $\zeta = \partial w / \partial y - \partial v / \partial z$ was calculated from the *vw*-crossflow measurements by using a central differencing scheme to evaluate the derivatives.

For the HDW wing, there was the presence of a double vortex system, consisting of a tip vortex and a HDW vortex. Figure 5A is of particular importance in the illustration of the initiation and

development of the tip vortex both along the tip and in the near field of a rectangular wing. As can be seen, the baseline-wing tip vortex became nearly developed for $x/c \ge 2$. The origin of the coordinates is shown in Figure 1C. For x/c < 1, the interaction and merge of the shear-layer vortices and main vortex leading to the tip vortex (for x/c > 1) can be clearly seen.

Lee and Choi further found that the interaction and merging of the double vortex was further expedited by upward HDW deflection. The addition of the small-chord tip-mounted HDW also led to an increased C_L and a decreased C_D (Figures 5C,D), leading to an improved C_L/C_D . The C_L increase can be attributed to the mitigation of the free end effects provided by the tip mounted HDW. The C_D reduction was due to the tip-mounted HDW-caused decrease in the lift-induced drag coefficient C_{Di} [= $D_i/\frac{1}{2}\rho U^2S$, where D_i is the lift-induced drag and S is the wing area; see Figure 5E). A 10% (or 34%) increase (or decrease) in C_L (or C_{Di}) at $\alpha = 10^\circ$ was produced by the 0.3*c* 50 HDW as compared to the baseline wing. The lift-induced drag D_i was computed *via* the Maskell integral model (Maskell, 1973; Brune, 1994; Kusunose, 1998).

$$D_{i} = \frac{1}{2} \rho_{\infty} \iint_{s\xi} \psi \zeta dy dz - \frac{1}{2} \rho_{\infty} \iint_{S_{1}} \phi \sigma dy dz - \frac{1}{2} \rho_{\infty} \iint_{S_{1}} (1 - M_{\infty}^{2}) (\Delta u)^{2} dy dz,$$
(1)

where $\psi(y,z)$ and $\phi(y,z)$ are stream function and velocity potential, and $\sigma = \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$. The details of the lift-induced drag computation were provided in the work of Gerontakos and Lee (2007).

For 2 < x/c < 4.5, the core flow of the tip vortex also became axisymmetric (manifested by the tangential velocity v_{θ} distribution across the vortex center with $v_{\theta,\max} \approx |v_{\theta,\min}|$), which suggests the near completion of the roll-up of the tip vortex in the near field. Additionally, a core circulation Γ_c to total circulation Γ_o ratio of about 74% of the tip vortex in comparison with 71% of Lam's solution (1941) was also attained. The circulation was computed *via* Stokes theorem by summing the vorticity multiplied by the incremental area of the measuring grid. The tip vortex measurement also allows the prediction of $C_{L,prediction} = 2(\Gamma_o/cU)$ (b'/b) = 0.542 which is 83% $C_{L,FB} = 0.651$ (measured with a force balance) at $\alpha = 10^\circ$. b' is the distance between the center of the tip vortices and b is the wing span. The vortex center was identified by the location of peak vorticity ζ_{peak} .

The C_L was also determined based on the integration of the spanwise circulation $\Gamma(z)$, inferred from the *vw*-crossflow measurement, and distribution from the whole wake scan (Figure 6A; Lin and Lee, 2022¹). The lift force *L* at each α was determined *via*



(A) Normalized spanwise circulation $\Gamma(z)$ distribution and (B) C_L at different α of a rectangular semi-wing with AR = 1.818 at $Re = 2.48 \times 10^5$ outside the ground effect (Lin and Lee, 2022¹).

$$L = \rho U \int_{-\frac{b_2}{2}}^{\frac{b_2}{2}} \Gamma(z) dz.$$
 (2)

In Figure 6A, the dip in the $\Gamma(z)$ distribution near the tip manifests the existence of a tip vortex with a stronger circulation. Special attention should be given to the large increase in $\Gamma(z)$ at the tip and the great drop in the root bound circulation $\Gamma_{b,m}$ identified at z = 0 for $\alpha = 16.3^{\circ}$ ($< \alpha_{ss} = 14^{\circ}$), attributing to the root stall of the rectangular semiwing. α_{ss} is the static-stall angle. For a root-stall wing, most of the inboard of the wing suffers from massive flow separation while the outboard wing region, especially the tip region, remains unaffected. The value of $C_{L,\Gamma(z)}$ (= $L/\frac{1}{2}\rho U^2S$),

