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SPECIALTY SECTION  
This article was submitted to Solid Earth  
Geophysics,  
a section of the journal  
Frontiers in Earth Science

RECEIVED 11 November 2022  
ACCEPTED 23 January 2023  
PUBLISHED 03 February 2023

CITATION  
Zhang Z, Feng J and Yao H (2023), 3-D  
azimuthal anisotropy structure reveals  
different deformation modes of the crust  
and upper mantle in the southeastern  
Tibetan Plateau.  
*Front. Earth Sci.* 11:1095609.  
doi: 10.3389/feart.2023.1095609

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# 3-D azimuthal anisotropy structure reveals different deformation modes of the crust and upper mantle in the southeastern Tibetan Plateau

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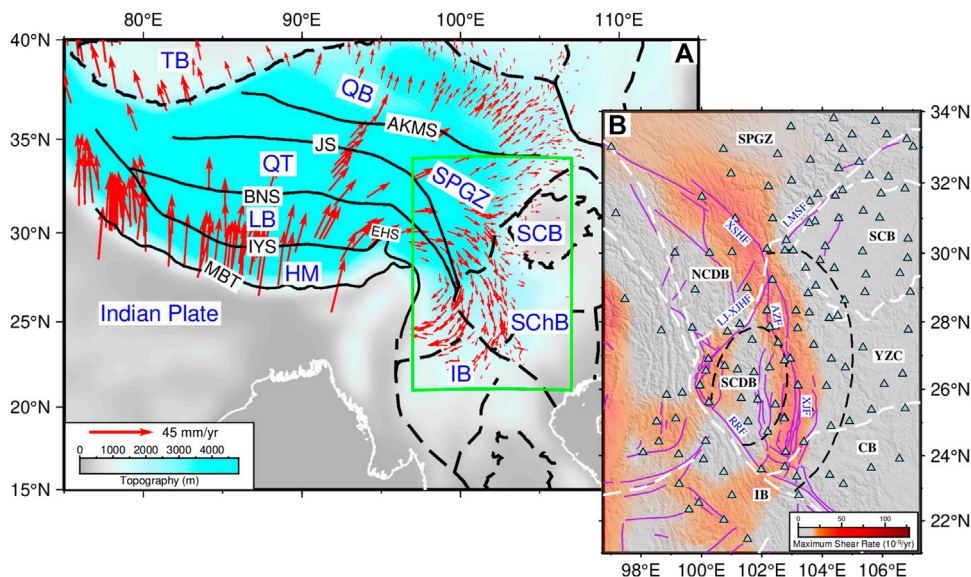
The tectonic evolution and deformation process of the southeastern Tibetan Plateau has been one of the focuses of the geoscience community in recent decades. However, the crustal and mantle deformation mechanism in the southeastern Tibetan Plateau is still under debate. Seismic anisotropy inferred from surface wave tomography could provide critical insights into the deformation mechanism of the Earth's tectonosphere. Here, we constructed a 3-D azimuthal anisotropy velocity model with Rayleigh wave phase velocity dispersion data from 132 permanent stations to analyze the deformation modes in the southeastern Tibetan Plateau. In the upper crust, the azimuthal anisotropy near the main strike-slip faults exhibits strong magnitude with fast axis subparallel to the fault strike, which is consistent with the rigid block extrusion pattern. In the mid-lower crust, two low-velocity anomalies appeared beneath the Sonpan-Ganzi Terrane and Xiaojiang Fault zone with strong azimuthal anisotropy, which may indicate ductile deformation of the weak mid-lower crust. However, the two low-velocity anomalies are separated by a high-velocity barrier with weak azimuthal anisotropy in the inner zone of the Emeishan large igneous province. In the upper mantle, the anisotropy pattern is relatively simple in the rigid Yangtze Craton and mainly represents fossil anisotropy. In the southern part, the lithosphere thinned beneath the Indochina and Cathaysia Blocks, and the anisotropy is plausibly caused by the upwelling and lateral flows of upwelling hot asthenospheric materials.

## KEYWORDS

southeastern Tibetan Plateau, surface wave tomography, azimuthal anisotropy, asthenospheric upwelling, deformation modes

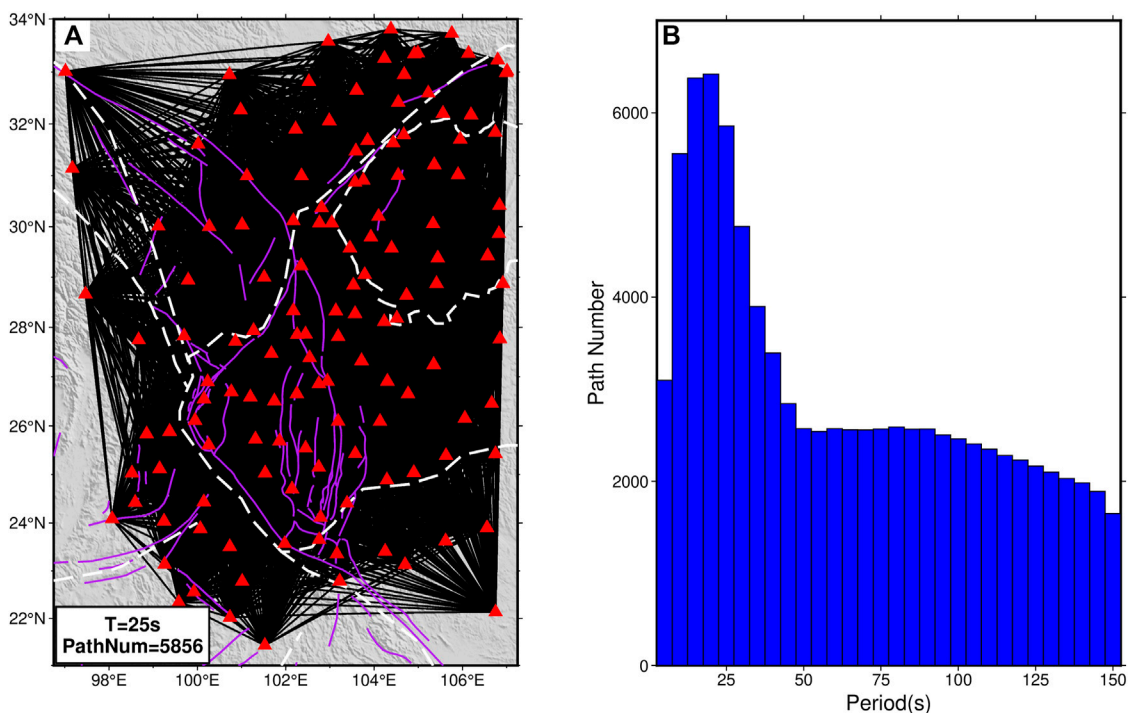
## 1 Introduction

As a result of the India-Asian collision since the Cenozoic (Molnar and Tapponnier, 1975; Rowley, 1996), the lithospheric architecture and the geodynamic process of the Tibetan Plateau and adjacent areas have long been major concerns of the geoscience community. Many models have been proposed to explain the extreme uplift and crustal thickening of the Tibetan Plateau, and two typical models have been widely adopted. One is a rigid block extrusion model that suggests lithospheric materials extruded from the Tibetan Plateau as rigid blocks along strike-slip faults (Tapponnier et al., 1982; England and Houseman, 1986; Tapponnier et al., 2001); another type of model is a mid-lower crustal channel flow model that emphasizes the existence