¹ Lin, G., and Lee, T. (2022). Lift computation through crossflow measurement behind a rectangular semi-wing in ground effect. J. Fluids Eng. Submitted manuscript.

obtained through the integration of $\Gamma(z)$ distribution, was found to be in good agreement with the $C_{L,FB}$ measured directly with a force balance (Figure 6B), suggesting that the circulation distributions were consistent with the measured lift data according to the Kutta–Joukowsky theorem. The prediction of $C_{L,\Gamma(z)}$ only applied to pre-stall α regime, that is., $\alpha \leq \alpha_{ss}$. Also, shown in Figure 6B is the prediction of $C_{L,Tb,m} = 2\Gamma_{b,m}/cU$ based on classical Prandtl's lifting-line theory. The estimated $C_{L,\Gamma(z)}$. At $\alpha = 10^\circ$, $C_{L,\Gamma(z)} = 0.596$ and $C_{L,\Gamma b,m} = 0.64$ in comparison with $C_{L,FB} = 0.661$ were obtained. Also, presented in Figure 6A is the $\Gamma(z)$ distribution of an elliptical wing for a direct comparison. Extension of the C_L determination based on the *vw*-crossflow measurements to in-ground effect is highly desired.

2.2.2 IGE

In this section, the effect of ground effect, both stationary and moving, on the tip vortex flow was reviewed. Lu et al. (2019) found that in close stationary ground proximity, there existed a unique multiple vortex system, consisting of a tip vortex (TV), a co-rotating ground vortex (GV), and a counterrotating secondary vortex (SV), downstream of the rectangular wing (see Figure 7A). The ground vortex adds vorticity to the tip vortex while the secondary vortex negates its vorticity. The ground vortex formed beneath the airfoil's leading-edge region was caused by the ground effect-produced ram pressure which pushes the streamwise boundary-layer flow backwards and toward its leading edge and rolling up into the observed recirculation region (as discussed earlier in Figure 2G). The secondary vortex was first observed experimentally by Harvey and Perry (1971) and was numerically simulated later by Corjon and Poinsot (1997), Puel and Victor (2000), and Holzapfel and Steen (2007). Harvey and Perry found that as a vortex descended close to the ground during landing and takeoff, the crossflow of the tip vortex gave rise to a spanwise boundary layer which rolled up into a counter-rotating secondary vortex relative to the descending tip vortex. In addition to the appearance of the multiple vortex system in close ground proximity, a large scatter in vortex flow characteristics and D_i also exists due to different ground boundary conditions, Re, flow facilities, wing planforms, and airfoil profiles employed (see, Chun et al. (1996), Joh and Kim (2004), Han and Choi (2005), Lee et al. (2010), Lu et al. (2019), and Lu and Lee (2021)).

Chun et al. (1996) reported that the stationary ground effect resulted in an insufficient space for the tip vortices to grow, causing a reduced lift-induced drag. Tuck and Standingford (1996) showed that the lift-induced drag increased with decreasing ground distance. The ground proximity-produced lift increase and the lift-induced drag decrease were also observed by Joh and Kim (2004). Han and Choi (2005) demonstrated theoretically that there was a lateral vortex displacement and reduction in the vortex strength in ground effect. Lee et al. (2010) suggested numerically that the ground proximity gave a lower lift-induced drag while a strengthened vortex compared to the OGE values.

Lu et al. (2019) investigated the ground effect on the tip vortex through the vw-crossflow measured with a miniature seven-hole pressure probe in the J.A. Bombardier wind tunnel at McGill University at $Re = 2.71 \times 10^5$. To minimize the longitudinal boundary layer developed on the stationary ground and its interaction with the wing model, the stationary ground was simulated by an elevated flat plate on which a thin laminar boundary layer of a thickness of 4 mm or equivalently a h/c = 1.6% was developed. Lu et al. reported that the lift-induced drag greatly reduced as the stationary ground was approached for h/c < 20% (Figure 8A) due to the large outboard displacement of the tip vortex, suggesting an increased effective wing aspect ratio and subsequently a reduced C_{Di} (Figure 8B) as compared to their OGE counterpart. The secondary vortex also caused a rebound of the tip vortex (Figure 8B). The C_{Di} computed via the Maskell method (Eq. 1) was also compared to that predicted by Eq. 2 developed by Prandtl for inviscid flow (Mantle, 2016).

$$C_{Di} = (1 - \sigma) \frac{C_L^2}{\pi A R'},\tag{3}$$

where $\sigma = (1-1.32 h/b)/(1/1.05 + 7.4 h/b)$ is a modifier called the influence coefficient which accounts for the effect of ground proximity, *h* is the height of the wing (at the quarter chord point) above the ground, and *b* is the span of the wing. The C_{Di} computed *via* the Maskell method had a similar trend to the inviscid-flow prediction (i.e., Eq. 3) but exhibited a lower magnitude than its inviscid-flow counterpart, that is, the inviscid flow prediction offers an upper limit of C_{Di} .

The C_{Di} in ground effect was also estimated via

$$C_{Di} = \frac{C_{L,OGE}^2}{\pi e A R_{eff}},\tag{4}$$

where $C_{L,OGE}$ is the OGE C_L value at $\alpha = 10^\circ$, e is known as the span efficiency representing the non-ellipticity of the spanwise lift distribution and is set at 0.9, $AR_{eff}(=b'/c)$ is the effective AR at each h/c, and b' is the distance between the two vortices. The stationary ground effect was found to produce a higher C_L and C_D than the OGE case (Figures 8C,D). The C_D increase was due to the increase in pressure drag resulting from the ram pressure exerting on the wing's lower surface and also the flow separation from the wing's upper surface. At the same C_L , the C_D was, however, decreased as the stationary ground was approached.

To differentiate the observed discrepancy in the tip vortex flow and lift-induced drag arising from stationary and moving ground conditions, the tip vortex and the associated lift-induced drag of a NACA 0012 rectangular semi-wing in stationary and moving ground effect was investigated by Lu and Lee (2021) in a subsonic wind tunnel by using PIV at $Re = 9.2 \times 10^4$. The moving ground condition was established by using a moving belt with a surface velocity set at the freestream velocity. They found that the



FIGURE 7

Effect of ground boundary conditions on iso- $\zeta c/U$ contour at different h/c for $\alpha = 10^{\circ}$. (A) Stationary ground and (B) moving ground. $\zeta_p (= \zeta_{peak}c/U)$ denotes normalized peak vorticity of the vortex. Gray dashed line denotes vortex center location. GV, MV, SLV, SV, and TV denote ground vortex, main vortex, shear-layer vortex, secondary vortex, and tip vortex, respectively. (C) Conceptual sketch of the existence of the spanwise ground vortex filament (SGVF) and its downstream development into the ground vortex, the formation of SV, and the evolution of MV, SLV, and TV. The evolution and streamlines is adapted from Chow et al. (1997) (Lu and Lee 2021).



multiple vortex system persisted for h/c > 40% (Figures 7A,B). For $h/c \ge 40\%$, only the tip vortex appeared. For h/c > 60%, the tip vortex resembled its OGE counterpart. More importantly, for the moving ground the ground vortex was absent (Figure 7B). The secondary vortex persisted regardless of the boundary ground conditions. The appearance of the secondary vortex significantly weakened the tip vortex strength and produced a large induceddrag reduction (Figures 9A,B). The secondary vortex developed over the moving ground produced a higher Γ_o and C_{Di} than their stationary ground counterpart. The Γ_o and C_{Di} of the secondary vortex always increased with reducing h/c.

Lu and Lee (2021) also concluded that the combined Γ_o and C_{Di} of the multiple vortex system also increased slowly with reducing h/c, reaching a sharp local peak, and started to drop rapidly as the ground was further approached (Figures 9C,D). At h/c = 5%, a 57% (or 62%) and 40% (or 32.2%) reduction in the combined Γ_o for the moving (or stationary) ground relative to the OGE case was observed. The moving ground proximity caused a larger outboard movement of the tip vortex than the stationary

ground (Figure 9E). The moving ground effect also produced a larger vortex rebound than the stationary ground effect (Figure 9F). Further downstream, the secondary vortex also rolled around the tip vortex and merged with the tip vortex. In summary, the ground vortex first appeared along the wing's tip region and continued downstream into the near field. The ground vortex persisted in the spanwise direction along the wing's leading edge, leading to the formation of the spanwise ground vortex filament (SGVF). The formation of the SGVF along the wing's leading edge, its downstream development into the ground vortex, and its interaction with the tip vortex and secondary vortex can be better understood by the conceptual sketch depicted in Figure 7C.