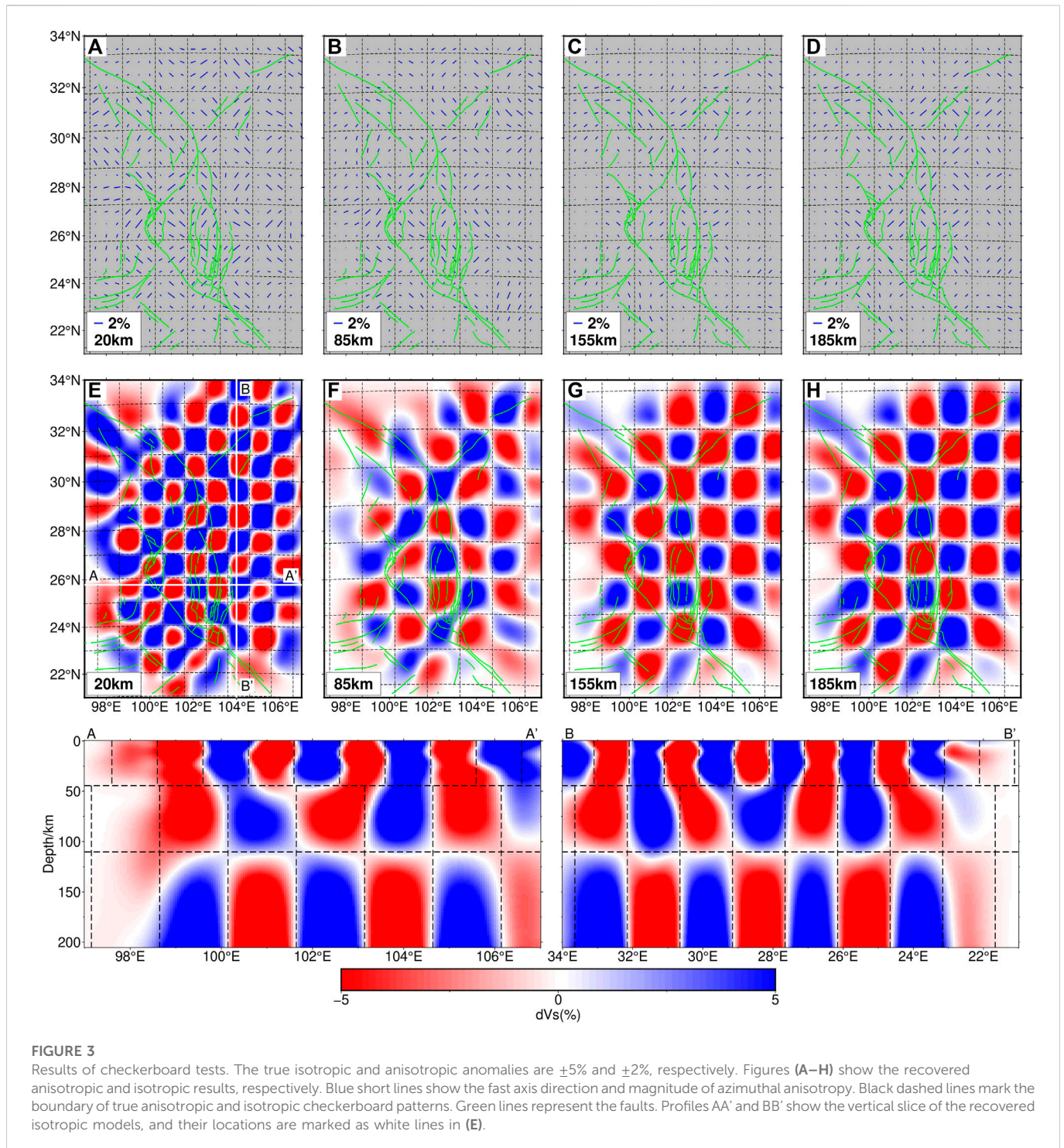
**FIGURE 1**

(A) Geological setting in the Tibetan Plateau. The red arrows exhibit the GPS velocity measurements with respect to a stable Eurasia plate from Zhang et al. (2004). The green box denotes the study area. (B) Station map and geological setting in the southeastern Tibetan Plateau. Light blue triangles mark the distribution of stations. The background color shows the maximum shear rate (modified from Wang and Shen, 2020). Purple lines mark faults: LMSF, Longmenshan Fault; LJ-XJHF, Lijiang-Xiaojinhe Fault; AZF, Anninghe-Zemuhe Fault; XJF, Xiaojiang Fault; RRF, Red River Fault. The black and white lines represent the suture or block boundary. AKMS, Ayimaqin-Kunlun-Muztagh Suture; JS, Jinsha Suture; BNS, Bangong-Nujiang Suture; IYS, Indus-Yarlung Zangbo Suture; EHS, Eastern Himalayan Syntaxis; MBT, Main Himalayan Thrust. TB, Tarim Basin; QB, Qaidam Basin; QT, Qiantang Terrane; LB, Lhasa Terrane; HM, Himalayan Block; SPGZ, Songpan-Ganzi Terrane; SChB, South China Block; SCB, Sichuan Basin; NCDB, North Chuan-Dian Block; SCDB, South Chuan-Dian Block; YZC, Yangtze Craton; CB, Cathaysia Block; IB, Indochina Block. Black dashed lines mark the inner and intermediate zones of the Emeishan large igneous province (Xu et al., 2004).



**FIGURE 2**

(A) Path coverage at a period of 25 s. The red triangles represent stations. "T" is the period, and "PathNum" is the path number at the corresponding period. (B) Number of paths of each period.



of low-viscosity channels in the mid-lower crust facilitating effective crustal material migration (Royden et al., 1997; Clark and Royden, 2000; Beaumont et al., 2001). As a significant weak window for material migration away from the Tibetan Plateau interior (Figure 1), the southeastern margin of the Tibetan Plateau plays an important role in understanding the tectonic evolution and material extrusion of the Tibetan Plateau.

The southeastern Tibetan Plateau consists of several blocks, including the Songpan-Ganzi Terrane in the north, the stable Yangtze Craton, the Cathaysia Block in the east, the Indochina

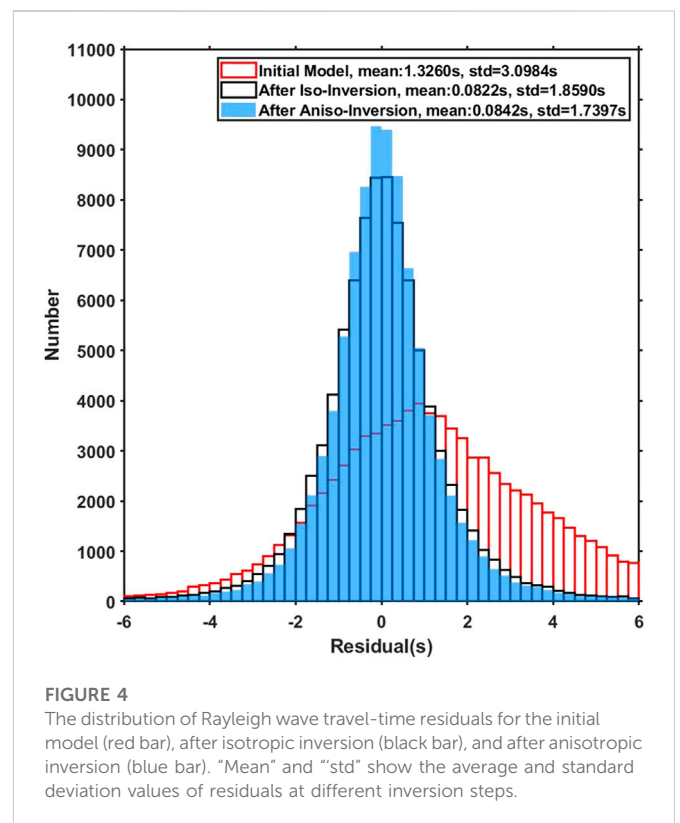
Block in the south and the Chuan-Dian Block (Figure 1). Field observations suggest that this area is dominated by strike-slip faults such as the Xianshuihe-Xiaojiang Fault and Red River Fault and lacks large-scale crustal shortening (Royden et al., 1997; Burchfiel and Chen, 2013). GPS data show clockwise rotational movement of the surface in this area and a strong shear strain rate along the main strike-slip faults (Figure 1) (King et al., 1997; Chen et al., 2000; Zhang et al., 2004; Wang and Shen, 2020).

To investigate the subsurface structure of the southeastern Tibetan Plateau, many tomography studies have been performed in recent

decades and have obtained many important results. Two significant low-velocity anomalies (Yao et al., 2008; Bao et al., 2015; Zhang et al., 2020; Han et al., 2022) with high conductivity (Bai et al., 2010; Li et al., 2019) and high seismic attenuation (Zhao et al., 2013; Dai et al., 2020) have been detected in the mid-lower crust by seismic and magnetotelluric tomography. The two low-velocity anomalies are separated by a high-velocity anomaly located in the South Chuan-Dian Block (Bao et al., 2015; Xu et al., 2015; Qiao et al., 2018; Yang et al., 2020; Zhang et al., 2020; Han et al., 2022). This crustal high-velocity anomaly is likely related to an ancient mantle plume that formed the Emeishan large igneous province (ELIP) in the western Yangtze Craton (black dashed line in Figure 1) (Chung and Jahn, 1995; Xu et al., 2001; Lo et al., 2002; He et al., 2003; Xu et al., 2004). In the Indochina and Cathaysia Blocks, significant lithospheric thinning and low-velocity material upwelling have been revealed by receiver functions (Yang et al., 2017) and seismic wave tomography (Li et al., 2008; Huang Z. C. et al., 2015; Lei and Zhao, 2016; Huang et al., 2019).