3 Reverse or inverted delta wing

Despite the extensive employment of reverse delta wings in the Lippisch-type WIG craft, investigations of the aerodynamics



and flow structure of reverse delta wings both outside and in ground effect were scarce (see, Gerhardt (1996), Musaj and Price (2008), Altaf et al. (2011), Wang et al. (2013), Lee and Ko (2016,

2017), Lee and He (2018), Lee et al. (2019), Ko et al. (2020), and Mahgou and Cortelezzi (2020)). In this section, the impact of the ground effect on the aerodynamics and flow structure, especially

the trailing vortices, of a slender reverse delta wing was reviewed. Passive control utilizing stand-alone and joint Gurney flap, cropping, and anhedral were also discussed. The aerodynamic and flow field characteristics of the reverse delta wing outside the ground effect (OGE) were also included to serve as a comparison.

3.1 Baseline reverse delta wing

3.1.1 OGE

The aerodynamics and flow behavior of a 75° -sweep reverse delta wing outside the ground effect at $Re = 3.82 \times 10^5$ were investigated recently by Altaf et al. (2011). Their force balance data show that the slender reverse delta wing produced a lower C_L and C_D than the delta wing. Also, the trailing vortices possessed a smaller tangential velocity, circulation, and vorticity than the delta wing. Since then, the reverse delta wing has also been employed in the passive control of wingtip-generated vortices by Lee and Su (2012) and Altaf et al. (2016). Lu and Lee (2019) also found that in ground effect the addition of a small tip-mounted halfreverse delta wing led to a rapid diffusion and breakdown of the wingtip vortex, suggesting an effective tip vortex control.

Lee and Ko (2016) and Lee and He (2018) further demonstrated that, in addition to the generation of a lower C_L and C_D (Figures 10A,B), the 65°-sweep slender reverse delta wing (see Figure 1D) also exhibited a delayed stall at Re = 3.81×10^5 as compared to its delta wing counterpart. For the delta wing, the static-stall angle α_{ss} occurred at 34° with $C_{L,max}$ = 1.26 as compared to 38° and 1.175 of the reverse delta wing. The gain in C_D reduction of the reverse delta wing overwhelmed the loss in C_L , leading to an improved C_L/C_D ratio as compared to the delta wing (Figure 10C). They also found that, in contrast to the leading-edge vortex (LEV) breakdown-induced stalling of the delta wing (Figures 10D,E), the stalling of the reverse delta wing was triggered by the disruption of the coherent multiple spanwise vortex filaments (SVFs) developed over its upper wing surface (Figures 10F,G). The RDW vortices were originated from the spanwise leading-edge vortex filament. In contrast to the LEV-induced massive flow separation, the disruption of the SVFs over the reverse delta wing was less drastic which resulted in a lowered C_D . The LEVs were located inboard and above the delta wing's upper surface, while the trailing vortices generated by the reverse delta wing were found to be located outside the wing but moved inboard as they progressed downstream.

The spatial progression of the iso- $\zeta c/U$ contours of the RDW trailing vortices and LEVs at selected α were depicted in Figures 11A,B. For clarity, enlarged views of the unique fist-

arm pattern of the RDW vortex and the LEV describing their diffusion and breakdown were also given at selected x/c. The RDW vortex had a much lower peak vorticity ζ_{peak} than the delta wing (Figure 12A). At $\alpha = 20^{\circ}$, the LEV breakdown occurred between x/c = 0.53 and 0.54 for the delta wing (see Figure 11B). By contrast, the RDW vortex remained concentrated and axisymmetric for $\alpha \leq 16^{\circ}$ and became diffused for $16^{\circ} < \alpha \leq 23^{\circ}$ for x/c > 0.8. For $\alpha > 22^{\circ}$, the RDW vortex resembled a circulation-like flow with small patches of vorticity for x/c > 0.3.

Lee and He (2018) further reported that the total circulation Γ_o of the RDW vortex was found to increase with x/c up to x/c > 0.7, attaining an almost constant value (with $\Gamma_o/cU = 0.241$) for 0.7 < x/c < 1.5 (Figure 12B). Also, the trailing-edge apex region covering 0.7 < x/c < 1 was characterized by a 3-D and separated flow (see also Figures **10F,G**). The invariant Γ_o of the RDW vortices for x/c > 1 was also used to predict the C_L via the $L = \rho U \Gamma_o b'$ relationship where $b' = 2z_c$ is the distance between the center of the two trailing vortices (Figure 12C). The $C_{L,predicted} = (2\Gamma_o/cU) (b'/$ b) = 0.62 at α = 16° accounted for 94% of $C_{L,FB}$ = 0.661 obtained directly by force balance (Figure 12D), suggesting the strength of the RDW trailing vortices is also a direct indicator of the lift generation of the reverse delta wing. The value of $C_{L,prediction}$ was found to be in good agreement with $C_{L,FB}$ for $\alpha \leq 22^{\circ}$. Meanwhile, the C_{Di} = 0.154 (computed via the Maskell method or Eq. 1) was found to account for 48% of $C_{D,FB} = 0.321$ (Figure 12E). The vertical movement of the vortices with x/c was displayed in Figure 12F. Both ζ_{peak} and $v_{\theta,peak}$ of the RDW vortex were found to increase with x/c, reaching a local maximum at around x/c = 0.5, and began to drop for 0.5 < $x/c \le 1.5$ (Figures 12A,G). The core velocity u_c of the RDW vortex was found to be insensitive to x (Figure 12H). The LEV was, however, travelling downstream with a core velocity $u_c \approx$ 2*U*. The critical LEV flow characteristics at $\alpha = 16^{\circ}$ were also included Figures 12A-G for reference.

3.1.2 IGE

In ground effect, the C_L and C_D of the baseline reverse delta wing increased persistently with reducing h/c for h/c <40% except for the near-stall α regime (Figures 13A,B). The definition of the ground distance h was given in Figure 1E. At a fixed α , the C_L increased non-linearly and was the greatest in close ground proximity. The ground proximity, however, caused a slightly earlier wing stall as compared to the OGE case. The stalling mechanism of the reverse delta wing remained virtually unaffected. At a fixed C_L , the C_D decreased below the baseline-wing value with reducing h/cfor $h/c \leq 10\%$. For h/c > 10%, the C_D was larger than the OGE value. Lee and Ko (2018) further reported that the ground Lee and Lin



FIGURE 10

(A–C) Aerodynamic coefficients of reverse delta wing (RDW) and regular delta wing (DW) in a free stream. Photos of flow patterns **(D–E)** DW at $\alpha = 19^{\circ}$ and 27.5° and **(F–G)** RDW at $\alpha = 14^{\circ}$ and 20°. 65RDW and 50RDW denote RDW with 65° and 50° sweep, respectively. SVF denotes spanwise vortex filament. Flow direction is from right to left (Lee and Ko 2016; Lee and He 2018; Lee et al., 2019).



proximity also caused a redistribution of the vorticity of the vortex leading to a lowered ζ_{peak} but a higher Γ_o as compared to its OGE counterpart. The ζ_{peak} reached a local maximum at around x/c = 0.3 and began to drop as it progressed further downstream. The vortex center was displaced further outboard compared to the OGE case but moved slightly away from the wing's mid-chord as it progressed downstream. The ram pressure, however, produced a higher $v_{\theta,peak}$ and Γ_o than the OGE case. A 37% and 65% increase in $v_{\theta,peak}$ and Γ_o at x/c = 1.01 in ground effect were

obtained. In addition, the effective in-ground effect flight of baseline reverse delta wings should be kept within 45%*c*.

3.2 Wings with Gurney flap, cropping, and anhedral

To augment the lift generation of the reverse delta wing, passive control using stand-alone and joint Gurney flap, cropping, and anhedral was employed. Figures 1F–H show the schematics of the

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Gurney flap, cropping, and anhedral and the definition of ground distance *h*. The Gurney flaps have been employed extensively on conventional wing planforms by researchers elsewhere (see, Wang et al. (2008)). Figures 13C–E show that outside the ground effect the Gurney flap produced a large C_L increase because of the reduction of flow leakage from the wing's trailing edges and, to a much less

extent, to the Gurney flap-induced spanwise camber effects. At the same C_L , the Gurney flap also produced a smaller C_D as compared to the baseline wing (Figure 13D).