Although large-scale mid-lower crustal low-velocity anomalies beneath the southeastern Tibetan Plateau have been confirmed, their spatial distribution and associated deformation mechanisms between the crust and upper mantle are still under debate. Seismic anisotropy is the dependence of seismic velocity on direction or upon angle (Thomsen, 2014), which is closely related to the regional stress distribution. Compared to isotropic velocity structures, anisotropic structures can provide crucial information about tectonic deformation.

Therefore, seismic anisotropy studies are needed to further investigate the deformation features and regional tectonic processes in the southeastern Tibetan Plateau (e.g., Crampin, 1981; Savage, 1999; Weiss et al., 1999; Mainprice et al., 2005). Teleseismic XKS shear-wave splitting observations revealed two distinct anisotropy patterns in this area (Lev et al., 2006; Chang et al., 2008; Chang et al., 2015). The fast axis is oriented NW–SE or nearly N–S north of 26°N but suddenly changes to nearly E–W south of 26°N. Shear-wave splitting from Pms (Chen et al., 2013; Kong et al., 2016; Han et al., 2020) and local earthquakes (Shi et al., 2012), which is sensitive to crustal anisotropy, shows fault-parallel fast direction and is almost perpendicular to the fast direction inferred from teleseismic shear-wave splitting south of 26°N (Huang Z. et al., 2015; Chang et al., 2015). All these shear-wave splitting results indicate a complicated, laterally varied and depth-dependent deformation mechanism in the southeastern Tibetan Plateau. However, it is very difficult to evaluate the depth range of the anisotropy source due to the relatively poor depth resolution of shear-wave splitting data (e.g., Savage, 1999). Seismic anisotropy inverted from surface waves is a powerful tool to analyze tectonic deformation and the source location of anisotropy (Yao et al., 2010). Several surface wave tomography studies have been performed in the southeastern Tibetan Plateau and have revealed strong variations in the depth of the anisotropy pattern (e.g., Liu et al., 2019; Bao et al., 2020; Liang et al., 2020; Han et al., 2022). All these azimuthal anisotropy models show nearly N-S fast axis directions or are parallel to the strike of faults in the upper crust, while the strong anisotropy area is overall consistent with the low-velocity area in the mid-lower crust. However, the fast axis of the model from Liu et al. (2019) is nearly the E-W direction in the upper mantle, similar to the teleseismic shear wave splitting results, the fast axis direction is



still nearly N-S in the other three models (Bao et al., 2020; Liang et al., 2020; Han et al., 2022). Although there are some anisotropy models of SE Tibet derived from body/surface wave tomography (Wei et al., 2013; Han et al., 2022) that are down to the asthenosphere, the depth range of most previous studies was mainly concentrated in the crust or uppermost mantle and cannot constrain the whole lithospheric mantle or asthenosphere.

In this paper, we use Rayleigh wave phase velocity dispersion data collected from permanent stations in the southeastern Tibetan Plateau and apply a direct inversion method (Liu et al., 2019) to invert the 3-D shear wave velocity structure and azimuthal anisotropy from the crust to the upper mantle (<200 km). Then, we carefully discuss the azimuthal anisotropy patterns and the corresponding tectonic deformation, especially for the depth distribution of anisotropy sources.

## 2 Data and methods

We measured the phase velocity dispersion curves in the period range of 5–150 s from ambient noise cross-correlations (Yang et al., 2020) and teleseismic waveforms recorded by 132 permanent stations (Figure 1) in the southeastern Tibetan Plateau (Zheng et al., 2010). Finally, we obtained 7,441 phase velocity dispersion curves in total. Figure 2 shows the ray path coverage at 25 s and the ray path number at each period (Ray path coverage at other periods and the distribution of teleseismic events used are shown in Supplementary Figure S1). The ray path number at the short and intermediate periods (5–50 s) increases dramatically after adding the dispersion measurements from ambient noise data.

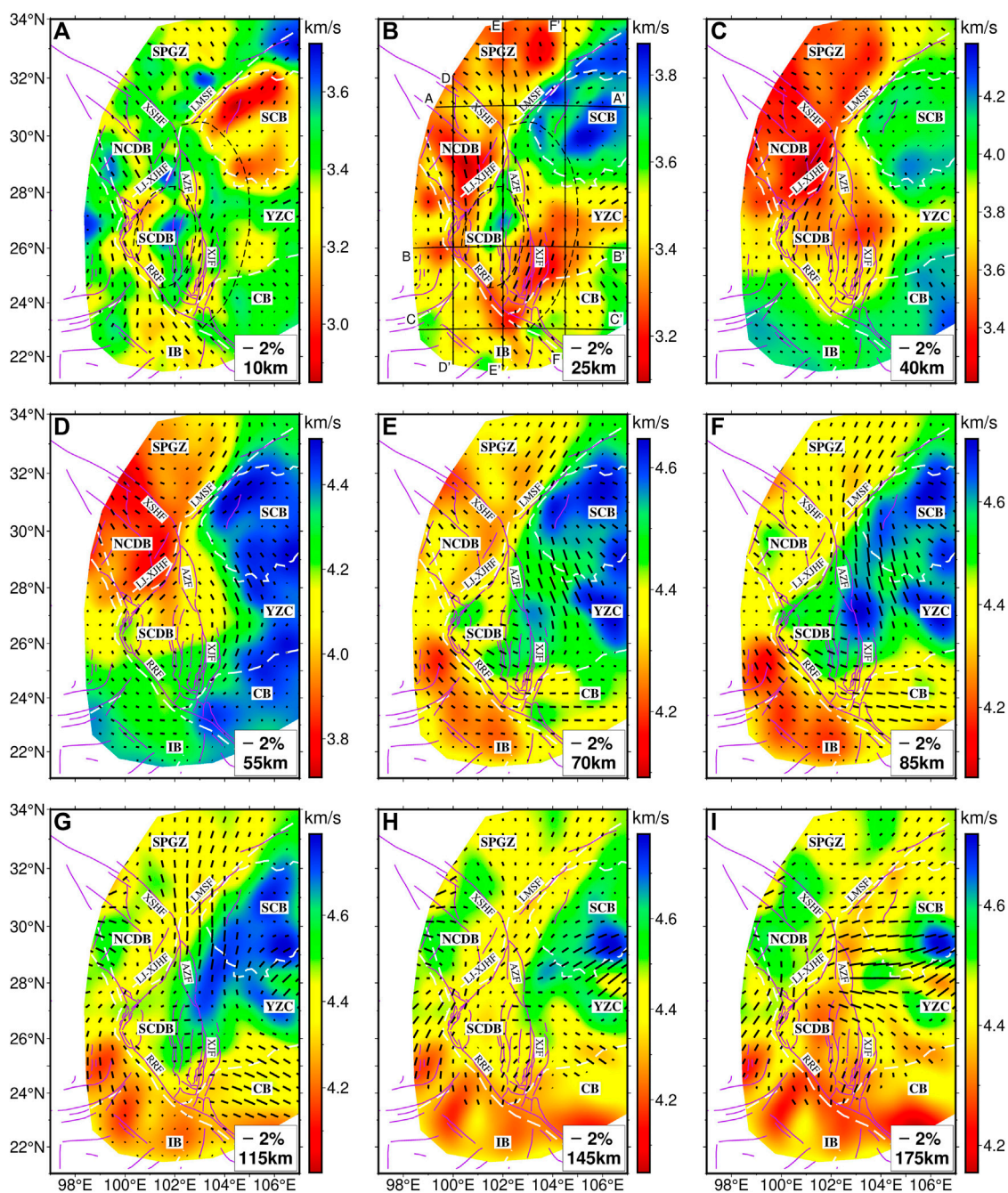


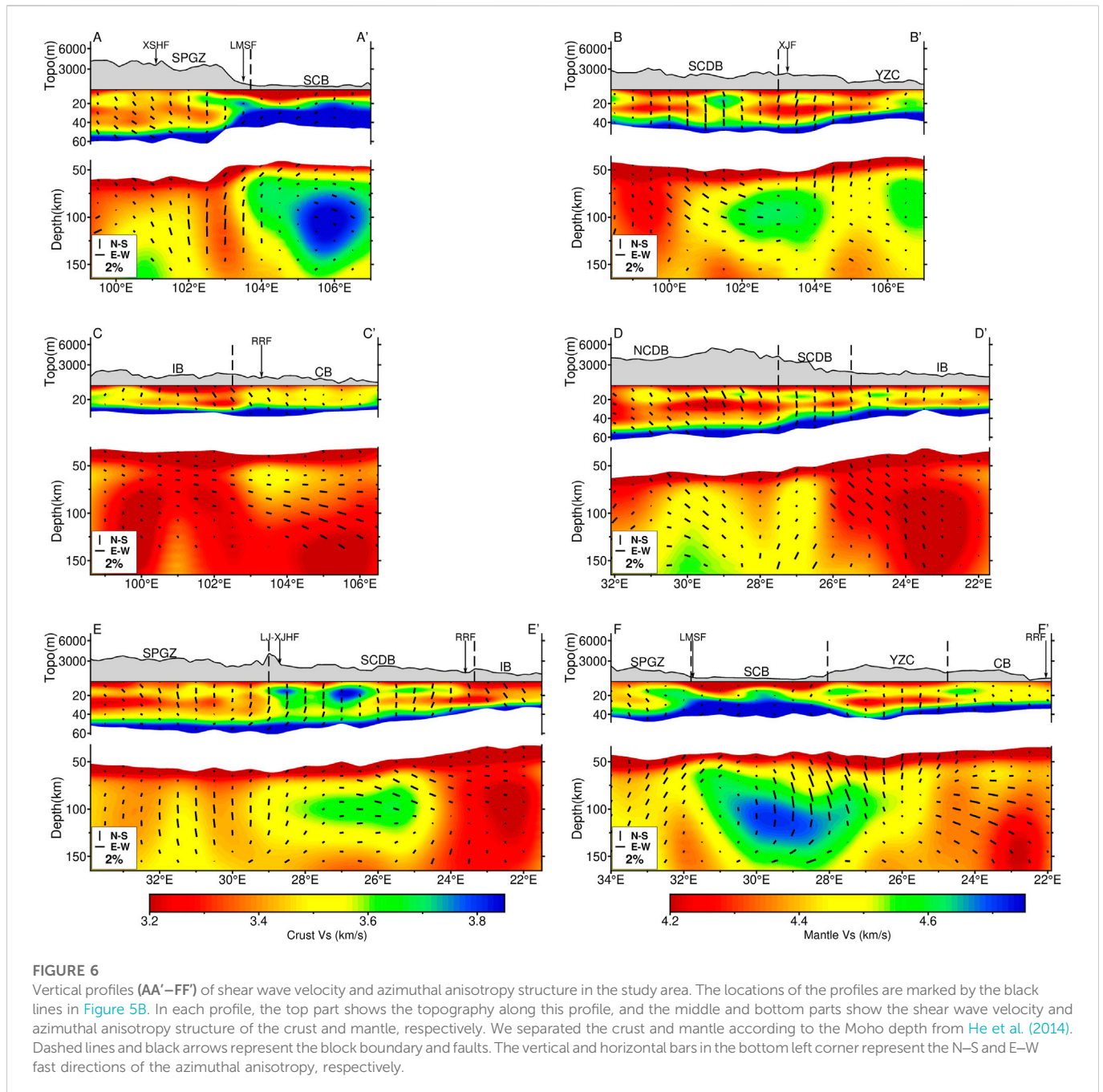
FIGURE 5

Map views of the 3-D shear wave velocity and azimuthal anisotropy structure at different depths. (A–I) Purple lines and white dashed lines are the faults and block boundaries, respectively (the abbreviations of faults and blocks are the same as Figure 1). Short black lines represent the azimuthal anisotropy. Black dashed lines mark the inner and intermediate zones of the Emeishan large igneous province.

At intermediate to long periods (50–150 s), the ray path number is approximately 2,000 and exhibits good azimuthal coverage in the center study area. The phase velocity dispersion data utilized in this study are the same as in our previous work (Zhang et al., 2020), for more data details, please refer to this paper and Supplementary Figure S2.

We used the direct inversion method proposed by Liu et al. (2019) to directly invert the 3-D shear wave velocity structure and azimuthal anisotropy in southeastern Tibetan Plateau from Rayleigh wave phase

velocity dispersion measurements. The direct inversion method has two obvious advantages: (1) The direct inversion method is based on a 3-D velocity structure with lateral and vertical model smoothness; (2) the forward calculation of the direct inversion method is based on the fast-marching ray-tracing method (Rawlinson and Sambridge, 2004), so it can consider the frequency-dependent ray-bending effect of surface waves and efficiently improve the inversion accuracy. Typically, the azimuthally anisotropic velocity perturbations are within several percent, so a reliable initial velocity model is needed



to ensure the convergence of the inversion for azimuthal anisotropy. Therefore, the procedure of the direct inversion method is divided into two parts: (1) first, we inverted only the 3-D isotropic shear wave velocity model directly from Rayleigh wave phase travel times (Fang et al., 2015); (2) then, we adopted the isotropic shear wave velocity model obtained in the first step as the initial model to invert the 3-D isotropic shear wave velocity and azimuthal anisotropy simultaneously.

We inverted the crust and upper mantle (0–200 km at depth) 3-D shear wave velocity and azimuthal anisotropy structure in the study area according to the period range of dispersion data (5–150 s). We took the smoothed SWChinaVs\_2018 model from Yang et al. (2020) as the initial crustal model ( $\leq 50$  km) and used the ak135 model (Kennett et al., 1995) as the initial

mantle part model. We divided the crust and mantle parts according to the Moho depth from previous studies (He et al., 2014), therefore, our initial velocity model included the Moho depth information. We use such an initial model to avoid the inaccuracy in the crust broadcast to the upper mantle in the inversion and try to ensure that the inversion result in the upper mantle is mainly restricted by the data. The grid size of the initial model is  $0.5^\circ \times 0.5^\circ$  in the horizontal direction and has variable intervals in the vertical direction considering the decreasing resolution of the surface wave with increasing depth. The grid interval in the depth, therefore, is 5 km from 0 to 70 km depth, 7.5 km from 70 to 115 km depth, and 10 km from 115 to 185 km depth. The weight (smoothing) parameters of isotropic and anisotropic were both subjectively set to 20 after many attempts.

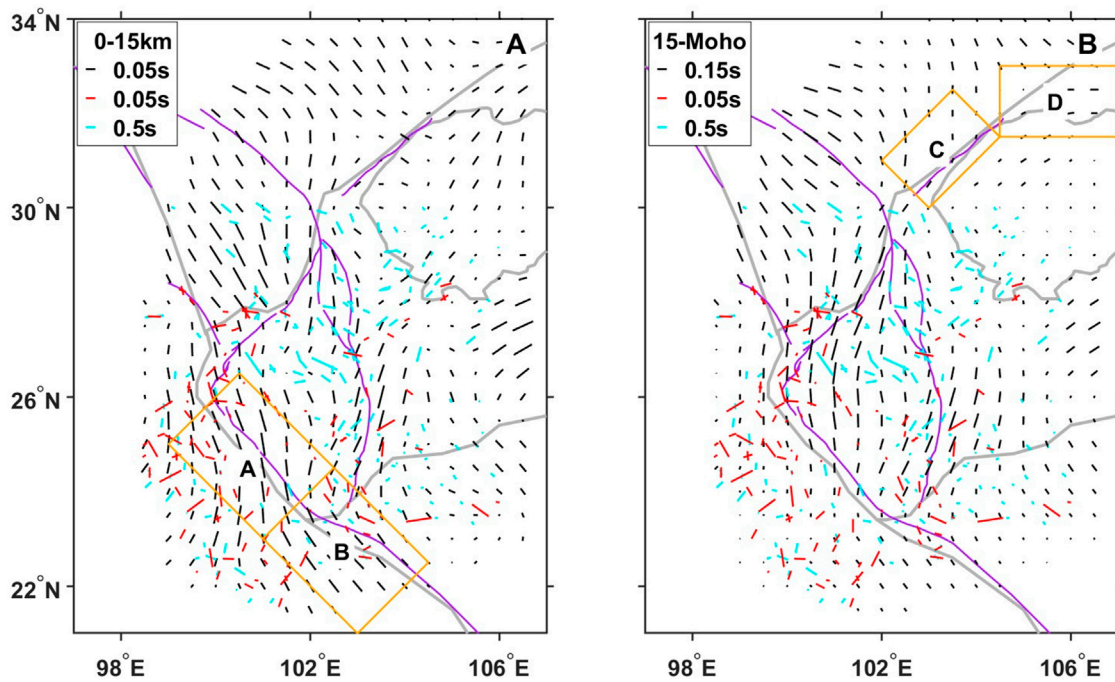


FIGURE 7

The comparison between the predicted shear wave splitting parameters (black bars) from our velocity model and the observed shear wave splitting parameters from local events (red bars) and Pms phase data (light blue bars) at upper crust (A) and mid-lower crust (B). The purple and gray lines represent the main fault and block boundary, respectively. The Moho depth is from He et al. (2014).