Also, since the flow in the trailing apex region of the reverse delta wing is 3-D and is always prone to separate, its removal thereby provides a welcomed weight reduction of the Lippisch-type WIG



craft. Figure 1G shows the schematic diagram of the cropped wing. Cropping (up to 40% reduction in the wing's chord or 16.3% reduction in the wing surface area) in a freestream at $Re = 3.81 \times$

10⁵ was tested by Lee and He (2018). The lift and drag forces were both normalized by the non-cropped baseline-wing surface area S_{BW} . Cropping ≤ 30%*c* was found to produce a minor change in C_L and C_D



(Figure 13C) as compared to the non-cropped wing. The 30%*c* cropping was therefore adopted in conjunction with anhedral and Gurney flap. The addition of anhedral ($\delta_A = 8^\circ$ to 45°) gave a

decreased C_L and C_D (Figures 13C,E) due to the anhedral-induced reduction in the wing surface area. The C_L decreased rapidly with increasing anhedral angle δ_A . The trailing vortices were found to move

further outboard with an increased vorticity level and tangential velocity with increasing anhedral. Among all the δ_A tested, the δ_A = 15° wing anhedral was utilized in the passive control of the reverse delta wing. At a fixed C_L , the C_D increased with increasing δ_A . In ground effect the passive control became dramatically beneficial. The cropping allowed the wing to be positioned closer to the ground, causing a persistent increase in the ram pressure and C_L , especially for h/c < 20% (Figure 14A). At a fixed C_L the C_D was lower (or higher) for $h/c \le 10\%$ (or h/c > 10%) than the baseline wing (Figure 14B). Also, in contrast to the deteriorated aerodynamic performance associated with the wing anhedral outside the ground effect, the addition of δ_A to the cropped wing created an almost sealed high-pressure "air tunnel" underneath the wing which significantly increased the value of C_L and C_D with reducing h/c (Figures 14C,D). The larger the δ_A was, the larger the C_L and C_D became. At $h/c \approx 0\%$, a 270% and 150% ΔC_L increment compared to its OGE counterpart for $\delta_A = 8^\circ$ and 45° , respectively, was obtained, which enables the short-distance take-off of the WIG craft.

The anhedral-induced C_L augmentation also led to an everincreasing total circulation of the RDW vortices. The vortices moved further outboard with reducing h/c. The RDW vortices, however, retained their regularity to a higher α with increasing anhedral and reducing h/c. The lift of the cropped and anhedral wing was further increased by the application of the Gurney flap (Figure 14E). The selection of $\delta_A = 15^\circ$ anhedral was based on the configuration of RFB X-114 and AirFish-8. The larger the flap height h_{SES} was, the larger the C_L increase became. At h/c = 5%, a 345% and 175% C_L increment were attained with $h_{SES} = 6\%c$ and 2%c, respectively, as compared to the baseline wing. The C_D of the joint configuration increased with reducing h/c and increasing h_{SES} (Figure 14F).

4 Delta wings in ground effect

In this section, the impact of ground effect on the regular delta wing is discussed. The aerodynamics and behavior of the leading-edge vortices (LEVs) of the delta wings in a free stream have been investigated extensively by researchers elsewhere (see, Lowson and Riley (1995), Nelson and Pelletier (2003), and Gursul (2005)). By contrast, the WIG craft utilizing delta wing planforms have received limited attention (Katz and Levin, 1984; Plotkin and Dobele, 1988; Qin et al., 2015; Qu et al., 2015a; Lee and Ko, 2018).

Qu et al. (2015b) found numerically that the C_L , C_D , and nosedown C_M of a slender half-model delta wing at $\alpha = 20^\circ$ and $Re = 1.2 \times 10^7$ increased with decreasing h/c, and that the ram pressure exerted on the wing's lower surface contributed to the change in the aerodynamic loads. The ground was set as a no-slip wall condition in their simulation. They also reported that the strength of the LEVs and their axial vorticity and core circulation increased in ground effect. The LEV breakdown, however, occurred earlier as the ground was approached. The large circumferential velocity and the resulted stronger centrifugal force core also led to an expanded LEV core in ground effect.

Lee and Ko (2018) demonstrated experimentally that for a 65°-sweep slender delta wing at $Re = 3.81 \times 10^5$ both C_L and C_D increased with reducing h/c (up to 50% of the wing chord, Figures 15A,B). The C_L increment was the greatest at low α and decreased rapidly with increasing h/c and α . The ground effect also gave rise to an increased adverse dp/dx gradient, leading to an earlier wing stall and flow separation as compared to their OGE counterpart. In ground effect, the LEVs became stronger and had an higher rotational speed than the OGE case (Figures 15C,D). The smaller the ground distance was, the stronger the LEV and the earlier vortex breakdown became. They also showed that outside the ground effect the LEV breakdown (identified by the sharp drop in ζ_{peak} , the sudden expansion of the vortex size, and the loss of the coherence of the vortex) was found to occur at $(x/c)_{BVD}$ = 0.76 at $\alpha = 20^{\circ}$. In ground effect, the (*x*/*c*) _{BVD} occurred at 0.71, 0.73, and 0.74 for h/c = 5%, 10%, and 20%, respectively. The LEV breakdown caused a massive flow separation over the wing's upper surface and, consequently, an ever-increased C_D.