## 3 Results

### 3.1 Checkerboard test

We performed checkerboard tests to estimate the data coverage and resolution of the direct inversion method. The checkerboard size of the isotropic model is  $1^{\circ} \times 1^{\circ}$  above 50 km depth and  $1.5^{\circ} \times 1.5^{\circ}$  beneath 50 km depth. The checkerboard size of the anisotropic model is  $1.5^{\circ} \times 1.5^{\circ}$  at all depths. Both isotropic and anisotropic checkerboard models are depth dependent, and the pattern reverses after a depth of 107.5 km. We added 1% and 0.5% Gaussian random noise to the synthetic travel-time data calculated from the isotropic model and anisotropic model, respectively. Other parameters are the same as those in the inversion.

The recovered result is good in the central study area but relatively poor in the western and southern margins, especially for the anisotropic pattern (Figure 3). The isotropic checkerboard pattern can be well recovered in most of the study area except in the northwest corner and west of  $99^{\circ}\text{E}$ . For the anisotropic checkerboard model, the area that can be recovered is almost the same as the isotropic results at shallow depths ( $\leq 85$  km). At deep depths ( $> 85$  km), the recovered anisotropic results are relatively poor at the margin of the study area but still show good resolution in the central area (approximately between  $99^{\circ}\text{E}$ – $106^{\circ}\text{E}$  and  $24^{\circ}\text{N}$ – $32^{\circ}\text{N}$ ). Both isotropic and anisotropic checkerboard tests suggest high resolution in the central area but low resolution in the western margin.

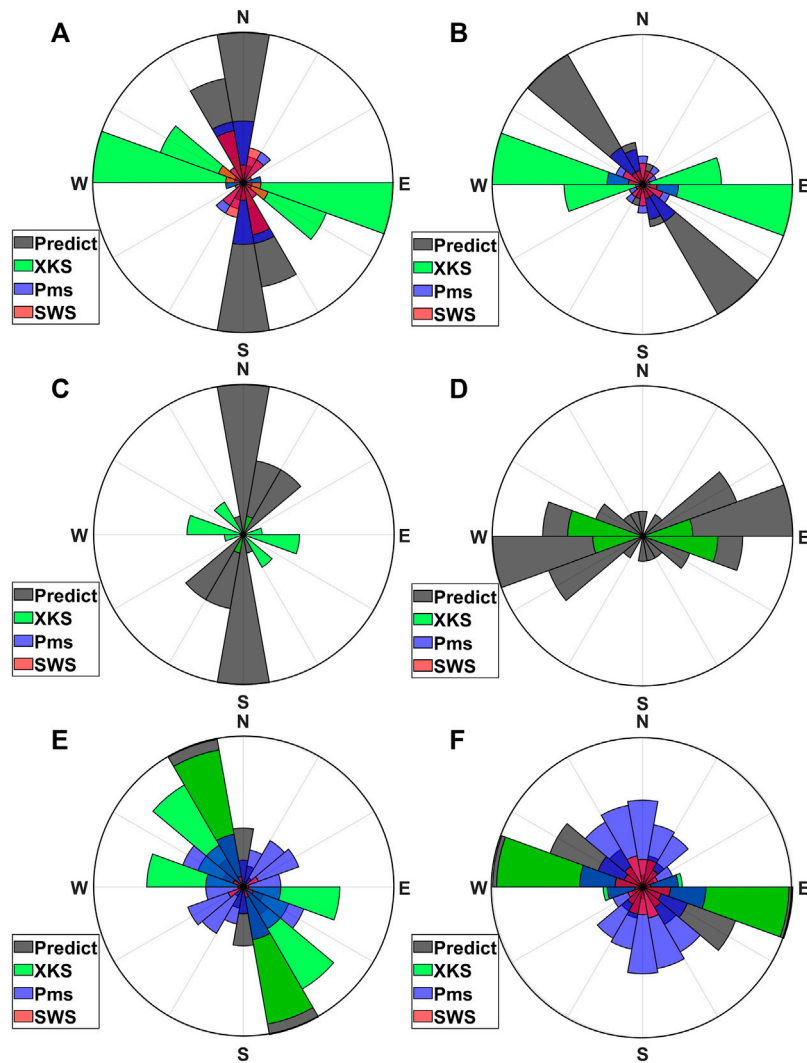
Three resolution synthetic tests were performed to demonstrate the trade-off between isotropic and anisotropic structures and the robustness of our inversion (Supplementary Figures S3–S7). The synthetic test results show good reliability of the isotropic and

anisotropic patterns. However, the resolution of anisotropic structure in the southern part of the study area is not good in the deep part. Therefore, we eliminated the west margin of the inverted model, and the anisotropic structure south of  $24^{\circ}\text{N}$  was not shown below 135 km depth (Figures 5H–I).

### 3.2 Isotropic shear wave velocity and azimuthal anisotropy structure

The residual distribution results show good convergence after inversion (Figure 4). The average and standard deviation values of residuals exhibit a significant decrease after isotropic inversion. After anisotropic inversion, the standard deviation value of the data residuals further decreases. Although the average value of the data residuals shows a slight increase after anisotropic inversion, it ( $\sim 0.08$  s) is only approximately 0.05% of the average surface travel time ( $\sim 153$  s) and is negligible within the measurement uncertainty (approximately 0.5%–1%) (Yao and van der Hilst, 2009).

Our 3-D isotropic shear wave velocity and azimuthal anisotropy structure demonstrate strong lateral contrast at given depths (Figure 5). At a depth of 10 km, there are two significant low-velocity anomalies in the northwestern and southeastern parts of the Sichuan Basin, and other areas mainly show relatively high-velocity anomalies except the fault zones. The magnitude of azimuthal anisotropy is relatively weak in the Yangtze Craton and Cathaysia Block. The fast axis is NW–SE in the Songpan–Ganzi Terrane and subparallel to the strike of the Xiaojiang Fault zone at a depth of 10 km.



**FIGURE 8**

Rose diagram of the fast axis direction (A–F) of the predicted (black bars) and the observed data from XKS phase data (green bars), Pms phase data (blue bars) and local events (red bars) at different areas marked in Figure 7 and Figure 9 by orange boxes. The depth range of the predicted fast axis direction is the same as the corresponding depth range of Figure 7 and Figure 9.

The velocity pattern is almost reversed at 25 km depth. The Sichuan Basin is represented by a high-velocity anomaly, and two low-velocity anomalies appear beneath the Songpan-Ganzi Terrane, North Chuan-dian Block and Xiaojiang Fault zone. However, the two low-velocity anomalies are separated by an obvious high-velocity anomaly in the inner zone of the ELIP. The two low-velocity anomalies exhibit strong azimuthal anisotropy with a fast axis direction nearly parallel to the strikes of the two low-velocity anomalies. In contrast, weak azimuthal anisotropy is observed in the high-velocity area in the inner zone of the ELIP.

Large-scale low-velocity anomalies appear in the Songpan-Ganzi Terrane, South Chuandian Block and west margin of the Yangtze Craton at 40 km depth, whereas high-velocity anomalies appear in the Indochina Block and Cathaysia Block. In the low-velocity area, the magnitude of anisotropy is strong, and the fast axis direction is parallel to the strike of major faults (e.g., Lijiang-Xiaojinhe Fault, Longmenshan Fault and Xiaojiang Fault)

but becomes relatively weak in the area with high-velocity anomalies.

The velocity structure at 55 km depth basically represents the upper mantle in most regions featured by high velocities except the Songpan-Ganzi Terrane, where the low velocities characterize the lower crust. The fast axis direction is NW–SE in the Songpan-Ganzi Terrane and North Chuan-dian Block, but it is changed to NE–SW when it reaches the Longmenshan Fault. It is worth noting that the azimuthal anisotropy becomes strong with NW–SE or nearly N–S fast axis direction in the Yangtze Craton.

Beneath 70 km depth, a low-velocity anomaly appears in the Indochina Block and gradually extends to the Cathaysia Block in the east at 115 km depth and then extends northward to the South Chuandian Block along the Xiaojiang Fault at approximately 175 km depth. South of 26°N, the fast axis direction of anisotropy is E–W at 70 km depth but becomes very weak in the Indochina Block with increasing depth. The fast axis



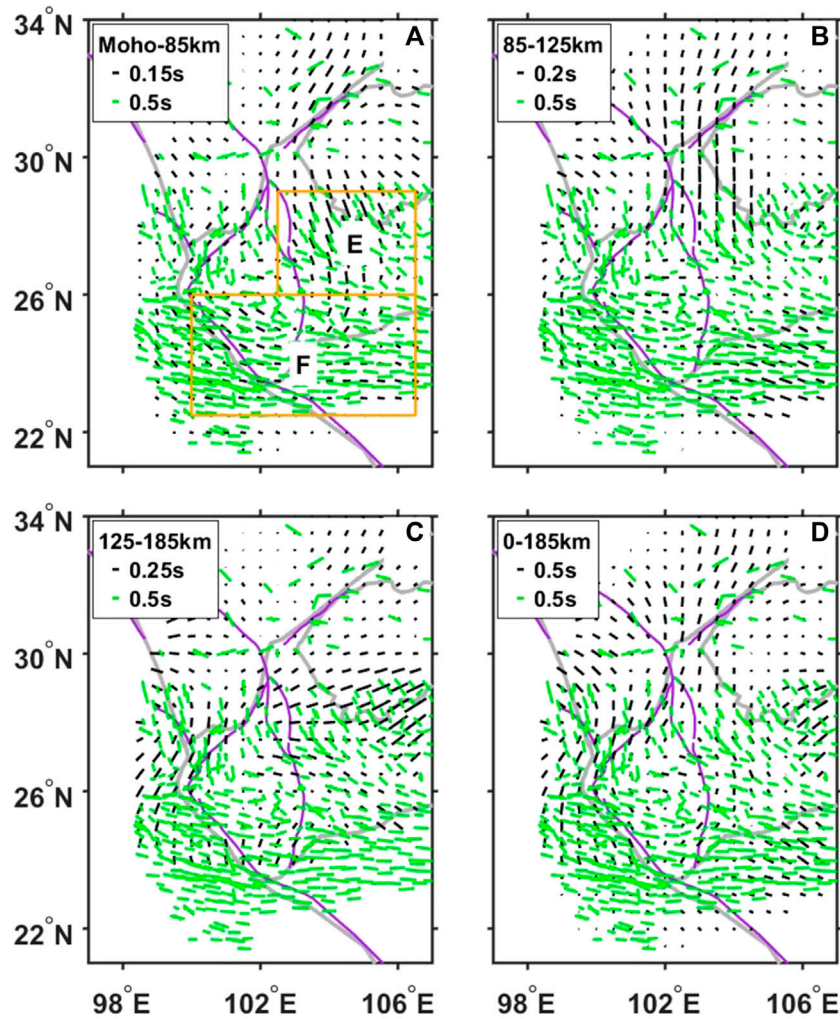


FIGURE 9

Same as Figure 7, but green bars represent the observed shear wave splitting parameters from the XKS phase data in (A–D).

direction of anisotropy is NW–SE or nearly N–S north of 26°N between 70 km and 110 km depths but gradually rotates to NE–SW below 115 km depth.

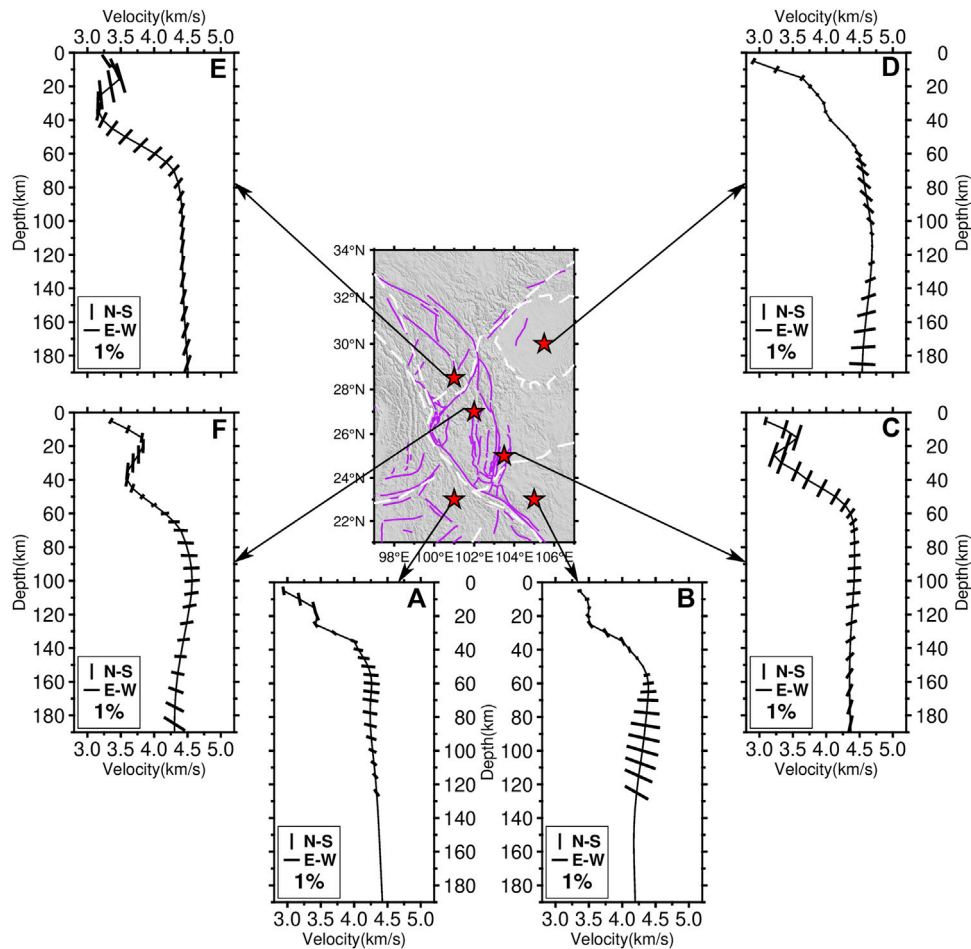
To further show the depth variation of our velocity model, we plotted six vertical profiles (Figure 6). The locations of these profiles are marked in Figure 5B. We notice a strong high-velocity body with weak anisotropy in the Sichuan Basin that extends downward to approximately 185 km depth in profiles AA' and FF'. Two significant low-velocity anomalies with strong azimuthal anisotropy can be observed from most profiles except profile CC' between 20 and 40 km depth. However, these two low-velocity anomalies are separated by the high-velocity anomaly in the South Chuandian Block in the middle-lower crust, as shown in profiles BB' and EE' and the high-velocity anomaly seems to extend downward to approximately 140 km depth. In profiles CC' to FF', we can observe large-scale low-velocity anomalies with nearly E–W fast axis directions in the mantle beneath the Indochina Block and Cathaysia Block. The low-velocity anomaly then extends northward to the South Chuandian Block at approximately 150 km depth, but the magnitude of anisotropy becomes weak beneath with increasing depth in the Indochina Block.