For the non-slender delta wing, there was a steeper lift-curve slope accompanied by an earlier stall angle at $\alpha_{ss} = 21^{\circ}$) as well as a lower $C_{L,max}$ of 0.99 than its slender counterpart with $\alpha_{ss} = 34^{\circ}$ and $C_{L,max} = 1.26$ (Figure 15E) in a free stream. The LEVs were ill-defined and were located closer to the non-slender delta wing surface (see Figure 11C), leading to a premature LEV breakdown and a lower $C_{L,max}$ and α_{ss} as compared to the slender wing. Most of the upper wing surface, however, remained unaffected from the LEV breakdown-caused flow separation, rendering a higher C_L for $\alpha \leq \alpha_{ss}$ than the slender wing. At low C_L , there was only a marginal change in C_D (Figure 15F), regardless of the slenderness and wing planform. In ground effect, the C_L and $C_{L,max}$ of the non-slender delta wing increased with reducing h/c for $h/c \leq 40\%$. The lift- α curve slope increased with reducing h/c. At the same C_L , the ground proximity, however, produced a lower C_D compared to the OGE case.

In short, the ground proximity leads to strengthened LEVs with an increased circulation, rotational speed, and axial velocity, and, more importantly, an increased lift of the delta wing. The enlargement of the LEVs and ram pressure, however, resulted in a larger drag force as compared to the outside ground effect. The ground effect-induced increase in the adverse pressure gradient inevitably caused an earlier LEV breakdown, leading to unsteady and asymmetric forces and a loss of lift. Control techniques capable of delaying LEV breakdown in ground effect are necessitated in order to make delta wing planforms practical for WIG craft application.

5 Conclusion

5.1 Rectangular wings and airfoils

For the chord-dominated ground effect, there is the appearance of a ground vortex or recirculation region underneath the airfoil's leading-edge region in close stationary ground effect due to the



Impact of ground effect on (A,B) aerodynamic coefficients of the delta wing and (C,D) LEV flow parameters at $\alpha = 20^\circ$. (E,F) Non-slender delta wing (Lee and Ko 2018).

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longitudinal boundary layer developed on the stationary ground surface. The ground vortex leads to a lower lift than its movingground counterpart. For the moving ground, the ground vortex is absent. In stationary ground effect, the presence of the longitudinal boundary layer also narrows the flow passage beneath the airfoil, producing a higher lift than the moving ground. The simple stationary ground is applicable by ensuring that the longitudinal boundary layer developed on its surface remains and has an equivalent thickness within 2% of the airfoil chord. The moving ground effect, however, produces a larger wake and drag than the stationary ground effect. For oscillating airfoils, the CDGE leads to a substantial increase in C_l and negative C_{m} especially during downstroke. For a static airfoil in non-uniform ground effect, simulated by a simplified sinusoidal wavy ground, there exists a cyclic change in C_l and C_m over an entire wavelength. The cyclic change in C_m is 180°-out-of-phase to the C_l .

For span-dominated ground effect, there exhibits a multiple vortex system, consisting of the tip vortex, co-rotating ground vortex, and counter-rotating secondary vortex behind the finite wing in the close stationary ground effect. The ground vortex adds vorticity to the tip vortex while the secondary vortex negates the vorticity. The ground vortex possesses a much weaker strength than the secondary vortex. In moving ground effect, the ground vortex is absent. The strength of the ground vortex and its interaction with the tip vortex are greatly minimized by using a thin laminar boundary layer developed on the flat ground surface. The moving ground effect also produces a stronger secondary vortex leading to a larger tip vortex rebound and outboard movement, as well as a smaller liftinduced drag and tip vortex strength than their stationary-ground counterpart. The most effective in-ground-effect height or distance for rectangular wings should be within 15% airfoil chord.