## 4 Discussion

### 4.1 Comparison with shear wave splitting data

Many shear wave splitting results have been applied in the southeastern Tibetan Plateau to understand its lithospheric and asthenospheric deformation (Sun et al., 2012; Huang Z. et al., 2015; Chang et al., 2015; Zheng et al., 2018). The poor vertical resolution of shear wave splitting results makes it difficult to determine the location of the anisotropy source, although it can provide a wide depth range by some methods (e.g., Chevrot, 2000; Chevrot, 2006; Monteiller and Chevrot, 2011). By contrast, the depth-dependent seismic anisotropy inferred from surface wave tomography can provide depth information for the anisotropy source. Here, we used our 3-D shear wave velocity model to calculate the predicted shear wave splitting parameters at different depth ranges (Montagner et al., 2000) and compared them with the observed data.

To analyze the contribution of crustal and upper mantle (<200 km) anisotropy to the shear wave splitting results, we compared the predicted shear wave splitting parameters from the crust and upper mantle (<200 km), respectively, with the observed



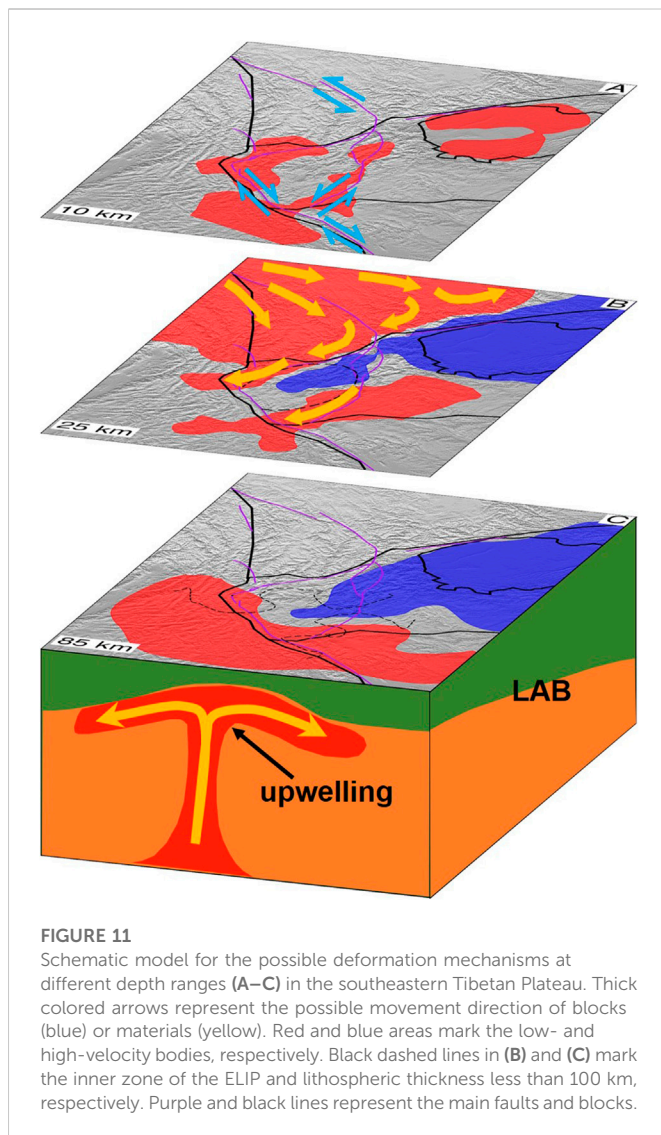
**FIGURE 10**

Shear wave velocity and azimuthal anisotropy varied with depth at six locations (A–F) marked by the red stars in the study area. Azimuthal anisotropy is not shown below 135 km depth in (A) and (B) due to lack of resolution south of 24°N.

values (Figures 7–9). The quantitative differences between the predicted and observed data are shown in Supplementary Figures S8–S10. The observed shear wave splitting parameters we compared in the crust are inverted from local events (Zhang and Gao, 2017; Zhang et al., 2018) and Pms phase data (Sun et al., 2012; Cai et al., 2016; Zheng et al., 2018), which are mainly sensitive to crustal anisotropy. The observed data from the XKS phase (Chang et al., 2008; Chang et al., 2015; Chang et al., 2017), representing the integrated effect of anisotropy along the ray path, were compared with the upper mantle anisotropy (<200 km) inferred from surface wave tomography. The predicted and observed parameters from local events and Pms phase data show a certain coherence in the crust (Figure 7; Figures 8A, B). However, the predicted anisotropy in the upper layer (0–15 km, Figure 7A) is smaller than that in the lower layer (15–Moho, Figure 7B) of the crust, which agrees with the splitting parameters based on two-layered model analysis in the crust (Han et al., 2020). These results also indicate different deformation mechanisms between the upper and mid-lower crust. The deformation in the mid-lower crust is more intense and is the main anisotropy source of the observed crustal shear wave splitting. The predicted crustal shear wave splitting parameters show large differences from the observed parameters based on

XKS phase data (Figures 8A–D), which suggests different deformation patterns in the crust and upper mantle.

Within the upper mantle (Moho–125 km), the predicted splitting parameters are consistent with the observed splitting parameters based on XKS phase (Figures 8E, F; Figures 9A, B). However, the predicted and observed splitting parameters are quite different in the Yangtze Craton near the lithosphere–asthenosphere boundary (125–185 km, Figure 9C), which suggests that the deeper part of the upper mantle (125–185 km) may experience other complicated deformation processes. Overall, the predicted fast axis direction is similar to the observed teleseismic shear wave splitting results in most of the study area, and the magnitude of anisotropy is also comparable (Figure 9D). These results suggest that the main anisotropy source above 185 km depth is from the lithospheric mantle north of 26°N and the asthenosphere south of 26°N. The azimuthal anisotropy in the upper mantle (<200 km) has a significant contribution to the observed shear wave splitting parameters based on the XKS phase. However, considering the depth range in our study and the approximations when we calculate the predicted shear wave splitting data, further study about the contribution of the anisotropy source in a deeper depth range is needed.



**FIGURE 11**  
Schematic model for the possible deformation mechanisms at different depth ranges (A–C) in the southeastern Tibetan Plateau. Thick colored arrows represent the possible movement direction of blocks (blue) or materials (yellow). Red and blue areas mark the low- and high-velocity bodies, respectively. Black dashed lines in (B) and (C) mark the inner zone of the ELIP and lithospheric thickness less than 100 km, respectively. Purple and black lines represent the main faults and blocks.

## 4.2 The deformation mechanism in the crust

Our 3-D isotropic shear wave velocity and azimuthal anisotropy structure show evident variation with respect to depth. The fast axis is oriented NW–SE in the Songpan-Ganzi Terrane and North Chuandian Block, which is mainly due to the southeastward extrusion of the crust in this area. As a result, GPS observations indicate that the traces of the Lijiang-Xiaojinhe Fault and Red River Fault have been distorted by crustal movements (Gan et al., 2022). Our results show distinct patterns of the fast axis direction along the Red River Fault (Figure 7A; Figures 8A, B). The fast axis is nearly N–S in the northwest part of the Red River Fault (Figure 8A), which is mainly caused by southward crustal movement. However, the fast axis changes to the NW–SE direction in the southeastern part of the Red River Fault within our study area (Figure 8B), which probably represents the fossil anisotropy reformed by the episodic strike-slip of the fault in the Cenozoic. The shear wave splitting parameters from local events (Zhang and Gao, 2017; Zhang et al., 2018) and the Pms phase (Sun et al., 2012; Cai et al., 2016; Zheng et al., 2018) also show similar results (Figures 8A, B). The central area of the South Chuandian Block shows high velocity and weak anisotropy

(Figure 10F), but the azimuthal anisotropy is strong and shows a fault-parallel fast axis direction in the boundary of the South Chuandian Block (Figure 10C, F), which indicates that the deformation within the upper crust is concentrated at the block boundary and faults.

In the mid-lower crust (approximately 25–40 km depth, Figures 5B, C), two obvious low-velocity anomalies appear in the Songpan-Ganzi Terrane and east of the Xiaojiang Fault. Previous studies (Yao et al., 2008; Yao et al., 2010; Bao et al., 2015; Chen et al., 2016; Qiao et al., 2018) have also observed two low-velocity anomalies and attributed them to the extrusion of viscous material flows from the central Tibetan Plateau. However, there is a high-velocity body in the South Chuandian Block that separates these two low-velocity anomalies. The high-velocity body in the South Chuandian Block is also confirmed by other data and methods (Bao et al., 2015; Qiao et al., 2018; Dai et al., 2020; Li et al., 2020; Yang et al., 2020; Han et al., 2022). This high-velocity body is located in the inner zone of the ELIP and may be at the lithosphere scale (Profiles BB' and EE' in Figure 6), which is speculated to be related to magma intrusion and underplating when the ELIP formed (Chen et al., 2015; Xu et al., 2015). The fast axis is nearly in the N–S direction west of the South Chuandian Block but suddenly becomes weak in the inner zone of the ELIP and agrees well with the teleseismic shear-wave splitting result (Li et al., 2021). The high-velocity and weak azimuthal anisotropy feature in the inner zone of the ELIP is also confirmed by a new surface wave tomography result based on temporary stations (Han et al., 2022). The weak anisotropy in the northeast corner of the South Chuandian Block further demonstrates the resistance effect of the ELIP and the disconnection of the two low-velocity anomalies in this area. The obstruction of a high-velocity anomaly within the ELIP may cause strong deformation localized along the margins of the South Chuandian Block and then transfer further to the XJF (Han et al., 2022). Receiver function results (Wang et al., 2017) suggest that the crust thickened near the XJF. Therefore, we prefer that the low-velocity anomaly east of the XJF is most likely caused by *in situ* plastic deformation and/or partial melting (Zhang et al., 2020) due to crustal thickening and strong deformation. The fast axis direction in these two low-velocity anomalies is subparallel to the trend of low-velocity anomalies (Figures 10C, F) and consistent with the local shear wave splitting results (Zhang and Gao, 2017; Zhang et al., 2018) and receiver functions (Sun et al., 2012; Cai et al., 2016; Zheng et al., 2018) (Figure 7B). The fast axis direction may indicate the migration direction of the low-velocity material. Notably, the fast axis is bifurcated near the Sichuan Basin; it is nearly N–S in the northwest margin of the Sichuan Basin but nearly E–W in the north margin (Figure 8C, D). This anisotropy pattern is also confirmed by other high-resolution surface wave tomography results (Zhang et al., 2022) and demonstrates the obstruction of the rigid Sichuan Basin for low-velocity material migration.

At 40 km depth, most areas are already in the mantle except the Chuandian Block and Songpan-Ganzi Terrane due to crustal thickening (Wang et al., 2017; Cheng et al., 2022). The azimuthal anisotropy is very strong in the low-velocity anomaly areas but becomes weak in the high-velocity anomaly areas (Figure 5C), which suggests that the lower crustal deformation pattern in the Chuandian Block and Songpan-Ganzi Terrane is still controlled by the deformation and/or migration of low velocities but obstructed by the rigid uppermost mantle in other areas.

Our azimuthal anisotropy pattern suggests different deformation mechanisms within the upper and mid-lower crust. The fast axis direction near the Lijiang-Xiaojinhe Fault, for instance, is almost perpendicular to the fault in the upper crust but soon changes to subparallel to the fault in the mid-lower crust (Figure 10E). Therefore, we prefer that the upper crustal azimuthal anisotropy in the southeastern Tibetan Plateau is dominated by large fault systems, and therefore, the magnitude of anisotropy is often weak in the center of blocks (Figures 10A–C), which agrees well with the main features of the rigid block extrusion model (Tapponnier et al., 1982; Tapponnier et al., 2001). In the mid-lower crust, the magnitude of azimuthal anisotropy is very strong in the two low-velocity anomalies but very weak in the high-velocity anomaly, and the faults are the main boundary of the velocity and anisotropy pattern. Therefore, the mid-lower crust in the southeastern Tibetan Plateau is more likely to undergo significant ductile deformation (Royden et al., 1997; Clark and Royden, 2000; Beaumont et al., 2001), and the migration of low-velocity material flows is bounded by faults.

### 4.3 The deformation mechanism in the upper mantle

Our results reveal an anisotropy pattern in the upper mantle (<200 km) that is distinct from that in the crust. At depths of 40–55 km, the velocity model mainly represents the uppermost mantle in the Yangtze Craton, Cathaysia Block, and Indochina Block. The azimuthal anisotropy is nearly N–S in the Yangtze Craton but very weak in the Indochina Block and Cathaysia Block, which indicates a rigid uppermost mantle and lack of deformation in the last two blocks. Below 70 km depth, the whole study area is in the upper mantle, and the anisotropy pattern is divided into two parts. North of 26°N, the fast axis is in the NW–SE or nearly N–S direction with a high shear wave velocity anomaly, but the direction rapidly changes to the E–W direction south of 26°N with a significant large-scale low-velocity anomaly (Figures 5E–I; Figures 10A, B). The anisotropy pattern in the upper mantle is in good agreement with the XKS splitting results (Chang et al., 2008; Huang Z. et al., 2015; Chang et al., 2015) (Figure 9). In the Yangtze Craton, the fast axis is oriented nearly N–S with a very high-velocity anomaly. Considering that the lithospheric thickness of the Yangtze Craton is more than 120 km and can even reach approximately 200 km under the Sichuan Basin (Pasyanos et al., 2014; Yang et al., 2017), we prefer it to reflect the fossil anisotropy of the rigid lithosphere.

Receiver function results (Hu et al., 2012; Yang et al., 2017) suggest that the lithospheric thickness has significantly thinned (<100 km) in the Indochina Block and Cathaysia Block. Lithospheric thinning may be caused by lithospheric delamination (Chung et al., 1997; Feng et al., 2022) and rollback of the Indian Plate (Li et al., 2008; Lei and Zhao, 2016; Huang et al., 2019). Then, asthenospheric upwelling and dehydration of the subducting plate caused the large-scale low-velocity anomaly in this area. However, we note that the anisotropy weakens with increasing depth in the Indochina Block (Figure 10A). We speculate that the variation in the anisotropy pattern in the upper mantle (<200 km) beneath the Indochina Block is mainly due to the upwelling of hot materials. The upwelling materials may form vertical mineral alignment and cause weak azimuthal anisotropy (Huang and Chevrot, 2021). After it reaches the basement of the lithosphere (approximately 70 km–100 km depth), it deflects transversely due to the resistance of rigid lithosphere and forms the E–W fast axis direction (Wu et al., 2019).

## 5 Conclusion

We used 7,441 broadband (5–150 s) phase velocity dispersion curves extracted from 132 permanent stations to invert the 3-D isotropic shear wave velocity model and azimuthal anisotropy in the southeastern Tibetan Plateau. Our 3-D model shows dramatic lateral and vertical variations in the isotropic shear wave velocity and azimuthal anisotropy patterns. Together with previous studies, we obtained the following major conclusions.

1. The upper crust is relatively rigid and extruded along the major strike-slip faults (Figure 11A), while two low-velocity channels exist in the mid-lower crust, and viscous material may facilitate regional deformation (Figure 11B).
2. The azimuthal anisotropy is probably the fossil anisotropy in the upper mantle of the YZC. The lithosphere has significantly thinned beneath the IB and CB. Then, the upwelling of hot asthenospheric materials and its lateral flows when meeting the rigid lithosphere formed weak anisotropy in the deeper part and a nearly E–W fast axis in the shallow part (Figure 11C).
3. The predicted shear wave splitting parameters show good coherence with the observed parameters in the depth range from the Moho to 125 km (Figures 9A, B). This result suggests that the anisotropy in the lithospheric mantle in this area has a significant contribution to the observed teleseismic shear wave splitting.

## Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding authors.

## Author contributions

ZZ: conceptualization, data curation, writing—original draft, writing—review and editing, validation and visualization. JF: conceptualization, writing—review and editing, validation, supervision and funding acquisition. HY: conceptualization, methodology, writing—review and editing, validation, supervision, funding acquisition and project administration. All authors contributed to the article and approved the submitted version.

## Funding

This work is supported by the Special Fund of Key Laboratory of Earthquake Prediction, CEA (2021IEF0103), the National Natural Science Foundation of China (42125401), and the National Key R&D Program of China (2021YFC3000600).

## Acknowledgments

The authors acknowledge Ph.D. student Ying Li from the Institute of Earthquake Forecasting, China Earthquake

Administration, for providing the shear wave splitting data for comparison with our results. The waveform data used in this study were provided by Data Management Centre of China National Seismic Network, Institute of Geophysics, China Earthquake Administration (doi:10.11998/SeisDmc/SN, <http://www.seisdmc.ac.cn>).

## Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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## Supplementary material

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