To further consolidate the findings, investigations with different moving ground surface velocities are desirable. Moving wavy grounds of different airfoil chord to wavelength ratios and ground distances also demand further investigation. The wavelength and amplitude of the ocean waves can serve as experimental guidelines. The effect of unsteady wings and airfoils subjected to attached-flow, lightstall, and deep-stall heaving and pitching motions, and ramp motions on the aerodynamics and tip vortex, including the liftinduced drag, in both flat and non-uniform ground effects also need further investigation. The heaving and pitching frequency and amplitude should follow that of the ocean waves. Estimation of the lift force as a function of ground distance based on the crossflow or vortical wake flow measurements is also highly desired. Finally, non-rectangular wing planforms in ground effect also merit investigation.

5.2 Reverse delta wings

It is known that the reverse delta wing produces a smaller C_L and C_D but a delayed wing stall as compared to the regular delta wing. In contrast to the leading-edge vortex breakdown-induced stall of the delta wing, the stalling of the reverse delta wing (RDW) is triggered by the disruption of the multiple spanwise vortex filaments developed over its upper surface. The strength of the outboard-located RDW trailing vortices also shows a direct correlation to the lift generation of the wing. In ground effect, the lift generation of the reverse delta wing increases with reducing ground distance. At a fixed ground distance, the lift increment is the largest in the low– α regime and decreases rapidly and non-linearly with increasing α . The in-ground-effect distance should be less than 40% of the chord of the reverse delta wing. However, the most effective flight height should be within 10% airfoil chord and at low α as well.

The lift generation of the reverse delta wing in ground effect increases significantly by the addition of stand-alone and joint cropping, anhedral, and Gurney flap. In contrast to the outside ground effect, the application of these passive control is always beneficial. A 270% increase in lift of the reverse delta wing is achieved through joint passive control.

Future experiments on static and unsteady reverse delta wings, with and without flow control, subject to individual and joint heaving and pitching motions over moving flat and nonuniform grounds are needed. The wavelength and amplitude of the ocean waves provide experimental guidelines for the pitching and heaving motions. More studies are desired to correlate the strength of the trailing vortices of the wing to its lift generation and lift-induced drag in ground effect. Nonslender reverse delta wings in ground effect also deserve investigation.

For the regular delta wing in ground effect, the lift and strength of the leading-edge vortices increase as compared to the OGE case. The ground proximity, however, causes an earlier leading-edge vortex breakdown as compared to the outside ground effect. Control techniques capable of delaying the ground proximity-caused premature leading-edge breakdown are highly desired to practicalize the application of delta wings in the WIG craft. Investigation of non-slender delta wings in ground effect is also desired. Unsteady delta wings over both flat and non-uniform ground surfaces also deserve consideration.

Author contributions

All authors listed have made a substantial, direct, and intellectual contribution to the work and approved it for publication.

Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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Nomenclature

a Wave amplitude **b** Wingspan b' Distance between the core of two vortices *c* Airfoil or wing chord C_D Total drag coefficient $C_{D,FB}$ C_D measured with force balance C_d Sectional drag coefficient C_{Di} Lift-induced drag coefficient C_l Sectional lift coefficient C_L Total lift coefficient $C_{L,FB}$ C_L measured with force balance C_m Pitch-moment coefficient C_p Surface pressure coefficient D_i Lift-induced drag f Oscillation frequency in Hz *h* Ground distance *h*_{SES} Gurney flap height *Re* Chord Reynolds number, = Uc/v**U** Freestream velocity, = u_{∞} u_c Vortex core axial velocity v,w Vertical and spanwise velocity v_{θ} Tangential velocity x,y,z Streamwise, vertical, and spanwise direction $y_{cs}z_{c}$ Vertical and spanwise vortex center α Angle of attack δ_A Wing anhedral κ Reduced frequency, = $\pi fc/U$ λ Wavelength Λ Sweep angle

 $\boldsymbol{\zeta}$ Streamwise vorticity ζ_{peak} Peak ζ Γ Circulation $\Gamma_{b,m}$ Root bound circulation measured at the root (z = 0) Γ_c Core circulation Γ_o Total circulation v Kinematic viscosity Abbreviation BA Baseline airfoil **BW** Baseline wing CDGE Chord-dominated ground effect DW Delta wing GEV Ground-effect vehicle GV Ground vortex HDW Half-delta wing IGE In ground effect LEV Leading-edge vortex MG Moving ground MV Main vortex OGE Outside ground effect PIV Particle image velocimetry RDW Reverse delta wing SDGE Span-dominated ground effect SG Stationary ground SGVF Spanwise ground vortex filament SLV Shear-layer vortex SV Secondary vortex SVF Spanwise vortex filament TV Tip vortex WIG Wing-in-ground effect